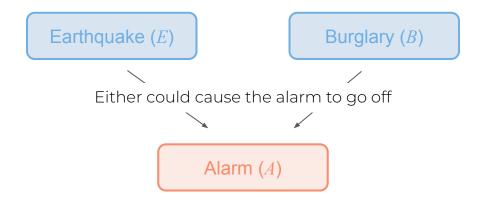
Scallop and Neuro-Symbolic Programming

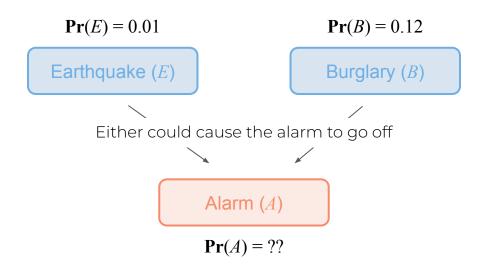
Lecture 2: Tags, Instrumentation, and Provenance

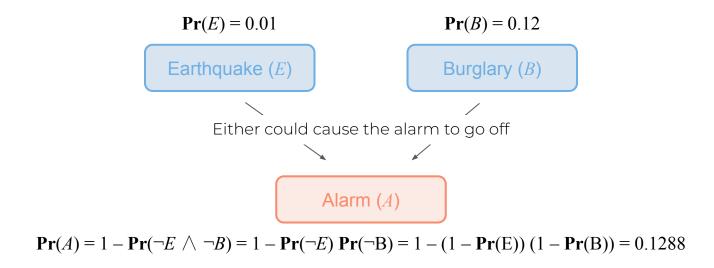
Agenda

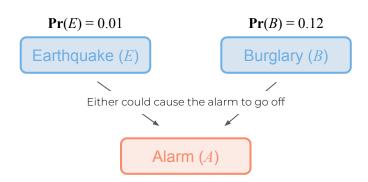
- Using Probabilities in Scallop
 Discrete Reasoning Augmented
- Tagging and Instrumentation
 How to Associate Extra Information when Reasoning
- The Ultimate Tag: Provenance
 Tracking, Recover, and WMC
- Provenance Framework
 Minmaxprob, AddMultProb, TopKProofs, TopBottomKClauses

Scallop: Working with Probabilities

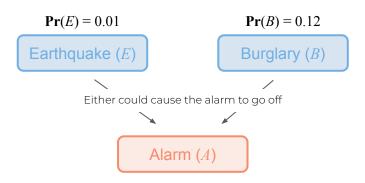








```
rel 0.01::earthquake()
rel 0.12::burglary()
rel alarm() = earthquake() or burglary()
```



```
rel 0.01::earthquake()
rel 0.12::burglary()
rel alarm() = earthquake() or burglary()
```

```
> scli alarm.scl --provenance topkproofs
alarm: {0.1288::()}
```

Tagging and Instrumentation

Proof Tree Revised

```
Pr(E) = 0.01
                                Pr(B) = 0.12
Earthquake (E)
                               Burglary (B)
        Either could cause the alarm to go off
                 Alarm (A)
rel 0.01::earthquake()
rel 0.12::burglary()
rel alarm() = earthquake() or burglary()
```



Proof Tree Revised

```
Pr(E) = 0.01
Pr(B) = 0.12
Earthquake (E)
Either could cause the alarm to go off
Alarm (A)
```

```
rel 0.01::earthquake()
rel 0.12::burglary()
rel alarm() = earthquake() or burglary()
```

```
earthquake() burglary()

alarm()
```

Add Tags to the Facts

```
Pr(E) = 0.01
Pr(B) = 0.12
Earthquake (E)
Either could cause the alarm to go off
Alarm (A)
```

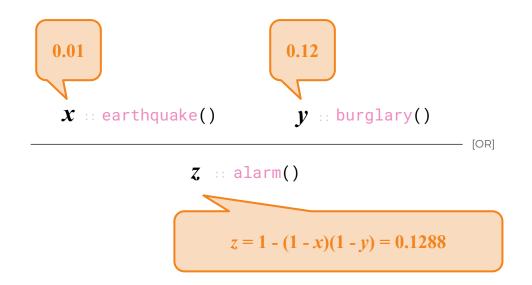
```
rel 0.01::earthquake()
rel 0.12::burglary()
rel alarm() = earthquake() or burglary()
```

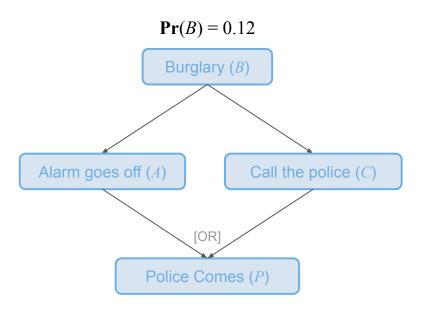
```
m{x} :: \mathsf{earthquake()} \qquad m{y} :: \mathsf{burglary()}  [OR] m{z} :: \mathsf{alarm()}
```

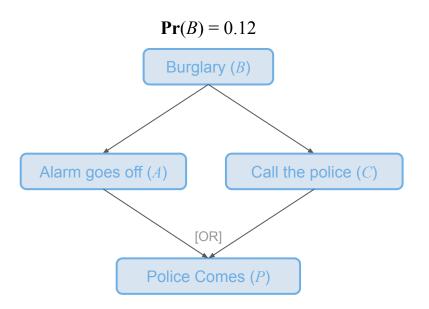
Add Tags to the Facts

```
m{x} :: earthquake() \qquad m{y} :: burglary()
m{z} :: alarm()
```

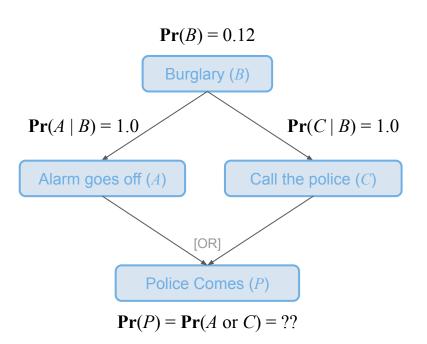
A simple and straightforward approach...



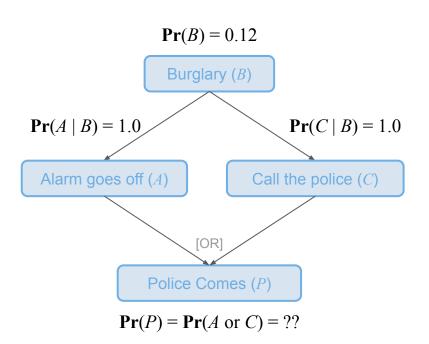


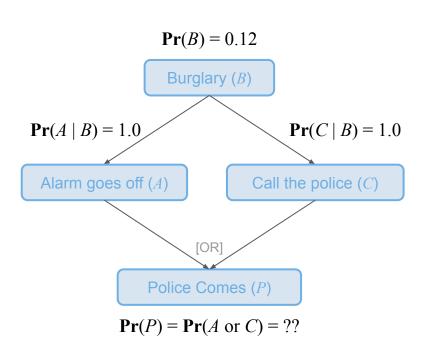


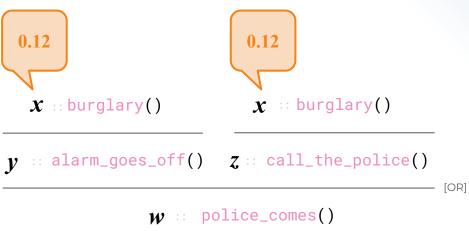
```
rel 0.12::burglary()
rel alarm_goes_off() = burglary()
rel call_the_police() = burglary()
rel police_comes() =
    alarm_goes_off() or call_the_police()
```

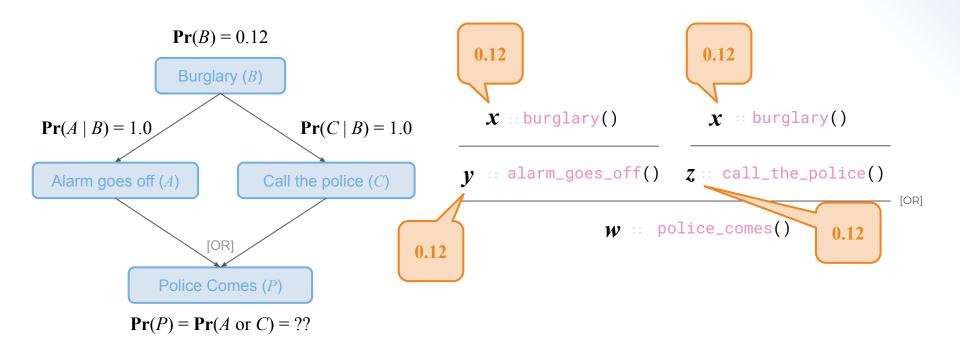


```
rel 0.12::burglary()
rel alarm_goes_off() = burglary()
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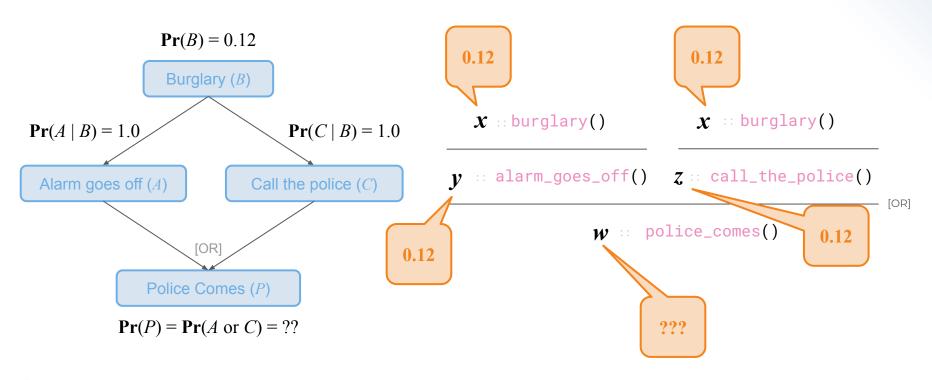




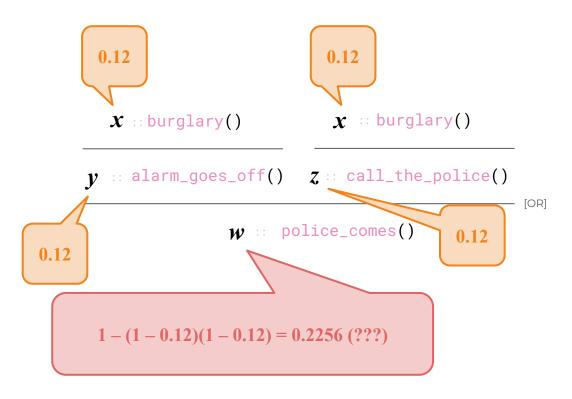




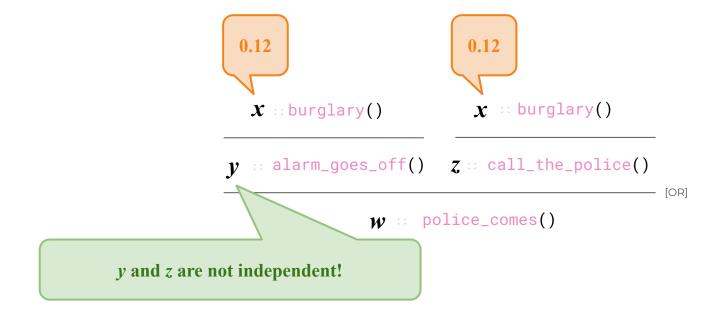












The Ultimate Tag: Provenance

Track how a fact is derived!

Context:
$$B := burglary(), Pr(B) = 0.12$$

$$B :: burglary() \\ \hline B :: alarm_goes_off() \\ \hline B :: call_the_police() \\ \hline P = B \text{ or } B = B :: police_comes()$$

Recover: Pr(P) = Pr(B) = 0.12

Track how a fact is derived!

Context:

$$E := \text{earthquake()}, Pr(E) = 0.01$$

$$B :: burglary(), Pr(B) = 0.12$$

$$E :: earthquake()$$
 $B :: burglary()$

$$A = E \text{ or } B :: alarm()$$

$$Pr(A) = Pr(E \text{ or } B) = 0.1288$$

Boolean Formula as Tag!

- Before running the program, we create boolean variables for each input fact with probability, and store the variables and their probabilities inside a context
- The tag for each input fact would be the boolean variable of itself
- During execution, we use "AND", "OR", and "NOT" to combine these variables into complex boolean formula
- At the end of execution, we recover the probability of the derived fact by performing "Weighted Model Counting (WMC)" on the boolean formula associated with that fact

```
(Boolean Variables) V

(Boolean Formula) F := V

| \operatorname{or}(F, F) |

| \operatorname{and}(F, F) |

| \operatorname{not}(F) |

(Context) \mathbf{C} :: V \to [0, 1]

(WMC) \operatorname{wmc} :: (F, \mathbf{C}) \to [0, 1]
```

```
Each input fact with probability will be assigned a boolean variable in V

(Boolean Formula) F := V

| \text{or}(F, F) |
| \text{and}(F, F) |
| \text{not}(F) |

(Context) C :: V \rightarrow [0, 1]

(WMC) \text{wmc} :: (F, C) \rightarrow [0, 1]
```

```
(Boolean Variables) V
(Boolean Formula) F := V
| \text{ or}(F, F) \\ | \text{ and}(F, F) \\ | \text{ not}(F)
(Context) C :: V \rightarrow [0, 1]
(WMC) V = V
| \text{ wmc} :: (F, C) \rightarrow [0, 1]
```

```
(Boolean Variables) V

(Boolean Formula) F := V

| \text{or}(F, F) |

| \text{and}(F, F) |

| \text{not}(F) |

(Context) C :: V \rightarrow [0, 1]

(WMC) \text{wmc} :: (F, C) \rightarrow [0, 1]
```

```
(Boolean Variables) V

(Boolean Formula) F := V

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| \operatorname{and}(F, F) |

| \operatorname{not}(F) |

(Context) C :: V \to [0, 1]

(WMC) V \to [0, 1]

A context is a mapping from each boolean variable to its probability
```

```
(Boolean Variables) V

(Boolean Formula) F := V

| \operatorname{or}(F, F) |

| \operatorname{and}(F, F) |

| \operatorname{not}(F) |

(Context) \mathbf{C} :: V \to [0, 1]

(WMC) wmc :: (F, \mathbf{C}) \to [0, 1]
```

Weighted Model Counting is a method that can compute the probability of a boolean formula being true, based on the context

Example: The sum of two probabilistic digits

```
rel digit_1 = {0.01::0; 0.01::1; 0.98::2}
rel digit_2 = {0.02::0; 0.97::1; 0.01::2}
rel sum_of_digits(x + y) = digit_1(x) and digit_2(y)
```

Example: The sum of two probabilistic digits

```
rel digit_1 = {0.01::0; 0.01::1; 0.98::2}
rel digit_2 = {0.02::0; 0.97::1; 0.01::2}
rel sum_of_digits(x + y) = digit_1(x) and digit_2(y)
                                sum_of_digits(0)
                                sum_of_digits(1)
                                sum_of_digits(2)
```



Example: The sum of two probabilistic digits

```
rel digit_1 = {0.01::0; 0.01::1; 0.98::2}
rel digit_2 = {0.02::0; 0.97::1; 0.01::2}
rel sum_of_digits(x + y) = digit_1(x) and digit_2(y)
```

```
(digit_1(0) and digit_2(0)) :: sum_of_digits(0)

(digit_1(0) and digit_2(1)) or
(digit_1(1) and digit_2(0)) :: sum_of_digits(1)

(digit_1(0) and digit_2(2)) or
(digit_1(2) and digit_2(0)) or
(digit_1(1) and digit_2(1)) :: sum_of_digits(2)
```



Example: The sum of two probabilistic digits

```
rel digit_1 = {0.01::0; 0.01::1; 0.98::2}
rel digit_2 = {0.02::0; 0.97::1; 0.01::2}
rel sum_of_digits(x + y) = digit_1(x) and digit_2(y)
```

```
sum_of_digits: {
    0.0002::(0),
    0.00989806::(1),
    0.029206969011999998::(2),
    0.950604939999998::(3),
    0.0098::(4)
}
```



Provenance Framework

Full Boolean Formula is Exact and Perfect, but...

- The Weighted Model Counting is a very time consuming task!
 - Model: Solution to a propositional boolean formula
 - Model Counting: Number of solutions to a propositional boolean formula
 - #SAT: #P-Complete Problem
 - Weighted Model Counting: "number of solutions" with weights assigned to each boolean variable
- Scallop, paired with a deep neural network, needs to reason about hundreds of facts for each data-point, while there could be thousands of data-points per dataset
 - Performance is a huge issue!

The need for a generalized framework

- We cannot afford to perform the exact probabilistic reasoning with full provenance
- However, there are many approximation algorithms that can also facilitate differentiable and probabilistic reasoning, and can yield good learning outcome
- Therefore, we want to design a generalized framework for instrumenting arbitrary tag for differentiable and probabilistic reasoning
- And we get customizability and scalability!

The need for a generalized framework

- We cannot afford to perform the exact probabilistic reasoning with full provenance
- However, there are many approximation algorithms that can also facilitate differentiable and probabilistic reasoning, and can yield good learning outcome
- Therefore, we want to design a generalized framework for instrumenting arbitrary tag for differentiable and probabilistic reasoning
- And we get customizability and scalability!

(Extended) **Provenance Semiring Framework**

Add Tags to the Facts

We let the tags associated with the facts $x, y, z \in T$, where T is a set of all possible tags, which we call $Tag\ Space$

Propagation of Tags through OR

For this Tag Space T, we define a binary operation \oplus to combine two tags when they are "OR"-ed together:

$$x :: earthquake()$$
 $y :: burglary()$

$$x \oplus y :: alarm()$$

Propagation of Tags through AND

For this Tag Space T, we define a binary operation \otimes to combine two tags when they are "AND"-ed together:

```
m{x}:: father("John", "Alice") m{y}:: mother("Alice", "Bob") \hfill & m{x} \otimes m{y}:: grandfather("John", "Bob") \hfill & m{x} \otimes m{x} \otimes m{y}:: grandfather("John", "Bob") \hfill & m{x} \otimes m{y}:: grandfather("John", "Bob
```

Propagation of Tag through Negation

For this Tag Space T, we define a unary operation Θ to negate a tag

True and False Tag

For this Tag Space T, we need additionally two elements that serves as "True" (1) and "False" (0):

They should have the following properties:

- \oplus (1, X) = 1
- \oplus (0, X) = X
- \otimes (1, X) = X
- $\otimes (0, X) = 0$

Provenance Framework for Probabilistic Reasoning

Example: Add/Mult Probability

Definition:

```
T := [0, 1]
0 := 0
1 := 1
\Phi(x, y) = min(1, x + y)
\otimes(x, y) = x \times y
\Theta(x) = 1 - x
```

```
0.01 :: earthquake() 0.12 :: burglary()
\oplus (0.01, 0.12) = min(1, 0.01 + 0.12) :: alarm()
= 0.13
```

Example: Min/Max Probability

Definition:

```
T ::= [0, 1]

0 ::= 0

1 ::= 1

\Phi ::= \Phi(x, y) = max(x, y)

\Phi ::= \Theta(x, y) = min(x, y)

\Phi ::= \Theta(x) = 1 - x
```

```
0.01 :: earthquake() 0.12 :: burglary() 0.01 :: alarm()
```

Example: Proofs (DNF Formula)

Definition:

```
T ::= P(P(V))
0 ::= \{\}
1 ::= \{\{\}\}\}
\Phi(X, Y) = X \cup Y
\otimes(X, Y) = \{P \cup Q \text{ for } P \in X, Q \in Y\}
\Phi(\text{Undefined})
```

```
rel digit_1 = {0.01::0; 0.01::1; 0.98::2}
rel digit_2 = {0.02::0; 0.97::1; 0.01::2}
rel sum_of_digits(x + y) = digit_1(x) and digit_2(y)

sum_of_digits(1):
    - Formula: (d1(0) and d2(1)) or (d1(1) and d2(0))
    - Tag: {{d1(0), d2(1)}, {d1(1), d2(0)}}
```

Example: Proofs (DNF Formula)

Definition:

```
T ::= P(P(V))
0 ::= \{\}
1 ::= \{\{\}\}\}
\Phi(X, Y) = X \cup Y
\otimes(X, Y) = \{P \cup Q \text{ for } P \in X, Q \in Y\}
\Theta(\text{Undefined})
```

Example:

```
rel digit_1 = {0.01::0; 0.01::1; 0.98::2}
rel digit_2 = {0.02::0; 0.97::1; 0.01::2}
rel sum_of_digits(x + y) = digit_1(x) and digit_2(y)
```

```
sum_of_digits(1):
    - Formula: (d1(0) and d2(1)) or (d1(1) and d2(0))
    - Tag: {{d1(0), d2(1)}, {d1(1), d2(0)}}
```

This provenance is only defined on positive Scallop program



Example: Top-k Proofs (DNF Formula)

Definition:

```
T ::= P(P(V))
0 ::= {}
1 ::= {{}}
\Phi(X, Y) = \text{top-k}(X \cup Y)
⊗(X, Y) = top-k({P \cup Q \text{ for } P \in X, \ Q \in Y})
\Phi(\text{Undefined})
```