one_mobile Experiment Report

Matthew Swartwout July 12, 2016

This is a summary of the data from the one_mobile experiment.

Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

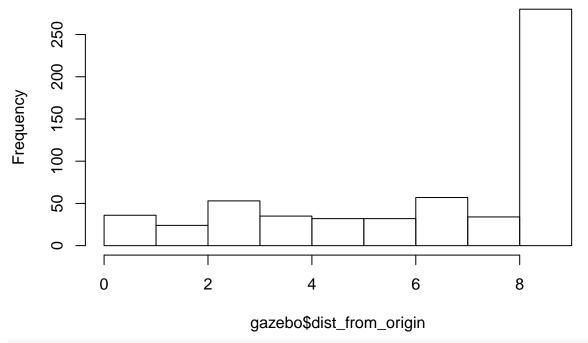
```
summary(continuous$x_error)
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
                                                                   Max.
## -4.394e-02 -1.544e-03
                           6.435e-05
                                      4.040e-03
                                                  1.065e-02
                                                             4.643e-02
summary(continuous$y_error)
##
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
                                                                   Max.
## -2.355e-02 -9.989e-05 1.908e-03
                                      7.570e-03
                                                  1.753e-02
                                                             5.393e-02
summary(continuous$dist_error)
##
        Min.
               1st Qu.
                           Median
                                               3rd Qu.
                                       Mean
                                                             Max.
## 2.100e-07 8.731e-04 1.447e-02 1.632e-02 2.881e-02 5.412e-02
summary(discrete$x_error)
##
               1st Qu.
        Min.
                           Median
                                               3rd Qu.
                                       Mean
                                                             Max.
## -0.332000 -0.002622 0.000013 0.012630 0.014370
                                                        0.358000
summary(discrete$y_error)
##
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
## -0.2226000 -0.0001666 0.0002314
                                                 0.0105300
                                      0.0048770
                                                             0.4109000
summary(discrete$dist_error)
##
        Min.
               1st Qu.
                           Median
                                       Mean
                                               3rd Qu.
                                                             Max.
## 0.0000000 0.0006044 0.0159300 0.0374900 0.0333800 0.4492000
if (params$robot >= 2) {
    summary(external_data_averages)
}
Shown below are plots representing the robot's motion and error over time.
plot(gazebo$x_position, gazebo$y_position,
     main = "Ground truth visited locations of robots")
```

Ground truth visited locations of robots



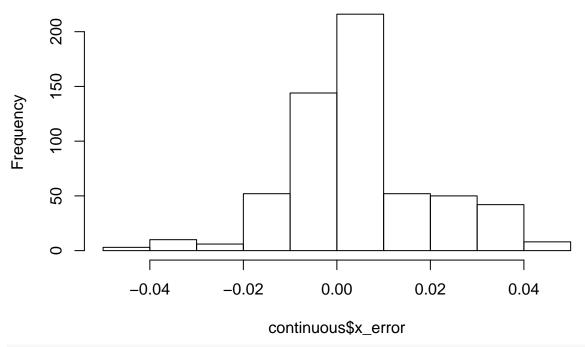
hist(gazebo\$dist_from_origin,
 main = "Distance from origin vs. time")

Distance from origin vs. time

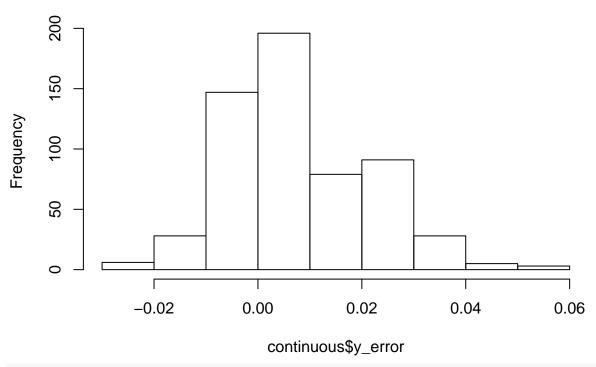


hist(continuous\$x_error,
 main = "Continuous x_error")

Continuous x_error

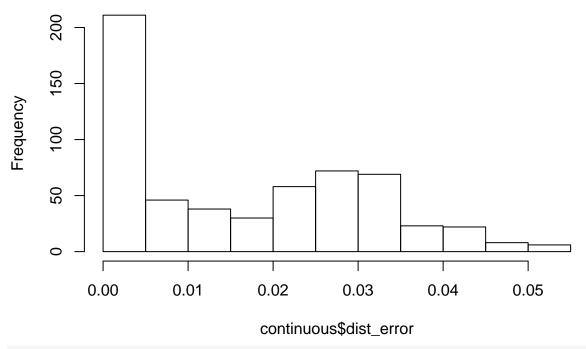


Continuous y_error



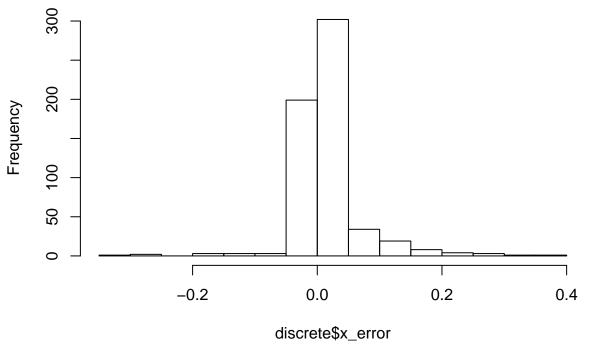
hist(continuous\$dist_error,
 main = "Continuous total distance error")

Continuous total distance error



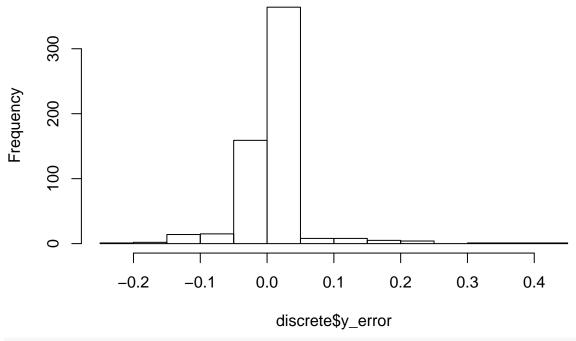
hist(discrete\$x_error,
 main = "Discrete x_error")

Discrete x_error



hist(discrete\$y_error,
 main = "Discrete y_error")

Discrete y_error



hist (discrete\$dist_error,
 main = "Discrete total distance error")

Discrete total distance error

