

#4) Show $\frac{d\vec{x}'}{dt} = A(t)\vec{x}' + \vec{g}(t)$; $\vec{x}'(0) = \vec{x}_0$
 solution \vec{x}'

eqn can be written as $\textcircled{\text{II}}$ put together

$$\vec{x}' = \vec{u}' + \vec{v}'$$

$\textcircled{\text{I}}$ Solve these two problems.

where: $\frac{d\vec{u}'}{dt} = A(t)\vec{u}'; \vec{u}'(0) = \vec{x}_0$

$$\frac{d\vec{v}'}{dt} = A(t)\vec{v}' + \vec{g}(t); \vec{v}'(0) = 0$$

Step I: Solve sub problems i.e. \vec{u}' & \vec{v}' problems.

Step II: Add \vec{u}' & \vec{v}' to find solution to original problem.

$$t^2 y'' + 4t y' + y = e^{-t}; \quad y(0) = y_0; \quad y'(0) = y_1$$

$$\hookrightarrow y(t) = t^1 = e^{\lambda \ln t} \quad \text{so let } x = \ln t$$

$$\lambda(\lambda-1) + 4\lambda + 1 = 0$$

$$\lambda^2 + 3\lambda + 1 = 0$$

$$\hookrightarrow \lambda = \frac{1}{2} \left(-3 \pm (9-4)^{1/2} \right)$$

$$\lambda_{\pm} = \frac{1}{2} (-3 \pm \sqrt{5})$$

$$\hookrightarrow y(1) = y_0; \quad y'(1) = y_1$$

$$y(t) = C_1 t^{\lambda_+} + C_2 t^{\lambda_-}$$

$$\hookrightarrow \begin{aligned} y(1) &= C_1 + C_2 = y_0 \\ y'(1) &= \lambda_+ C_1 + \lambda_- C_2 = y_1 \end{aligned} \quad \rightarrow \begin{pmatrix} 1 & 1 \\ \lambda_+ & \lambda_- \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \end{pmatrix}$$

Ex: Solve

①

$$y'' + y = e^{-t} \cos(2t) ; y(0) = 2, y'(0) = 1$$

$$\hookrightarrow \mathcal{L}\{y'\} = s\bar{y} - y(0)$$

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$$\mathcal{L}\{y''\} = s^2\bar{y} - sy(0) - y'(0)$$

$$\mathcal{L}\{\cos(\omega t)\} = \frac{s}{s^2 + \omega^2} ; \mathcal{L}\{\sin(\omega t)\} = \frac{\omega}{s^2 + \omega^2}$$

$$\mathcal{L}\{e^{ct}f(t)\} = F(s-c)$$

$$\hookrightarrow (s^2 + 1)\bar{y} - 2s - 1 = \frac{(s+1)}{(s+1)^2 + 4}$$

$$\hookrightarrow \bar{y} = \frac{(2s+1)}{s^2+1} + \frac{(s+1)}{(s+1)^2+4} \cdot \frac{1}{1+s^2}$$

first, corresponds
to \bar{y}_h

needs a little more work,
corresponds to
 \bar{y}_p .

So:

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$$\frac{(s+1)}{((s+1)^2+4)(s^2+1)} = \frac{as+b}{s^2+1} + \frac{c(s+1)+2d}{(s+1)^2+4}$$

$$L_p (s+1) = (as+b)((s+1)^2+4) + (c(2s+1)+2d)(s^2+1)$$

$$L_p 5b+c+2d = 1 \quad : s^0$$

$$5a+2b+c = 1 \quad : s^1$$

$$2a+b+c+2d = 0 \quad : s^2$$

$$a+c = 0 \quad : s^3$$

$$L_p a = -c$$

$$L_p 5b+c+2d = 1$$

$$2b-4c = 1$$

$$b-c+2d = 0$$

$$\left(\begin{array}{ccc|c} 5 & 1 & 2 & 1 \\ 2 & -4 & 0 & 1 \\ 1 & -1 & 2 & 0 \end{array} \right)$$

Lp haser fun ... say pg. 322

in contrast, once we know for Ansatz (3)

$$y'' + y = e^{-t} \cos(2t) \quad \underline{y = e^{-\lambda t} \cdot t^2} \quad \lambda^2 + 1 = 0$$

LA Homogeneous: $y_1 = \cos(t), y_2 = \sin(t)$ $\frac{d}{dt} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$

$$\hookrightarrow W = y_1 y_2' - y_1' y_2 = 1 \quad | \quad | = 1$$

$$\hookrightarrow y_h = C_1 \cos(t) + C_2 \sin(t)$$

$$\hookrightarrow y = C_1 e^{it} + C_2 e^{-it}$$

$$\hookrightarrow C_1 = y(0) = 2; \quad C_2 = y'(0) = 1$$

$$= C_1 (\cos(t) + i \sin(t))$$

$$= C_1 \cos(t) + C_2 \sin(t)$$

Scalar form of:

LA Variation of parameters

$$y(t) = 2 \cos(t) + \sin(t) - \cos(t) \int_0^t \sin(s) e^{-s} \cos(2s) ds$$

$$+ \sin(t) \int_0^t \cos(s) \cos(2s) e^{-s} ds$$

$$\sin(s) \cos(2s) = \frac{1}{2} (\sin(s+2s) + \sin(s-2s))$$

$$\cos(s) \cos(2s) = \frac{1}{2} (\cos(s-2s) + \cos(s+2s)) \dots$$

(4)

Similarly, we can generalize to

$$ay'' + by' + cy = f(t), \quad y(0) = y_0, \quad y'(0) = y_1$$

$$\hookrightarrow a(s^2 \bar{y} - sy_0 - y_1) + b(s\bar{y} - y_0) + c\bar{y} = F(s)$$

$$\hookrightarrow (as^2 + bs + c)\bar{y} - asy_0 - ay_1 - by_0 = F(s)$$

$$\hookrightarrow \bar{y} = \underbrace{\frac{(as+by_0 + ay_1)}{as^2 + bs + c}}_{\text{Homogeneous}} + \underbrace{\frac{F(s)}{as^2 + bs + c}}_{\text{Particular}}$$

or... using variation of parameters (real form):

$$y = e^{\lambda t} \hookrightarrow a\lambda^2 + b\lambda + c = 0$$

$$\hookrightarrow \lambda_{\pm} = \frac{1}{2a}(-b \pm (b^2 - 4ac)^{1/2})$$

$$\hookrightarrow y_1 = e^{\lambda_+ t}; \quad y_2 = e^{\lambda_- t} \quad (b^2 - 4ac \neq 0)$$

$$\hookrightarrow W = y_1 y_2' - y_1' y_2 = (\lambda_- - \lambda_+) e^{(\lambda_+ + \lambda_-)t}$$

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$$\hookrightarrow \text{Initial Conditions: } y_1(t) = e^{\lambda_+ t}; y_2(t) = e^{\lambda_- t}$$

$$\hookrightarrow C_1 y_1(0) + C_2 y_2(0) = C_1 + C_2 = y_0$$

$$C_1 \lambda_+ y_1'(0) + C_2 \lambda_- y_2'(0) = C_1 \lambda_+ + C_2 \lambda_- = y_1$$

$$\hookrightarrow \begin{pmatrix} 1 & 1 \\ \lambda_+ & \lambda_- \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} y_0 \\ y_1 \end{pmatrix}$$

$$\hookrightarrow \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \frac{1}{\lambda_- - \lambda_+} \begin{pmatrix} \lambda_- & -1 \\ -\lambda_+ & 1 \end{pmatrix} \begin{pmatrix} y_0 \\ y_1 \end{pmatrix}$$

$$y_p(t) = \frac{1}{\lambda_- - \lambda_+} \left\{ -e^{\lambda_+ t} \int_0^t e^{-\lambda_- s} f(s) ds + e^{\lambda_- t} \int_0^t e^{-\lambda_+ s} f(s) ds \right\}$$

I'll take my chances here, thanks.

And for systems:

(6)

$$\frac{d\bar{x}}{dt} = A\bar{x} + \bar{g}(t); \quad x(0) = \bar{x}_0$$

$$\hookrightarrow s\bar{\bar{x}} - \bar{x}_0 = A\bar{\bar{x}} + \bar{\bar{G}}(s)$$

$$\hookrightarrow (sI - A)\bar{\bar{x}} = \bar{x}_0 + \bar{\bar{G}}(s)$$

$$\hookrightarrow \bar{\bar{x}} = (sI - A)^{-1}\bar{x}_0 + (sI - A)^{-1}\bar{\bar{G}}(s)$$

becomes later
an eval

or:

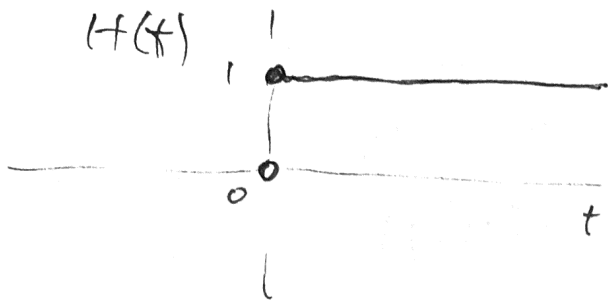
$$\text{find } A = V \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} V^{-1} \quad \left(\text{or } = V \begin{pmatrix} \lambda & 1 \\ 0 & \lambda \end{pmatrix} V^{-1} \dots \right)$$

$$\hookrightarrow \bar{x}(t) = V \begin{pmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{pmatrix} V^{-1} \bar{x}_0 + V \begin{pmatrix} e^{\lambda_1 t} & 0 \\ 0 & e^{\lambda_2 t} \end{pmatrix} \int_0^t \begin{pmatrix} e^{-\lambda_1 s} & 0 \\ 0 & e^{-\lambda_2 s} \end{pmatrix} V^{-1} \bar{g}(s) ds$$

5.5 Discontinuous functions

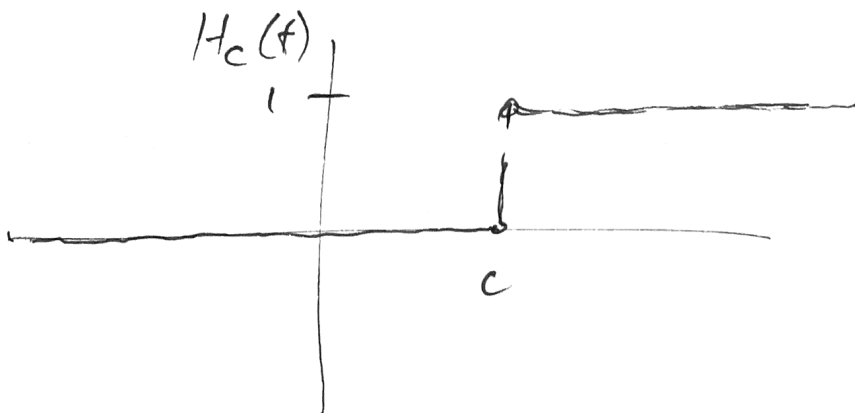
Heaviside Function:

$$H(t) = \begin{cases} 0, & t < 0 \\ 1, & t \geq 0 \end{cases}$$



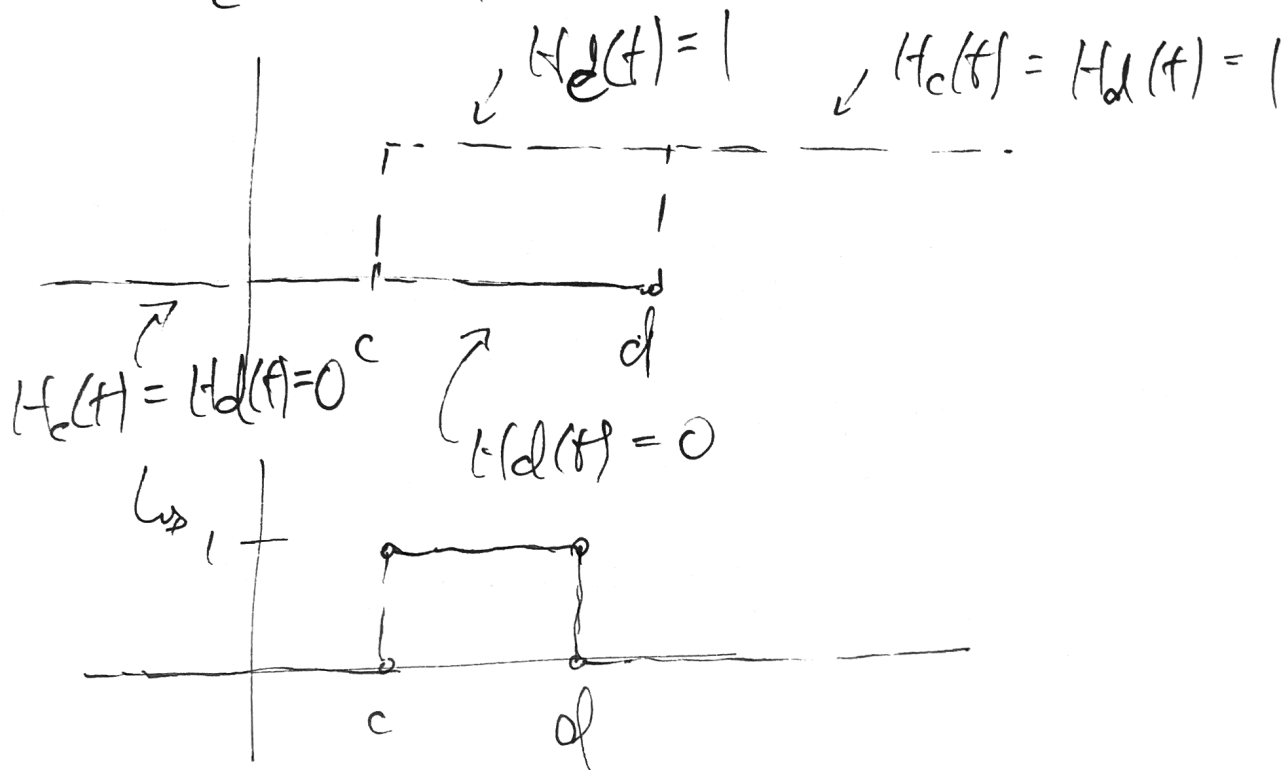
$$H_c(t) = H(t-c) = \begin{cases} 0 & t-c < 0 \\ 1 & t-c \geq 0 \end{cases}$$

$$= \begin{cases} 0 & t < c \\ 1 & t \geq c \end{cases}$$



So let $d > c$

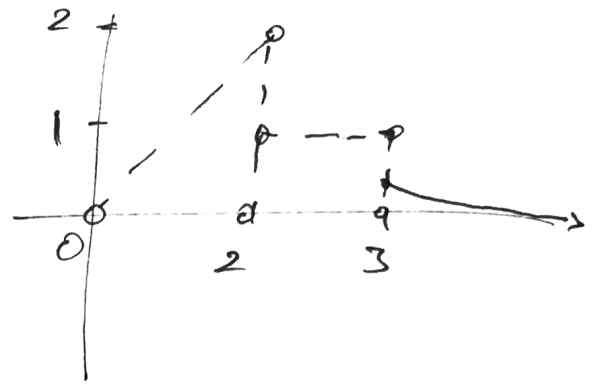
↳ $H_c(t) - H_d(t)$



Let: $f(t) = \begin{cases} 0 & t < 2 \\ 3 & 2 \leq t < 4 \\ 0 & t \geq 4 \end{cases}$

↳ $f(t) = 3 (H_2(t) - H_4(t))$
 $= 3 H_{(2,4)}(t)$

$$\text{Let } f(t) = \begin{cases} t & 0 < t < 2 \\ 1 & 2 \leq t \leq 3 \\ e^{-2t} & 3 \leq t \end{cases}$$



$$\begin{aligned} \text{Let } f(t) &= t H_{(0,2)}(t) + H_{[2,3)}(t) + e^{-2t} H_{[3,\infty)}(t) \\ &H_0(t) = 1 \text{ for } t \geq 0 \\ &= t(1 - H_2(t)) + (H_2(t) - H_3(t)) + e^{-2t} H_3(t) \\ &= \underline{t + (1-t)H_2(t) + (e^{-2t} - 1)H_3(t)} \end{aligned}$$

Now:

$$\begin{aligned} \mathcal{L}\{H_c(t)\} &= \int_0^{\infty} e^{-st} H(t-c) dt = \int_0^c + \int_c^{\infty} \\ &= \int_c^{\infty} e^{-st} dt \\ &= -\frac{1}{s} e^{-st} \Big|_c^{\infty} = \frac{1}{s} e^{-sc}; \quad s > 0. \end{aligned}$$

Shifted Functions:

$$\text{Say } g(t) = \begin{cases} 0, & t < c \\ f(t-c), & t \geq c \end{cases}$$

$$\text{or } g(t) = H_c(t) f(t-c)$$

$$\begin{aligned} \text{Lap } \mathcal{L}[H_c(t) f(t-c)] &= \int_0^{\infty} e^{-st} H_c(t) f(t-c) dt \\ &= \int_0^c e^{-st} H_c(t) f(t-c) dt + \int_c^{\infty} e^{-st} H_c(t) f(t-c) dt \\ &= \int_c^{\infty} e^{-st} f(t-c) dt \\ \tilde{t} &= t-c \rightarrow t = \tilde{t} + c \\ &= e^{-sc} \int_0^{\infty} e^{-s\tilde{t}} f(\tilde{t}) d\tilde{t} \\ &= e^{-sc} F(s). \end{aligned}$$

So now for

$$f(t) = \begin{cases} t & 0 < t < 2 \\ 1 & 2 \leq t < 3 \\ e^{-2t} & 3 \leq t \end{cases}$$

$$\hookrightarrow f(t) = t + (1-t)H_2(t) + (e^{-2t} - 1)H_3(t)$$

$$= t + (1 - (t-2+2))H_2(t) + (e^{-2(t-3+3)} - 1)H_3(t)$$

$$= t - (1 + (t-2))H_2(t) + (e^{-6}e^{-2(t-3)} - 1)H_3(t)$$

$$\hookrightarrow \mathcal{L}\{f\} = \frac{1}{s^2} - \left(\frac{1}{s} + \frac{1}{s^2}\right)e^{-2s} + \left(\frac{e^{-6}}{s+2} - \frac{1}{s}\right)e^{-3s}.$$