

# Neural dynamics of vision

A computational perspective

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January 26, 2021



Dedicated to Calvin and Hobbes.



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# Preface

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## Structure of book

Each unit will focus on <SOMETHING>.

## About the companion website

The website<sup>1</sup> for this file contains:

- A link to (freely downloadable) latest version of this document.
- Link to download LaTeX source for this document.
- Miscellaneous material (e.g. suggested readings etc).

## Acknowledgements

- A special word of thanks goes to Professor Don Knuth<sup>2</sup> (for T<sub>E</sub>X) and Leslie Lamport<sup>3</sup> (for L<sup>A</sup>T<sub>E</sub>X).
- I'll also like to thank Gummi<sup>4</sup> developers and LaTeXila<sup>5</sup> development team for their awesome L<sup>A</sup>T<sub>E</sub>X editors.
- I'm deeply indebted my parents, colleagues and friends for their support and encouragement.

Amber Jain

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<sup>1</sup><https://github.com/amberj/latex-book-template>

<sup>2</sup><http://www-cs-faculty.stanford.edu/~uno/>

<sup>3</sup><http://www.lamport.org/>

<sup>4</sup><http://gummi.midnightcoding.org/>

<sup>5</sup><http://projects.gnome.org/latexila/>



# 1

## The Neural Code

*“This is a quote and I don’t know who said this.”*

– Author’s name, *Source of this quote*

### 1.1 Section heading



## 2

# Learning Theory

*“This is a quote and I don’t know who said this.”*

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### 2.1 Section heading



# 3

## Biologically-Inspired Computer Vision

*“This is a quote and I don’t know who said this.”*

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### 3.1 Natural Image Statistics

### 3.2 Gabor Analysis



## 4

# Semantic Coding

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### 4.1 Section heading





## 5

# Information and Coding Theory

*“We may have knowledge of the past but cannot control it; we may control the future but have no knowledge of it”*

– Claude Shannon

## 5.1 Introduction

Information theory is a framework first introduced by Claude Shannon’s seminal paper *A mathematical theory of communication* published in 1948. At its core, information theory makes the intuitive concept of *information* mathematically rigorous and forms the foundation of many modern communication systems. Neural circuits in the visual system are an especially interesting example of such a communication system. Therefore, in this section, the information theoretic concepts necessary for studying neural circuits are introduced.

## 5.2 Entropy

The concept of entropy is not exclusive to information theory; rather, it is used widely in disciplines such as physics and mathematical statistics. In fact, entropy was originally defined in statistical physics when Ludwig Boltzmann gave a statistical description of a thermodynamic system of particles. Since this is arguably the more intuitive path as opposed to an entirely mathematical description, I will follow a similar line of reasoning in the following paragraphs.

In every application, the entropy  $\mathbf{H}$  is a measure of uncertainty or how much information is contained in a random variable  $x$ . In information theory, the entropy is a property of a probability distribution of a random variable

$P(x)$  where  $x$  can take on continuous or discrete values. For the discrete case, we can express the entropy in bits

$$\mathbf{H} = \sum_{x \in S} P(x) \log \frac{1}{P(x)} \quad (5.1)$$

where the set  $S$  spans the entire space of possible discrete values of  $x$ . We can go on to derive upper and lower bounds for the entropy. Notice that  $\mathbf{H} \geq 0$  since  $P(x) \leq 1$  and therefore  $\log P(x) \leq 0$  for all  $x$ . At the same time, if we define a variable  $Y = \frac{1}{\log x}$ , we can write

$$\begin{aligned} \mathbf{H} &= \mathbf{E}[\log Y] \\ &\leq \log \mathbf{E}[Y] \\ &= \log \sum_y P(x) \frac{1}{P(x)} \\ &= \log |S| \end{aligned}$$

which is just the entropy of a uniform distribution.

### 5.3 Joint Entropy

$$\begin{aligned} \mathbf{H}(X, Y) &= \sum_{x,y} P(x, y) \log \frac{1}{P(x, y)} \\ &= \sum_{x,y} P(x)P(y|x) \log \frac{1}{P(x)P(y|x)} \\ &= \sum_{x,y} P(x)P(y|x) \log \frac{1}{P(x)} + \sum_{x,y} P(x)P(y|x) \log \frac{1}{P(y|x)} \\ &= \sum_{x,y} P(x)P(y|x) \log \frac{1}{P(x)} + \sum_x P(x) \sum_y P(y|x) \log \frac{1}{P(y|x)} \\ &= H(X) + H(Y|X) \end{aligned}$$

This result defines the **chain rule** for entropy.

### 5.4 Source Coding

**Definition 1.** A code of a set  $S$  that uses an alphabet  $\Omega$  is a map  $C : S \rightarrow \Omega$  that assigns each element of  $S$  a finite string over the alphabet  $\Omega$ . We say that the mapping  $C$  is **prefix free** if for all pairs  $x, y \in S$  where  $x \neq y$ ,  $C(x)$  is not a prefix of  $C(y)$ .

Most of the time the alphabet  $\Omega$  we use is the set  $0, 1$ .

### 5.4.1 Kraft's Inequality

**Definition 2.** For a binary code, there exists a prefix free code  $C$  with codeword lengths  $l_i$  if and only if

$$\sum_i 2^{-l_i} \leq 1 \quad (5.2)$$

At this point we would like to apply the concept of entropy to source coding. Indeed, it is true that if we have a random variable  $X$  over the set  $S$ , the minimum number of bits it will take us to communicate the value of  $X$  on average is the entropy  $H(X)$ .

*Proof.* The expected number of bits to communicate  $X$  is given by  $\sum_x p(x)|C(x)|$

$$\begin{aligned} H(X) - \sum_x P(x)|C(x)| &= \sum_x P(x) \left[ \log \frac{1}{P(x)} - |C(x)| \right] \\ &= \sum_x P(x) \log \frac{1}{P(x) 2^{|C(x)|}} \\ &\geq \log \sum_x P(x) \frac{1}{P(x) 2^{|C(x)|}} \\ &= \log \sum_x \frac{1}{2^{|C(x)|}} \\ &\leq 0 \end{aligned} \quad \square$$

by Kraft's inequality for prefix-free codes.

### 5.4.2 Jensen's Inequality

Jensen's inequality is a statement about convexity. Consider a binary variable  $x$  that takes the value 0 with probability  $\alpha$  and value 1 with probability  $1 - \alpha$ .

$$x = \begin{cases} 0 & \alpha \\ 1 & 1 - \alpha \end{cases}$$

A function  $f$  of the variable  $x$  is said to be *convex* if the following inequality holds

$$\alpha f(x) + (1 - \alpha) f(y) \leq f(\alpha x + (1 - \alpha) y)$$

which when generalized for an arbitrary random variable  $x$  forms Jensen's inequality

$$\mathbf{E}[f(x)] \leq f(\mathbf{E}[x]) \quad (5.3)$$

### 5.4.3 The Data-Processing Inequality

The data-processing inequality states that for any function  $f$  s.t.  $y = f(X)$ , we have that  $H(Y) \geq H(X)$ . In plain english, that means that the process of transforming  $X$  can never decrease its entropy. Recall from our analysis of joint entropy above that

$$H(X, Y) = H(X) + H(Y|X) \quad (5.4)$$

$$= H(Y) + H(X|Y) \quad (5.5)$$

If we can show that  $H(y|x) = 0$  then the data-processing inequality holds. This is more obvious if you notice that if  $y = f(x)$  then the distribution  $P(x, y) = P(x)$  or  $P(y|x) = 0$ .

In terms of our venn diagram above,  $H(y)$  is a \*subset\* of  $H(x)$  which also implies the following for the mutual information:  $I(x, y) = H(y)$ .

### 5.4.4 Example 1: Applying Jensen's Inequality

Let's consider a function  $f : \mathbb{R} \rightarrow \mathbb{R}$ . Using Jensen's inequality, we can prove that  $f = x^2$  or  $f = x \log x$  are convex functions. Let's begin by applying it to  $x^2$  for a general normalized probability distribution  $p(x)$ .

$$\begin{aligned} \int p(x) f(x) dx &= \int x^2 p(x) dx \\ &= x^2 - 2 \int x dx \\ &= 0 \leq x^2 \quad \forall x \end{aligned}$$

We have a similar proof for  $f(x) = x \log x$

$$\begin{aligned} \int p(x) f(x) dx &= \int x \log x p(x) dx \\ &= x \log x - \int \frac{d}{dx} x \log x dx \\ &= 0 \leq \mu \log \mu \end{aligned}$$

where  $\mu = \mathbf{E}[x] \geq 0$  since  $f$  is only defined on  $[0, \infty]$ .

### 5.4.5 Example 2: Proving Cauchy-Schwarz

A common form of the Cauchy-Schwarz inequality states that for two vectors  $u$  and  $v$ , we have

$$u \cdot v \leq \|u\| \|v\|$$

## **5.5 Error Correcting Codes**



## 6

# Microscopy and Image Analysis

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### 6.1 Section heading