1 Weighted Jacobi, Gauß-Seidel and Sucessive Over-Relaxation

9 Bonus points

Let $A \in \mathbb{R}^{n \times n}$ be a matrix with nonzero diagonal entries $a_{ii} \neq 0$ and consider the splitting A = L + D + U into lower triangular, diagonal and upper triangular part of A. Also recall that splitting methods are of the form

$$x^{k+1} = (I - NA)x^k + Nb,$$

where the significant matrix M := I - NA is called iteration matrix.

Show the following:

- 1. Weighted Jacobi: $N = \theta D^{-1}$
 - For the iteration matrix we find

$$M_{Iac} := I - \theta D^{-1} A = (1 - \theta)I - \theta D^{-1} (L + U)$$

• The *i*-the component of $x^{k+1} = (I - NA)x^k + Nb$ is given by

$$x_i^{k+1} = (1-\theta)x_i^k + \frac{\theta}{a_{ii}} \left(b_i - \sum_{j \neq i} a_{ij} x_j^{k+1}\right).$$

- 2. **Gauß-Seidel:** $N = (L + D)^{-1}$
 - For the iteration matrix we find

$$M_{GS} := I - (L+D)^{-1}A = -(L+D)^{-1}U$$

• The *i*-the component of $x^{k+1} = (I - NA)x^k + Nb$ is given by

$$x_i^{k+1} = \frac{1}{a_{ii}} \left(b_i - \sum_{i=1}^{i-1} a_{ij} x_j^{k+1} - \sum_{i=i+1}^{n} a_{ij} x_j^k \right).$$

- 3. Sucessive Over–Relaxation (variant of Gauß-Seidel): $N = \theta \cdot (\theta L + D)^{-1}$
 - For the iteration matrix we find

$$M_{SOR} := I - \theta(\theta L + D)^{-1} A = (\theta L + D)^{-1} ((1 - \theta)D - \theta U).$$

ullet The i-the component of $x^{k+1}=(I-NA)x^k+Nb$ is given by

$$x_i^{k+1} = (1-\theta)x_i^k + \frac{\theta}{a_{ii}} \left(b_i - \sum_{j=1}^{i-1} a_{ij} x_j^{k+1} - \sum_{j=i+1}^{n} a_{ij} x_j^k \right).$$

Remark: We observe that SOR for $\theta=1$ is Gauß–Seidel and otherwise is a combination of the previous step x^k and the Gauß-Seidel update. For spd matrices it allows for $\theta>1$ which is why it is called over–relaxation.

Hint: For 2. and 3. cast the formulas into the form $x^{k+1} = T^{-1}w$ for some lower triangular matrix T and some vector w and then use forward substitution.

Solution:

We first recall the forward substitution formula for inverting lower triangular matrices: Let $T = (\ell_{ij}) \in \mathbb{R}^{n \times n}$ be triangular and $w \in \mathbb{R}^n$, then the *i*-th component of $z = T^{-1}w$ is given by

$$z_i = \frac{1}{\ell_{ii}} \left(w_i - \sum_{j=1}^{i-1} \ell_{ij} z_j \right), \quad i \in \{1, \dots, n\}.$$

1. Jacobi:

• Using the splitting A = L + D + U we find

$$M_{Iac} := I - \theta D^{-1} A = I - \theta D^{-1} (L + D + U) = I - \theta (I + D^{-1} (L + U)) = (1 - \theta) I - \theta D^{-1} (L + U)$$

• The inverse of D is $D^{-1} = \operatorname{diag}(\frac{1}{a_{11}}, \dots, \frac{1}{a_{nn}})$. Thus the i-th component of $\theta D^{-1}b$ is given by $\theta \frac{b_i}{a_{ii}}$. Now applying the definition of the matrix vector product we find for the i-th component of $\theta D^{-1}Ax^k$ that $\theta \frac{1}{a_{ii}} \sum_{j=1}^n a_{ij} x_j^k$. Combining this we obtain for the i-th of the Jacobi iterate the searched formula

$$x_i^{k+1} = x_i^k - \theta \frac{1}{a_{ii}} \sum_{j=1}^n a_{ij} x_j^k + \theta \frac{b_i}{a_{ii}} = x_i^k - \theta x_i^k - \theta \frac{1}{a_{ii}} \sum_{j \neq i} a_{ij} x_j^k + \theta \frac{b_i}{a_{ii}}$$
$$= (1 - \theta) x_i^k + \frac{\theta}{a_{ii}} \left(b_i - \sum_{j \neq i} a_{ij} x_j^{k+1} \right).$$

2. Gauß-Seidel

• Using the splitting A = L + D + U we find

$$M_{GS} := I - (L+D)^{-1}A = I - (L+D)^{-1}(L+D+U) = I - (I+(L+D)^{-1}U) = -(L+D)^{-1}U$$

• We cast the formula into a lower triangular system:

$$x^{k+1} = (I - NA)x^k + Nb = M_{GS}x^k + Nb$$
$$= -(L+D)^{-1}Ux^k + (L+D)^{-1}b$$
$$= (L+D)^{-1}(b-Ux^k)$$

Now we consider $z=x^{k+1}$, T=(L+D) and $w=b-Ux^k$ and apply forward substitution to obtain

$$x_i^{k+1} = z_i = \frac{1}{\ell_{ii}} \left(w_i - \sum_{j=1}^{i-1} \ell_{ij} z_j \right), \quad i \in \{1, \dots, n\}$$

$$= \frac{1}{a_{ii}} \left(b_i - \sum_{j=i+1}^{n} a_{ij} x_j^k - \sum_{j=1}^{i-1} a_{ij} x_j^{k+1} \right), \quad i \in \{1, \dots, n\}.$$

3. **SOR**

• We use

$$N = \theta \cdot (\theta L + D)^{-1} = \left(\frac{1}{\theta}\right)^{-1} (\theta L + D)^{-1} = \left(L + \frac{1}{\theta}D\right)^{-1}$$

and the splitting

$$A = L + D + U = L + D + U \pm \frac{1}{\theta}D = (L + \frac{1}{\theta}D) + U + (1 - \frac{1}{\theta})D.$$

Then we find

$$M_{SOR} := I - NA = I - \left(L + \frac{1}{\theta}D\right)^{-1} \left(\left(L + \frac{1}{\theta}D\right) + U + \left(1 - \frac{1}{\theta}\right)D\right)$$

$$= -\left(L + \frac{1}{\theta}D\right)^{-1} \left(U + \left(1 - \frac{1}{\theta}\right)D\right)$$

$$= \left(L + \frac{1}{\theta}D\right)^{-1} \left(\frac{1 - \theta}{\theta}D - U\right)$$

$$= \theta \cdot (\theta L + D)^{-1} \left(\frac{1 - \theta}{\theta}D - U\right)$$

$$= (\theta L + D)^{-1} \left((1 - \theta)D - \theta U\right).$$

• We cast the formula into a lower triangular system:

$$x^{k+1} = (I - NA)x^k + Nb = M_{SOR}x^k + Nb$$

= $(\theta L + D)^{-1} ((1 - \theta)D - \theta U)x^k + \theta \cdot (\theta L + D)^{-1}b$
= $(\theta L + D)^{-1} (\theta b - ((1 - \theta)D - \theta U)x^k)$

Now we consider $z=x^{k+1}$, $T=(\theta L+D)$ and $w=\theta b-(1-\theta)Dx^k-\theta Ux^k$ and apply forward substitution to obtain

$$\begin{aligned} x_i^{k+1} &= z_i = \frac{1}{\ell_{ii}} \left(w_i - \sum_{j=1}^{i-1} \ell_{ij} z_j \right), \quad i \in \{1, \dots, n\} \\ &= \frac{1}{a_{ii}} \left(\theta b_i - (1 - \theta) a_{ii} x_i^k - \theta \sum_{j=i+1}^n a_{ij} x_j^k - \sum_{j=1}^{i-1} \theta a_{ij} x_j^{k+1} \right), \quad i \in \{1, \dots, n\} \\ &= (1 - \theta) x_i^k + \frac{\theta}{a_{ii}} \left(b_i - \sum_{j=i+1}^n a_{ij} x_j^k - \sum_{j=1}^{i-1} a_{ij} x_j^{k+1} \right), \quad i \in \{1, \dots, n\}. \end{aligned}$$