one_mobile Experiment Report

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This is a summary of the data from the one_mobile experiment.

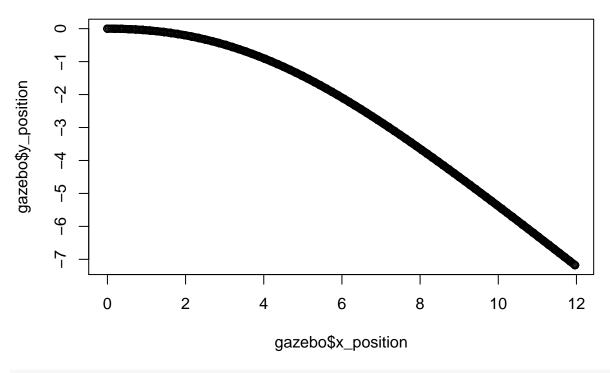
Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

```
summary(continuous$x_error)
               1st Qu.
##
                                               3rd Qu.
        Min.
                           Median
                                       Mean
    0.000016
              3.532000
                        6.629000
                                   6.374000
                                             9.321000 11.960000
summary(continuous$y_error)
      Min. 1st Qu. Median
                               Mean 3rd Qu.
                                               Max.
## -7.1750 -4.7810 -2.5500 -2.8470 -0.6909
                                             0.0000
summary(continuous$dist_error)
##
        Min.
               1st Qu.
                          Median
                                       Mean
                                               3rd Qu.
                                                            Max.
              3.599000 7.102000 7.028000 10.480000 13.950000
summary(discrete$x_error)
         Min.
                 1st Qu.
                              Median
                                                    3rd Qu.
                                           Mean
## -0.0643400
               0.0000050
                          0.0001593
                                                 0.0248100
                                      0.0475200
                                                             0.3840000
summary(discrete$y_error)
##
                 1st Qu.
                              Median
                                           Mean
                                                    3rd Qu.
                                                                  Max.
## -0.3316000 -0.0119000 -0.0001312 -0.0315000 -0.0000029
                                                             0.0735600
summary(discrete$dist_error)
        Min.
               1st Qu.
                          Median
                                       Mean
                                               3rd Qu.
                                                            Max.
## 0.0000001 0.0000077 0.0002543 0.0591900 0.0364800 0.4488000
if (params$robot >= 2) {
    summary(external_data_averages)
```

Shown below are plots representing the robot's motion and error over time.

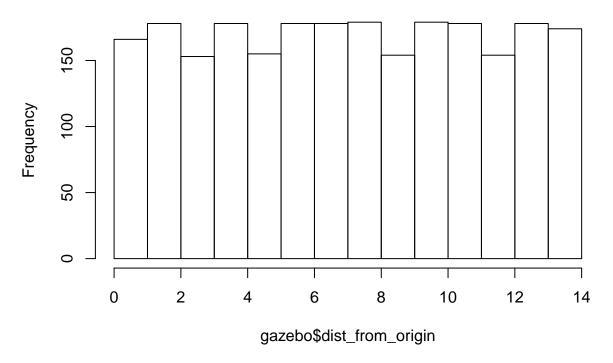
```
plot(gazebo$x_position, gazebo$y_position,
    main = "Ground truth visited locations of robots")
```

Ground truth visited locations of robots



```
hist(gazebo$dist_from_origin,
    main = "Distance from origin vs. time")
```

Distance from origin vs. time



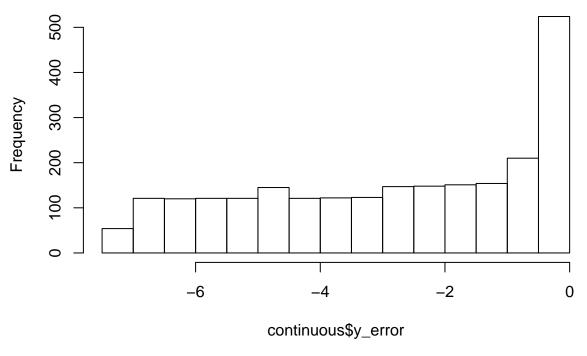
hist(continuous\$x_error,
 main = "Continuous x_error")

Continuous x_error



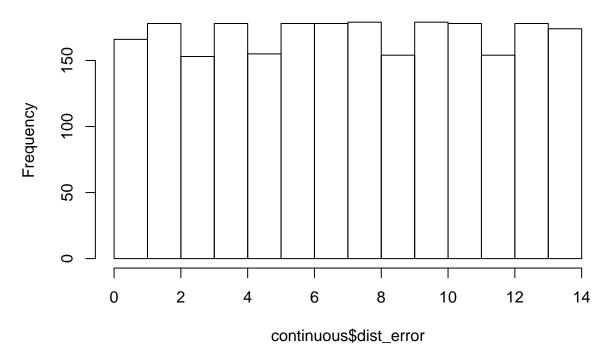
```
hist(continuous$y_error,
    main = "Continuous y_error")
```

Continuous y_error



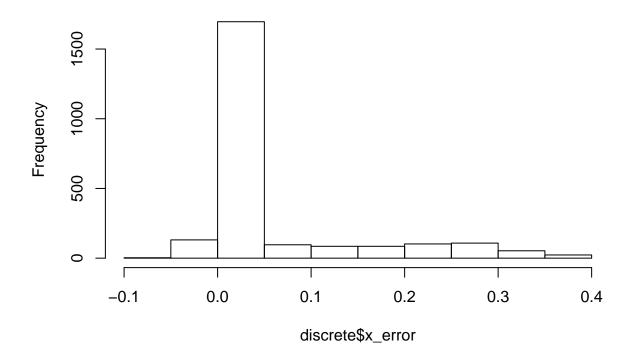
```
hist(continuous$dist_error,
    main = "Continuous total distance error")
```

Continuous total distance error



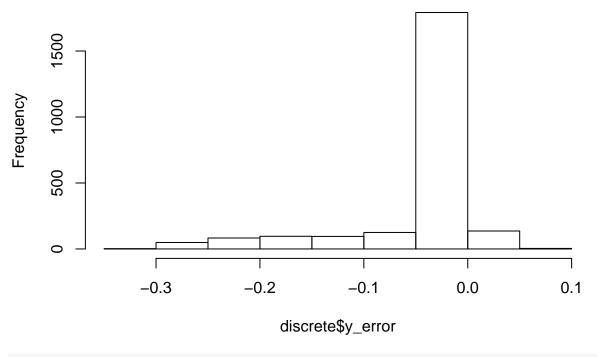
hist(discrete\$x_error,
 main = "Discrete x_error")

Discrete x_error



```
hist(discrete$y_error,
    main = "Discrete y_error")
```

Discrete y_error



```
hist (discrete$dist_error,
    main = "Discrete total distance error")
```

Discrete total distance error

