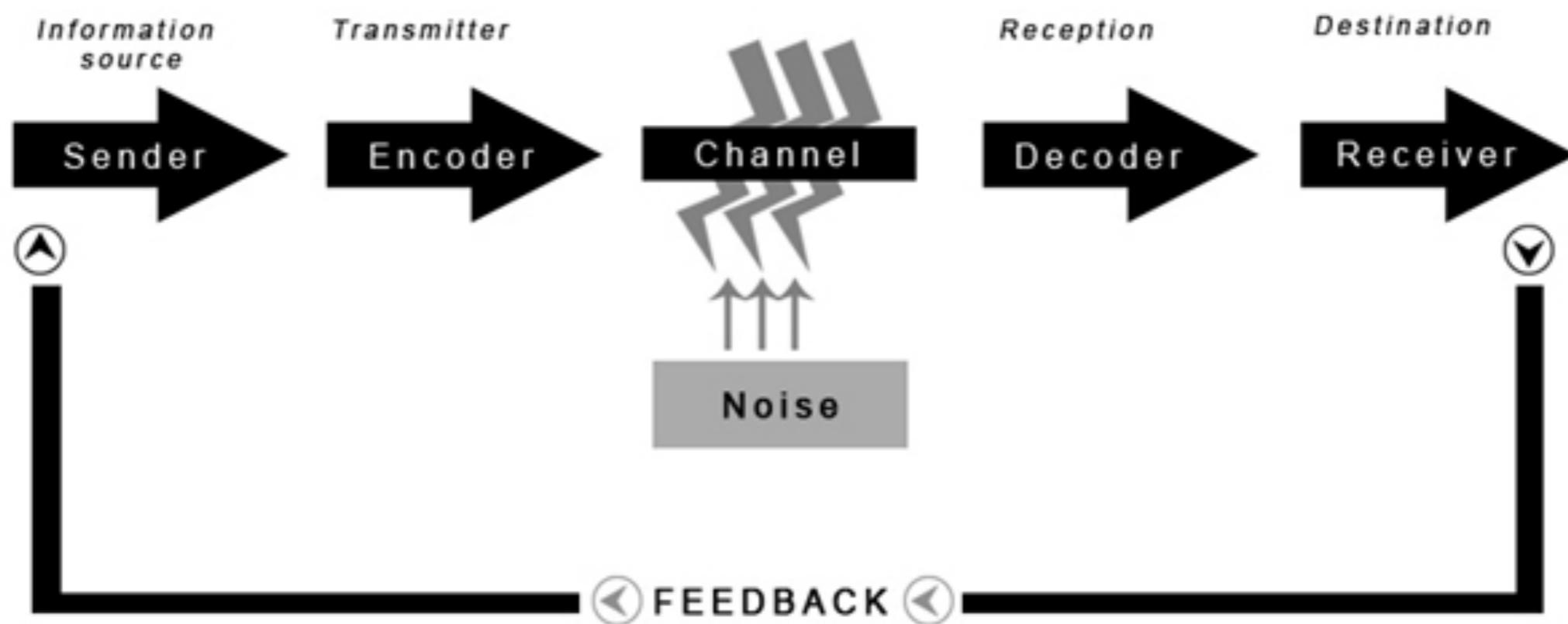


Lecture 9: Decoding neural signals



SHANNON-WEAVER's MODEL OF COMMUNICATION

A few definitions to start:

- $P[s]$, the probability of stimulus s being presented. This is often called the prior probability,
- $P[r]$, the probability of response r being recorded,
- $P[r, s]$, the probability of stimulus s being presented and response r being recorded,
- $P[r|s]$, the conditional probability of evoking response r given that stimulus s was presented, and
- $P[s|r]$, the conditional probability that stimulus s was presented given that the response r was recorded.

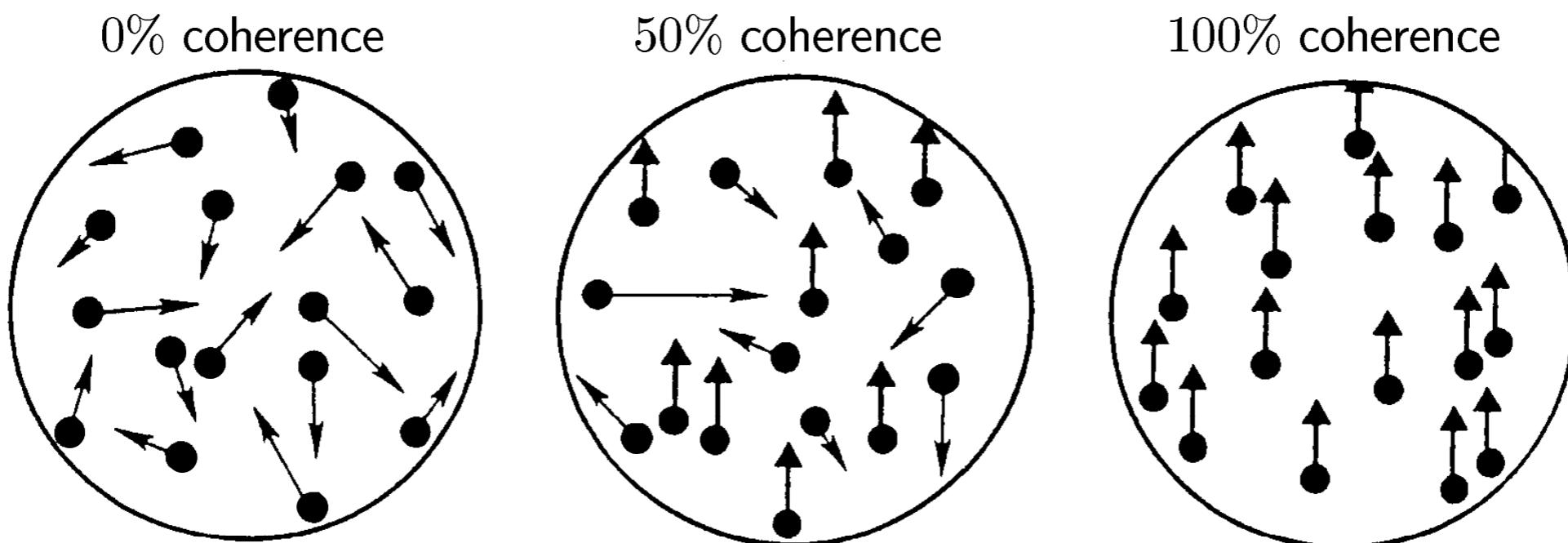
Bayes' Rule:

$$P[\mathbf{r}] = \sum_s P[\mathbf{r}|s]P[s] \text{ and similarly } P[s] = \sum_{\mathbf{r}} P[s|\mathbf{r}]P[\mathbf{r}]$$

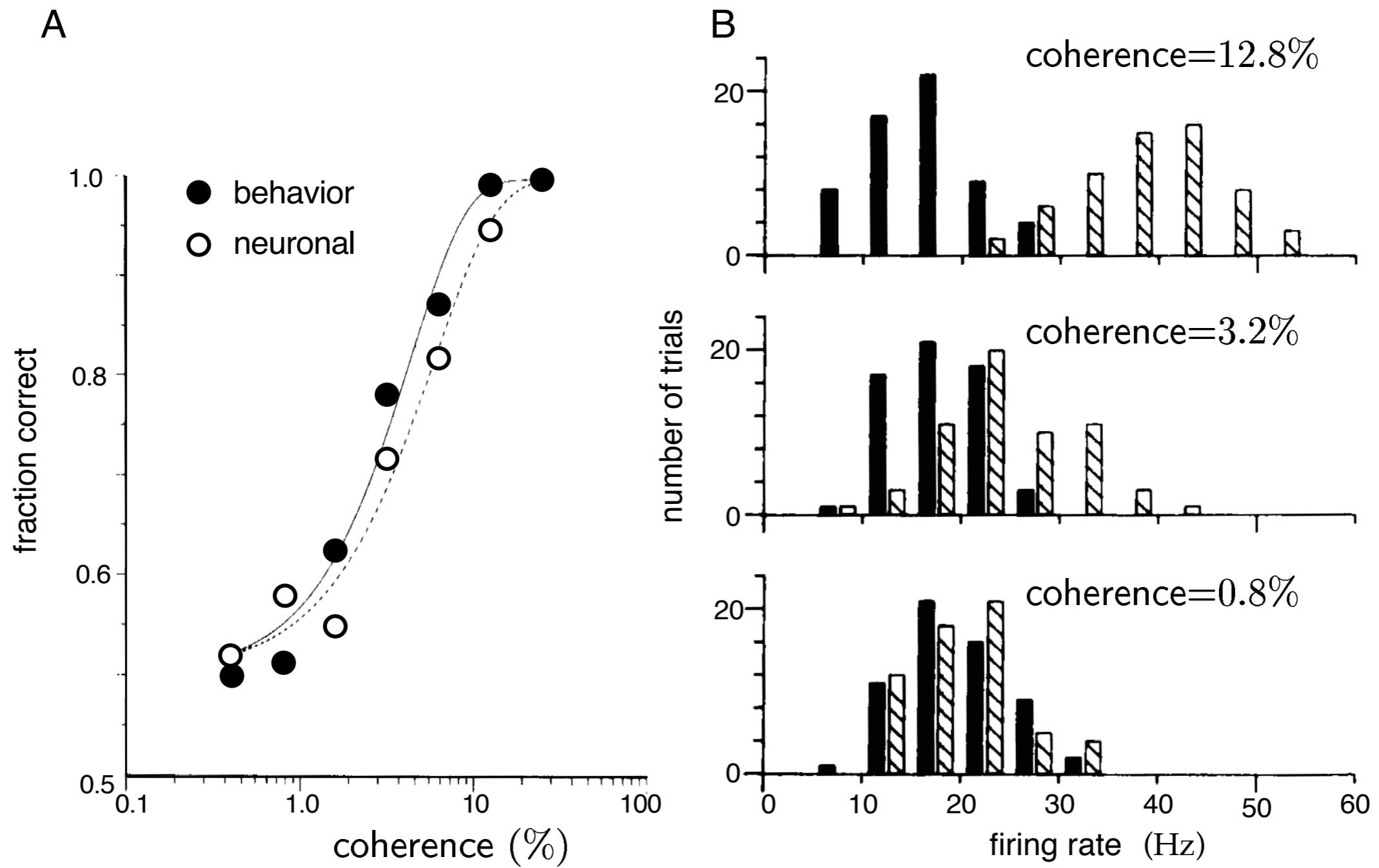
$$P[\mathbf{r}, s] = P[\mathbf{r}|s]P[s] = P[s|\mathbf{r}]P[\mathbf{r}]$$

$$P[s|\mathbf{r}] = \frac{P[\mathbf{r}|s]P[s]}{P[\mathbf{r}]}$$

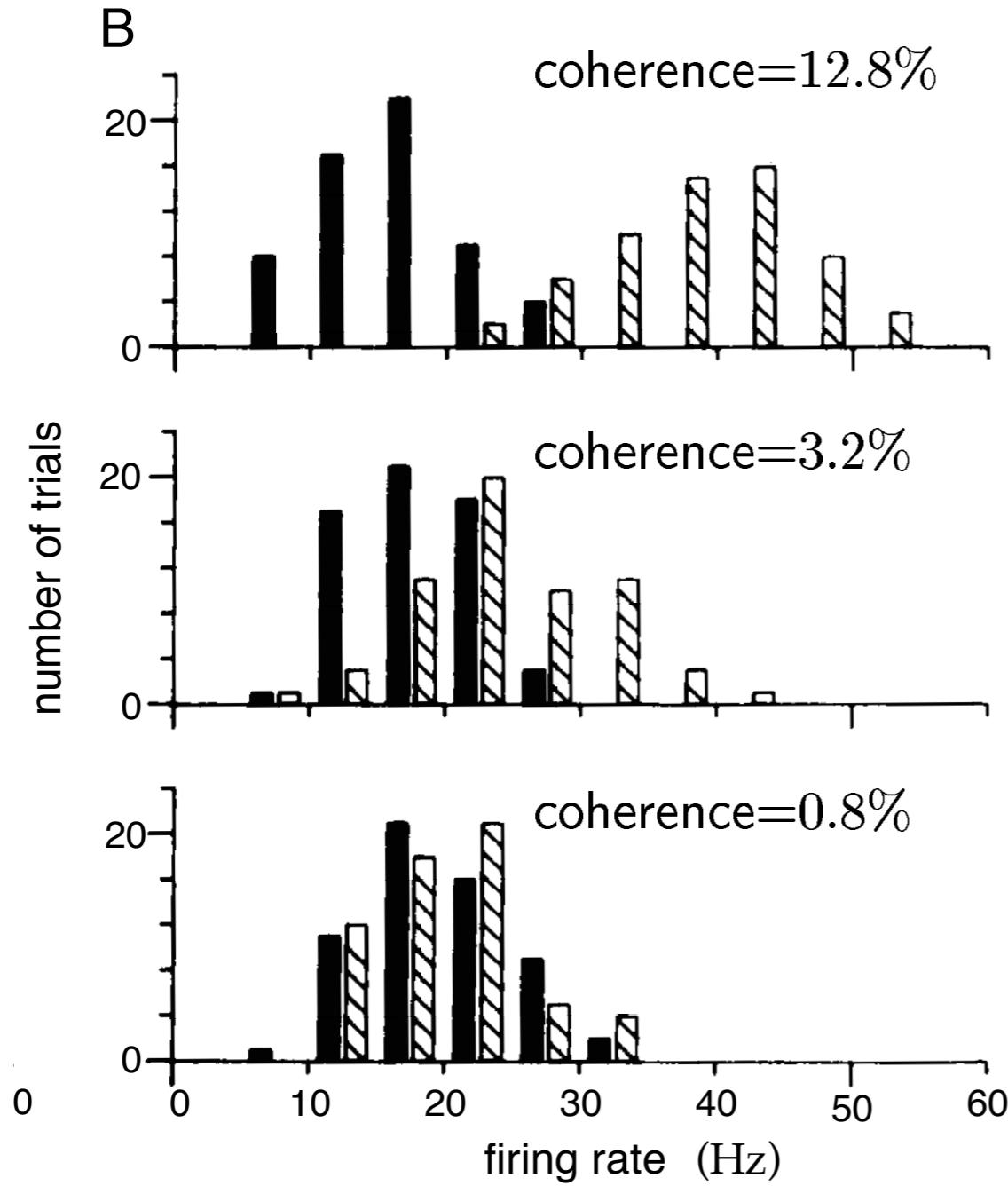
Stochastic stimulus, random moving dots:



Behavior on the random dot discrimination task:



Discriminability:



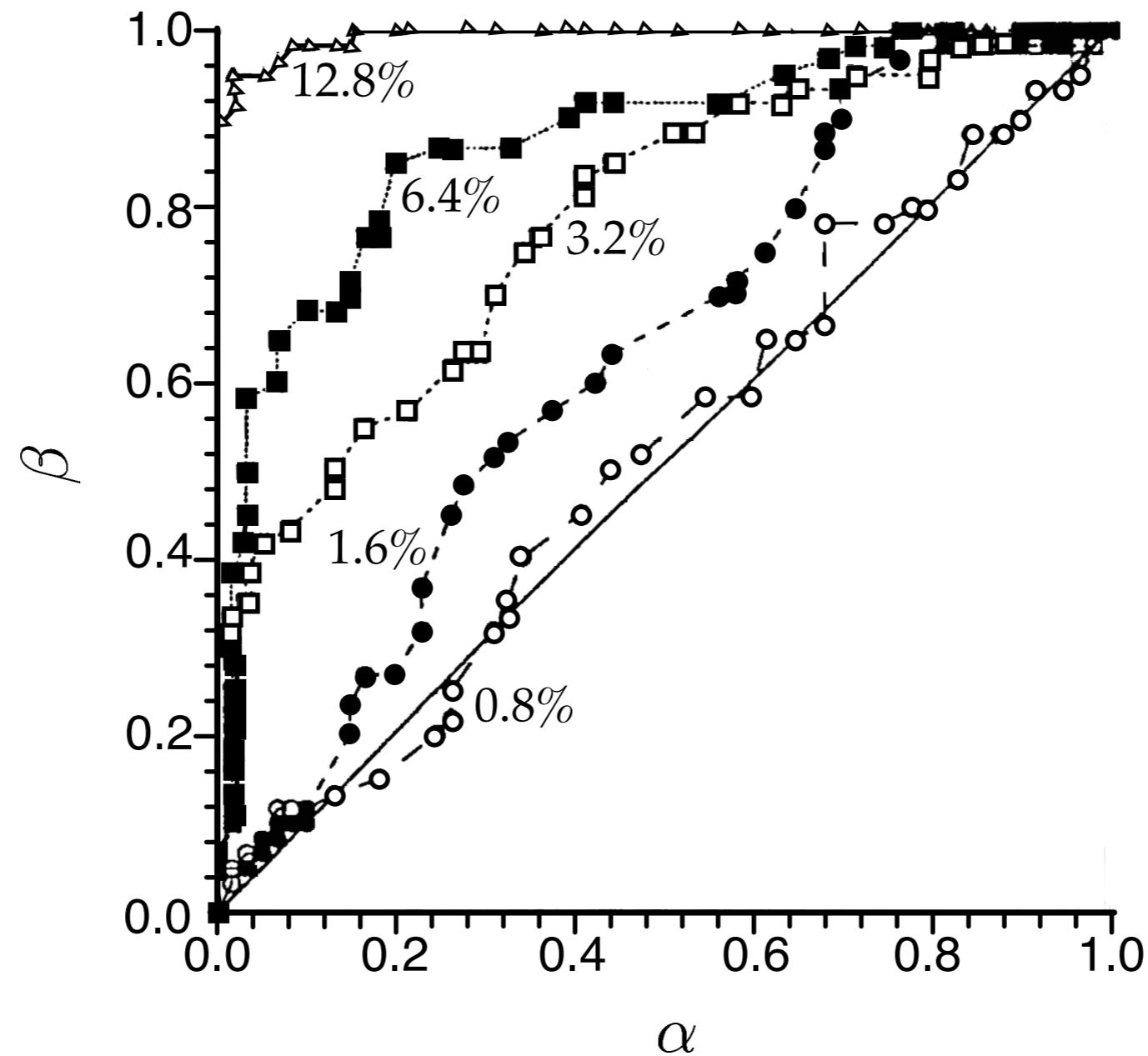
$$d' = \frac{\langle r \rangle_+ - \langle r \rangle_-}{\sigma_r}$$

Standard error measures in signal detection theory:

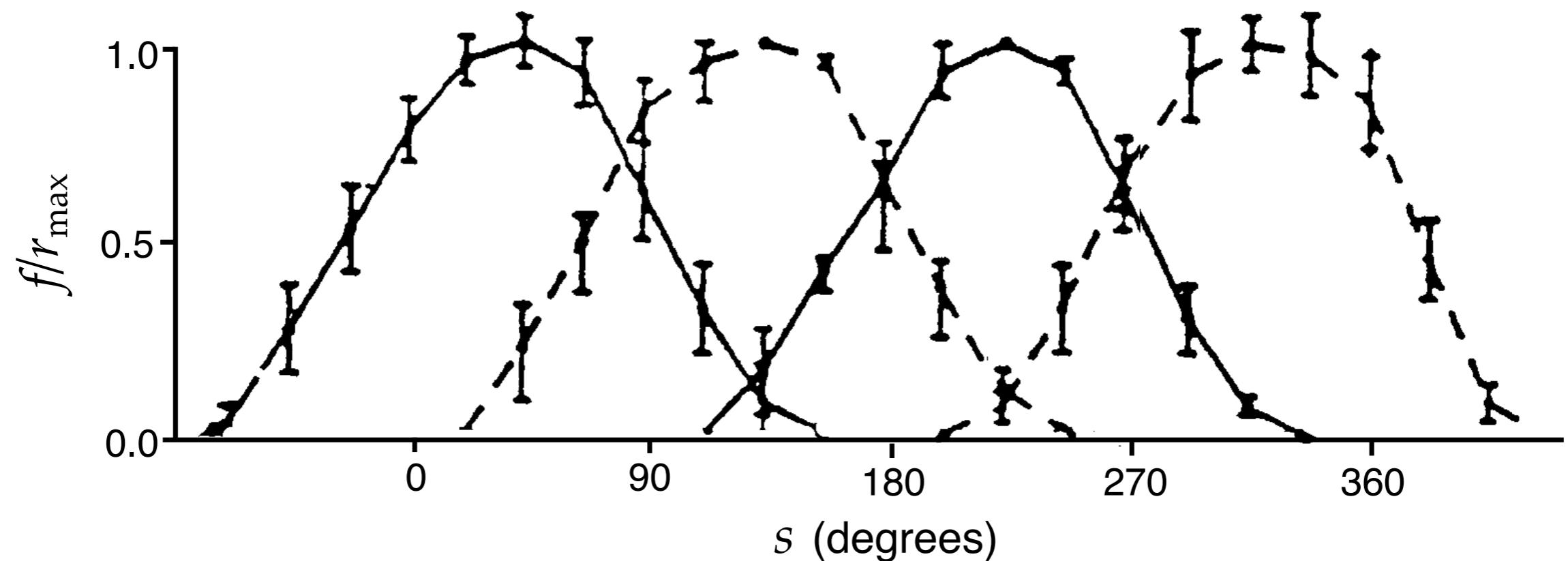
$\alpha(z) = P[r \geq z | -]$ is the size or false alarm rate of the test, and
 $\beta(z) = P[r \geq z | +]$ is the power or hit rate of the test.

		probability
stimulus	correct	incorrect
+	β	$1 - \beta$
-	$1 - \alpha$	α

ROC curves for various coherence levels:



Population decoding:

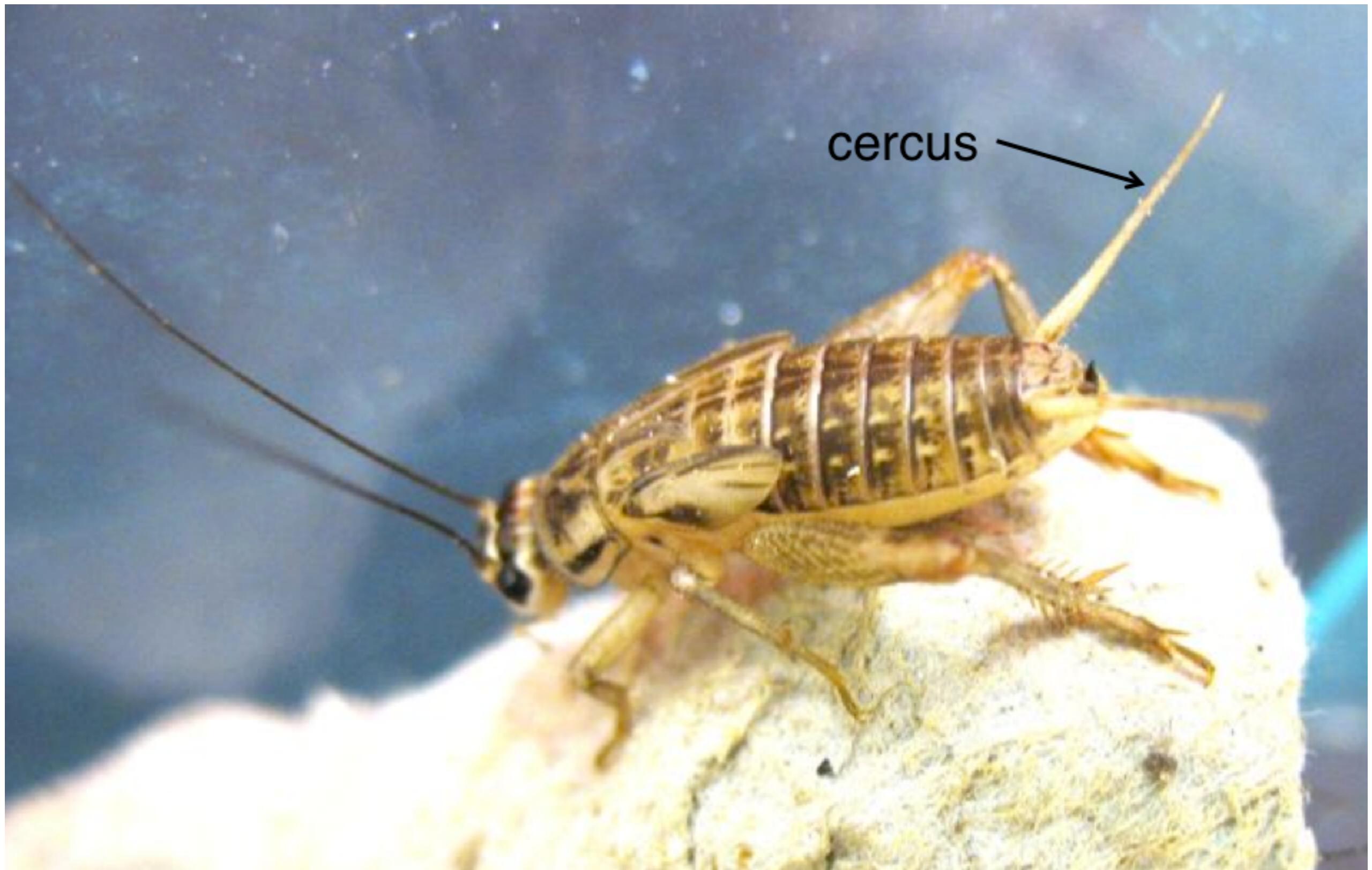


Cosine tuning curves:

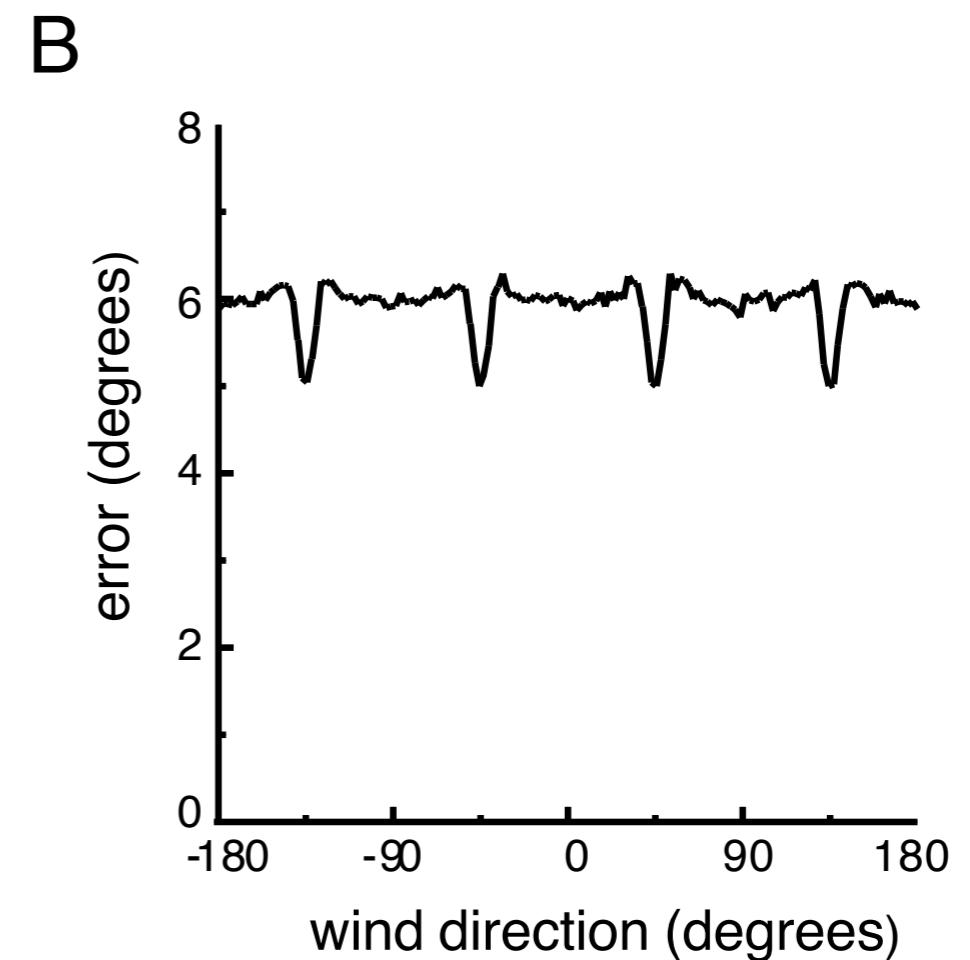
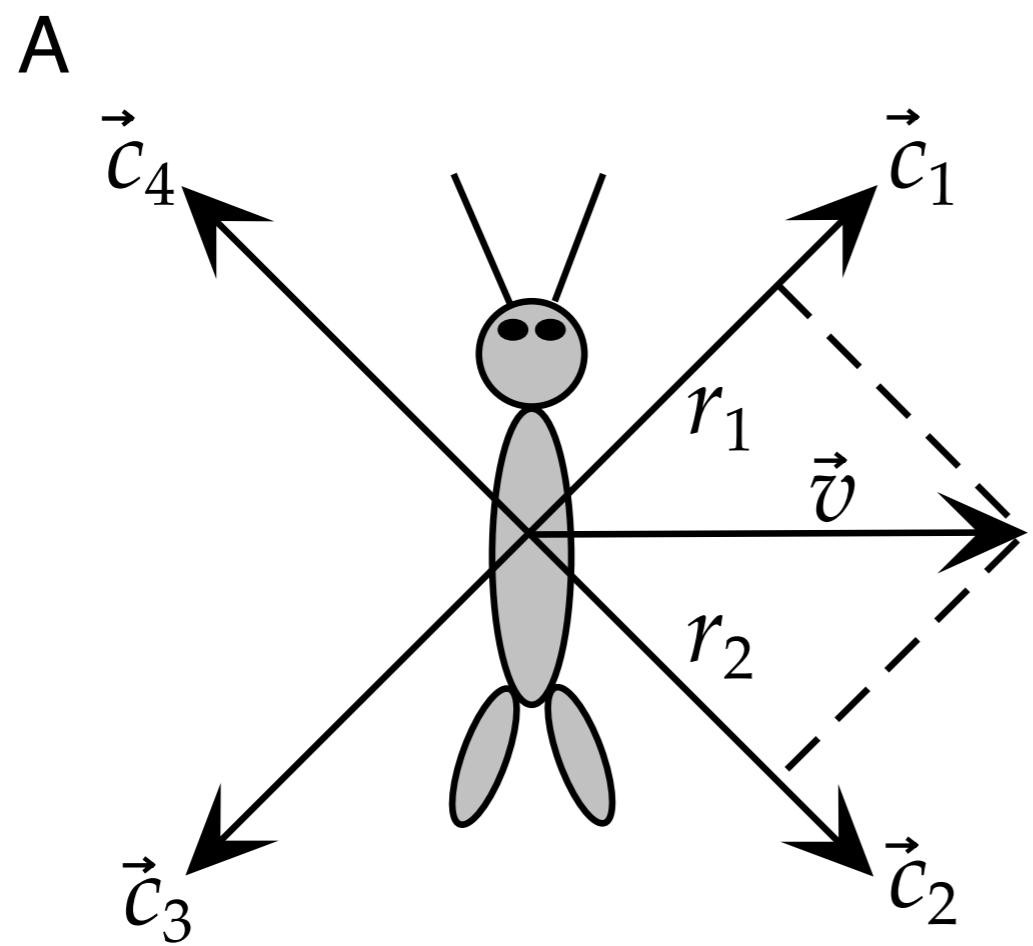
$$\left(\frac{f(s)}{r_{\max}} \right)_a = [(\cos(s - s_a)]_+$$

$$\left(\frac{f(s)}{r_{\max}} \right)_a = [\vec{v} \cdot \vec{c}_a]_+$$

Estimating wind direction from the cricket cercal system:



Estimating wind direction from the cricket cercal system:



Population vector estimate of direction:

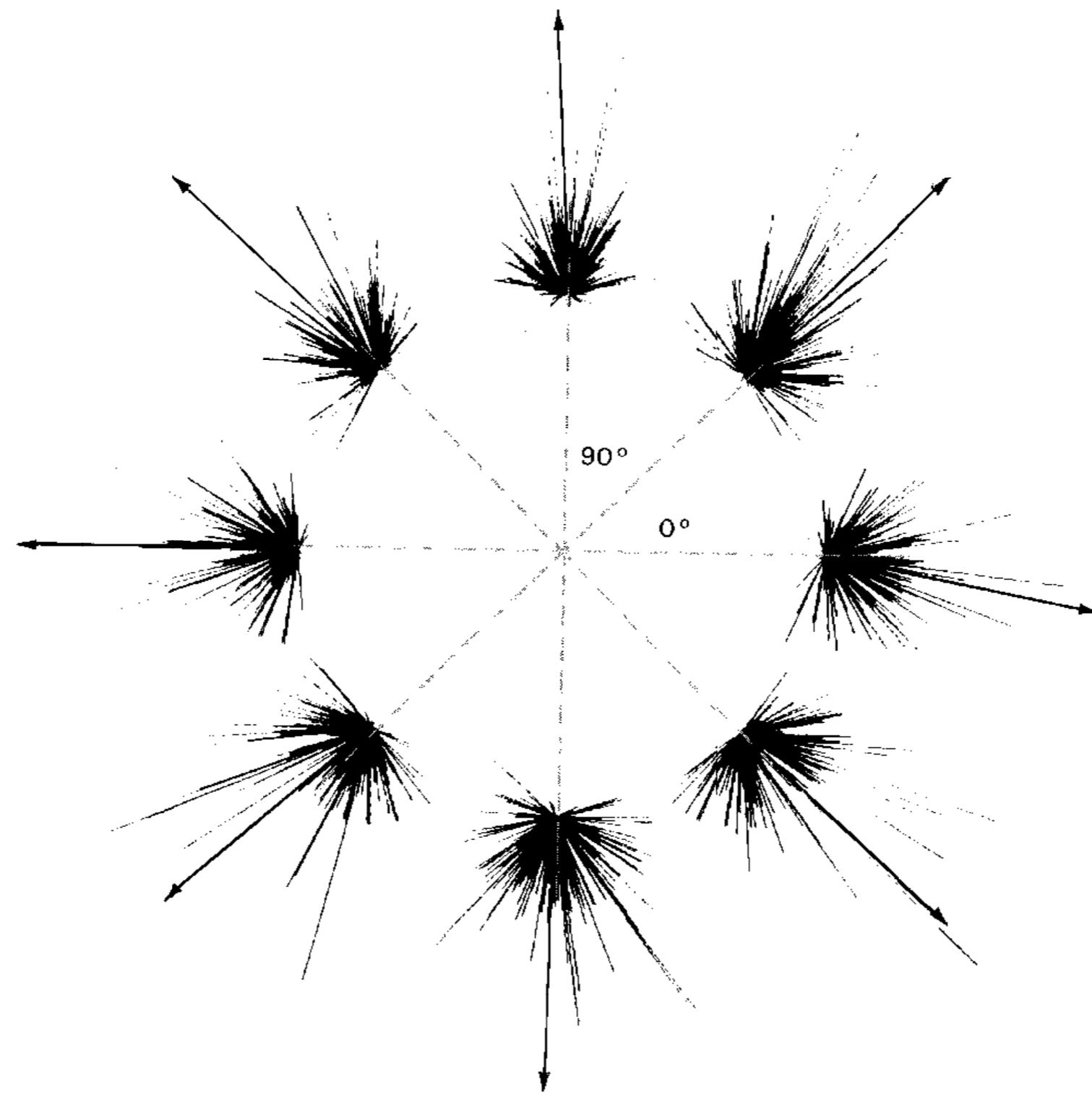
$$\vec{v}_{\text{pop}} = \sum_{a=1}^4 \left(\frac{r}{r_{\max}} \right)_a \vec{c}_a$$

$$\left(\frac{\langle r \rangle - r_0}{r_{\max}} \right)_a = \left(\frac{f(s) - r_0}{r_{\max}} \right)_a = \vec{v} \cdot \vec{c}_a$$

$$\vec{v}_{\text{pop}} = \sum_{a=1}^N \left(\frac{r - r_0}{r_{\max}} \right)_a \vec{c}_a$$

$$\langle \vec{v}_{\text{pop}} \rangle = \sum_{a=1}^N (\vec{v} \cdot \vec{c}_a) \vec{c}_a$$

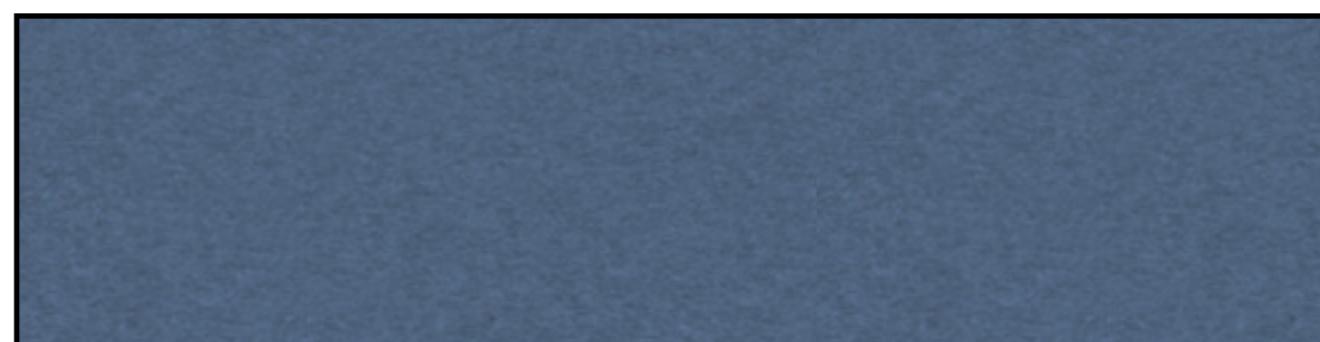
Population vectors in a center-out reach task (monkey):



Optimal estimate of the stimulus, Bayesian version:

$$p[s|r] = \frac{p[r|s]p[s]}{p[r]}$$

$$\int ds L(s, s_{\text{bayes}}) p[s|r]$$



chalkboard interlude

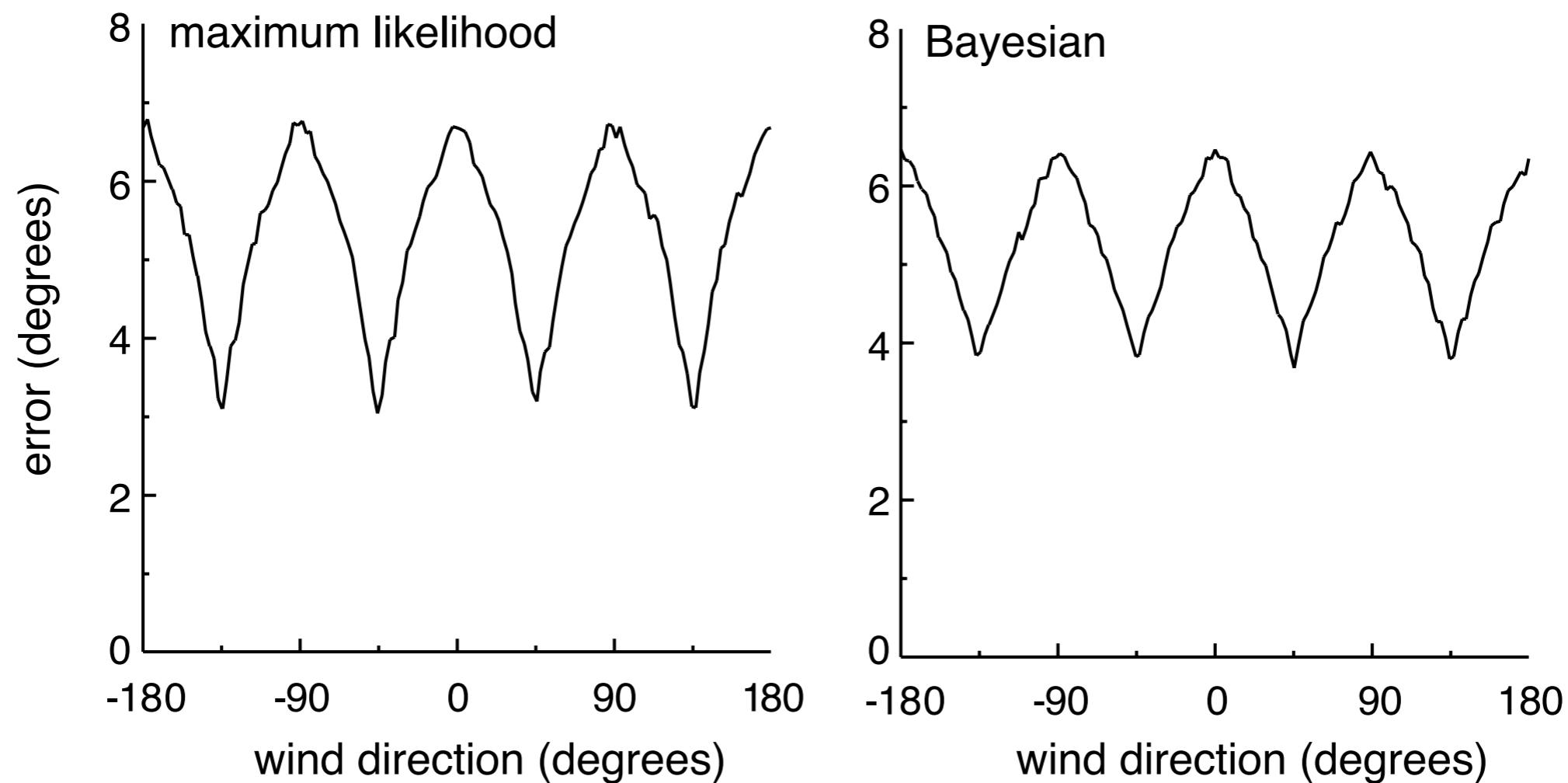
Optimal estimate of the stimulus, Bayesian version:

$$p[s|r] = \frac{p[r|s]p[s]}{p[r]}$$

$$\int ds L(s, s_{\text{bayes}}) p[s|r]$$

$$s_{\text{bayes}} = \int ds p[s|r]s$$

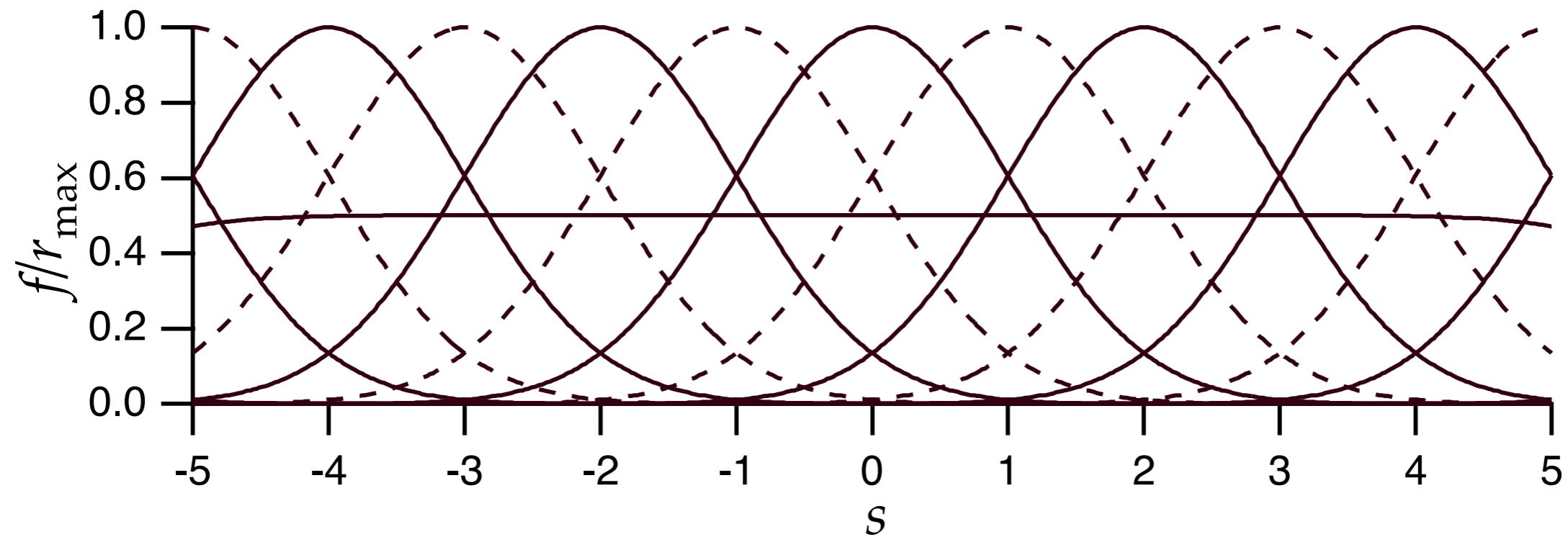
Comparing ML to Bayes for the cercal system:



Gaussian tuning curve for an arbitrary variable:

$$f_a(s) = r_{\max} \exp \left(-\frac{1}{2} \left(\frac{s - s_a}{\sigma_a} \right)^2 \right)$$

A population of Gaussian tuned cells:

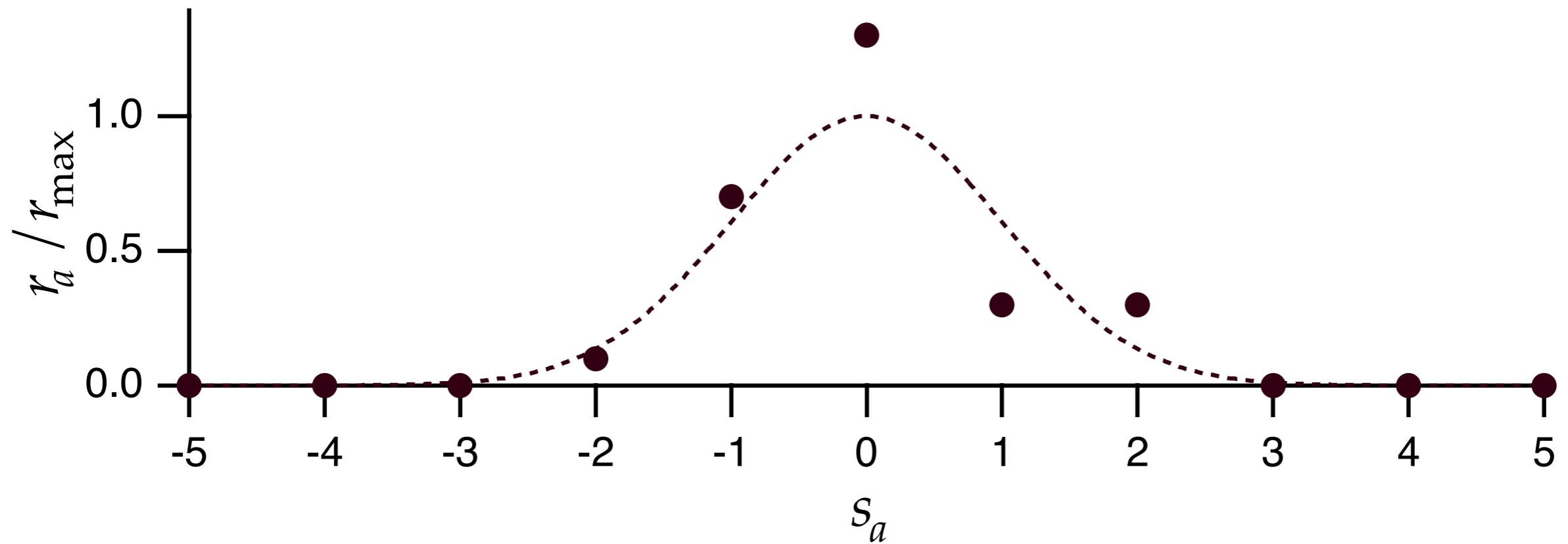


Conditional distribution for independent neurons:

$$P[r_a|s] = \frac{(f_a(s)T)^{r_a T}}{(r_a T)!} \exp(-f_a(s)T)$$

$$P[\mathbf{r}|s] = \prod_{a=1}^N \frac{(f_a(s)T)^{r_a T}}{(r_a T)!} \exp(-f_a(s)T)$$

Simulated response to $s_a = 0$:



Deriving the ML estimate of the stimulus:

$$P[r_a|s] = \frac{(f_a(s)T)^{r_a T}}{(r_a T)!} \exp(-f_a(s)T)$$

$$P[\mathbf{r}|s] = \prod_{a=1}^N \frac{(f_a(s)T)^{r_a T}}{(r_a T)!} \exp(-f_a(s)T)$$

$$\ln P[\mathbf{r}|s] = T \sum_{a=1}^N r_a \ln(f_a(s)) + \dots$$

$$\sum_{a=1}^N r_a \frac{f'_a(s_{\text{ML}})}{f_a(s_{\text{ML}})} = 0 \quad s_{\text{ML}} = \frac{\sum r_a s_a / \sigma_a^2}{\sum r_a / \sigma_a^2} \quad s_{\text{ML}} = \frac{\sum r_a s_a}{\sum r_a}$$

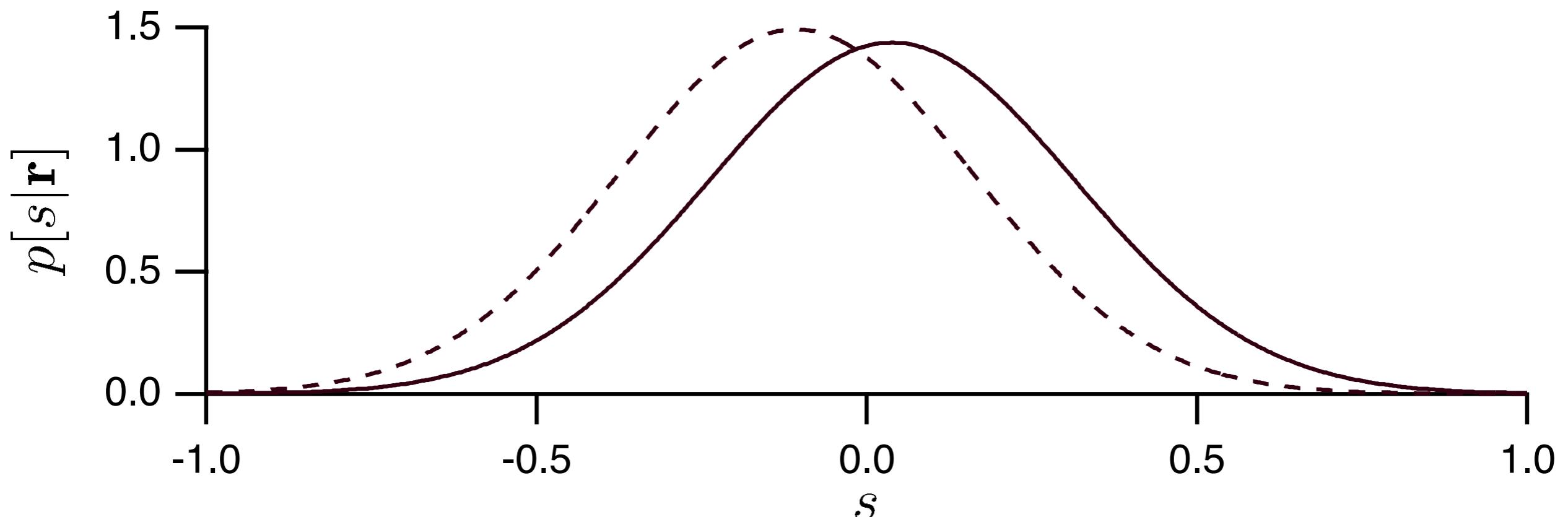
Constructing the MAP estimate of the stimulus:

$$\ln p[s|\mathbf{r}] = T \sum_{a=1}^N r_a \ln(f_a(s)) + \ln p[s] + \dots$$

$$T \sum_{a=1}^N \frac{r_a f'_a(s_{\text{MAP}})}{f_a(s_{\text{MAP}})} + \frac{p'[s_{\text{MAP}}]}{p[s_{\text{MAP}}]} = 0$$

$$s_{\text{MAP}} = \frac{T \sum r_a s_a / \sigma_a^2 + s_{\text{prior}} / \sigma_{\text{prior}}^2}{T \sum r_a / \sigma_a^2 + 1 / \sigma_{\text{prior}}^2}$$

MAP allows us to take $P(s)$ into account:



Bias and variance in our estimates:

$$b_{\text{est}}(s) = \langle s_{\text{est}} \rangle - s$$

$$\sigma_{\text{est}}^2(s) = \langle (s_{\text{est}} - \langle s_{\text{est}} \rangle)^2 \rangle$$

$$\langle (s_{\text{est}} - s)^2 \rangle = \langle (s_{\text{est}} - \langle s_{\text{est}} \rangle - b_{\text{est}}(s))^2 \rangle = \sigma_{\text{est}}^2(s) + b_{\text{est}}^2(s)$$