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-- CWRUCutter_PWMOutput.vhd
-- EJ Kreinar
-- Creates a PWM signal
-- Inputs:
    POS_PULSE_LEN: # of Ticks that the PWM output should be high
     CYC_PULSE_LEN: # of Ticks in a period
-- Outputs:
   PWM_OUT: The PWM output signal
-- Notes:
-- History
-- 9/19: ejk43- Created
Library ieee;
use ieee.std_logic_1164.all;
use ieee.numeric_std.all;
entity CWRUCutter_PWMOutput is
    port (
                      : in std_logic;
        CLK
        aRESET
                     : in std_logic;
        POS_PULSE_LEN : in std_logic_vector(31 downto 0) := (others => '0');
        CYC_PULSE_LEN : in std_logic_vector(31 downto 0) := (others => '0');
        PWM_OUT
                 : out std_logic
      );
end CWRUCutter_PWMOutput;
architecture rtl of CWRUCutter_PWMOutput is
    signal pwm_count: unsigned(31 downto 0);
    signal pwm_reset: std_logic;
    signal pos_int : std_logic_vector(31 downto 0);
    signal cyc_int : std_logic_vector(31 downto 0);
    -- signal pos_reg: unsigned(32 downto 0);
    -- signal cyc_reg: unsigned(32 downto 0);
begin
    process(aRESET, CLK) begin
      if(aRESET = '1') then
        PWM OUT
                    <= '0';
        pwm_count
                      <= (others => '0');
                     <= '0';
        pwm_reset
        pos_int
                      <= (others => '0');
                     <= (others => '0');
        cyc_int
      elsif rising_edge(clk) then
        -- RESET
        -- Reset at end of each cycle AND at beginning
        -- of the loop (because cyc_int = '0')
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if std_logic_vector(pwm_count) = cyc_int then
            pwm_reset <= '1';</pre>
        else
            pwm_reset <= '0';</pre>
        end if;
        -- COUNTER
        if pwm_reset = '1' then
            pwm_count <= (others => '0');
            pos_int <= POS_PULSE_LEN;</pre>
            cyc_int <= CYC_PULSE_LEN;</pre>
        else
            pwm_count <= pwm_count + 1;</pre>
        end if;
        -- OUTPUT
        if pwm_reset = '1' then
            PWM_OUT <= '1';
        elsif std_logic_vector(pwm_count) = pos_int then
            PWM_OUT <= '0';
        end if;
      end if;
    end process;
end rtl;
```