## one\_stationary.R

## matt

Wed Jun 22 16:41:34 2016

```
t1_gazebo <- read.csv("~/thesis/experiment_data/one_stationary/turtlebot1_gazebo_odometry_filtered.csv"
t1_continuous <- read.csv("~/thesis/experiment_data/one_stationary/turtlebot1_continuous_odometry_filtered.
t1_discrete <- read.csv("~/thesis/experiment_data/one_stationary/turtlebot1_discrete_odometry_filtered.
t1_external_count <- read.csv("~/thesis/experiment_data/one_stationary/turtlebot1_external_pose_count.c

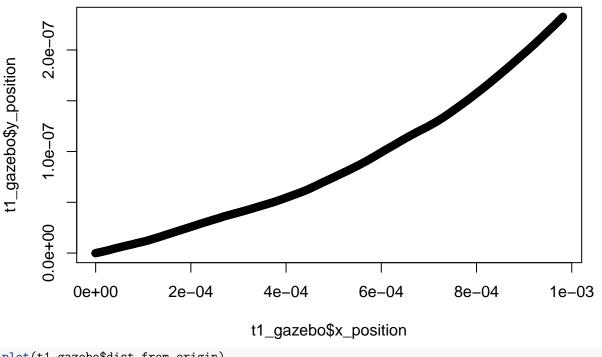
t1_gazebo$dist_from_origin <- sqrt(t1_gazebo$x_position ^ 2 + t1_gazebo$y_position ^ 2)

t1_discrete$x_error <- t1_gazebo$x_position - t1_discrete$x_position
 t1_discrete$y_error <- t1_gazebo$y_position - t1_discrete$y_position
 t1_discrete$dist_error <- sqrt(t1_discrete$x_error ^ 2 + t1_discrete$y_error ^ 2)

t1_continuous$x_error <- t1_gazebo$x_position - t1_continuous$x_position
 t1_continuous$y_error <- t1_gazebo$y_position - t1_continuous$y_position
 t1_continuous$dist_error <- sqrt(t1_continuous$x_error ^ 2 + t1_continuous$y_error ^ 2)

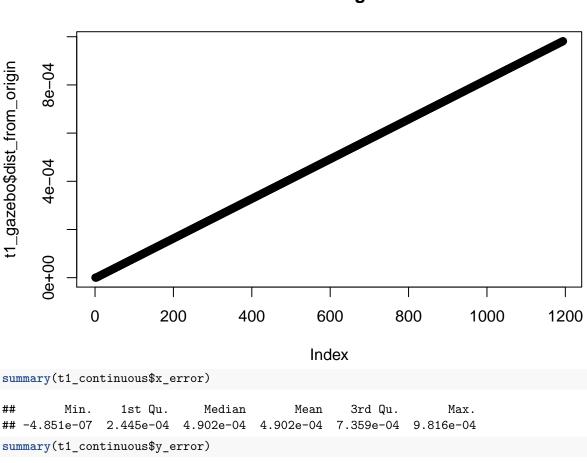
plot(t1_gazebo$x_position, t1_gazebo$y_position)
 title("Ground truth visited locations of robot")</pre>
```

## **Ground truth visited locations of robot**



```
plot(t1_gazebo$dist_from_origin)
title("Distance from origin vs. time")
```

## Distance from origin vs. time



## Min. 1st Qu. Median Mean 3rd Qu. Max. ## -1.205e-10 3.243e-08 7.244e-08 8.738e-08 1.354e-07 2.327e-07 summary(t1\_continuous\$dist\_error)

## Min. 1st Qu. Median Mean 3rd Qu. Max. ## 2.553e-07 2.445e-04 4.902e-04 4.902e-04 7.359e-04 9.816e-04 summary(t1\_discrete\$x\_error)

## Min. 1st Qu. Median Mean 3rd Qu. Max. ## -4.851e-07 2.445e-04 4.902e-04 4.902e-04 7.359e-04 9.816e-04 summary(t1\_discrete\$y\_error)

## Min. 1st Qu. Median Mean 3rd Qu. Max. ## -1.205e-10 3.243e-08 7.244e-08 8.738e-08 1.354e-07 2.327e-07 summary(t1\_discrete\$dist\_error)

## Min. 1st Qu. Median Mean 3rd Qu. Max. ## 2.553e-07 2.445e-04 4.902e-04 4.902e-04 7.359e-04 9.816e-04