The Cholesky Decomposition for SPD Matrices

- 1. Find SciPy routines to perform the Cholesky factorization and solution steps separately. Non-obligatory: Implement them on your own (algorithms can be found on Wikipedia).
- 2. Compare the performance of the Cholesky routines to the LU routines from SciPy by testing them on large symmetric and positive definite matrices $A \in \mathbb{R}^{n \times n}$ (e.g., $A = B^TB + \delta I$ for some random $B \in \mathbb{R}^{n \times n}$ and $\delta > 0$) and some (random) right-hand side $b \in \mathbb{R}^n$.

Solution:

```
import numpy as np
import scipy.linalg as linalg
from time import time
def Aspd(n,delta):
   B = np.random.rand(n,n)
    return B.T@B + delta * np.eye(n)
def FacSol(A,b, method = "lu"):
    # choose correct SciPy routines
    if method == "lu":
        factor = lambda A : linalg.lu_factor(A)
        solve = lambda tup, b : linalg.lu_solve(tup, b, overwrite_b=True)
    else:
       factor = lambda A : linalg.cho_factor(A)
        solve = lambda tup, b : linalg.cho_solve(tup, b, overwrite_b=True)
    # factor
    tfac = time()
    tup = factor(A)
    tfac = time()-tfac
    # solve
   tsolve = time()
    x = solve(tup, b)
   tsolve = time()-tsolve
    return {"x": x, method: tup, "t": (tfac, tsolve)}
if __name__ == "__main__":
    n = 1000
    delta = 0.5
    runs = 10
    for i in range(runs):
       print("run", i)
       A = Aspd(n, delta)
       b = np.random.rand(n)
       print("dim, method, [t_factor t_solve], Ax==b")
        for method in ["lu", "cho"]:
           data = FacSol(A.copy(),b.copy(), method)
           print(n, method, "\t ",np.round(data["t"],4),"\t ",np.allclose(A.dot(data["x"]),
       print("----")
```