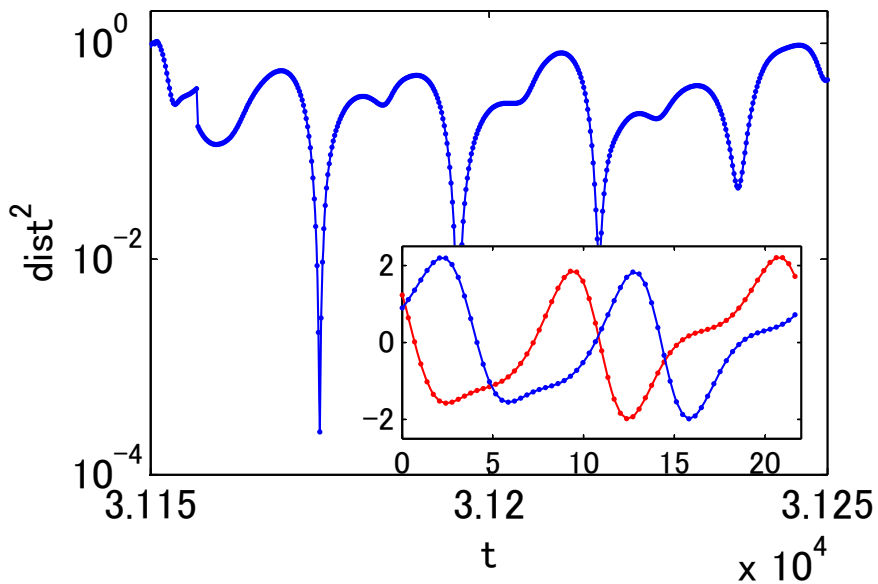
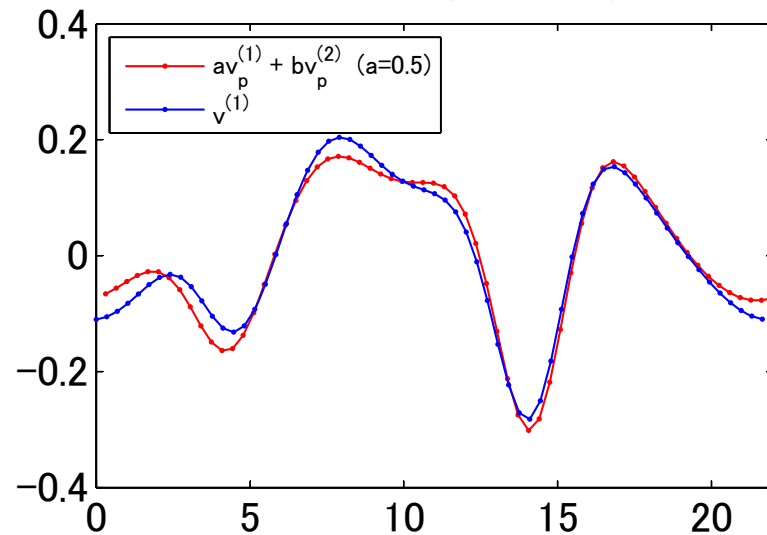


instant $t=31175$ is used.

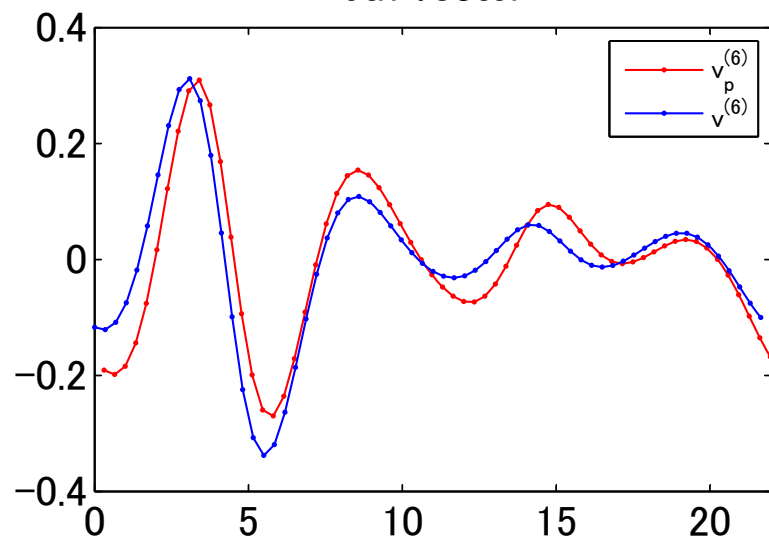
inset: snapshot of trajectory and UPO



1st vector (x shifted)



6th vector



9th vector

