



Symbot 1.0 Traveler

BOT REMOVAL/QUICK TURN (THIS PAGE - MUST BE COMPLETED)
MAINTENANCE NEEDED (REAR PAGE - IF REQ'D)



System Operator:

Bot Removal Data

BOT#		Pull Score		Location (which level and where - deck, aisle, charger, etc.)		Date/Time:	
# of Inductions (Last 2 Weeks)				# of Removals (Last 2 weeks)			

REASON FOR REMOVAL

From Qlik, copy/paste the Detailed Description of the Alarm(s) from the Pull Score or Out of Structure Pull Score sheet on the Bot Diagnostics report

IF APPLICABLE - NON PULL SCORE REASONS (System Flag, Disconnect, etc.)

Bot Lift Operator - Quick Turn/Bot Removal/PM:

SECTION 1 - BOT CLEANING

Remove case (if applicable)	Complete <input type="radio"/>	Cleaned all Sensors (Lens Wipe)	Complete <input type="radio"/>	Cleaned Charge Pad Plates (bot off)	Complete <input type="radio"/>
Cleaned BOT Covers	Complete <input type="radio"/>	Cleaned all Cameras (Lens Wipe)	Complete <input type="radio"/>	Compressed air to dislodge debris	Complete <input type="radio"/>
Cleaned Payload Bay	Complete <input type="radio"/>	Cleaned Pulleys and Rollers	Complete <input type="radio"/>	Cleaned Pick/Justification Arms	Complete <input type="radio"/>

SECTION 2 - PHYSICAL INSPECTION

Verify Extension Home Alignment	Pass <input type="radio"/> / Fail <input type="radio"/>	Verify E-stop button is functional	Pass <input type="radio"/> / Fail <input type="radio"/>
Inspect Junction Box for damage or Wire Contact	Pass <input type="radio"/> / Fail <input type="radio"/>	Inspect Rear and Front Bumper for damage and straightness	Pass <input type="radio"/> / Fail <input type="radio"/>
Inspect covers for damage that interferes with bot operation	Pass <input type="radio"/> / Fail <input type="radio"/>	Verify payload bay is level	Pass <input type="radio"/> / Fail <input type="radio"/>
Inspect lift tower for nominal spacing, and verticality/parallelism	Pass <input type="radio"/> / Fail <input type="radio"/>	Inspect pop-up trays and pop-up tray bolts for damage	Pass <input type="radio"/> / Fail <input type="radio"/>
Inspect Guide Rollers for proper height from rail surface	Pass <input type="radio"/> / Fail <input type="radio"/>	Inspect Justification Arms for damage	Pass <input type="radio"/> / Fail <input type="radio"/>
Inspect Camera Brackets for damage and parallelism to deck	Pass <input type="radio"/> / Fail <input type="radio"/>	Inspect Pick Arms for damage	Pass <input type="radio"/> / Fail <input type="radio"/>

SECTION 3 - WHEEL/ SUSPENSION INSPECTION

<p>Guide Wheel Diameter $\geq 48\text{mm}$</p> <p>Front Left Pass <input type="radio"/> / Fail <input type="radio"/></p> <p>Front Right Pass <input type="radio"/> / Fail <input type="radio"/></p> <p>Rear Left Pass <input type="radio"/> / Fail <input type="radio"/></p> <p>Rear Right Pass <input type="radio"/> / Fail <input type="radio"/></p>	<p>Caster Wheel Diameter $\geq 82\text{mm}$ (3.23")</p> <p>Front Left Pass <input type="radio"/> / Fail <input type="radio"/></p> <p>Front Right Pass <input type="radio"/> / Fail <input type="radio"/></p> <p>LEFT Caster Assembly Swivels Freely Pass <input type="radio"/> / Fail <input type="radio"/></p> <p>RIGHT Caster Assembly Swivels Freely Pass <input type="radio"/> / Fail <input type="radio"/></p>
<p>Drive Wheel Diameter $\geq 195\text{mm}$ (7.67")</p> <p>Rear Left Pass <input type="radio"/> / Fail <input type="radio"/></p> <p>Rear Right Pass <input type="radio"/> / Fail <input type="radio"/></p>	<p>Ride Height Distance Check</p> <p>Ride Height: $8\text{mm} \pm 1.0\text{mm}$ ($12\text{mm} \pm 1.0\text{mm}$ for new wheels)</p> <p>Pass <input type="radio"/> / Fail <input type="radio"/></p>

SECTION 4 - BELT/CHAIN INSPECTION

1. Checking a used belt in a bot (without loosening it), if it falls within the "Used Range", do not touch it. 2. Used belt that has been re-installed for some reason should be tensioned to "Used Re-Tension" 3. "New" refers to newly installed belts/cables, it does not refer to belts/cables on newly received bots onsite.

Axis + P/N	New	Used Range	Used Re-Tension	Measurement Readings & Condition			
Lift Tower Belt - 100-07350	$55 \pm 1\text{Hz}$	44-55Hz	$45\text{Hz} \pm 1\text{Hz}$	Front:		Rear:	Belt Damaged? Yes <input type="radio"/> / No <input type="radio"/>
Front Lift Cables - 400-01361	$80 \pm 5\text{Hz}$	75-85Hz	$80 \pm 5\text{Hz}$	Left Side:		Right Side:	Cable Damaged? Yes <input type="radio"/> / No <input type="radio"/>
Rear Lift Cables - 400-01361	$80 \pm 5\text{Hz}$	75-85Hz	$80 \pm 5\text{Hz}$	Left Side:		Right Side:	Cable Damaged? Yes <input type="radio"/> / No <input type="radio"/>
Extension Belt - 906-00616	$47 \pm 1\text{Hz}$	36-47Hz	$37\text{Hz} \pm 1\text{Hz}$	Front:		Rear:	Belt Damaged? Yes <input type="radio"/> / No <input type="radio"/>
Justification Belt- 906-00625	$41 \pm 1\text{Hz}$	40-42Hz	$41 \pm 1\text{Hz}$	Front:		Rear:	Belt Damaged? Yes <input type="radio"/> / No <input type="radio"/>

If **any** failed tests occur, the bot must be red tagged and sent to Maintenance for further troubleshooting!

Maintenance Technician:							
RECENT SERVICE/ ACTION RECORD							
Tech: PRINTED NAME	DATE	TIME	WORK ORDER	REMOVED / TRIAGED / CLEANED			
BOT TROUBLESHOOTING CHECKLIST							
1	Check for lift bearing damage and belt skip			22	Clean CED/CYD/COH sensors		
2	Raise payload bay			23	Put locking pins in		
3	Install fall protection pins			24	Connect to Symdart		
4	Inspect lower lift bearings and lift motor drive belt			25	Run baseline test to verify all case handling components work		
5	Inspect bump stops (903-00393) for wear, if there is wear on any replace all four			26	Adjust CED/CYD sensors to the middle of the square holes on the calibration jig		
6	Inspect holding bolt on lift cables, tighten if needed			27	Calibrate sensors		
7	Inspect lift tower guide rollers for wear, verify they aren't loose or missing			28	Run pick/place test		
8	Check for missing payload bolts			29	Take out locking pins		
9	Thoroughly wipe down everything under payload bay			30	Run Caster test and clean/inspect wheels		
10	Verify justification belt (906-00625) is at 40-42 Hz			31	Clean front bumpers/guide wheels and replace if worn		
11	Loosen and retighten coupling screw on cross shaft			32	Inspect and clean Front LFS (410-02562) with a clean dry cloth		
12	Remove fall protection pins			33	Ensure Traction can cables are tight		
13	Lower payload bay back down.			34	Run Traction Drive test and clean/inspect traction wheels (185-00652)		
14	Check tensions of all lift cables, ensure each cable is at 75-85 Hz			35	Clean rear bumpers (185-00488 & 185-00023)/guide wheels (185-00610) and replace if worn		
15	Check tensions of lift belts (100-07350), ensure belts are at 44-55 Hz on pick side			36	Inspect and clean rear LFS (410-02562) with a clean dry cloth		
16	Check for gap in extension axis and wear in extension assembly bearings			37	Clean slot sensor (310-00025) with a clean dry cloth, verify it is facing down		
17	Check tensions of extension belts, ensure belts are at 36-47 Hz			38	Clean charge pads		
18	Verify both J-arms reach the home position and have full range of motion			39	Run LFS test 3-5 times, replace LFS (410-02562) or ECU (410-02774) if necessary		
19	Turn on bot			40	Disconnect bot		
20	Thoroughly wipe down bot, blower can be used to get dust that is in hard-to-reach spots			41	Turn bot off		
21	Lubricate (908-00137) all Linear Rails			42	Verify stepper or 3-axis lights aren't on, this could indicate a bad PDU (410-02540)		
COMMONLY USED PART NUMBERS							
Traction Drive Wheel	185-00652	Ultracapacitor Module	365-00905	Floating Bumper (Non-Pick Side)	185-00488	PDU Assembly	410-02540
Guide Wheel	185-00610	Lower Rear Suspension Link	100-07106	Guide Roller Assembly Non-Pick Side	410-02702	Network Bridge	360-00051
ESD Caster Wheel Assy (Blue)	410-02864	Caster Assembly Non-Pick Side	410-02713	Guide Roller Assembly Pick Side	410-02703	Front Cover Assembly	410-02657
Caster Wheel Assy (Grey)	410-02534	Caster Assembly Pick Side	410-02712	Fixed Bumper (Pick Side)	185-00023	Rear Cover Assembly	410-02658
Front Bumper	195-04676	Left Traction Motor Assembly, AMA Drive	410-02704	Right Traction Motor Assembly, AMA Drive	410-02524	Front Lift Tower Assembly	410-02693
		Line Following Sensor Assembly	410-02562			Rear Lift Tower Assembly	410-02694