BPNN 实验报告

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1. 实验内容:

实现基本 后传递神经元网络 Back Propagation Neural Networks (BPNN) 算法

2. 实验环境

- a) python3.7
- b) VSCode
- c) Win10

3. 实现的功能:

- a) 1输入层, N隐藏层, 1输出层(N可变)
- b) 隐藏层的节点数目可变
- c) 激活函数有三种
- d) 输入数据为矩阵
- e) 输入层维度与输出层维度均可变
- f) Learning Rate 与 limits 均可变

4. 用法:

BBNP 类有五个常规参数:

输入样例、期望样例、隐藏层节点数量、激励函数类型、隐藏层数量,以及两个缺省参数: 迭代数量、learning rate,默认值分别为 10000 与 0.05 在实例化之后,调用成员函数 test()即可进行迭代,并返回最终结果值,同时在 console 里打出 log

```
def main():
   #init test data
    cases = [
           [0.5, 0.9, 0.1],
           [0.1, 0.7, 0.4],
          [0.99, 0.11, 0.3]
    expects = [
       [0.1, 0.291, 0.7],
       [0.6, 0.8, 0.1],
       [0.1, 0.8, 0.81]
    number_of_neurons = 5
    function mode = 2
    n_{\text{layers}} = 3
    limits = 100
    #init the main class with default learning-rate=0.05
    bn = BPNN(cases, expects, number_of_neurons, function_mode, n_layers, limits)
   bn.test()
```

5. 源码:

a) 主入口

```
def __init__(self, cases, expects, nh, mode, nlayer, limits = 100000, learn = 0.05):
    if len(cases) < 1:
       print("case can not be empty!!")
       exit(0)
    if len(cases) != len(expects):
       print("cases and expects not matching !")
       exit(0)
    if limits <= 0 :
      print("limits should be a positive number!")
       exit(0)
    if learn<0 or learn >0.1:
      print("learning-rate should be between [0, 1]!")
       exit(0)
    self.input_n = len(cases[0]) + 1 #include bias
    self.hidden_n = nh + 1#include bias
    self.output_n = len(cases[0])
    self.mode = mode
    self.layer_n = nlayer
    self.cases = cases
    self.expects = expects
    self.limits = limits
    self.learn = learn
    #init datas
    self.input_datas = [1.0] * self.input_n
    self.hidden_datas = [1.0] * self.hidden_n
    self.output_datas = [1.0] * self.output_n
    self.ih_weights = []
    self.ho_weights = []
    #init weights
    for i in range(self.input_n):
       tmp = []
        for h in range(self.hidden_n - 1):
         tmp.append(rand(-0.2, 0.2))
           self.ih_weights.append(tmp)
    for h in range(self.hidden_n):
       tmp = []
        for o in range(self.output_n):
            tmp.append(rand(-0.2, 0.2))
          self.ho_weights.append(tmp)
```

自定义一个 BPNN 类, input、hidden、output 分别代表输入层、隐藏层与输出层 三个 data 矩阵存放各个神经元节点的数据, 初始化为 1.0; 另外两个矩阵存放两个权重矩阵, 初始化为(-0.2, 0.2)间的随机值

b) 激励函数选择:简单地使用 mode 来进行选择

```
def sigmoid(x, mode):
   if mode == 1:
     return logistic(x)
   elif mode == 2:
      return tanh(x)
   elif mode == 3:
      return relu(x)
   else:
      print("mode does not exist!")
      return 0
def sigmoid_derivative(x, mode):
   if mode ==1:
      return logistic_derivative(x)
   elif mode ==2:
     return tanh_derivative(x)
   elif mode == 3:
   return relu_derivative(x)
   print("mode doex not exist")
```

c) Predict

进行加权计算, 算出 hidden 层和 output 层每个节点的输出

```
def predict(self, inputs):
   # activate input layer
   for i in range(self.input_n - 1):
    self.input_datas[i] = inputs[i]
   # activate hidden layer
   for j in range(self.hidden_n - 1):
       sum = 0.0
       for i in range(self.input n):
       sum += self.input_datas[i] * self.ih_weights[i][j]
       self.hidden_datas[j] = sigmoid(sum, self.mode)
   # activate output layer
   for k in range(self.output_n):
       sum = 0.0
       for j in range(self.hidden_n - 1):
       sum += self.hidden_datas[j] * self.ho_weights[j][k]
       self.output_datas[k] = sigmoid(sum, self.mode)
   return self.output_datas
```

d) Back_propagate:

反向传播并更新权值

```
def back propagate(self, case, expect, learn ):
   #feed forward
   self.predict(case)
   #get output layer error
   output_errors = [0.0] * self.output_n
   for i in range(self.output_n):
       error = expect[i] - self.output_datas[i]
      output_errors[i] = sigmoid_derivative(self.output_datas[i], self.mode)*error
   #get hidden layer error
   hidden_errors = [0.0]*(self.hidden_n - 1)
   for i in range(self.hidden_n - 1):
      error = 0.0
       for j in range(self.output_n):
           error += output_errors[j] * self.ho_weights[i][j]
       hidden_errors[i] = sigmoid_derivative(self.hidden_datas[i], self.mode) * error
    #update ho_weights
   for i in range(self.hidden n - 1):
       for j in range(self.output_n):
          change = output_errors[j] * self.hidden_datas[i]
           self.ho_weights[i][j] += learn * change
    #update ih_weights
   for i in range(self.input_n):
       for j in range(self.hidden_n - 1):
           change = hidden_errors[j] * self.input_datas[i]
         self.ih_weights[i][j] += learn * change
```

e) Train:

用于迭代测试

f) Test:

用于实现多个隐藏层的情况。每层处理完的输出结果当作下一层的输入

```
def test(self):
    cases = copy.deepcopy(self.cases)
    origin = copy.deepcopy(cases)
    expects = self.expects
    flag = self.layer_n
    while flag != 0 :
        flag -= 1
        res = self.train(cases, expects)
        #update the cases
        cases = copy.deepcopy(res)
        #print("new cases:", cases)
    print("cases:",origin)
    print("expect:", expects)
    print("result:", res)
    return res
```

6. 测试

- a) 默认迭代 10000 次, learning-rate 默认为 0.05
- b) 选取 3 个 layer, 5 个 neuro, 1000 次迭代, 激励函数为 tanh 的情况:

```
cases: [[0.5, 0.9, 0.1], [0.1, 0.7, 0.4], [0.99, 0.11, 0.3]]
expect: [[0.1, 0.291, 0.7], [0.6, 0.8, 0.1], [0.1, 0.8, 0.81]]
result: [0.10003144929185592, 0.2911425893948132, 0.6997617719916662]
result: [0.6003567397367211, 0.7993341627730737, 0.10001873857122212]
result: [0.1000067221231542, 0.8009606390580444, 0.8090355099920381]
```

根据以上数据可发现,期望数据与原始数据差别越小则迭代出的结果越精确,这一点与常识相符。同时另外两种激励函数得经过更多数量级的迭代才能达到如此精度,可能是算法有问题或者激励函数的缺陷,在此不做过多阐述。

7. 感悟

这次用 python 简单地写了一个 BPNN 算法,通过网站查找资料,见过了许许多多不同的实现方法,虽然每个人的实现细节都不太一样,比如偏置节点的权重变或者不变、后传递时是否需要加入矫正率来使结果更精确等等,但是主要的思路都大同小异,以后可能会更多地用到该思想,希望通过这次实验能让我对机器学习有更深的理解。