

Take Me Out to (Analyze) the Ballgame

Visualization and Analysis Techniques for Big Spatial Data

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Oregon State University

August 31, 2017

Baseball, Baseball, Baseball

- Chris, rookie year

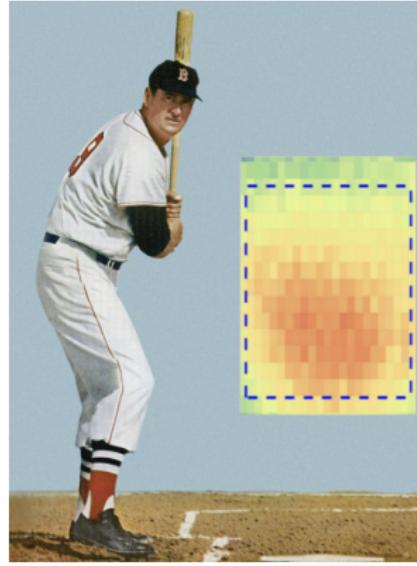
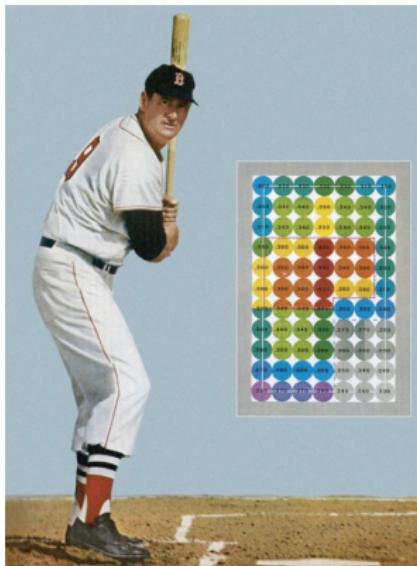


- Chris, Boston Red Sox



Hitting Analytics

- “The Science of Hitting”₁₉₇₀
- The Statistics of Hitting



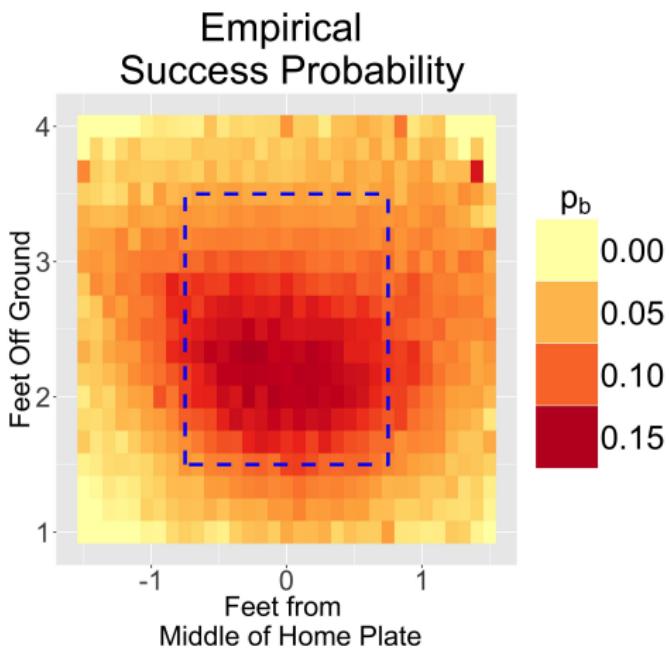
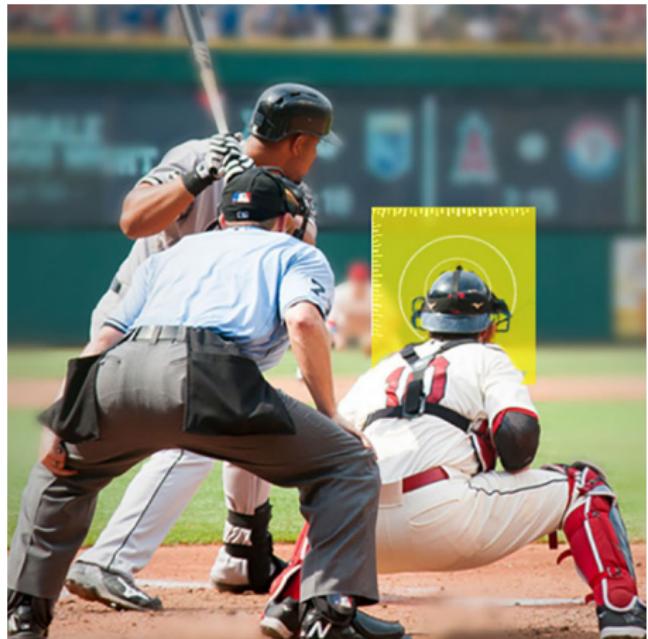
- Iconic breakthrough, hitter
- No data

- PITCHf/x data, R, heat maps
- SGLMMs, Stan, PPMs, INLA

Outline

- 1 Variable-Resolution Heat Maps
- 2 Interactive Heat Map Confidence Intervals
- 3 Approaches to Big Data Spatial Mixed Models for Baseball Data
 - Computational Optimization in Stan
 - Predictive Process Models
 - Integrated Nested Laplace Approximation

Empirical Success Probability Heat Map



Empirical Success Probability Heat Map

- Swings: $i = 1, 2, \dots, N$

- Bernoulli(π_i) trials:

$$S_i = \begin{cases} 1; & \text{swing success} \\ 0; & \text{swing failure} \end{cases}$$

- Location (x_i, y_i)

- Grid boxes G_1, G_2, \dots, G_B

- Box b totals:

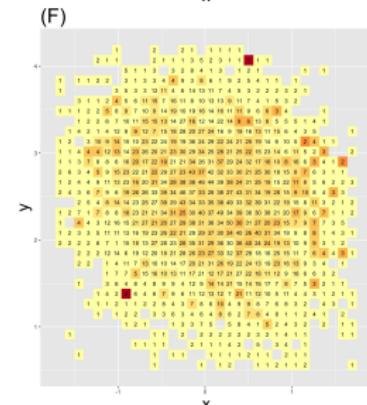
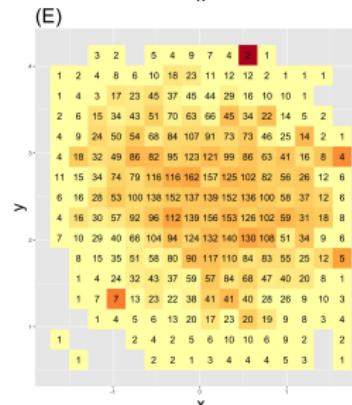
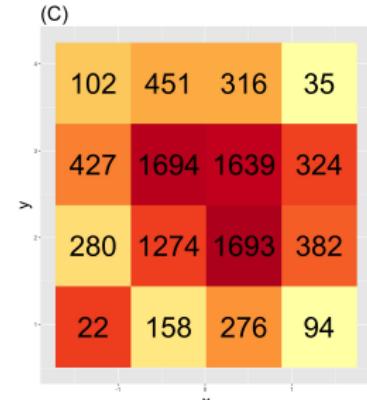
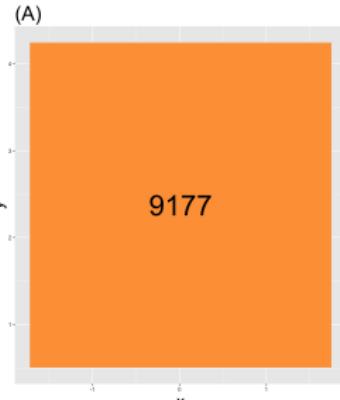
$$N_b = \sum_{i=1}^N I_{(x_i, y_i) \in G_b}$$

- Box b empirical success:

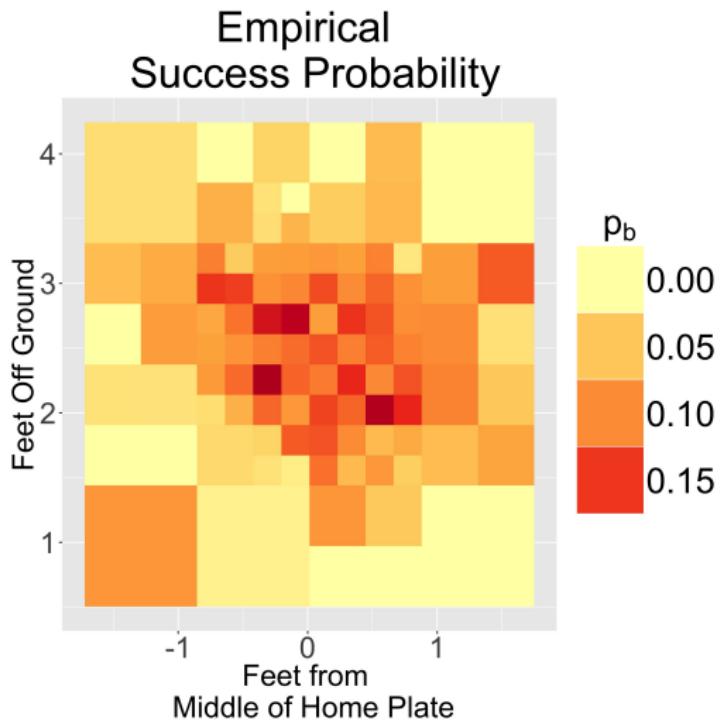
$$p_b = \frac{1}{N_b} \sum_{i=1}^N S_i I_{(x_i, y_i) \in G_b}$$

Heat Map Resolution Selection

Jhonny Peralta



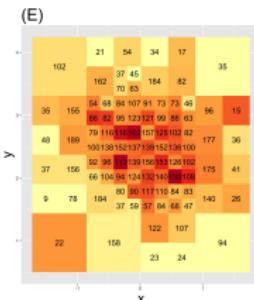
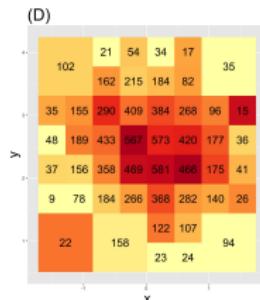
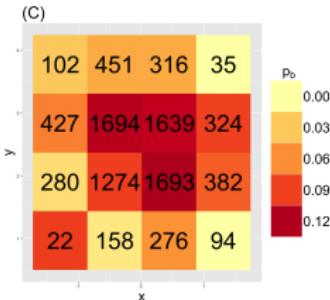
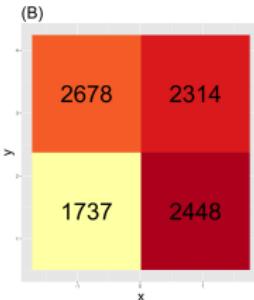
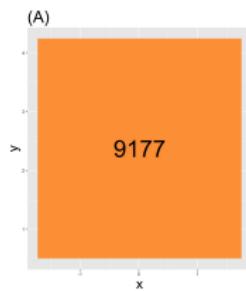
A Thing of Beauty



Variable-Resolution Heat Maps

Jhonny Peralta

- VR algorithm
 - ▶ Stopping rule
 - ▶ Subdivision method



Variable-Resolution Heat Maps

Combine Resolutions

- Sample size stopping rule
- Combine resolutions
- Resolution conveys varying data abundance
- Improvements:
 - ▶ .**gif** option
 - ▶ Alternate stopping rule types
 - ▶ Alternate subdivision method

varyres(...) in **varyres**

`varyres {varyres}`

R Documentation

A variable-resolution heat map generator

Description

This function creates variable resolution heat maps according to a stopping rule

Usage

```
varyres(dataset, cutoff, fun = mean, max = 6)
```

Arguments

dataset data frame with spatial data: x-coordinates (x), y coordinates (y), and Bernoulli responses at those locations (res)

cutoff Box subdivisions cease when a box sample size drops below the cutoff

fun Function to apply to responses in each box

max The maximum number of subdivision iterations the algorithm will perform

Value

A list containing a data frame for each iteration of the subdivision algorithm; and a vector of the number of boxes eligible for subdivision at each iteration.

Examples

```
data(hitter)
data <- varyres(hitter, mean, cutoff = 200, max = 6)
mapit(data[[4]])
```

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Generalized Linear Model

$$Y_i | \mathbf{X}_i(\mathbf{s}_i) \stackrel{\text{ind}}{\sim} \text{Bernoulli}(\pi_i)$$

$$\text{logit}(\pi_i | \mathbf{s}_i) = \mathbf{X}_i(\mathbf{s}_i)\beta$$

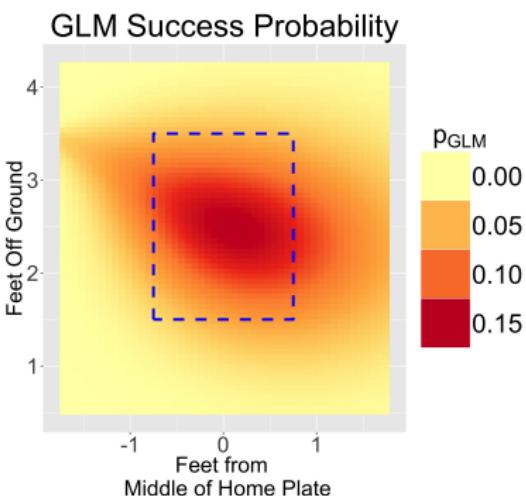
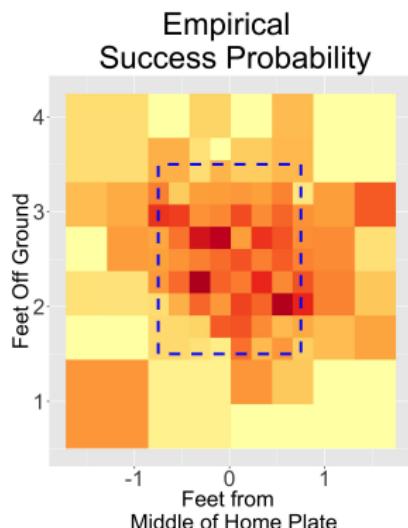
- Swings: $i = 1, 2, \dots, N$
- Pitch location: $\mathbf{s}_i = (x_i, y_i)$
- Biomechanical covariates: $\mathbf{X}_i(\mathbf{s}_i)$
- Fit to Jhonny Peralta data

Logistic Regression Model

Jhonny Peralta

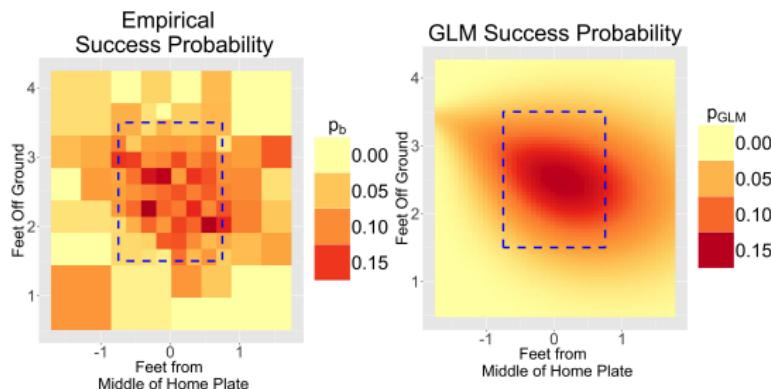
$$Y_i | \mathbf{X}_i(\mathbf{s}_i) \stackrel{\text{ind}}{\sim} \text{Bernoulli}(\pi_i)$$

$$\text{logit}(\pi_i | \mathbf{s}_i) = \mathbf{X}_i(\mathbf{s}_i)\beta,$$



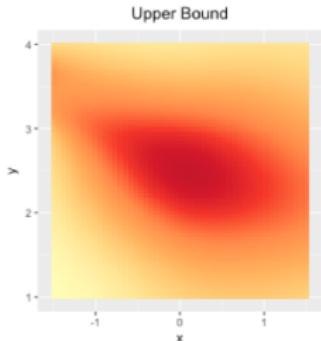
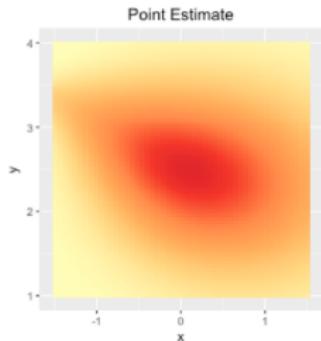
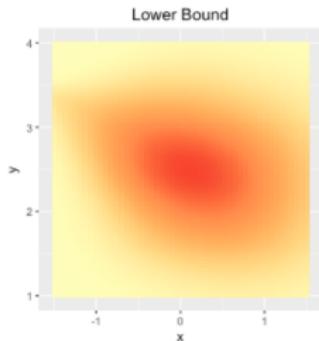
Logistic Regression Model

Jhonny Peralta



- Hosmer-Lemeshow (logistic regression) GOF test
 - ▶ H_0 : Well fit
 - ▶ H_A : Lack of fit
 - ▶ p-value = 0.8217
- Confidence intervals

Interactive Confidence Intervals



This is the 99 % confidence interval layer.

Confidence Interval



mapapp: An R Package

mapapp: An R Package

- Challenge: Where does user stop and package begin?
- Future improvement

```
all_in_one <- get_CI(model, x, y, levels)
shinyHMCI(all_in_one)
```

- ➊ `get_CI(...)` — creates proper data structure
- ➋ `shinyHMCI(all_in_one)` — creates Shiny app
...and **.gif** option.

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Spatial Generalized Linear Mixed Model (SGLMM)

$$Y_i | \mathbf{X}_i(\mathbf{s}_i) \stackrel{\text{ind}}{\sim} \text{Bernoulli}(\pi_i)$$

$$\text{logit}(\pi_i | \mathbf{s}_i) = \mathbf{X}_i(\mathbf{s}_i)\boldsymbol{\beta} + w(\mathbf{s}_i)$$

- $w(\mathbf{s}_i)$ — spatial random effect, location \mathbf{s}_i .
- $w(\mathbf{s}) = (w(\mathbf{s}_1), w(\mathbf{s}_2), \dots, w(\mathbf{s}_N))$ — vector
- $w(\mathbf{s})$ - Gaussian Random Field (GRF)

Gaussian Random Field: $\mathbf{w}(\mathbf{s})$

$$\mathbf{w}(\mathbf{s})|\boldsymbol{\theta} \sim \text{MVN}(\mathbf{0}, \Sigma(\boldsymbol{\theta}))$$

$$\Sigma(\phi, \sigma^2)_{i,k} = \sigma^2 \exp(-||\mathbf{s}_i - \mathbf{s}_k||/\phi)$$

- Spatial exponential covariance
 - ▶ $||\mathbf{s}_i - \mathbf{s}_k||$ - Euclidean distance
 - ▶ σ^2 - scale parameter
 - ▶ ϕ - range parameter.
- Notice: $\Sigma(\boldsymbol{\theta}) — n \times n$

Computational Cost: “Big N” Problem

- Peralta: $n = 9177$
- $\mathbf{w}(\mathbf{s})$: 9177×9177 cov. matrix
- MCMC iterations require: Σ^{-1} , determinant of Σ
- $\mathcal{O}(n^3)$ rate of increase:

$$t(n) \leq M \cdot n^3$$

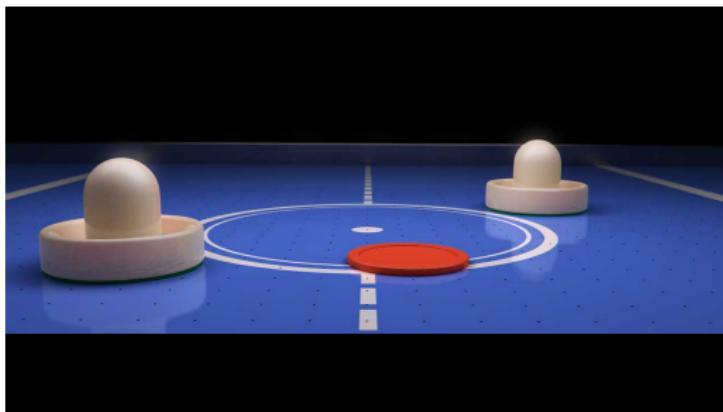
as $n \rightarrow \infty$

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Hamiltonian Monte Carlo (HMC)

- Stan uses Hamiltonian proposal mechanism
 - ➊ Disk on surface, with position (β, θ) and momentum
 - ➋ Randomly sample momentum (auxiliary)
 - ➌ Calculate new position (parameters)
 - ➍ That's your Metropolis proposal.



Stan Computational Optimization

- ϕ, β : informative/proper priors \rightarrow identifiability/cost/convergence
- QR factorization of X, Cholesky decomposition of $\Sigma(\theta)$
- Matrices & vectors faster than loops & scalars
- n = 25: 40 seconds \rightarrow 3 seconds
- n = 2000 — overnight, 350 draws



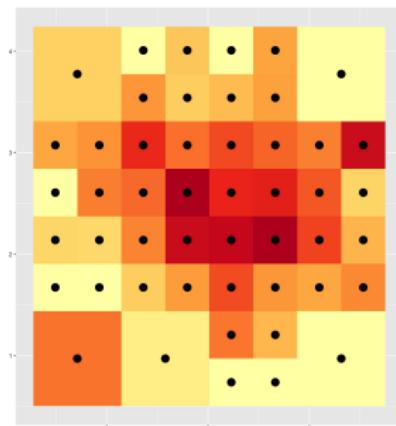
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 - **Predictive Process Models**
 - Integrated Nested Laplace Approximation

Predictive Process Models (PPMs)

[Banerjee et al., 2008]

- Knots: $\mathbf{S}^* = \{\mathbf{s}_1^*, \dots, \mathbf{s}_m^*\}$
 - ▶ $m \ll n$



$$\text{logit}(\pi_i | \mathbf{s}_i) = \mathbf{X}_i(\mathbf{s}_i)\boldsymbol{\beta} + \tilde{\mathbf{w}}(\mathbf{s}_i)$$

$$\tilde{\mathbf{w}}(\mathbf{s}) \sim \text{MVN}\{0, \tilde{\Sigma}(\boldsymbol{\theta})\}$$

$$\tilde{\Sigma}(\boldsymbol{\theta})_{i,j} = \sigma^{*T}(\mathbf{s}_i; \boldsymbol{\theta}) \cdot \Sigma^{*-1}(\boldsymbol{\theta}) \cdot \sigma^*(\mathbf{s}_j; \boldsymbol{\theta})$$

- $\sigma^*(\mathbf{s}_i; \boldsymbol{\theta}) = \text{Cov}(\mathbf{s}_i, \mathbf{S}^*)$

- $\Sigma^*(\boldsymbol{\theta}) = \text{Var}(\mathbf{S}^*)$

PPM Results

- Implement in **spBayes** [Finley et al., 2013].
- MCMC chains **did not converge** — trace-plots:



- ▶ $n = 1000$, knots = 97, 10K samples, ≈ 6.7 mins
- ▶ $n = 1000$, knots = 49, 30K samples, ≈ 7 mins
- ▶ $n = 3000$, knots = 49, 80K samples, ≈ 54 mins
- Speed issue for extending MCMC chains

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Integrated Nested Laplace Approximation (INLA)

[Rue et al., 2009]

$$\text{logit}(\pi_i) = \mathbf{X}_i(\mathbf{s}_i)\boldsymbol{\beta} + \mathbf{w}(\mathbf{s}_i)$$

$$\mathbf{w}(\mathbf{s})|\boldsymbol{\theta} \sim \text{MVN}(\mathbf{0}, \boldsymbol{\Sigma}(\boldsymbol{\theta}))$$

- Assume Matérn covariance
- Two parts (continuous domain)
 - ▶ Part 1: Stochastic Partial Differential Equation (SPDE)
 - ▶ Part 2: Integrated Nested Laplace Approximation (INLA)



INLA: Step 1

- Parameter vector: $\rho = (\beta^T, \tilde{w}^T)^T$
 - ▶ Q : precision matrix of ρ
- Hyperparameter vector: $\theta = (\kappa, \sigma)$

① Gaussian approximation:

$$p(\rho|\theta, y) \propto p(y|\rho, \theta)p(\rho|\theta)p(\theta)$$

$$p(\rho|\theta, y) \propto \exp\left(-\frac{1}{2}\rho^T Q \rho + \sum_i \log p(y_i|\rho, \theta)\right)$$

$$p_G(\rho|\theta, y) \propto \exp\left(-\frac{1}{2}(\rho - \mu)^T (Q + \text{diag}(c))(\rho - \mu)\right)$$

- ▶ Gaussian kernel: c and μ depend on second order Taylor expansions of $f(\rho) = \sum_i \log p(y_i|\rho, \theta)$

INLA: Step 2

- Fact: $P(A, B) = P(A|B)P(B) = P(B|A)P(A)$

$$p(\boldsymbol{y}|\boldsymbol{\theta}) = \frac{p(\boldsymbol{y}|\boldsymbol{\rho}, \boldsymbol{\theta})p(\boldsymbol{\rho}|\boldsymbol{\theta})}{p(\boldsymbol{\rho}|\boldsymbol{y}, \boldsymbol{\theta})}$$

- Bayes proportionality:

$$\begin{aligned} p(\boldsymbol{\theta}|\boldsymbol{y}) &\propto p(\boldsymbol{y}|\boldsymbol{\theta})p(\boldsymbol{\theta}) \\ &\propto \frac{p(\boldsymbol{y}|\boldsymbol{\rho}, \boldsymbol{\theta})p(\boldsymbol{\rho}|\boldsymbol{\theta})}{p(\boldsymbol{\rho}|\boldsymbol{y}, \boldsymbol{\theta})} \cdot p(\boldsymbol{\theta}) \end{aligned}$$

- For a given $\boldsymbol{\theta}$, let $\boldsymbol{\rho}_0 = \operatorname{argmax}_{\boldsymbol{\rho}} p(\boldsymbol{\rho}|\boldsymbol{y}, \boldsymbol{\theta})$. Then,

$$\tilde{p}(\boldsymbol{\theta}|\boldsymbol{y}) \propto \frac{p(\boldsymbol{y}|\boldsymbol{\rho}_0, \boldsymbol{\theta})p(\boldsymbol{\rho}_0|\boldsymbol{\theta})}{p_G(\boldsymbol{\rho}_0|\boldsymbol{y}, \boldsymbol{\theta})} \cdot p(\boldsymbol{\theta})$$

INLA: Step 2

- Fact: $P(A, B) = P(A|B)P(B) = P(B|A)P(A)$

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INLA: Step 3 & Step 4

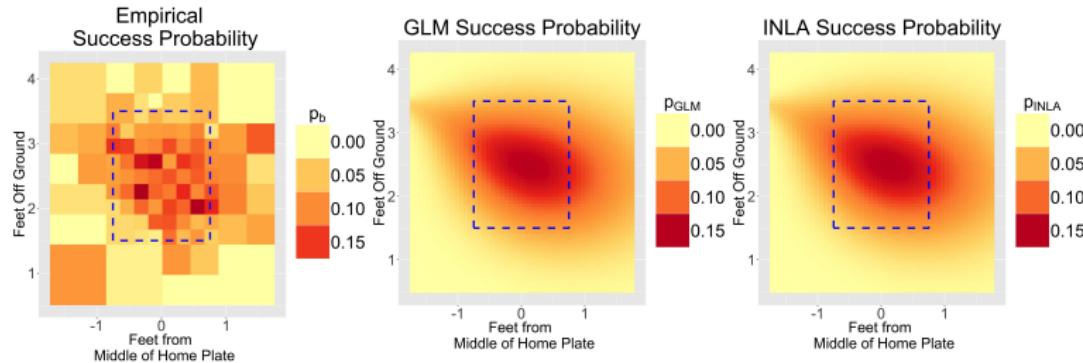
③ Numerical integration:

$$p(\rho_j | \mathbf{y}) \approx \int p_G(\rho_j | \boldsymbol{\theta}, \mathbf{y}) \tilde{p}(\boldsymbol{\theta} | \mathbf{y}) d\boldsymbol{\theta}$$

④ Numerical integration:

$$p(\theta_k | \mathbf{y}) \approx \int \tilde{p}(\boldsymbol{\theta} | \mathbf{y}) d\boldsymbol{\theta}_{-k}$$

INLA Model Fit: 34 seconds



| INLA | | |
|----------|----------------|----------------------------------|
| ρ_i | $\hat{\rho}_i$ | SE |
| κ | 3.23 | $\pm 1 \text{ SE}: (1.35, 7.54)$ |
| σ | 0.11 | $\pm 1 \text{ SE}: (0.05, 0.26)$ |

- $\hat{\kappa}$ — long range correlation
- $\text{SE}(w(\mathbf{s})) = 0.11$.
- $p_i = 0.15 \rightarrow p_i \pm 1 \cdot \text{SE} = (0.137, 0.165)$
- $p_i = 0.15 \rightarrow p_i \pm 2 \cdot \text{SE} = (0.125, 0.181)$

Summary

- Resolution selection? Variable-resolution heat maps and **varyres**
- Heat map confidence intervals? Interactive HMCIs and **mapapp**
- Fitting big data SGLMMs to baseball data?
 - ▶ Stan - inadequate
 - ▶ PPM - Slow and did not converge
 - ▶ INLA - Fast, successful(?); to be continued...

Thanks for listening.

Sudipto Banerjee, Alan E Gelfand, Andrew O Finley, and Huiyan Sang.
Gaussian predictive process models for large spatial data sets.
Journal of the Royal Statistical Society: Series B (Statistical Methodology), 70(4):825–848, 2008.

Andrew O Finley, Sudipto Banerjee, and Alan E Gelfand. spbayes for large univariate and multivariate point-referenced spatio-temporal data models. *arXiv preprint arXiv:1310.8192*, 2013.

Håvard Rue, Sara Martino, and Nicolas Chopin. Approximate bayesian inference for latent gaussian models by using integrated nested laplace approximations. *Journal of the royal statistical society: Series b (statistical methodology)*, 71(2):319–392, 2009.

Finn Lindgren, Håvard Rue, and Johan Lindström. An explicit link between gaussian fields and gaussian markov random fields: the stochastic partial differential equation approach. *Journal of the Royal Statistical Society: Series B (Statistical Methodology)*, 73(4):423–498, 2011.

Moving Forward

- Improve packages
- Submit packages to CRAN
- Learn a LOT more about INLA results, estimates, standard errors
- Biomechanists at OSU
- Compare GLM and SGLMM with scoring rules
- Exit velocity as response variable
- Independence assumption, pitch sequences
- Randomized pitch selection

If I knew then...

- Skip UNC
- Start research → start packages
- Use courses to practice writing, get feedback, etc.
- Emphasize literature review
- Exit velocity as response???

Glad I did know...

- “Write and show as you go.”
- Growth mindset

Responsibilities

- Reproducibility.
- Acknowledge uncertainty.
- Honesty
 - ▶ Expertise
 - ▶ Data
 - ▶ Methods
 - ▶ Results
- Warren Buffet anecdote

Important Theorems

- Law of Large Numbers - “Guarantees stable, long term results for random events.”
- Central Limit Theorem
- Bayes Theorem
- Taylor’s Theorem
- Ito’s Lemma - stochastic calculus, mathematical finance, Black-Scholes, options pricing!

GLM Confidence Intervals

Asymptotically...

- $E(\hat{\beta}) = \beta$
- $\text{Var}(\beta) = (\mathbf{X}^\top \hat{\mathbf{V}} \mathbf{X})^{-1}$
 - ▶ $\hat{\mathbf{V}}_{i,i} = p_i(1 - p_i)$

Variable-Resolution Algorithm

Pseudo-code

- * Keep track of three containers: History, Current, Iteration

```
function(dataset,  
        fun = mean, # function to apply to box data  
        cutoff,      # stopping rule threshold  
        max ) {      # maximum number of iterations
```

```
HISTORY_CONTAINER # store iterative results
```

```
CURRENT_CONTAINER: box centers, statistic,  
                    box observations, box heights/widths,  
                    box vert/horiz, upper/lower bounds
```

```
Add CURRENT_CONTAINER to HISTORY_CONTAINER
```

Variable-Resolution Algorithm

Pseudo-code

```
WHILE(exists N_b > cutoff and ITERATION < max) {  
    ITERATION CONTAINER <- list()  
  
    FOR(All BOX_b in CURRENT CONTAINER) {  
        IF(BOX_b count > cutoff) {  
  
            Retrieve BOX_b data, subdivide/calculate  
            BOX_b sub-box info, add to  
            ITERATION CONTAINER  
        }  
    }  
    Update CURRENT_CONTAINER: remove obsolete boxes,  
    add ITERATION CONTAINER boxes  
    Add CURRENT CONTAINER to HISTORY CONTAINER  
}
```

HMC, Longer Version

- $H(q(t), p(t)) = U(q(t)) + K(p(t))$
- Total energy of a system
- t = time
- q = position (variables of interest), U = potential energy
- p = momentum (auxiliary), K = kinetic energy
- $H(q, p) = -\log f_q(q) + p^T \mathbf{M}^{-1} p / 2$
- Tidy partial derivatives

Stan Optimization

- QR factorization of X

$$X = QR$$

$$X\beta = QR\beta \rightarrow \text{Let } \theta = R\beta$$

$$X\beta = Q\theta$$

$$\beta = R^{-1}\theta$$

- Cholesky decomposition of $\Sigma(\theta)$

```
L = cholesky_decompose(Sigma);  
Z ~ normal(0, 1);  
Z_mod = L * Z;  
Y ~ bernoulli_logit(Q*theta + Z_mod);
```

Stan Model Fitting

- N = 1000: 7 hours 45 mins for 1500 draws
 - ▶ Note: GLM (w/o spatial effect): 6 seconds.
- N = 2000 overnight, 350 draws



Predictive Process Models (PPMs)

[Banerjee et al., 2008]

- Cov $(w(\mathbf{s}_i), w(\mathbf{s}_k)) = \Sigma(\mathbf{s}_i, \mathbf{s}_k; \boldsymbol{\theta}) = [\Sigma(\mathbf{s}_i, \mathbf{s}_k; \boldsymbol{\theta})]_{i,k=1}^n$
- Knots: $\mathbf{S}^* = \{\mathbf{s}_1^*, \dots, \mathbf{s}_m^*\}$
 - ▶ $m << n$
- Knot random effects: $\mathbf{w}^* = [w(\mathbf{s}_i^*)]_{i=1}^m$
- Knot GRF: $\mathbf{w}^* | \boldsymbol{\theta} \sim \text{MVN}\{\mathbf{0}, \Sigma^*(\boldsymbol{\theta})\}$ — m -dim
 - ▶ Knot covariance: $\Sigma^*(\boldsymbol{\theta}) = [\Sigma(\mathbf{s}_i^*, \mathbf{s}_k^*)]_{i,k=1}^m$
- $\sigma(\mathbf{s}_0; \boldsymbol{\theta}) = [\Sigma(\mathbf{s}_0, \mathbf{s}_k^*; \boldsymbol{\theta})]_{k=1}^m$ — $m \times 1$ vector

PPM Kriging

- $\sigma(\mathbf{s}_0; \boldsymbol{\theta}) = [\Sigma(\mathbf{s}_0, \mathbf{s}_k^*; \boldsymbol{\theta})]_{k=1}^m$ — $m \times 1$ vector
 - ▶ Cov($w(\mathbf{s}_0)$, knots)
- $\tilde{w}(\mathbf{s}_0)$ - interpolated random effect

$$\begin{aligned}\tilde{w}(\mathbf{s}_0) &= E[w(\mathbf{s}_0) | \mathbf{w}^*] \\ &= \boldsymbol{\sigma}^T(\mathbf{s}_0; \boldsymbol{\theta}) \cdot \boldsymbol{\Sigma}^{*-1}(\boldsymbol{\theta}) \cdot \mathbf{w}^*\end{aligned}$$

- Spatially varying linear combination
- Minimizes squared error loss function (linear predictors, GRFs)

Now replace $w(\mathbf{s}_i)$ with $\tilde{w}(\mathbf{s}_i)$.

The Predictive Process: $\tilde{w}(\mathbf{s})$

Another Gaussian Random Field

$$\begin{aligned}\tilde{\mathbf{w}}(\mathbf{s}) &\sim \text{MVN}\{0, \tilde{\Sigma}(\cdot)\} \\ \tilde{\Sigma}(\mathbf{s}, \mathbf{s}'; \boldsymbol{\theta}) &= \boldsymbol{\sigma}^T(\mathbf{s}; \boldsymbol{\theta}) \cdot \boldsymbol{\Sigma}^{*-1}(\boldsymbol{\theta}) \cdot \boldsymbol{\sigma}(\mathbf{s}'; \boldsymbol{\theta})\end{aligned}$$

Predictive process model:

$$\text{logit}(\pi_i | \mathbf{s}_i) = \mathbf{X}_i(\mathbf{s}_i)\boldsymbol{\beta} + \tilde{w}(\mathbf{s}_i)$$

- Note dimension of covariance matrix.
- Implement in **spBayes** [Finley et al., 2013].
- Convergence problems

Part 1: Stochastic Partial Differential Equation (SPDE)

[Lindgren et al., 2011]

- Goal: Represent Matérn GRF as GMRF
- SPDE:

$$(\kappa^2 - \Delta) \mathbf{w}(\mathbf{s}) = \mathbf{W}(\mathbf{s})$$

- Finite Element Method: project SPDE onto basis representation
- Piecewise linear basis representation

$$\tilde{\mathbf{w}}(\mathbf{s}) = \sum_k \psi_k(\mathbf{s}) \omega_k$$

- ▶ Domain triangulation
- ▶ $\psi_k(\mathbf{s})$ — deterministic basis functions
- ▶ ω_k — weights, explicit with sparse precision matrix

Part 1: Stochastic Partial Differential Equation (SPDE)

[Lindgren et al., 2011]

- For $\langle f(\mathbf{u}), g(\mathbf{u}) \rangle = \int f(\mathbf{u})g(\mathbf{u})d\mathbf{u}$:

$$\left[\left\langle \phi_I, (\kappa^2 - \Delta) \tilde{\mathbf{w}} \right\rangle \right]_I \stackrel{D}{=} [\langle \phi_I, \mathbf{W} \rangle]_I$$

- Galerkin solution, $\phi = \psi$:

$$\left[\left\langle \psi_I, (\kappa^2 - \Delta) \left(\sum_{k=1}^{n_v} \psi_k \omega_k \right) \right\rangle \right]_I \stackrel{D}{=} [\langle \psi_I, \mathbf{W} \rangle]_I$$

$$(\kappa^2 \mathbf{C} + \mathbf{G}) \omega \stackrel{D}{=} \mathcal{N}(\mathbf{0}, \mathbf{C})$$

where $\mathbf{C} = \langle \psi_I, \psi_k \rangle$ and $\mathbf{G} = \langle \psi_I, -\Delta \psi_k \rangle$

- $\omega \sim \mathcal{N}(\mathbf{0}, \mathbf{Q}^{-1})$ for

$$\mathbf{Q} = (\kappa^2 \tilde{\mathbf{C}} + \mathbf{G})^T \mathbf{C}^{-1} (\kappa^2 \tilde{\mathbf{C}} + \mathbf{G}).$$

Estimates

| GLM | | | |
|------------------|-----------|-------|------|
| Covariate | β_i | MLE | SE |
| 1 | β_0 | -4.08 | 0.70 |
| r | β_1 | 1.19 | 0.51 |
| θ | β_2 | -1.93 | 1.90 |
| $r * \theta$ | β_3 | -1.64 | 0.70 |
| r^2 | β_4 | -0.32 | 0.09 |
| θ^2 | β_5 | -3.92 | 1.10 |
| $r^2 * \theta^2$ | β_6 | -0.46 | 0.21 |

| INLA | | | |
|------------------|-----------|----------------|----------------------------------|
| Covariate | ρ_i | $\hat{\rho}_i$ | SE |
| N/A | κ | 3.23 | $\pm 1 \text{ SE}: (1.35, 7.54)$ |
| N/A | σ | 0.11 | $\pm 1 \text{ SE}: (0.05, 0.26)$ |
| 1 | β_0 | -4.14 | 0.76 |
| r | β_1 | 1.25 | 0.55 |
| θ | β_2 | -1.90 | 1.96 |
| $r * \theta$ | β_3 | -1.70 | 0.93 |
| r^2 | β_4 | -0.33 | 0.10 |
| θ^2 | β_5 | -3.93 | 1.14 |
| $r^2 * \theta^2$ | β_6 | -0.48 | 0.22 |

- $\hat{\kappa}$ — long range correlation
- $\text{SE}(w(s)) = 0.11$.
- $\rightarrow 0.15 \pm 1 \cdot \text{SE} = (0.137, 0.165)$
- $\rightarrow 0.15 \pm 2 \cdot \text{SE} = (0.125, 0.181)$