Econ, Problem Set #5, DSGE

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1.1 We guess for the policy function $K_{t+1} = Ae^{z_t}Kt^{\alpha}$ and plug into toe euler equation (60):

$$\begin{split} \frac{1}{e^{z_t}K_t^{\alpha}-K_{t+1}} &= \beta E_t \left\{ \frac{\alpha e^{z_{t+1}}K_{t+1}^{\alpha-1}}{e^{z_{t+1}}K_{t+1}^{\alpha}-K_{t+2}} \right\} \\ \frac{1}{e^{z_t}K_t^{\alpha}-Ae^{z_t}K^{\alpha}} &= \beta E_t \left\{ \frac{\alpha e^{z_{t+1}}K_{t+1}^{\alpha-1}}{e^{z_{t+1}}K_{t+1}^{\alpha}-Ae^{z_{t+1}}K_{t+1}^{\alpha}} \right\} \\ \frac{1}{e^{z_t}K_t^{\alpha}-Ae^{z_t}K^{\alpha}} &= \beta E_t \left\{ \frac{\alpha K_{t+1}^{\alpha-1}}{K_{t+1}^{\alpha}-AK_{t+1}^{\alpha}} \right\} \\ \frac{1}{(1-A)e^{z_t}K_t^{\alpha}} &= \beta \frac{\alpha K_{t+1}^{\alpha-1}}{(1-A)K_{t+1}^{\alpha}} \\ \frac{1}{e^{z_t}K_t^{\alpha}} &= \beta \frac{\alpha K_{t+1}^{\alpha-1}}{K_{t+1}^{\alpha}} \\ \frac{1}{e^{z_t}K_t^{\alpha}} &= \beta \frac{\alpha}{K_{t+1}} \quad \text{plugging in the guess once more gives} \\ \frac{1}{e^{z_t}K_t^{\alpha}} &= \beta \frac{\alpha}{Ae^{z_t}K_t^{\alpha}} \\ A &= \beta \alpha \end{split}$$

1.2 For the specific functions the equilibrium equations are the following:

$$\frac{1}{c_t} = \beta E_t \left\{ \frac{1}{c_{t+1}} [(r_{t+1} - \delta)(1 - \tau) + 1] \right\}$$

$$a \frac{1}{1 - l_t} = \frac{w_t (1 - \tau)}{c_t}$$

$$r_t = \alpha e^{z_t} \left(\frac{K_t}{L_t} \right)^{\alpha - 1}$$

$$w_t = (1 - \alpha) e^{z_t} \left(\frac{K_t}{L_t} \right)^{\alpha}$$

1.4 Characterizing equations are as follows:

$$c_{t} = (1 - \tau)[w_{t}l_{t} + (r_{t} - \delta)k_{t}] + k_{t} + T_{t} - k_{t+1}$$

$$c_{t}^{-\gamma} = \beta E_{t}[c_{t}^{-\gamma}((r_{t+1} - \delta)(1 - \tau) + 1)]$$

$$a(1 - l_{t})^{-\xi} = c_{t}^{-\gamma}w_{t}(1 - \tau)$$

$$r_{t} = e^{z_{t}}\alpha[\alpha K_{t}^{\eta} + (1 - \alpha)L_{t}^{\eta}]^{\frac{1}{\eta} - 1}K_{t}^{\eta - 1}$$

$$w_{t} = e^{z_{t}}(1 - \alpha)[\alpha K_{t}^{\eta} + (1 - \alpha)L_{t}^{\eta}]^{\frac{1}{\eta} - 1}L_{t}^{\eta - 1}$$

$$T_{t} = \tau[w_{t}l_{t} + (r_{t} - \delta)k_{t}]$$

$$z_{t} = (1 - \rho)\overline{z} + \rho z_{t-1} + \epsilon_{t}^{2}$$

1.5 Solving for the steady States \bar{r} and \bar{K} and plugging in the parameter values from the exercise gives

$$\bar{r} = \frac{1-\beta}{\beta(1-\tau)} + \delta = 0.124$$

$$\bar{k} = \left(\bar{r}^{\frac{1}{\alpha - 1}}\right) \frac{1}{\alpha} = 7.287$$