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STOCHASTIC COMPUTATION IN RECURRENT NETWORKS OF SPIKING
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CLAYTON W. SEITZ

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Epigraph

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ABSTRACT

The primate cerebral cortex is a complex system estimated to harbor more than 25 billion neurons communicating via action potentials or ‘spikes’ and is responsible for many higher-order brain functions including memory and learning. Recent years have hosted many efforts to understand how such complex phenomena emerge from the communication of individual cells. Many studies have provided evidence that long term plasticity (LTP) in the connections between neurons permits a long-lasting alteration of network dynamics and, in turn, forms the basis of long-term memory and learning. Capturing the features of neural activity observed *in-vivo* in computer based models such as recurrent spiking neural networks (RSNNs) while explaining the manipulation of information by cortical microcircuits in mathematical detail has become the gold standard for computational neuroscience. At the same time, more biophysical approaches have described the dynamics of an RSNN by modeling the membrane potential of a cortical neuron as obeying a form of Langevin dynamics i.e., a diffusion process. Here, we apply a similiar physical treatment to the study of an RSNN by modeling the membrane potential dynamics of an integrate and fire neuron statistically using Fokker-Planck equations. With this statistical framework in hand, we can recast the biological system as a diffusion process in higher dimensions and explore the relationships between synaptic connectivity to the correlation structure of neural spike trains. This approach serves to bridge fundamental biological mechanisms and their impact on network dynamics and the emergent computational capabilities of cortical microcircuits.

CHAPTER 1

INTRODUCTION

Towards the Hopfield network [2] which spawned an entire field of research applying techniques from the statistical physics of spin glasses to the description of neural activity. A popular approach towards the end of 20th century simplified a network of neurons firing action potentials to an ensemble of coupled spins obeying an energy function over the space of states. , the Hopfield model related the patterns learned by a network to the energy landscape over the discrete space of states. The storage capacity of these networks and the geometry of this energy landscape were of particular interest and rigorous mathematical treatment has been used to show limits on the basins of attraction in such energy landscapes [4,10,11]. However, recent experimental evidence has suggested that networks of neurons may follow a stochastic, rather than deterministic, computational paradigm. There are many examples in the literature of trial-to-trial variability in the response of cortical neurons to identical stimuli, suggesting that computations in the brain are inherently stochastic. The origins of this stochasticity are hypothesized to originate in noise in synaptic conductances and infidelity in processes clearing neurotransmitters from the synaptic cleft. Interestingly, an extension of the Hopfield model - the Boltzmann machine actually leverages stochastic activity of Ising spins to perform powerful computations [14]. In such a model, the set of synaptic weights Φ “embody” the joint distribution $P_{\Phi}(X, R) = P_{\Phi}(X)P_{\Phi}(R|X)$ over network inputs and network response, respectively. Then, computations can be viewed as probabilistic inference after suitable transformations of the weights $\Delta\Phi$. Such physically inspired models have proven useful; however, the models are sufficiently abstract to make experimental comparisons difficult. More recent endeavors appear to make useful predictions on network dynamics by using Fokker-Planck equations to compute distributions of the membrane voltage as a function of time [5]. Here, we apply a similar formalism to the description of network dynamics with heterogeneous and stochastic synaptic weights to probe the distribution over

network states $P_{\Phi}(R)$ and describe how this framework can be used to provide insights on how the neural networks embody the distribution $P_{\Phi}(R|X)$ in statistical inference tasks. To conclude, we discuss the effect of synaptic plasticity.

The quantitative discussion of the dynamics of many complex systems (systems where the number of interacting units N is large) in nature from networks of spiking neurons, geophysical systems, to excitable media, all necessarily require a statistical description. Indeed, enumerating the available states to such a system itself has proven intractable, even for small systems over short time scales. As an example, consider the states of an interacting system of N binary variables denoted $\{z_i\}_{i=1}^N$ which might be physically realized as an ensemble of spins in a ferromagnet. Even for extremely small cases such as $N = 100$ the system can take on $2^{100} = 1.26 \times 10^{30}$ different configurations and by $N = 300$ the number of configurations exceed our best estimates for the number of atoms in the known universe. At the same time, we cannot hope to make enough measurements of such a system to estimate the probability distribution over the space of states and make inferences on the organization and interactions of the individual elements based on such a distribution. We can, however, develop model distributions over the available states based on stochastic interaction between the individual units that account for the degrees of freedom which we cannot approach analytically - a technique often employed in the description of the statistical physics of particles. This family of techniques, often formally referred to as Langevin dynamics, is defined by the use of stochastic differential equations to model the evolution of systems with high degrees of freedom. A Fokker-Planck equation allows us to solve for the time evolution of the probability distribution over such a variable, providing insights into the dynamics which cannot be seen from any one trajectory through the space of states.

CHAPTER 2

STOCHASTIC SYSTEMS AND FOKKER-PLANCK EQUATIONS

2.1 The Langevin Equation

In the context of neuroscience, the Fokker-Planck approach has been taken by many in describing the dynamics of the membrane potential distribution in a population of neurons. In the following paragraphs, we will sketch a derivation of the Fokker-Planck equation for a general stochastic process in one dimension and apply this result to networks of integrate and fire neurons.

2.1.1 The Kramers-Moyal expansion

Given many instantiations of a stochastic variable V , we can construct a normalized histogram over all observations as a function of time $P(V, t)$. However, in order to systematically explore the relationship between the parameterization of the process and $P(V, t)$ we require an expression for $\dot{P}(V, t)$. If we make a fundamental assumption that the evolution of $P(V, t)$ follows a Markov process i.e. its evolution has the memoryless property, then we can write

$$P(V, t) = \int T(V', t|V, t - \tau) P(V, t - \tau) dV \quad (2.1)$$

which is known as the Chapman-Kolmogorov equation. The factor $T(V', t|V, t - \tau)$ is known as the *transition operator* in a Markov process and determines the evolution of $P(V, t)$ in time. We proceed by writing $T(V', t|V, t - \tau)$ in a form referred to as the Kramers-Moyal expansion

$$\begin{aligned}
T(V', t|V, t - \tau) &= \int \delta(u - V') T(u, t|V, t - \tau) du \\
&= \int \delta(V + u - V' - V) T(u, t|V, t - \tau) du
\end{aligned}$$

If we use the Taylor expansion of the δ -function

$$\delta(V + u - V' - V) = \sum_{n=0}^{\infty} \frac{(u - V)^n}{n!} \left(-\frac{\partial}{\partial V} \right)^n \delta(V - V')$$

Inserting this into the result from above, pulling out terms independent of u and swapping the order of the sum and integration gives

$$T(V', t|V, t - \tau) = \sum_{n=0}^{\infty} \frac{1}{n!} \left(-\frac{\partial}{\partial V} \right)^n \delta(V - V') \int (u - V)^n T(u, t|V, t - \tau) du \quad (2.2)$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} \left(-\frac{\partial}{\partial V} \right)^n \delta(V - V') M_n(V, t) \quad (2.3)$$

noticing that $M_n(V, t) = \int (u - V)^n T(u, t|V, t - \tau) du$ is just the n th moment of the transition operator T . Plugging (2.6) back in to (2.4) gives

$$P(V, t) = \int \left(1 + \sum_{n=1}^{\infty} \frac{1}{n!} \left(-\frac{\partial}{\partial V} \right)^n M_n(V, t) \right) \delta(V - V') P(V, t - \tau) dV \quad (2.4)$$

$$= P(V', t - \tau) + \sum_{n=1}^{\infty} \frac{1}{n!} \left(-\frac{\partial}{\partial V} \right)^n [M_n(V, t) P(V, t)] \quad (2.5)$$

Approximating the derivative as a finite difference and taking the limit $\tau \rightarrow 0$ gives

$$\dot{P}(V, t) = \lim_{\tau \rightarrow 0} \left(\frac{P(V, t) - P(V, t - \tau)}{\tau} \right) \quad (2.6)$$

$$= \sum_{n=1}^{\infty} \frac{1}{n!} \left(-\frac{\partial}{\partial V} \right)^n [M_n(V, t) P(V, t)] \quad (2.7)$$

which is formally known as the Kramers-Moyal (KM) expansion. The Fokker-Planck equation is a special case of (2.10) where we neglect terms $n > 2$ in the *diffusion approximation*.

2.1.2 Fokker-Planck for a Gaussian process

Consider the following Langevin equation (first order stochastic differential equation) representing a leaky integration process

$$\tau \dot{V}(t) = -V(t) + J\eta(t)$$

with initial condition $V(0) = 0$ and noise amplitude J . To illustrate the applicability of (2.10) in predicting the distribution $P(V, t)$, we consider the highly simplified case where the stochastic term is a 1D Gaussian white noise with linear drift and unit variance i.e. $\eta(t) \sim \mathcal{N}(\alpha t, 1)$. Therefore, the first two moments are $\mu(t) = \alpha t$ and $\sigma^2(t) = 1$ and all higher order moments are zero, giving the following Fokker-Planck equation

$$\dot{P}(V, t) = -\alpha t \frac{\partial}{\partial V} [P(V, t)] + \frac{1}{2} \frac{\partial^2}{\partial V^2} [P(V, t)]$$

which we integrate numerically using the forward Euler method

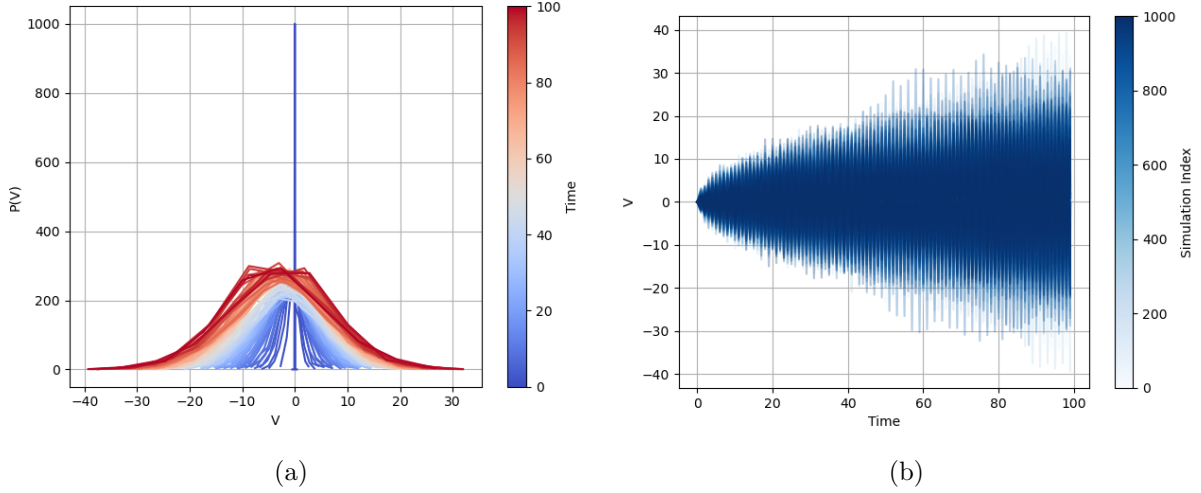


Figure 2.1: Results of numerical integration of a Langevin equation for a gaussian white noise process with $J = 1$, $\tau = 1$, $\alpha = 0.01$, and $V(0) = 0$. (a) Distribution of the stochastic variable over $N = 1000$ units as a function of time. (b) Time course for $N = 1000$ units

$$\begin{aligned}
 P(V, t + \Delta t) = P(V, t) + \Delta t & \left[\alpha t \cdot \frac{P(V + \Delta V, t) - P(V, t)}{\Delta V} \right] \\
 & - \Delta t \left[\frac{1}{2} \frac{P(V + \Delta V, t) - 2P(V, t) + P(V - \Delta V, t)}{\Delta V^2} \right]
 \end{aligned}$$

2.2 Fokker-Planck for Homogeneous Sparse Networks

The moments $M_n(t)$ derived above in the Kramers-Moyal expansion are dependent on the connectivity of the network and the statistics of the input. We will first consider a classic case, where we have a sparse directed network with constant synaptic efficacy between all presynaptic and postsynaptic pairs of cells. This primary pool of neurons is subject to stimulation by N_{in} input neurons with a connection probability γ_{in} giving $C_{\text{in}} = \gamma_{\text{in}} N_{\text{rec}}$ unique connections between the input population and a single neuron in the recurrent pool. Within the recurrent pool, we have a connection probability of $\gamma_{\text{rec}} \ll 1$ for any pair giving $C_{\text{rec}} = \gamma_{\text{rec}} N_{\text{rec}}$ recurrent inputs per postsynaptic cell. We assume that a presynaptic action

potential invokes a post synaptic potential (PSP) with magnitude J_0 in the postsynaptic cell with $J_0 \ll \theta$ for both input and recurrent projections. The first moment of the transition operator $T(V', t|V, t - \tau)$ is given by

$$\begin{aligned}\mu(t) &= \mu_{in} + \mu_{rec}(t) \\ &= (C_{in}\nu_{in}(t) + C_{rec}\nu_{rec}(t)) \tau \langle J \rangle \\ &= (C_{in}\nu_{in}(t) + C_{rec}\nu_{rec}(t)) \tau J_0\end{aligned}$$

where $\nu_{in}(t)$ is the rate parameter for the input Poisson process. The second moment

$$\begin{aligned}\sigma^2(t) &= \sigma_{rec}^2 + \sigma_{ext}^2 \\ &= (C_{in}\nu_{in}(t) + C_{rec}\nu_{rec}(t)) \tau \langle J^2 \rangle \\ &= (C_{in}\nu_{in}(t) + C_{rec}\nu_{rec}(t)) \tau J_0^2\end{aligned}$$

After inserting the first two moments into (2.10) we arrive at the following Fokker-Planck equation

$$\dot{P}(V, t) = -\frac{\partial}{\partial V}[\mu(t)P(V, t)] + \frac{1}{2}\frac{\partial^2}{\partial V^2}[\sigma^2(t)P(V, t)]$$

At this point, it is necessary to impose the appropriate boundary conditions on the above Fokker-Planck equation as in so as to maintain biological realism. The Fokker-Planck equation can be written as the continuity equation

$$\frac{\partial P(v, t)}{\partial t} = -\frac{\partial S}{\partial V}$$

(Risken, 1984) with

$$S(V, t) = -\frac{v - V_L - \mu}{\tau} P(V, t) - \frac{\sigma^2(t)}{2\tau} \frac{\partial P(V, t)}{\partial V}$$

which is known as the *probability current* through voltage V at a time t . The instantaneous firing rate is equivalent to the probability current through the threshold i.e. $\nu(t) = S(\theta, t)$. Furthermore, we require that the probability current through the firing threshold $P(\theta, t) = 0$ and that instead this probability emerges at the resting potential after a refractory period of τ_{ref} . This condition gives the following boundary condition for the derivative of the probability with respect to voltage

$$\frac{\partial P(\theta, t)}{\partial V} = -\frac{2\tau\nu(t)}{\sigma^2(t)}$$

To account for the refractory period τ_{ref} , we define an auxiliary distribution

$$p_r(t) = \int_{t-\tau_{\text{ref}}}^t \nu(t) dt$$

which together with the distribution $P(V, t)$ satisfy the normalization condition:

$$\int P(v, t) dV + p_r(t) = 1$$

$$\frac{\partial P(v, t)}{\partial t} = \left(\mu(t) - \frac{v - v_L}{\tau} \right) \frac{\partial}{\partial v} P(v, t) - \frac{\sigma^2(t)}{2\tau} \frac{\partial^2}{\partial v^2} P(v, t) + \nu(t - \tau_{\text{ref}}) \delta(v - V_R)$$

which we approximate by central finite differences

$$\begin{aligned} \frac{p(v, t + \Delta t) - p(v, t)}{\Delta t} &= \left(\mu(t) - \frac{v - v_L}{\tau} + \mu_{ext} \right) \frac{p(v + \Delta v, t) - p(v, t)}{\Delta v} \\ &\quad - \frac{1}{2} \left(\sigma^2(t) + \sigma_{ext}^2 \right) \frac{p(v + \Delta v, t) - 2p(v, t) + p(v - \Delta v, t)}{\Delta v^2} \end{aligned}$$

CHAPTER 3

DYNAMICAL STATES OF RECURRENT NETWORKS

3.1 Introduction

CHAPTER 4

STOCHASTIC COMPUTATION BY RECURRENT NETWORKS

4.1 Introduction

CHAPTER 5

CONCLUSIONS

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