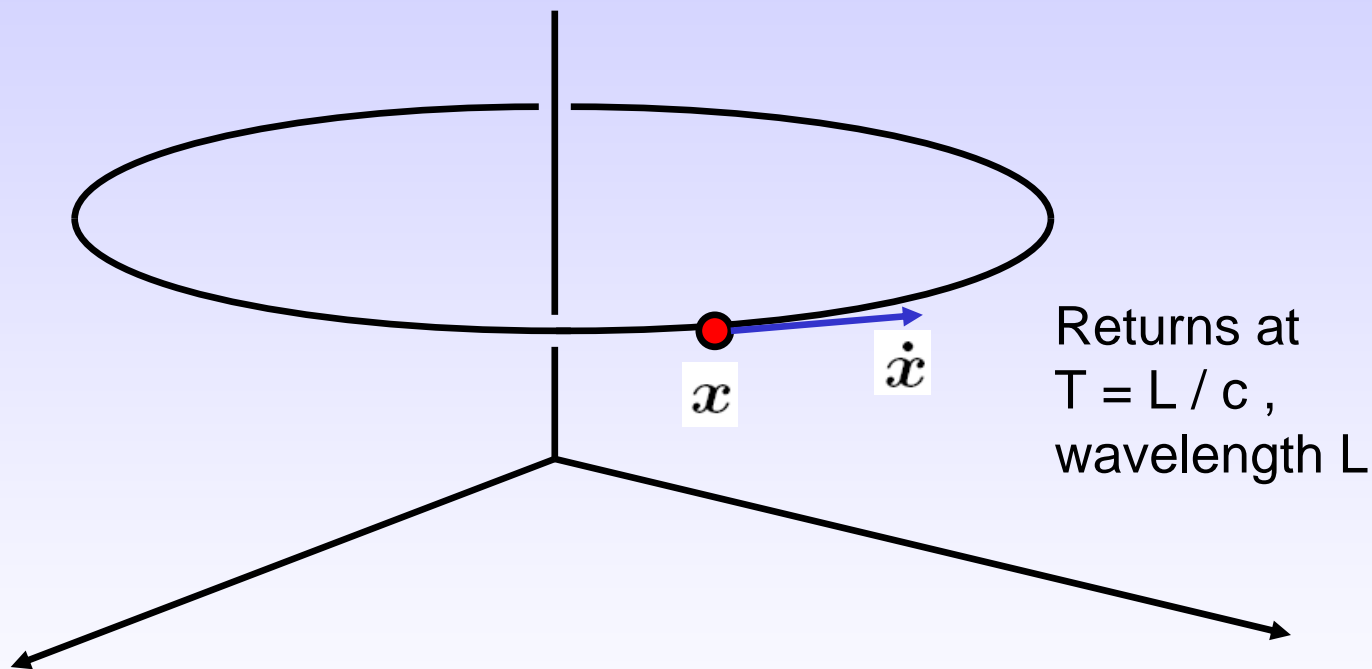
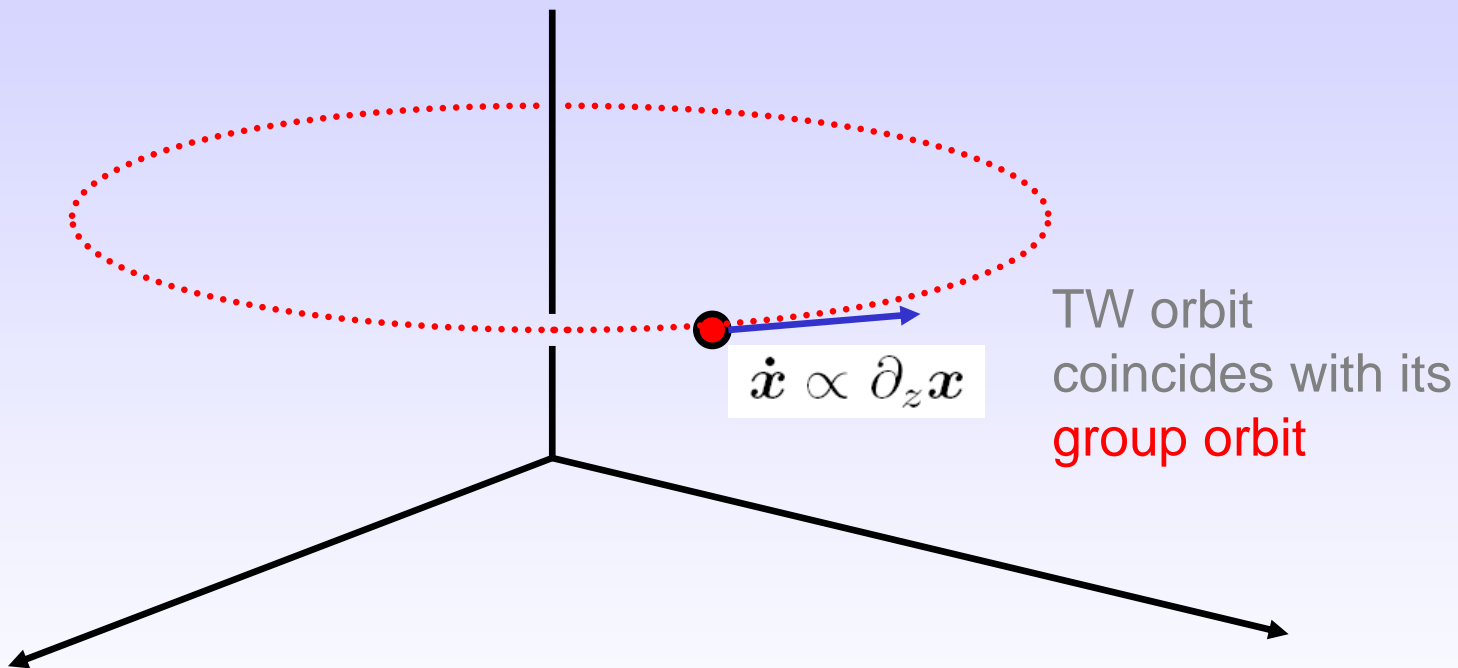


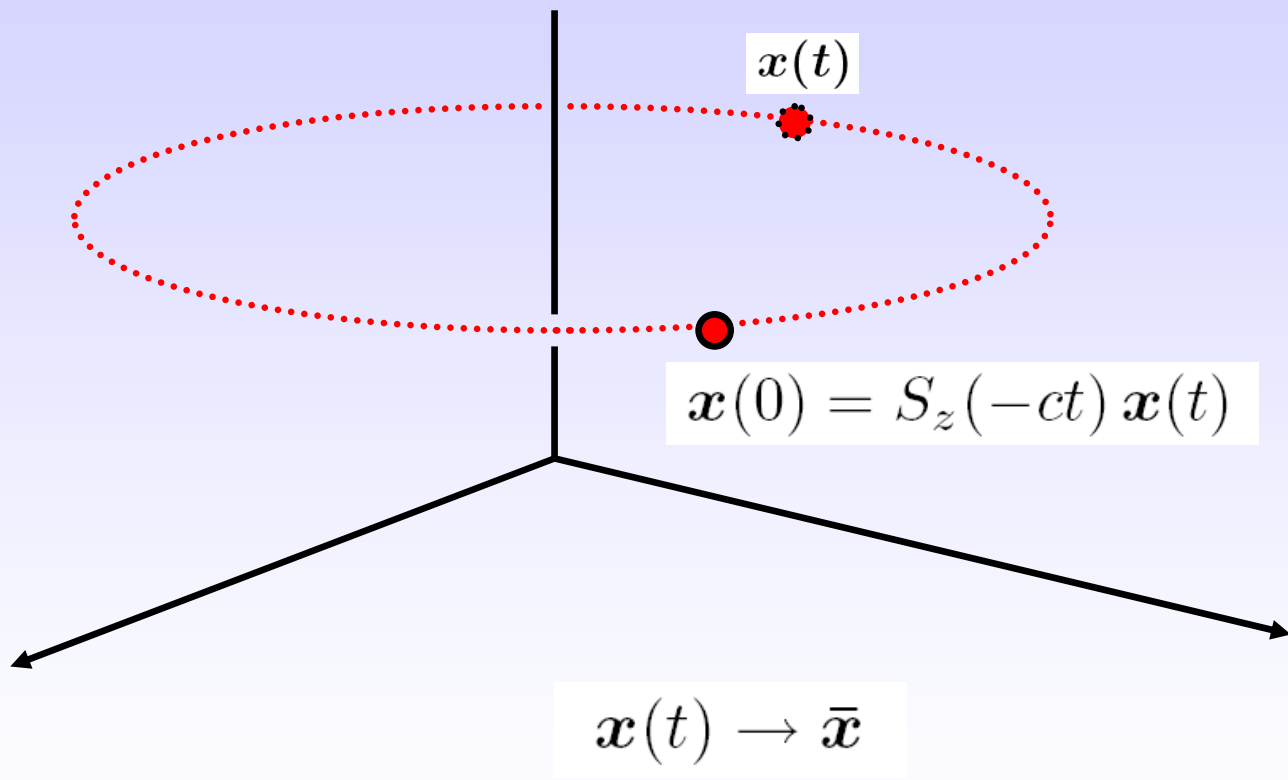
TW **orbit** in phase space



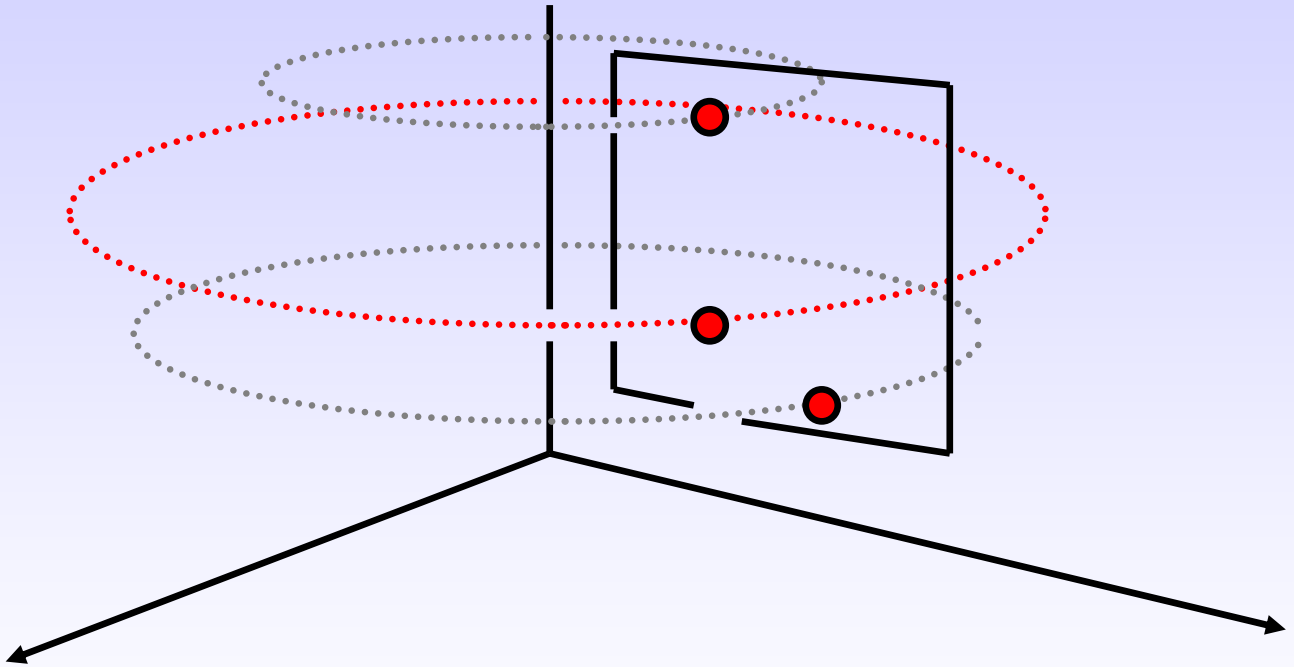
Axial shifts of TW state



Reduction of TW orbit to point by shifts

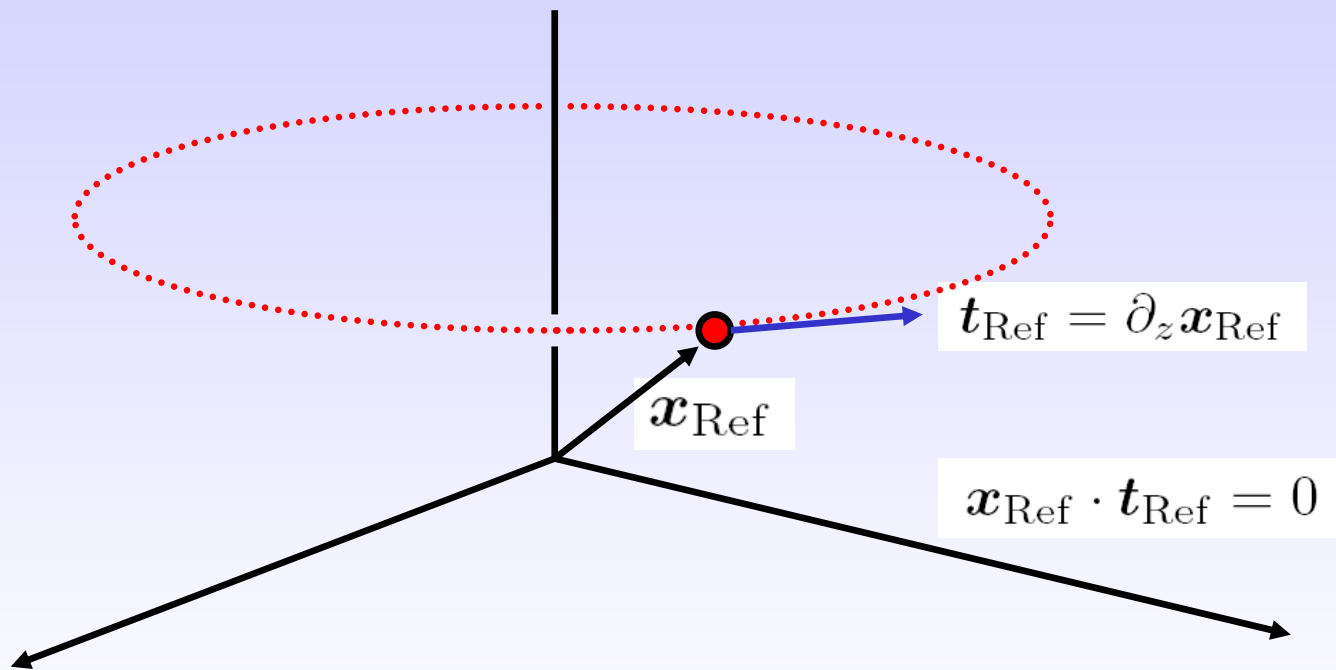


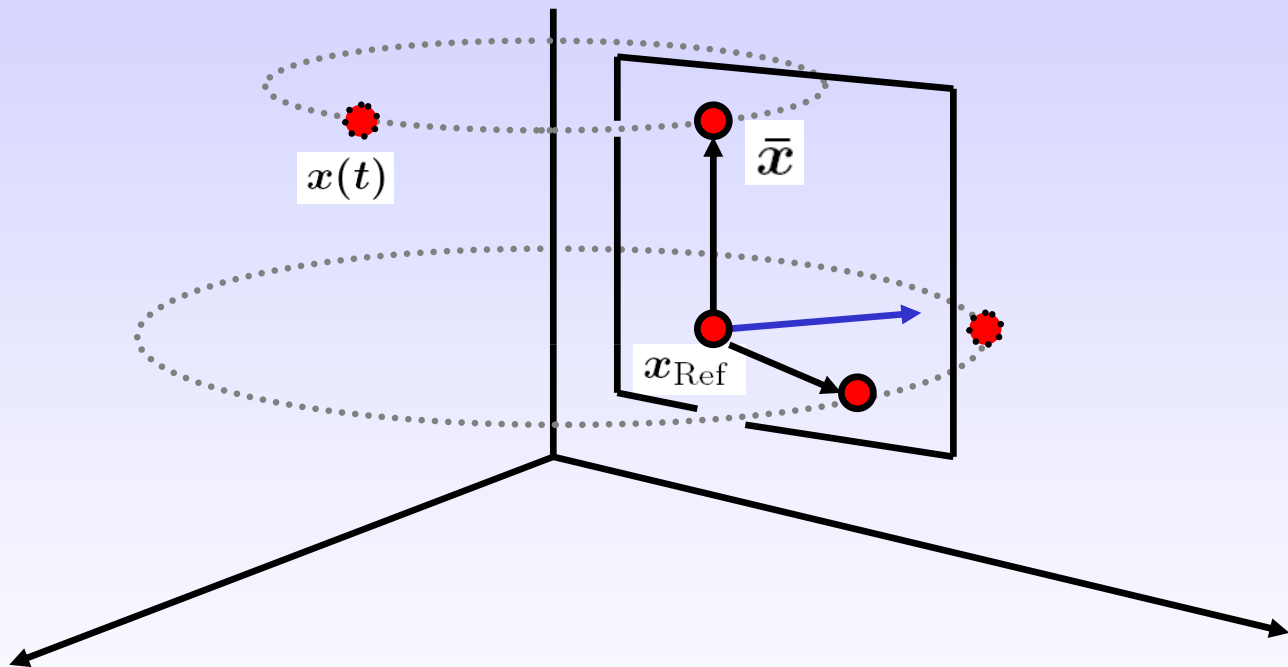
Reduce all TWs into a single **slice**



$$\mathbf{x}_i(0) = S_z(-c_i t) \mathbf{x}_i(t)$$

How? - several speeds c , possibly unknown

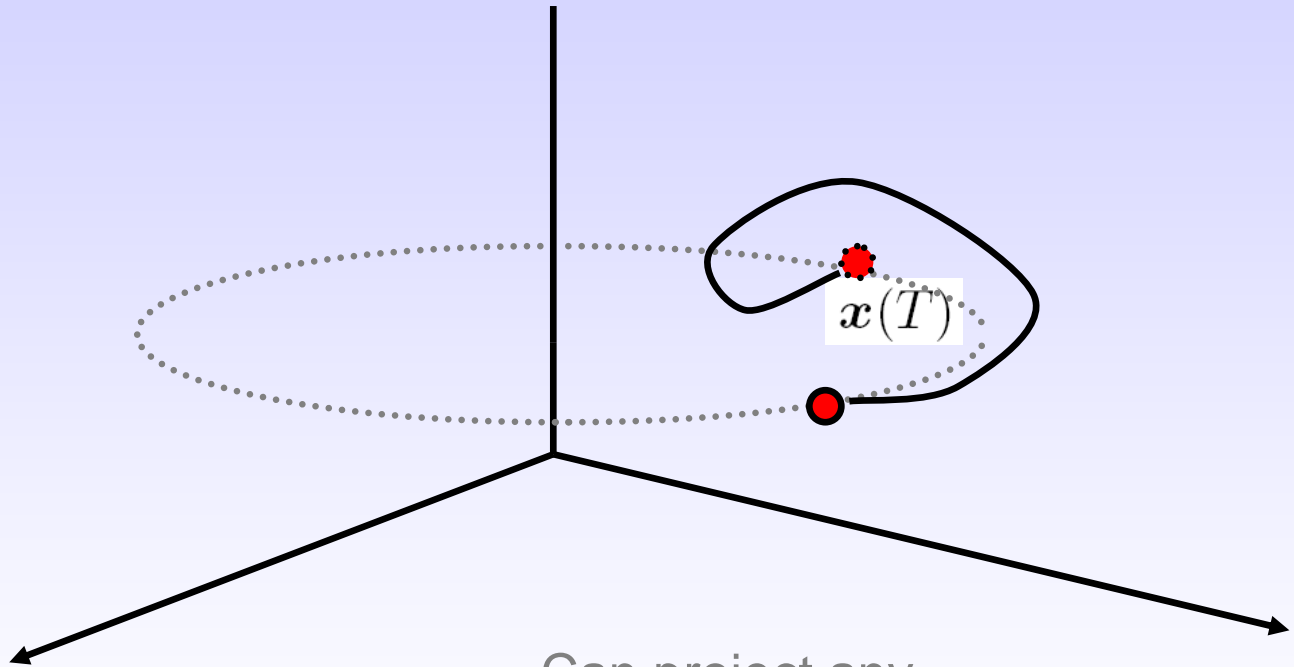




$$\underline{x} = \mathcal{U}^s \mathbf{x}(\mathfrak{f}) : (\underline{x} - \mathbf{x}^{B^{\mathfrak{e}l}}) \cdot \mathfrak{f}^{B^{\mathfrak{e}l}} = 0$$

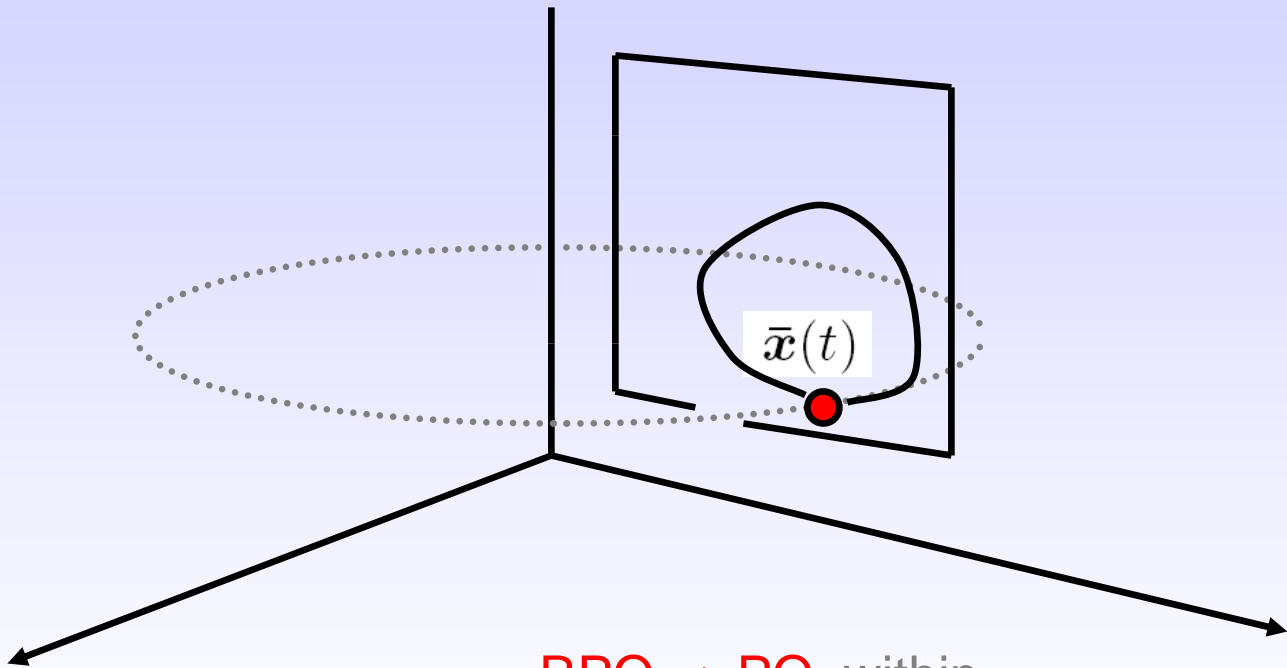
All **TWs** → **points** in the slice

Application to a relative periodic orbit (RPO)

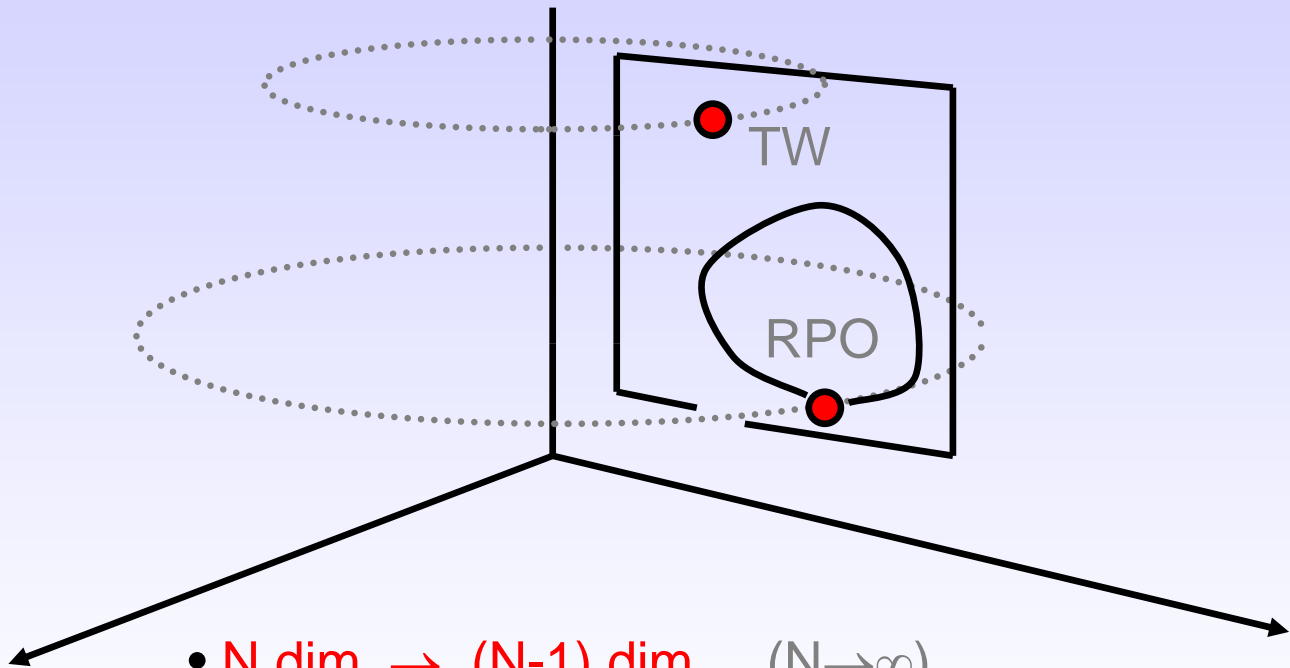


Can project any
trajectory into the slice

Application to a relative periodic orbit (RPO)

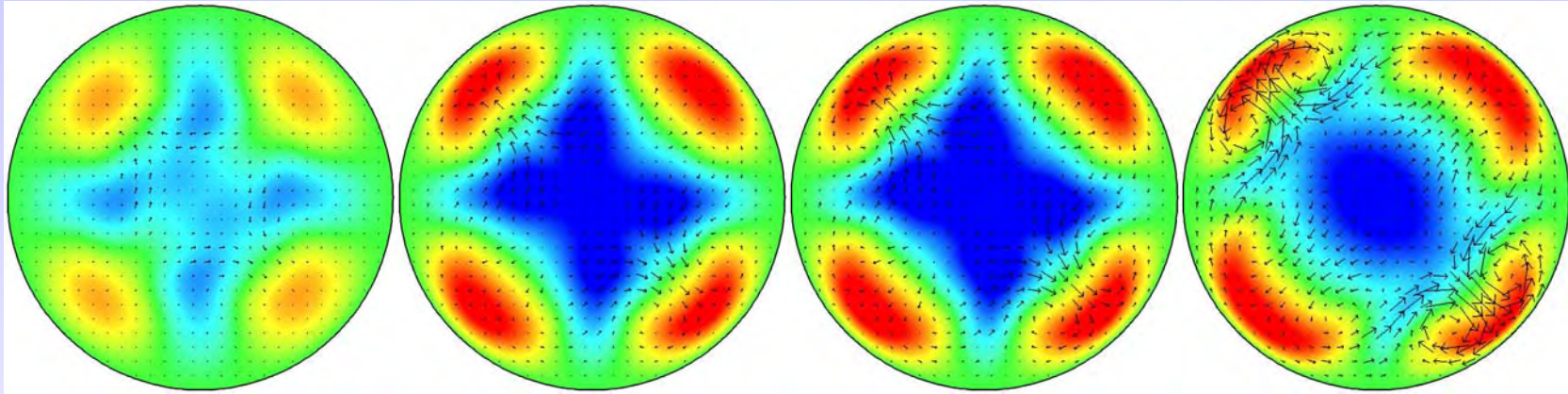


RPO \rightarrow PO within
the slice



- **N dim \rightarrow (N-1) dim** ($N \rightarrow \infty$)
- Automatic removal of strong shift (gives c for TW)
- TW \rightarrow point
- RPO \rightarrow PO

Application to Pipe Flow, $N2$ $L=2.5 D$ states



LB

M1

M2

UB

1 real

1 complex

2 real

4 complex

1 real

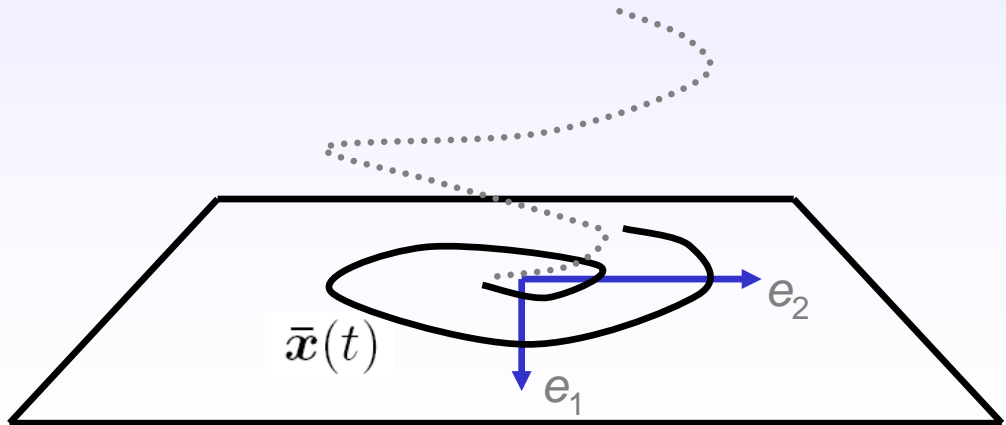
unstable eigenvalues

Projection within slice, (N-1) dim \rightarrow 2 dim

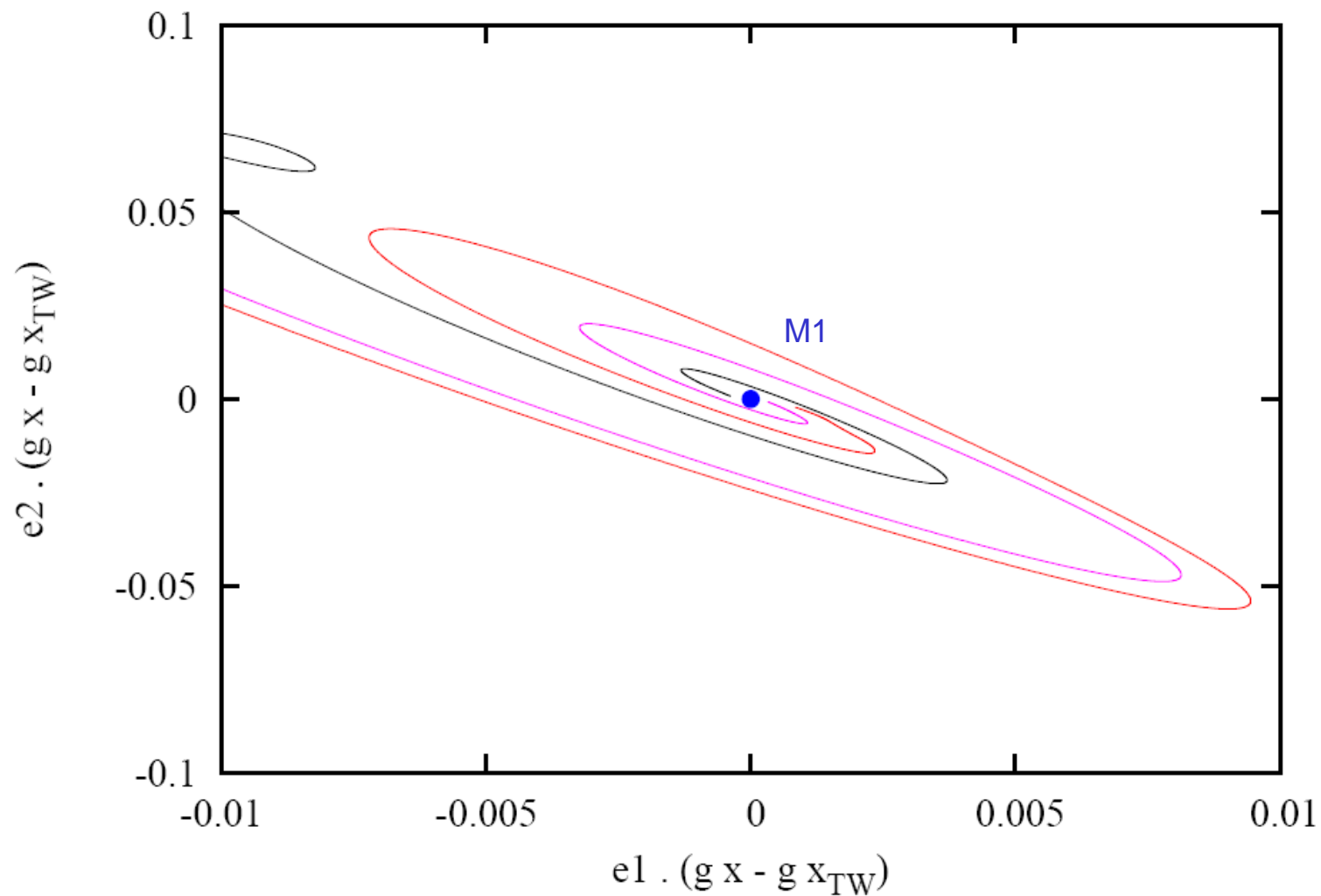
$$e_1 \cdot (\bar{\mathbf{x}}(t) - \mathbf{x}_{\text{Ref}})$$

$$\underline{e_2} \cdot (\bar{\mathbf{x}}(t) - \mathbf{x}_{\text{Ref}})$$

unstable directions of \mathbf{x}_{Ref} (M1 state)



Local dynamics, projection within slice



Embedded RPO

