# one\_stationary Experiment Report

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This is a summary of the data from the one\_stationary experiment.

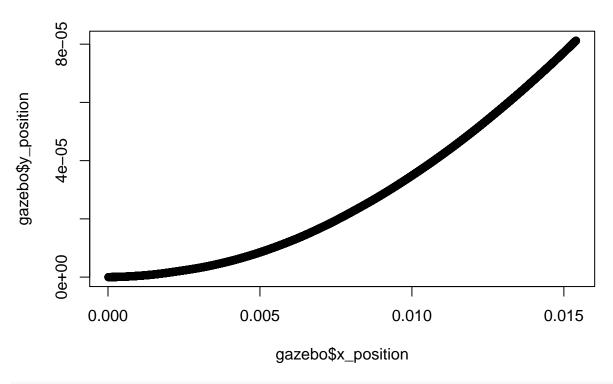
Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

```
summary(continuous$x_error)
##
               1st Qu.
                          Median
                                       Mean
                                              3rd Qu.
        Min.
## 2.999e-06 1.458e-05 1.830e-05 1.770e-05 2.139e-05 3.752e-05
summary(continuous$y error)
                 1st Qu.
##
                             Median
                                                   3rd Qu.
                                                                 Max.
         Min.
                                           Mean
## -9.339e-09
               4.456e-08 8.527e-08 1.181e-07
                                                 1.853e-07 4.544e-07
summary(continuous$dist_error)
                          Median
        Min.
               1st Qu.
                                      Mean
                                              3rd Qu.
## 2.999e-06 1.458e-05 1.830e-05 1.770e-05 2.139e-05 3.753e-05
summary(discrete$x_error)
             1st Qu.
                       Median
                                        3rd Qu.
                                  Mean
## -4.37900 -0.45480
                      0.01812
                              0.07371
                                        0.64580
                                                  2.95300
summary(discrete$y_error)
##
               1st Qu.
                          Median
                                       Mean
                                              3rd Qu.
                                                           Max.
## -4.336000 -0.564000 0.007488 0.061680 0.670600
                                                       3.743000
summary(discrete$dist_error)
                                  Mean 3rd Qu.
       Min. 1st Qu.
                       Median
## 0.000014 0.503700 1.043000 1.277000 1.917000 4.790000
if (params$robot >= 2) {
    summary(external_data_averages)
```

Shown below are plots representing the robot's motion and error over time.

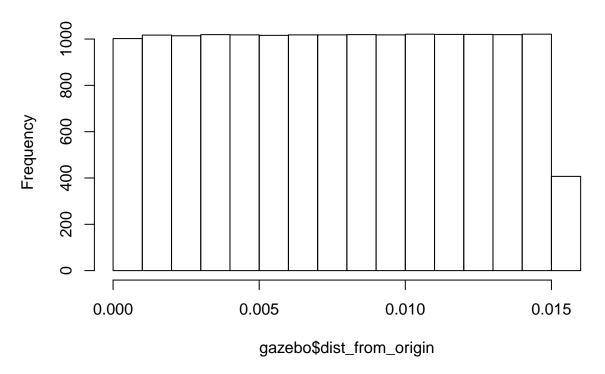
```
plot(gazebo$x_position, gazebo$y_position,
    main = "Ground truth visited locations of robots")
```

### **Ground truth visited locations of robots**



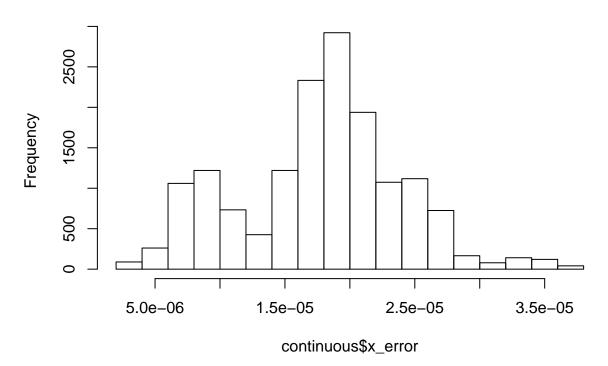
```
hist(gazebo$dist_from_origin,
    main = "Distance from origin vs. time")
```

## Distance from origin vs. time



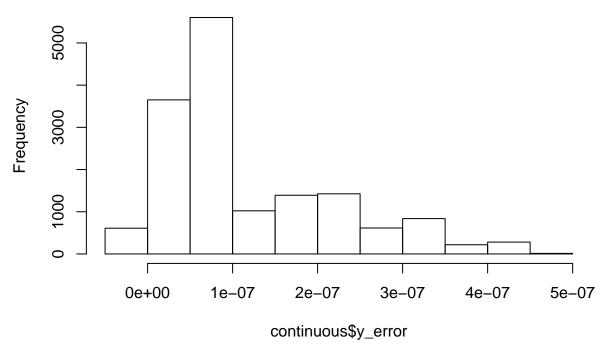
hist(continuous\$x\_error,
 main = "Continuous x\_error")

## Continuous x\_error



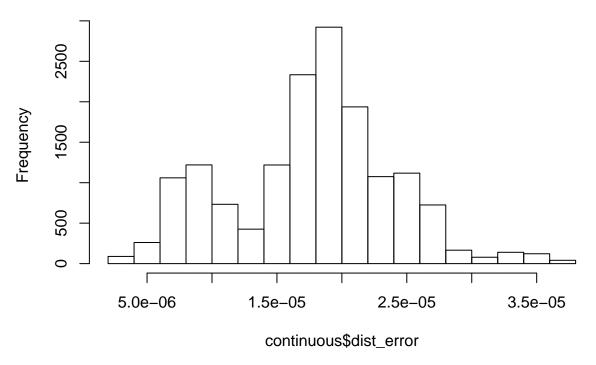
```
hist(continuous$y_error,
    main = "Continuous y_error")
```

# Continuous y\_error



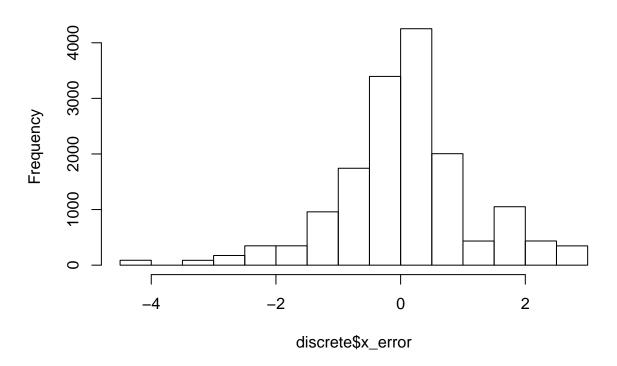
```
hist(continuous$dist_error,
    main = "Continuous total distance error")
```

### **Continuous total distance error**



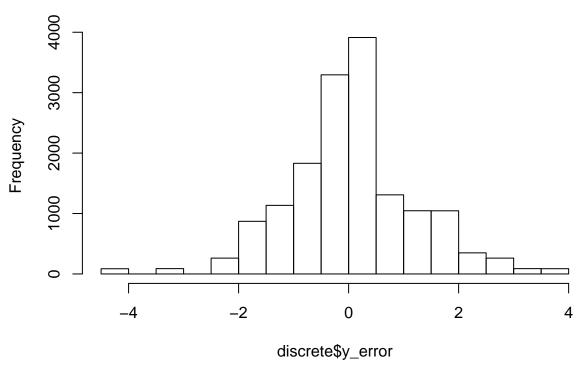
hist(discrete\$x\_error,
 main = "Discrete x\_error")

## Discrete x\_error



```
hist(discrete$y_error,
    main = "Discrete y_error")
```

## Discrete y\_error



```
hist (discrete$dist_error,
    main = "Discrete total distance error")
```

## Discrete total distance error

