two_mobile Experiment Report

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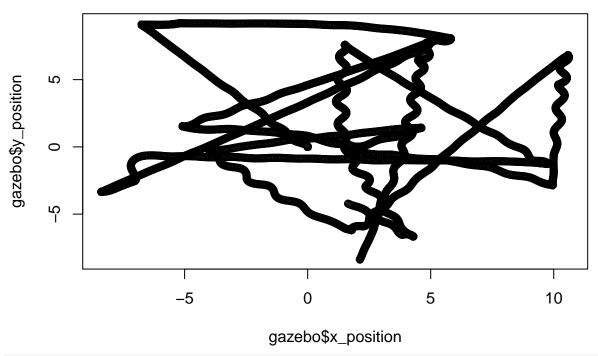
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This is a summary of the data from the two_mobile experiment.

Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

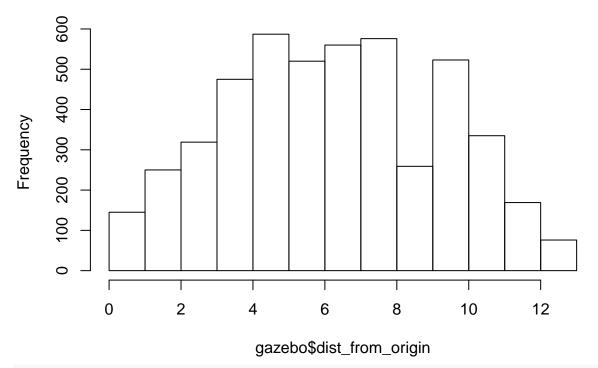
```
summary(continuous$x_error)
       Min. 1st Qu.
                       Median
                                   Mean 3rd Qu.
                                                      Max.
## -0.98070 -0.40150 -0.19170 -0.23690 -0.02373
                                                  0.14840
summary(continuous$y_error)
##
            1st Qu.
                       Median
                                   Mean
                                         3rd Qu.
                                                      Max.
## -0.54180 -0.25140 -0.02361 -0.08977
                                         0.06782
                                                   0.26310
summary(continuous$dist_error)
##
        Min.
               1st Qu.
                           Median
                                       Mean
                                              3rd Qu.
                                                            Max.
## 0.0000001 0.1092000 0.3276000 0.3418000 0.4838000 0.9857000
summary(discrete$x_error)
##
       Min. 1st Qu.
                       Median
                                         3rd Qu.
                                   Mean
                                                      Max.
                                         1.66000
## -0.80970 -0.02245 0.60000
                                0.79960
                                                  2.01700
summary(discrete$y_error)
##
       Min. 1st Qu.
                       Median
                                   Mean
                                                      Max.
## -0.49080 -0.22370 0.00000 -0.05375
                                         0.08874
                                                  0.30210
summary(discrete$dist_error)
##
        Min.
               1st Qu.
                           Median
                                       Mean
                                              3rd Qu.
                                                            Max.
## 0.0000001 0.1475000 0.9324000 0.9725000 1.6790000 2.0280000
if (params$robot >= 2) {
    summary(external_data_averages)
}
        Length Class Mode
## [1,] 1
               -none- numeric
## [2,] 1
               -none- numeric
Shown below are plots representing the robot's motion and error over time.
plot(gazebo$x_position, gazebo$y_position,
    main = "Ground truth visited locations of robots")
```

Ground truth visited locations of robots



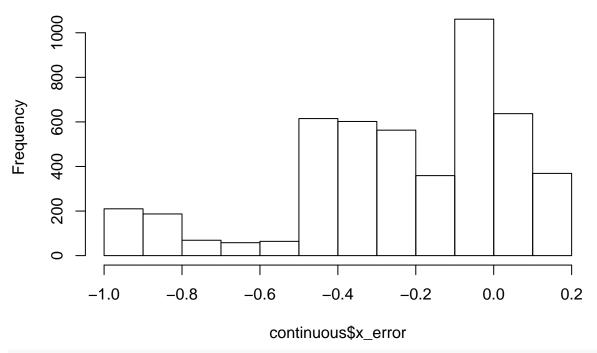
hist(gazebo\$dist_from_origin,
 main = "Distance from origin vs. time")

Distance from origin vs. time



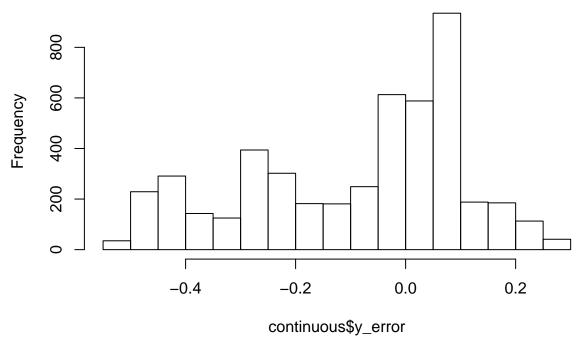
hist(continuous\$x_error,
 main = "Continuous x_error")

Continuous x_error



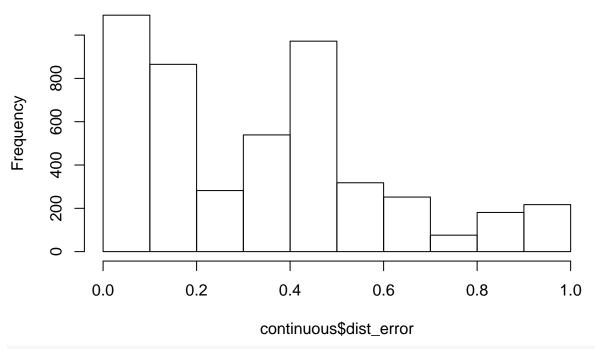
hist(continuous\$y_error,
 main = "Continuous y_error")

Continuous y_error



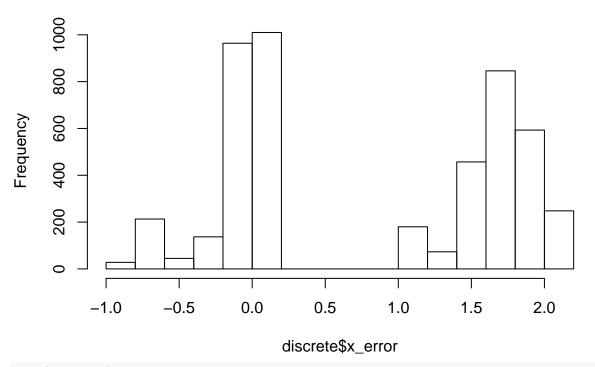
hist(continuous\$dist_error,
 main = "Continuous total distance error")

Continuous total distance error



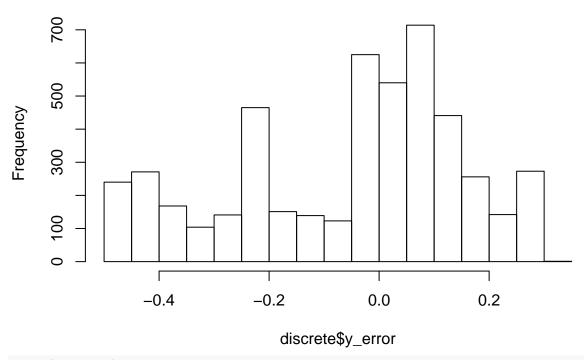
hist(discrete\$x_error,
 main = "Discrete x_error")

Discrete x_error



hist(discrete\$y_error,
 main = "Discrete y_error")

Discrete y_error



hist (discrete\$dist_error,
 main = "Discrete total distance error")

Discrete total distance error

