

five_mobile_restricted Turtlebot 1 Report

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June 24, 2016

This is a summary of the data from the five_mobile_restricted experiment, Turtlebot #1.

The runtime of this experiment was 1 hours, 59 minutes, and 3657.6 seconds.

The total number of external pose measurements recieved by the robot during this time was 212847 which means poses were received at an average of 29.5719406 poses per second.

Shown below is the summary of each filter's error for both x and y coordinates, and also the error in total distance.

```
summary(continuous$x_error)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
## -0.09403 0.11250 0.12500 0.09609 0.13760 0.15020
```

```
summary(continuous$y_error)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
## -0.06217 0.03479 0.04207 0.03724 0.04940 0.10180
```

```
summary(continuous$dist_error)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
## 3.800e-07 1.253e-01 1.337e-01 1.184e-01 1.431e-01 1.535e-01
```

```
summary(discrete$x_error)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
## -0.03484 0.46200 0.47450 0.41630 0.48700 0.65370
```

```
summary(discrete$y_error)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
## -0.0436 0.2816 0.2893 0.2958 0.2971 0.5762
```

```
summary(discrete$dist_error)
```

```
##      Min. 1st Qu.  Median    Mean 3rd Qu.    Max.
## 0.0000004 0.5523000 0.5587000 0.5267000 0.5654000 0.6885000
```