## 1 Splitting Methods: relax. Richardson, relax. Jacobi, Gauß-Seidel and SOR

1. Implement a function

x, error, numiter = iter\_solve(A, b, x0, method="Jacobi", theta=.1, tol=1e-08, maxiter=50) which takes as arguments

- A : a matrix  $A \in \mathbb{R}^{n \times n}$
- b : a vector  $b \in \mathbb{R}^n$
- x0 : an initial guess  $x^0 \in \mathbb{R}^n$
- method: optional parameter to choose between relax. Richardson, weighted Jacobi, Gauß-Seidel and SOR and which is set to "Jacobi" by default
- theta : relaxation parameter  $\theta$  which is set to 0.1 by default (note: Gauß-Seidel is SOR with theta=1.0)
- $\bullet$  tol : error tolerance as float, which is set to  $10^{-8}$  by default
- maxiter : maximum number of iterations, which is set to 50 by default

and then solves the system Ax = b by applying the specified iterative scheme. It shall then return

- x : list of all iterates  $x^k$
- error : list containing all residuals  $||Ax^k b||_2$
- numiter : number of iterations that have been performed

The iteration shall break if the residual is tolerably small, i.e.,

$$||Ax^k - b||_2 < \text{tol}$$

or the maximum number of iterations maxiter has been reached.

Hint: Implement the element-based formulas for the Jacobi, Gauß-Seidel and SOR method (see previous exercise).

2. 2d: Test all methods on the following two-dimensional setting:

$$A = 4 \begin{pmatrix} 2 & -1 \\ -1 & 2 \end{pmatrix}, \quad b = \begin{pmatrix} 0 \\ 0 \end{pmatrix}.$$

What is the exact solution  $x^*$ ? Play around with the parameters x0, theta, tol and maxiter. Also create the following two plots for one fixed setting:

- Plot the error  $||Ax^k b||_2$  for each iterate  $x^k \in \mathbb{R}^2$ , k = 1, ..., m, for <u>all</u> methods into one plot (use different colors).
- Plot the iterates  $x^k \in \mathbb{R}^2$ , k = 1, ..., m, themselves for all methods into one plot (use different colors).
- 3. nd: Next, test all methods on the higher-dimensional analogue

$$A = n^{2} \begin{pmatrix} 2 & -1 & 0 & \dots & 0 \\ -1 & 2 & -1 & & \vdots \\ 0 & \ddots & \ddots & \ddots & 0 \\ \vdots & & -1 & 2 & -1 \\ 0 & \dots & 0 & -1 & 2 \end{pmatrix} \in \mathbb{R}^{n \times n},$$

for different dimensions  $n \in \mathbb{N}$  and data  $b, x^0 \in \mathbb{R}^n$  of your choice. Play around with the parameters.

*Hint:* Of course, it can happen that the iterations do not converge. Use small values for  $\theta$  when you use the Richardson iteration. This will assure that  $\rho(I-NA) < 1$ .

## Solution:

```
import numpy as np
import matplotlib.pyplot as plt
import warnings
warnings.filterwarnings("ignore")
                     ITERATIVE SOLVER
def Richardson_step(A, b, theta, x):
    return x - theta * (A @ x - b)
def Jacobi_step(A, b, theta, x):
   n = len(x)
    xnew = np.zeros(n)
    for i in range(n):
        s1 = np.dot(A[i, :i], x[:i])
        s2 = np.dot(A[i, i + 1:], x[i + 1:])
        xnew[i] = (1. - theta) * x[i] + theta / A[i, i] * (b[i] - s1 - s2)
    return xnew
def SOR_step(A, b, theta, x):
    n = len(x)
    xnew = np.zeros(n)
    for i in range(n):
        s1 = np.dot(A[i, :i], xnew[:i]) # <-- here we use already the new info
        s2 = np.dot(A[i, i + 1:], x[i + 1:])
        xnew[i] = (1. - theta) * x[i] + theta / A[i, i] * (b[i] - s1 - s2)
    return xnew
def steepestDescent_step(A, b, theta, x):
    r = A@x - b
    theta = np.dot(r, r) / np.dot(A@r, r)
    return x - theta * (A @ x - b)
def conjugateGradient(A, b, x0, maxiter=50, tol=1e-8):
   X = [x0]
    n = len(x0)
   error = []
   r = b - A @ X[0]
    p = r
    alpha_alt = np.dot(r, r)
    for numiter in range(max(maxiter, n)):
        error += [np.linalg.norm(A.dot(X[-1]) - b)]
        if error[-1] < tol:</pre>
           return X, error, numiter
        v = A @ p
        lambd = alpha_alt / np.dot(v, p)
        X += [X[-1] + lambd * p]
        r = r - lambd * v
        alpha_neu = np.dot(r, r)
        p = r + alpha_neu/alpha_alt * p
        alpha_alt = alpha_neu
    return X, error, numiter
```

```
def iter_solve(A, b, x0, method="Jacobi", theta=.1, maxiter=50, tol=1e-8):
    solves a system Ax = b, where A is assumed to be invertible,
    with relaxed splitting methods: Jacobi, Richardson
    Parameters
    A : (n, n) numpy.ndarray
        system matrix
    b : (n,) numpy.ndarray
        right-hand side
    x0: (n,) numpy.ndarray
         initial guess
    method : string
            indicates method: "Jacobi" (=default), "Richardson", "GS", "SOR"
    theta : number (int or float)
            relaxation parameter (step length) default theta = 0.1
    tol : number (float)
           error tolerance, iteration stops if ||Ax-b|| < tol
    maxiter : int
       number of iterations that are performed , default m=50
    Returns
    X : list of length N (=m or less), containing iterates
       columns represent iterates from x_0 to x_{N-1}
    error : list of length numiter containing norm of all residuals
    numiter: integer indicating how many iterations have been performed
   X = [x0]
    error = []
    if method in ["GS", "SOR", "Jacobi", "steepestDescent"] and \
       np.prod(A.diagonal()) == 0:
       print(f"WARNING: Method was chosen to be {method} \
              but A has zero diagonal entries!")
       return None
    elif method == "GS":
       theta = 1.0
       method = "SOR"
    elif method == "CG":
       return conjugateGradient(A, b, x0, maxiter=maxiter, tol=tol)
    # choose the function to compute the iteration instruction
    # according to method
    stepInstructionDictionary = {"Jacobi": Jacobi_step,
                                 "Richardson": Richardson_step,
                                 "SOR": SOR_step,
                                 "steepestDescent": steepestDescent_step}
    stepInstruction = stepInstructionDictionary[method]
    # ITERATION
    for numiter in range(maxiter):
        error += [np.linalg.norm(A.dot(X[-1]) - b)]
        if error[-1] < tol:</pre>
           return X, error, numiter
        X += [stepInstruction(A, b, theta, X[-1])]
    return X, error, numiter
def main(A, b, x0, maxiter, methThet, plot=False, verbose=False):
   X = np.zeros((maxiter, 2, len(methThet)))
```

```
colors = ['r', 'g', 'b', "y", "c", "m"]
            PLOT error and iterates
   #
   # -----
                 _____#
   if plot:
      plt.figure()
   for i, method in enumerate(methThet):
       X, error, numiter = iter_solve(A, b, x0, method=method,
                                  theta=methThet[method],
                                  maxiter=maxiter)
       if verbose:
          print(method, "\n \t\t >", f"NumIter = {numiter}",
               f"\t residual = {error[-1]:0.2e}")
      if plot:
          plt.subplot(1, 2, 1)
          plt.plot(error, colors[i]+"-x")
          plt.title("Residual $||Ax_k - b||_2$")
          plt.legend(method)
          plt.subplot(1, 2, 2)
          X = np.array(X)
          plt.plot(X[:, 0], X[:, 1], colors[i] + "o-")
          plt.legend(list(methThet.keys()))
          plt.title("Iterates $x_k$")
          plt.axis("equal")
   if plot:
       plt.show()
       plt.axis("equal")
   return X, error, numiter
if __name__ == "__main__":
   # -----#
   # 2d EXAMPLE
   A = 4. * np.array([[2, -1],
                   [-1, 2]])
   b = np.zeros(2)
   x0 = np.array([5, 8])
   maxiter = 100
   print("-"*40+"\n 2d EXAMPLE (numiter, error) \n"+"-"*40)
   X, error, numiter = main(A, b, x0, maxiter,
                         methThet, plot=True, verbose=True)
                HIGHER DIMENSIONAL EXAMPLE
   n = 100 # 10000 # 100000
   A = n ** 2 * (2 * np.eye(n, k=0) - np.eye(n, k=1) - np.eye(n, k=-1))
   b = np.random.rand(n)
   x0 = np.random.rand(n) # b#*100#
   firstMmethods = 4
   maxiter = 50
   methThet = {"Richardson": 0.00001, "Jacobi": 0.5, "GS": 1, "SOR": 1.9,
              "steepestDescent": 1}
   print("-"*40 + "\n nd EXAMPLE with n = {}\n".format(n) + "-"*40)
   X, error, numiter = main(A, b, x0, maxiter,
                        methThet, plot=0, verbose=True)
```