one_mobile Experiment Report

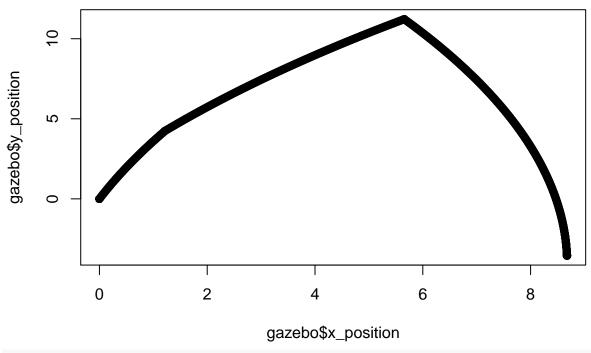
Matthew Swartwout June 28, 2016

This is a summary of the data from the one_mobile experiment.

Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

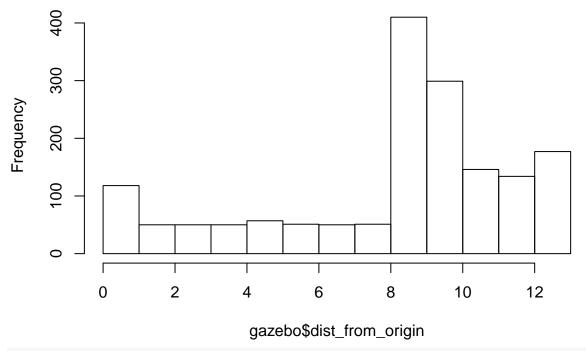
```
summary(continuous$x_error)
         Min.
                 1st Qu.
                              Median
                                           Mean
                                                    3rd Qu.
## -7.800e-07
               1.431e-02
                          1.626e-02
                                      1.593e-02
                                                  1.917e-02 3.191e-02
summary(continuous$y_error)
##
         Min.
                 1st Qu.
                              Median
                                           Mean
                                                    3rd Qu.
                                                                  Max.
## -0.0003903 0.0119400 0.0215800
                                                  0.0301800
                                      0.0201900
                                                             0.0367400
summary(continuous$dist_error)
##
        Min.
               1st Qu.
                           Median
                                               3rd Qu.
                                       Mean
                                                            Max.
## 1.100e-07 2.198e-02 2.961e-02 2.637e-02 3.408e-02 4.529e-02
summary(discrete$x_error)
##
         Min.
                 1st Qu.
                              Median
                                                    3rd Qu.
                                           Mean
                                                                  Max.
## -7.790e-07 4.649e-03
                          7.695e-03 8.096e-03 1.080e-02 1.814e-02
summary(discrete$y_error)
##
        Min.
               1st Qu.
                           Median
                                       Mean
                                               3rd Qu.
                                                            Max.
## -0.020760 -0.017500 -0.008840 -0.007754 0.001410
                                                        0.010030
summary(discrete$dist_error)
##
        Min.
               1st Qu.
                           Median
                                       Mean
                                               3rd Qu.
                                                            Max.
## 1.110e-07 1.101e-02 1.608e-02 1.476e-02 1.895e-02 2.248e-02
if (params$robot >= 2) {
    summary(external_data_averages)
}
Shown below are plots representing the robot's motion and error over time.
plot(gazebo$x_position, gazebo$y_position,
     main = "Ground truth visited locations of robot")
```

Ground truth visited locations of robot



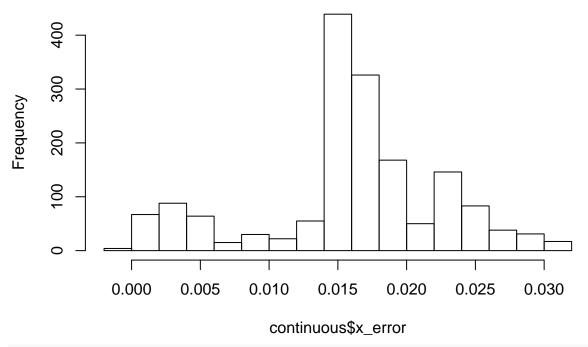
hist(gazebo\$dist_from_origin,
 main = "Distance from origin vs. time")

Distance from origin vs. time

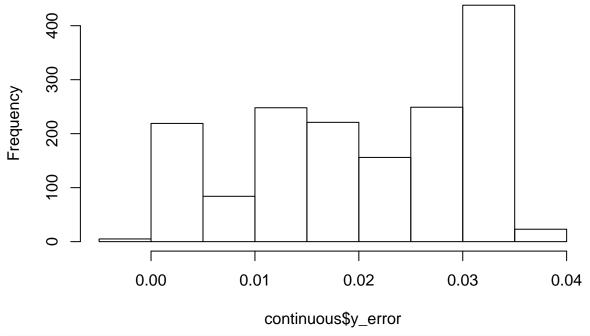


hist(continuous\$x_error,
 main = "Continuous x_error")

Continuous x_error

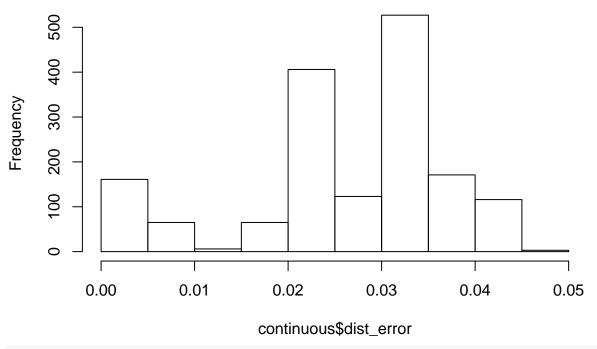


Continuous y_error



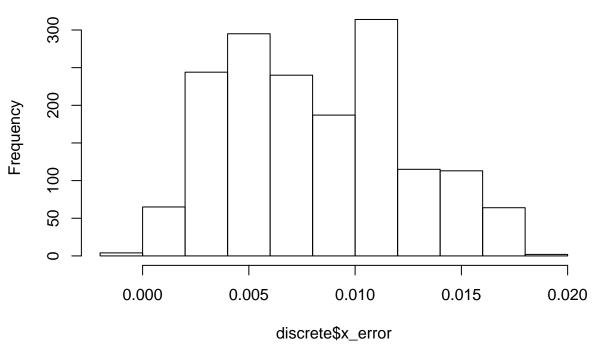
hist(continuous\$dist_error,
 main = "Continuous total distance error")

Continuous total distance error



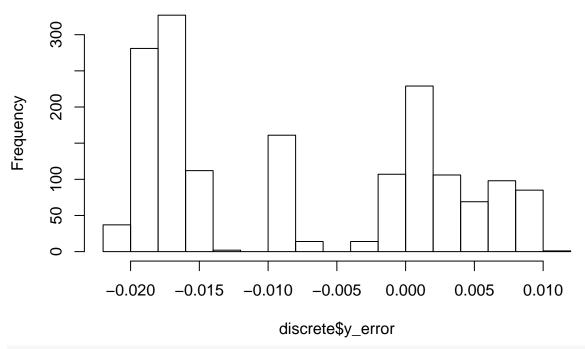
hist(discrete\$x_error,
 main = "Discrete x_error")

Discrete x_error



hist(discrete\$y_error,
 main = "Discrete y_error")

Discrete y_error



hist (discrete\$dist_error,
 main = "Discrete total distance error")

Discrete total distance error

