

Singular Perturbations:

①

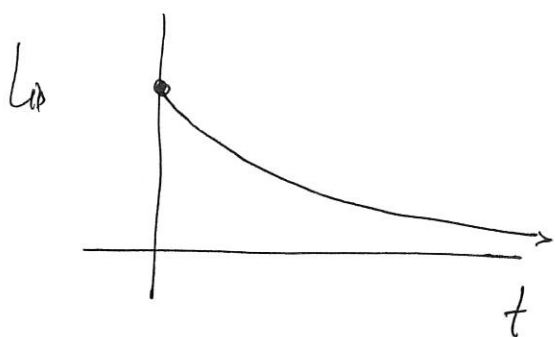
$$\varepsilon \ddot{x} + \dot{x} + x = 0$$

$$x(0) = 1, \dot{x}(0) = 0$$

if we try $x = x_0 + \varepsilon x_1 + \varepsilon^2 x_2 + \dots$

$$\hookrightarrow \dot{x}_0 + x_0 = 0 \rightarrow x_0(t) = \tilde{x}_0 e^{-t} \rightarrow x_0(0) = 1 \text{ but}$$

$$\underline{\dot{x}_0(0) \neq 0.}$$



So what to do?

$$\text{Let } \tau = t/\varepsilon \rightarrow \frac{d}{dt} = \frac{1}{\varepsilon} \frac{d}{d\tau}$$

$$\hookrightarrow \frac{\varepsilon}{\varepsilon^2} \frac{d^2 x}{d\tau^2} + \frac{1}{\varepsilon} \frac{dx}{d\tau} + x = 0$$

(2)

$$\hookrightarrow \frac{d^2 x}{d\bar{\tau}^2} + \frac{\delta}{\varepsilon} \frac{dx}{d\bar{\tau}} + \frac{\delta^2}{\varepsilon} x = 0$$

If we choose $\delta = \varepsilon \longrightarrow$ "Width of the Boundary Layer"

$$\hookrightarrow \frac{d^2 x}{d\bar{\tau}^2} + \frac{dx}{d\bar{\tau}} + \varepsilon x = 0$$

Let $x = \bar{x}_0(\bar{\tau}) + \varepsilon \bar{x}_1(\bar{\tau}) + \varepsilon^2 \bar{x}_2(\bar{\tau}) + \dots$

$$\hookrightarrow \frac{d^2 \bar{x}_0}{d\bar{\tau}^2} + \frac{d\bar{x}_0}{d\bar{\tau}} = 0$$

Save for
later
skip for
Now!

$$\hookrightarrow \frac{d\bar{x}_0}{d\bar{\tau}} + \bar{x}_0 = C_0 \rightarrow \frac{d}{d\bar{\tau}}(\bar{x}_0 e^{\bar{\tau}}) = C_0 e^{\bar{\tau}}$$

$$\hookrightarrow \bar{x}_0(\bar{\tau}) = ~~C_0 + D_0 e^{-\bar{\tau}}~~ C_0 + D_0 e^{-\bar{\tau}}$$

$$\bar{x}_0(0) = C_0 + D_0 = 1$$

$$\left. \frac{d\bar{x}_0}{d\bar{\tau}} \right|_{\bar{\tau}=0} = ~~D_0~~ D_0 = 0 \rightarrow ~~D_0 = 0~~ D_0 = 0 \quad C_0 = 1$$

$$\lambda = \frac{1}{2\varepsilon} \left(-1 \pm (1-4\varepsilon)^{1/2} \right) \quad \left\{ \begin{array}{l} \text{Solve} \\ \varepsilon \ddot{x} + \dot{x} + x = 0 \\ \text{Directly} \end{array} \right. \quad (1) \quad \text{Q}$$

$$x(t) = A e^{\lambda_+ t} + \beta e^{\lambda_- t}$$

$$A + \beta = 1, \quad A \lambda_+ + \beta \lambda_- = 0$$

$$\hookrightarrow A \lambda_+ + (1-A) \lambda_- = 0$$

$$\hookrightarrow A(\lambda_+ - \lambda_-) = -\lambda_-$$

$$\hookrightarrow A = \frac{\lambda_-}{\lambda_- - \lambda_+}$$

$$\beta = 1 - \frac{\lambda_-}{\lambda_- - \lambda_+} = \frac{\lambda_+}{\lambda_- - \lambda_+}$$

$$x(t) = \frac{1}{\lambda_- - \lambda_+} \left(\lambda_- e^{\lambda_+ t} - \lambda_+ e^{\lambda_- t} \right)$$

$$\lambda_- - \lambda_+ = -\frac{1}{\varepsilon} (1-4\varepsilon)^{1/2} = -\frac{1}{\varepsilon} (1-2\varepsilon + O(\varepsilon^2)) = -\frac{1}{\varepsilon} + 2 + O(\varepsilon)$$

(2)

$$\lambda_+ = \frac{1}{2\varepsilon} \left(-1 + (1 - 2\varepsilon + O(\varepsilon^2)) \right) = -1 + O(\varepsilon)$$

$$\lambda_- = \frac{1}{2\varepsilon} \left(-1 - (1 - 2\varepsilon + O(\varepsilon^2)) \right) = -\frac{1}{\varepsilon} + 1 + O(\varepsilon)$$

$$\hookrightarrow x(t) \sim \frac{1}{2 - \frac{1}{\varepsilon} + O(\varepsilon)} \left[\left(1 - \frac{1}{\varepsilon}\right) e^{-t_-} (-1 + O(\varepsilon)) e^{-t/\varepsilon} \right]$$

$$\sim \frac{-\varepsilon}{1 - 2\varepsilon + O(\varepsilon^2)} \left[\left(1 - \frac{1}{\varepsilon}\right) e^{-t_-} (-1 + O(\varepsilon)) e^{-t/\varepsilon} \right]$$

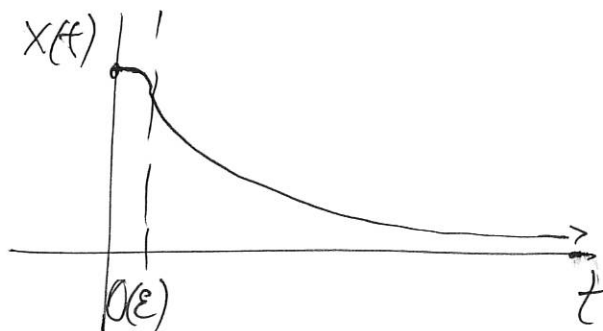
$$\sim -\varepsilon(1 + 2\varepsilon + O(\varepsilon^2)) \left(\left(1 - \frac{1}{\varepsilon}\right) e^{-t_-} (-1 + O(\varepsilon)) e^{-t/\varepsilon} \right)$$

$$\sim e^{-t} + \varepsilon (2e^{-t} - e^{-t} - e^{-t/\varepsilon}) + O(\varepsilon^2)$$

$$\sim e^{-t} + \varepsilon (e^{-t} - e^{-t/\varepsilon}) + O(\varepsilon^2)$$

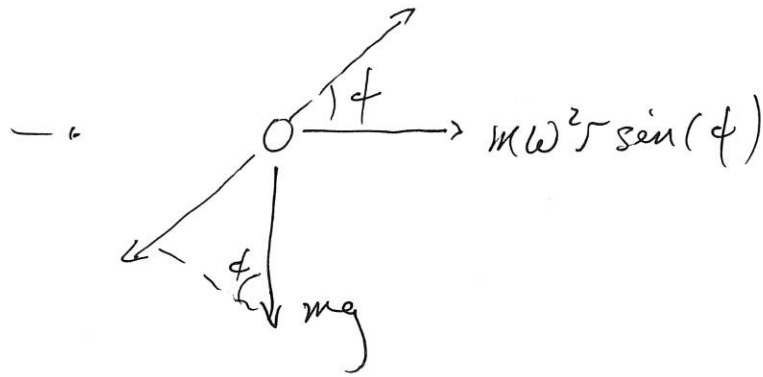
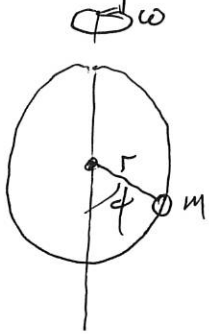
$$\hookrightarrow x(0) = 1 + O(\varepsilon^2)$$

$$\dot{x}(0) = O(\varepsilon)$$



Overdamped Bead on a Hoop:

(1)



↳

$$mr\ddot{\phi} = -b\dot{\phi} - mg\sin(\phi) + m\omega^2 r \sin(\phi)\cos(\phi)$$

So note, ϕ is an angle, and thus it really doesn't have units.

Thus, we let $\tau = t/\tau$

$$\hookrightarrow \frac{d}{dt} = \frac{1}{\tau} \frac{d}{d\tau}, \quad \frac{d^2}{dt^2} = \frac{1}{\tau^2} \frac{d^2}{d\tau^2}$$

Likewise, we treat mg as the characteristic magnitude of a force.

Thus, after reeling and dividing, we get

(2)

$$\frac{r}{gT^2} \frac{d^2\phi}{dT^2} = -\frac{b}{mgT} \frac{d\phi}{dT} - \sin(\phi) + \frac{r\omega^2}{g} \sin(\phi) \cos(\phi)$$

So, let $\gamma = r\omega^2/g$, and now we ask, how to choose T ?

Choice 1: $b/mgT = 1$ or $T = b/mg \rightarrow b = F \cdot T = m \frac{L}{T^2} T$

\hookrightarrow Note, this emphasizes the role of friction in $\frac{mL}{T}$
the problem.

$$\hookrightarrow \frac{r}{g} \frac{1}{T^2} = \frac{r}{g} \left(\frac{mg}{b} \right)^2 = rg \left(\frac{m}{b} \right)^2 = \frac{rm}{b^2} mg$$

$$\bar{E} \sim mV^2 \Rightarrow \frac{m}{b^2} \sim \frac{1}{\bar{E}} \Rightarrow (rg) \left(\frac{m}{b^2} \right)$$

is an energy balance.

Or $\frac{r}{g} \frac{1}{\tau^2} = (rmg) / (b^2/m) \leftarrow \begin{matrix} \text{characteristic work done} \\ \text{by friction} \end{matrix}$ (13)

\nearrow characteristic work done by gravity

Now further suppose that

$$rmg \ll b^2/m \quad \text{i.e. friction does most of the work}$$

\hookrightarrow we then introduce the non-dimensional parameter ε

$$\varepsilon = (rmg) / (b^2/m), \quad \underline{0 < \varepsilon \ll 1}$$

$$\hookrightarrow \varepsilon \frac{d^2 \phi}{d\tau^2} = -\frac{d\phi}{d\tau} - \sin(\phi) + \gamma \sin(\phi) \cos(\phi)$$

Again, we have two initial conditions

(14)

$$\phi(0) = \phi_0, \quad \dot{\phi}(0) = \phi_1$$

So, if we ignore ε term, ~~we~~ we cannot satisfy both initial conditions.

But let's see what happens when we do anyway

$$\frac{d\phi}{dt} = \sin(\phi)(\gamma \cos(\phi) - 1) = f(\phi; \gamma)$$

$$\hookrightarrow \text{FP's: } \sin(\phi) = 0, \quad \cos(\phi) = 1/\gamma$$

$$\hookrightarrow \phi^* = 0, \pi$$

$$\hookrightarrow \gamma > 1 \rightarrow \phi^* = \pm \cos^{-1}(1/\gamma)$$

$$\begin{aligned} \text{St: } \partial_{\phi} f &= \cos(\phi)(\gamma \cos(\phi) - 1) - \gamma \sin^2(\phi) \\ &= \gamma \cos(2\phi) - \cos(\phi) \end{aligned}$$

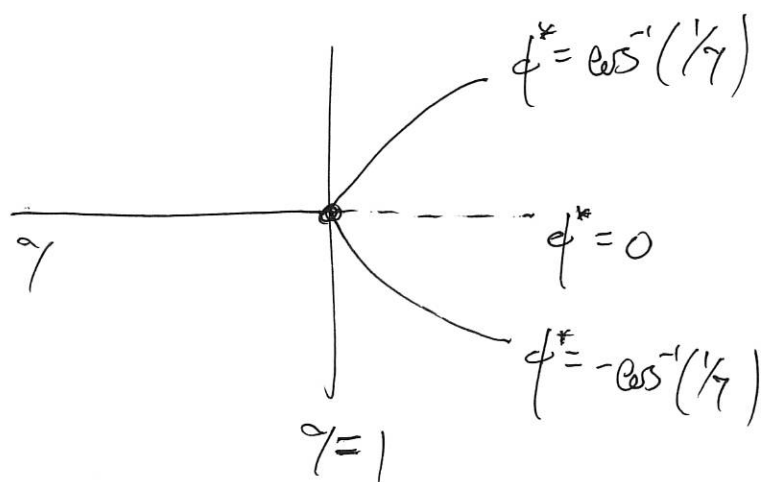
(5)

$$\partial_{\phi} f|_{\phi^*=0} = \gamma - 1$$

$$\partial_{\phi} f|_{\phi^* = \pm \cos^{-1}(\frac{1}{\gamma})} = -\gamma(1 - \frac{1}{\gamma^2})$$

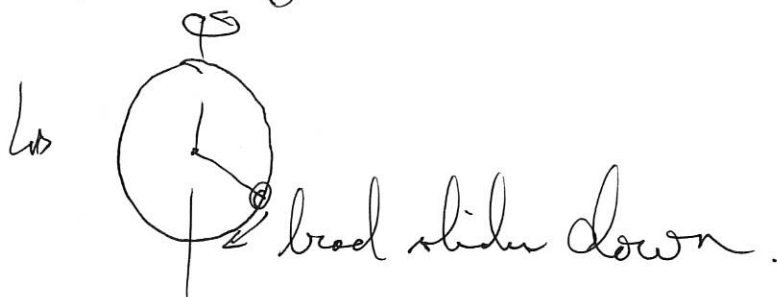
$$\partial_{\phi} f|_{\phi^* = \pi} = \gamma + 1$$

Always unstable

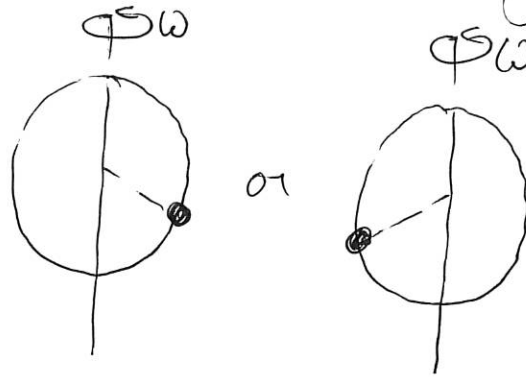


} Supercritical
Pitchfork
Bifurcation

So $\gamma = r\omega^2/g \rightarrow \text{for } \gamma < 1 \text{ or } \omega^2 < g/5$



But when $\gamma > 1$ or $\omega^2 > g/r$, centrifugal force can hold us off (6)



The particular perturbation decides which of the two states we fall into. We call this a symmetry broken state.

But what of our angular acceleration?

$$\text{Let } \bar{T} = \tau/g$$

$$\hookrightarrow \frac{\varepsilon}{g^2} \frac{d^2 \phi}{d\bar{t}^2} = -\frac{1}{g} \frac{d\phi}{d\bar{t}} - \sin(\phi) + \gamma \sin(\phi) \cos^2(\phi)$$

(7)

$$\hookrightarrow \frac{d^2 \phi}{d\bar{t}^2} = -\frac{\delta}{\varepsilon} \frac{d\phi}{d\bar{t}} + \frac{\delta^2}{\varepsilon} \sin(\phi)(\gamma \cos(\phi) - 1)$$

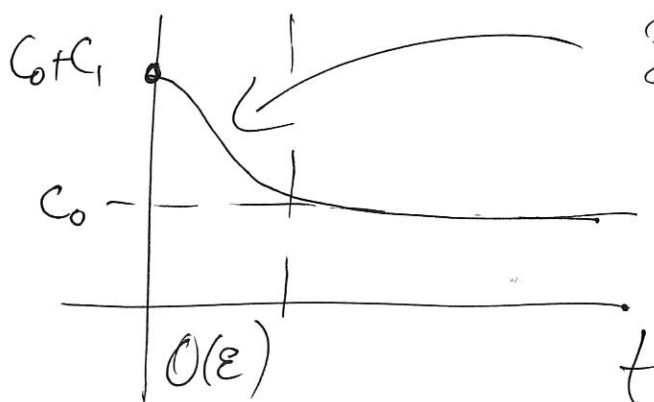
\hookrightarrow if we choose $\delta = \varepsilon$

$$\hookrightarrow \frac{d^2 \phi}{d\bar{t}^2} = -\frac{d\phi}{d\bar{t}} + \varepsilon \sin(\phi)(\gamma \cos(\phi) - 1)$$

$$\hookrightarrow \frac{d^2 \phi}{d\bar{t}^2} + \frac{d\phi}{d\bar{t}} = 0$$

$$\hookrightarrow \phi(\bar{t}) = C_0 + C_1 e^{-\bar{t}}$$

$$\text{or } \phi(t) = C_0 + C_1 e^{-t/\varepsilon}$$



So there is a fast transient in this problem.