

Honors Single Variable Calculus 110.113

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1 Project Homework

Project homework requires working with new concepts that build upon our lecture material. The problems are not so hard.

1.1 Introduction

Reading: Grimmet and Welsh's Probability: an introduction. [1], this is freely available [here](#). Also Tao's lecture notes, freely available online [4].

... in mathematics you don't understand things. You just get used to them - von Neumann

Learning Objectives

A recurring theme that you would see throughout your study of more "theoretical" sciences is

- Making *good* definitions.
- *Working* with definitions

This project aims to familiarize you with the foundations of probability theory as set up by A. Komolgorov. In pure mathematics and its applications, it is desirable to have a foundation where one can discuss non deterministic statements, which we will refer as *events*, and non deterministic values, which are *random variables*. The project will proceed in the following order:

1. Probability space, [2](#).
2. Theory of distributions, [4](#).
3. Central limit theorem, [6](#).

2 Defining a probability space following A. Kolmogorov

Reading: Grimmet and Welsh's Probability: an introduction. [1], this is freely available [here](#).

Definition 2.1. A *measure space* consists of a pair (Ω, \mathcal{E}) where Ω is a set, and \mathcal{E} is a σ -algebra on Ω .

- elements $E \in \mathcal{E}$ are referred as *events*, *events space* or *measurable sets*.

In most of our set ups, \mathcal{E} is really chosen to be 2^Ω .

Definition 2.2. Let (Ω, \mathcal{E}) be a measure space. A (*finite*) *probability measure* is a map $p : \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$ satisfying

1. $p(\Omega) = 1$
2. Finitely additivity. Let $\{A_i\}_{i \in I}$ be a finite (that is $|I| = n$ for some $n \in \mathbb{N}$) collection of disjoint elements in \mathcal{E} ¹. Then

$$p\left(\bigcup_{i=0}^N A_i\right) = \sum_{i=0}^N p(A_i)$$

Once we have learnt the definition of series, we will add in another axiom called *countable additivity*.

Definition 2.3. A *probability space* is the datum of (Ω, \mathcal{E}, p) , where p is a probability measure.

Example

The discrete case. Let Ω be a finite set. $\mathcal{E} := 2^\Omega$ is the set of all subsets of Ω . This is a σ -algebra. Let p_w be any finite collection of real numbers such that

$$\sum_{w \in \Omega} p_w = 1$$

Thanks to 2.4, p extends to a map $p : \mathcal{E} \rightarrow \mathbb{R}_{\geq 0}$. One can show that (Ω, \mathcal{E}, p) is a probability space, i.e. p satisfies the axiom of def. 2.3.

Proposition 2.4. There is a map

$$p : 2^\Omega \rightarrow [0, 1]$$

uniquely extending the condition

$$p(\{w\}) = p_w \quad w \in \Omega$$

¹Remember, these are subsets of 2^Ω .

Proof. Exercise. □

Due to prop. 2.4 we define the following:

Definition 2.5. Let Ω be a finite set. A *probability mass function* on Ω is a map

$$p : \Omega \rightarrow [0, 1]$$

satisfying

$$\sum_{w \in \Omega} p(w) = 1$$

we denote $p_w := p(w)$

2.1 Problems: modeling of n -coin tosses

Example

Modeling n tosses of a fair coin. We define $(\Omega_n, \mathcal{E}_n, p)$.

- Ω_n is the set of all n consecutive ordered sets of letters which are either H or T .^a
- \mathcal{E}_n is the set of all subsets of Ω_n . One event can be

$$E_{\geq k} := \{\omega \in \Omega_n : \text{at least } k \text{ heads appear in the } n \text{ tosses}\}$$

This is the set of all sequences with at least k H s.

- Set $p(\{\omega\}) = \frac{1}{2^n}$ for all singleton subsets $\{\omega\} \in \mathcal{E}_n$ where $\omega \in \Omega_n$. This uniquely extends to a function (why?)

$$p : \mathcal{E}_n \rightarrow \mathbb{R}_{\geq 0}$$

^aOf course, from our language of set theory, this is not a valid set. But we can equally use 0 or 1 to model this, in this case, this follows from the axioms.

The following problems are related to the model described above on n -tosses of a fair coin.

1. (a) List out the elements in the events, def 2.1, of

$$\Omega_n$$

for $n = 1, 2$ and 3 . Prove Ω_n has 2^n elements for $n \in \mathbb{N}_{\geq 1}$.²

²This will be a shorthand for positive integers.

- (b) Consider the probability space $(\Omega_3, \mathcal{E}_3, p)$ ($n = 3$ in example). List out the elements of $E_{\geq i}$ for $i = 1, 2, 3$.
2. For a $n \in \mathbb{N}_{\geq 1}$. Consider the events $E_{\geq i}$ described in example of the probability space $(\Omega_n, \mathcal{E}_n, p)$. Give a formula for

$$p(E_{\geq i})$$

for $0 \leq i \leq n$.

3. Consider now the probability space $(\Omega_{2n}, \mathcal{E}_{2n}, p)$. How many elements are in the event

$$E := \{\text{exactly } n \text{ heads appear}\}$$

Prove that

$$p(E) = \frac{1}{2^{2n}} \binom{2n}{n}$$

3

³One can apply *Stirling's* formula to show that this is $\sim \frac{1}{\sqrt{\pi n}}$ as $n \rightarrow \infty$.

3 Conditional Expectation

Let us consider the discrete case for warm-up. Once we have learned integration, we will repeat the same story for density functions. The definition below is often referred as Baye's rule. Fix a probability space (Ω, \mathcal{E}, p) .

Definition 3.1. Let $A, B \in \mathcal{E}$. The *conditional probability of A given B*

$$p(A|B) := \frac{p(A \cap B)}{p(B)}$$

provided $p(B) > 0$.

This is what often leads to a formulation of Baye's rule. One of the earliest applications is in the field of *Bayesian inference*, and was used in text classification by Mosteller and Wallace (1964), see [2, 4].

3.1 Problems

Definition 3.2. A *partition of a X* is a collection of subsets X_i , indexed by a set $i \in I$ such that

1. $\bigcup_{i \in I} X_i = X$
2. The sets X_i s are pairwise disjoint: for any $i, j \in I$, the intersection (Def. ??) of X_i and X_j is empty, $X_i \cap X_j = \emptyset$.

We will now work on this definition by proving some important results.

1. (**) Let I be a finite set. Let $\{B_1, B_2, \dots\}_{i \in I}$ be a finite partition, 3.2, of Ω and $p(B_i) > 0$ for all $i \in I$. Prove that

$$p(A) = \sum_{i \in I} p(A|B_i)p(B_i)$$

using the additivity axiom.

2. (**) By conditioning on something, we would expect that we get a *new* probability space. If $B \in \mathcal{E}$ such that $p(B) > 0$ show that $q : \mathcal{E} \rightarrow \mathbb{R}$ given by $q(A) := p(A|B)$ defines a probability space (Ω, \mathcal{E}, q) .

4 Constructing random variables

Learning Objectives

From random variables we will introduce distributions. There are two types:

- discrete distributions.
- continuous distributions.

A random variable is a quantity which depends on random events.⁴ It is a function on the possible outcomes.

Example

Suppose we are in the case of modeling 1 coin toss, 2.1, $(\Omega_1, \mathcal{E}_1, p)$. Then $\Omega_1 = \{H, T\}$ has 2^1 elements. Suppose we want to encode the idea: that "I go to party if I flip a heads". We encode

- "go to party" by number 1 and 0 otherwise.
- The idea that "go to party if heads and not if tails" is encoded

$$X : \Omega_1 \rightarrow \mathbb{R}$$

$$X(H) = 1, \quad X(T) = 0$$

We may ask "What is the probability that I go to party? " This is equivalent to asking what are the set of all possible tosses where I get H , or what is the set

$$p(X = 1) := p(X^{-1}(1)) = p(H) = \frac{1}{2}$$

Definition 4.1. Let (Ω, \mathcal{E}) and (Ω', \mathcal{E}') be two measurable spaces. A *measurable map* between the measurable spaces is

1. A map

$$f : \Omega \rightarrow \Omega'$$

2. For all $E' \in \mathcal{E}'$, $f^{-1}(E') \in \mathcal{E}$.

We will fix a probability space (Ω, \mathcal{E}, p) for discourse.

⁴It is neither *random* nor a *variable*

Definition 4.2. A random variable is a map⁵ of measurable spaces $X : (\Omega, \mathcal{E}) \rightarrow (\mathbb{R}, \mathcal{B}(\mathbb{R}))$.

1. It is *discrete*, if its *image*, $X(\Omega)$, is *countable* or *finite*.
2. *Continuous*, if it satisfies the property 4.7.

We denote the collection of discrete random variables on (Ω, \mathcal{E}, p) as $\text{RV}^{\text{disc}}(\Omega, \mathcal{E}, p)$.

However, what is the most interesting about a random variable?

- The values it takes.
- The probabilities it associates. For discrete rv, we can associate pmf, 2.5. For continuous rv, we associate a cdf, or in short, *distribution*, 4.1. Note that in literature, some may conflate the two terms together, as in the case of the pmfs we discuss below, def. 4.4, def. 4.5.

Definition 4.3. The *probability mass function (pmf)* of a discrete random variable X is a function

$$p_X : \mathbb{R} \rightarrow [0, 1]$$

such that

$$p_X(x) := p(X^{-1}(x))$$

We give three important distributions.

Definition 4.4. Bernoulli distribution. Let X be a random variable. ⁶

- It takes the value 0 and 1.
- $p_X(1) = p$ and $p_X(0) = q := 1 - p$.

In this case we write $X \sim \text{Ber}p$.

Definition 4.5. X has *Poisson* distribution with parameter $\lambda > 0$.

$$p(X = k) = \frac{1}{k!} \lambda^k e^{-\lambda} \quad k \in \mathbb{N}_{\geq 0}$$

In this case we write $X \sim \text{Poi}(\lambda)$

As mentioned earlier, we do not mention the model. By definition, this should be a pmf but we can also check

$$\sum_{k=0}^{\infty} \frac{1}{k!} \lambda^k e^{-\lambda} = e^{-\lambda} \sum_{k=0}^{\infty} \frac{1}{k!} \lambda^k = e^{-\lambda} e^{\lambda} = 1$$

Here are some common models that realize this random variables.

⁵Maps and functions are used interchangeably.

⁶This implies it is defined on some sample space.

Example

World cup soccer match.

- Ω the set of data of each world cup soccer match.
- $X : \Omega \rightarrow \mathbb{R}$, takes a match data, and out put the number of goals scored. e.g (fake) $X(\text{TW vs USA}) = 50$.
- The average event rate is 2.5 goals

We can thus use this random variable to model

$$p(k \text{ goals in a match}) = \frac{2.5^k e^{-2.5}}{k!}$$

4.1 Continuous random variables

Learning Objectives

- Discuss the normal distribution.

Definition 4.6. Let (Ω, \mathcal{E}, p) be a measure space. If $X \in \text{RV}(\Omega, \mathcal{E}, p)$, the *distribution of X* is

$$F_X : \mathbb{R} \rightarrow [0, 1]$$

$$F_X(x) := p(X \leq x)$$

Definition 4.7. A random variable X is *continuous* if its distribution may be written

$$F_X(x) = \int_{-\infty}^x f_X(u) du \quad x \in \mathbb{R}$$

for some nonnegative function $f_X : \mathbb{R} \rightarrow \mathbb{R}$. We say X has *probability density function (pdf)* f_X ⁷. Here the integral means the *improper integral* of f_X , ??.

Alternatively, the distribution can be encoded as *pushforward measure* of p . We will not delve into this too much.

Proposition 4.8. As set up in 4.6. Distribution can alternatively be regarded as

$$F_X = X_*p : B(\mathbb{R}) \rightarrow \mathbb{R}$$

where $B(\mathbb{R})$ is the natural *Borel* σ -algebra on \mathbb{R} , see 6.2. This is referred as the *law of X* .

⁷A prior this also mean that f_X is a function for which the integral exists.

What values can F_X tell us? It tell us the probability of observalues in some interval. For instance, for $(a, b]$,

$$p(a < X \leq b) = p(\{X \leq b\} \setminus \{X \leq a\}) = p(X \leq b) - p(X \leq a) = F_X(b) - F_X(a)$$

In this sense, the distribution of a function can recover the probability mass function, [2.5](#).

Definition 4.9. The *uniform distribution on $[a, b]$* . Let $a, b \in \mathbb{R}$, where $a < b$. Then define

$$F(x) = \begin{cases} 0 & \text{if } x < a \\ \frac{x-a}{b-a} & \text{if } a \leq x \leq b \\ 1 & \text{if } x > b \end{cases}$$

We can draw a sketch of this function. [diagram to be inserted]

4.1.1 Characterization of functions which are distributions

Can we characterize functions F which are distributions? The answer is positive, see thm 4.10. Often, we do not really care about the model of the random variable X .

- We only care about the probabilities assigned in the distribution function.
- It can be tedious about random variables and models.

So it really boils down to the study of certain functions with certain properties.

Theorem 4.10. F_X is the distribution of a random variable $X \in \text{RV}(\Omega, \mathcal{E}, p)$ iff F_X is a function satisfying the three axioms:

- $F_X(x) \leq F_X(y)$ if $x \leq y$.
- $F_X(x) \rightarrow 0$ as $x \rightarrow -\infty$, and $F_X(x) \rightarrow 1$ as $x \rightarrow \infty$.
- F_X is right continuous: for all $s \in \mathbb{R}$, $\lim_{t \rightarrow s^+} F_X(t) = F_X(s)$.

Note that the converse says that we can construct a probability space with a random variable such that F_X is the distribution associated to X .

Proof. (\Rightarrow) Suppose F is a distribution.

1. If $x \leq y$, then $\{X \leq x\} \subseteq \{X \leq y\}$. Then by axiom of measure, $p, F_X(x) = p(X \leq x) \leq p(X \leq y) = F_X(y)$
2. These two results are saying

$$p(X \leq -\infty) = 0 \quad p(X \leq +\infty) = 1$$

These follow from the continuity of p .

(\Leftarrow) We omit this for now and leave as a challenge. □

Note: distribution is not necessarily continuous.

4.1.2 Problems

Omitted.

5 What can we associate to random variable

Learning Objectives

- Learn how to compute expectation in the discrete and continuous case.

All forms of expectation for X a RV on probability space (Ω, \mathcal{E}, p) can be expressed as

$$\mathbb{E}[X] := \int_{\Omega} X dp$$

as we have not discussed integration in this context, we will do special cases.

Definition 5.1. The expectation for a discrete random variable, 4.2. Let $X \in \text{RV}^{\text{disc}}(\Omega, \mathcal{E}, p)$ ⁸ many outcomes. Then

$$\mathbb{E}[X] := \sum_{i=1}^{\infty} x_i p(X = x_i)$$

if the sum absolutely ⁹converges.

Definition 5.2. Let $X \in \text{RV}^{\text{cts}}(\Omega, \mathcal{E}, p)$. The *expectation* of X is given by

$$\mathbb{E}[X] := \int_{-\infty}^{\infty} x f_X(x) dx$$

whenever the integral absolutely converges, i.e. $\int_{-\infty}^{\infty} |x f_X(x)| dx$ exists.

The next quantity, whose definition is the same for both discrete and continuous.

Definition 5.3. Let X be a discrete or continuous random variable. Then

$$\text{Var}(X) := \mathbb{E}[(X - \mathbb{E}(X))^2]$$

This measures the degree of dispersion of a random variable *around its mean*.

5.0.1 problems

1. $X \sim \text{Ber}p$. Show

$$\mathbb{E}[X] = p$$

2. $X \sim \text{Bin}(n, p)$, show

$$\mathbb{E}[X] = np$$

⁸The countable case is not hard but requires some technical check.

⁹If it does not then it may not be well-defined.

3. In the n coin toss example, suppose there is a probability p of coming up heads.

$$p(H) = p, p(T) = 1 - p$$

We aim to compute the expected number of heads in terms of n and p .

- (a) Our probability space would be different. 2.1. How should we modify p ? In particular, give a formula for

$$p(\{\omega\})$$

where ω is a sequence of H and T.

- (b) Let X_i be the random variable that takes 1 when a head occurs at the i th toss, so that

$$X_i(\omega) := \begin{cases} 1 & \text{if } \omega_i = \text{head} \\ 0 & \text{otherwise} \end{cases}$$

where ω_i denotes the value of the i th toss.

$$\mathbb{E}(X_i) \quad 1 \leq i \leq n?$$

- (c) Let X be the random variable that counts the number of heads after n tosses. Express $\mathbb{E}(X)$ in terms of $\mathbb{E}(X_i)$, and hence find the value of $\mathbb{E}(X)$ in terms of n and p .

4. (*) Let $X \in \text{RV}^{\text{disc}}(\Omega, \mathcal{E}, p)$. Show that

$$\text{Var}(X) := \mathbb{E}(X^2) - E(X)^2$$

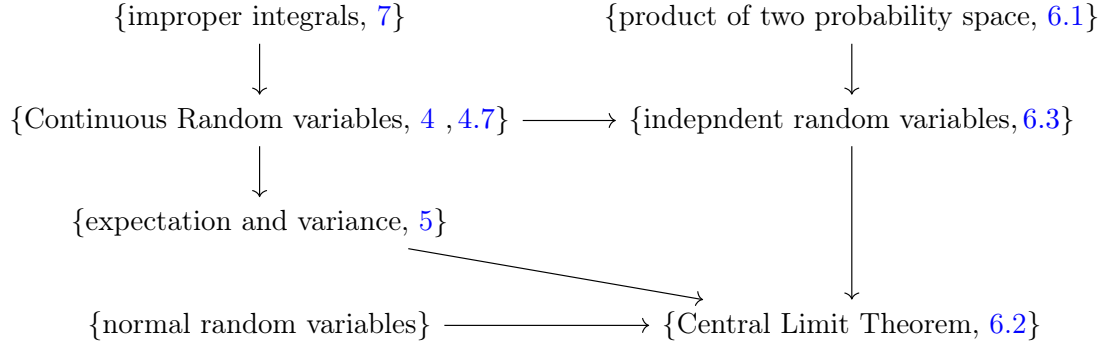
5.1 Continuity of measure

Omitted.

6 Central Limit Theorem

Learning Objectives

- Understand the statement of the central limit theorem *rigorously*.



The central limit theorem discusses the *stochastic convergence* of essentially random events eventually limiting to a event. We will make this idea precise.

There are various types of convergence we consider. The "weakest mode" of convergence is *convergence in distribution*.

Definition 6.1. Let $X_i \in \text{Seq}(\text{RV}(\Omega, \mathcal{E}, p))$, with F_i their associated distributions. We say X_n *converges to X in distribution*, or write

$$X_n \xrightarrow{\mathcal{D}} X$$

where $X \in \text{RV}^{\text{cts}}(\Omega, \mathcal{E}, p)$, is a random variable, with cdf, F if: for all $x \in X$ where F is continuous

$$\lim_{n \rightarrow \infty} F_n(x) \rightarrow F(x)$$

where F is continuous.

Theorem 6.2. Let X_1, X_2, \dots, X_n be iid copies of a random variable X . Suppose $\mathbb{E}[X_i] = \mu$, $\text{Var}[X_i] = \sigma^2 < \infty$. Then

$$\sqrt{n} (\bar{X}_n - \mu) \xrightarrow{\mathcal{D}} \mathcal{N}(0, \sigma^2)$$

$$\bar{X}_n := \frac{X_1 + \dots + X_n}{n}$$

6.0.1 Problems

1. Give 3 real life examples of normal distributions.
2. Give a one-page write-up of the the central limit theorem, 6.2. The content should be:
 - (a) Explain every term in the theorem. This is combining and digesting the content of the notes.
 - (b) Describe 2 applications of central limit theorem.

6.1 Product measures

Learning Objectives

- The notion of *product measure*. This forms as the foundation of multivariable calculus.

To begin with independence we need the notion of the product of a family of measurable space.

Definition 6.3. Let $(\Omega_1, \mathcal{E}_1), (\Omega_2, \mathcal{E}_2)$ be two measurable spaces. We will define a σ -algebra on $\Omega_1 \times \Omega_2$ as follows:

1. We consider the following *cylinder sets*

$$\mathcal{C} := \{(x_1, x_2) \in \Omega_1 \times \Omega_2 : x_i \in E_i\}$$

for $i \in \{1, 2\}$, $E_i \in \mathcal{E}_i$. Alternatively, these are sets of the form

$$E_1 \times \Omega_2, \Omega_1 \times E_2 \quad \text{where } E_1 \in \mathcal{E}_1, E_2 \in \mathcal{E}_2$$

2. We consider the *smallest σ -algebra* containing all the cylinder sets in $\Omega_1 \times \Omega_2$, $\sup^\sigma(\mathcal{C})$, as def 6.4.

Definition 6.4. Let $\mathcal{E}_0 \subseteq 2^\Omega$ be any collection of subsets of Ω . The *smallest σ -algebra* containing \mathcal{E}_0 , denoted

$$\sup^\sigma(\mathcal{E}_0)$$

is the unique σ -algebra on Ω satisfying

1. $\sup^\sigma(\mathcal{E}_0)$ is a σ -algebra on Ω which contains \mathcal{E}_0 .
2. If \mathcal{E}' is any other σ -algebra that contains \mathcal{E}_0 , then it contains $\sup^\sigma(\mathcal{E}_0)$, i.e. $\sup^\sigma(\mathcal{E}_0) \subseteq \mathcal{E}'$.

This is a common operation in many areas of maths. This is taking the least upper bound, *least upper bound*, def. ?? ¹⁰ in the context of the power set, $(2^\Omega, \subseteq)$. This operation only makes sense if it exists.

Proposition 6.5. Let $\mathcal{E}_0 \subseteq 2^\Omega$ be any collection of subsets of Ω . The operation of *smallest σ -algebra* 6.4 exists and is unique.

Proof. We show that $\sup^\sigma(\mathcal{E}_0)$ exists. To do this:

1. Note that there exists at least *one* σ algebra which contains \mathcal{E}_0 . $\mathcal{E}_0 \subseteq 2^\Omega$.
2. Let \mathcal{A} be the collection of all σ -algebras \mathcal{E}' which contains \mathcal{E}_0 . Then

$$\bigcap_{\mathcal{E}' \in \mathcal{A}} \mathcal{E}'$$

is the smallest σ -algebra which contains \mathcal{E}_0 . (Why?)

□

We have the following nontrivial result.

Theorem 6.6. Product of two probability spaces. Let $(\Omega_1, \mathcal{E}_1, p_1)$ and $(\Omega_2, \mathcal{E}_2, p_2)$ then there is a unique probability measure $p_1 \times p_2$ on $(\Omega_1 \times \Omega_2, \mathcal{E}_1 \times \mathcal{E}_2)$ satisfying

$$p_1 \times p_2(E_1 \times E_2) = p_1(E_1)p_2(E_2) \quad E_1 \in \mathcal{E}_1, E_2 \in \mathcal{E}_2$$

Proof. We will use the monotone class lemma, Prop. 6.7 to streamline the argument. □

Proposition 6.7. Monotone class lemma. Let \mathcal{A} be a boolean algebra, def ??, on Ω . Then

$$\sup^\sigma(\mathcal{A}) = \sup^{\text{mon}}(\mathcal{A})$$

6.2 The Borel σ -algebra on \mathbb{R}

Definition 6.8. $E \subseteq \mathbb{R}$ is open if for all $x \in E$, there is some $\varepsilon > 0$, such that $(x - \varepsilon, x + \varepsilon) \subseteq E$.

Then

Definition 6.9. The *Borel σ -algebra on \mathbb{R}* is

$$\mathcal{B}(\mathbb{R}) := \sup^\sigma \text{open}(\mathbb{R})$$

where $\text{open}(\mathbb{R})$ is the set of opens in \mathbb{R} .

¹⁰but where as the relation there is the order relation, (\mathbb{R}, \leq)

But how do we have a handle of such a complicated set?

Proposition 6.10. 1. If $E \subseteq_{\text{open}} \mathbb{R}$ then there exists at most countably many disjoint open interval I_j such that

$$E = \bigcup_{j=1}^{\infty} I_j$$

2. We have the following equality

$$\mathcal{B}(\mathbb{R}) = \sup^{\sigma}(\{(-\infty, a] : a \in \mathbb{Q}\})$$

6.2.1 Problems

1. Complete the proof of Prop. 6.5

- Show why the construction explained in proof yields a sigma algebra.
- Show that the newly constructed is unique.

2. (****) Prove 1. of 6.10.

3. (****) Prove 2. of 6.10.

6.3 Independence of random variables

Definition 6.11. Let $X_1, X_2, \dots, X_n \in \text{RV}(\Omega, \mathcal{E}, p)$ be n random variables. Then X_1, X_2, \dots are *jointly independent* if for all tuples of events $\{E_i\}_{i=1}^n$ in $B(\mathbb{R})$ (so each $E_i \in B(\mathbb{R})$, the borel set)

$$p\left(\bigcap X_i^{-1}(E_i)\right) = \prod p(X_i^{-1}(E_i))$$

There is a simplification of the above condition,

Proposition 6.12. [4, 2, Exercise 21] Let $X_1, \dots, X_n \in \text{RV}(\Omega, \mathcal{E}, p)$. Then X_i are jointly independent iff

$$p\left(\bigcap_{i=1}^n X_i(\leq t_i)\right) = p\left(\bigcap X_i^{-1}((-\infty, t_i])\right) = \prod_{i=1}^n p(X_i \leq t_i)$$

Note the first equality is the definition.

6.4 The normal distribution

Learning Objectives

- Do computations with the standard normal density function, 6.13.

The normal distribution is one of the most important *continuous* distributions. Many populations have distribution that fit closely to an appropriate normal curve.

1. height, weight physical characteristic.

One reason normal distribution is important is because of the central limit theorem, 6.2.

Definition 6.13. The *standard normal density function of mean μ and variance σ^2*

$$f_{\mu,\sigma}(x) := \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2}} \quad f_X : \mathbb{R} \rightarrow \mathbb{R} \quad (1)$$

where $\mu, \sigma \in \mathbb{R}$.

Let us list properties of the graph of f_X .

1. Normal distributions satisfy that they are closed under scaling and shifting.

Definition 6.14. Let X_1, \dots, X_n be random variables. We denote

$$\bar{X}_n := \frac{\sum_{i=1}^n X_i}{n}$$

Theorem 6.15. WLLN. Let X_1, \dots, X_n be iid random variables, such that $\mathbb{E}(X_i) = \mu < \infty$. Then

$$\lim_{n \rightarrow \infty} p(|\bar{X}_n - \mu| \geq \varepsilon) = 0$$

6.5 Problems

1. Graph the following density functions for:
 - f_X , the standard normal distribution, def 6.13.
2. Let $Z \sim N(0, 1)$, find the value of (e.g. on lookup tables available online)

$$p(Z \leq -1.25)$$

Show that $p(Z \leq -x) = p(Z \geq x)$.

3. Let X be a discrete random variable such that

$$p(X = k) = p_k \quad k = 0, 1, 2, \dots$$

Explain why

$$F_X(x) = \begin{cases} 0 & x < 0 \\ p_0 + \dots + p_{\lfloor x \rfloor} & x \geq 0 \end{cases}$$

4. Continuity of random variable. Let $X \in \text{RV}(\Omega, \mathcal{E}, p)$.
 - Show that if $p(X = c) > 0$, then F_X has a discontinuity at c . Is the converse true?
 - Let X be a continuous random variable. Show that $p(X = x) = 0$ for all $x \in \mathbb{R}$.

7 Improper Integral

Reading: [3, p283].

Definition 7.1. Let $a \in \bar{\mathbb{R}}$, see def. ??, $G : (a, +\infty) \rightarrow \mathbb{R}$ be a function.

$$\lim_{t \rightarrow +\infty} G$$

exists if there exists $L \in \bar{\mathbb{R}}$, such that

1. If $L \in \mathbb{R}$ finite: for all $\varepsilon > 0$, there exists $N_\varepsilon > 0$, such that for all $t > N_\varepsilon$,

$$|L - G(t)| < \varepsilon \quad \forall t > N_\varepsilon$$

2. If $L = +\infty$: for all M , there exists N_M such that for all $t > N_M$,

$$G(t) > M$$

This allows us to define the limit of integral.

Definition 7.2. For all $t > a$, if

$$G(t) := \int_a^t f(x) dx$$

exists and is finite, we can define a function

$$G : (a, +\infty) \rightarrow \mathbb{R}$$

We define

$$\int_a^\infty f(x) dx := \lim_{t \rightarrow +\infty} \int_a^t f(x) dx$$

if it exists and is *finite*. We say the integral $\int_a^\infty f(x) dx$ is *convergent* and *divergent* otherwise.

similarly we can define:

Definition 7.3. For all $t < b$ if

$$G(t) := \int_t^b f(x) dx$$

exists and is finite, define

$$G : (-\infty, b) \rightarrow \mathbb{R}$$

$$\int_{-\infty}^b f(x) dx := \lim_{t \rightarrow -\infty} \int_t^b f(x) dx$$

provided it exists and is finite. ¹¹ We say the integral $\int_{-\infty}^t f(x) dx$ is *convergent* and *divergent* otherwise.

¹¹We leave the reader to fill in the definition of $\lim_{t \rightarrow -\infty}$ for a function $H : (-\infty, b) \rightarrow \mathbb{R}$.

We can then extend this definition to two sided integral.

Definition 7.4. Let $c \in \mathbb{R}$. If

$$\int_{-\infty}^c f(x) dx \text{ and } \int_c^{\infty} f(x) dx$$

are convergent, then

$$\int_{-\infty}^{\infty} f(x) dx := \int_{-\infty}^c f(x) dx + \int_c^{\infty} f(x) dx$$

Note: $\int_{-\infty}^{\infty} f(x) dx$ exists, then for any other choice of c' ,

$$\int_{-\infty}^{c'} f(x) dx + \int_{c'}^{+\infty} f(x) dx = \int_{-\infty}^c f(x) dx + \int_c^{\infty} f(x) dx$$

Example

1. $\int_1^{\infty} \frac{1}{x} dx$. Recall

7.0.1 Problems:

1. Show that $\int_{-\infty}^0 \frac{1}{2-x} dx$ is divergent.
2. Compute

$$\int_{-\infty}^{\infty} x e^{-x^2}$$

References

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