#### The variational autoencoder

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#### Outline

References

### The logic of generative modeling

Say we have a set of variables  $x = (x_1, x_2, ..., x_n)$  which might have some statistical dependence

The variable x might be an amino acid sequence, gene expression data, microscopy image, etc.

- ▶ Often we are handed a batch of empirical samples  $\{x_i\}_{i=1}^N$
- ▶ We want to know the generating distribution p(x)

In supervised generative learning, we try to explicitly learn the joint distribution  $p(x) = \prod_{i=1}^{N-1} p(x_i|x_{i+1:N})p(x_N)$ , which is generally more difficult than discriminative learning.

# Perks of generative modeling

- Fitting complete multivariate distributions p(x) goes beyond correlation-based or clustering approaches
- Correlations cannot discover partial correlation in the context of other neighbors
- Fitting p(x) permits sampling based inference

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# Why generative modeling is difficult

When describing a distribution over multiple variables, we may not know the proper normalization Z. That is,

$$p(x) = \frac{1}{Z}\tilde{p}(x)$$

This very important situation arises in several contexts:

- 1. In Bayesian inference where  $p(x_1|x_2) = p(x_2|x_1)p(x_1)/p(x_2)$  is intractable due to  $Z = p(x_2) = \int p(x_2|x_1)p(x_1)dx_1$ . This integral can be very difficult or impossible to compute.
- 2. In models from statistical physics, e.g. the Ising model, we only know  $\tilde{p}(x) = e^{-H(x)}$  where H(x) is the Hamiltonian

### Bayesian inference

The variable x has a latent representation or code z. We often say that z is the *causal source* of x. Ultimately, we would like to know the distribution  $P_{\Phi}(x)$ 

$$P_{\phi}(\mathsf{x}) = rac{P_{\phi}(\mathsf{x}|\mathsf{z})P_{\phi}(\mathsf{z})}{Q_{\psi}(\mathsf{z}|\mathsf{x})}$$

in order to find the model parameters that maximize the likelihood of the observed data:

$$\Phi^* = \operatorname*{argmin}_{\Phi} - \log P_{\Phi}(x)$$

but we generally do not know  $P_{\psi}(\mathbf{z}|\mathbf{x})$  due to the intractable integral  $Z = \int P_{\phi}(\mathbf{x}|\mathbf{z})P_{\phi}(\mathbf{z})d\mathbf{z}$  (see slide 5)

### Computing the evidence

We can rewrite the evidence as

$$\begin{aligned} P_{\phi}(\mathsf{x}) &= \int P_{\phi}(\mathsf{z}) P_{\phi}(\mathsf{x}|\mathsf{z}) d\mathsf{z} \\ &= \int P_{\phi}(\mathsf{z}) P_{\phi}(\mathsf{x}|\mathsf{z}) \frac{P_{\phi}(\mathsf{z}|\mathsf{x})}{P_{\phi}(\mathsf{z}|\mathsf{x})} d\mathsf{z} \\ &= \mathbb{E}_{\mathsf{z} \sim P_{\phi}(\mathsf{z}|\mathsf{x})} \frac{P_{\phi}(\mathsf{z}) P_{\phi}(\mathsf{x}|\mathsf{z})}{P_{\phi}(\mathsf{z}|\mathsf{x})} \end{aligned}$$

where  $P_{\phi}(\mathbf{z}|\mathbf{x})$  is our model "encoder"

# The evidence lower bound (ELBO)

$$\begin{split} \log P_{\phi}(\mathbf{x}) &= \log \int_{z} P(x,z) dx \\ &= \log \int_{z} P(x,z) \frac{Q(z|x)}{Q(z|x)} dz \\ &= \log \mathbb{E}_{\mathbf{z} \sim P_{\phi}(\mathbf{z}|\mathbf{x})} \frac{P(x|z)P(z)}{Q(z|x)} \\ &\geq \mathbb{E}_{\mathbf{z} \sim P_{\phi}(\mathbf{z}|\mathbf{x})} \log \frac{Q(x|z)}{P(z)} + \log P(x|z) \\ &- \log P_{\phi}(\mathbf{x}) \leq \mathbb{E}_{\mathbf{z} \sim P_{\phi}(\mathbf{z}|\mathbf{x})} \log \frac{Q(x|z)}{P(z)} - \log P(x|z) \end{split}$$

### The ELBO objective

$$\begin{split} \Phi^* &= \mathcal{L}(\Phi) \\ &= \underset{\Phi}{\operatorname{argmin}} \ \mathbb{E}_{\mathsf{x} \sim \operatorname{Pop}, \ \mathsf{z} \sim P_{\phi}(\mathsf{z}|\mathsf{x})} \log \frac{Q_{\Psi}(\mathsf{z}|\mathsf{x})}{P(\mathsf{z})} - \log P(\mathsf{x}|\mathsf{z}) \end{split}$$

The ELBO can be rewritten in terms of a KL-divergence and population entropy. We often think of  $\Phi$  as "position" and the loss  $\mathcal L$  as an "energy"

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