

# The Finite State Projection Algorithm

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# Master equations

- ▶ Master equations describe the time-evolution of a **discrete state** Markov process in **continuous time**
- ▶ We define a probability  $T_{ij}$  of transitioning to the arbitrary state  $\omega_j$  from  $\omega_i$  where  $\omega_i, \omega_j \in \Omega$
- ▶ These probabilities are efficiently described by a matrix  $\mathbf{T} \in \mathbb{R}^{N \times N}$  where  $N = |\Omega|$
- ▶  $\mathbf{T}[(l, t + dt), (j, t)] = \mathbf{Pr}((l, t + dt), (j, t))$  is a conditional distribution, given that we are in a state  $j$  at time  $t$

Initially we assume  $\mathbf{T}$  is constant in time

# The forward equation

The time evolution of  $P(\Omega, t) \in \mathbb{R}^{N \times 1}$  is determined by the net probability flux into and out of each state:

$$\begin{aligned} P(\omega_i, t + dt) &= \overbrace{T_{ii}P(\omega_i)dt + \sum_{j \neq i} T_{ij}P(\omega_j, t)dt}^{j \rightarrow i} + \overbrace{\sum_{j \neq i} T_{ji}P(\omega_i, t)dt}^{i \rightarrow j} \\ &= \overbrace{\sum_{j \neq i} T_{ij}P(\omega_j, t)dt}^{j \rightarrow i} + \overbrace{P(\omega_i, t) \sum_j T_{ji}dt}^{i \rightarrow j} \\ &= \overbrace{\sum_{j \neq i} T_{ij}P(\omega_j, t)dt}^{j \rightarrow i} + \overbrace{P(\omega_i, t) \left( 1 - \sum_j T_{ij}dt \right)}^{i \rightarrow j} \end{aligned}$$

$$P(\omega_i, t + dt) = \sum_{j \neq i} T_{ij} P(\omega_j, t) dt + P(\omega_i, t) \left( 1 - \sum_j T_{ij} dt \right)$$

$$\lim_{dt \rightarrow 0} \frac{P(\omega_i, t + dt) - P(\omega_i, t)}{dt} = \sum_{j \neq i} T_{ij} P(\omega_j, t) - P(\omega_i, t) \sum_j T_{ij}$$

Rearranging, we arrive at the **master equation**

$$\frac{dP(\omega_i)}{dt} = \sum_j T_{ji} P(\omega_j, t) - T_{ij} P(\omega_i, t)$$

## Operator formulation

It is common to then define an operator  $\mathbf{W}$  s.t.  $W_{ij} = T_{ij}$  and  $W_{ii} = -\sum_j T_{ij}$

$$\frac{dP(\omega_i)}{dt} = \sum_j W_{ij} P(\omega_j) \rightarrow \frac{dP(\omega)}{dt} = \mathbf{W}P(\omega)$$

We have the following simplified form of a general master equation

$$\frac{dP(\omega)}{dt} = \mathbf{W}P(\omega)$$

# The chemical master equation

We transition from a state  $\omega_j$  to  $\omega_i$  via reaction  $\nu$

Thus states are related by  $\omega_i = \omega_j + \nu_j$ . Suppose that  $\mathbf{T}$  varies with the state  $\mathbf{x}$

$$\begin{aligned}\frac{dP(\omega_i)}{dt} &= \sum_j T_{ji}P(\omega_j, t) - T_{ij}P(\omega_i, t) \\ &= \sum_j T_{ji}(\mathbf{x} - \nu)P_j(\mathbf{x} - \nu, t) - T_{ij}(\mathbf{x})P_j(\mathbf{x}, t)\end{aligned}$$

Or in vector form, we have

$$\frac{dP(\mathbf{x})}{dt} = \sum_j T_j(\mathbf{x} - \nu)P_j(\mathbf{x} - \nu, t) - T_j(\mathbf{x})P_j(\mathbf{x}, t)$$

# The chemical master equation intuition

We arrived at the following equation

$$\mathcal{J} = \frac{dP(\mathbf{x})}{dt} = \sum_j T_j(\mathbf{x} - \boldsymbol{\nu})P_j(\mathbf{x} - \boldsymbol{\nu}, t) - T_j(\mathbf{x})P_j(\mathbf{x}, t)$$

where  $\mathcal{J}$  is a probability current

$P(\mathbf{x}, t)$  is a density over the state space  $\Omega$ . This is then a sum over the entire state space

Each term of the above sum is a vector multiplied by a scalar. The current  $\mathcal{J}$  is a vector expressed as a sum of vectors

# The chemical master equation intuition

We write it as a matrix multiplication by arranging  $T_j(\mathbf{x} - \boldsymbol{\nu}_j)$  as the columns of a matrix  $\mathcal{L}(\mathbf{x} - \boldsymbol{\nu}_j)$

$$\mathcal{J}(\mathbf{x}, t) = \mathcal{L}(\mathbf{x} - \boldsymbol{\nu}_j, t)P(\mathbf{x} - \boldsymbol{\nu}_j, t) - \mathcal{L}(\mathbf{x}, t)P(\mathbf{x}, t)$$

But  $\boldsymbol{\nu}_i = 0$  so we define  $\mathbf{W} = \mathcal{L}(\mathbf{x} - \boldsymbol{\nu}_j, t) - \text{diag}(\mathcal{L}(\mathbf{x}, t))$  which gives

$$\mathcal{J}(\mathbf{x}, t) = \mathbf{W}P(\mathbf{x}, t)$$