

Elements of Mathematics
Sheet 01

Due date: **XXX**

Name:

Matriculation number:

Task:	1	2	3	4	Total	Grade
Points:						
Total:	6	6	12	10	34	–

A matrix as a Linear Function

Let $A \in \mathbb{F}^{m \times n}$ be a matrix. Then consider the mapping $f_A: \mathbb{F}^n \rightarrow \mathbb{F}^m, x \mapsto Ax$.

1. Show that

$$f_A(\lambda x + y) = \lambda f_A(x) + f_A(y),$$

for all $x, y \in \mathbb{F}^n$ and $\lambda \in \mathbb{F}$.

Hint: A vector is a matrix with just one column, so you can make use of the computation rules for matrices given in the lecture notes.

Remark: Functions satisfying this property are called **linear**.

2. Use this fact to show the following equivalence:

$$\ker(A) := \{x \in \mathbb{F}^n : Ax = 0\} = \{0\} \quad \Leftrightarrow \quad f_A(x) = f_A(y) \text{ implies } x = y, \\ \text{(i.e., } f_A \text{ is an injective mapping).}$$

Hint: Split up the equality \Leftrightarrow into \Rightarrow and \Leftarrow and prove each of them separately.

The Subspaces Kernel and Image

1. Let $A \in \mathbb{F}^{m \times n}$. Show that $\ker(A)$ and $\text{Im}(A)$ are subspaces of \mathbb{F}^n and \mathbb{F}^m , respectively.
2. Construct two example matrices and consider their kernel and image.

Rank/Image and Nullity/Kernel

Consider the matrix

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 1 & 1 & 1 \end{pmatrix},$$

the column vector $\mathbf{1} := \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$ (i.e., a (3×1) matrix) and the row vector $\tilde{\mathbf{1}} := (1 \ 1 \ 1)$ (i.e., a (1×3) matrix).

1. Show that $A = \mathbf{1}\tilde{\mathbf{1}}$.
2. Find two distinct nonzero vectors x and y , so that $Ax = 0$ and $Ay = 0$.
3. How does the image $\text{Im}(A)$ look like? First draw a picture. Then find a basis of $\text{Im}(A)$ to determine the rank of the matrix.
4. How does the kernel $\ker(A)$ look like? First draw a picture. Then find a basis of $\ker(A)$ to determine the nullity of the matrix.

Remark: You have to prove that your vectors are a basis.

The Matrix-Vector Product

Implement a function that takes as input a matrix $A \in \mathbb{R}^{m \times n}$ and a vector $x \in \mathbb{R}^n$ and then returns the matrix-vector product Ax .

1. Implement the following four ways:
 - a) **Dense:** Input expected as `numpy.ndarray`:
Assume that the matrix and the vector are delivered to your function as `numpy.ndarray`.
 - i. Implement the matrix-vector product “by hand” using for loops, i.e., *without* using numpy functions/methods.

ii. Implement the matrix-vector product using `A.dot(x)`, `A@x`, `numpy.matmul(A,x)` or `numpy.dot(A,x)`.

b) **Sparse:** Matrix expected in **CSR format**:

Assume that the matrix is delivered to your function as `scipy.sparse.csr_matrix` object. The vector x can either be expected as `numpy.ndarray` or simply as a Python list.

i. Access the three CSR lists via `A.data`, `A.indptr`, `A.indices` and implement the matrix-vector product "by hand" using for loops.

ii. Implement the matrix-vector product using `A.dot(x)` or `A@x`.

2. **Test** your four different routines from above on the following matrix $A \in \mathbb{R}^{n \times n}$ with constant diagonals given by

$$A = \begin{pmatrix} 2 & -1 & 0 & \cdots & 0 \\ -1 & 2 & -1 & \ddots & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & \ddots & -1 & 2 & -1 \\ 0 & \cdots & 0 & -1 & 2 \end{pmatrix} \in \mathbb{R}^{n \times n}$$

and the input vector

$$x = (1, \dots, 1)^T \in \mathbb{R}^n \quad (\text{you can use: } x = \text{numpy.ones}(n)).$$

a) Determine how $b := A \cdot x \in \mathbb{R}^n$ looks like in this example in order to facilitate a test.

b) Test whether your four routines compute the matrix-vector product correctly by checking $A \cdot x = b$.

c) Use different values for the dimension n (especially large $n \geq 10^5$ – note that you may exceed your hardware capacities for the dense computations).

Remark: The matrix has "2" on the main diagonal and "−1" on the first off-diagonals.

3. For all cases:

a) **Memory:** What is the number of Gbytes needed to store an $m \times n$ array of floats? Print the number of Gbytes which are needed to store the matrix in all cases.

Hint: A number implemented as float in Python implements double precision and therefore needs 64 Bits of storage. For a `numpy.ndarray` you can type `A.nbytes` and for the `scipy.sparse.csr_matrix` you can type `A.data.nbytes + A.indptr.nbytes + A.indices.nbytes`.

b) **Computation times:** Measure the time which is needed in each case to compute the matrix-vector product for a random input vector $x = \text{numpy.random.rand}(n)$.

Hint: In the IPython shell you can simply use the *magic function* `%timeit` to measure the time for a certain operation. For example, you can type `%timeit pythonfunction(x)`. Alternatively you can use the package `timeit`.

Sparse Matrix

10	0	0	0	-2
3	9	0	0	0
0	7	8	7	0
3	0	8	7	5
0	8	0	9	13

data

10	-2	3	9	7	8	7	3	8	7	5	8	9	13
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(column) indices

0	4	0	1	1	2	3	0	2	3	4	1	3	4
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row pointer (indptr)

0	2	4	7	11	14
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Example of a Matrix in CSR Format