

Minimum Norm Least Squares with Pseudoinverse

Let $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$. Consider the SVD $A = U\Sigma V^\top$ and set $A^+ = V\Sigma^+U^\top$, where $\Sigma^+ = \text{diag}(\frac{1}{\sigma_1}, \dots, \frac{1}{\sigma_r}, 0, \dots, 0)$ is the pseudoinverse of a diagonal matrix as derived in the lecture. Show that

$$x^+ := A^+b = \arg \min_{x \in \{x: A^\top Ax = A^\top b\}} \|x\|_2^2,$$

i.e., x^+ is the minimum norm least squares solution.

Hint: First consider the simple case that A is diagonal and then use the SVD for the general case.

Solution:

(1) Special Case: Diagonal matrix

Let us start with the simple case: $A \in \mathbb{R}^{m \times n}$ diagonal

$$A = \begin{pmatrix} a_{11} & & & 0 \\ & \ddots & & \\ & & a_{rr} & \\ 0 & & & \ddots & \\ & & & & 0 \end{pmatrix} \in \mathbb{R}^{m \times n}, a_{ii} \neq 0, \quad A^\top A = \begin{pmatrix} a_{11}^2 & & & 0 \\ & \ddots & & \\ & & a_{rr}^2 & \\ 0 & & & \ddots & \\ & & & & 0 \end{pmatrix} \in \mathbb{R}^{n \times n}$$

Normal equation:

$$\begin{aligned} A^\top Ax = A^\top b &= \begin{pmatrix} a_{11}b_1 \\ \vdots \\ a_{rr}b_r \\ 0 \\ \vdots \\ 0 \end{pmatrix} \Leftrightarrow \begin{aligned} a_{11}^2 x_1 &= a_{11}b_1 \\ \vdots \\ a_{rr}^2 x_r &= a_{rr}b_r \\ 0 \cdot x_i &= 0 \quad (i > r) \end{aligned} \Leftrightarrow \begin{aligned} x_1 &= \frac{b_1}{a_{11}} \\ \vdots \\ x_r &= \frac{b_r}{a_{rr}} \\ x_{r+1} &= 0 \\ \vdots \\ x_n &= 0 \end{aligned} \\ \Rightarrow x^+ &= \begin{pmatrix} \frac{1}{a_{11}}b_1 \\ \vdots \\ \frac{1}{a_{rr}}b_r \\ 0 \\ \vdots \end{pmatrix} = A^+b, \quad A^+ = \begin{pmatrix} \frac{1}{a_{11}} & & & 0 \\ & \ddots & & \\ & & \frac{1}{a_{rr}} & \\ 0 & & & \ddots & \\ & & & & 0 \end{pmatrix} \in \mathbb{R}^{n \times m} \end{aligned}$$

Note: The x_i for $i > r$ can be chosen arbitrarily, but setting them to zero gives the smallest vector.

(2) General Case

By using the SVD $A = U\Sigma V^\top$ we find

$$A^\top A = (U\Sigma V^\top)^\top U\Sigma V^\top = V\Sigma^\top \Sigma V^\top,$$

so that the normal equation reads as

$$\begin{aligned} (*) \quad A^\top Ax = A^\top b &\Leftrightarrow V\Sigma^\top \Sigma (V^\top x) = V\Sigma^\top (U^\top b) \\ &\stackrel{V^\top, |}{\Leftrightarrow} \underbrace{\Sigma^\top \Sigma (V^\top x) = \Sigma^\top (U^\top b)}_{(\text{normal equation for } (\Sigma, U^\top b))} \quad (\#) \end{aligned}$$

Consequently, x solves $(*)$ if and only if $y := V^\top x$ solves $(\#)$. Since V is orthogonal both solutions have the same norm, more precisely,

$$\|x\|_2^2 = x^\top x = x^\top (V^\top V)x = \|Vx\|_2^2 = \|y\|_2^2.$$

For diagonal matrices we have shown that $y^+ = \Sigma^+ U^T b$ is the smallest solution of (\sharp) . Thus, $x^+ := Vy^+ = \Sigma^+ U^T b$ is the smallest solution of $(*)$, i.e., the minimum norm least squares solution.

All in all: Since orthogonal matrices (here U and V) are not only invertible but also isometric and the SVD $A = U\Sigma V^T$ always exists, we could rely on the result for diagonal matrices (here Σ).