1. a)
$$p(x|y,z) = \frac{p(x,y,z)}{p(y,z)} = \frac{kf(x,z)g(y,z)h(z)}{g(y,z)h(z)}$$

$$p(x|y,z)=kf(x,z)$$

p(X/y, z) & f(x, z) since K is a constant

b)
$$p(y|x,z) = \frac{p(x,y,z)}{p(x,z)} = \frac{kf(x,z)g(y,z)h(z)}{f(x,z)h(z)}$$

p(y1x,z)=kg(y,z) p(y1x,z) or g(y,z) since K is a constant

c) X and Y are conditionally independent given Z iff p(x,y|z) = p(x|z) p(y|z)

$$\frac{\rho(x,y,z)}{\rho(z)} = \frac{\rho(x,z)}{\rho(z)} \cdot \frac{\rho(y,z)}{\rho(z)}$$

$$\frac{f(x,z)g(y,z)h(z)}{h(z)} = \frac{f(x,z)h(z)}{h(z)} \cdot \frac{g(y,z)h(z)}{h(z)}$$

$$f(x^3z)g(x,z) = F(x,z)g(x,z)$$

				01	1	_
Y	0 02	4	0	0.2	0.3	0.5
				0.3	0.2	0.5
	1.5 1.5		<u> </u>	1.5	1.5	T

Var(Y) is higher. This makes sense because no info is given so there is more uncertainty

d)
$$P_r(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$
 $P_r(x=0|Y=1) = \frac{P_r(Y=1|x=0)}{P_r(Y=1)}$

$$P_r(X=0|Y=1) = \frac{.6 \cdot .5}{.5} = \frac{.6}{.6}$$
3. a) $P_{oisson}(0) = \frac{0 \cdot e^{-\theta}}{k!}$ $P_r(A|B) = \frac{1}{200 \cdot e^{-\theta}}$ $P_r(A|B) = \frac{1}{200$