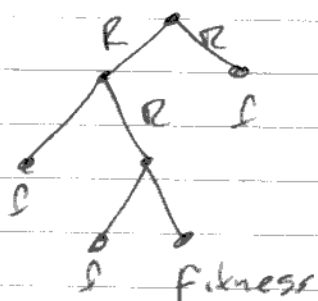


In what ways can a search space be characterized?



R - resource expended

Distinct leaf nodes

Distinct nodes

Distinct paths

Edges

- total resource expenditure to evaluate all paths w/o backtracking (requires memory)
- what if there are decoupled components that aggregate to produce fitness? what if those decoupled components are unknown?

Searching