# one\_mobile\_noisy\_true Experiment Report

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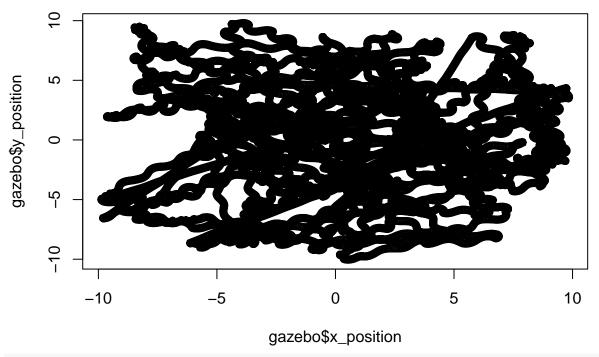
July 13, 2016

This is a summary of the data from the one\_mobile\_noisy\_true experiment.

Shown below is the summary of the error of all robots combined for both x and y coordinates, and also the error in total distance.

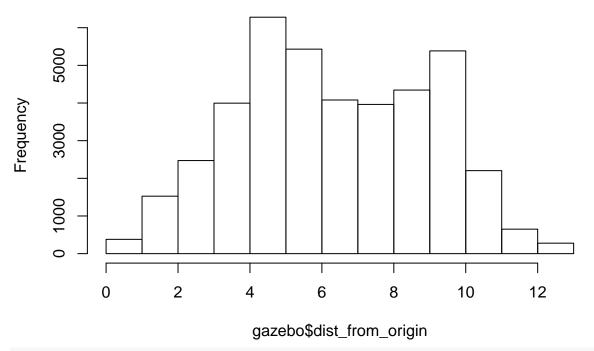
```
summary(continuous$x_error)
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
## -6.955e-02 -8.225e-03 -3.921e-05
                                      3.127e-04
                                                  8.747e-03
                                                             6.261e-02
summary(continuous$y_error)
##
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
                                                                   Max.
## -0.0624100 -0.0092530 -0.0001994 -0.0003033
                                                  0.0082320
                                                             0.0634300
summary(continuous$dist_error)
##
        Min.
               1st Qu.
                           Median
                                               3rd Qu.
                                       Mean
## 1.599e-05 6.670e-03 1.935e-02 2.130e-02 3.514e-02 7.053e-02
summary(discrete$x_error)
##
         Min.
                 1st Qu.
                              Median
                                                    3rd Qu.
                                            Mean
                                                                   Max.
## -0.4167000 -0.0029860
                           0.000005
                                     0.0017600
                                                 0.0028650
                                                             0.3879000
summary(discrete$y_error)
##
         Min.
                 1st Qu.
                              Median
                                            Mean
                                                    3rd Qu.
                                                                   Max.
## -0.3878000 -0.0035010 0.0000011 -0.0010120
                                                 0.0026590
                                                             0.4416000
summary(discrete$dist_error)
##
        Min.
               1st Qu.
                           Median
                                       Mean
                                               3rd Qu.
                                                             Max.
## 0.0000000 0.0008857 0.0060000 0.0260100 0.0222400 0.4668000
if (params$robot >= 2) {
    summary(external_data_averages)
Shown below are plots representing the robot's motion and error over time.
plot(gazebo$x_position, gazebo$y_position,
     main = "Ground truth visited locations of robots")
```

#### **Ground truth visited locations of robots**



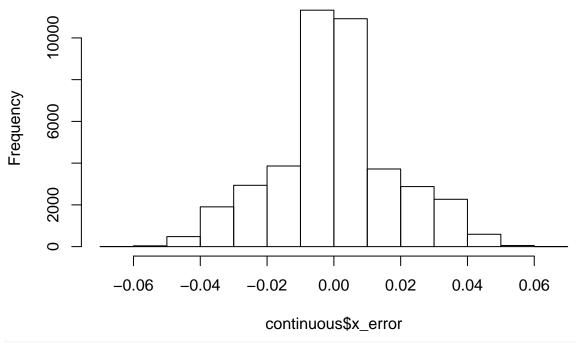
hist(gazebo\$dist\_from\_origin,
 main = "Distance from origin vs. time")

## Distance from origin vs. time

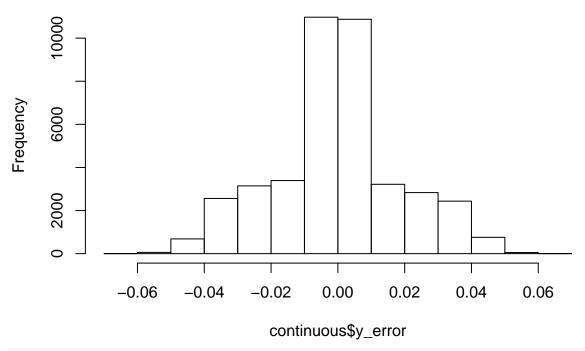


hist(continuous\$x\_error,
 main = "Continuous x\_error")

### Continuous x\_error

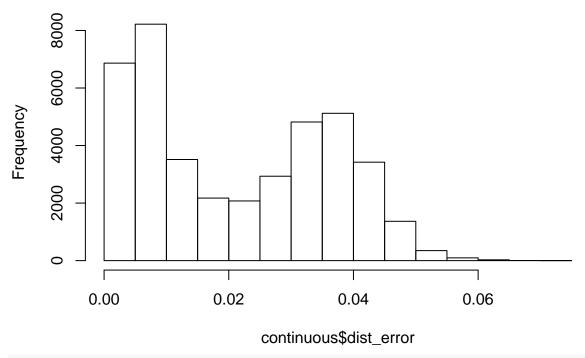


## Continuous y\_error



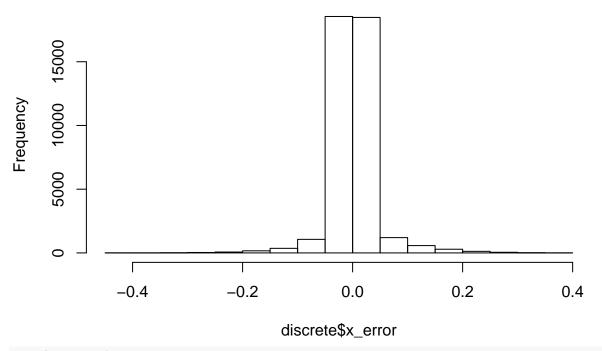
hist(continuous\$dist\_error,
 main = "Continuous total distance error")

## **Continuous total distance error**



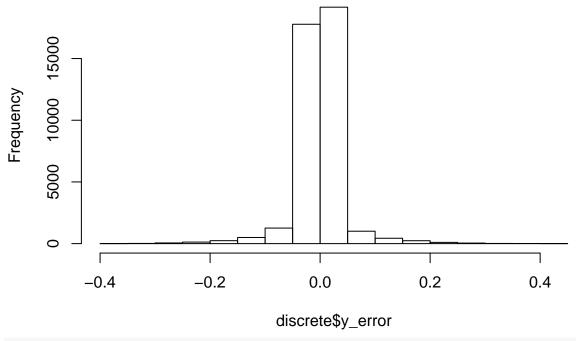
hist(discrete\$x\_error,
 main = "Discrete x\_error")

### Discrete x\_error



hist(discrete\$y\_error,
 main = "Discrete y\_error")

# Discrete y\_error



hist (discrete\$dist\_error,
 main = "Discrete total distance error")

### Discrete total distance error

