

one_stationary Experiment Report

Matthew Swartwout

July 11, 2016

This is a summary of the data from the one_stationary experiment.

Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

```
summary(continuous$x_error)
```

##	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
##	2.000	2.001	2.001	2.001	2.002	2.002

```
summary(continuous$y_error)
```

##	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
##	2	2	2	2	2	2

```
summary(continuous$dist_error)
```

##	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
##	2.828	2.829	2.829	2.829	2.830	2.830

```
summary(discrete$x_error)
```

##	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
##	1.266e-06	3.129e-06	4.976e-06	5.264e-06	7.403e-06	9.310e-06

```
summary(discrete$y_error)
```

##	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
##	-4.717e-09	1.316e-09	3.633e-09	4.342e-09	6.647e-09	1.794e-08

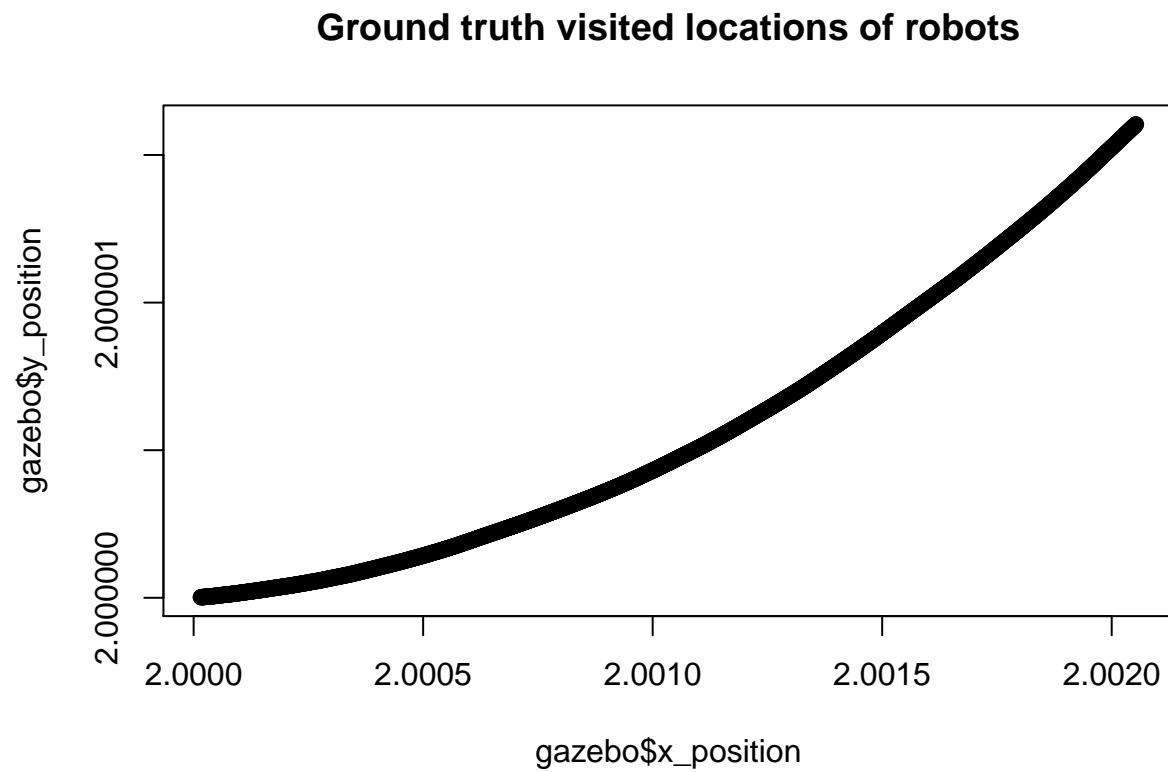
```
summary(discrete$dist_error)
```

##	Min.	1st Qu.	Median	Mean	3rd Qu.	Max.
##	1.266e-06	3.129e-06	4.976e-06	5.264e-06	7.403e-06	9.310e-06

```
if (params$robot >= 2) {  
  summary(external_data_averages)  
}
```

Shown below are plots representing the robot's motion and error over time.

```
plot(gazebo$x_position, gazebo$y_position,  
     main = "Ground truth visited locations of robots")
```



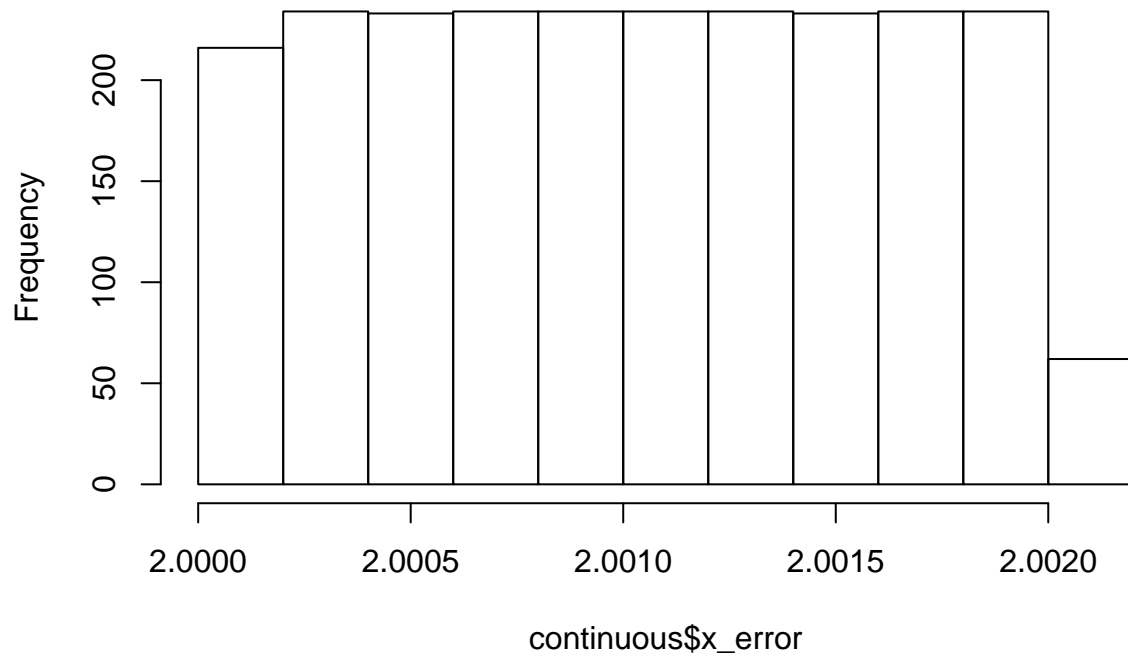
```
hist(gazebo$dist_from_origin,  
     main = "Distance from origin vs. time")
```

Distance from origin vs. time

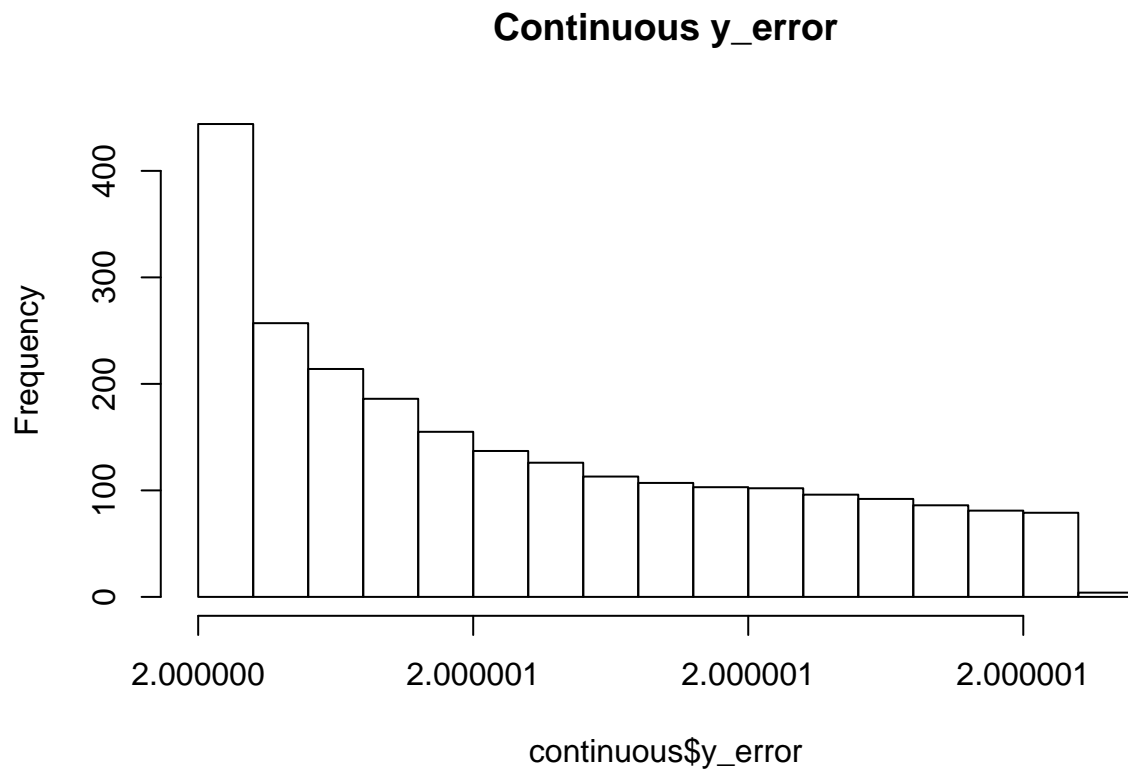


```
hist(continuous$x_error,  
     main = "Continuous x_error")
```

Continuous x_error

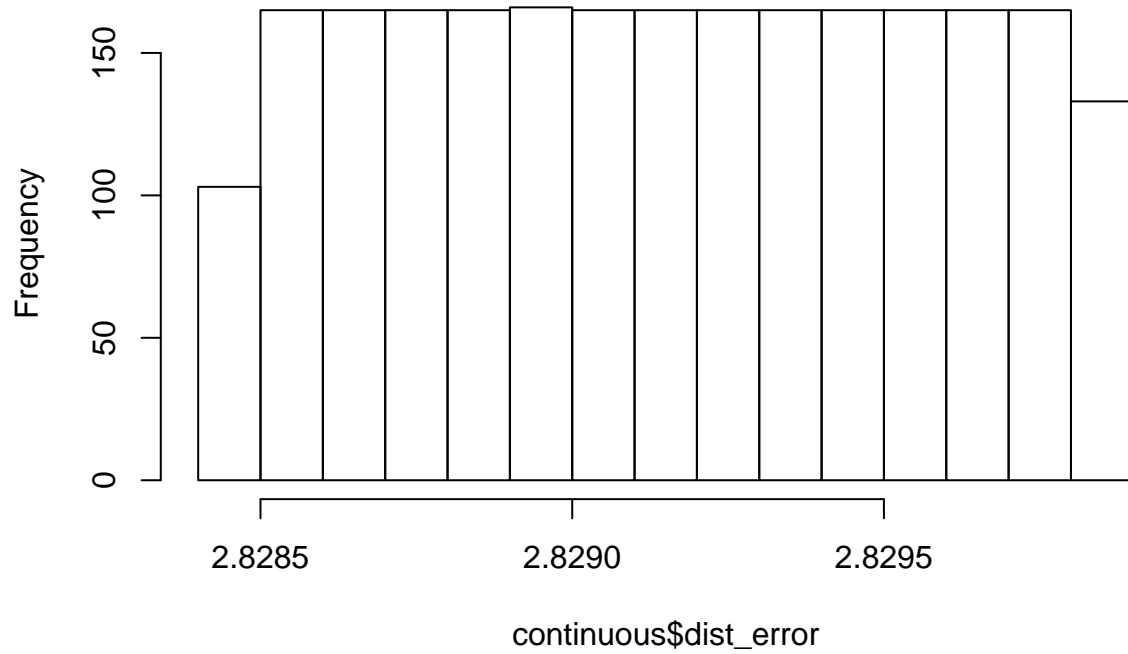


```
hist(continuous$y_error,  
     main = "Continuous y_error")
```



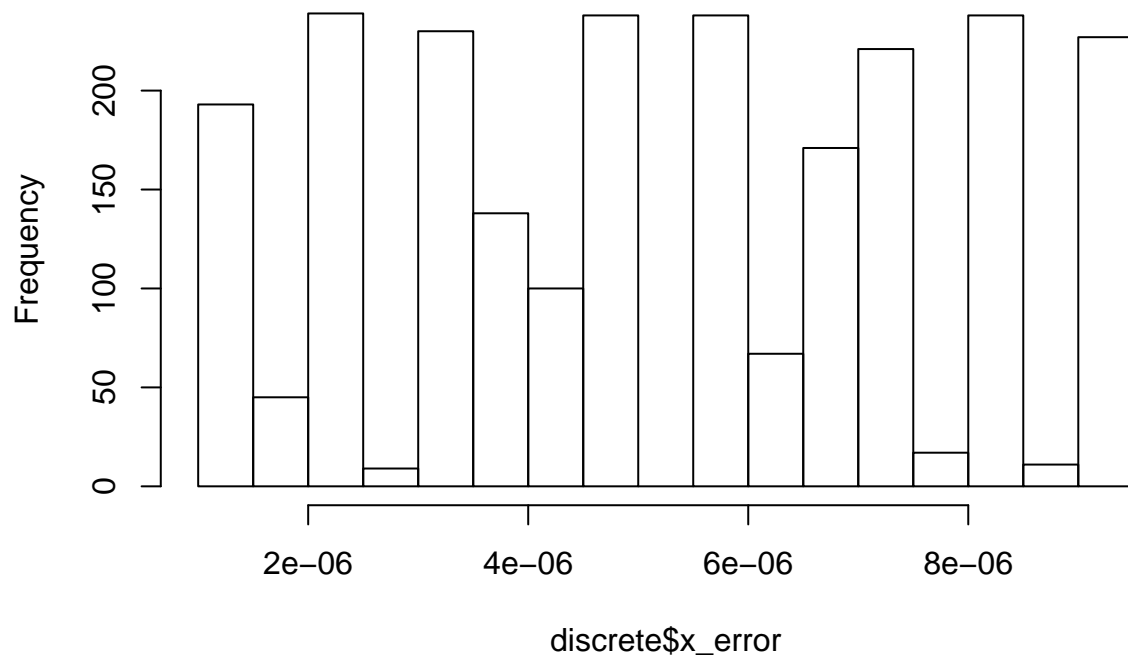
```
hist(continuous$dist_error,  
     main = "Continuous total distance error")
```

Continuous total distance error

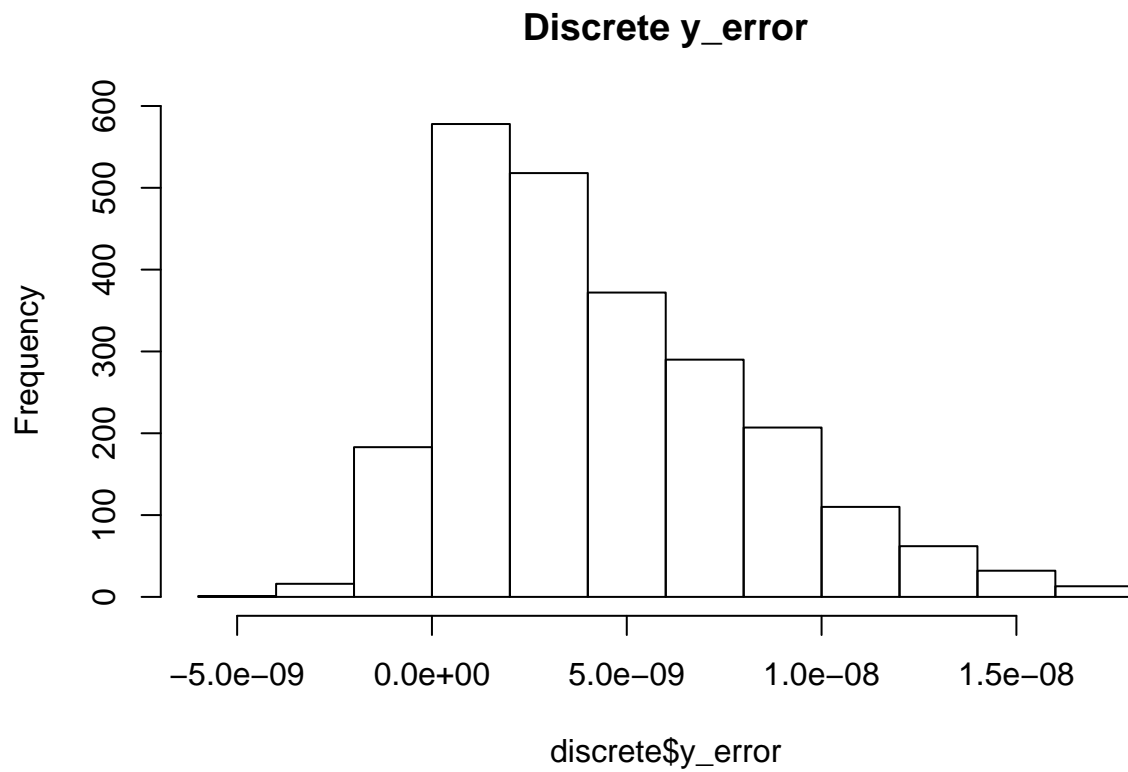


```
hist(discrete$x_error,  
     main = "Discrete x_error")
```

Discrete x_error



```
hist(discrete$y_error,  
     main = "Discrete y_error")
```



```
hist (discrete$dist_error,  
      main = "Discrete total distance error")
```

