

Module 2

Probability Distributions

Spring 2026

Learning goals

- ❑ Review key probability distributions, activities focus on Gaussian PDFs in multiple dimensions.
 - ❑ Discrete probability distributions such as Bernoulli or Binomial, or continuous PDFs such as Student-t, are discussed in chapter 2. They will not be used in the current set of activities, but are relevant to future work.
- ❑ Reflect on why the Gaussian Distribution is so widely used to model the distribution of continuous variables. We will introduce PDF representing correlated variables

Why probability distributions matter

- ❑ Measurements are noisy
- ❑ Models are uncertain
- ❑ Predictions require uncertainty

Probability as uncertainty, not randomness

- ❑ Describes incomplete information
- ❑ Applies to:
 - experiments
 - Parameters
 - predictions
- ❑ Probability is bookkeeping for uncertainty!

Discrete Probability

Example: coin toss

$$\begin{aligned}p(x = \text{heads}|\mu) &= \mu \\p(x = \text{tails}|\mu) &= 1 - \mu\end{aligned}$$

Described by Bernoulli distribution

$$\text{Bern}(x|\mu) = \mu^x(1 - \mu)^{1-x}$$

$$\sum_i p(x_i) = 1$$

Binomial Distribution

- How many times would we expect m heads in N coin flips?

$$\text{Bin}(m|N, \mu) = \binom{N}{m} \mu^m (1 - \mu)^{N-m}$$

$$\binom{N}{m} = \frac{N!}{(N-m)!m!}$$

-> number of ways of choosing m objects out of N identical objects

From probabilities to densities

- ❑ What if parameters are continuous? e.g. voltage, position, etc
- ❑ Probability of exact value is zero
- ❑ We must define a probability *density* instead

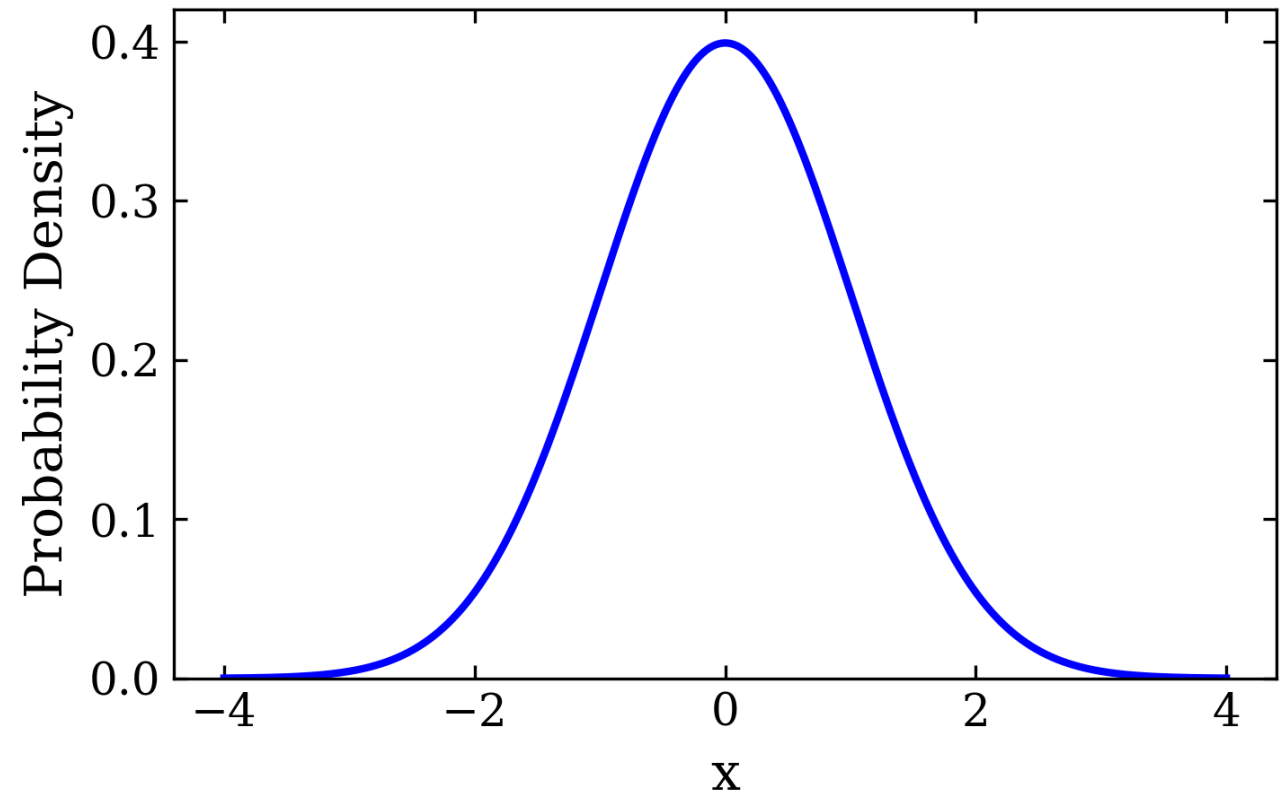
- ❑ Think about probability not at fixed point, but over an interval

Probability density function (PDF)

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$$p(x) \geq 0$$

$$\int_{-\infty}^{\infty} p(x) dx = 1$$



Probability density function (PDF)

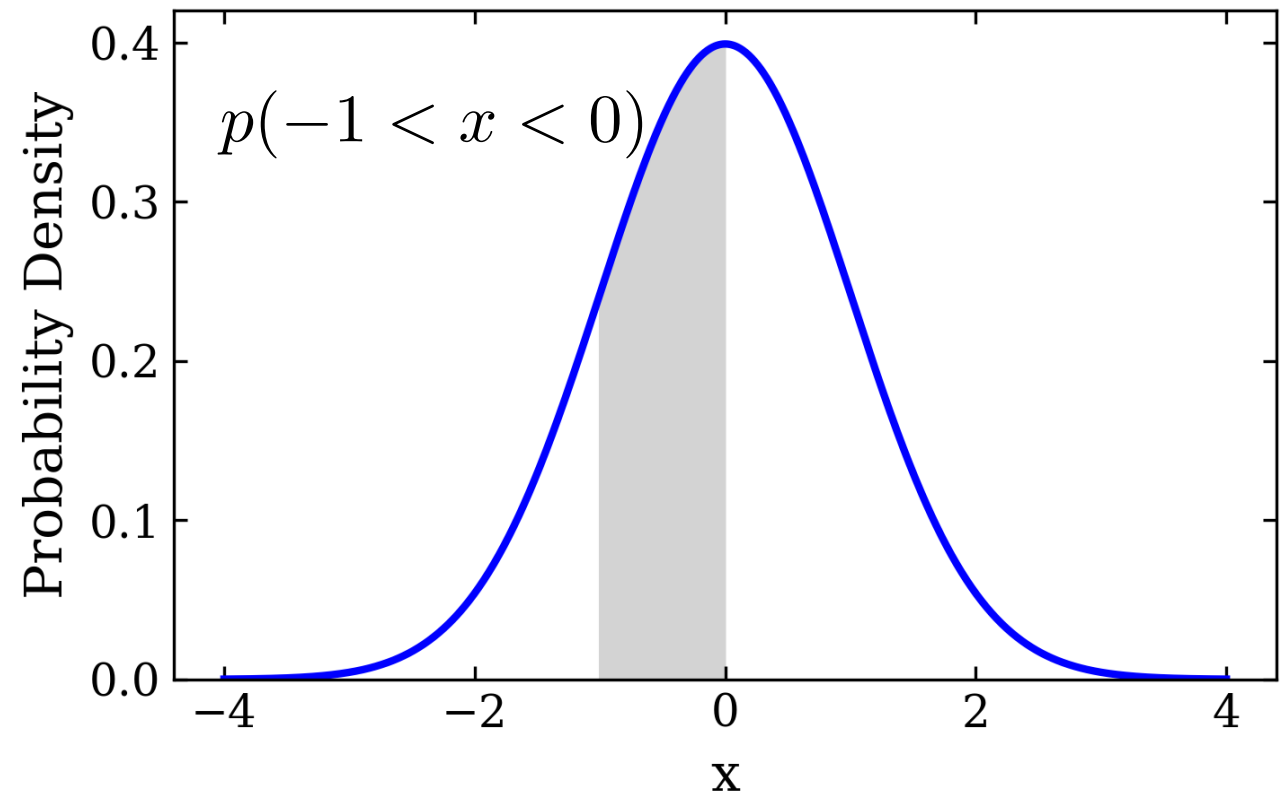
Probability density function

$$p(x) \geq 0$$

$$\int_{-\infty}^{\infty} p(x) dx = 1$$

Area = probability

Height = density (NOT probability)

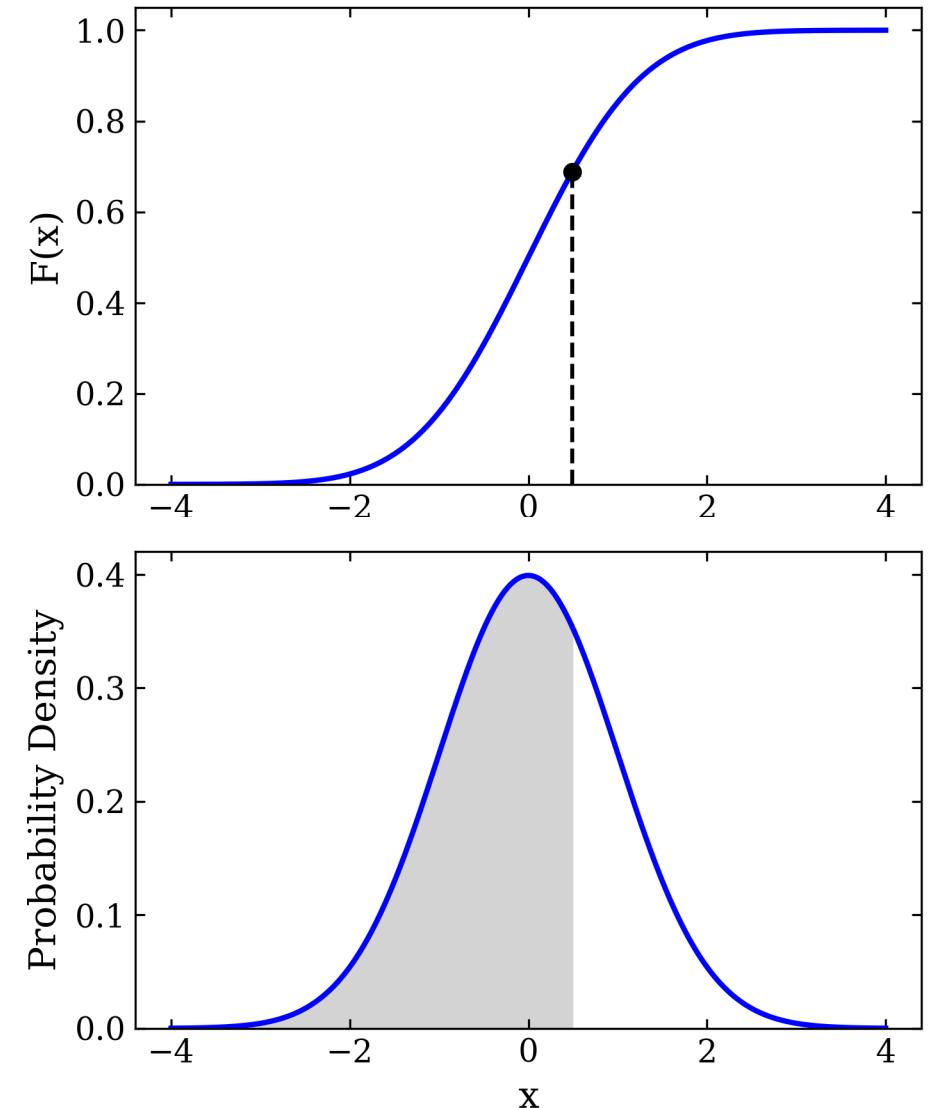


Cumulative distribution function (CDF)

$$F(x) = P(X \leq x) = \int_{-\infty}^x p(x') dx'$$

- ❑ Monotonic function describing total of probabilities
- ❑ Useful for calculating probability within an interval, hypothesis testing, etc

$$P(a < X \leq b) = F(b) - F(a)$$



Expectation values

□ Expectation value: weighted average of a function $f(x)$ under probability distribution $p(x)$

Discrete:
$$\mathbb{E}[f] = \sum_x p(x) f(x)$$

Continuous:
$$\mathbb{E}[f] = \int p(x) f(x) dx$$

Variance

□ Variance: measure of how much variability there is in $f(x)$ around its mean value $\mathbb{E}[f]$

$$\text{var}[f] = \mathbb{E}[(f(x) - \mathbb{E}[f(x)])^2]$$

$$\text{var}[f] = \mathbb{E}[f(x)^2] - \mathbb{E}[f(x)]^2$$

Covariance

- Covariance quantifies the extent in which the variance of multiple variables is related

$$\text{cov}[X_i, X_j] = \mathbb{E}[\{X_i - \mathbb{E}[X_i]\}\{X_j - \mathbb{E}[X_j]\}]$$

- Variance can be thought of as a specific case of the covariance matrix

$$\text{cov}[\mathbf{X}] = \begin{bmatrix} \text{var}(X_i) & \text{cov}(X_i, X_j) \\ \text{cov}(X_j, X_i) & \text{var}(X_j) \end{bmatrix}$$

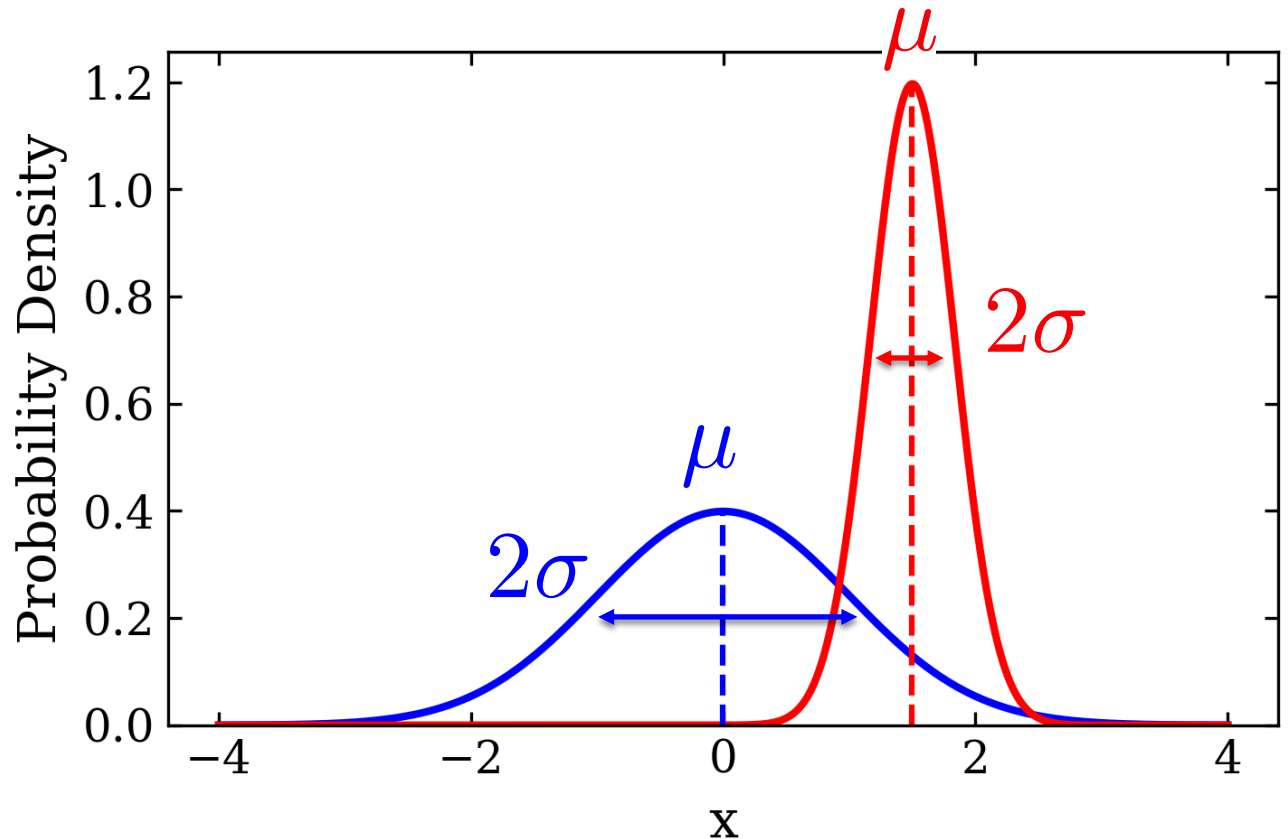
Normal (Gaussian) Distribution

$$\mathcal{N}(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

- ❑ Parameterized by μ and σ^2
- ❑ μ : center of distribution
- ❑ σ : width of distribution

$$\mu = \mathbb{E}[x]$$

$$\sigma^2 = \text{var}[x]$$



Why do we care about Gaussians?

□ Gaussian distributions occur everywhere in physics

- Thermal noise
- Electronics noise
- Measurement errors
- etc...

□ But why?

Central Limit Theorem

□ **The scaled sum of a sequence of i.i.d. random variables with finite mean and variance converges in distribution to the normal distribution.**

Let x_1, \dots, x_N be independent random variables with finite mean μ and variance σ^2 . Then the distribution of the sample mean:

$$\bar{x} = \frac{1}{N} \sum_i x_i$$

approaches a Gaussian distribution as $N \rightarrow \infty$, regardless of the original distribution.

Central Limit Theorem

Assume you have N independent measurements x_1, \dots, x_N drawn from a distribution with

$$\mathbb{E}[x_i] = \mu \quad \text{Var}(x_i) = \sigma^2$$

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Define the sample mean: $\bar{x} = \frac{1}{N} \sum_{i=1}^N x_i$

Calculate the variance of the mean

$$\text{Var}(\bar{x}) = \text{Var}\left(\frac{1}{N} \sum_{i=1}^N x_i\right) = \frac{1}{N^2} \text{Var}\left(\sum_{i=1}^N x_i\right)$$

Central Limit Theorem

$$\text{Var}\left(\sum_{i=1}^N x_i\right) = \sum_{i=1}^N \text{Var}(x_i) + 2 \sum_{i < j} \text{Cov}(x_i, x_j)$$

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If the x_i are independent, $\text{Cov}(x_i, x_j) = 0$ for $i \neq j$. Then:

$$\text{Var}\left(\sum_{i=1}^N x_i\right) = \sum_{i=1}^N \sigma^2 = N\sigma^2 \longrightarrow \text{Var}(\bar{x}) = \frac{1}{N^2} (N\sigma^2) = \frac{\sigma^2}{N}$$

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Averaging N independent noisy measurements cancels fluctuations, so the noise amplitude shrinks like \sqrt{N}

$$\sigma_{\bar{x}} = \frac{\sigma}{\sqrt{N}}$$

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However, most measurements are

Central Limit Theorem

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For a given sample of noise V_{noise} in an electrical system, you are really measuring the *sum* of many physical processes

$$V_{\text{noise}} = \delta V_1 + \delta V_2 + \delta V_3 + \dots$$

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Gaussian random variable

- thermal motion of many electrons
- microscopic scattering
- phonons
- shot noise contributions
- Not necessarily gaussian

You will see this in the coding activity

Lecture 2

What about sums of Gaussians?

What if we want to add multiple Gaussian variables?

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$$\boxed{\sigma_Z^2 = \sigma_X^2 + \sigma_Y^2}$$

Random Event Processes

Not all randomness comes from noise

❑ Many measurements involve discrete random events

Examples:

- radioactive decays
- photon detections
- dark counts in detectors
- cosmic ray hits

We want a statistical model for:

- when events occur
- how many events occur

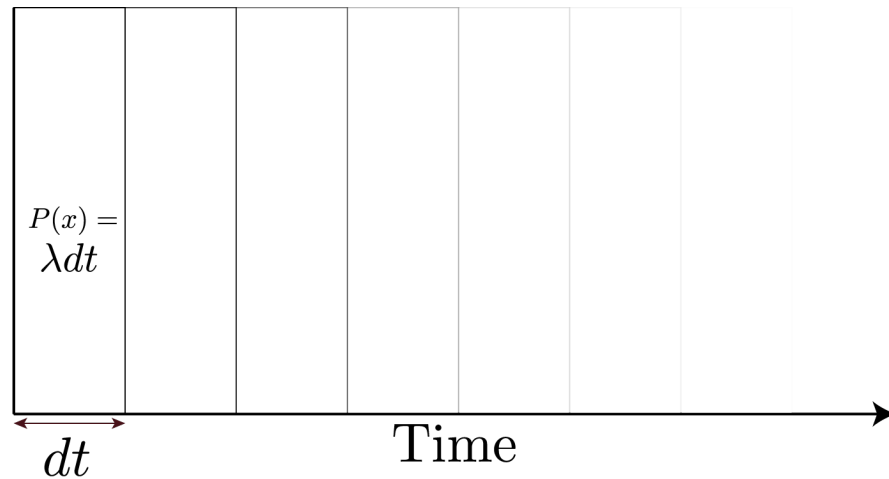
Constant Rate Assumption

- ❑ Let us assume events occur independently
- ❑ And assume constant average rate λ
 λ = average events per unit time
- ❑ In a small time interval dt : $P(\text{event in } dt) = \lambda dt$
- ❑ This is the defining assumption of a **Poisson process**
→ No memory, no aging, no buildup

We will motivate this as follows:

Discrete Time Approximation

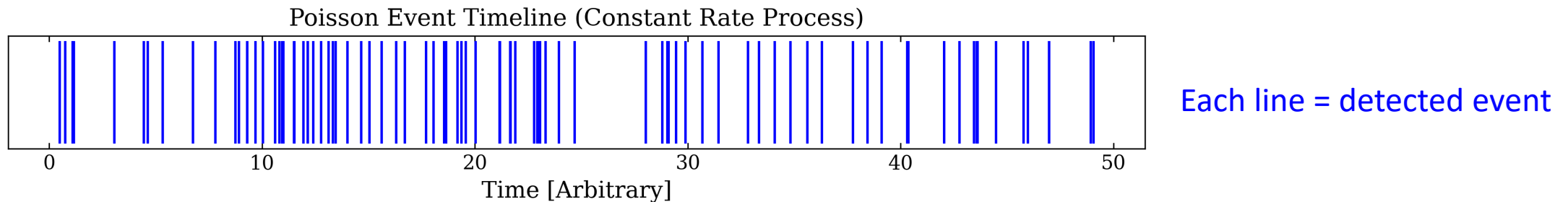
- ❑ Let us divide time into small bins dt
- ❑ In each bin event occurs with probability λdt



- ❑ Each bin is a Bernoulli trial

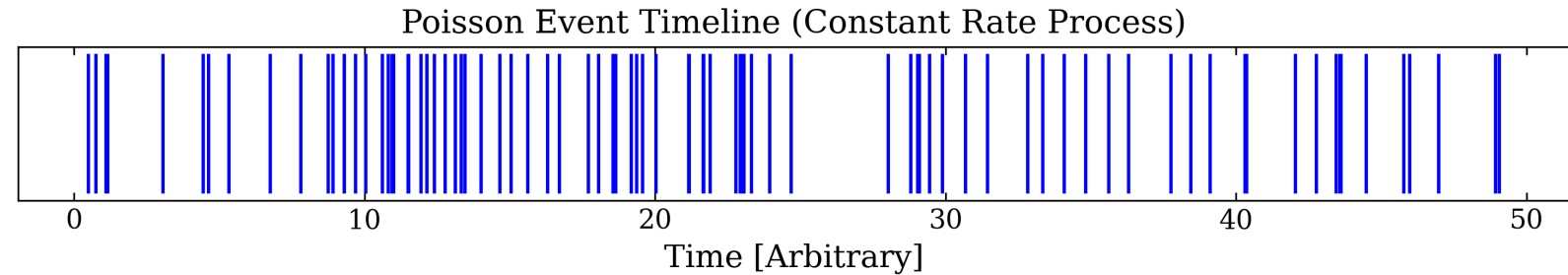
Simulated Event Timeline

- For every bin dt we sample u from a random uniform distribution (0,1)
- If $u > \lambda dt$ then we say an 'event' occurred \rightarrow repeat for all dt



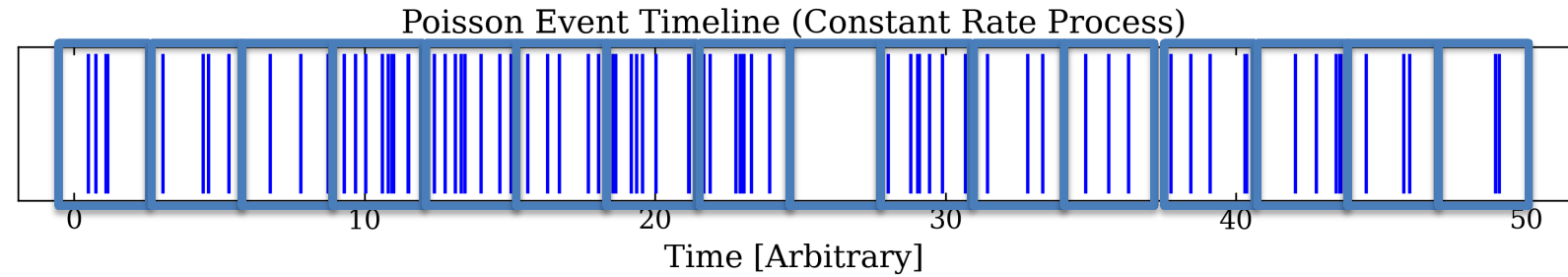
- Arrival times are irregular and unpredictable \rightarrow average density is constant

Counting Events in Fixed Windows



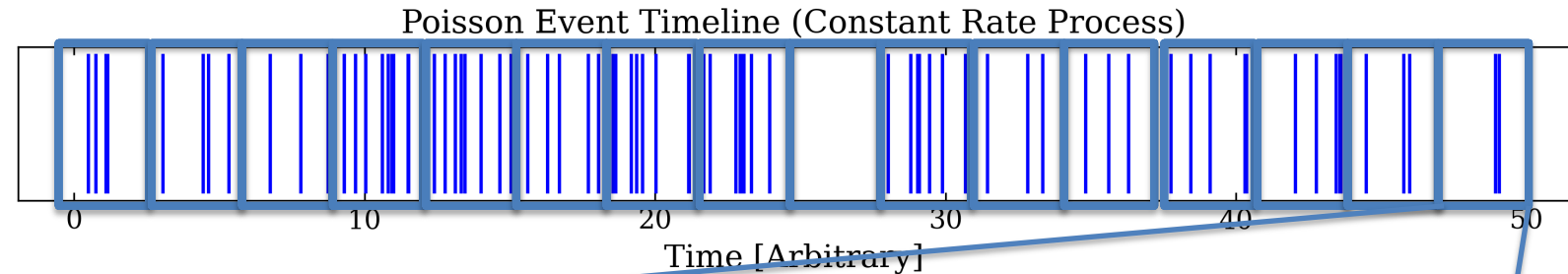
- We now divide into equal time windows

Counting Events in Fixed Windows

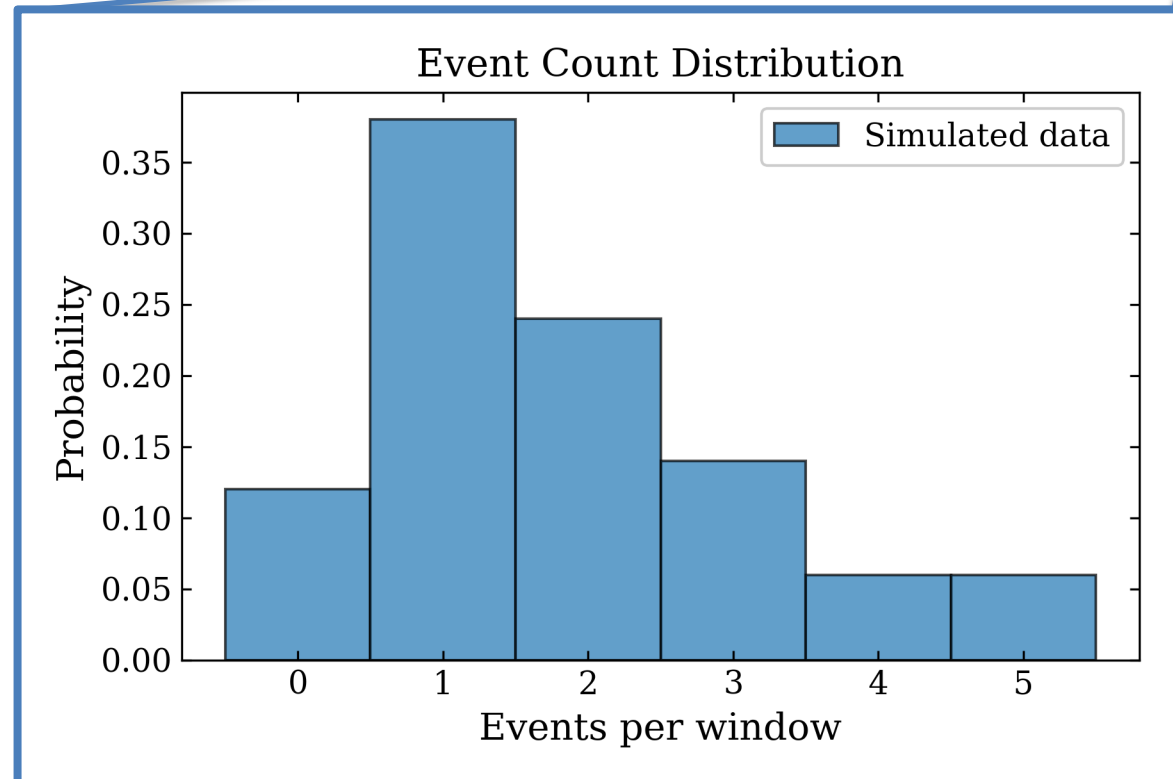


- We now divide into equal time windows

Counting Events in Fixed Windows



- Then build histogram of event counts per time window
- -> repeat and average over all windows to estimate probability



What describes this process?

□ Recall, over short interval Δt :

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Bernoulli trial

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❑ Small time interval is now defined as: $\Delta t = \frac{T}{N}$

❑ Probability of one event in a bin is now:

$$p(1) = \lambda \Delta t = \frac{\lambda T}{N}$$

Binomial Selection

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Substitute in $p = \frac{\lambda T}{N}$

$$P_N(k) = \binom{N}{k} \left(\frac{\lambda T}{N} \right)^k \left(1 - \frac{\lambda T}{N} \right)^{N-k}$$

Large N limit

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- Binomial coefficient $\rightarrow \binom{N}{k} \approx \frac{N^k}{k!}$

- Power term $\rightarrow \left(\frac{\lambda T}{N}\right)^k = \frac{(\lambda T)^k}{N^k}$

- Exponential term $\rightarrow \lim_{N \rightarrow \infty} \left(1 - \frac{\lambda T}{N}\right)^N = e^{-\lambda T}$

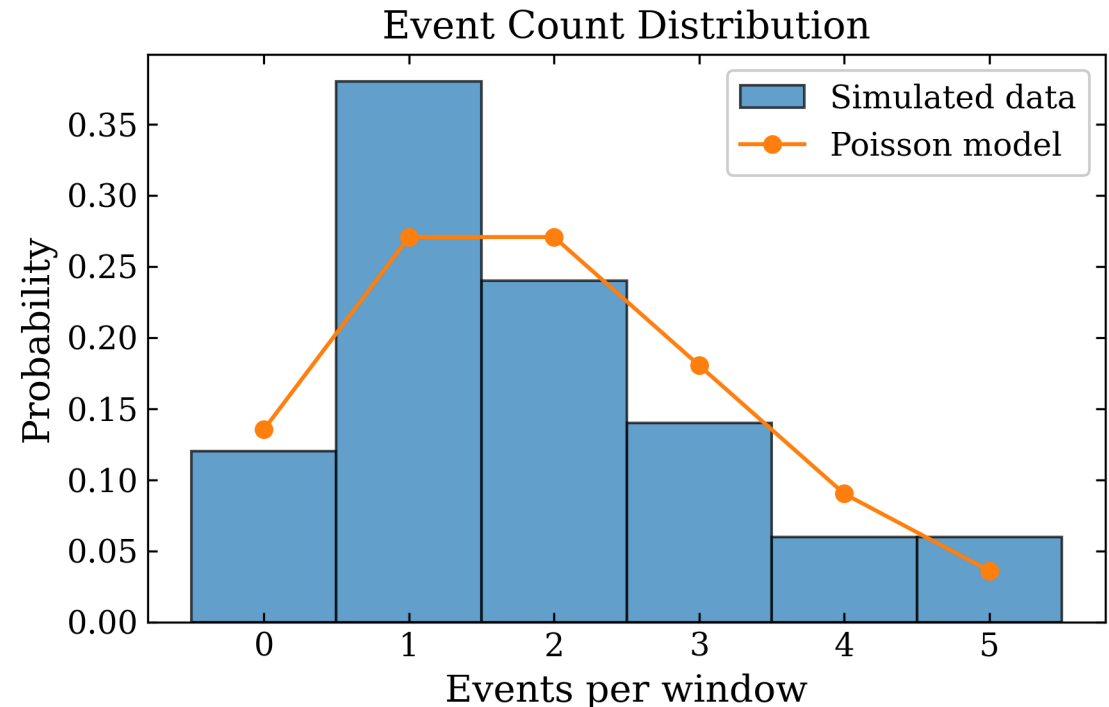
Large N limit

Let $\mu = \lambda T$

Arrive at the Poisson distribution:

$$P(k \mid \mu) = \frac{\mu^k}{k!} e^{-\mu}$$

$$\mathbb{E}(k) = \text{var}(k) = \mu$$



Timing Distribution

Similar concept: the distribution of waiting times between events

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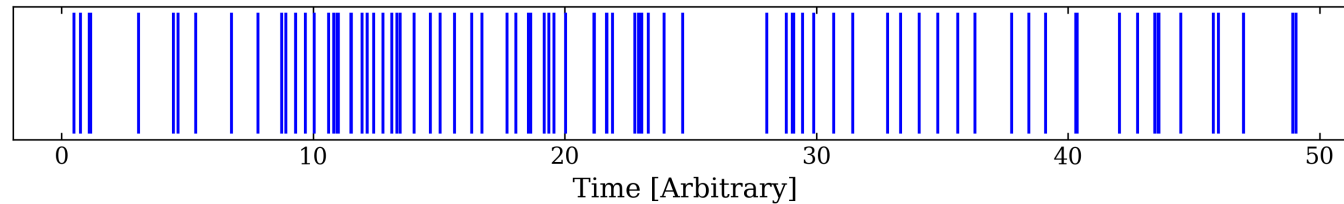
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- PDF is thus:

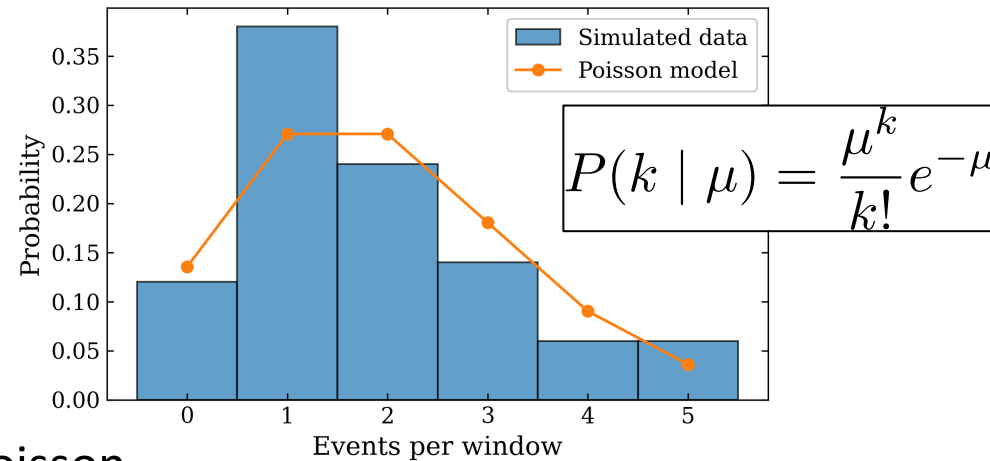
$$p(t) = \frac{d}{dt} F(t) = \lambda e^{-\lambda t}$$

Poisson and Exponential Distribution

Poisson Event Timeline (Constant Rate Process)



Event Count Distribution

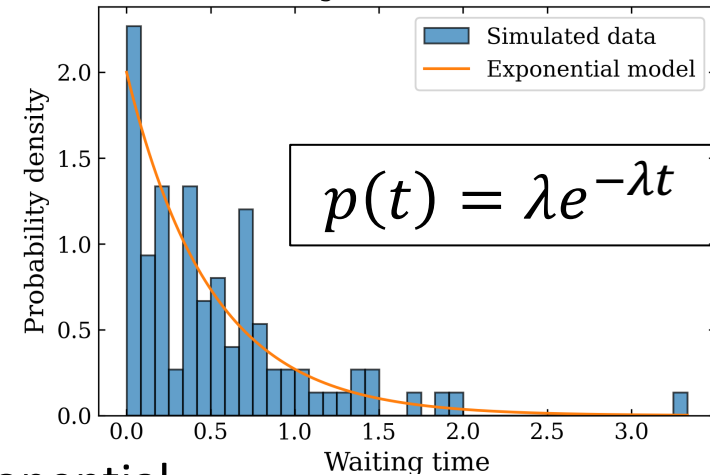


Poisson

- Discrete distribution
- “**how many** events in fixed time”

$$\mathbb{E}(k) = \text{var}(k) = \mu$$

Waiting Time Distribution



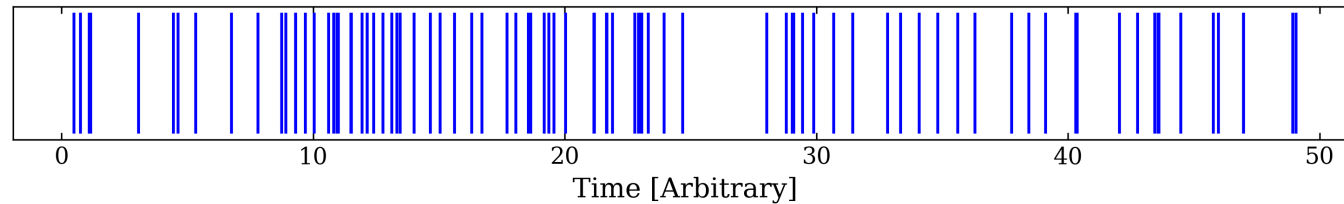
Exponential

- Continuous distribution
- “**when** the next event happens”

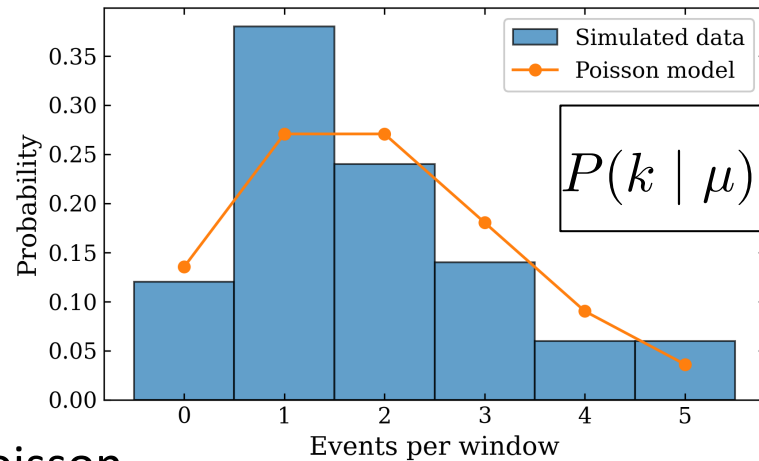
$$\mathbb{E}(t) = \frac{1}{\lambda}$$
$$\text{var}(t) = \frac{1}{\lambda^2}$$

Poisson and Exponential Distribution

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$$P(k | \mu) = \frac{\mu^k}{k!} e^{-\mu}$$

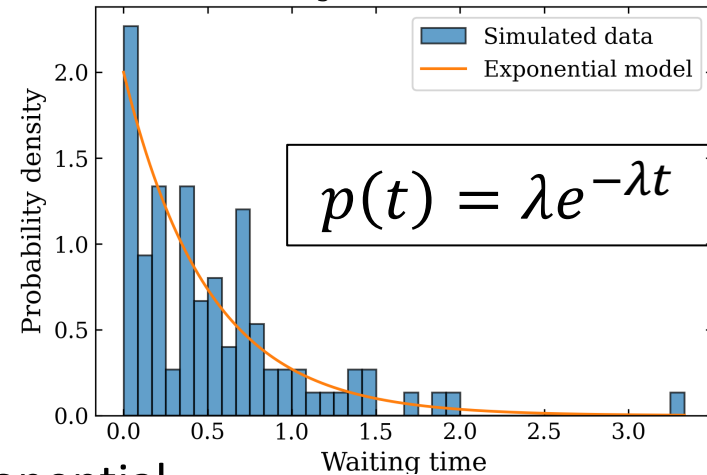
Poisson

- Discrete distribution
- “**how many** events in fixed time”

$$\mathbb{E}(k) = \text{var}(k) = \mu$$

Big deal!

Waiting Time Distribution



$$p(t) = \lambda e^{-\lambda t}$$

Exponential

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- “**when** the next event happens”

$$\mathbb{E}(t) = \frac{1}{\lambda}$$
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- ❑ $\mu = \lambda T \gg 1$ means:
 - High event rate
 - Long observation period
- ❑ → accumulating many statistically independent event opportunities
- ❑ Total observed events is a *sum*

$$\boxed{\text{Poisson}(\mu)_{\mu \rightarrow \infty} \rightarrow \mathcal{N}(\mu, \mu)}$$

Large μ limit

$$\text{Poisson}(\mu)_{\substack{\mu \rightarrow \infty \\ > 10}} \rightarrow \mathcal{N}(\mu, \mu)$$

Now we get the best of both worlds

- Can take advantage of techniques for gaussian estimation
- **Mean and variance however still describe underlying Poisson physics!!**

