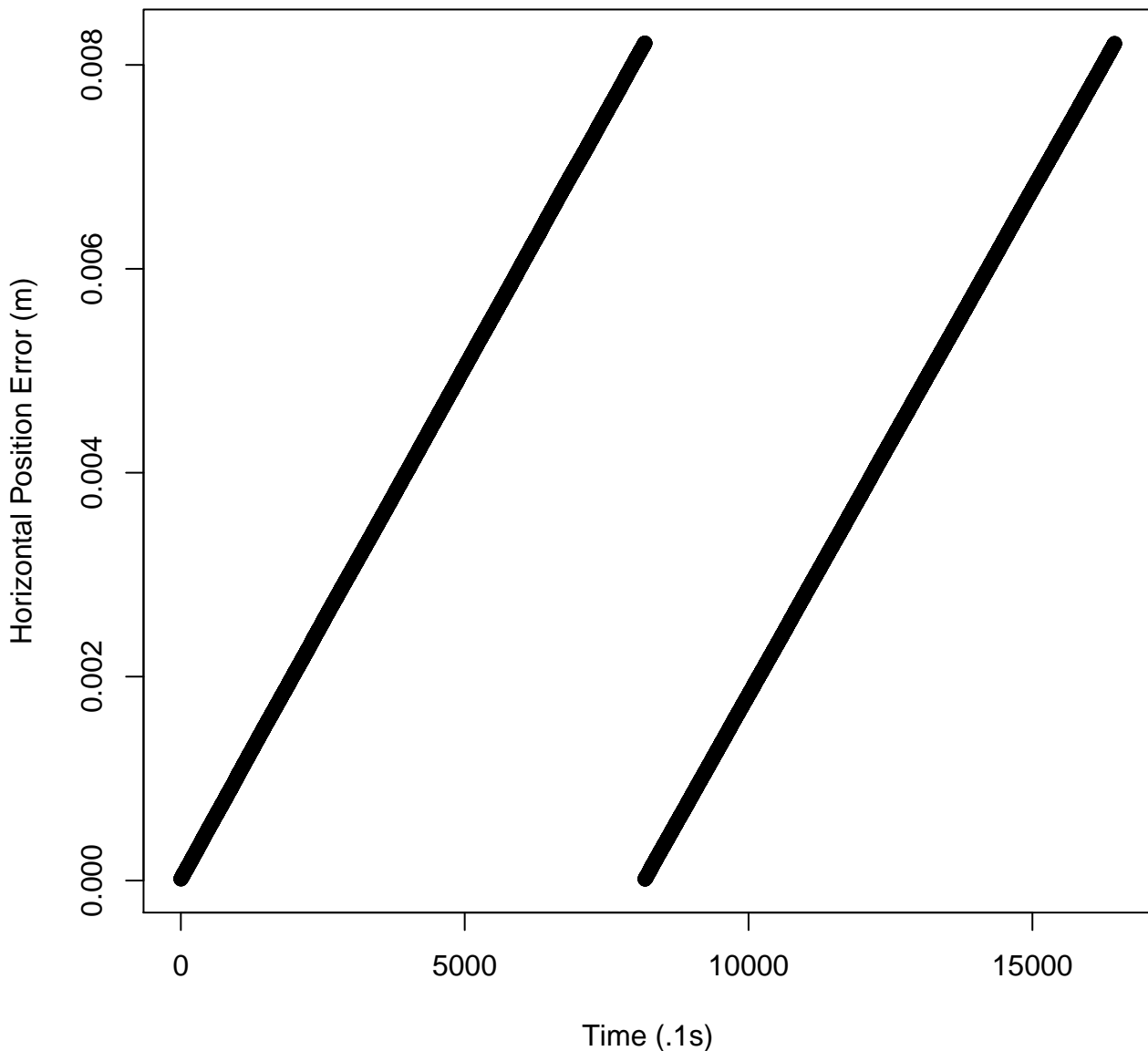


Continuous Filter Error



For two_stationary_noiseless_no_gps Experiment