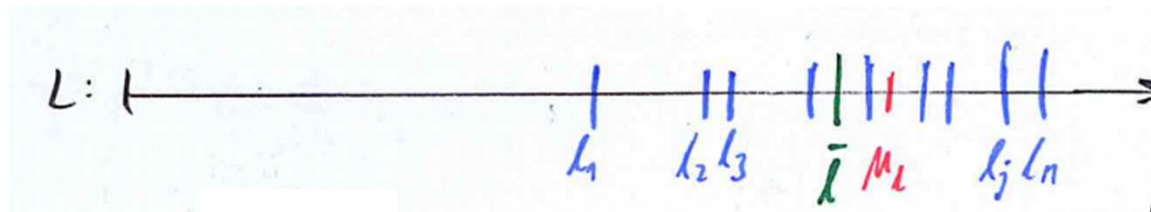


2.4.1 Definition of dispersion measures

Given: Random variable L with its realizations l_j , $j = 1, 2, 3, \dots, n$

sample \rightarrow „observation vector“



for when we integrate

$$\mathbf{l} = \begin{bmatrix} l_1 \\ l_2 \\ \vdots \\ l_n \end{bmatrix}$$

n observations for the same random variable L

All observations originate from the same population ($n \rightarrow \infty$)

\Rightarrow Expectation $E(L) = \mu_L$

Wanted: Dispersion measure

Handwritten notes: "Zusatz" (addition) pointing to ε_j , "Wert of n " pointing to $\forall j$, "Mean" pointing to μ_L

$$\varepsilon_j = l_j - \mu_L \quad \forall j$$

Random Deviations, „random errors“
„actual – nominal“

$$\boldsymbol{\varepsilon} = \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{bmatrix} = \begin{bmatrix} l_1 - \mu_L \\ l_2 - \mu_L \\ \vdots \\ l_n - \mu_L \end{bmatrix} = \mathbf{l} - \mathbf{e} \cdot \mu_L$$

Vector of deviations “error vector”

Values ε_j contain information about dispersion of single observation

Variance, if probability density is known (theoretical variance)

Definition of variance as measure of dispersion of a random variable (accuracy measure):

sign = theoretical variance

$$\sigma_l^2 = E(\varepsilon^2) = E\{(l - \mu_L)^2\} = \boxed{E(l^2) - \mu_L^2} \quad \text{-- end point?}$$
expectation of random error

$$\sigma_l^2 = E(\varepsilon^2) = \lim_{n \rightarrow \infty} \left\{ \frac{1}{n} \sum_{j=1}^n \varepsilon_j^2 \right\} = \lim_{n \rightarrow \infty} \left\{ \frac{1}{n} \cdot \boldsymbol{\varepsilon}^T \cdot \boldsymbol{\varepsilon} \right\} \quad \underline{\text{Theoretical Variance}}$$

Variance σ^2 is the mean of the squared ε_j

$$\sigma_l = +\sqrt{\sigma_l^2} \quad \underline{\text{Theoretical Standard deviation}}$$

Standard deviation σ is the (positive) square root of the variance σ^2

If we know the probability density function $f(x)$, we can compute the variance of a random variable directly (without observations):

$$\sigma_x^2 = E(\varepsilon^2) = E\{(x - \mu_X)^2\}$$

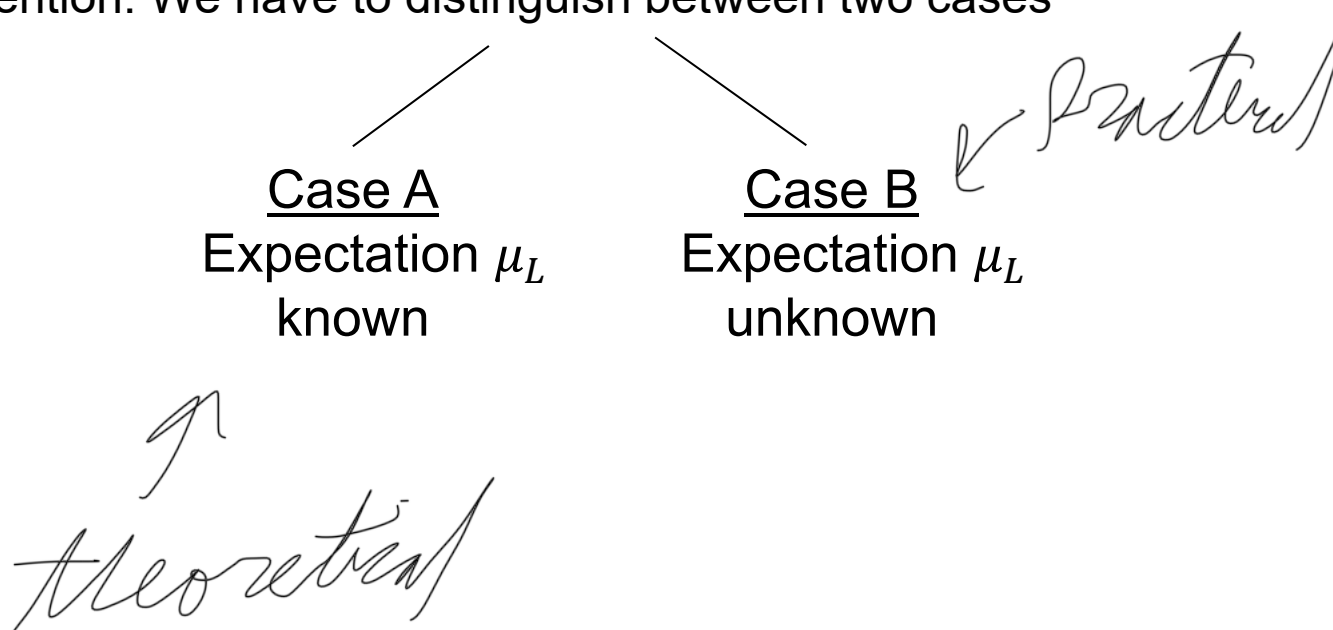
$$\boxed{\sigma_x^2 = \int_{-\infty}^{+\infty} (x - \mu_X)^2 f(x) dx}$$
 Theoretical Variance

with $f(x)$ = density of x

2.4.2 Empirical dispersion measures

If we consider n observations (measurements, empirical values), we can compute the empirical standard deviation s as estimation for the theoretical standard deviation σ .

Attention: We have to distinguish between two cases



2.4.2.1 Expectation μ_L of the random variable is known (CASE A)

Given:

- Random variable L with its realizations l_j , $j = 1, 2, 3, \dots, n$
- Observation vector $\mathbf{I}^T = (l_1 l_2 \dots l_n)$ with $n \ll \infty$
- Known expectation $E(L) = \mu_L$

\Rightarrow Vector of random deviations $\boxed{\boldsymbol{\varepsilon} = \mathbf{L} - \mathbf{e} \cdot \mu_L}$

2.4.2.1 Expectation μ_L of the random variable is known (CASE A)

Wanted: Estimation s_l^2 for the theoretical variance σ_l^2

$$s_l^2 = \frac{\varepsilon_1^2 + \varepsilon_2^2 + \dots + \varepsilon_n^2}{n} = \frac{1}{n} \sum_{j=1}^n \varepsilon_j^2 = \frac{1}{n} \mathbf{\varepsilon}^T \cdot \mathbf{\varepsilon}$$

Empirical Variance of a single observation

Very important! KNOWN!

$$s_l = +\sqrt{s_l^2}$$

Empirical **Standard Deviation** of a single observation

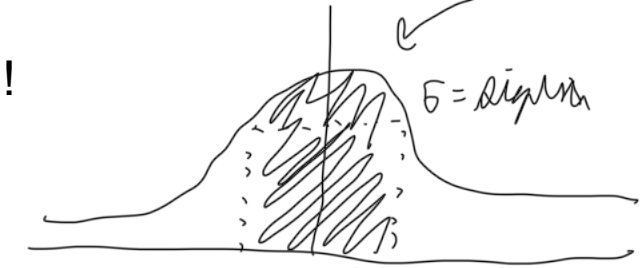
— also depression value → mechanical

It holds: $E(s_l^2) = \sigma_l^2$ Empirical variance s_l^2 is an unbiased estimate of the theoretical variance σ_l^2 .

it pulls in

but: $E(s_l) \neq \sigma_l$ Empirical standard deviation s_l is not an unbiased estimate of the theoretical standard deviation σ_l !

Usually $E(s_l) < \sigma_l$



S_l = 2.29 cm

≈ 68.3%

2.4.2.2 Expectation μ_L of the random variable is unknown (CASE B)

Given: - Random variable L with its realizations l_j , $j = 1, 2, 3, \dots, n$
- Observation vector $\mathbf{I}^T = (l_1 l_2 \dots l_n)$ with $n \ll \infty$

Not known: Expectation $E(L) = \mu_L$

Wanted: Estimation s_l^2 for the theoretical variance σ_l^2

2.4.2.2 Expectation μ_L of the random variable is unknown (CASE B)

Solution: **Replace expectation μ_L by the mean value \bar{l}**

Mean!

$$\bar{l} = \frac{1}{n} \sum_{j=1}^n l_j = \frac{1}{n} \cdot \mathbf{e}^T \cdot \mathbf{l}$$

Empirical mean or arithmetic mean

with $\mathbf{e} = \begin{bmatrix} 1 \\ 1 \\ \vdots \\ 1 \end{bmatrix}$

$$v_j = \bar{l} - l_j \quad \forall j$$

Mean
Observations

Residuals

Check: $\sum_{j=1}^n v_j \stackrel{!}{=} 0$

Must be 0

$$\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = \begin{bmatrix} \bar{v} - v_1 \\ \bar{v} - v_2 \\ \vdots \\ \bar{v} - v_n \end{bmatrix} = \mathbf{e} \cdot \bar{l} - \mathbf{l}$$

Vector of residuals

- slide 92
computational error

2.4.2.2 Expectation μ_L of the random variable is unknown (CASE B)

$$s_l^2 = \frac{v_1^2 + v_2^2 + \dots + v_n^2}{\underbrace{(n-1)}_f} = \frac{1}{(n-1)} \sum_{i=1}^n v_i^2 = \frac{1}{n-1} \mathbf{v}^T \cdot \mathbf{v} \quad \text{Empirical Variance of a single observation}$$

f : degree of freedom – *how much info do you have too much*
 • “redundancy”
 – *you measure 10x = 4° of freedom*

$$s_l = + \sqrt{s_l^2}$$

Empirical Standard Deviation of a single observation

2.4.2.2 Expectation μ_L of the random variable is unknown (CASE B)

It holds: $E(s_l^2) = \sigma_l^2$ Empirical variance s_l^2 is an unbiased estimate
of the theoretical variance σ_l^2 .

but: $E(s_l) \neq \sigma_l$ Empirical standard deviations s_l is not an unbiased estimate
of the theoretical standard deviation σ_l .

Usually $E(s_l) < \sigma_l$.

One “information” (one degree of freedom f) ”number of redundant observations”
is used for the estimation of the mean $\bar{l} \Rightarrow$ we have to divide by $f = n - 1$.

2.4.2.3 Standard Deviation of an arithmetic mean

- Given:
- Standard deviation of a single observation s_l from random deviations (CASE A from 2.4.2.1) or from residuals (CASE B from 2.4.2.2)
 - Arithmetic mean \bar{l} from n observations

Definitions: Variance of an arithmetic mean \bar{l} from n observations

$$s_{\bar{l}}^2 = \frac{s_l^2}{n}$$

Standard deviation of an arithmetic mean \bar{l} from n observations

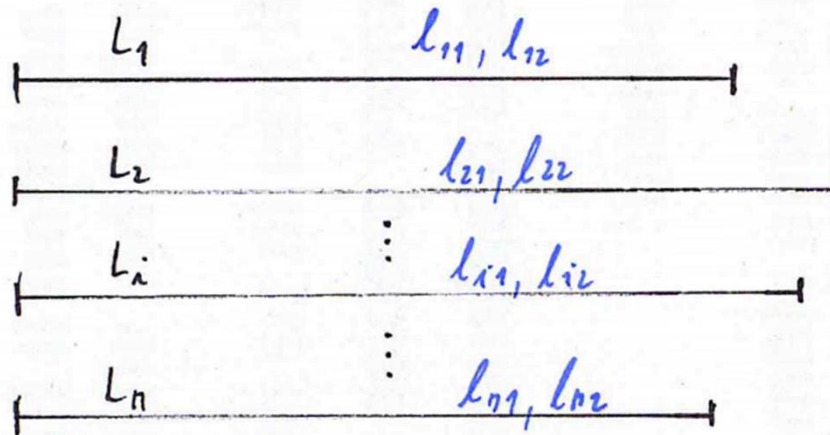
$$s_{\bar{l}} = \frac{s_l}{\sqrt{n}}$$

Standard deviation of a single observation s_l can be computed from random deviations or from residuals.

Residual Vector
scale, rotation, shear
 $\vec{y} \rightarrow \vec{x} = \vec{z} = \text{vector}$
slide 39

2.4.2.4 Standard Deviation for double measurements of same precision

Given: Several random variables have each been measured 2 times



$$\mathbf{L}^T = [L_1 \ L_2 \ \cdots \ L_n]$$

Random Vector

$$\mathbf{I}_1^T = [l_{11} \ l_{21} \ \cdots \ l_{n1}]$$

first series of observations

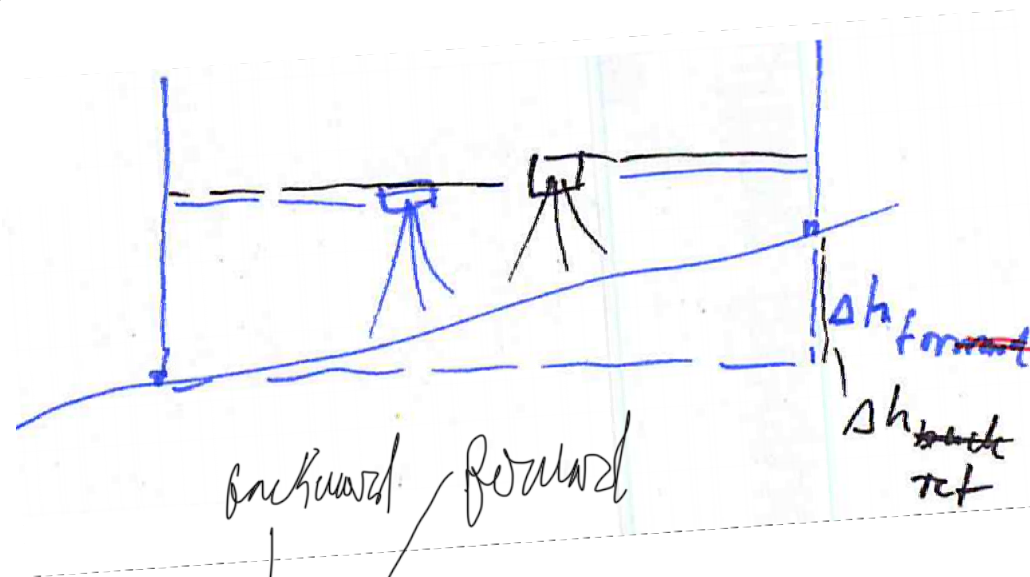
$$\mathbf{I}_2^T = [l_{12} \ l_{22} \ \cdots \ l_{n2}]$$

second series of observations

Wanted: Estimation s_l^2 for the theoretical variance σ_l^2

Solution: Computation of differences from double measurements

Example: Difference in the height difference from forward survey and return survey
 $(d = \Delta h_{for} - \Delta h_{ret})$ in differential levelling



Observation differences d_j for each double measurement

$$d_j = l_{j2} - l_{j1} \quad \text{for } j = 1, 2, \dots, n$$

$$\mathbf{d} = \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \end{bmatrix} = \mathbf{l}_2 - \mathbf{l}_1 = \begin{bmatrix} l_{12} - l_{11} \\ l_{22} - l_{21} \\ \vdots \\ l_{n2} - l_{n1} \end{bmatrix}$$

Standard deviation of a single observation l_{j1} or l_{j2}

$$s_l = \sqrt{\frac{1}{2n} \mathbf{d}^T \cdot \mathbf{d}} = \sqrt{\frac{d_1^2 + d_2^2 + \dots + d_n^2}{2n}} = \sqrt{\frac{\sum d^2}{2n}} \quad \text{Empirical Standard Deviation of a single observation}$$

Standard Deviation $s_{\bar{l}}$ of the arithmetic mean from both observations

$$s_{\bar{l}} = \frac{s_l}{\sqrt{2}} = \frac{1}{2} \sqrt{\frac{\sum d^2}{n}} \quad \text{Empirical Standard Deviation of the arithmetic mean}$$

Adjustment Theory I

Chapter 2: Random Variables

Prof. Dr.-Ing. Frank Neitzel

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