

# Interactive Evolution of Camouflage

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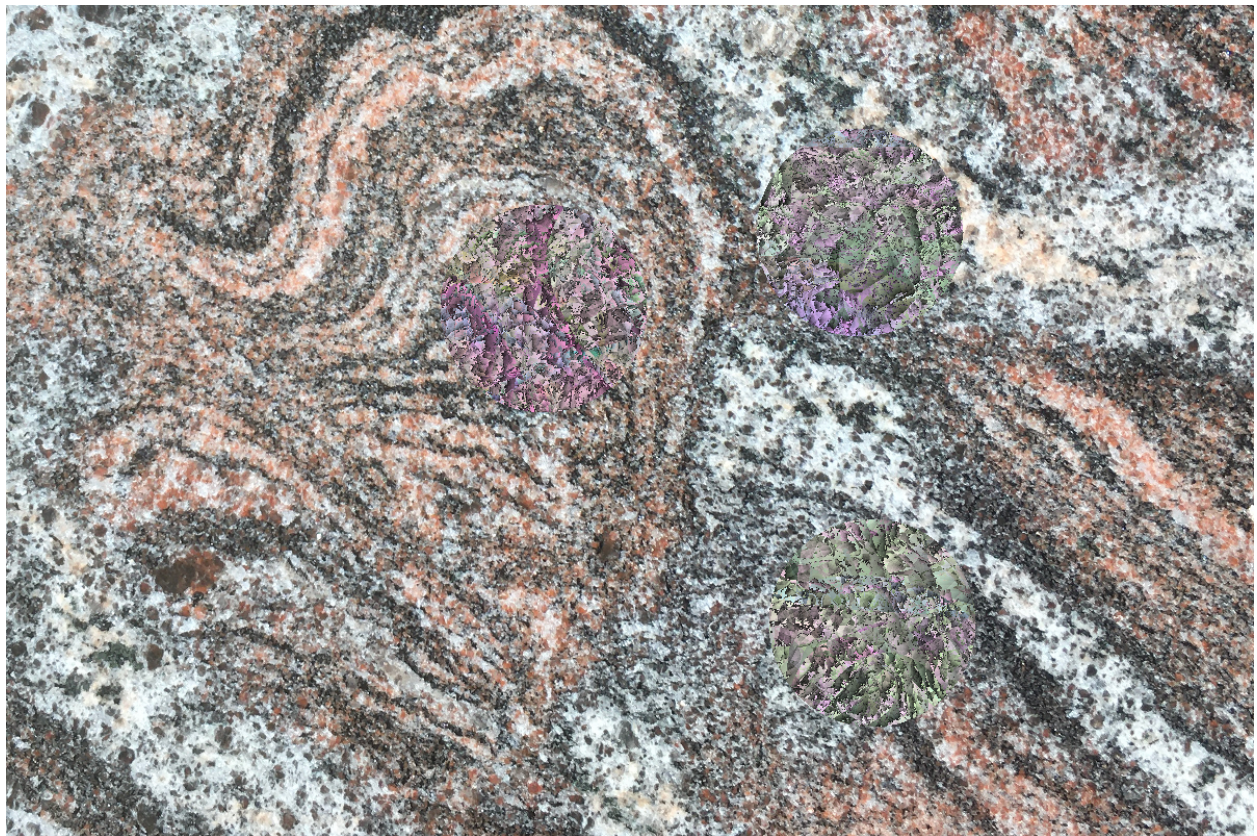


Fig. 1: photograph of a polished granite counter-top in bright sun, overlaid with three synthetic “prey,” circular samples of evolved camouflage texture.

# Abstract

A simple computer simulation of the evolution of camouflage in nature is described. Several examples are given. The model is based on a game-like concept with a human “player” in the loop to act as a predator. This is a reimplementation of a technique first implemented in 2009 [???]. The basic concepts are the same between the earlier work and this new implementation. The point of this work was to write a clean modern software infrastructure, to verify the old results could be reproduced, and to then move on new topics in this general area of research.

## Background

This report describes experiments in generating 2d camouflage patterns in response to 2d background textures. In these experiments, the backgrounds are all photographs of the natural world, taken with a mobile phone.

After a brief description of the software used, results of interactive “runs” will be presented, followed by some conclusions.

## Description of software

These experiments use three primary software components. First is a library for procedural texture synthesis called *TexSyn*. Second is a general purpose engine for optimization via evolutionary computation, called *LazyPredator*. And third is a simple interactive application that uses those components to make a game-like simulation where camouflage evolves in response to selection pressure from a predator played by the human.

## App

That interactive app is defined by a c++ class called *EvoCamoGame* and is invoked from the unix style command line (maxOS *Terminal* app) with an executable called *evo\_camo\_game*.

## Procedural texture synthesis

*TexSyn* is a library for procedural texture synthesis. It defines objects representing an abstract model of two dimensional color textures. Common digital images are defined by a rectangular array of pixel values each representing a color. *TexSyn*’s textures are purely procedural: defined by code. These textures represent an infinite 2d plane. For any given location on that plane the texture can return a color.

In c++ terms: these textures are represented by instances of type *Texture*, a base class. *Texture* defines a “virtual member function” called *getColor()* which maps a *Vec2* position ( $x, y$  Cartesian coordinates as floating point numbers) into a *Color* value ( $r, g, b$  where monitor gamut is the positive unit cube). *TexSyn* defines about fifty specialized types derived from *Texture*. They each “override” the *getColor()* function. A few define a texture from only numeric parameters, such as *Uniform*, which has the same color everywhere on the plane. Most of *TexSyn*’s classes are *texture operators* which take one or more *Textures* as parameters. Complex *TexSyn* textures are nested expressions — “trees” — which describe combinations of many texture operators. Typically these trees have between 100 and 200 operators (plus various numeric values at the leaves) but there is no explicit upper bound on size.

[??? should I give an example of code and image here, or save that for a later more detailed section ???]

The development of *TexSyn* since late 2019 has been documented in this [development log](#). The open source code for *TexSyn* is in a publicly available [repository](#) at [GitHub](#).

## Optimization

In these experiments, an *optimization* process is used to find textures that meet certain criteria. Generally this means to start from some sort of initial guess, often random, and incrementally improving it to be closer to a goal. In this work the initial guess is a “random texture”—perhaps better to say an arbitrary texture, sampled from a very large distribution of possible textures. This universe of textures is defined by nested expressions (trees) of *TexSyn* operators, of less than a given maximum size.

There are many kinds of optimization processes used across various fields, with a long history going back to *Newton’s method*. Widely known are the gradient descent techniques used in very high dimensional space for modern *deep learning*.

An even more ancient method for optimization is evolution in the natural world. While not strictly “optimization” from a mathematical perspective, the process of evolution explores spaces of vast dimensionality to produce well adapted and complex living organisms. In nature this exploration is based primarily on genetic variation from crossover and mutation of DNA. Resulting organisms compete for survival and resources. Those who thrive have increased “reproductive success” and so pass on more of their genes to their offspring.

Complex natural organism such as animals have nervous systems that learn and reason from experience. Stepping back, it is possible to see intelligence (during an animal’s lifetime) and evolution (across many generations of animals) as related phenomena. They are both processes of *self organization*. This is the perspective of Leslie Valiant’s engaging 2013 book *Probably Approximately Correct (Nature’s Algorithms for Learning and Prospering in a Complex World)*.

Similarly, we can draw a rough equivalence between computer optimization algorithms inspired by learning and those inspired by evolution.

## Evolutionary computation

...

[??? procedural metric/fitness/loss, or not (interactive) ???]

## Genetic programming

...

## OpenCV

...

**old:**

This is an alpha test version of software for “interactive evolution of camouflage” as described in my 2011 paper: Interactive Evolution of Camouflage. This 2021 app `evo_camo_game` is built from new components: the TexSyn library for procedural texture synthesis, and the LazyPredator library for evolutionary optimization via genetic programming. For more information see the development blog for TexSyn.

Very quick overview

This program is a crude simulation of the evolution of camouflage in nature. There is a predator-prey system. Software for texture optimization plays the part of an evolving population of camouflaged “prey.” The human user serves as a predator hunting its prey with vision. This can be seen as a sort of minimalist “game” or a human based computation. The app displays a window with a random portion taken from a given set of photographs. Over that background are drawn three randomly positioned disks of synthetic texture—three “prey.” The human user/player/predator then decides which of the three textures/prey is most conspicuous or least well camouflaged, indicating their selection by clicking/tapping on that prey. The window will go blank then display the next step. Runs typically consist of 1000 such steps or more. They can be stopped at any time. Results are currently saved during as image files, and texture “source code” in text files, as described below.