



Computer Vision

Intermediate Project Results

Team: B0
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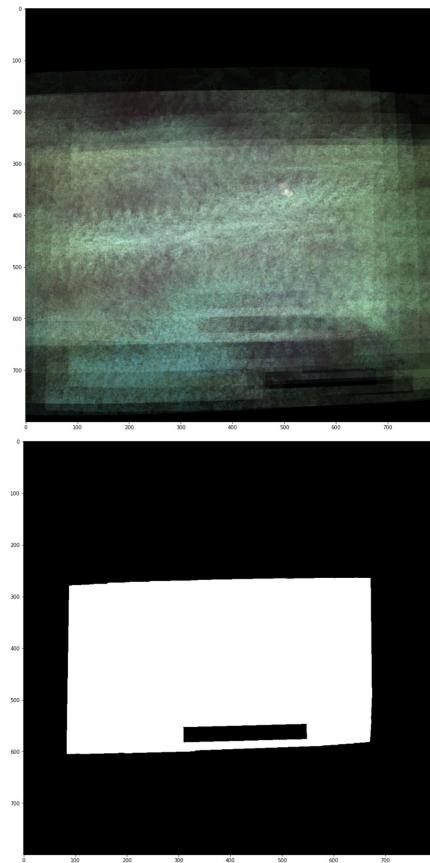
Image Integration

We tried different approaches:

e.g: "Pixel Labeling Via Energy Minimization",
simple Median

The simple “naive” approach seems to work best:

- Apply homographies
- Compute the average of all images
- Compute the mask where all images overlap

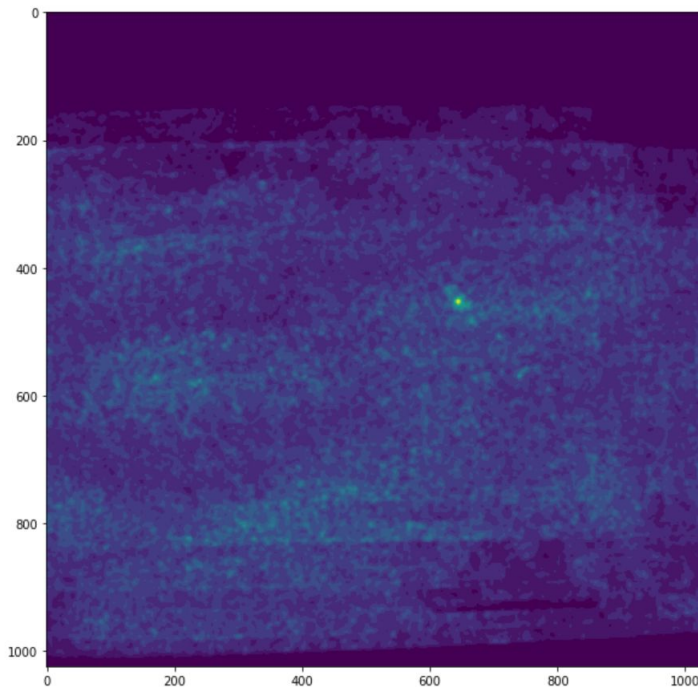


Anomaly Detection

Inspired by: *"Reducing Anomaly Detection in Images to Detection in Noise"*

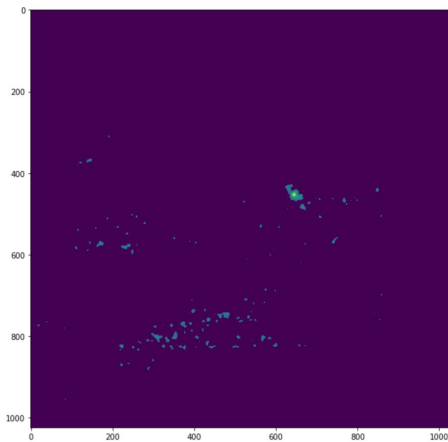
- Divide image into patches
- Train KNN on these patches
- Compare each patch to its knn-neighbors

Computationally expensive (>1 min per image)

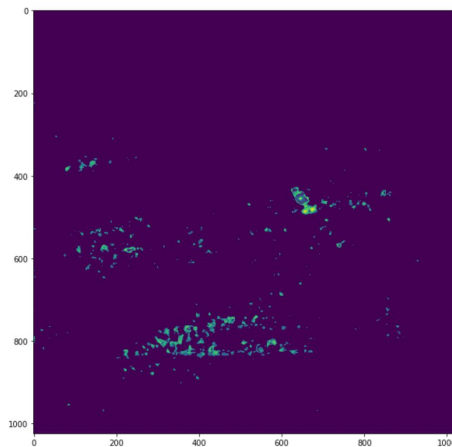




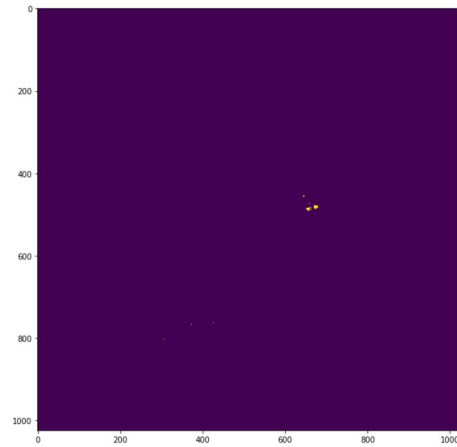
Anomaly Processing



Cutoff small values



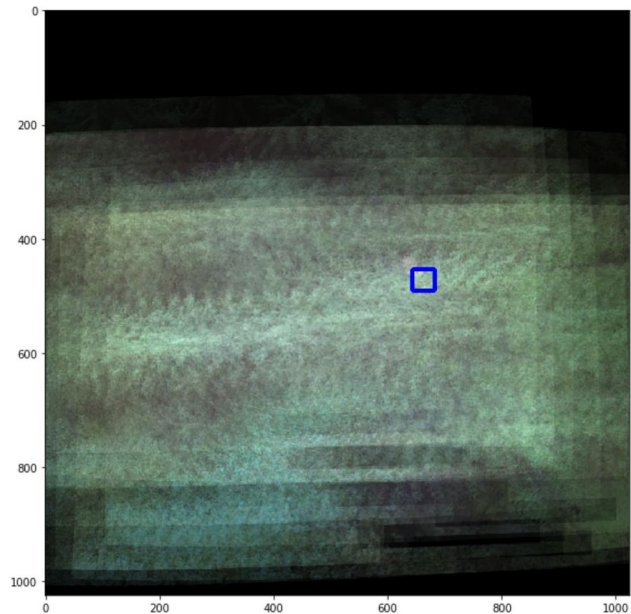
Pairwise difference
between all timesteps



Keep the highest values

Bounding Boxes

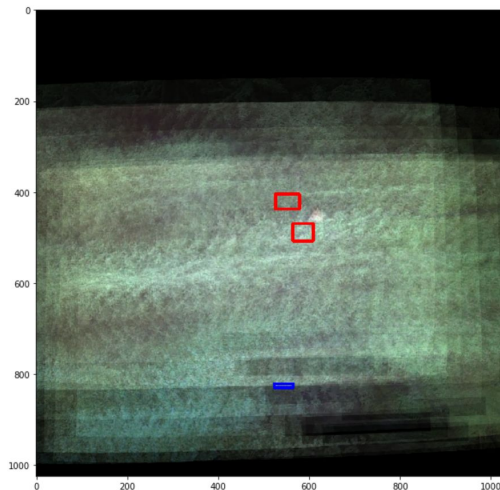
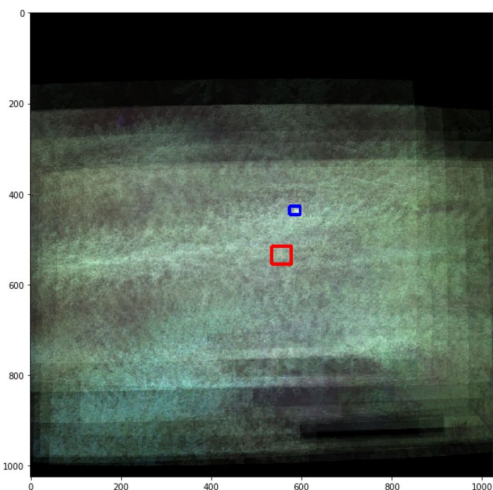
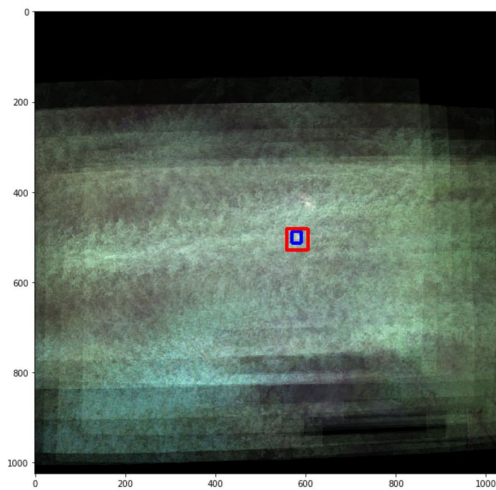
- Draw contours around “islands” of pixels
- Combine close islands together
- Check that the anomaly is not just a few pixels / random noise
- Create a rectangle around the island





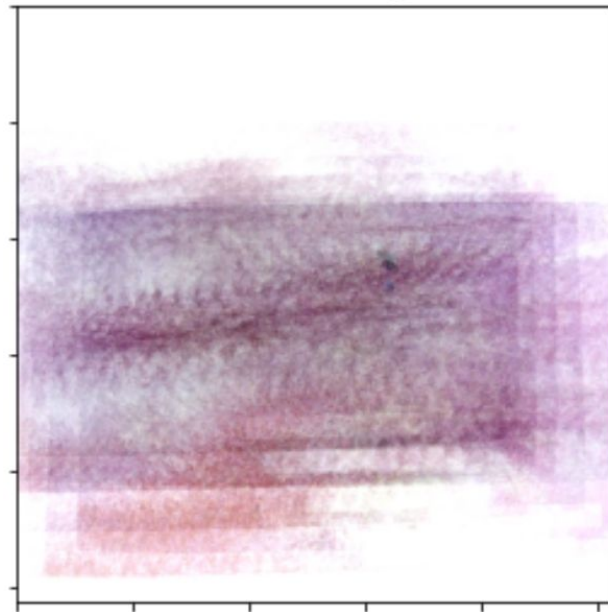
Results

Final average precision: 0.212



Future Improvements

- Better anomaly detection
 - Mask/filter out the white object
 - Make it less sensitive to noise
 - Preprocessing (adjust color, contrast)
- Better bounding boxes
 - Correct detections don't have good IoU
 - Better algorithm for determining size and position of bounding boxes





Thank you for your attention!

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