two_mobile Experiment Report

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This is a summary of the data from the two_mobile experiment.

Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

```
summary(continuous$x_error)
##
                 1st Qu.
                             Median
                                                   3rd Qu.
         Min.
                                           Mean
                                                                 Max.
## -4.205e-02 -2.281e-03 3.050e-06
                                     6.555e-04 1.919e-03 5.341e-02
summary(continuous$y_error)
##
         Min.
                 1st Qu.
                             Median
                                           Mean
                                                   3rd Qu.
                                                                 Max.
## -5.618e-02 -2.537e-03 -9.940e-06 3.832e-04 1.857e-03 7.308e-02
summary(continuous$dist_error)
               1st Qu.
                          Median
                                      Mean
                                              3rd Qu.
## 2.800e-07 5.586e-04 4.890e-03 8.065e-03 1.157e-02 7.312e-02
summary(discrete$x_error)
         Min.
                 1st Qu.
                             Median
                                                   3rd Qu.
                                                                 Max.
## -0.3076000 -0.0162400
                          0.0000033 0.0006270
                                                0.0088380 0.4689000
summary(discrete$y_error)
                 1st Qu.
                             Median
                                                   3rd Qu.
##
         Min.
                                           Mean
                                                                 Max.
## -0.2849000 -0.0137600 -0.0000022 0.0055010
                                                 0.0115400
                                                            0.3728000
summary(discrete$dist_error)
##
                                      Mean
               1st Qu.
                          Median
                                              3rd Qu.
## 0.0000002 0.0026340 0.0366100 0.0503500 0.0592100 0.4706000
if (params$robot >= 2) {
    summary(external_data_averages)
}
##
       Length Class Mode
## [1,] 1
               -none- numeric
## [2,] 1
               -none- numeric
```

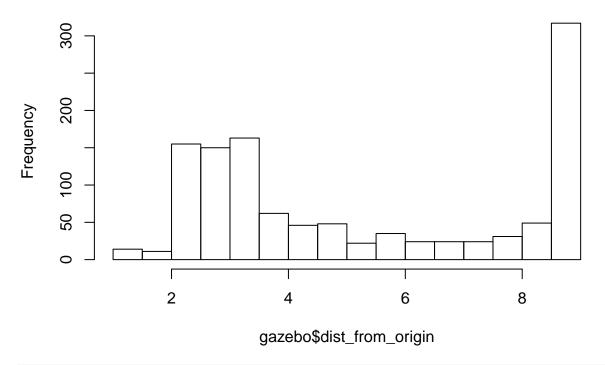
Shown below are plots representing the robot's motion and error over time.

Ground truth visited locations of robots



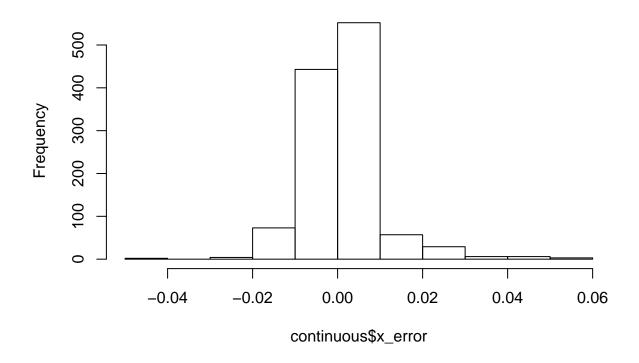
hist(gazebo\$dist_from_origin,
 main = "Distance from origin vs. time")

Distance from origin vs. time



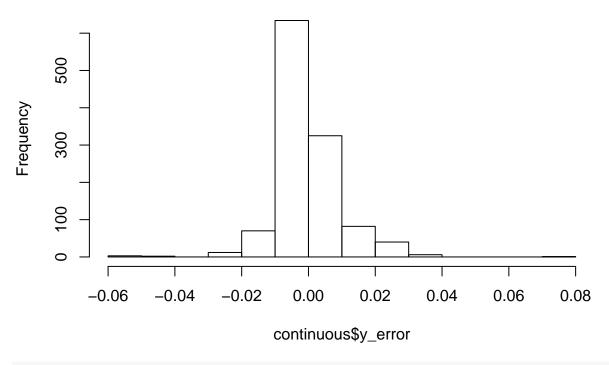
hist(continuous\$x_error,
 main = "Continuous x_error")

Continuous x_error



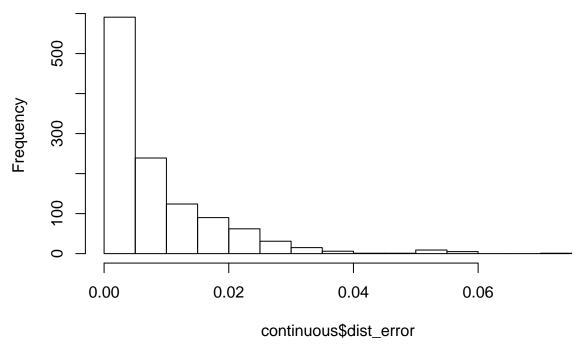
```
hist(continuous$y_error,
    main = "Continuous y_error")
```

Continuous y_error



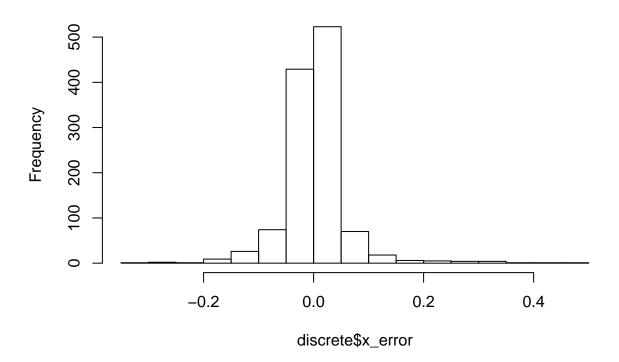
```
hist(continuous$dist_error,
    main = "Continuous total distance error")
```

Continuous total distance error



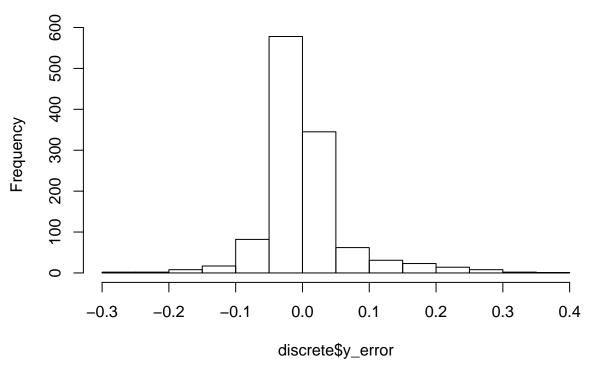
hist(discrete\$x_error,
 main = "Discrete x_error")

Discrete x_error



```
hist(discrete$y_error,
    main = "Discrete y_error")
```





hist (discrete\$dist_error,
 main = "Discrete total distance error")

Discrete total distance error

