CMPSCI 240: Reasoning about Uncertainty

Lecture 4: Sequential experiments

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Outline

- 1 Recap
- 2 Sequential Experiments
- 3 Total Probability and Bayes Theorem



Conditional Probability Laws

- Conditional probability laws specify the conditional probability P(A|B) of any event A given that we know with certainty that the true outcome is contained in event B.
- **Conditional probability of event** A given event B where P(B) > 0:

$$P(A \mid B) = P(A \cap B)/P(B)$$

and so
$$P(A \cap B) = P(B)P(A|B)$$
.

- Basic Properties:
 - **1** P(A|B) ≥ 0
 - $P(\Omega|B) = 1$
 - 3 $P(A^C|B) = 1 P(A|B)$
 - 4 If $A_1, ..., A_N$ are mutually disjoint events

$$P(A_1 \cup \ldots \cup A_N | B) = P(A_1 | B) + \ldots + P(A_N | B)$$

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- A sequential experiment is an experiment that involves several different steps that happen in sequence.
- Each step is an event that narrows down the possible outcomes until the final step, which assigns a unique outcome.
- Probability laws for sequential experiments are often much more intuitive to specify using conditional probability.

- **Problem:** We're in charge of air traffic control. We know that if a plane is near the airport, the radar will correctly detect it with probability 0.99. If a plane is not present, the radar still generates a detection with probability 0.1. We know that an aircraft is near the airport with probability 0.05. What is the probability that no plane is present and the radar generates a detection?
- Steps in the sequential experiment:
 - Is an aircraft present? Define event A= "an aircraft is present"
 - 2 Does the radar generate a detection? Define event D="radar generates detection"
- Outcomes of the sequential experiment:
 - **1** $A \cap D$: Aircraft and detection
 - \triangle $A \cap D^C$: Aircraft and no detection
 - **3** $A^C \cap D$: No aircraft and detection
 - 4 $A^{C} \cap D^{C}$: No aircraft and no detection

Recap

- **Problem:** If a plane is near the airport, the radar will correctly detect it with probability 0.99. If a plane is not present, the radar still generates a detection with probability 0.1. We know that an aircraft is near the airport with probability 0.05.
- **Question:** What probabilities can we deduce?
- Answer:
 - 1 P(D|A) = 0.99: "If a plane is near the airport, the radar will correctly detect it with probability 0.99"
 - $P(D|A^{C}) = 0.1$: "If a plane is not present, the radar still generates a detection with probability 0.1"
 - P(A) = 0.05: "An aircraft is near the airport with probability 0.05"

- **Question:** If P(D|A) = 0.99, $P(D|A^C) = 0.1$ and P(A) = 0.05, what is the probability that no plane is present and the radar generates a detection? In other words, what is $P(A^C \cap D)$?
- Answer:

$$P(A^{C} \cap D) = P(D|A^{C})P(A^{C}) = P(D|A^{C})(1 - P(A))$$

= 0.1 \cdot 0.95 = 0.095

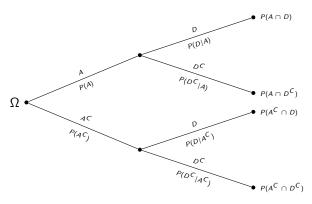
- **Question:** If P(D|A) = 0.99, $P(D|A^C) = 0.1$ and P(A) = 0.05, what is the probability that a plane is present and the radar does not generate a detection?
- **Answer:** The probability we want to compute is $P(A \cap D^C)$. Using the multiplication and complement rules, we find:

$$P(A \cap D^{C}) = P(D^{C}|A)P(A) = (1 - P(D|A))P(A)$$

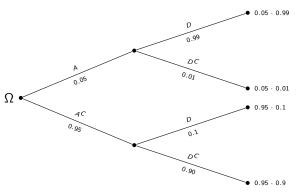
= 0.01 \cdot 0.05 = 0.0005

- One convenient way to describe these types of sequential experiments is to use a conditional probability tree.
 - 11 The steps in the experiment correspond to edges in the tree.
 - 2 A path from the root to a leaf is an outcome.
 - The probability of any outcome can be computed by multiplying the edge probabilities on the path from the outcome to the root.

Given the conditional probabilities P(D|A) = 0.99, $P(D|A^C) = 0.1$ and P(A) = 0.05, we construct the corresponding tree as shown below.



We then substitute the numerical values derived from the probabilities P(D|A) = 0.99, $P(D|A^C) = 0.1$ and P(A) = 0.05 into the tree.



To get the probability of an outcome, just multiply the probabilities along the corresponding path.

Extending to more steps: N-Step Multiplication Rule

Now suppose we have N events $A_1, ..., A_N$ and we're interested in the probability of the conjunction of these events

$$P(\cap_{n=1}^N A_n) = P(A_1 \cap \cdots \cap A_N)$$
.

■ The N-step multiplication rule states that:

$$P(\bigcap_{n=1}^{N} A_n) = \prod_{n=1}^{N} P(A_n | \bigcap_{i=1}^{n-1} A_i)$$

= $P(A_1)P(A_2 | A_1)P(A_3 | A_1 \cap A_2) \cdots P(A_N | A_1 \cap \cdots \cap A_{N-1})$

N-Step Multiplication Rule

We can prove the result using repeated application of the multiplication rule for conditional probabilities.

$$P(A_1)P(A_2|A_1)P(A_3|A_1 \cap A_2) \cdots P(A_N|A_1 \cap \cdots \cap A_{N-1})$$

$$= P(A_1) \cdot \frac{P(A_1 \cap A_2)}{P(A_1)} \cdot \frac{P(A_1 \cap A_2 \cap A_3)}{P(A_1 \cap A_2)} \cdots \frac{P(A_1 \cap A_2 \cap \cdots \cap A_N)}{P(A_1 \cap A_2 \cap \cdots \cap A_{N-1})}$$

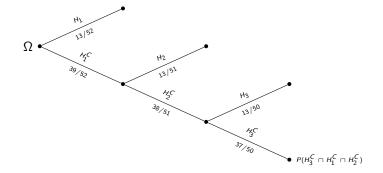
$$= P(A_1 \cap A_2 \cap \cdots \cap A_N)$$

- Consider a card game where you draw three consecutive cards from a deck without replacement and win if none of the cards is a heart.
- **Question:** What is the probability that you win the game?
 - 1 Let H_1 , H_2 , H_3 be the events that the first, second, and third cards that you draw are hearts.
 - **2** The probability that we want to compute is thus $P(H_1^C \cap H_2^C \cap H_3^C)$.
 - 3 Using the multiplication rule, we can compute it as

$$P(H_1^C)P(H_2^C|H_1^C)P(H_3^C|H_1^C\cap H_2^C) = \frac{39}{52} \cdot \frac{38}{51} \cdot \frac{37}{50} \approx 0.41$$

Example: Pick Three Cards

Consider a simple card game where you win if you draw three consecutive cards from a deck without replacement and none of the cards is a heart. Question: What does the conditional probability tree look like?



Suppose we draw two cards at random without replacement from a standard deck of cards. Let H_1 and H_2 be the events that the first and second cards that you draw are hearts.

Q1: What is the probability $P(H_2^C|H_1)$?

A: 1/2 B: 38/52 C: 39/52 D: 38/51 E: 39/51

Answer: F

Q2: What is the probability $P(H_1 \cap H_2)$?

A: $\frac{13}{52} \times \frac{12}{52}$ B: $\frac{13}{52} \times \frac{13}{52}$ C: $\frac{13}{52} \times \frac{12}{51}$ D: $\frac{13}{52} \times \frac{13}{51}$

Answer: C

- 3 Total Probability and Bayes Theorem

Total Probability and Bayes Theorem

■ Total Probability If A_1, \ldots, A_n partition Ω then for any event B:

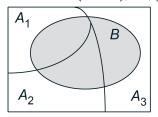
$$P(B) = P(B|A_1)P(A_1) + \ldots + P(B|A_n)P(A_n) = \sum_{i=1}^n P(B|A_i)P(A_i)$$

Bayes Theorem If A_1, \ldots, A_n partition Ω then for any event B:

$$P(A_i|B) = \frac{P(A_i \cap B)}{P(B)} = \frac{P(B|A_i)P(A_i)}{\sum_{j=1}^{n} P(B|A_j)P(A_j)}$$

Proof of Total Probability Theorem

■ Since A_1, \ldots, A_n partition Ω then $(B \cap A_1), \ldots, (B \cap A_n)$ partition B.



■ For any A_i , the multiplication rule gives us

$$P(B \cap A_i) = P(B|A_i)P(A_i) .$$

Putting these results together we have the following proof:

$$P(B) = P((B \cap A_1) \cup \cdots \cup (B \cap A_n))$$

= $P(B \cap A_1) + \cdots + P(B \cap A_n)$
= $P(B|A_1)P(A_1) + \cdots + P(B|A_n)P(A_n)$