TTIC 31230, Fundamentals of Deep Learning

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Deep Learning Frameworks

Deep Learning Frameworks

A framework provides a high level language for writing models $P_{\Phi}(y|x)$.

A framework compiles a model into an optimization algorithm.

$$\Phi^* \approx \underset{\Phi}{\operatorname{argmin}} E_{(x,y) \sim \operatorname{Train}} - \ln P_{\Phi}(y|x)$$

A framework also typically provides support for managing large training sets and pre-trained model parameter values (also called "models").

Some Frameworks

- PyTorch
- Tensorflow
- Keras
- Microsoft Cogntive Toolkit
- Chainer

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• EDF (Educational Framework in Python/NumPy used for the first problem set in this class).

An Example

We consider the problem of taking an input x (such as an image of a hand written digit) and classifying it into some small number of classes (such as the digits 0 through 9) using a multi layer perceptron (MLP).

Multiclass Classification

Assume a population distribution on pairs (x, y) for $x \in \mathbb{R}^d$ and $y \in \{y_1, \dots, y_k\}$.

For MNIST x is a 28×28 image which we take to be a 784 dimensional vector giving $x \in \mathbb{R}^{784}$.

For MNIST k = 10.

Let Train be a sample $(x_0, y_0), \ldots, (x_{N-1}, y_{N-1})$ drawn IID from the population.

A Multi Layer Perceptron (MLP)

$$h = \sigma \left(W^0 x - b^0 \right)$$

$$s = \sigma \left(W^1 h - b^1 \right)$$

$$P_{\Phi}[\hat{y}] = \text{softmax } s[\hat{y}]$$

 W^1 and W^2 are matrices. b_1 and b_2 are vectors.

 σ is a scalar-to-scalar activation function applied to each component of a vector.

Activation Functions

An activation function $\sigma : \mathbb{R} \to \mathbb{R}$ (scalar-to-scalar) is applied to each component of a vector.

sigmoid:
$$\sigma(u) = \frac{1}{1+e^{-u}}$$

other common activation functions are

$$ReLU(u) = max(0, u), tanh(u) = 2\sigma(2u) - 1$$

The Framework Source Code

The source code is a sequence of assignment statements taking as input a training point, typically $\langle x, y \rangle$, and outputs a loss value \mathcal{L} , typically $-\ln P_{\Phi}(y|x)$.

$$\mathbf{h} = \sigma \left(W^0 \mathbf{x} - b^0 \right)$$

$$\mathbf{s} = \sigma \left(W^1 \mathbf{h} - b^1 \right)$$

$$P[\hat{y}] = \operatorname{softmax}_{\hat{y}} s[\hat{y}]$$

$$\mathcal{L} = -\ln P[y]$$

Source Code

$$h = \sigma \left(W^{0}x - b^{0} \right)$$

$$s = \sigma \left(W^{1}h - b^{1} \right)$$

$$P[\hat{y}] = \operatorname{softmax}_{\hat{y}} s[\hat{y}]$$

$$\mathcal{L} = -\ln P[y]$$

The source code is sometimes called a **computational graph**. I prefer to call it the source code.

Source Code

$$egin{aligned} m{h} &= \sigma \left(W^0 m{x} - b^0
ight) \ m{s} &= \sigma \left(W^1 m{h} - b^1
ight) \ P_{\Phi}[\hat{y}] &= \operatorname{softmax}_{\hat{y}} \, m{s}[\hat{y}] \ \mathcal{L} &= -\ln P[y] \end{aligned}$$

The framework automatically computes $\nabla_{\Phi} \mathcal{L}_{\Phi}(\langle x, y \rangle)$ where $\Phi = (W^0, b^0, W^1, b^1)$.

Frameworks Automate Stochastic Gradient Descent (SGD)

$$\Phi^* = \underset{\Phi}{\operatorname{argmin}} E_{z \sim \operatorname{Train}} \mathcal{L}_{\Phi}(z)$$

- 1. Randomly Initialize Φ (initialization is important and must be done with care).
- 2. Repeat until "converged":
 - draw $z \sim$ Train at random.
 - $\bullet \Phi = \eta \nabla_{\Phi} \mathcal{L}_{\Phi}(z)$

Epochs

In practice we cycle through the training data visiting each training pair once.

One pass through the training data is called an **Epoch**.

Summary

A framework provides a high level language for defining $\mathcal{L}_{\Phi}(z)$.

The framework compiles the source code for $\mathcal{L}_{\Phi}(z)$ into an optimization algorithm.

$$\Phi^* = \underset{\Phi}{\operatorname{argmin}} E_{z \sim \operatorname{Train}} \mathcal{L}_{\Phi}(z)$$

\mathbf{END}