# two\_mobile\_restricted Experiment Report

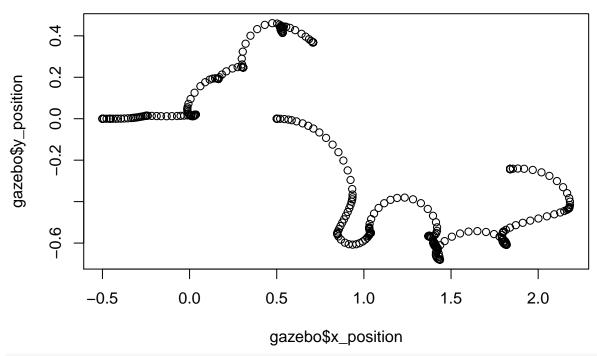
# Matthew Swartwout July 12, 2016

This is a summary of the data from the two\_mobile\_restricted experiment.

Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

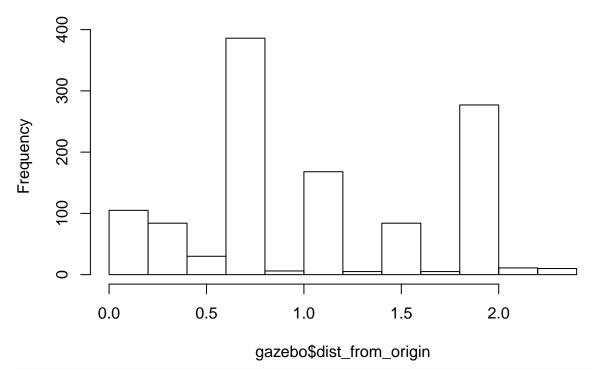
```
summary(continuous$x_error)
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
## -3.750e-02 -2.420e-06
                           2.140e-06
                                      1.427e-03
                                                  4.451e-05
                                                             4.859e-02
summary(continuous$y_error)
##
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
                                                                   Max.
## -4.436e-02 -1.250e-05 -1.430e-06 -5.128e-04
                                                  1.160e-06
                                                             2.566e-02
summary(continuous$dist_error)
##
        Min.
               1st Qu.
                           Median
                                       Mean
                                               3rd Qu.
## 4.400e-07 2.660e-06 1.534e-05 3.597e-03 1.289e-03 4.964e-02
summary(discrete$x_error)
##
        Min.
               1st Qu.
                           Median
                                               3rd Qu.
                                       Mean
                                                            Max.
## -0.198500 -0.016630 0.000002 0.007922
                                             0.023230
summary(discrete$y_error)
##
         Min.
                 1st Qu.
                              Median
## -2.783e-01 -1.046e-02 -7.400e-07 -5.011e-04 4.275e-02 2.823e-01
summary(discrete$dist_error)
        Min.
               1st Qu.
                           Median
                                       Mean
                                               3rd Qu.
                                                            Max.
## 0.0000001 0.0000253 0.0502200 0.0810700 0.1608000 0.4459000
if (params$robot >= 2) {
    summary(external_data_averages)
}
        Length Class Mode
## [1,] 1
               -none- numeric
## [2,] 1
               -none- numeric
Shown below are plots representing the robot's motion and error over time.
plot(gazebo$x_position, gazebo$y_position,
     main = "Ground truth visited locations of robots")
```

#### **Ground truth visited locations of robots**



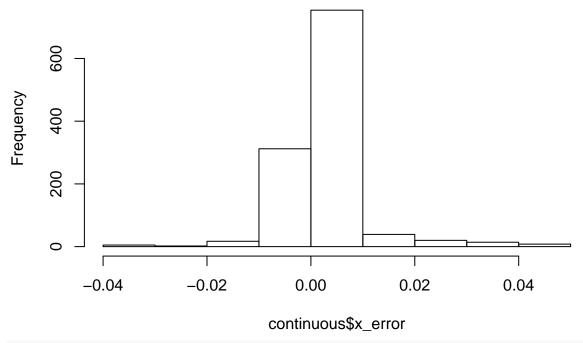
hist(gazebo\$dist\_from\_origin,
 main = "Distance from origin vs. time")

### Distance from origin vs. time



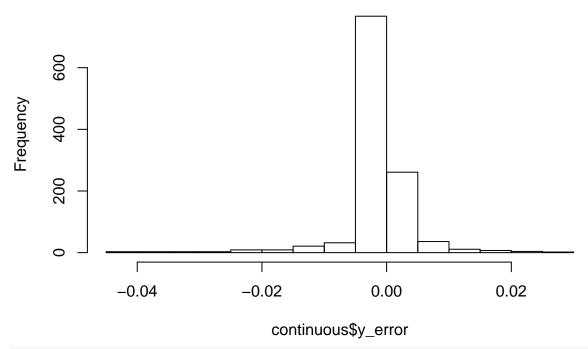
hist(continuous\$x\_error,
 main = "Continuous x\_error")

## Continuous x\_error



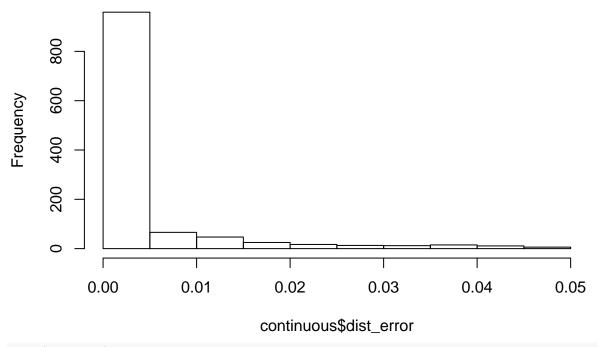
hist(continuous\$y\_error,
 main = "Continuous y\_error")

## Continuous y\_error



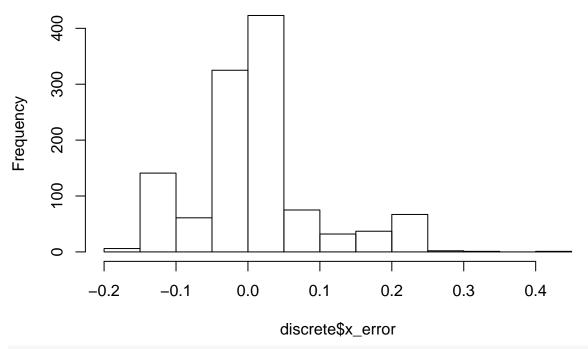
hist(continuous\$dist\_error,
 main = "Continuous total distance error")

#### **Continuous total distance error**



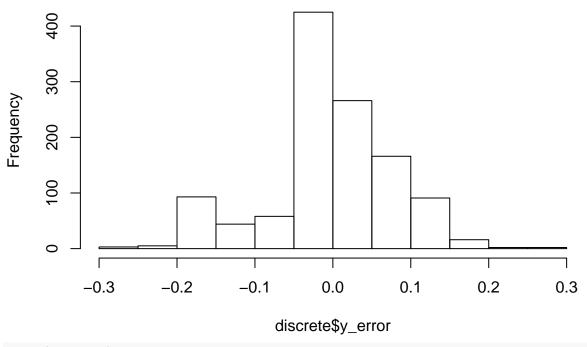
hist(discrete\$x\_error,
 main = "Discrete x\_error")

### Discrete x\_error



hist(discrete\$y\_error,
 main = "Discrete y\_error")

## Discrete y\_error



hist (discrete\$dist\_error,
 main = "Discrete total distance error")

#### Discrete total distance error

