

two_mobile_restricted Turtlebot 1 Report

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This is a summary of the data from the two_mobile_restricted experiment, Turtlebot #1.

The runtime of this experiment was 1 hours, 59 minutes, and 3658.7 seconds.

The total number of external pose measurements recieved by the robot during this time was 217228 which means poses were received at an average of 30.176004 poses per second.

Shown below is the summary of each filter's error for both x and y coordinates, and also the error in total distance.

```
summary(t1_continuous$x_error)
```

```
##      Min.   1st Qu.   Median     Mean   3rd Qu.     Max.
## -0.001963  0.012160  0.017090  0.016920  0.021910  0.026630
```

```
summary(t1_continuous$y_error)
```

```
##      Min.   1st Qu.   Median     Mean   3rd Qu.     Max.
## -0.003293  0.012140  0.026110  0.026200  0.040120  0.054170
```

```
summary(t1_continuous$dist_error)
```

```
##      Min.   1st Qu.   Median     Mean   3rd Qu.     Max.
## 5.220e-06 1.719e-02 3.121e-02 3.167e-02 4.571e-02 6.036e-02
```

```
summary(t1_discrete$x_error)
```

```
##      Min.   1st Qu.   Median     Mean   3rd Qu.     Max.
## -0.02305  0.01535  0.02025  0.02000  0.02504  0.02975
```

```
summary(t1_discrete$y_error)
```

```
##      Min.   1st Qu.   Median     Mean   3rd Qu.     Max.
## -0.01440  0.01001  0.02373  0.02386  0.03764  0.05169
```

```
summary(t1_discrete$dist_error)
```

```
##      Min.   1st Qu.   Median     Mean   3rd Qu.     Max.
## 5.220e-06 1.843e-02 3.110e-02 3.217e-02 4.520e-02 5.964e-02
```