

# Conor Wood Hayes

 cwoodhayes.github.io  github.com/cwoodhayes  linkedin.com/in/cwoodhayes  cwoodhayes@gmail.com  (949) 554 3392

## EDUCATION

**Northwestern University** – *M.S. Robotics* Sep 2025–Dec 2026 (expected)  
**University of Southern California** – *B.S. Computer Engineering & Computer Science* 2015–2019  
*Magna Cum Laude. Minor in Chinese for the Professions, Thematic Option (Honors in Liberal Arts)*

## SKILLS

**Programming Languages:** Python, C++, C, CMake, Bash/Zsh, Rust, SQL, TypeScript, Verilog, Assembly  
**Robotics:** SLAM, Computer Vision, Tactile Sensing, State Estimation, Robot Kinematics & Dynamics, Path Planning, Control Theory  
**Machine Learning & AI:** Deep Learning, Imitation Learning, Foundation Models (LLM/VLM/VLA), Reinforcement Learning  
**Software:** ROS 2, PyTorch, NumPy, Pandas, Linux, Git, Docker, AWS, CI/CD, Databases  
**Hardware:** PCB Design, Electronics, Microcontrollers, CAD (OnShape), 3D Printing, Laser Cutting

## WORK EXPERIENCE

**Conor Hayes Software Consulting, Inc** | *CEO* 2023 - 2025, IN/NY/CA  
– Built reusable hardware testing framework (Python) for two \$500K nuclear fusion test racks, driving on-time delivery in 8mos.  
– Redesigned BLE protocol (C, TypeScript) for NRF52-based wearable. +2 sensors, +800% bandwidth, -10% power consumption.  
– Prototyped a low-latency peer-to-peer telepresence platform for controlling robots via web client (WebRTC, AWS, TypeScript).

**Wesper, Inc** | *Software Engineer (8th employee @ startup)* 2020 - 2022, New York City  
– Developed sleep apnea diagnosis wearable from prototype to FDA cleared mass product as lead firmware developer (C, NRF5X).  
– Added new sensors, on-device algorithms, and BLE services to enable real-time reporting of heart rate, SpO2, and sleep pose.  
– Led a team of 3 to build backend from scratch (AWS ECS, EC2,  $\lambda$ , S3, RDS MySQL, Python) to ingest and process all patient data.

**Honeybee Robotics** | *Software & Electrical Engineering Intern* May - Aug 2018, Pasadena, CA  
– Developed drivers, middleware (C++, ZeroMQ), and GUIs (Qt), for ROS-based testing framework for space exploration robotics.  
– Designed, assembled, and validated PCB (Altium) to provide human-in-the-loop control of small drills on remote oil rigs.

**NASA Jet Propulsion Laboratory** | *Flight Electronics Intern (Group 349E) - Sphinx Project* Jan - Aug 2017, Pasadena, CA  
– Developed still-in-use automated test system & BSP modules (C, Python, assembly) for first deep-space cubesat avionics system.  
– Supported initial board bring-up, discovered critical bugs in novel rad-hardened NAND flash controller & other peripherals.

## PROJECTS

**PolyUMI — Visual-Tactile Data Collector for Dextrous Manipulation Imitation Learning** Jan-Mar 2026  
– Designed & built wireless handheld grasping data collector (based on UMI) with novel sensor array including visual touch sensor.  
– Developed data extraction, cleaning, & visualization pipeline (Python, ROS 2) to support training a visual-tactile diffusion policy.  
– Created motion mimicry demo for Franka Panda 7DoF arm that replays PolyUMI trajectories as derived from ORB-SLAM.

**LeHome Challenge 2026 - Vision-Language-Action (VLA) Model for Bimanual Garment Folding** Jan-Mar 2026  
– Trained 2 SO-101 arms to fold laundry using VLA (LeRobot SmolVLA) fine-tuned on teleoperation data in Isaac Sim.  
– Generated diverse synthetic training data with domain randomization + data augmentation (NVIDIA Cosmos, Python).

**Simultaneous Localization and Mapping (SLAM) from Scratch** Jan-Mar 2026  
– Developed & deployed from-scratch Extended Kalman Filter (EKF) LiDAR SLAM pipeline for Turtlebot3 (ROS2, C++).  
– Implemented custom RViz-based simulation environment to test diff-drive control, odometry, and lidar algorithms.

**PenPal — Handwriting with the Franka Panda 7DoF Robot Arm** Nov-Dec 2025  
– Designed system architecture, led group of 4 to create a robot arm-based handwriting system for a randomly moving whiteboard.  
– Developed online, reactive trajectory generation and closed-loop visual cartesian control (Python, ROS 2, MoveIt 2, RealSense).  
– Integrated VLM (gemini-2.0-flash) to create real-time conversational loop (user writes question, arm writes response, repeat).

**Traveler IV — First 100% undergrad-made rocket to fly to space (USC Rocket Propulsion Lab)** 2018-2019  
– Built & led 30-person avionics team overseeing all software & electronics to manufacture and fly high-performance rockets.  
– Developed flight software (C++), PCB's (Altium), EGSE (Python, ham radio), and data analysis (Matlab) for custom avionics system.  
– Debugged electrical, software, and radio issues in the field under timing constraints, inclement weather, and poor infrastructure.

## AWARDS + HOBBIES

**American Institute of Astronautics and Aeronautics** | *Achievement Award* Oct 2019  
**National Academy of Engineering/USC** | *Grand Challenges Scholar* May 2019  
**University of Southern California** | *Renaissance Scholar (0.9% of graduating class)* May 2019  
**Recorded Music:** Accumulated 700,000+ Spotify streams on original music under artist name *Wise John* (24 songs, 1 album, 1 EP).