

# Learning causal DAGs using adaptive interventions

Davin Choo

24 Feb 2023  
Computing Research Week - Open House 2023

This talk is based on joint work with  
**Arnab Bhattacharyya, Themis Gouleakis, Kirankumar Shiragur**



# Important decisions in life...

- **What if I ate Kaya Toast instead of Roti Prata for breakfast?**  
Will I feel more satisfied?



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# Important decisions in life...

- **What if** I ate Kaya Toast instead of Roti Prata for breakfast? Will I feel more satisfied?



- **What if** I exercised more? Will I become fitter?
- **What if** I went to University X instead of NUS? Will I be more successful?
- ...

# Important decisions in life...

- **What if** I ate Kaya Toast instead of Roti Prata for breakfast? Will I feel more satisfied?



- **What if** I exercised more? Will I become fitter?
- **What if** I went to University X instead of NUS? Will I be more successful? **Not necessarily. We have great people here 😊**
- ...



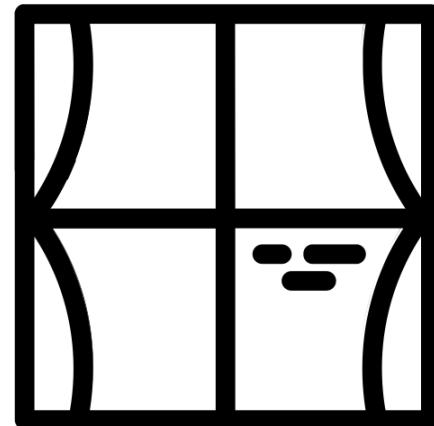
David Hume  
Philosopher

One of his philosophical ideas:

- To draw any causal conclusions from past experiences, one has to assume that the future resembles the past
- This assumption cannot be justified



Yesterday



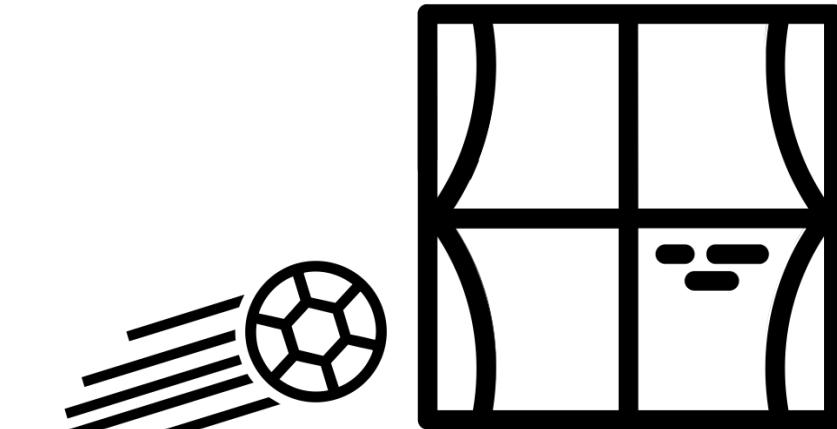
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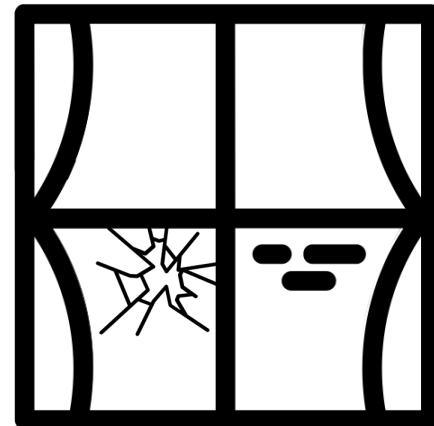
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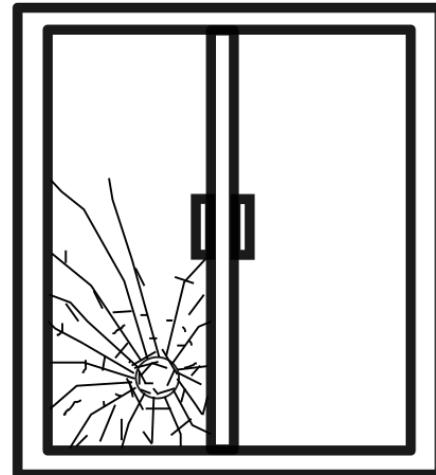
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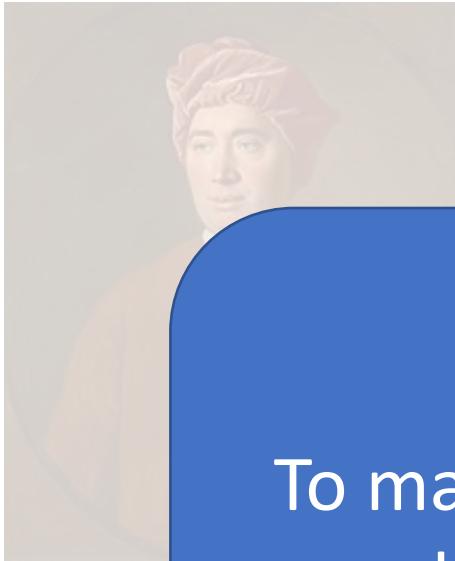
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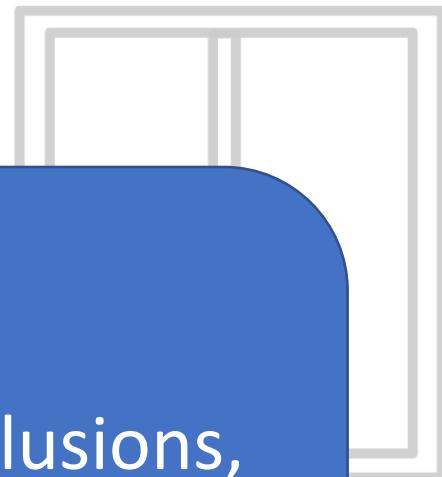
Did the ball smash the  
window?

OR

Did the smashed window  
summon the ball?



Today



To make useful causal conclusions,  
make useful/reasonable model  
assumptions or conduct experiments

One of

- To draw causal conclusions from past experiences, one has to assume that the future resembles the past
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NEWS | 13 October 2021

# Nobel-winning ‘natural experiments’ approach made economics more robust

**Joshua Angrist, Guido Imbens and David Card share the prize for finding a way to identify cause and effect in social science.**

Philip Ball 



Left to Right: Joshua Angrist, Guido Imbens and David Card share the [2021 Nobel prize](#) in economic sciences for work that has helped economics research undergo a ‘credibility revolution’. Credit: MIT/EPA-EFE/Shutterstock, Andrew Brodhead/Stanford News Service/EPA-EFE/Shutterstock, Noah Berger/AP/Shutterstock

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## JUDEA PEARL

United States – 2011

### CITATION

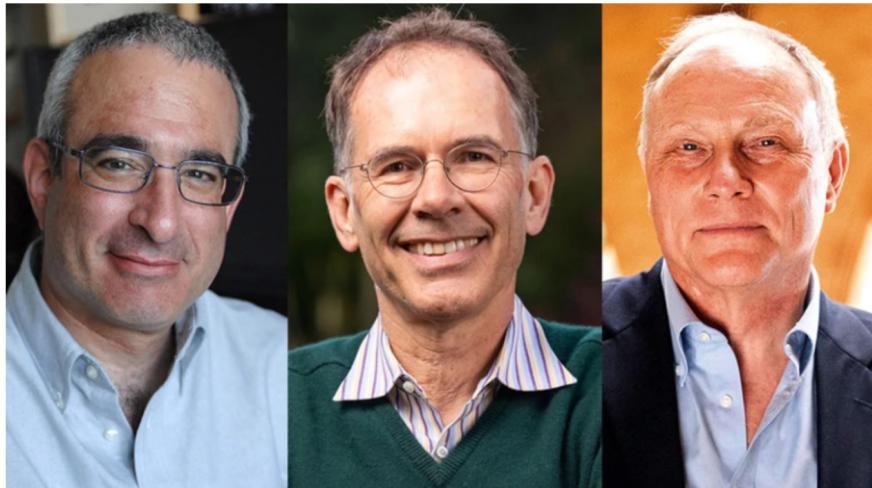
(2011 Turing award)

For fundamental contributions to artificial intelligence through the development of a calculus for probabilistic and causal reasoning.

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For fundamental contributions to artificial intelligence through the development of a calculus for probabilistic and causal reasoning.

- Bayesian networks
  - Represent causal relationships as a directed acyclic graph (DAG)
- Do-calculus
  - A formalization of interventions
  - “What happens if we perform experiments on the causal graph?”

# Modelling causal relations

**“We may regard the present state of the universe as the effect of its past and the cause of its future...”** – Pierre Simon Laplace,  
*A Philosophical Essay on Probabilities*, 1814



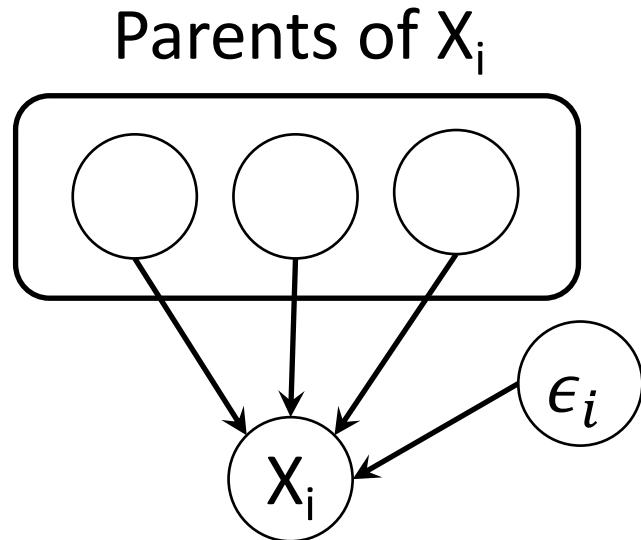
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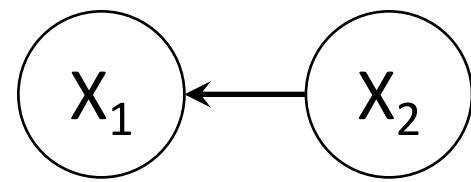
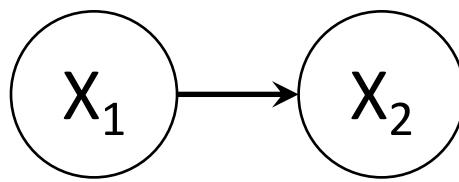
$$X_i = f_i(pa_i, \epsilon_i)$$

The value of each variable  $X_i$  is function  $f_i$  of the values taken by its parents  $pa_i$  and some noise  $\epsilon_i$



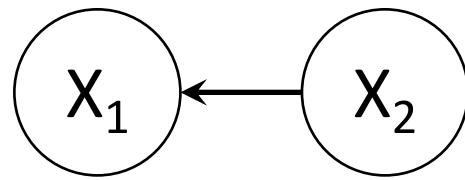
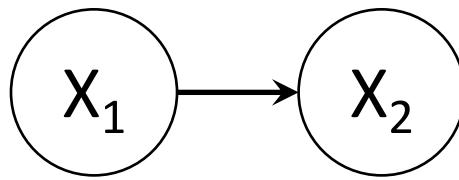
# Which model generated this data?

$X_1$	-0.27	0.29	0.37	-0.09	0.34	0.33	0.30	-1.34	0.68
$X_2$	-0.10	1.65	0.47	1.92	2.04	1.67	0.11	-3.58	1.97



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- $X_1 = \epsilon_1$
- $X_2 = a \cdot X_1 + \epsilon_2$
- $X_1 = b \cdot X_2 + \epsilon_3$
- $X_2 = \epsilon_4$

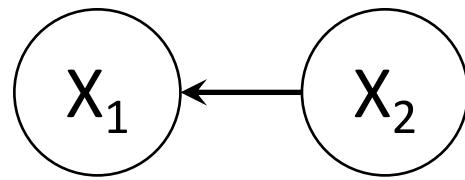
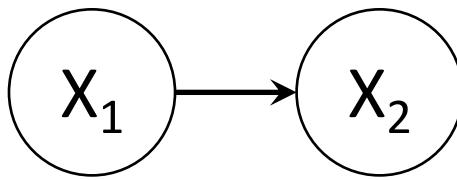
Simple linear relationship between variables

a and b are (hidden) positive constants

$\epsilon$ 's are independent Gaussian terms with mean 0

# Two equivalent causal models

$X_1$	-0.27	0.29	0.37	-0.09	0.34	0.33	0.30	-1.34	0.68
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- $X_1 = \epsilon_1 \sim N(0, 1)$
- $X_2 = X_1 + \epsilon_2 \sim N(0, 2)$
- $\epsilon_1 \sim N(0, 1)$
- $\epsilon_2 \sim N(0, 1)$
- $X_1 = \frac{1}{2} \cdot X_2 + \epsilon_3 \sim N(0, 1)$
- $X_2 = \epsilon_4 \sim N(0, 2)$
- $\epsilon_3 \sim N\left(0, \frac{1}{2}\right)$
- $\epsilon_4 \sim N(0, 2)$

# Two equivalent causal models

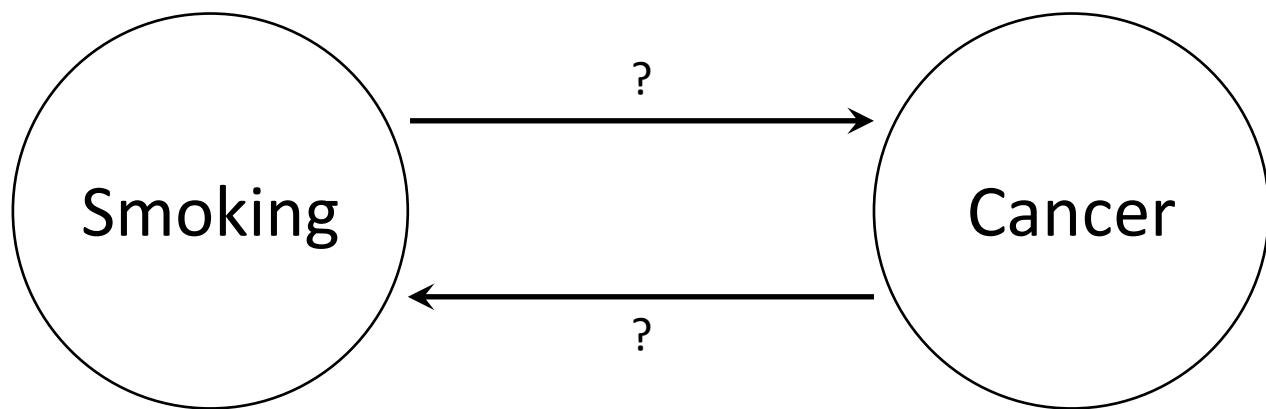
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So what?  
Who cares?

- $X_1 = \epsilon_1 \sim N(0, 1)$
- $X_2 = X_1 + \epsilon_2 \sim N(0, 2)$
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# Smoking

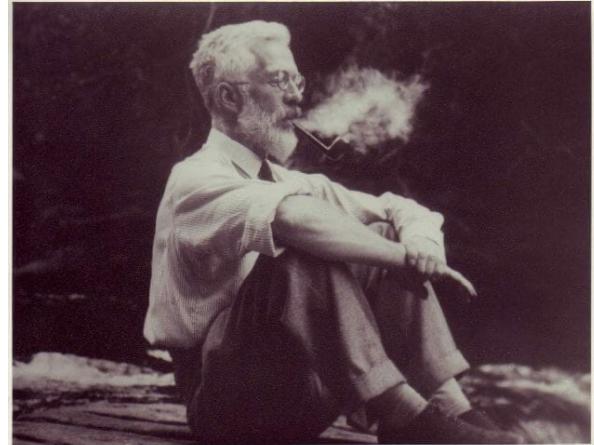
<b>Smoking</b>	Yes	Yes	Yes	No	No	No	...
<b>Cancer</b>	No	Yes	Yes	No	No	Yes	...



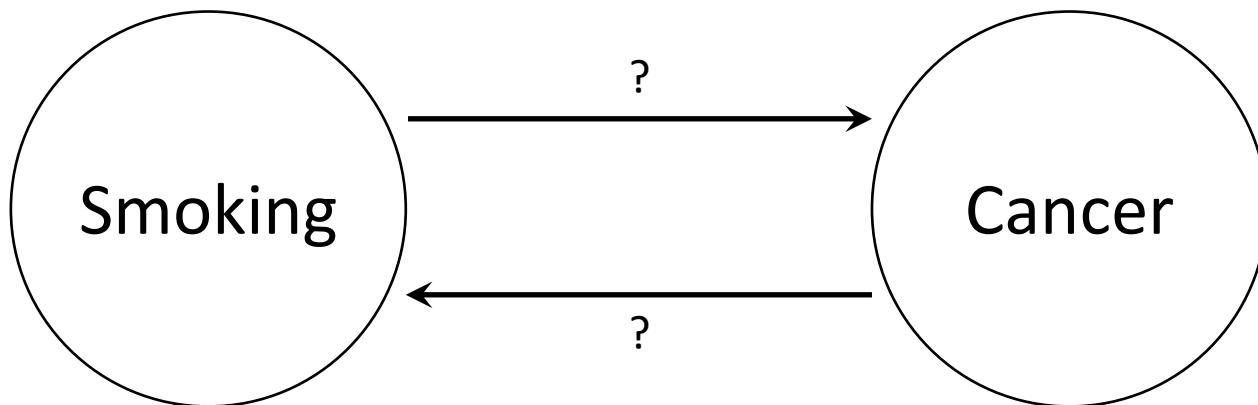
# Smoking

Fisher's letter to Nature, 1958:

"The curious associations with lung cancer found in relation to smoking habits do not, in the minds of some of us, lend themselves easily to the simple conclusion that the products of combustion reaching the surface of the bronchus induce, though after a long interval, the development of a cancer... **Such results suggest that an error has been made, of an old kind, in arguing from correlation to causation...**"



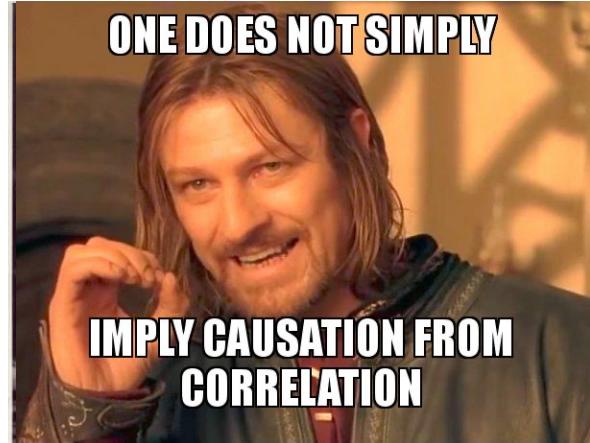
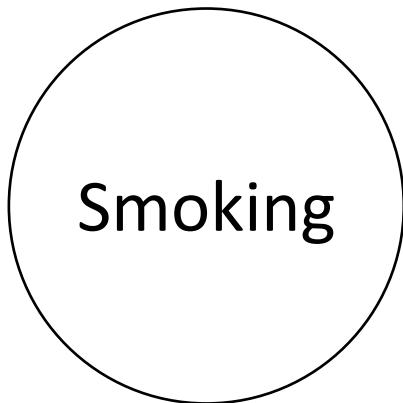
Ronald Fisher



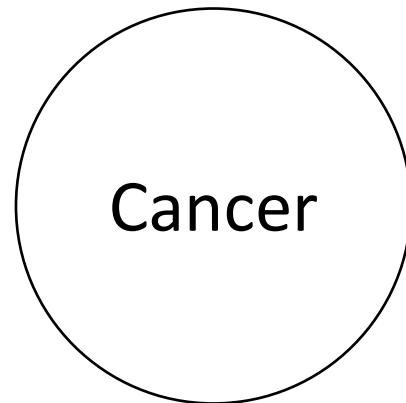
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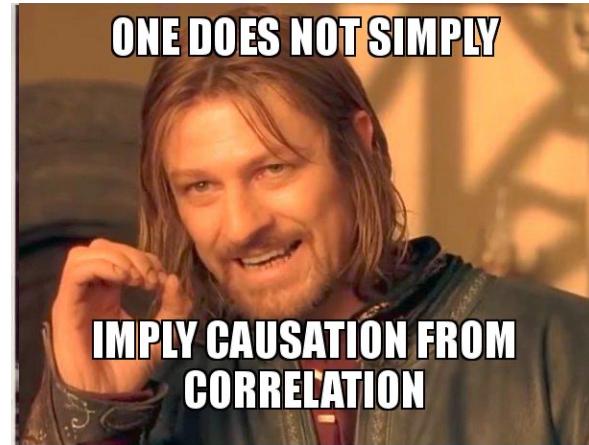
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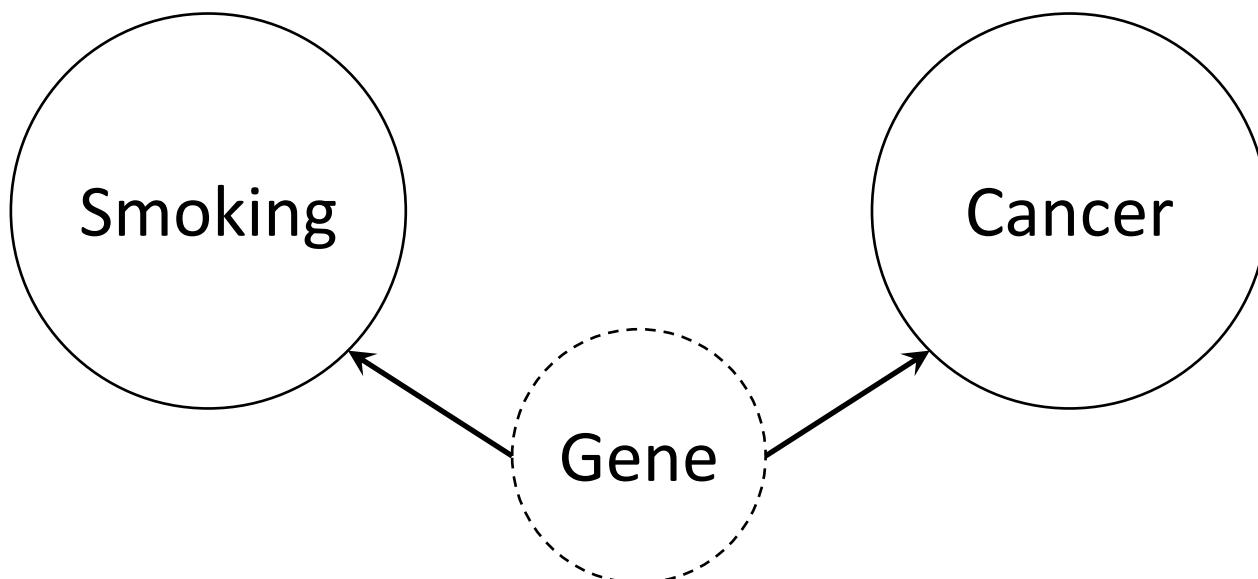
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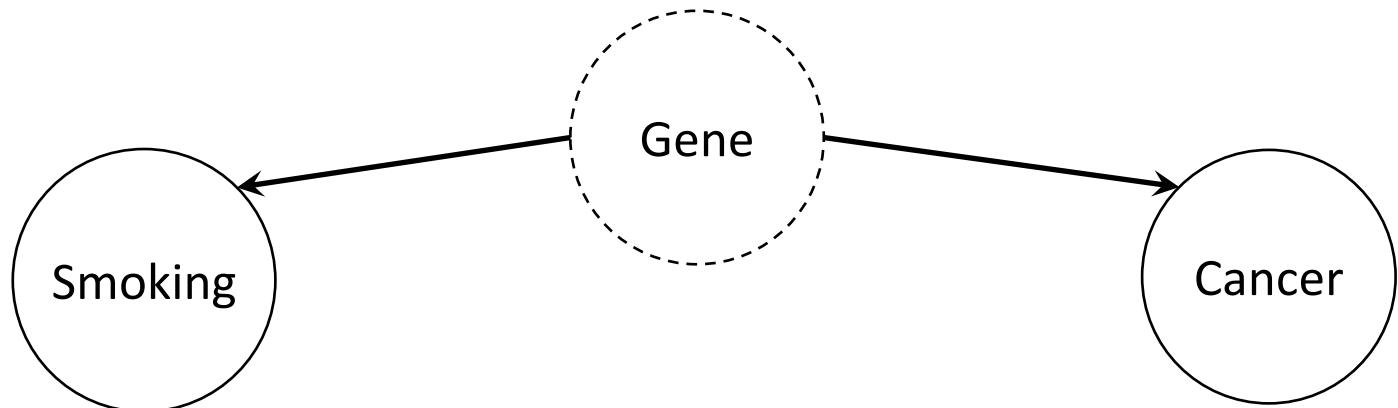
"... Such results suggest that an error has been made, of an old kind, in arguing from correlation to causation, and that the possibility should be explored that the different smoking classes, non-smokers, cigarette smokers, cigar smokers, pipe smokers, etc., have adopted their habits partly by reason of their personal temperaments and dispositions, and are not lightly to be assumed to be equivalent in their **genotypic composition...**"



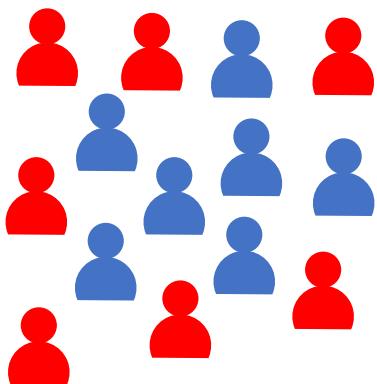
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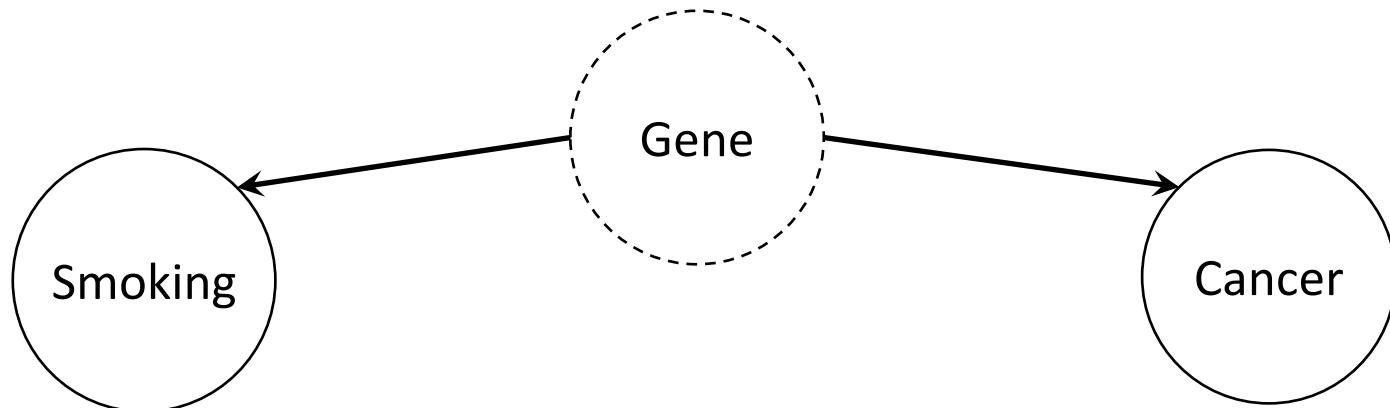


Maybe there's an unmeasured confounder?

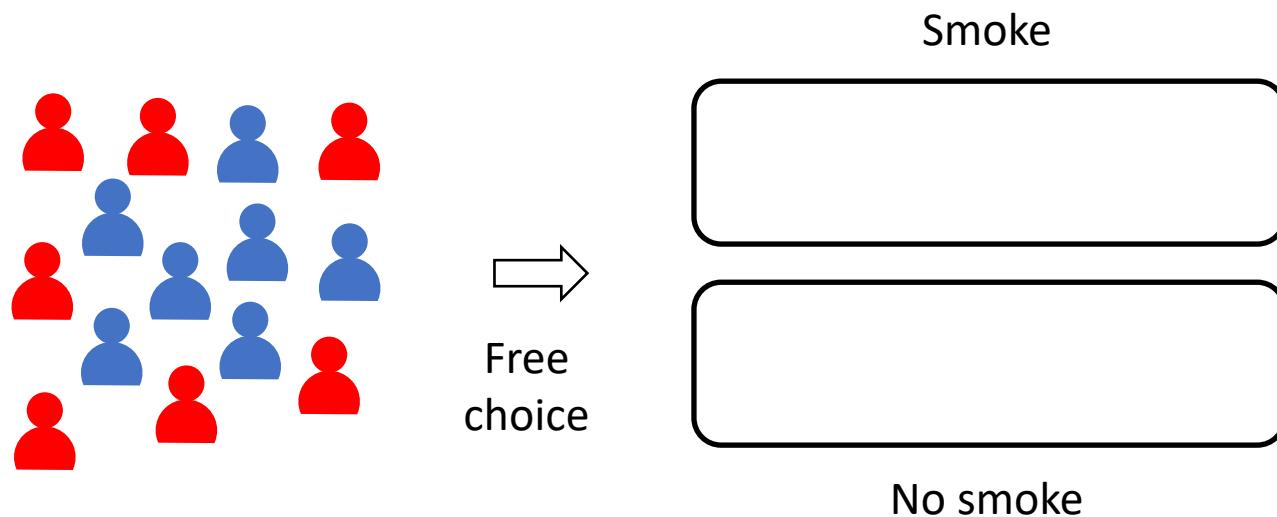


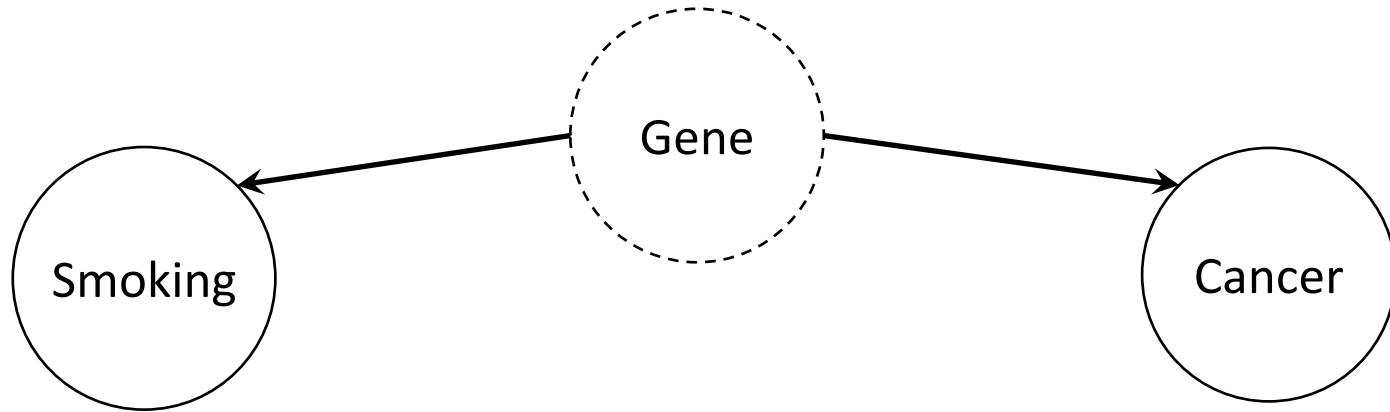
Hypothesis: There are two types of people in the world



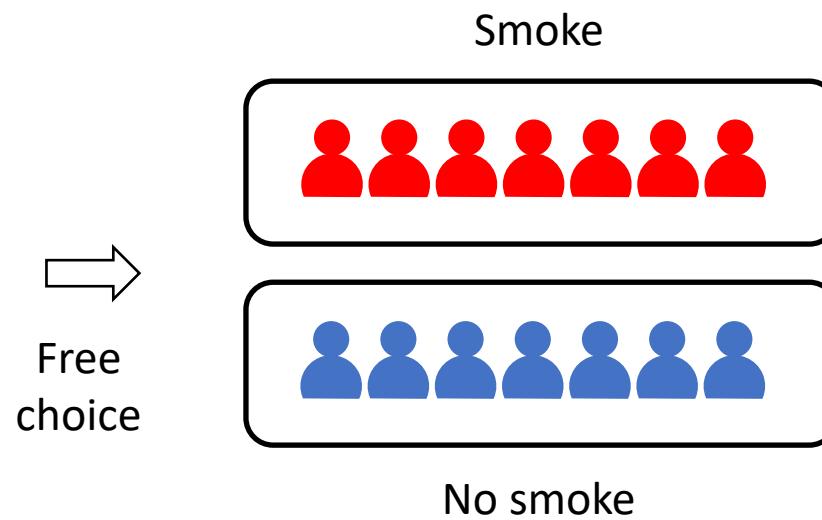


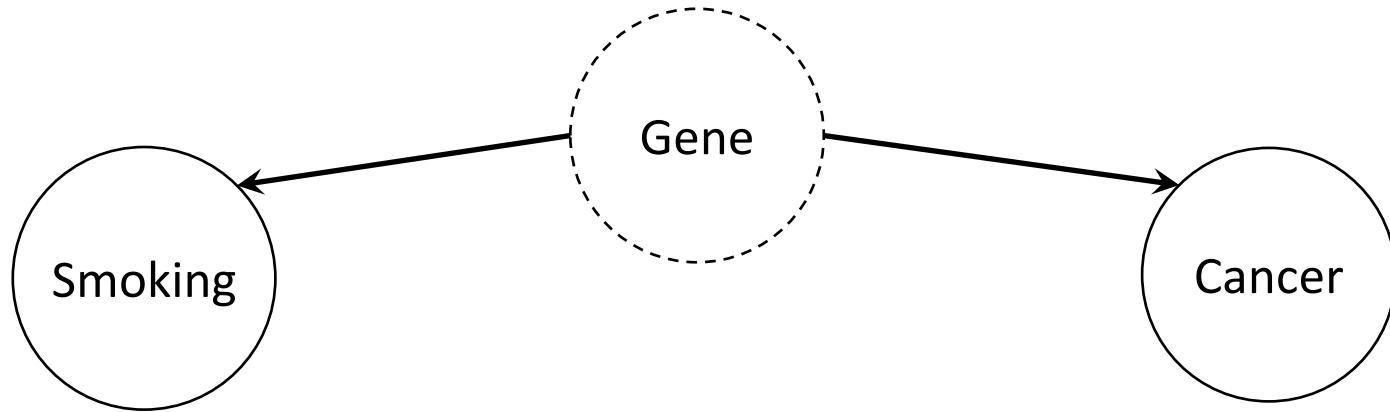
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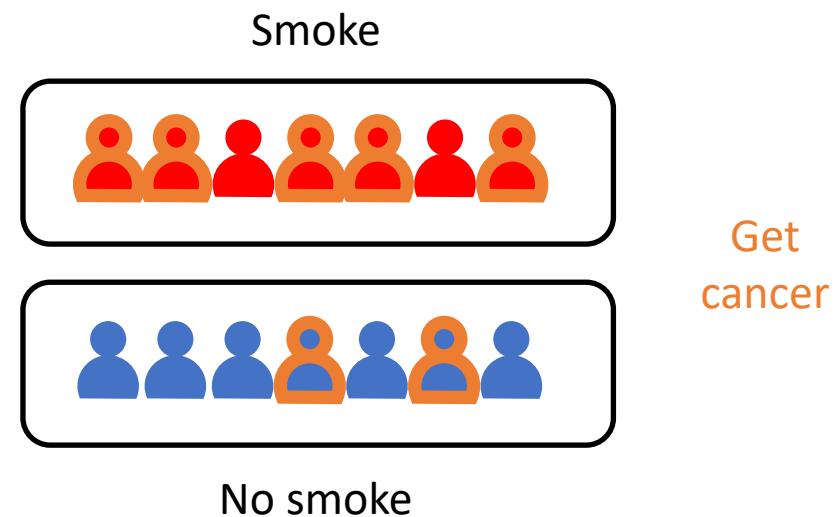


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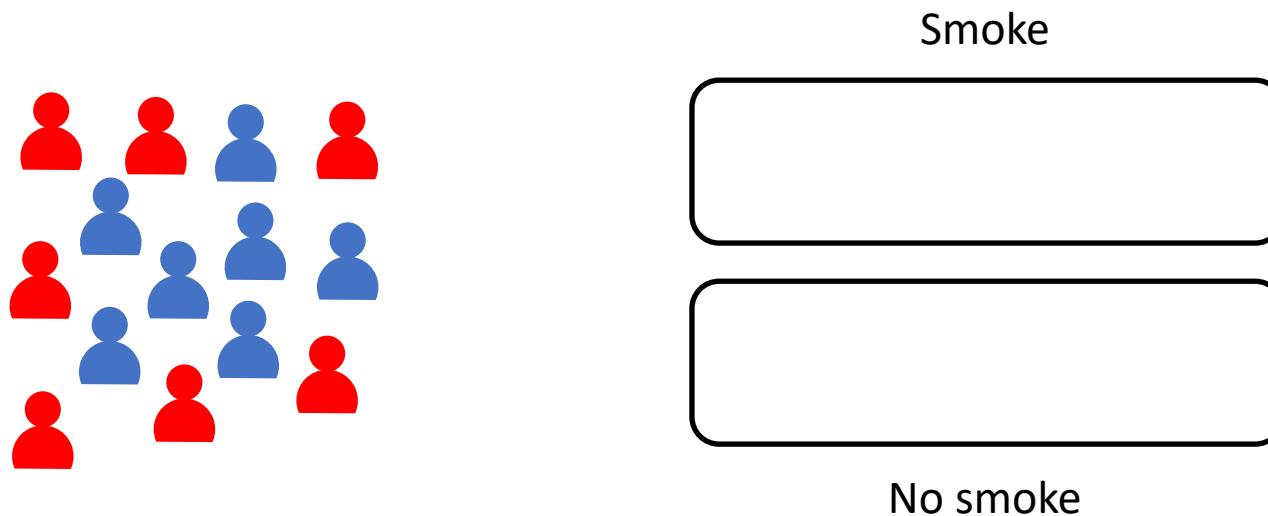


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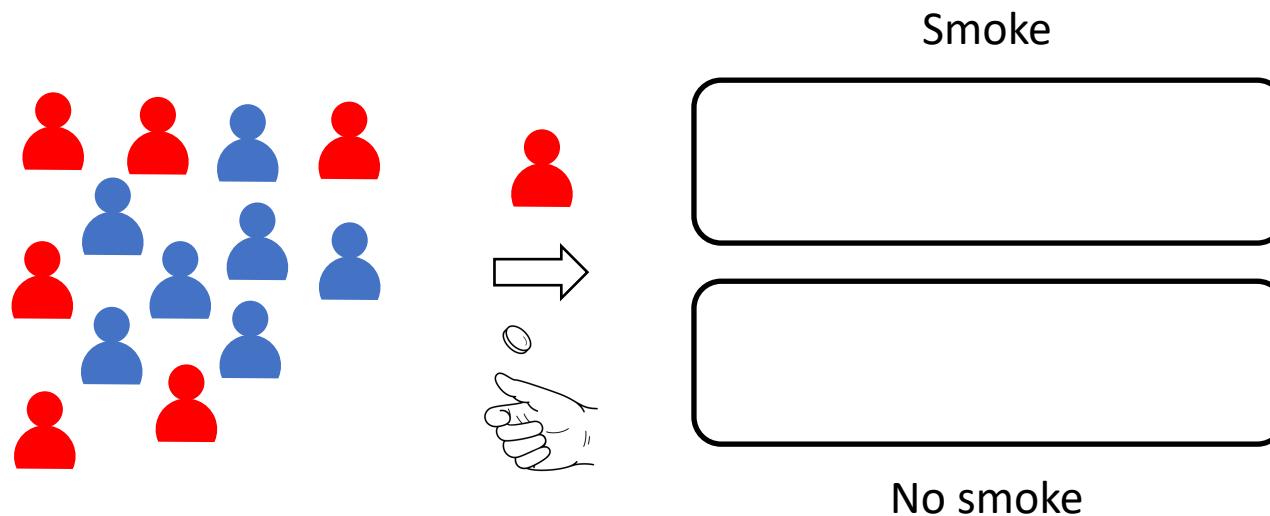
# Randomized controlled trials

- Gold standard in scientific exploration
- RCTs  $\equiv$  Interventions in causality



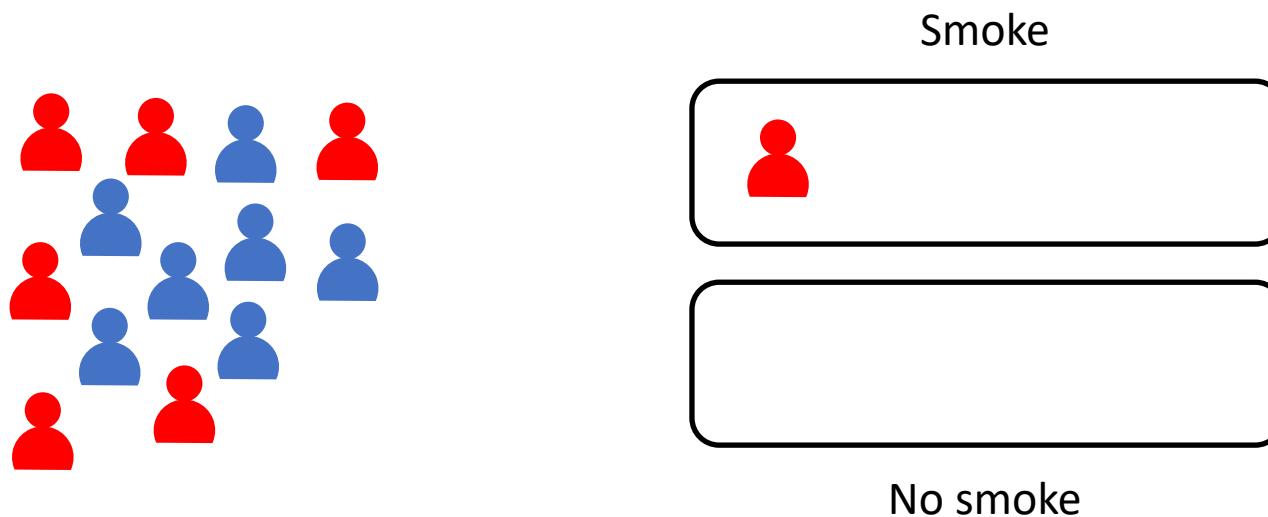
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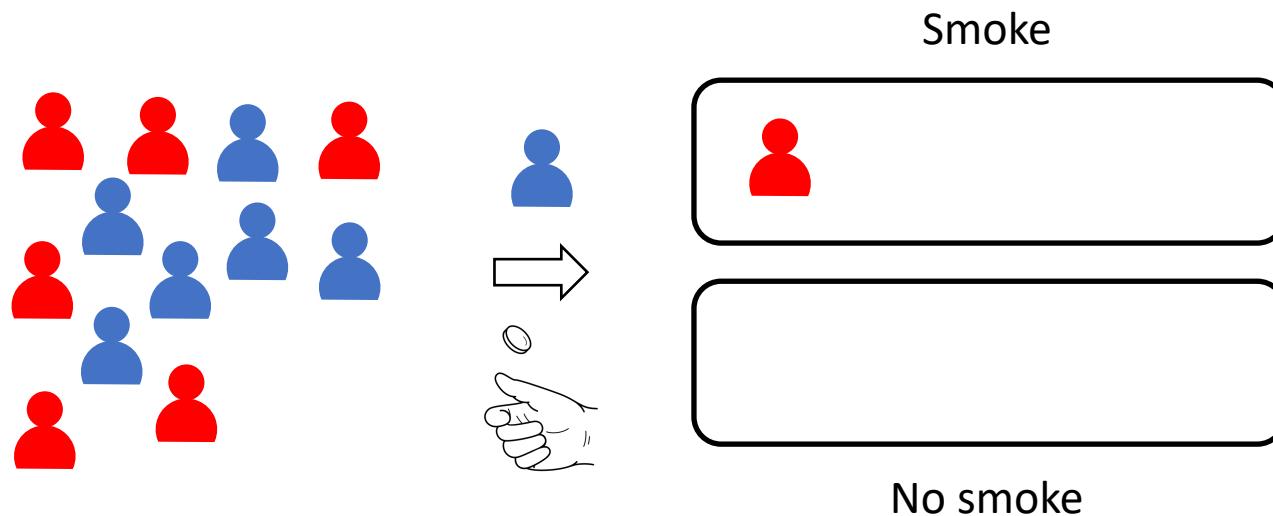
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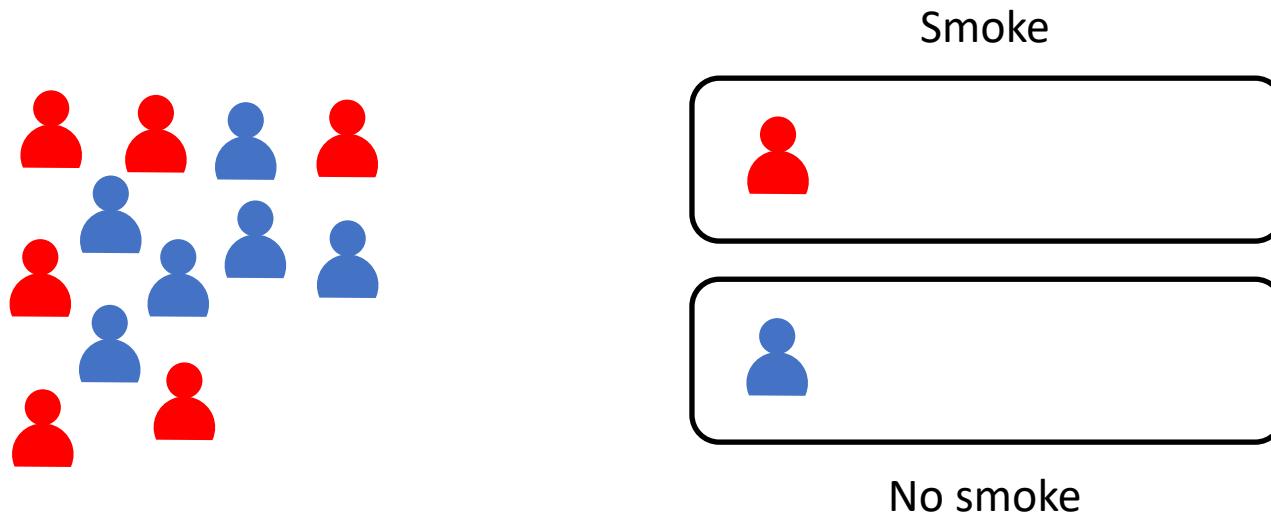
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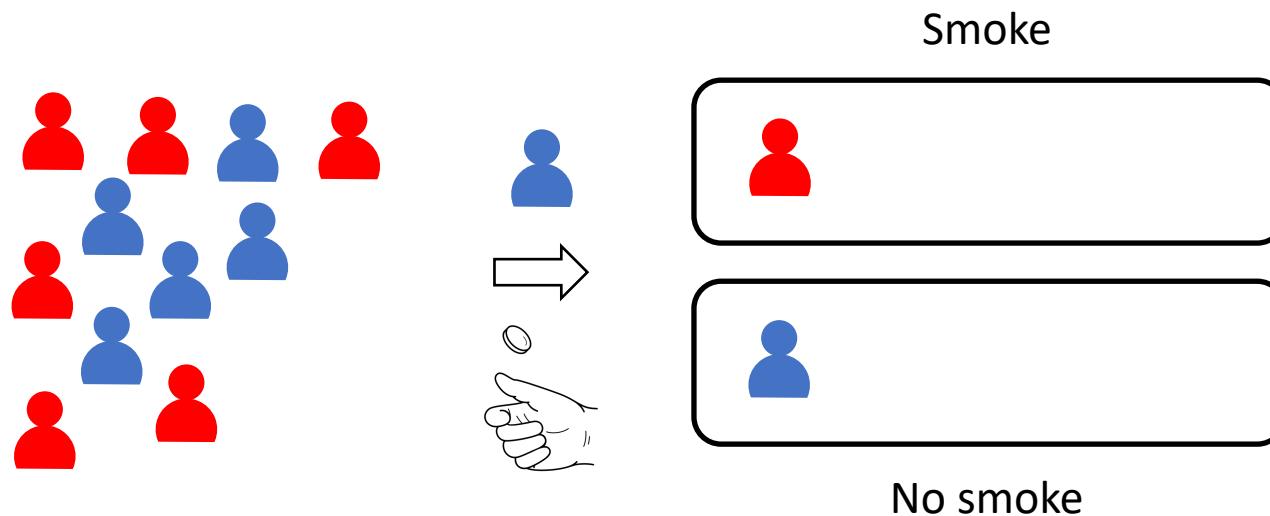
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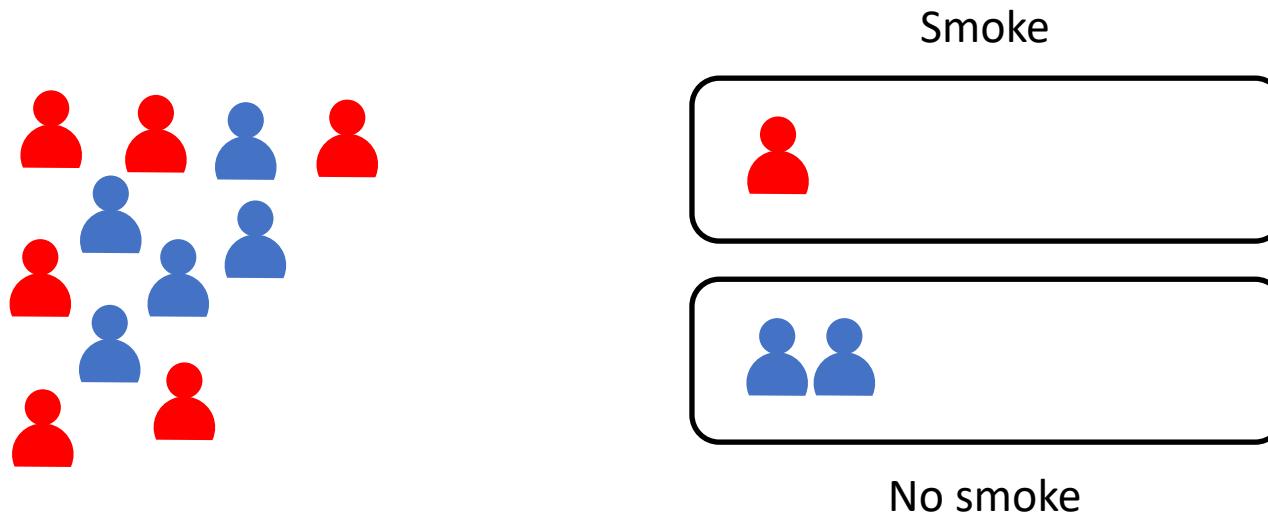
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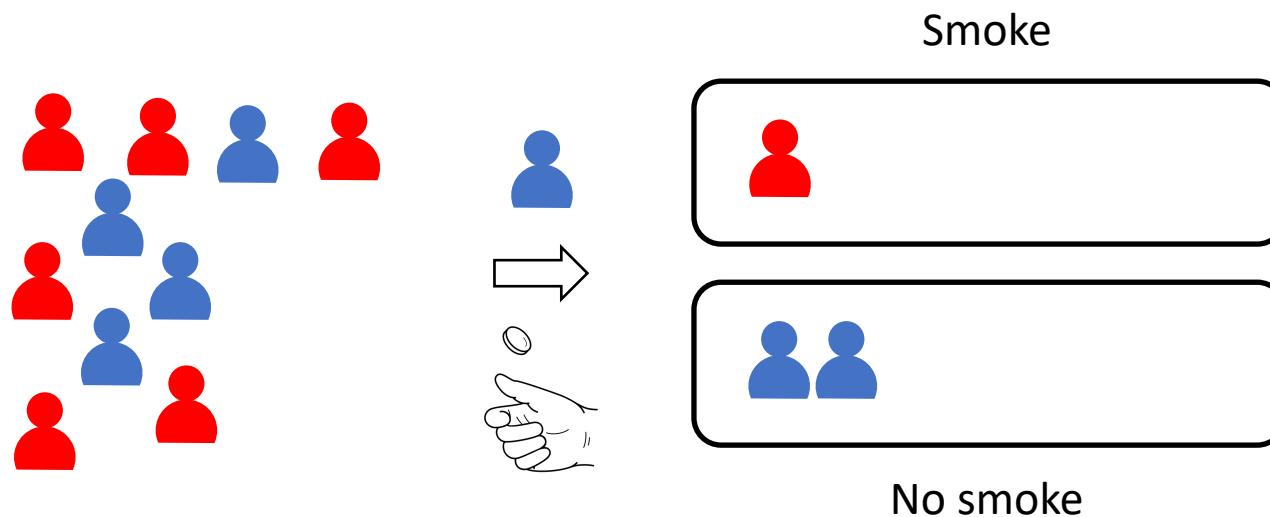
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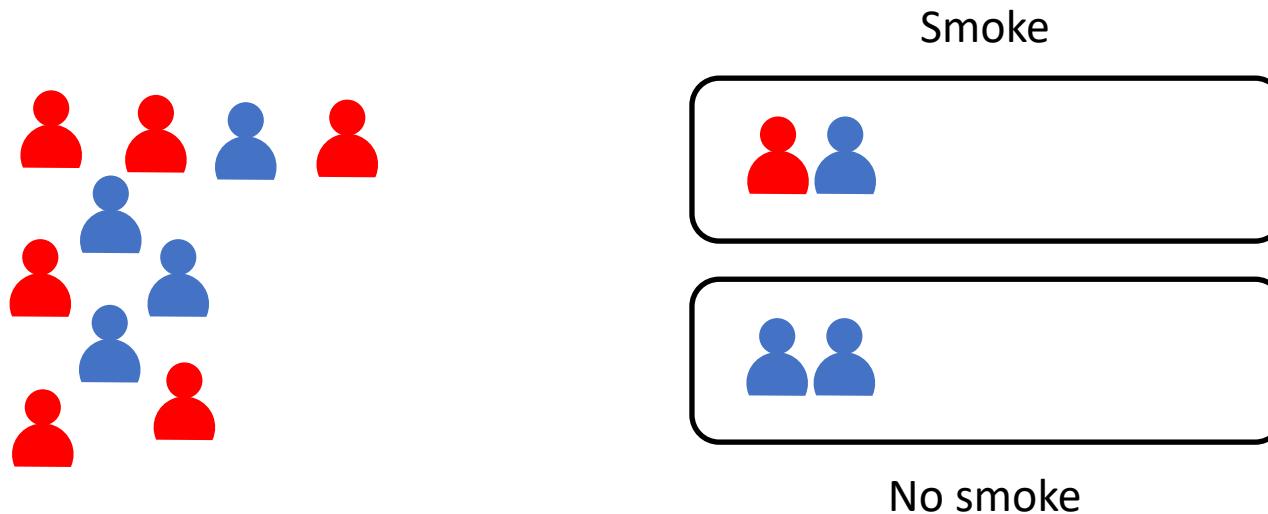
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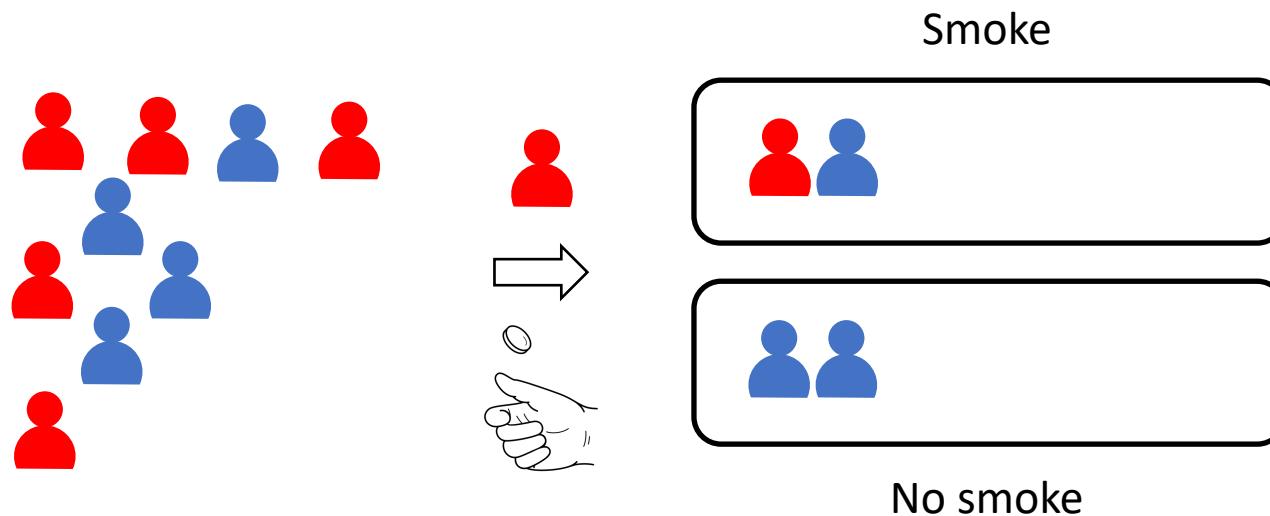
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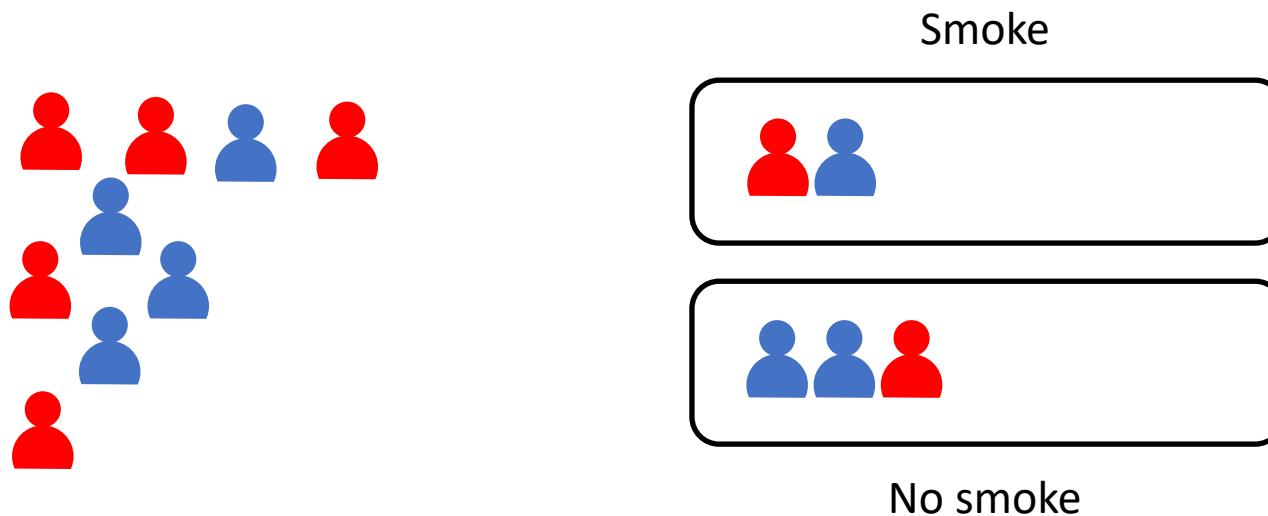
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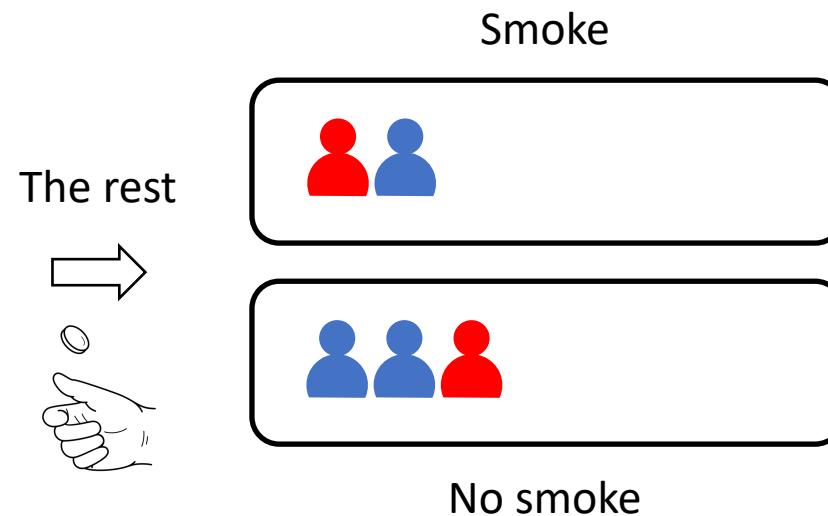
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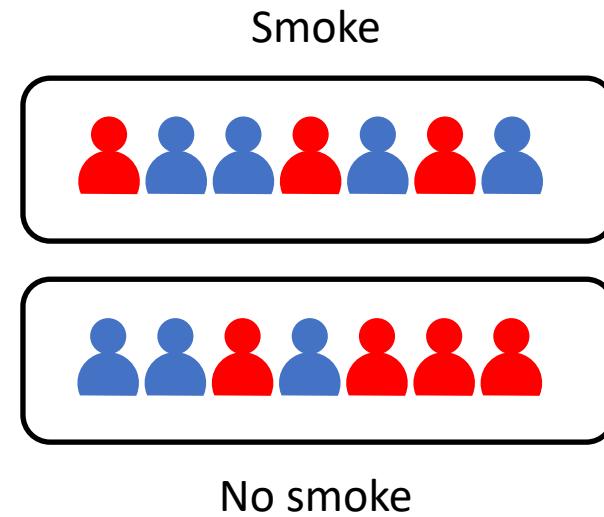
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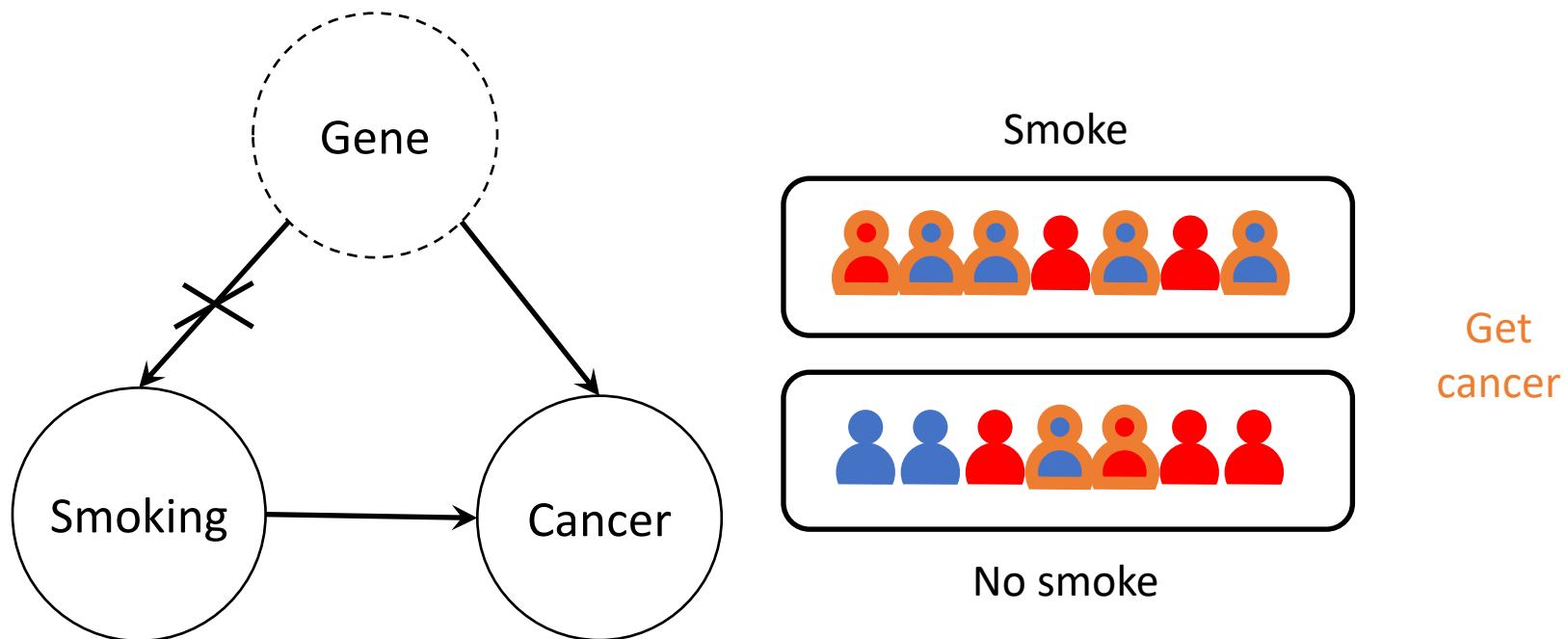
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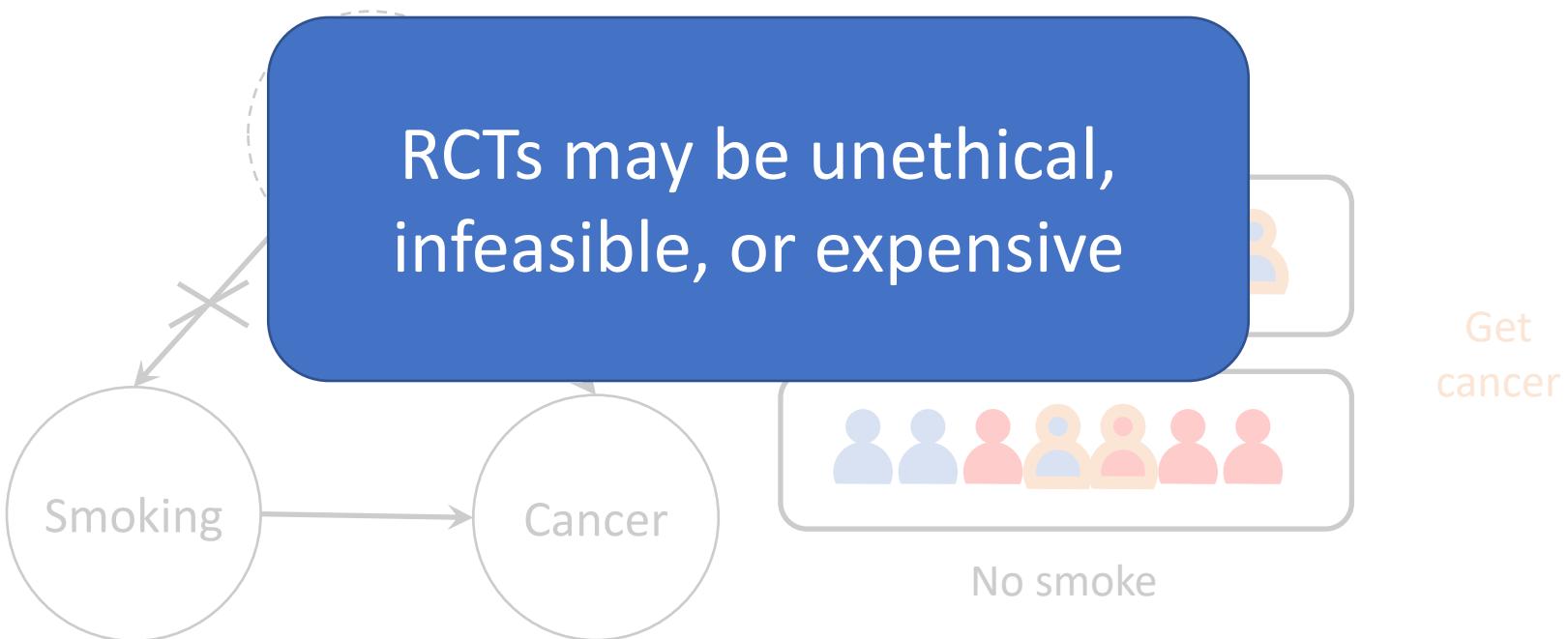
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RCT removed causal link from “gene” to “smoking”  
If smoking and cancer still highly correlated, then smoking causes cancer

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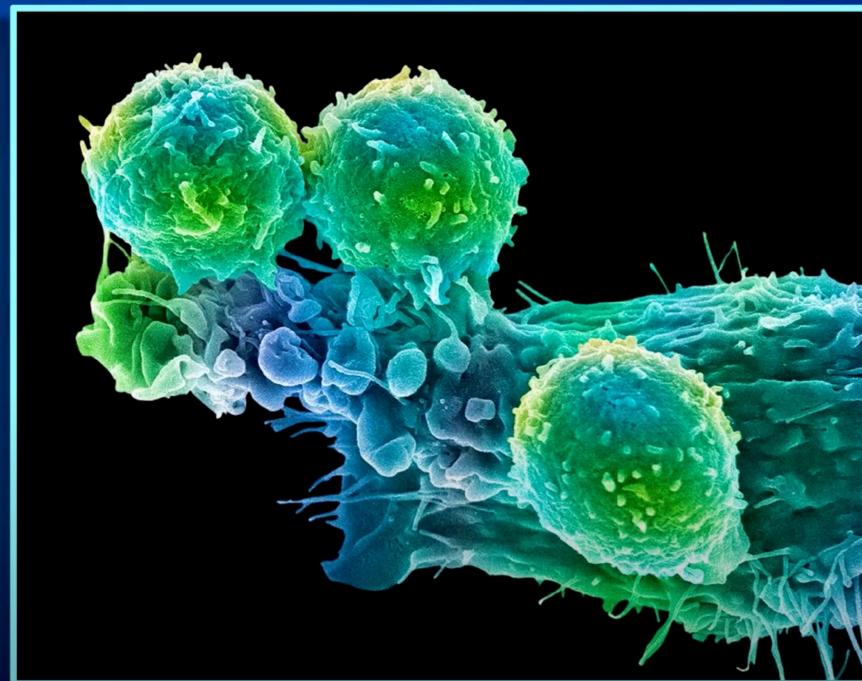
# CANCER IMMUNOTHERAPY DATA SCIENCE GRAND CHALLENGE

2023

≡ Lecture 1, Biology: Section B

Press **esc** to exit full screen

## T cells attacking a cancer cell



Janeway Immunology  
Image by Steve  
Gschmeissner/Science Photo Library

# CANCER IMMUNOTHERAPY DATA SCIENCE GRAND CHALLENGE

2023

Lecture 1, Biology: Section C

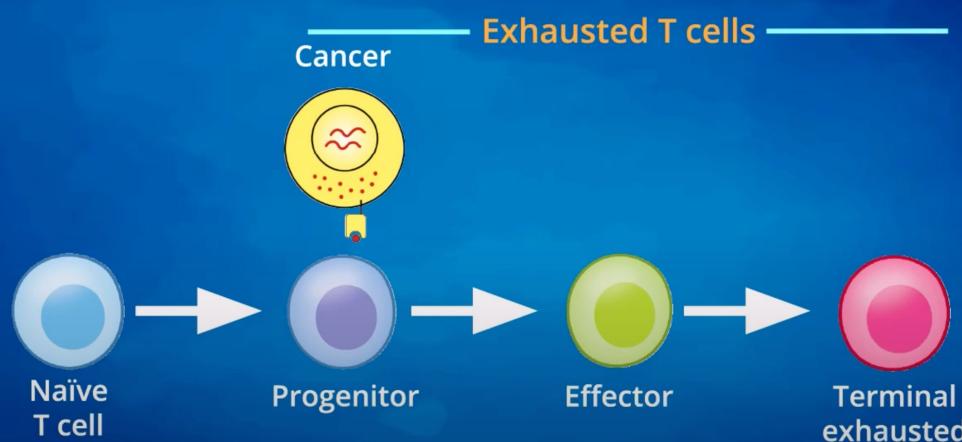
## Cancer evades T cell killing by driving T cells to exhaustion.



Site:

Blood

Tumor



T cell states are encoded by gene expression programs, which change upon encounter with cancer cells.

# CANCER IMMUNOTHERAPY DATA SCIENCE GRAND CHALLENGE

2023

≡ Lecture 1, Biology: Section D

Press **esc** to exit full screen

## Cancer immunotherapies only work for some people and for some cancer types



- Cancer cells do not act through PD-1 or CTLA-4.
- Cancer cells directly inhibit T cells through a new signaling pathway.
- Cancer cells indirectly inhibit T cells by creating a suppressive immune environment.
- CAR T cell exhaustion.
- And more...

- clinicaltrials.gov: 2500 studies found for *Immune checkpoint inhibitor* and 1000 studies found for CAR T cell

### Challenge opportunity

What other genetic changes in T cells would make them better cancer killers?

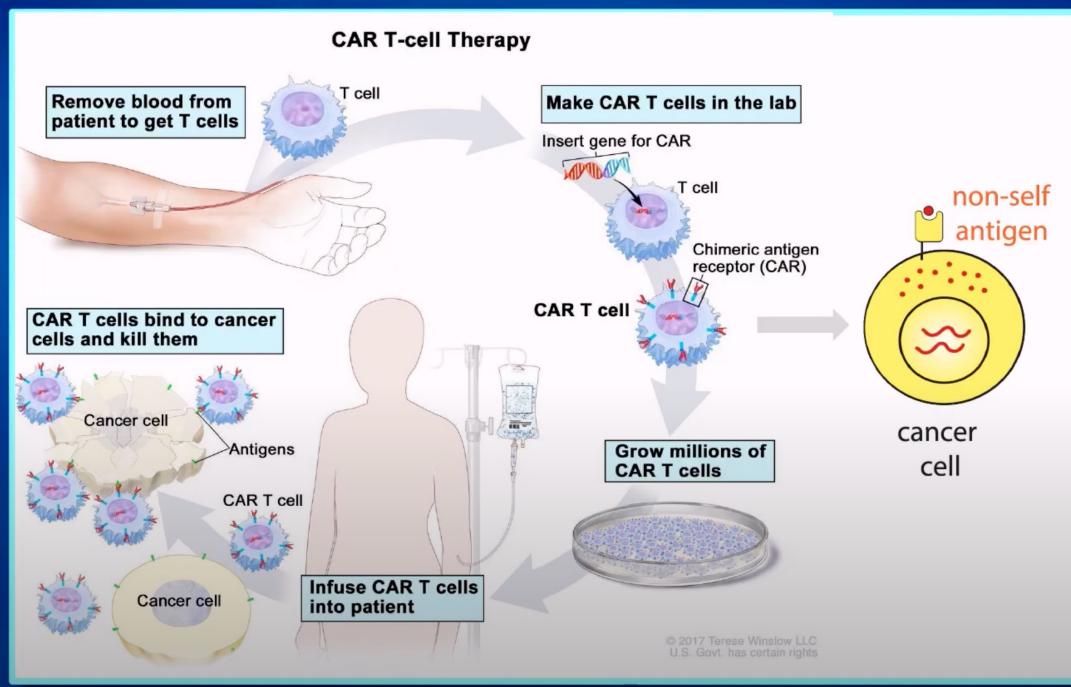
# CANCER IMMUNOTHERAPY DATA SCIENCE GRAND CHALLENGE

2023

Lecture 1, Biology: Section D

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## Cancer Immunotherapy: CAR T-cell therapy



Treating diffuse large  
B-cell lymphoma with  
CAR T cells.

- ~50% of treated patients have durable complete response.

cancer.gov

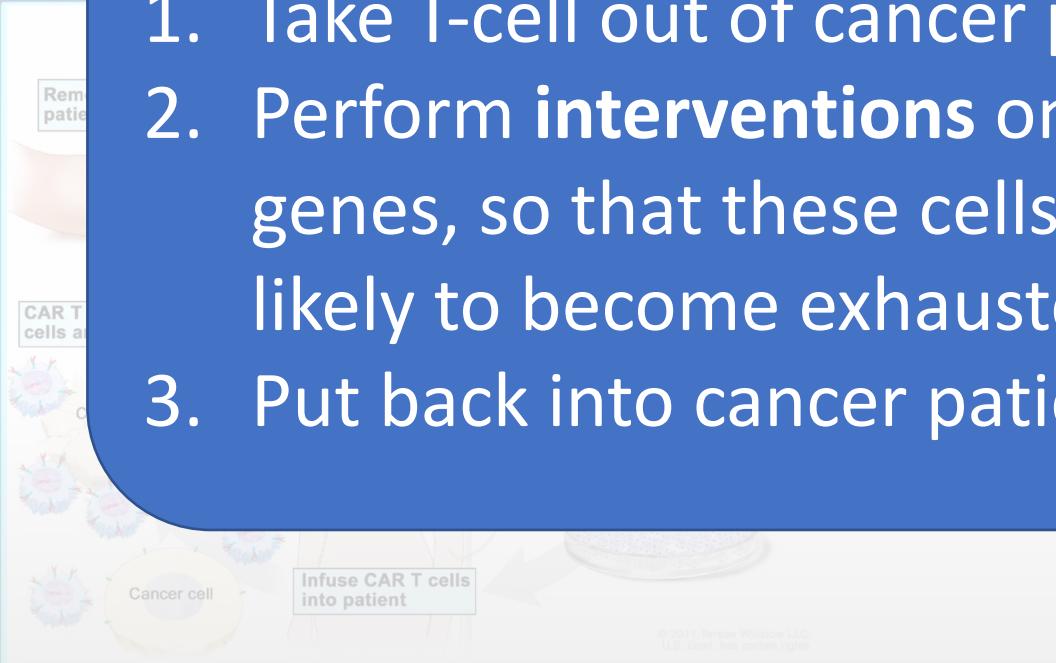
June, C. H. et al *New England*

*Journal of Medicine* (2018)



Basically,

1. Take T-cell out of cancer patient
2. Perform **interventions** on T-cell genes, so that these cells are less likely to become exhausted
3. Put back into cancer patient



Lecture 1

Cancer

Removal patient

CAR T cells are modified

Infuse CAR T cells into patient

Cancer cell

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cancer.gov

June, C. H. et al *New England Journal of Medicine* (2018)

5:24 / 8:58

NEWS | 07 October 2020



# Pioneers of revolutionary CRISPR gene editing win chemistry Nobel

Emmanuelle Charpentier and Jennifer Doudna share the award for developing the precise genome-editing technology.

Heidi Ledford & Ewen Callaway



Ba

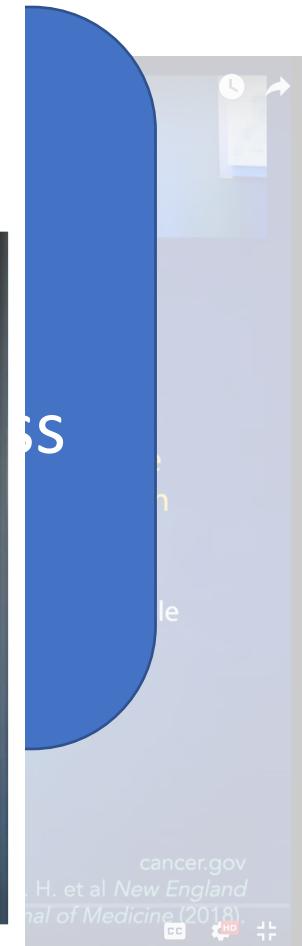
1.

2.

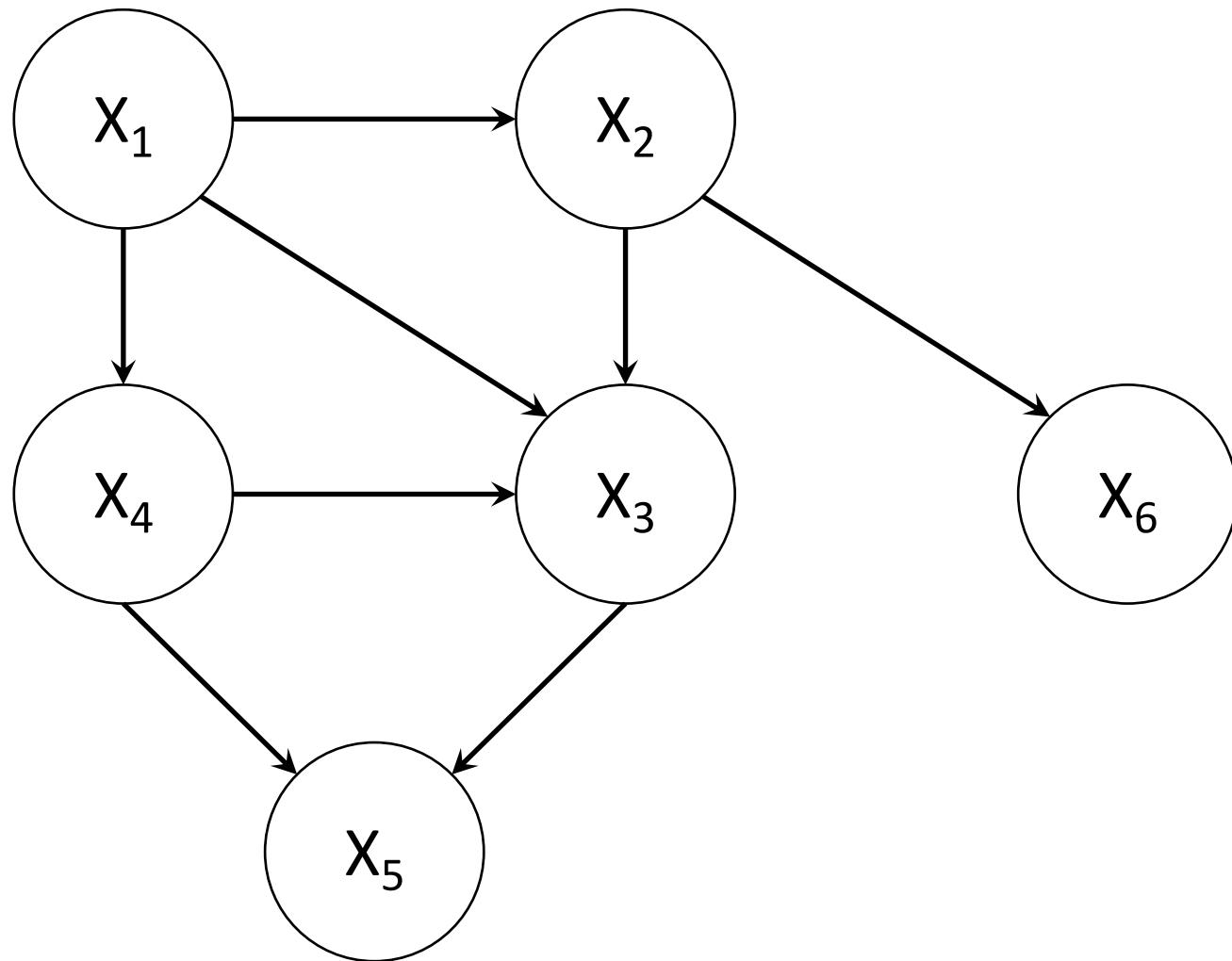
3.



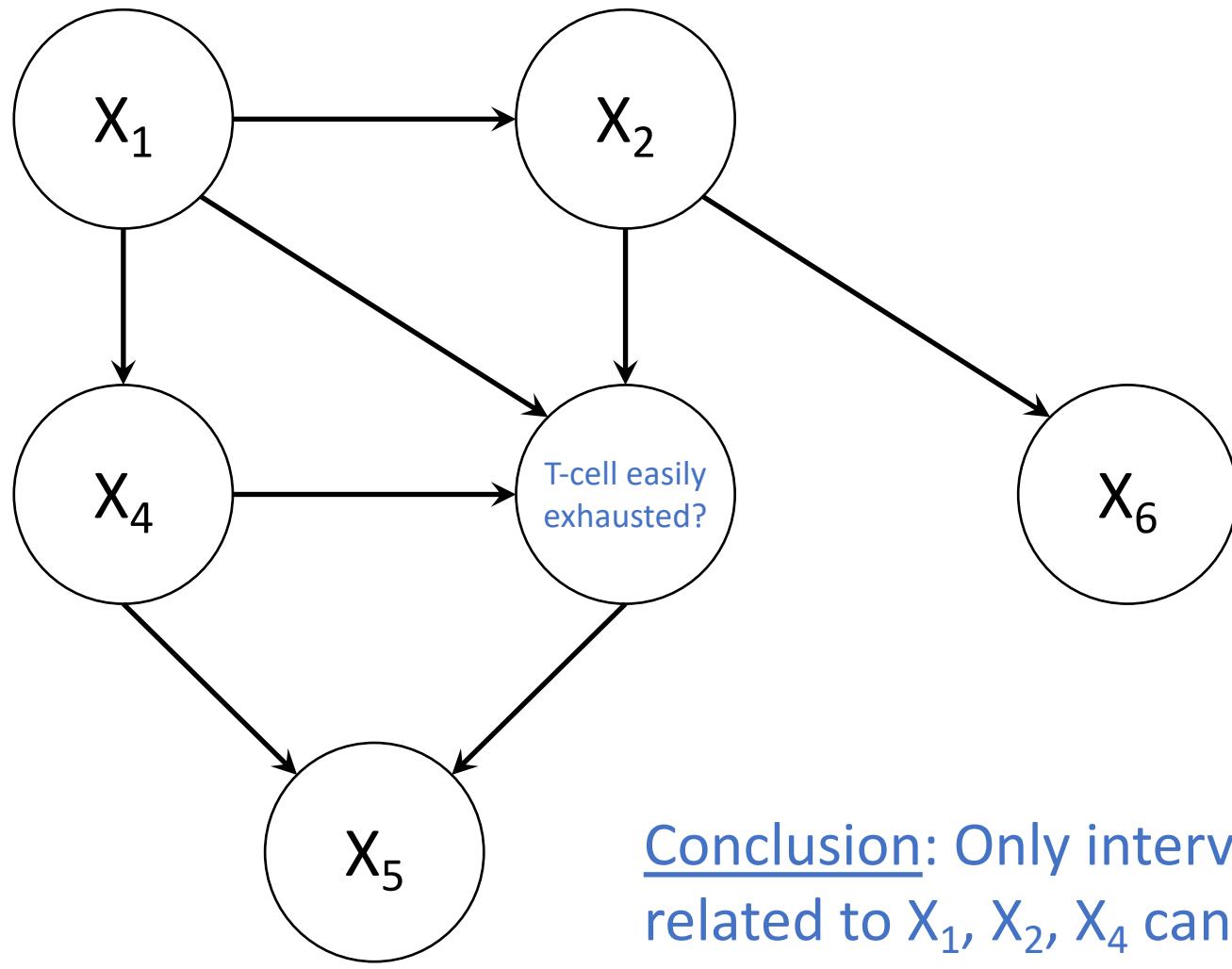
Jennifer Doudna and Emmanuelle Charpentier share the 2020 Nobel chemistry prize for their discovery of a game-changing gene-editing technique. Credit: Alexander Heinel/Picture Alliance/DPA



# Why structure learning

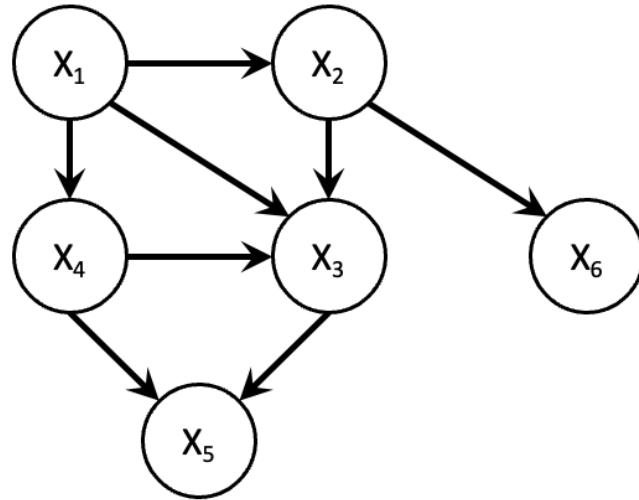


# Why structure learning



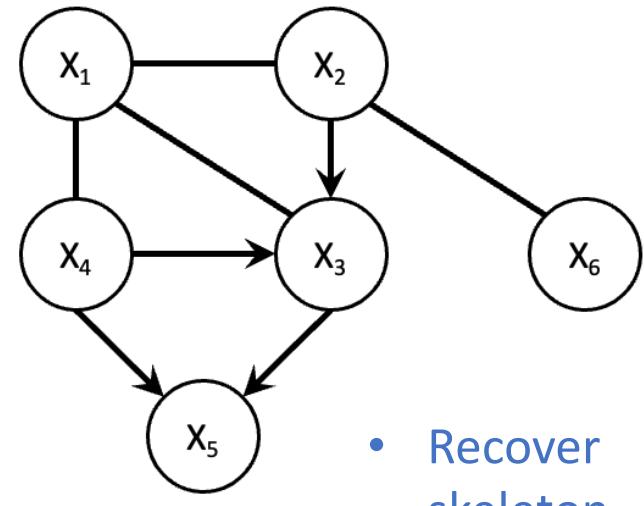
# Structure learning (simplified)

This represents an equivalence class of graphs



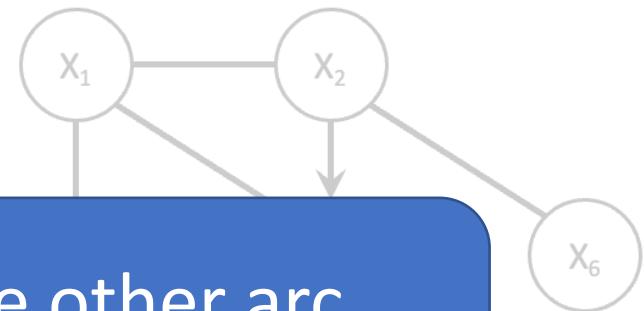
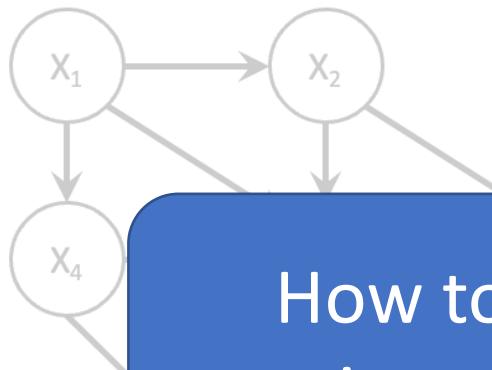
Get samples

	X <sub>1</sub>	X <sub>2</sub>	X <sub>3</sub>	X <sub>4</sub>	X <sub>5</sub>	X <sub>6</sub>
Sample 1	0.22	0.04	0.84	0.48	0.98	0.82
Sample 2	0.87	0.17	0.61	0.67	0.67	0.23
Sample 3	0.55	0.54	0.67	0.86	0.93	0.23
...	...	...	...	...	...	...
Sample M	0.12	0.95	0.79	0.47	0.05	0.92



- Recover skeleton
- Orient *some* edges

# Structure learning (simplified)



How to recover all the other arc orientations? Use interventions!

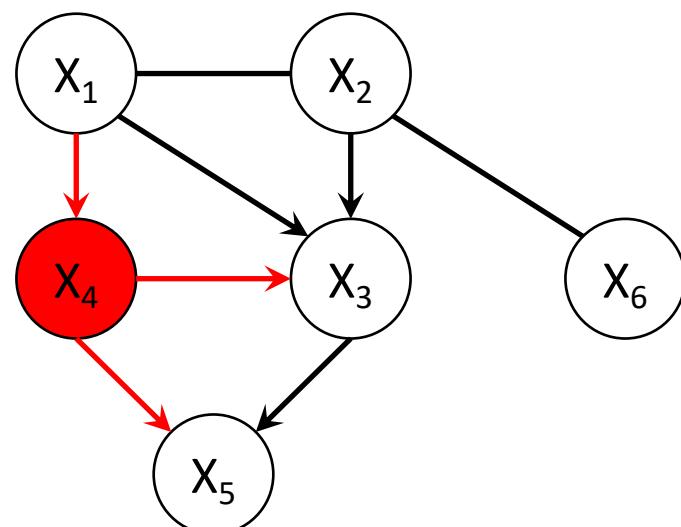
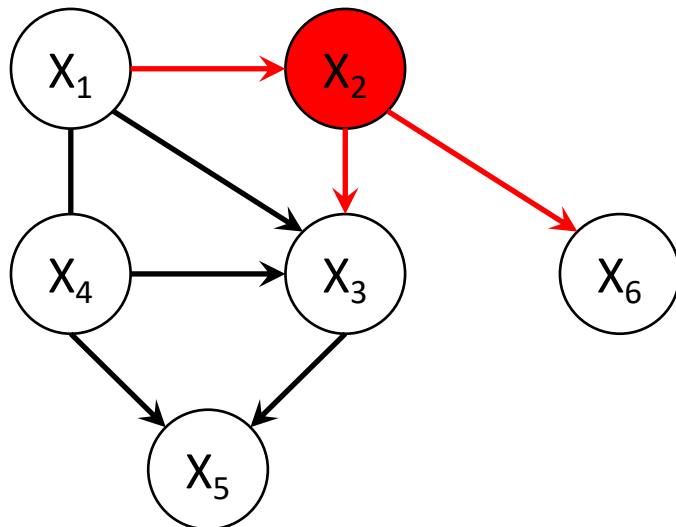
Get samples

	$X_1$	$X_2$	$X_3$	$X_4$	$X_5$	$X_6$
Sample 1	0.22	0.04	0.84	0.48	0.98	0.82
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...	...	...	...	...	...	...
Sample M	0.12	0.95	0.79	0.47	0.05	0.92

- cover skeleton
- Orient some edges

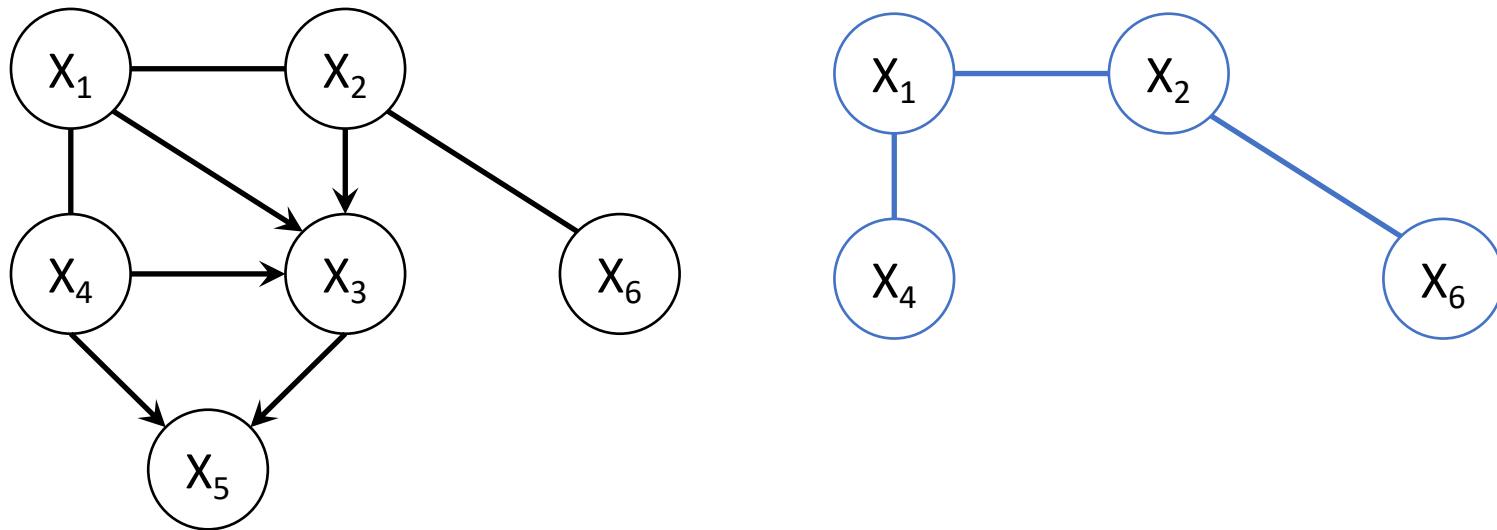
# What do interventions give us?

- When we intervene on a vertex, we recover the orientations of edges incident to the vertex



# What do interventions give us?

- When we intervene on a vertex, we recover the orientations of edges incident to the vertex



- Naïve: Compute **minimum vertex cover** on  
subgraph induced by unoriented arcs

# Meek rules

[Meek 1995]

- **Sound and complete**

(with respect to arc orientations with acyclic completion)



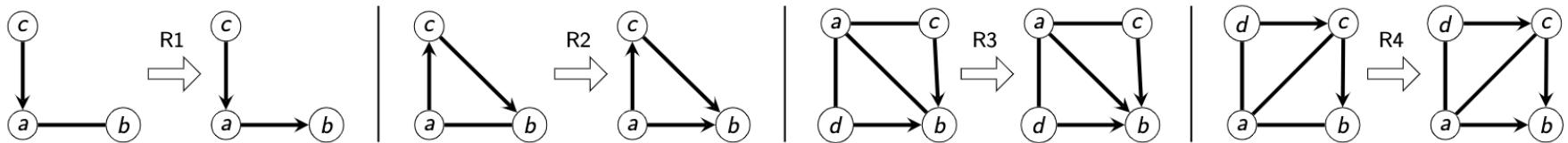
We won't miss out on  
any information

We won't wrongly  
orient arcs

# Meek rules [Meek 1995]

- **Sound and complete**

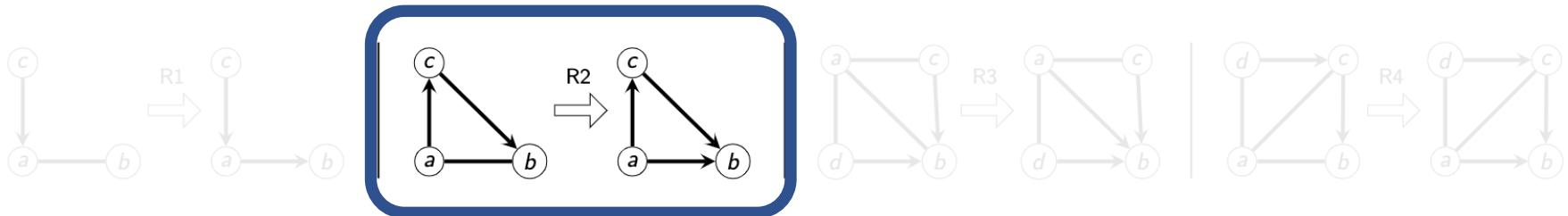
(with respect to arc orientations with acyclic completion)



# Meek rules [Meek 1995]

- **Sound and complete**

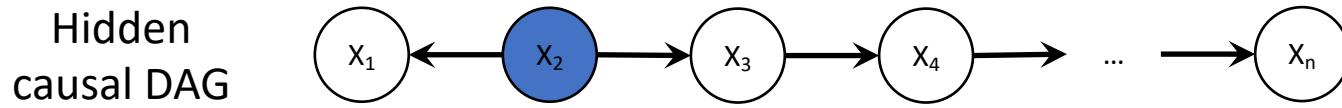
(with respect to arc orientations with acyclic completion)



If  $b \leftarrow a$ , then cycle

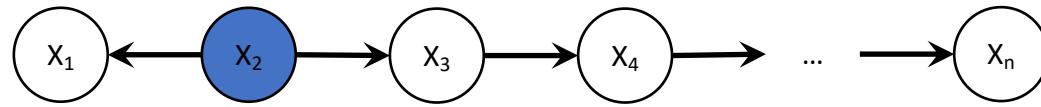
- Converge in polynomial time [Wienöbst, Bannach, Liśkiewicz 2021]

# A simple causal graph example

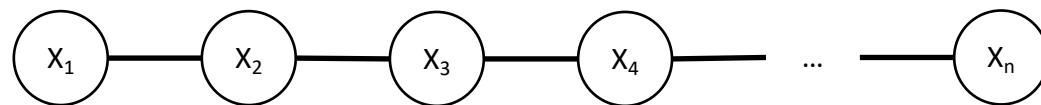


# A simple causal graph example

Hidden  
causal DAG

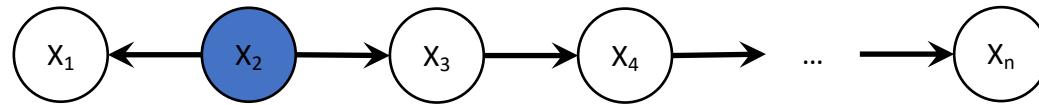


What we  
recover from  
data

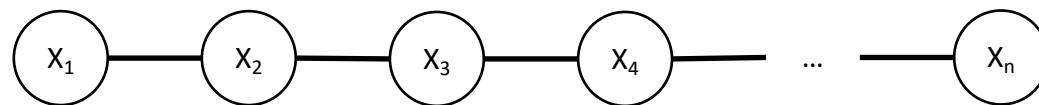


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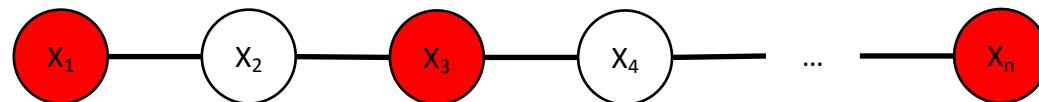
Hidden  
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What we  
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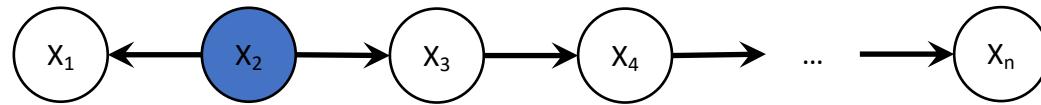


Naïve:  
Vertex cover

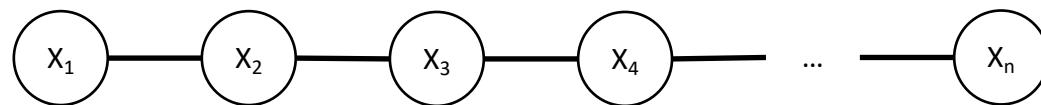


# A simple causal graph example

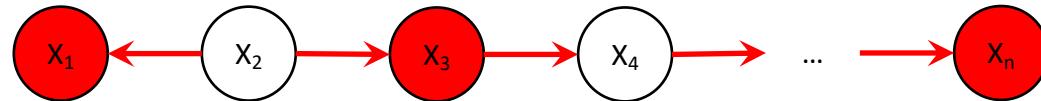
Hidden  
causal DAG



What we  
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Naïve:  
Vertex cover

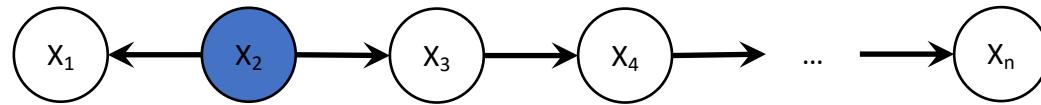


Recover incident edges

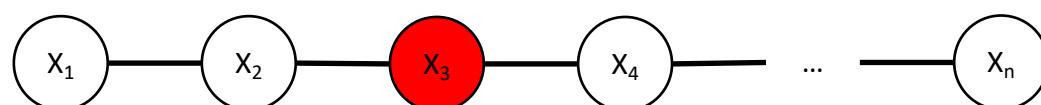
Need  $\approx \frac{n}{2}$   
interventions

# A simple causal graph example

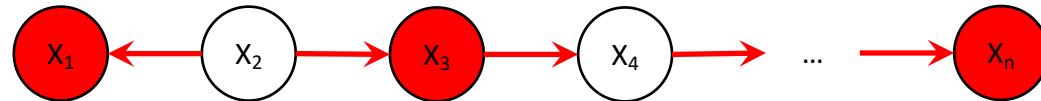
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causal DAG



Suppose we  
intervene  $x_3$



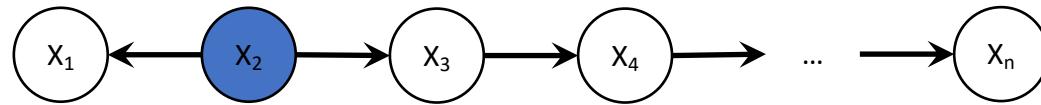
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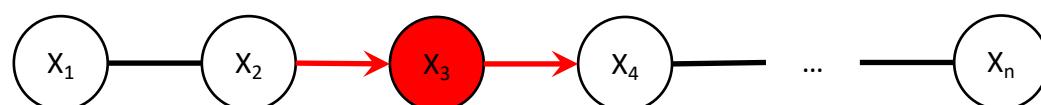
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Hidden  
causal DAG

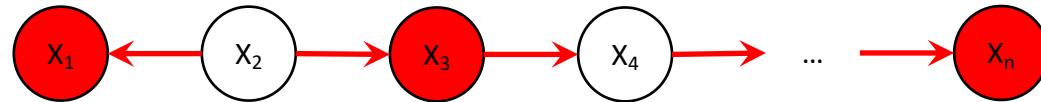


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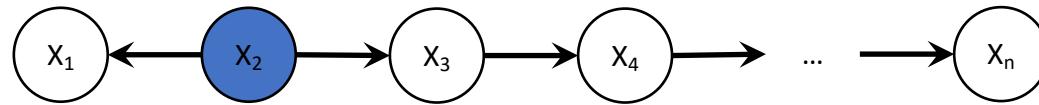
Naïve:  
Vertex cover



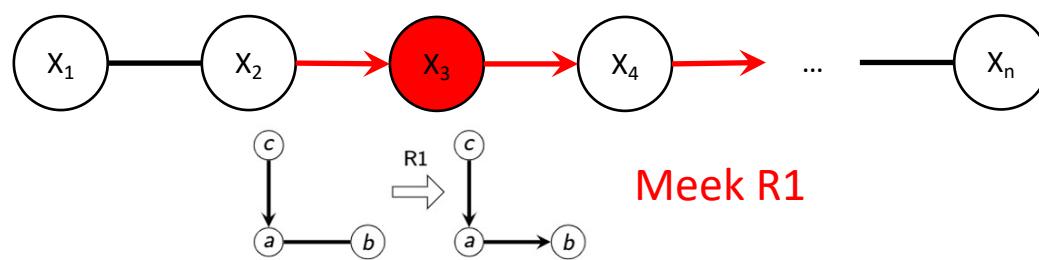
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# A simple causal graph example

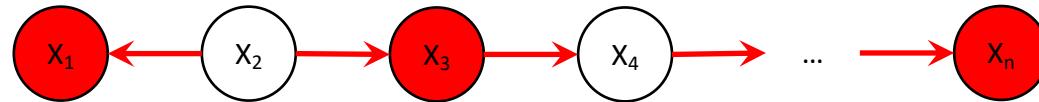
Hidden  
causal DAG



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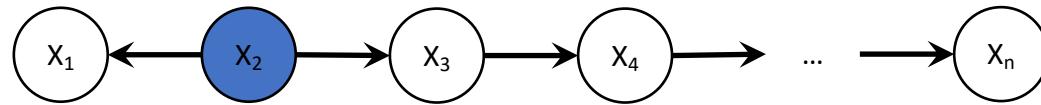
Naïve:  
Vertex cover



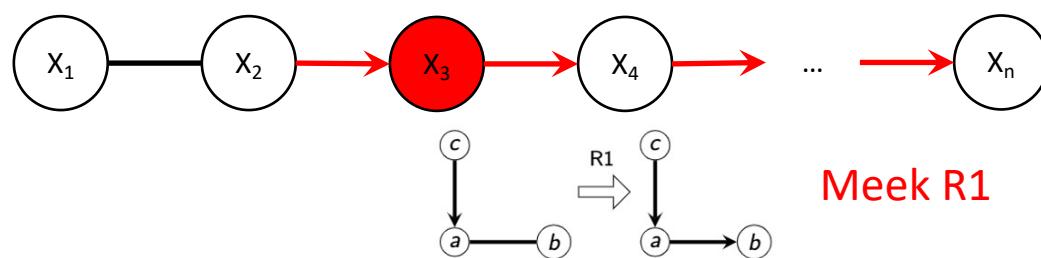
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# A simple causal graph example

Hidden  
causal DAG

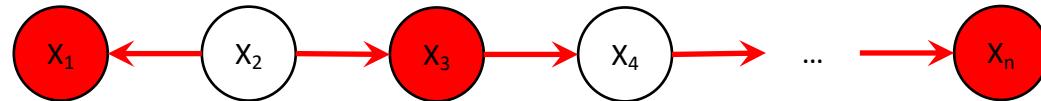


Suppose we  
intervene  $X_3$



Meek R1

Naïve:  
Vertex cover

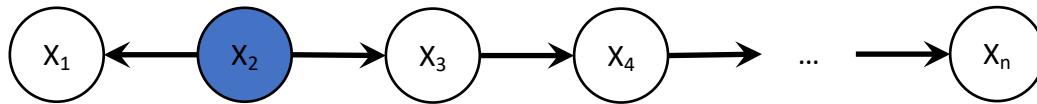


Need  $\approx \frac{n}{2}$   
interventions

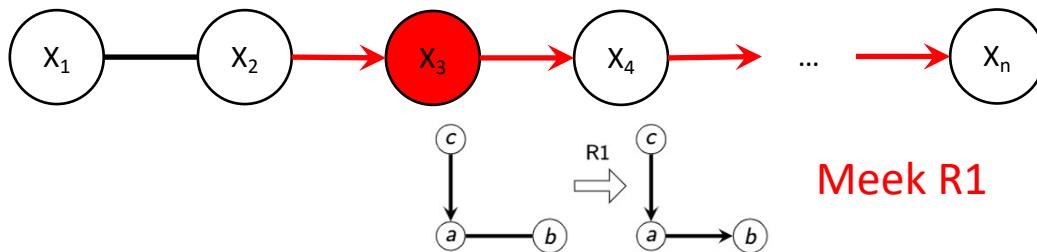
A S

Question: How many interventions do we need for this example?

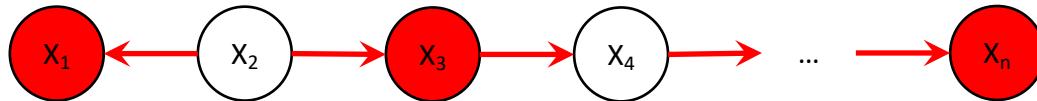
Hidden causal DAG



Suppose we intervene  $X_3$



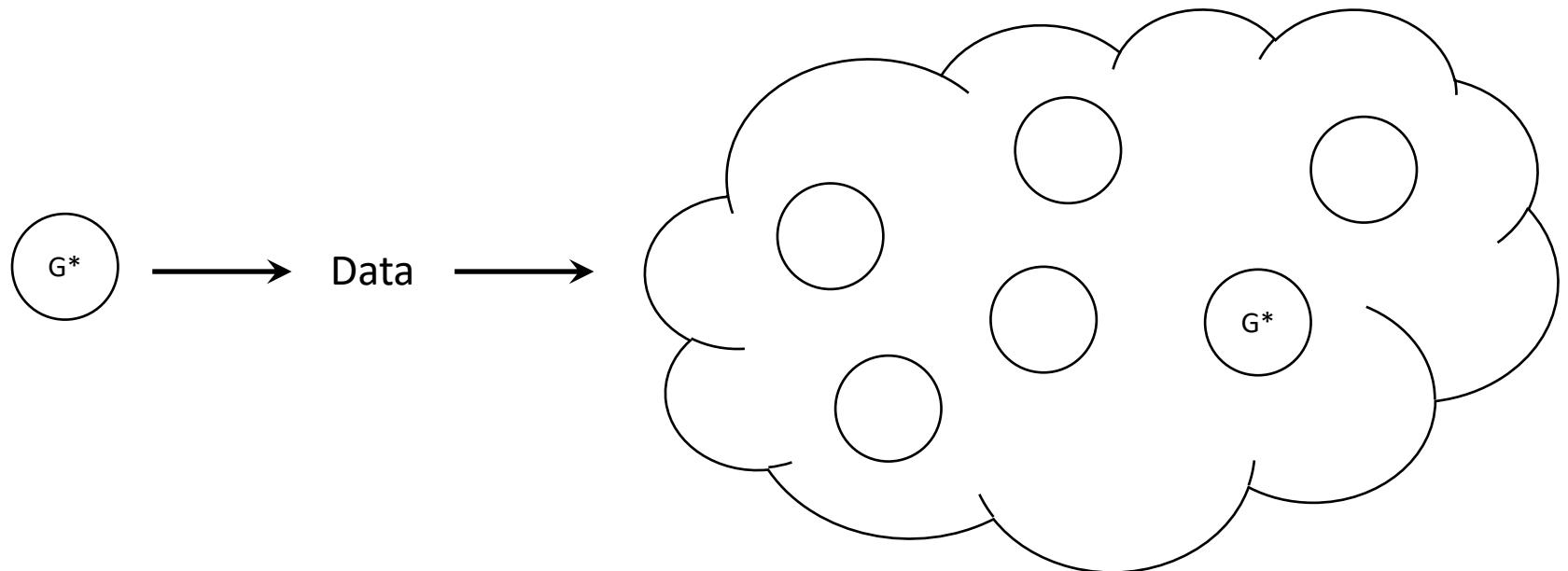
Naïve:  
Vertex cover



Need  $\approx \frac{n}{2}$  interventions

# Searching using adaptive interventions

**Identify  $G^*$**

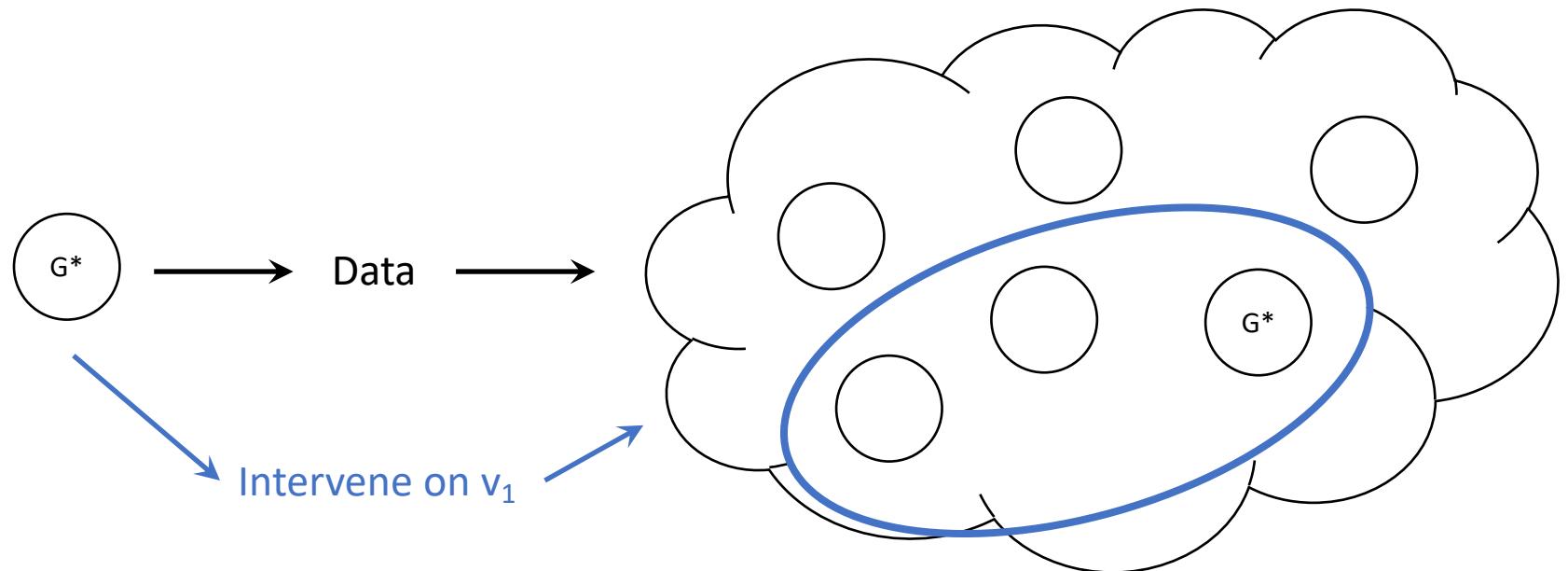


Equivalence class of causal graphs

Can be represented by a partially oriented causal graph

# Searching using adaptive interventions

Identify  $G^*$  using **interventions**

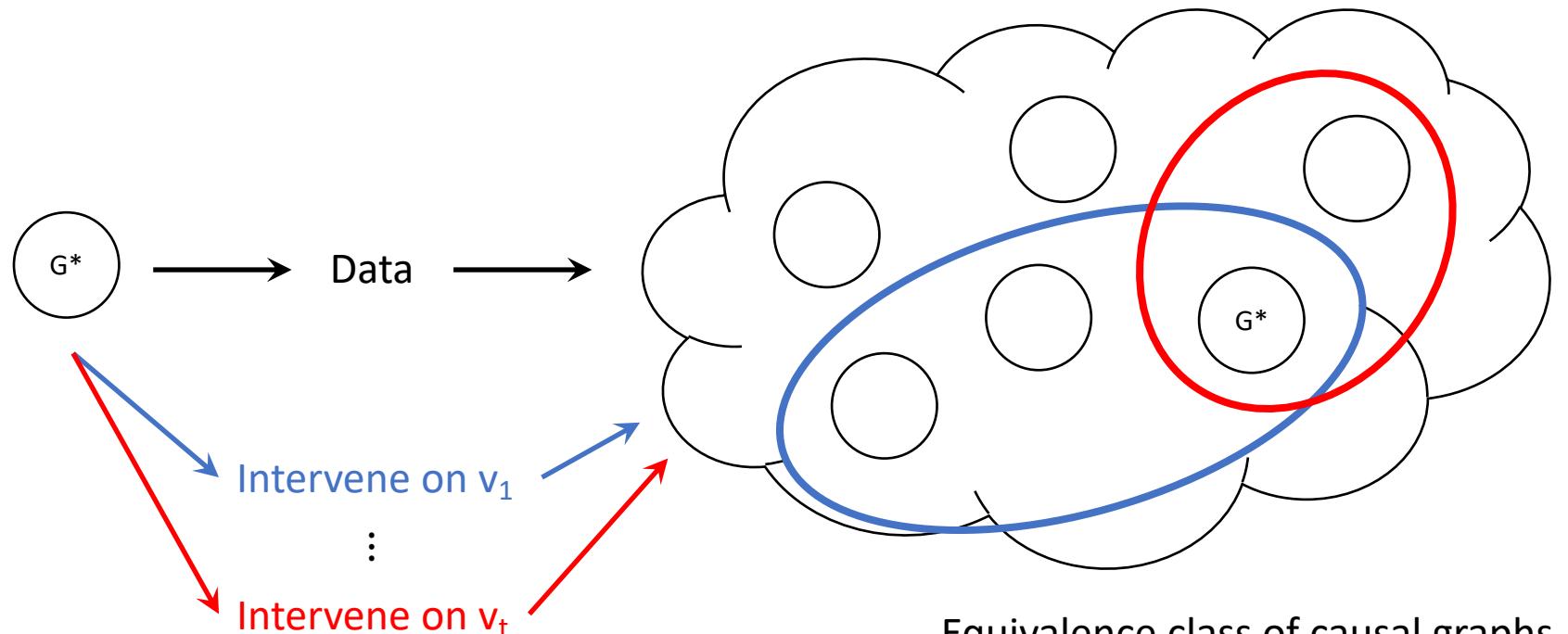


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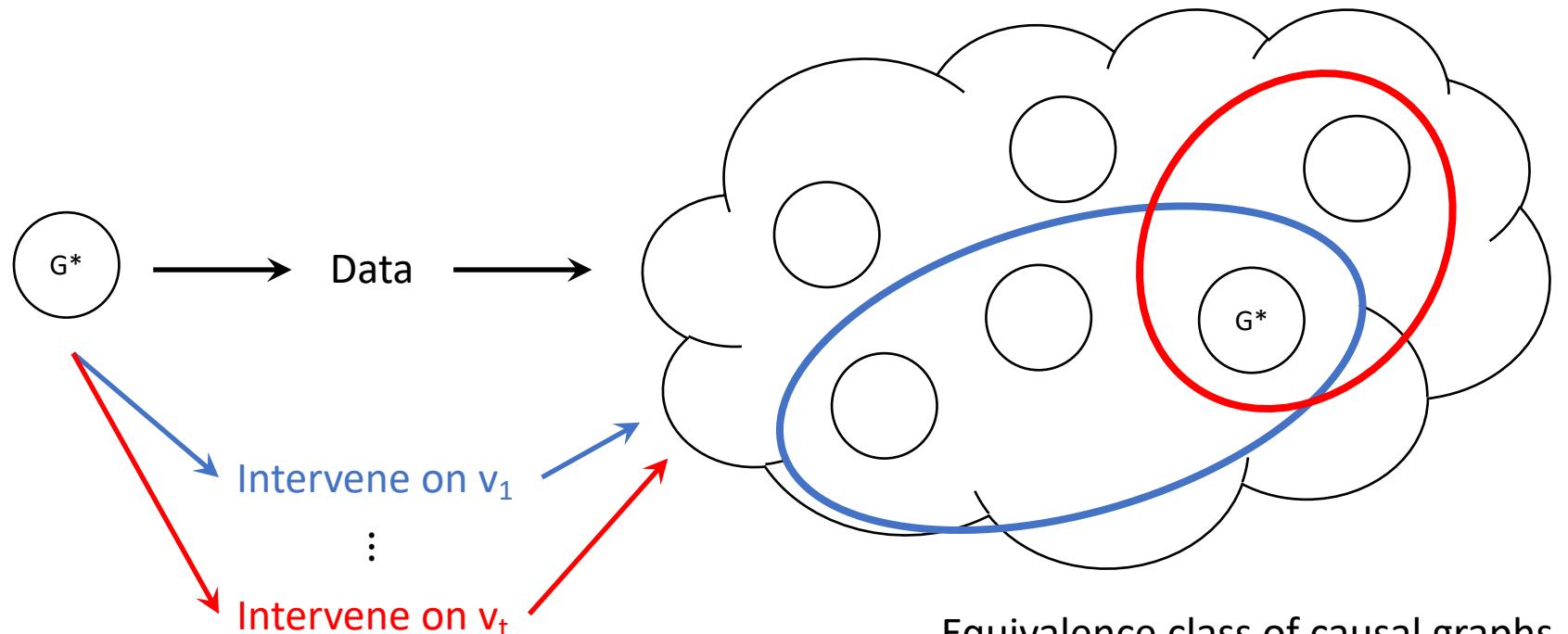
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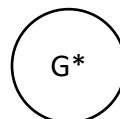
Identify  $G^*$  using **as few interventions as possible** (minimize  $t$ )



Equivalence class of causal graphs

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# Verification: A simpler problem

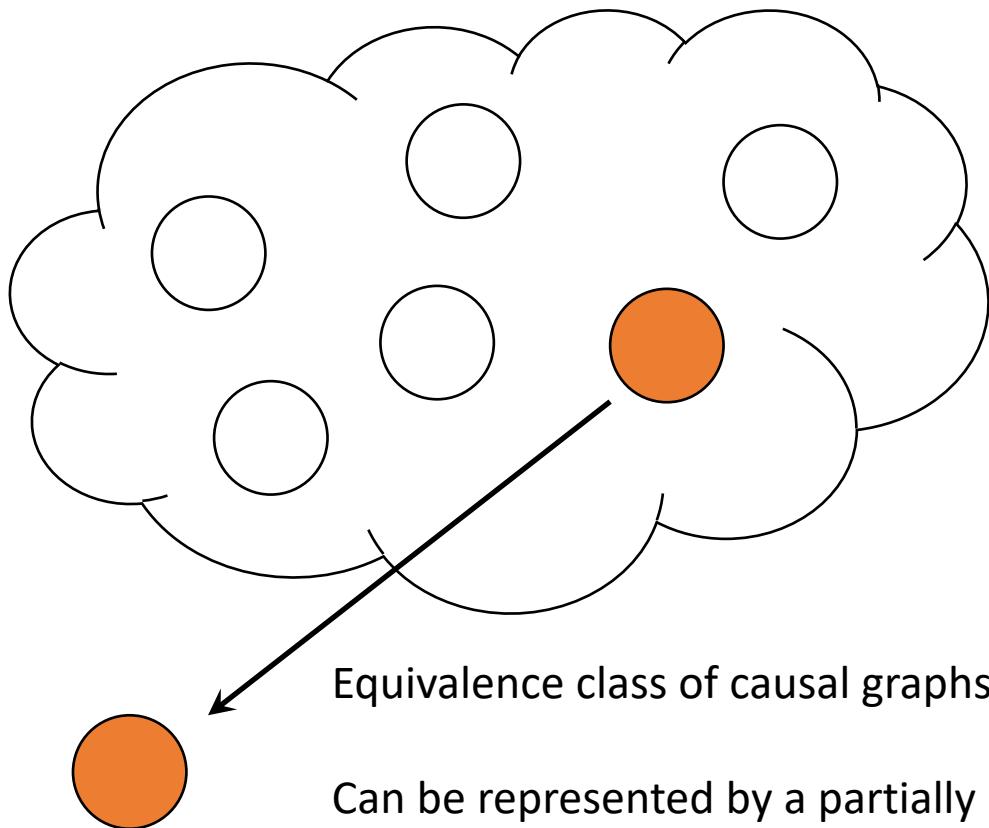


Data



Question:

Is = ?

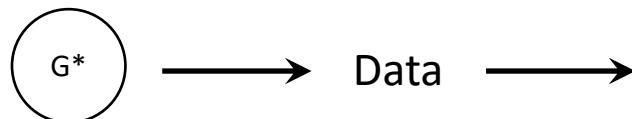


Equivalence class of causal graphs

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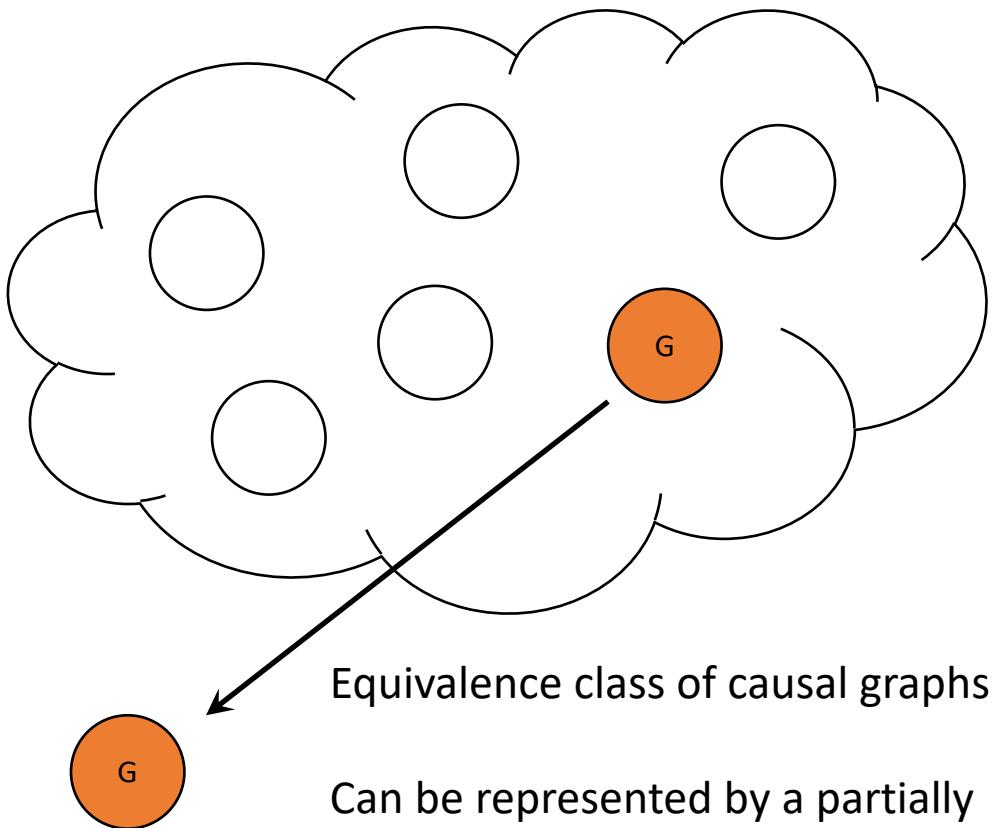
# Verification: A simpler problem

Let  $\nu(G)$  be the minimum number of interventions needed to answer this question



Question:

Is = ?



# Verification: A simpler problem

- What was known

$$1. \nu(G) \geq \left\lfloor \frac{\omega(G)}{2} \right\rfloor$$

[Squires, Magliacane, Greenewald, Katz, Kocaoglu, Shanmugam 2020]

Maximal clique size

$$2. \left\lceil \frac{n-r}{2} \right\rceil \leq \nu(G) \leq n - r$$

[Porwal, Srivastava, Sinha 2022]

Number of maximal cliques

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- What we show [Choo, Shiragur, Bhattacharyya 2022]

- **Exact** characterization of  $\nu(G)$  for any causal DAG G via a minimum vertex cover on an induced subgraph of G

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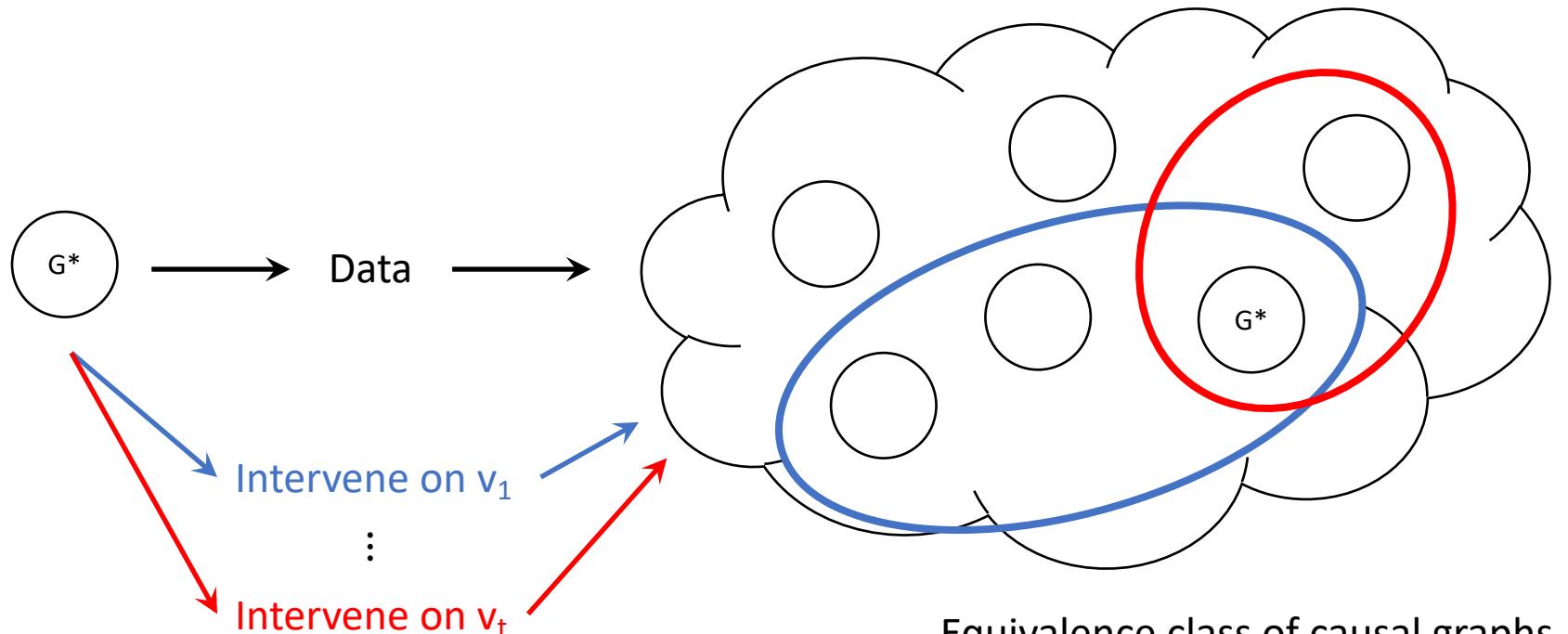
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- **Exact** characterization of  $\nu(G)$  for any causal DAG G via a **minimum vertex cover on an induced subgraph of G**
- Proof idea: Induction on a topo ordering + Meek rules
- Efficiently computable since **this subgraph is a forest**

# Back to the search problem

Identify  $G^*$  using **as few interventions as possible** (minimize  $t$ )



Can be represented by a partially oriented causal graph

# Two classes of interventions

- Non-adaptive
  - Given equivalence class, decide on a single fixed set of interventions that recovers *any possible causal DAG*
  - Need to intervene on a ***G-separating system***

[Kocaoglu, Dimakis, Vishwanath 2017]



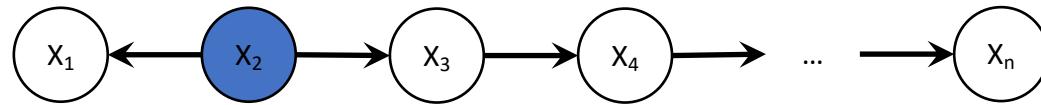
In this simplified talk, where we intervene on a single vertex per intervention, **this is just vertex cover**

# Two classes of interventions

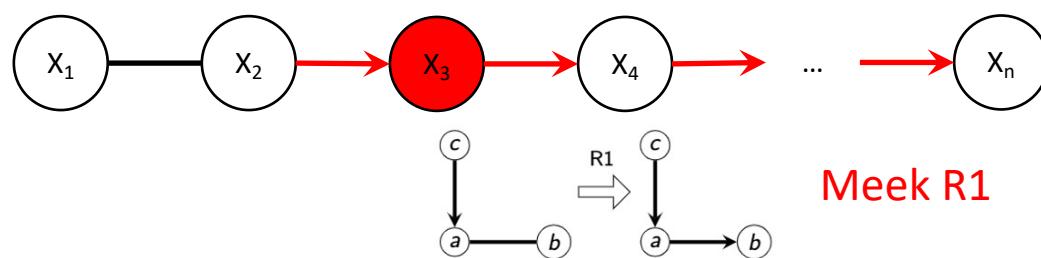
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  - Need to intervene on a *G-separating system*  
[Kocaoglu, Dimakis, Vishwanath 2017]
- Adaptive
  - Given equivalence class,
    - Decide on first intervention
    - See outcome
    - Decide on second intervention
    - See outcome
    - ...

# The power of adaptivity

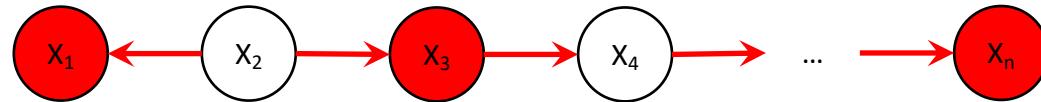
Hidden causal DAG



Suppose we intervene  $X_3$



Naïve:  
Vertex cover



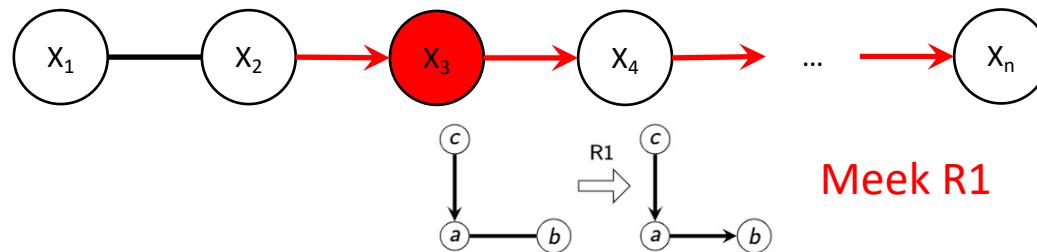
Need  $\approx \frac{n}{2}$   
interventions

# The power of adaptivity

Hidden  
causal

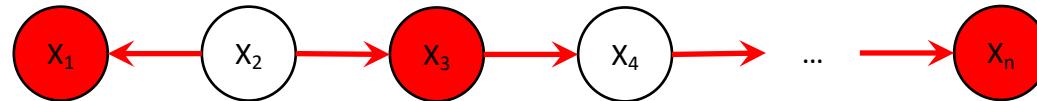
We can do something like binary search  
and only use  $\mathcal{O}(\log n)$  interventions

Suppose we  
intervene  $X_3$



$\mathcal{O}(\log n)$   
interventions  
suffice

Naïve:  
Vertex cover



Need  $\approx \frac{n}{2}$   
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# The adaptive search problem

- What we know
  - We know at least  $\nu(G^*)$  is necessary
  - Prior works only have guarantees for special classes of graphs: cliques, trees, intersection incomparable, etc.

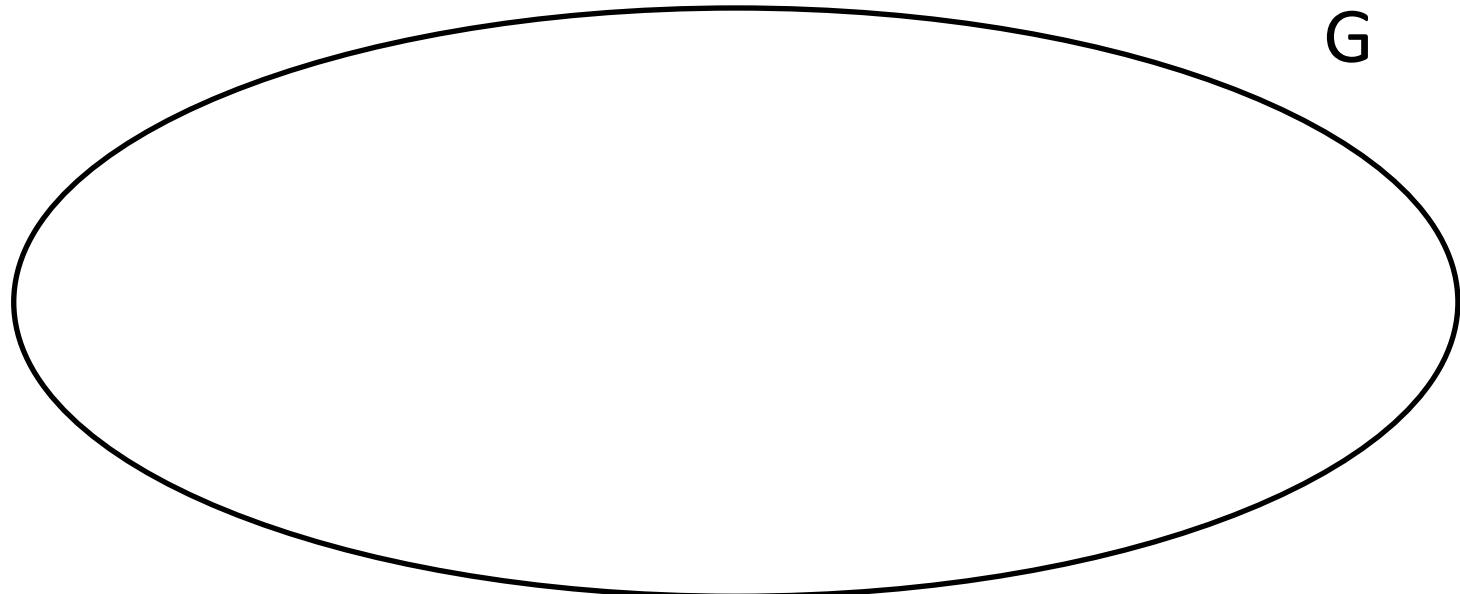
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- What we show [Choo, Shiragur, Bhattacharyya 2022]
  - Punchline:  $\mathcal{O}(\log n \cdot \nu(G^*))$  interventions suffice
  - “Search is almost as easy as verification”

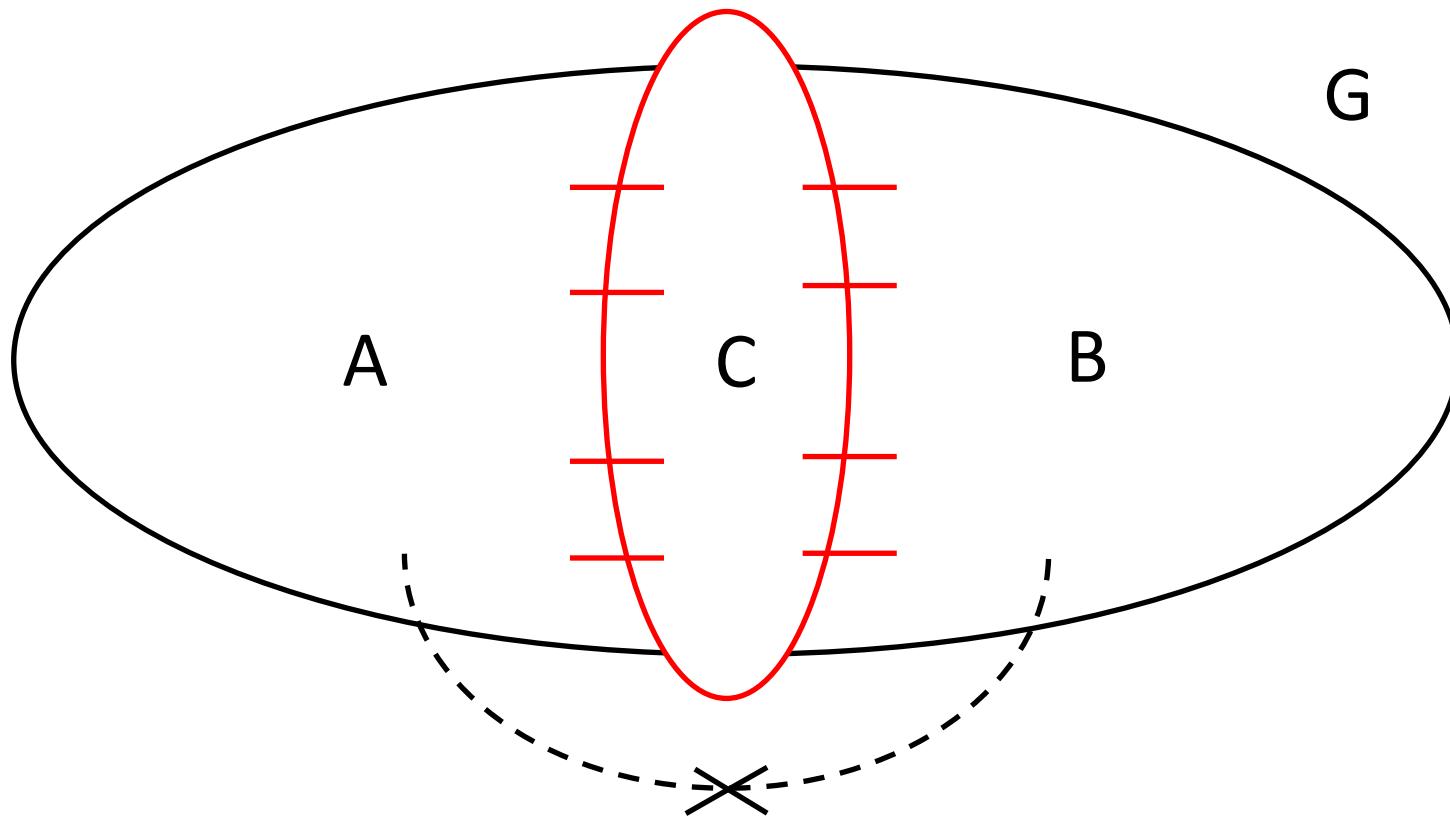
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  - Punchline:  $\mathcal{O}(\log n \cdot \nu(G^*))$  interventions suffice
  - “Search is almost as easy as verification”
  - Algorithm does not even know what  $\nu(G^*)$  is!
  - $\Omega(\log n)$  is unavoidable when causal graph is a directed path on  $n$  nodes

# Key algorithmic idea: Graph separators



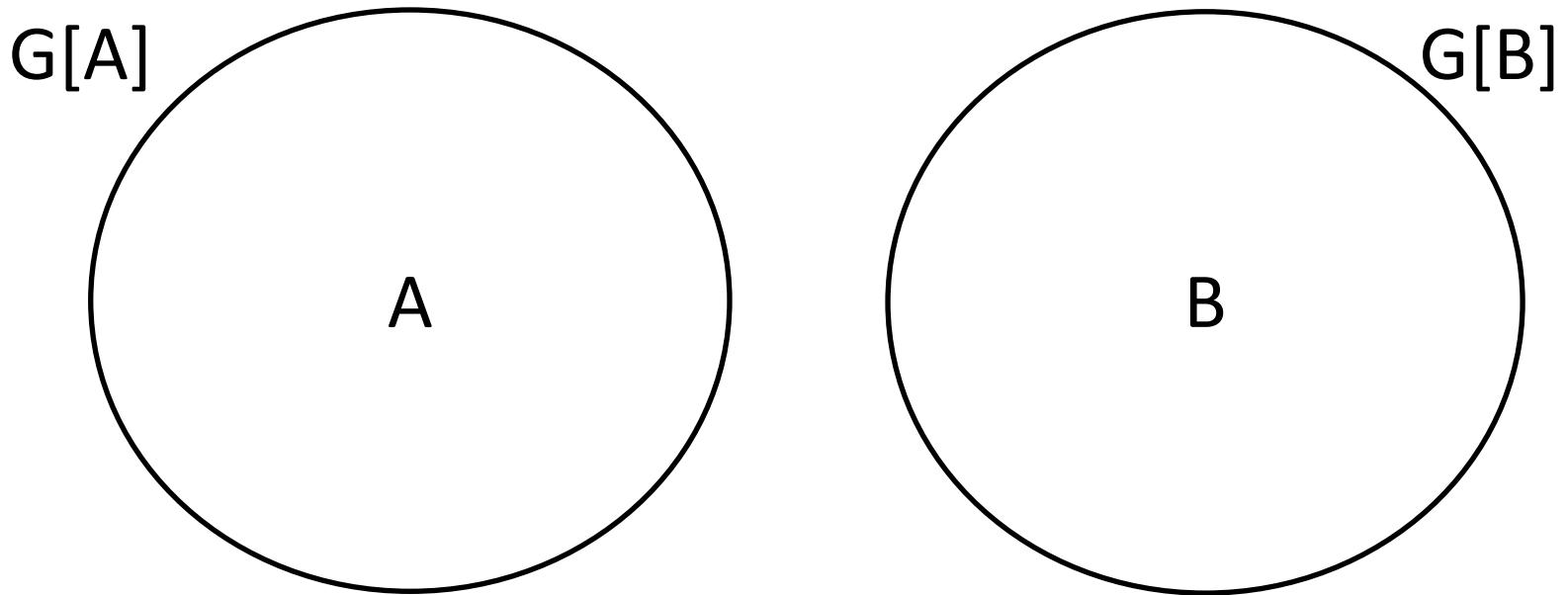
# Key algorithmic idea: Graph separators



Partition vertex set  $V$  into  $A$ ,  $B$ ,  $C$ :

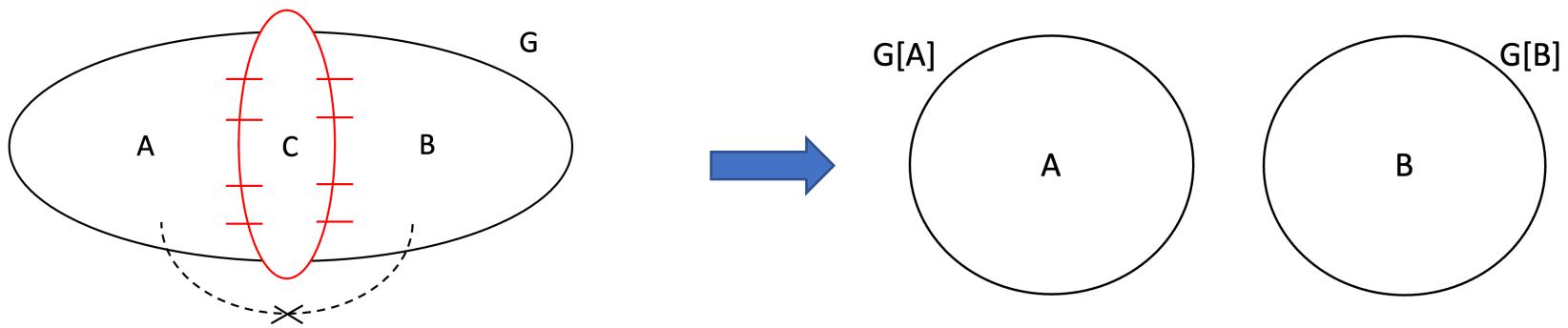
1.  $C$  separates  $A$  and  $B$
2.  $|A|, |B| \leq |V| / 2$

# Key algorithmic idea: Graph separators



Recurse on smaller subgraphs of half the size

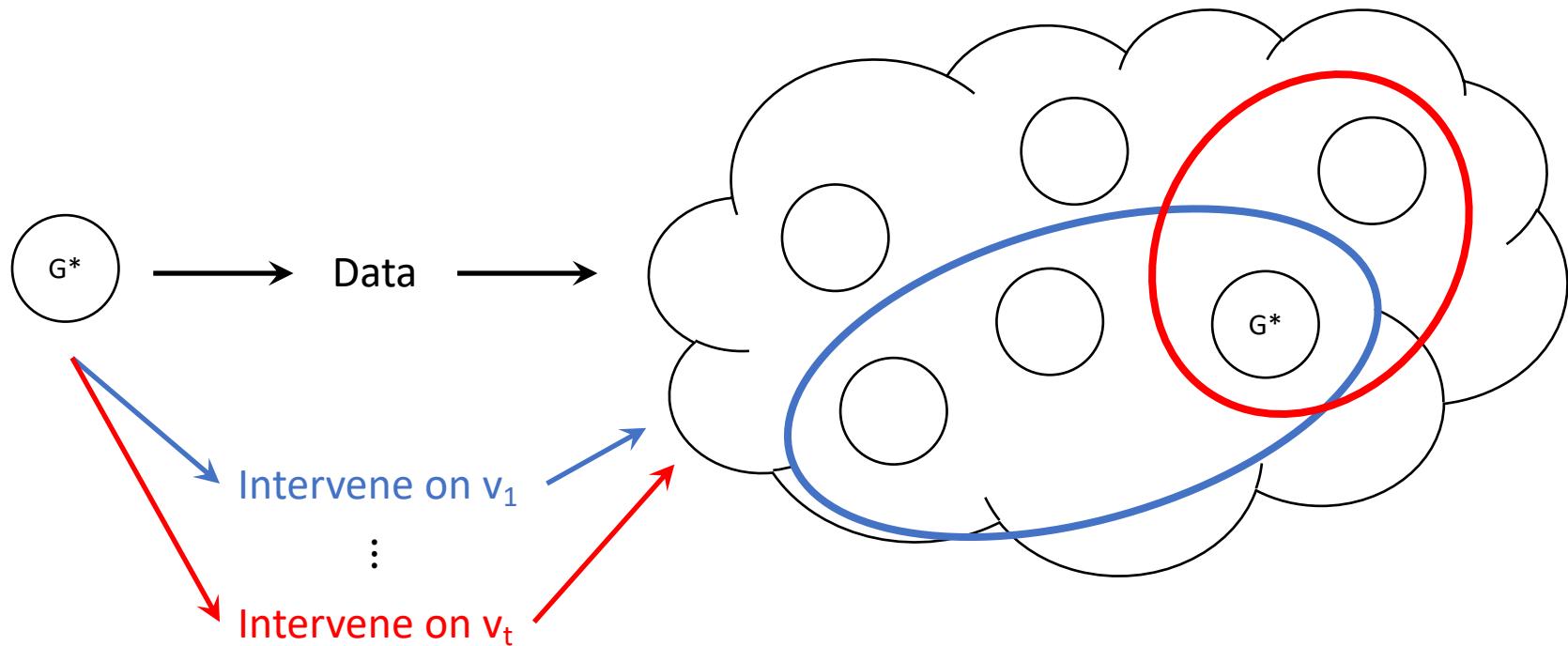
# Key algorithmic idea: Graph separators



- Analysis:
  - $\mathcal{O}(\log n)$  rounds  $\leftarrow$  Chordal graph separator [Gilbert, Rose, Edenbrandt 1984]
  - $\mathcal{O}(v(G^*))$  per round  $\leftarrow$  We prove new lower bound on  $v(G^*)$

# Problem setup

Identify  $G^*$  using **as few interventions as possible** (minimize  $t$ )



**Verification:**  $\nu(G^*) = \text{size of minimum vertex cover of covered edges}$

[CSB 2022]

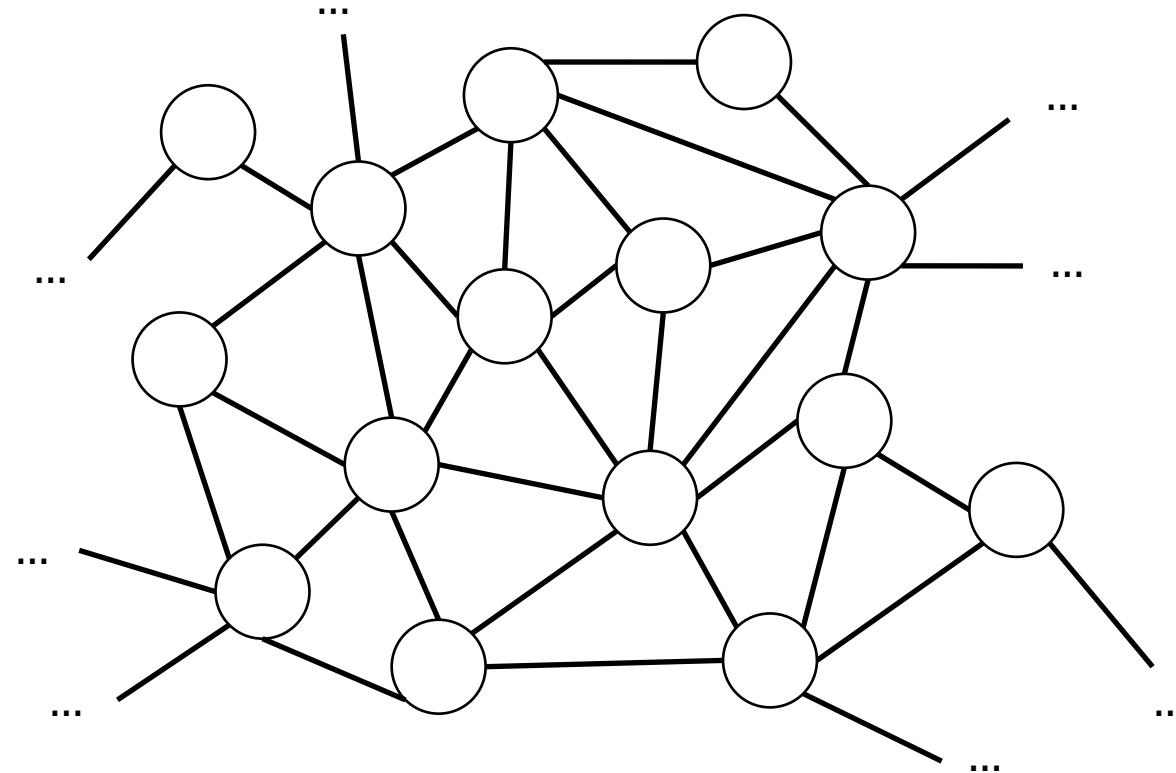
**Search:**  $\mathcal{O}(\log n \cdot \nu(G^*))$  interventions suffice

[CSB 2022]

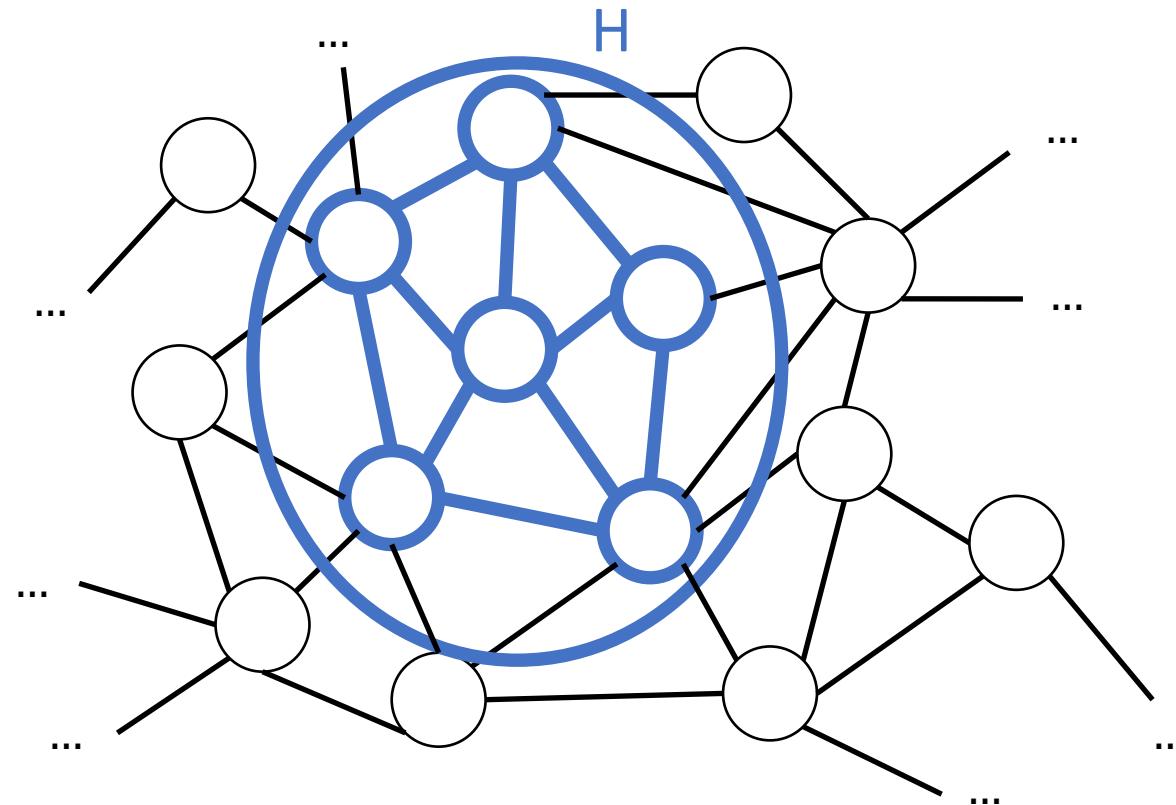
# Natural extensions and questions

- What if the causal graph is HUGE?

# What if causal graph is HUGE?



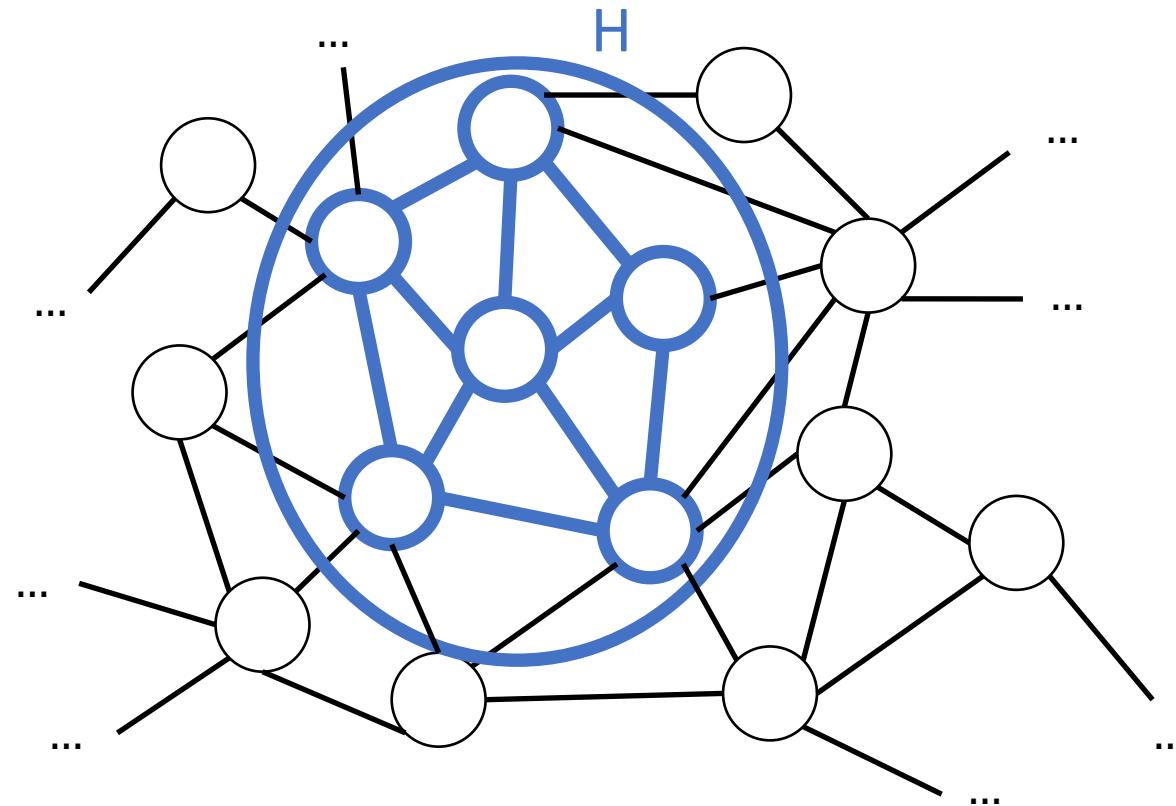
# What if causal graph is HUGE?



**Local causal discovery:**

Only care about a small subgraph of the larger graph

# What if causal graph is HUGE?



## Local causal discovery:

Only care about a small subgraph of the larger graph

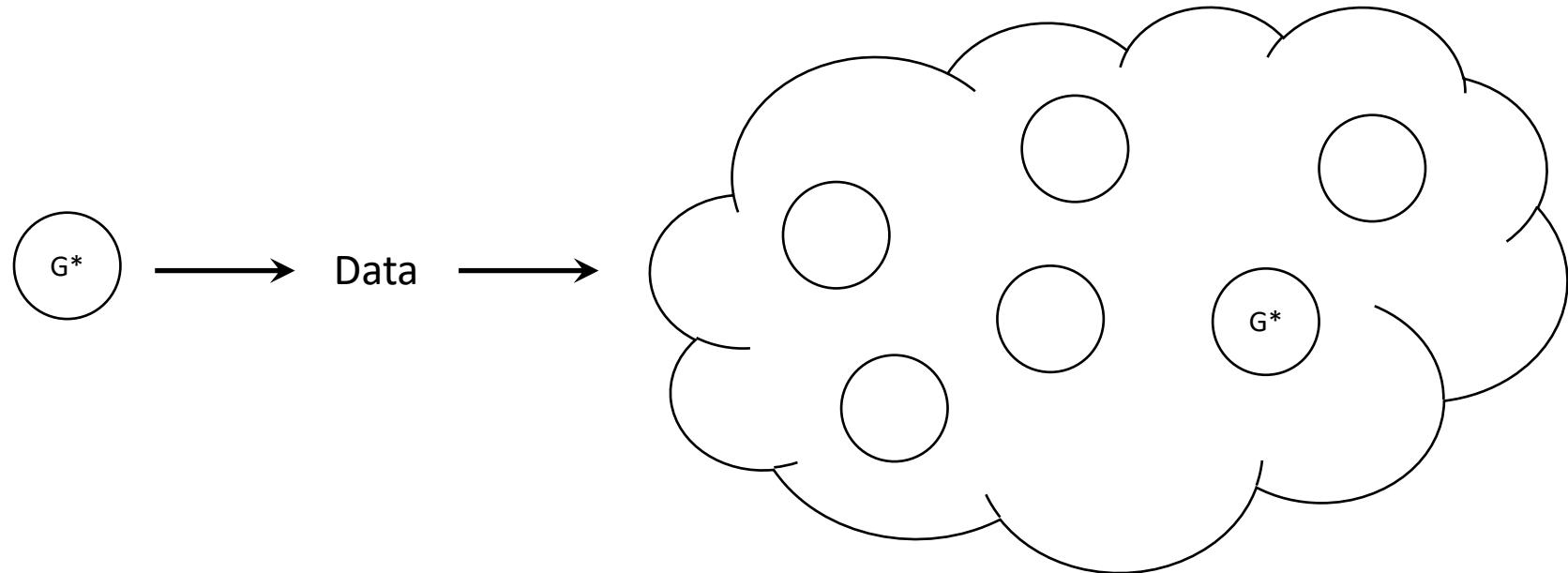
(Informal) Verification: Generalization of “DP on covered edge forest”. [CS 2023]

(Informal) Search:  $\mathcal{O}(\log |H| \cdot \nu(G^*))$  interventions suffices [CS 2023]

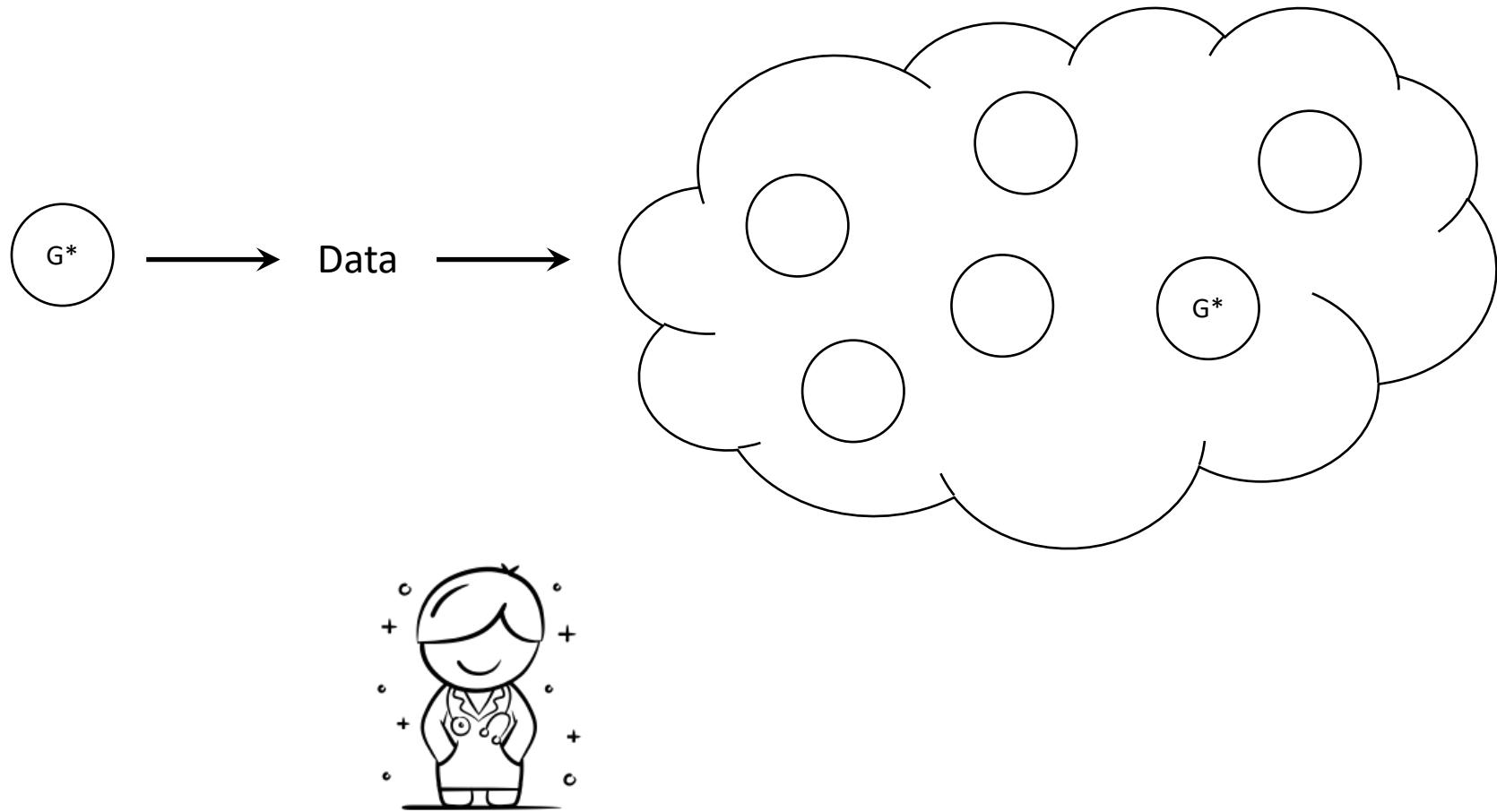
# Natural extensions and questions

- What if the causal graph is HUGE?
- What if we consult domain experts for advice?

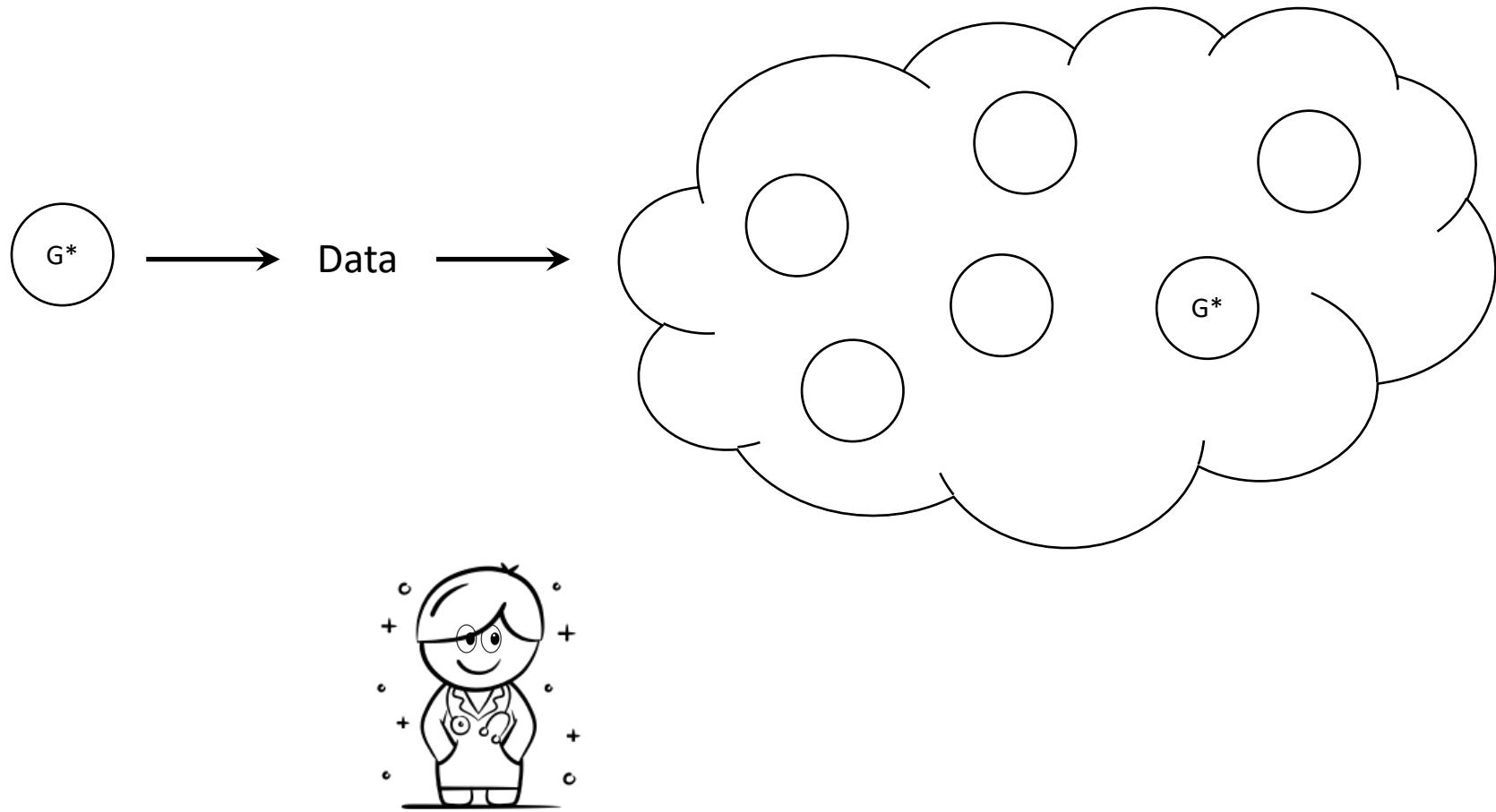
In many problem domains...



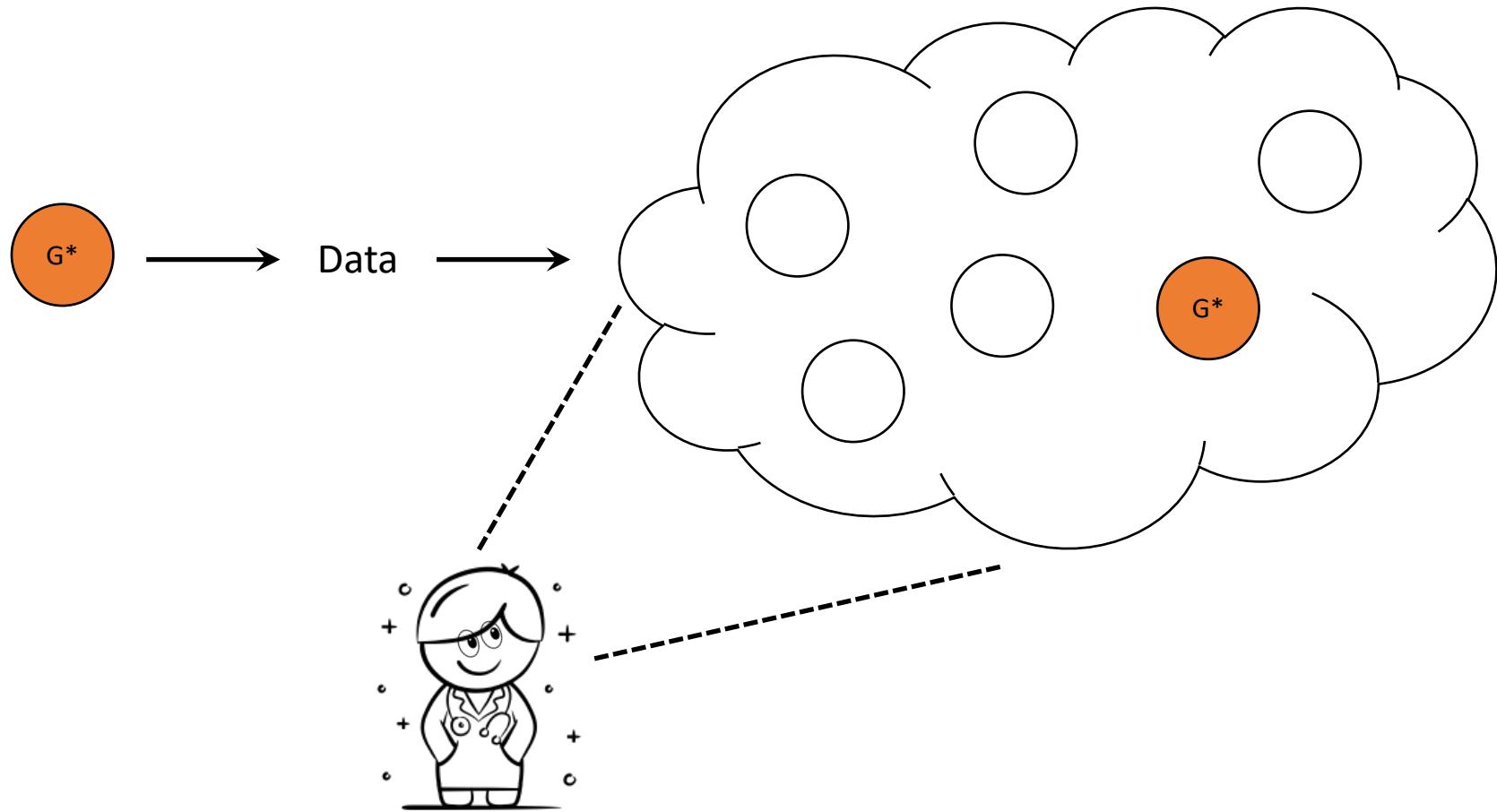
# There are domain experts!



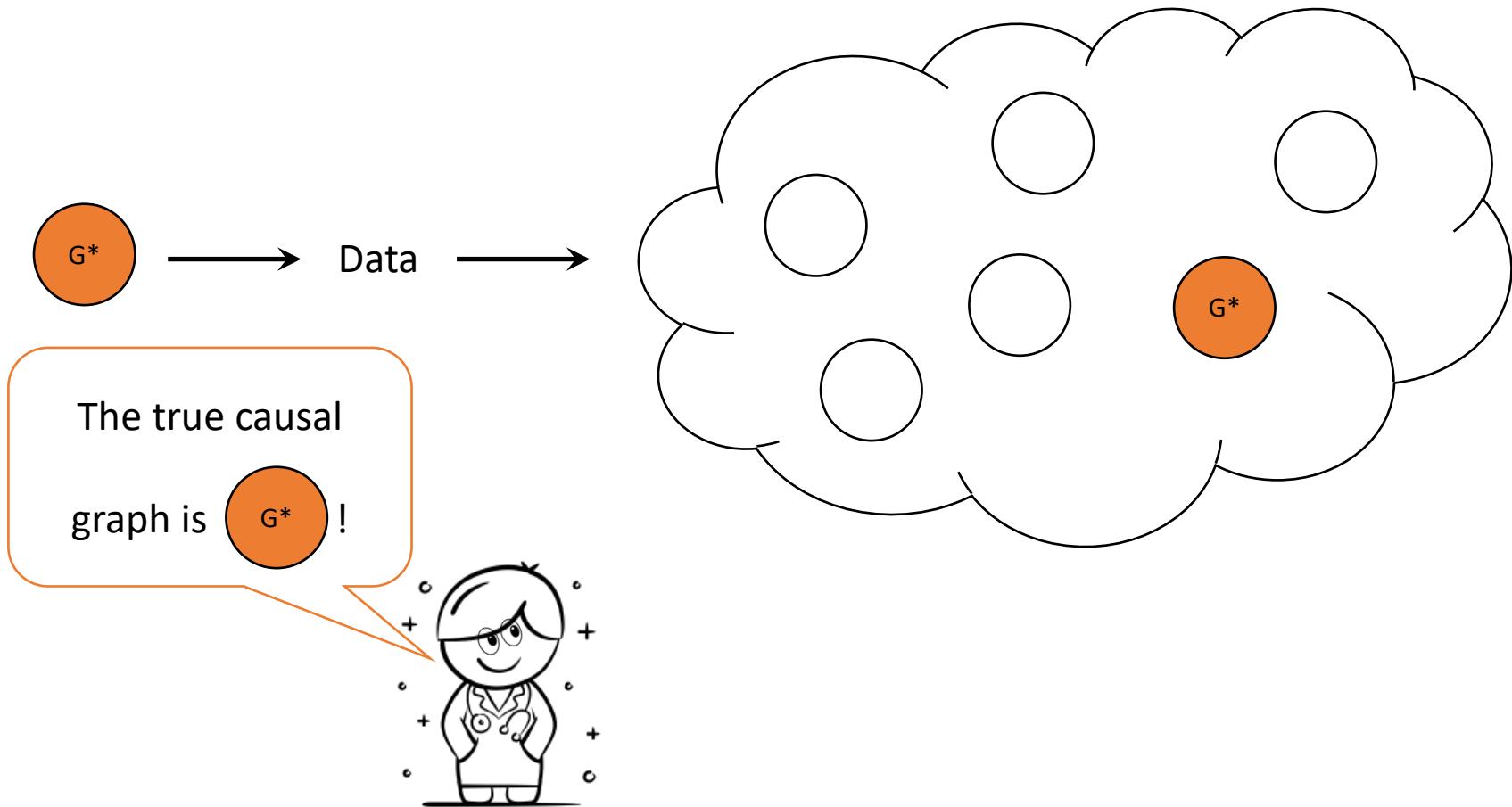
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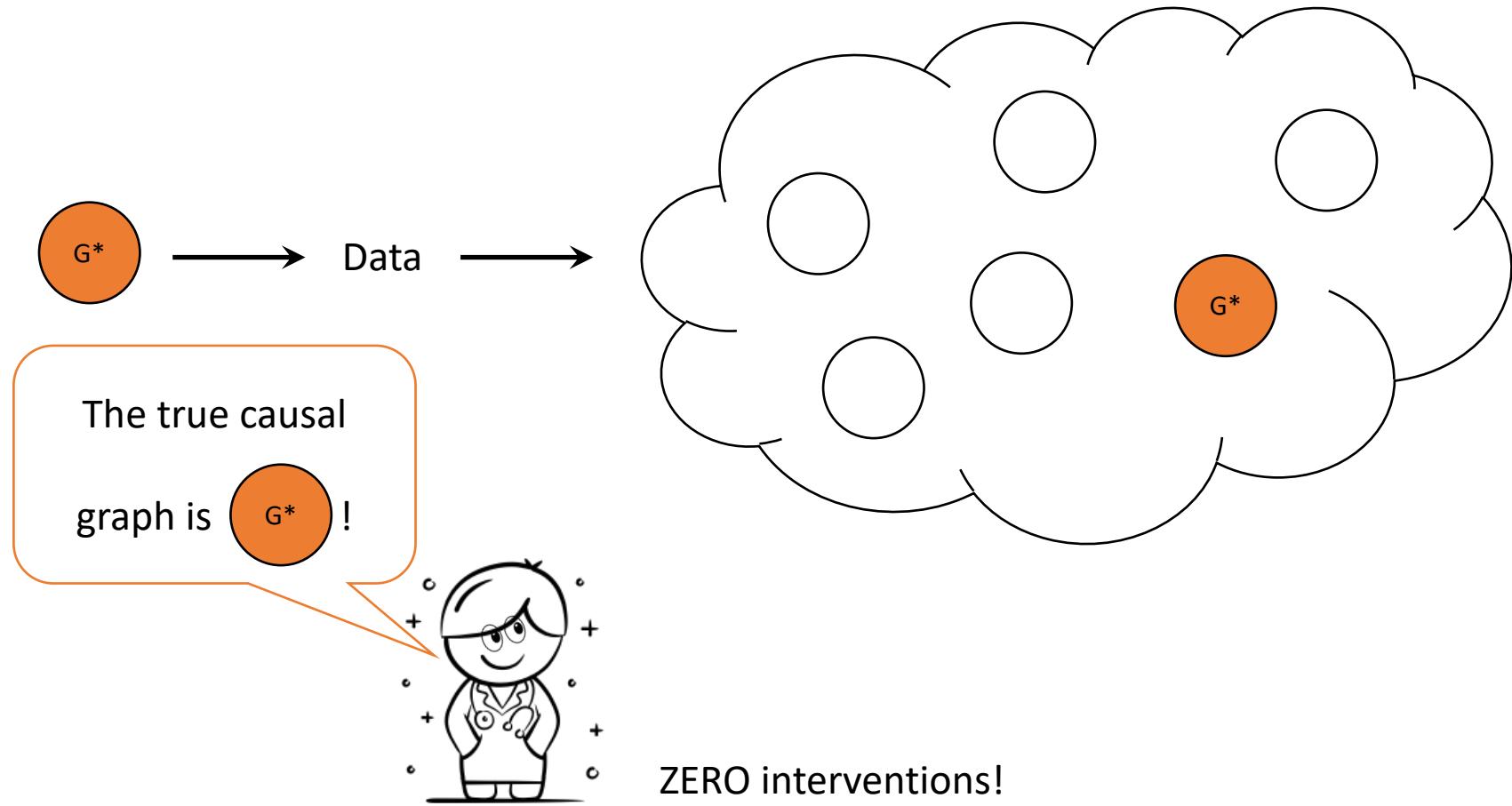
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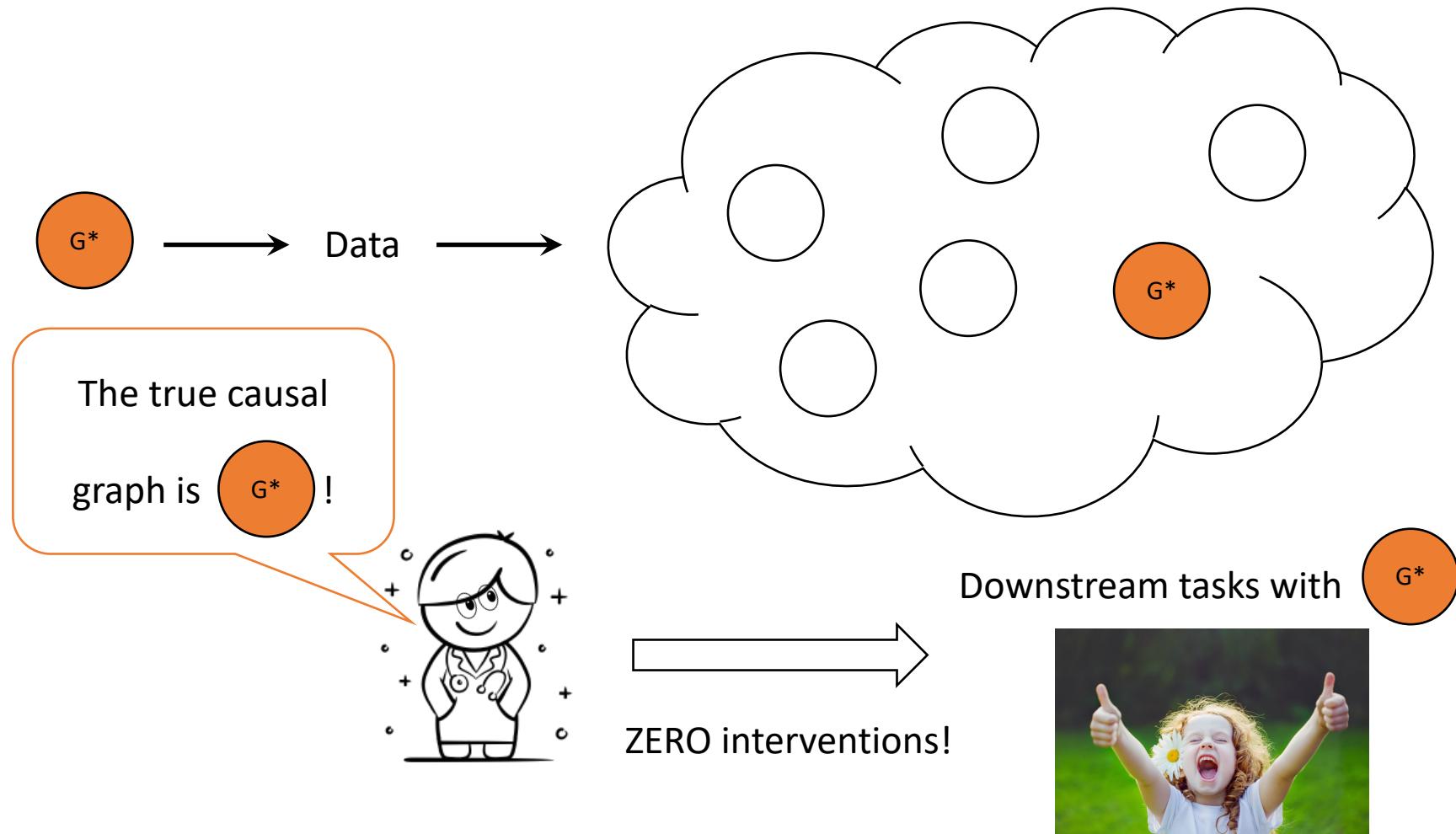
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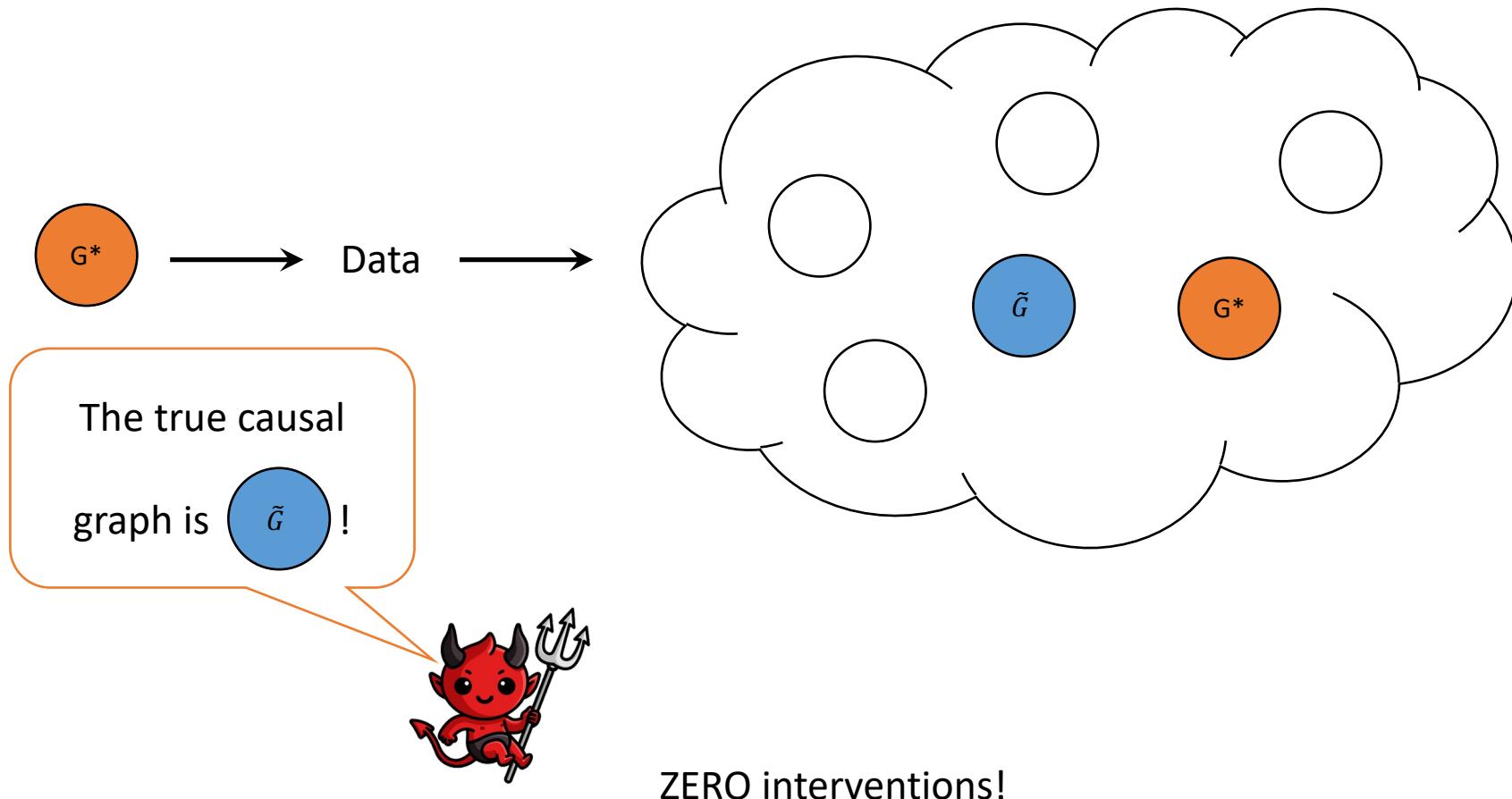
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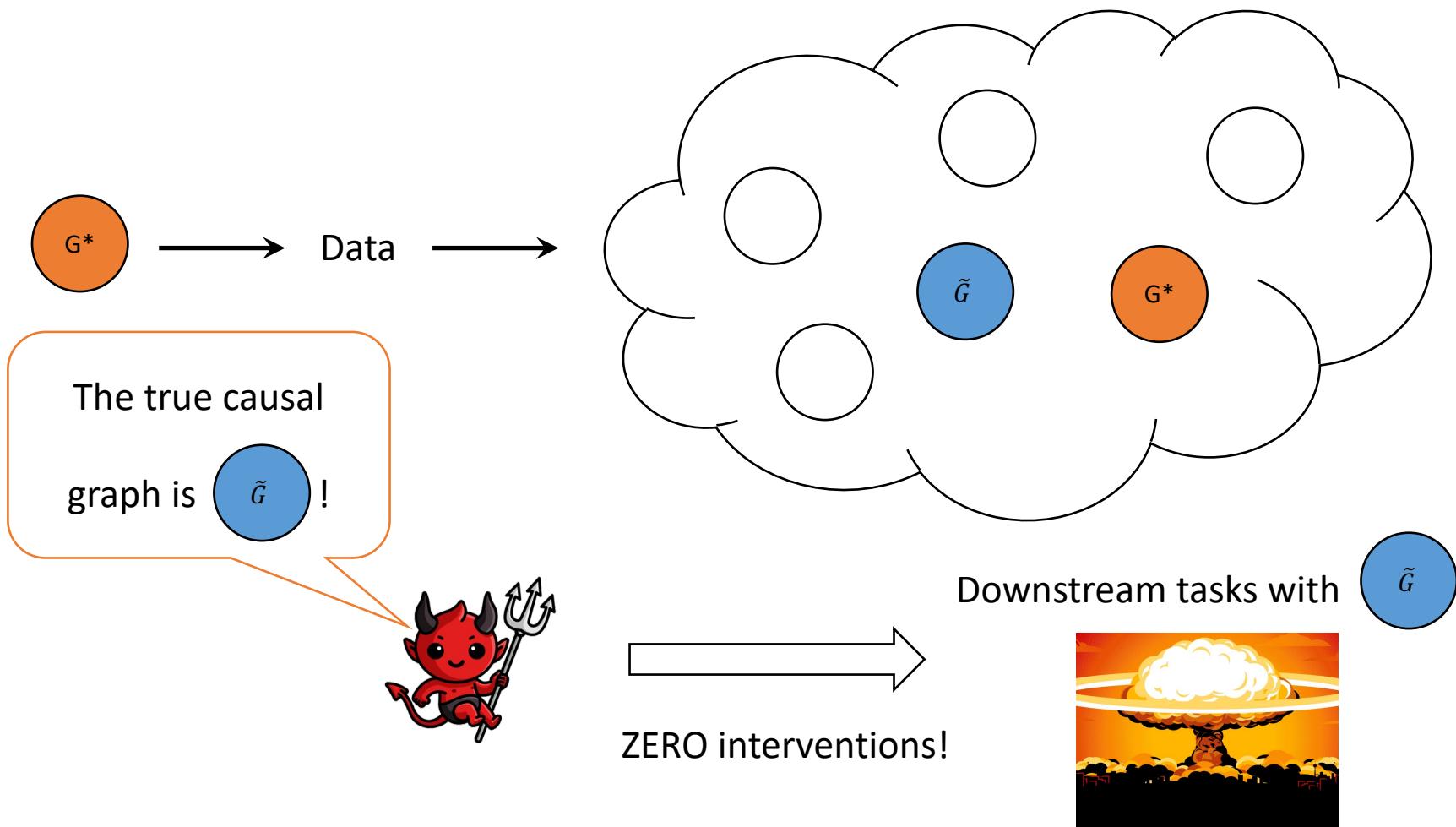
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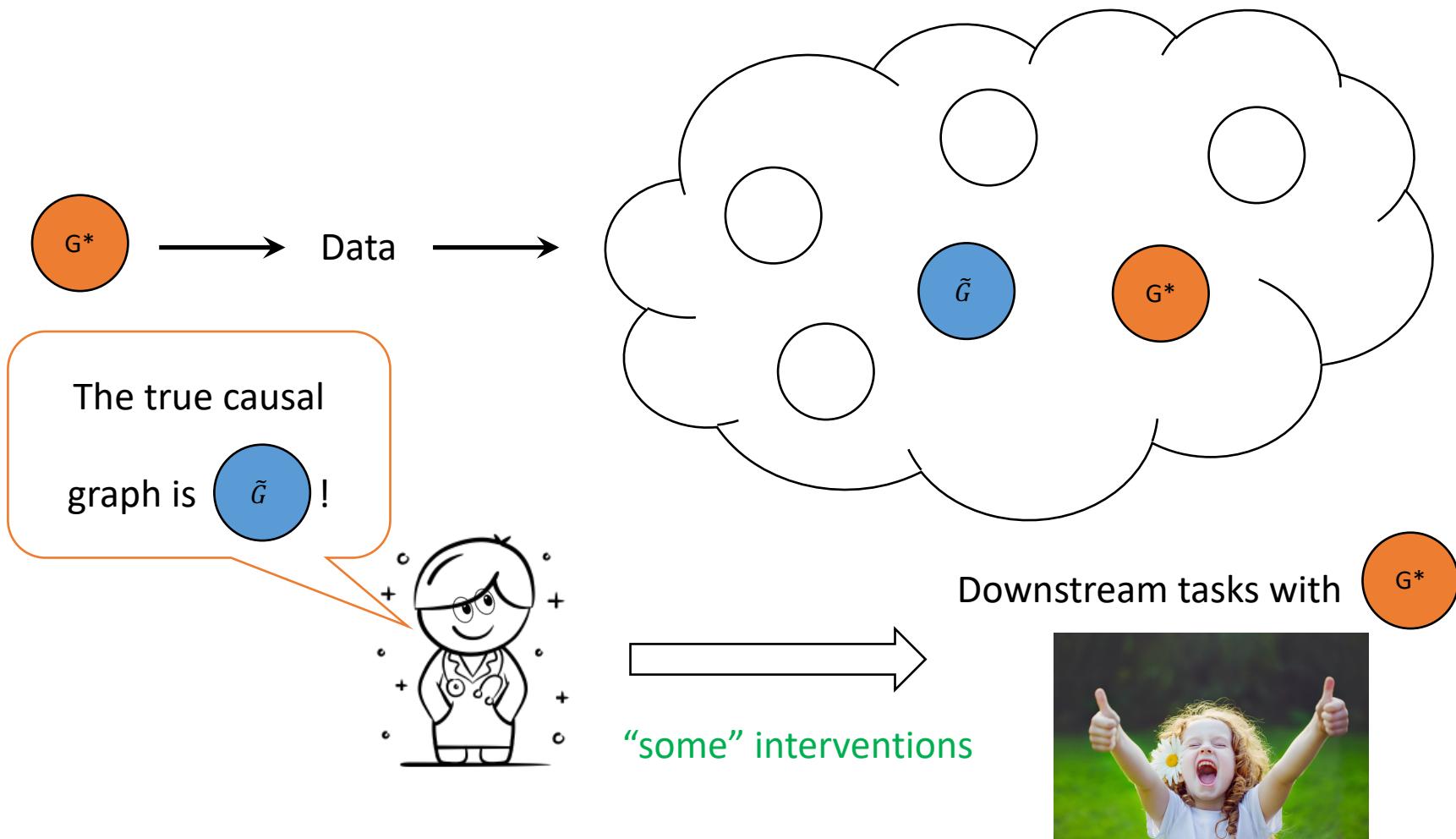
# But... experts can be wrong



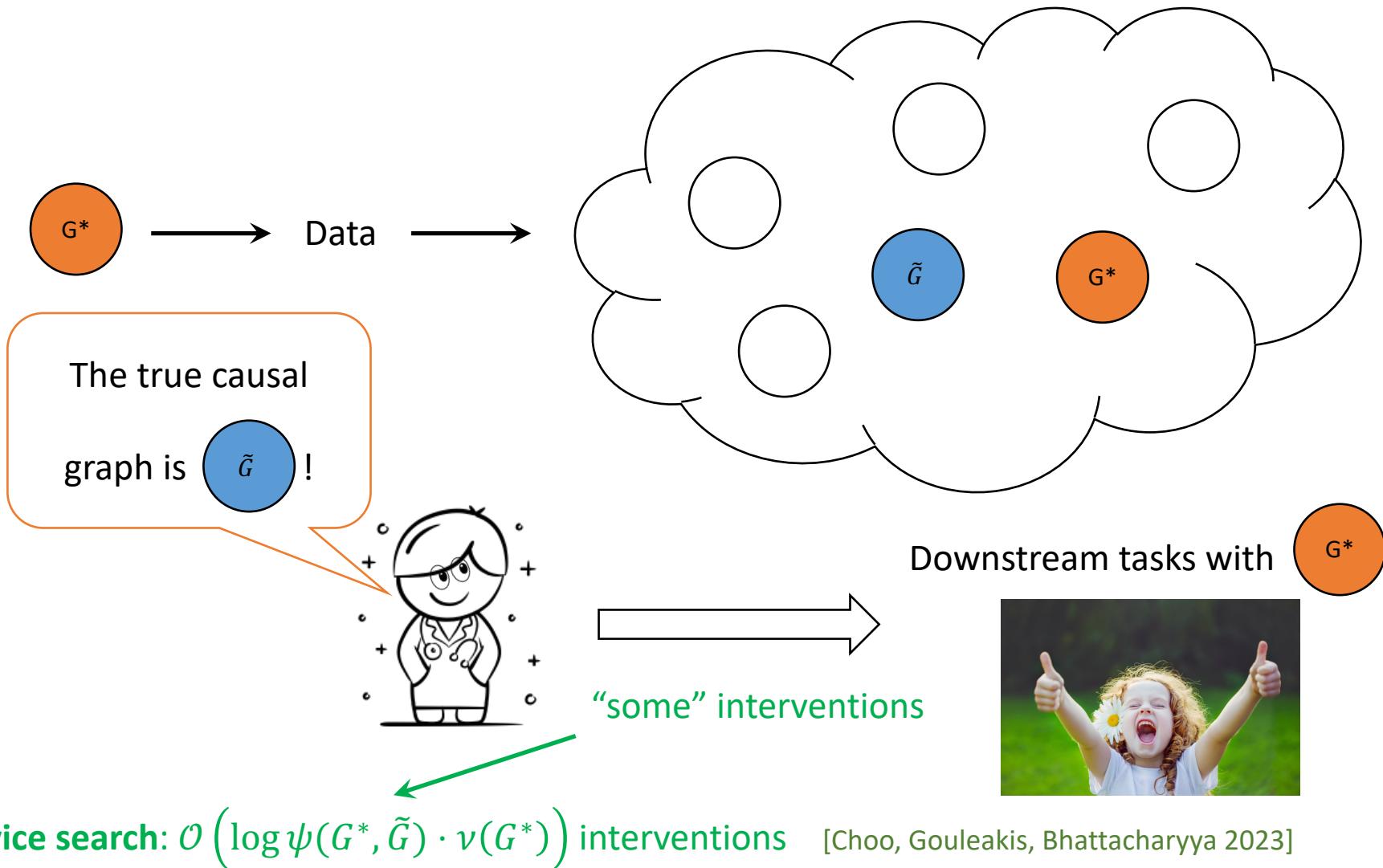
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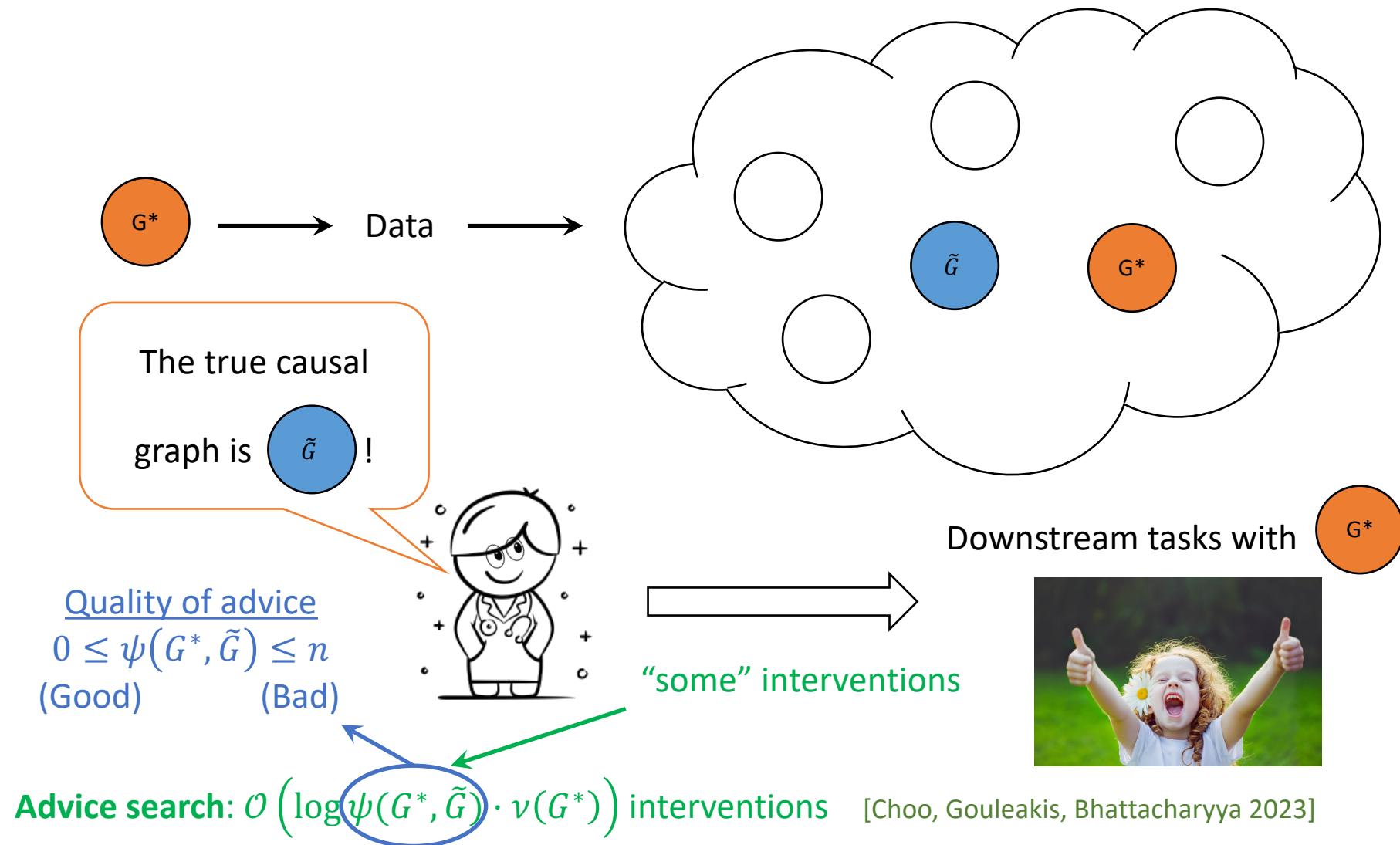
# How to use imperfect advice?



# How to use imperfect advice?



# How to use imperfect advice?



# Natural extensions and questions

- What if the causal graph is HUGE?
- What if we consult domain experts for advice?
- What if we have limited rounds of adaptivity?
- What if vertices have different interventional costs?
- What if we intervene  $>1$  vertex per intervention?
- Can we weaken/remove some causal assumptions?

# Some of our relevant papers

Choo, Shiragur, Bhattacharyya. **Verification and search algorithms for causal DAGs.** NeurIPS 2022.

Choo, Shiragur. **Subset verification and search algorithms for causal DAGs.** AISTATS 2023.

Choo, Gouleakis, Bhattacharyya. **Active causal structure learning with advice.** Submitted to ICML 2023. Under review.

Choo, Shiragur. **New metrics and search algorithms for weighted causal DAGs.** Submitted to ICML 2023. Under review.

Choo, Shiragur. **Adaptivity Complexity for Causal Graph Discovery.** Submitted to UAI 2023. Under review.



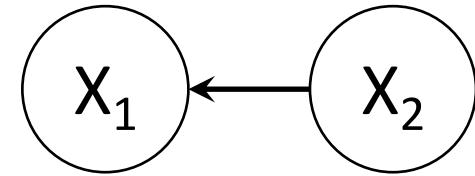
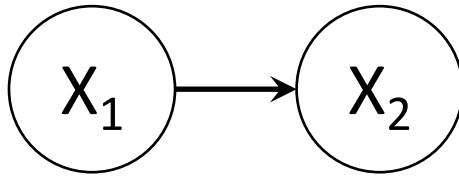
# History about causal inference (5min)

- David Hume (early 18<sup>th</sup> century)
- Judea pearl
- Smoking, Fisher
- Etc
- Oil is bad. Then suddenly say oil is not bad, it's sugar
- Correlation versus causation
- PICTURES
- Sell the past

# Causal graphical models

- Application: Gene regulatory network
- Some story
- Why do we care
- Broad challenge
- One way to model: Graphical modelling
- Sell the future

# Two equivalent causal models

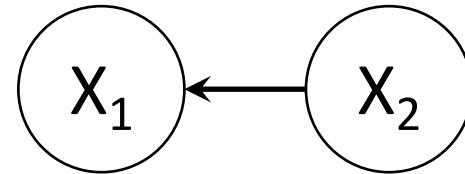
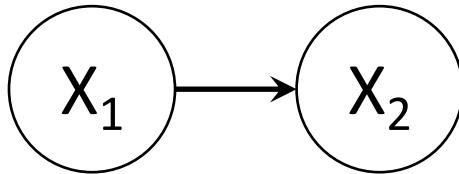


- $X_1 \leftarrow N(0,1)$
- $X_2 \leftarrow X_1$

- $X_2 \leftarrow N(0,1)$
- $X_1 \leftarrow X_2$

Data from both are fully characterized by covariance matrix  $\begin{bmatrix} 1 & 1 \\ 1 & 2 \end{bmatrix}$

# Two equivalent causal models



- $X_1 = \epsilon_1$
  - $X_2 = a \cdot X_1 + \epsilon_2$
  - $\epsilon_1 \sim N(0, 1)$
  - $\epsilon_2 \sim N(0, 1)$
- $X_1 = \frac{a}{a^2+1} \cdot X_2 + \epsilon_1$
  - $X_2 = \epsilon_2$
  - $\epsilon_1 \sim N\left(0, \frac{1}{a^2+1}\right)$
  - $\epsilon_2 \sim N(0, a^2 + 1)$

Data from both are fully characterized by covariance matrix  $\begin{bmatrix} 1 & a \\ a & a^2 + 1 \end{bmatrix}$

# Two equivalent causal models

- $X_1 \sim \mathcal{N}(0, 1)$
- $X_2 \sim \mathcal{N}(0, 1)$
- $\epsilon_1 \sim \mathcal{N}(0, 1)$
- $\epsilon_2 \sim \mathcal{N}(0, 1)$

1. Make more assumptions

OR

1. Perform interventions

Data from

$$\begin{bmatrix} a \\ a^2 + 1 \end{bmatrix}$$

# The problem of structure learning

- Broad challenge
- Debugging cloud micro-services
- Causal bandits

# What is studied in causality?

- Judea Pearl
- Blah blah
- In this talk, we focus on the problem of structure learning

# Why structure learning?

- Broad challenge
- Debugging cloud micro-services
- Causal bandits

# Intervention example in gene regulatory network

- CRISPR, nobel prize
- Perturb-seq
- Pull up numbers
  - about interventions is costly
  - Way more observational data than interventions

# Adaptivity

Contrast non-adaptive versus adaptive

e.g. finding a number in a sorted array

# To explain why is it difficult

Say what people have tried

Say what we have

-----

Keep the talk light-hearted

Increase humor in slides

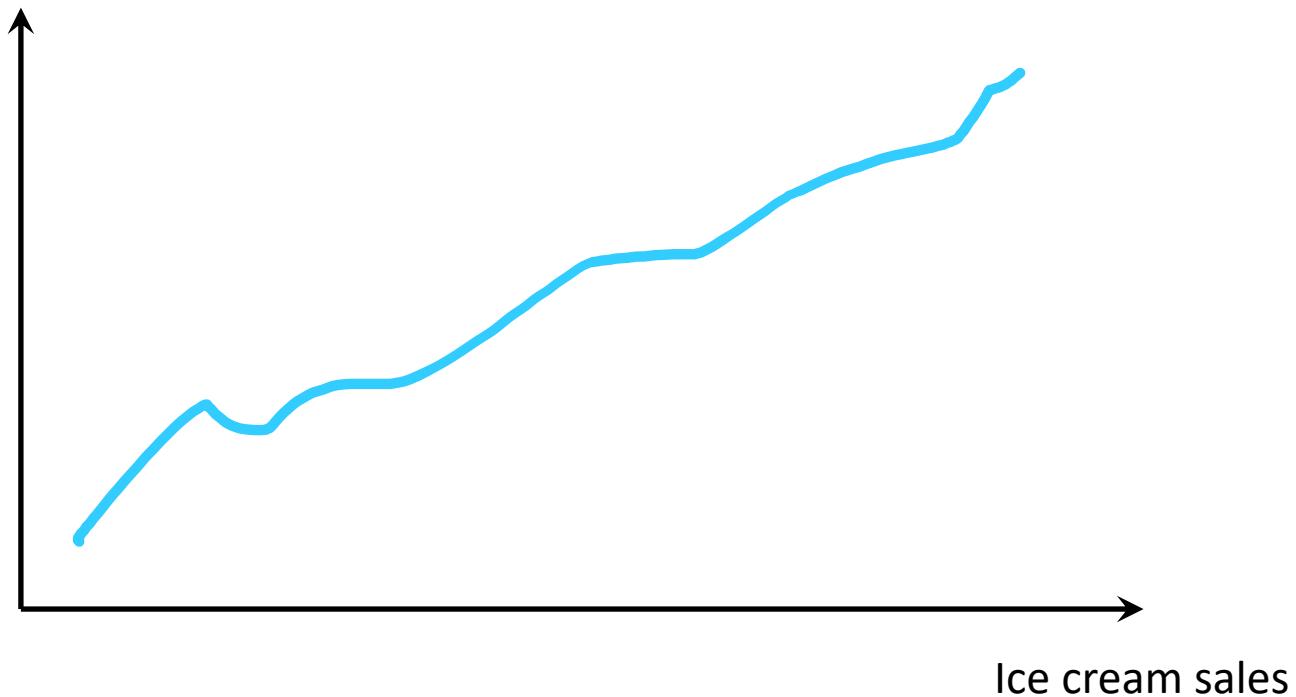
Relate to open house / NUS / Singapore

# Causal graphical models

- Talk only about search results
- Only say “compete against an algorithm that KNOWS the ground truth”. Don’t even define verification number
- Say that the problem becomes super hard if we allow non-uniform costs

# Correlation is not causation

Deaths by shark attacks



# Correlation is not causation

Deaths by shark attacks



**STOP ICE CREAM SALES!**



**RELEASE THE SHARKS!**



Ice cream sales

Suppose we are given some data and we want to discover causal relationships between them

	$X_1$	$X_2$	$X_3$	$X_4$	$X_5$	$X_6$
Sample 1	0.22	0.04	0.84	0.48	0.98	0.82
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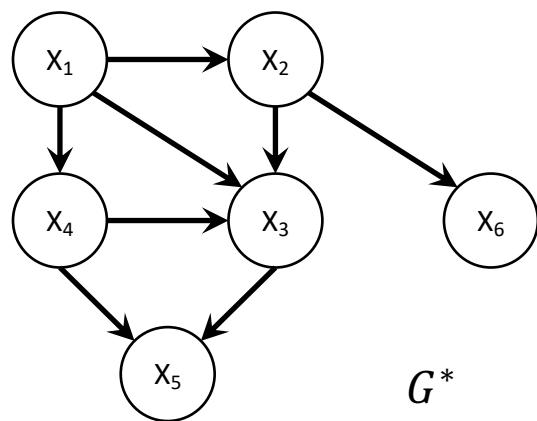
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<b>Genetics</b>	Gene 1	Gene 2	Gene 3	Gene 4	Gene 5	Gene 6
<b>Finance</b>	AAPL	GOOGL	MSFT	AMZN	META	TSLA
...	...	...	...	...	...	...
<b>Health care</b>	Diet	Exercise	Weight	Blood pressure	Blood glucose	Cholesterol levels

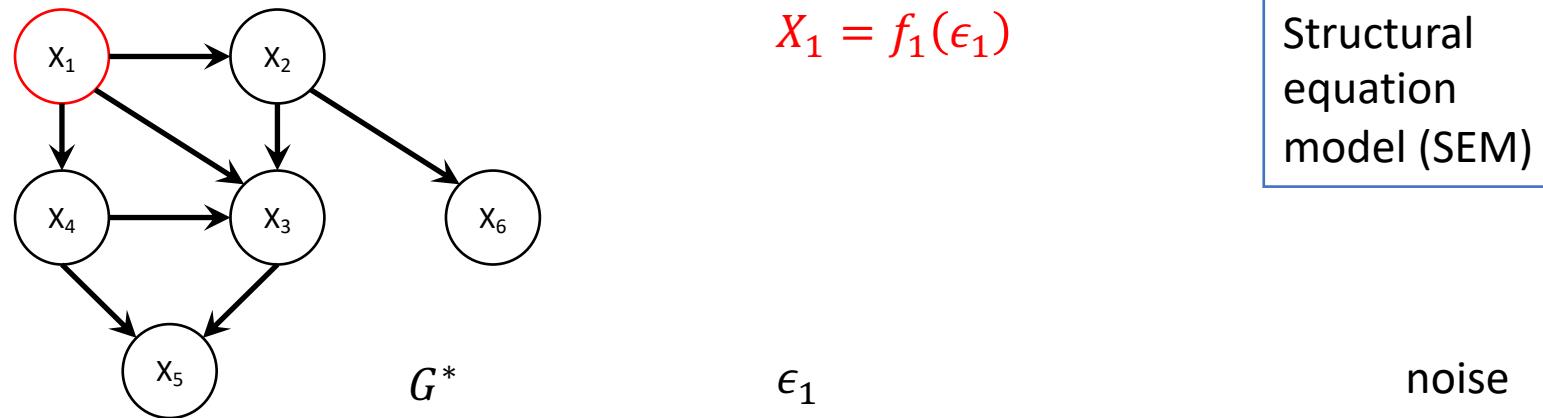
# One possible way: use graphical modelling

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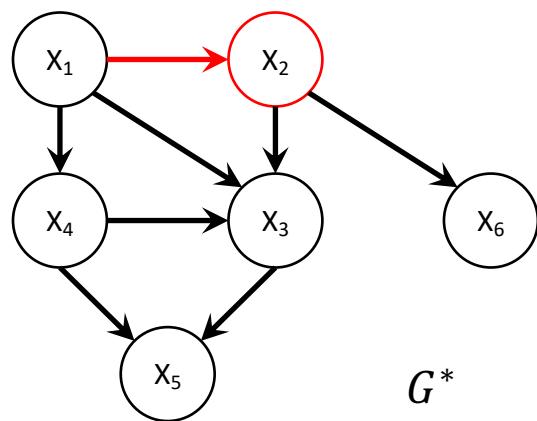
# A directed acyclic graphs (DAG) representation

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$$X_1 = f_1(\epsilon_1)$$
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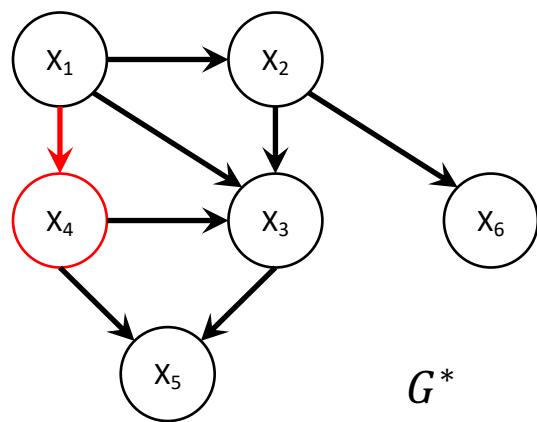
Structural  
equation  
model (SEM)

$\epsilon_1, \epsilon_2,$

independent noise

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$$X_1 = f_1(\epsilon_1)$$
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$$X_4 = f_4(X_1, \epsilon_4)$$

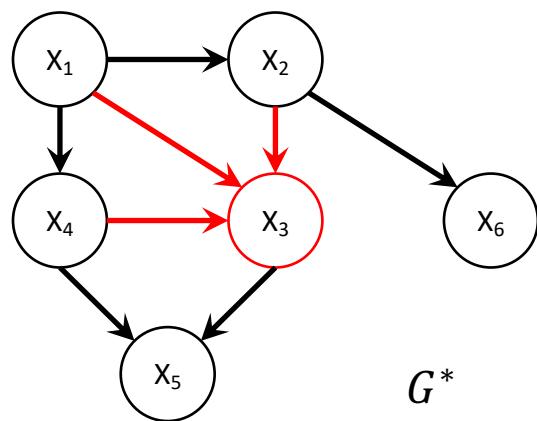
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$$\begin{aligned}X_1 &= f_1(\epsilon_1) \\X_2 &= f_2(X_1, \epsilon_2) \\X_3 &= f_3(X_1, X_2, X_4, \epsilon_3) \\X_4 &= f_4(X_1, \epsilon_4)\end{aligned}$$

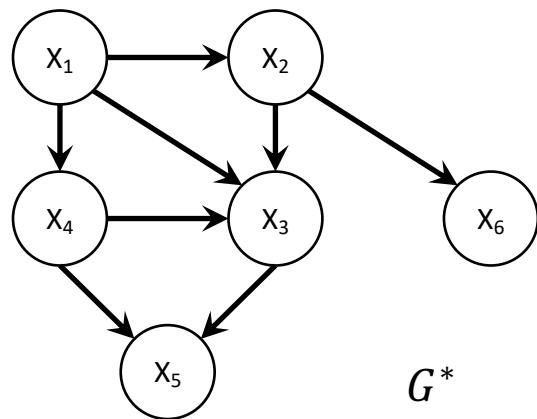
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$\epsilon_1, \epsilon_2, \epsilon_3, \epsilon_4$

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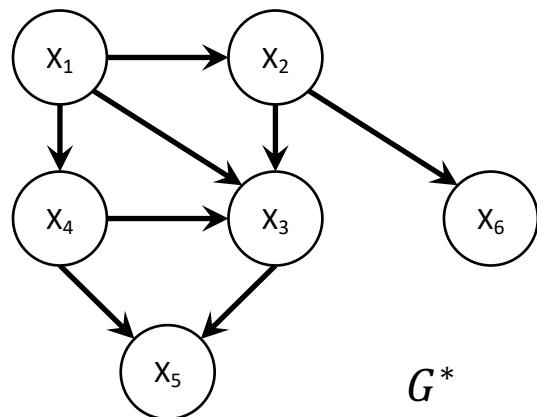


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 \epsilon_1, \epsilon_2, \epsilon_3, \epsilon_4, \epsilon_5, \epsilon_6 &\text{ independent noise}
 \end{aligned}$$

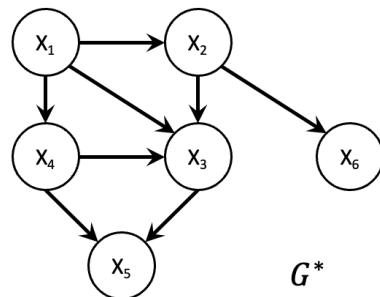
Structural equation model (SEM)

Using the Bayesian network, one can decompose the joint distribution as follows:

$$\Pr[X_1] \cdot \Pr[X_2 | X_1] \cdot \Pr[X_4 | X_1] \cdot \Pr[X_3 | X_1, X_2, X_4] \cdot \Pr[X_5 | X_3, X_4] \cdot \Pr[X_6 | X_2]$$

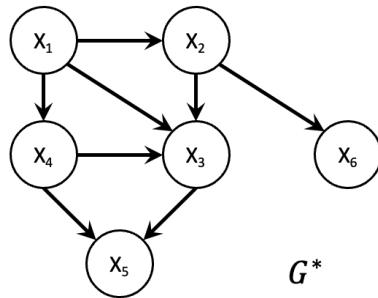
# Conditional independence (CI) tests

- A standard way (under some causal assumptions) to recover graph structure from data is to perform CI tests
  - e.g. PC (Peter-Clark) algorithm [Spirtes, Glymour, Scheines, Heckerman 2000]



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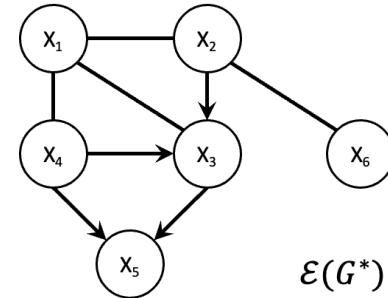
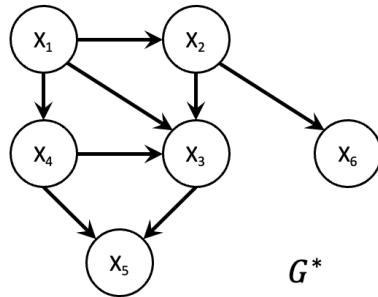
$G^*$



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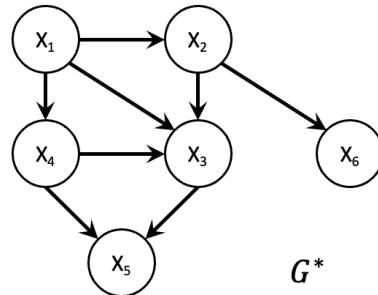
Get samples

	X <sub>1</sub>	X <sub>2</sub>	X <sub>3</sub>	X <sub>4</sub>	X <sub>5</sub>	X <sub>6</sub>
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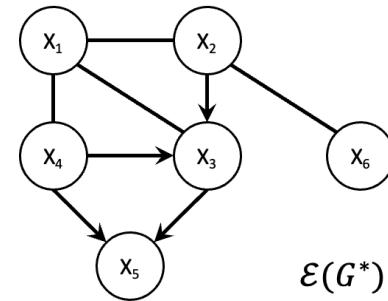
- Do CI tests
- Recover skeleton
  - Orient *some* edges

# Conditional independence (CI) tests

- A standard way (under some causal assumptions) to recover graph structure from data is to perform CI tests
  - e.g. PC (Peter-Clark) algorithm [Spirtes, Glymour, Scheines, Heckerman 2000]



$G^*$



$\mathcal{E}(G^*)$

(Recover up to an equivalence class)

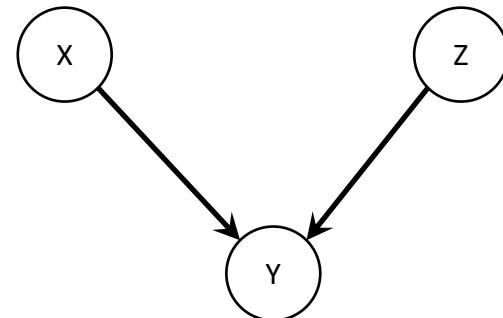
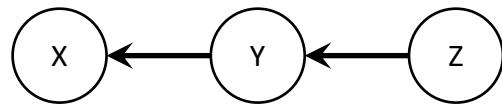
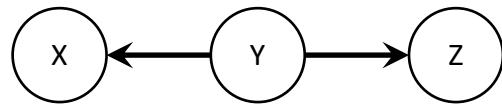
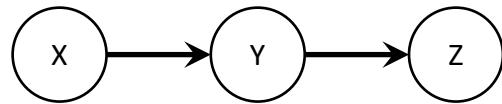
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Do CI tests

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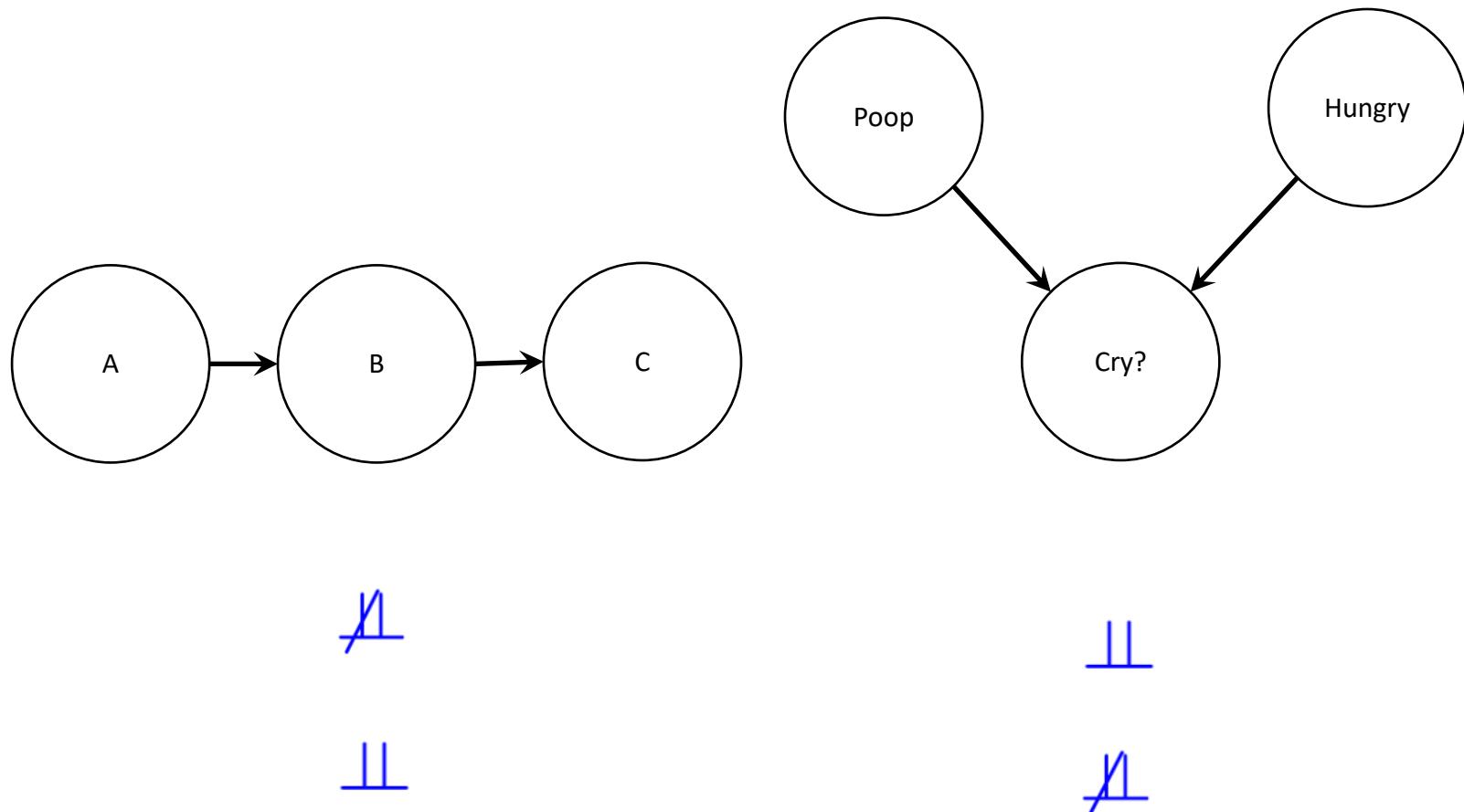
# Unshielded colliders / v-structures



$X \perp\!\!\!\perp Y$   
 $X \perp\!\!\!\perp Z$   
 $Y \perp\!\!\!\perp Z$   
 $X \perp\!\!\!\perp Y \mid Z$   
 $X \perp\!\!\!\perp Z \mid Y$   
 $Y \perp\!\!\!\perp Z \mid X$

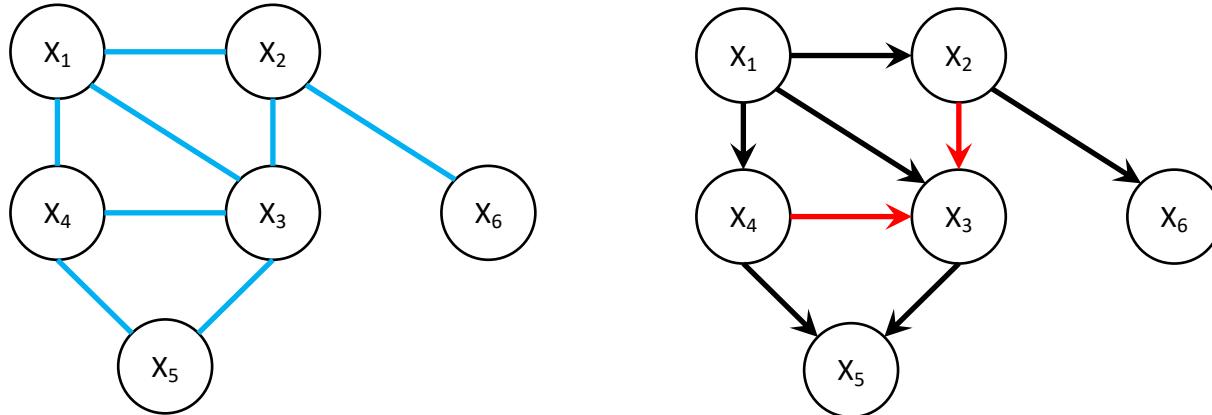
$X \perp\!\!\!\perp Y$   
 $X \perp\!\!\!\perp Z$   
 $Y \perp\!\!\!\perp Z$   
 $X \perp\!\!\!\perp Y \mid Z$   
 $X \perp\!\!\!\perp Z \mid Y$   
 $Y \perp\!\!\!\perp Z \mid X$

# Example



# Markov Equivalence Class (MEC)

- Two DAGs are Markov equivalent if they encode the same CI relations
- **skeleton** and **v-structures** of DAG  $G^*$  earlier



- **Theorem** [Verma, Pearl 1990; Andersson, Madigan, Perlman 1997]  
G and G' are Markov equivalent **if and only if**
  - 1) G and G' have the same skeleton
  - 2) G and G' have the same v-structures
- For any DAG  $G^*$ , we use  $[G^*]$  to denote its MEC

# Essential graphs $\mathcal{E}(G^*)$

- Used to graphically represent a MEC  $[G^*]$
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  - $X \sim Y$  is unoriented arc if there **exists** disagreement
    - $\exists G_1, G_2 \in [G^*]$  in MEC such that  $X \rightarrow Y$  in  $G_1$  and  $X \leftarrow Y$  in  $G_2$ .

# Essential graphs $\mathcal{E}(G^*)$

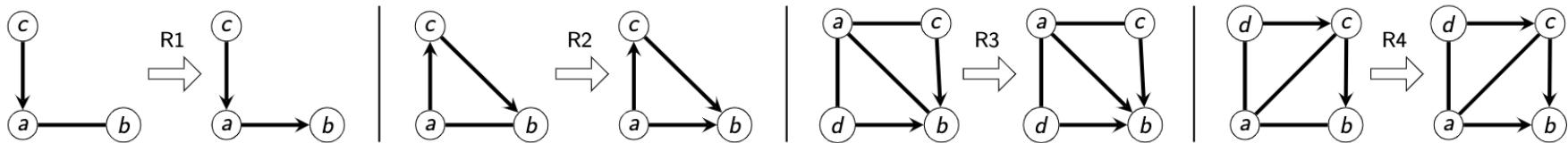
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    - $\exists G_1, G_2 \in [G^*]$  in MEC such that  $X \rightarrow Y$  in  $G_1$  and  $X \leftarrow Y$  in  $G_2$ .
- How to compute essential graph  $\mathcal{E}(G^*)$  of  $G^*$ ?
  1. Look at skeleton of  $G^*$
  2. Orient v-structures in  $G^*$
  3. Apply Meek rules [Meek 1995]

# Meek rules

[Meek 1995]

- **Sound and complete**

(with respect to arc orientations with acyclic completion)



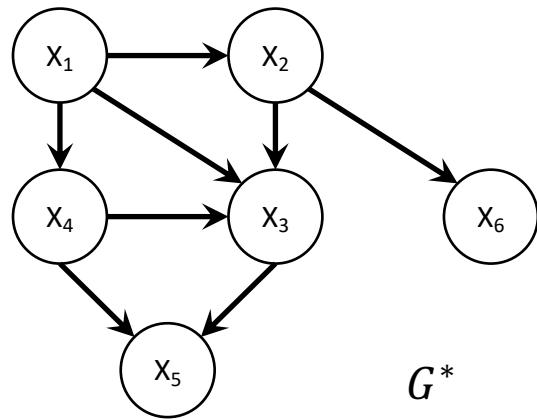
If  $b \leftarrow a$ ,  
then v-structure

If  $b \leftarrow a$ ,  
then cycle

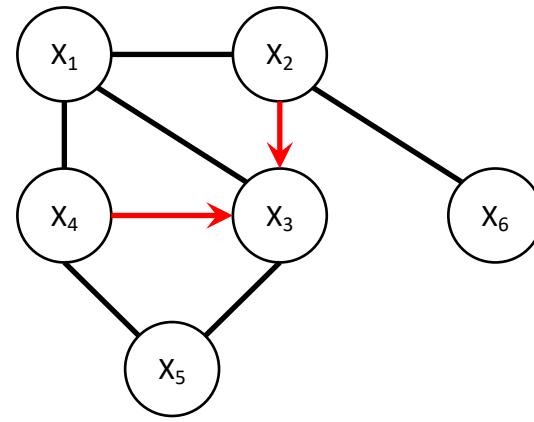
If  $b \leftarrow a$ , then unoriented arcs would  
have been oriented **in the same way** in  
all DAGs within the MEC (via R2)

- Converge in polynomial time [Wienöbst, Bannach, Liśkiewicz 2021]

# Essential graph example

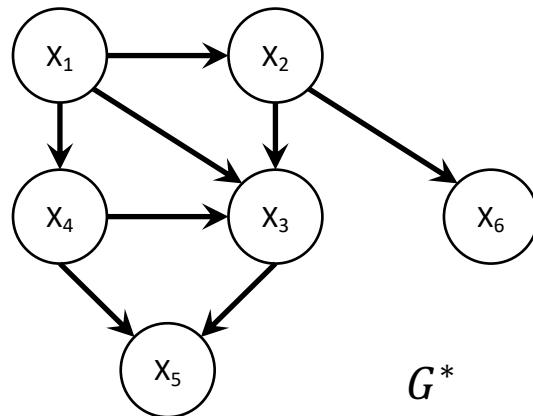


$G^*$

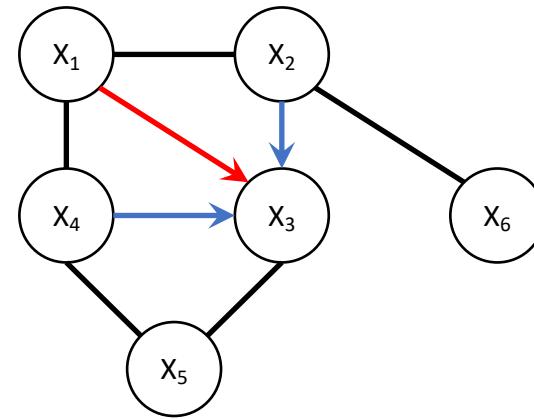


- Use CI tests: recover skeleton and v-structures

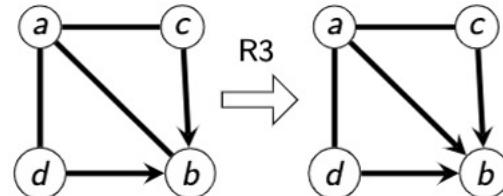
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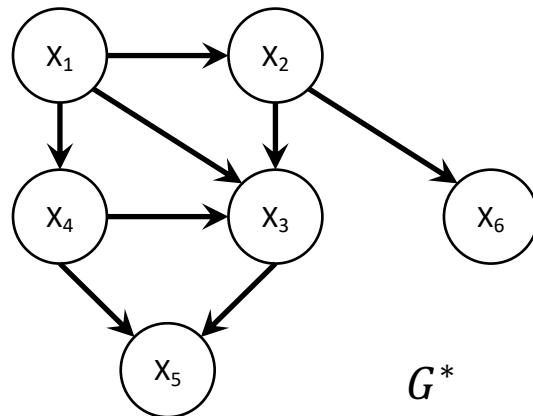
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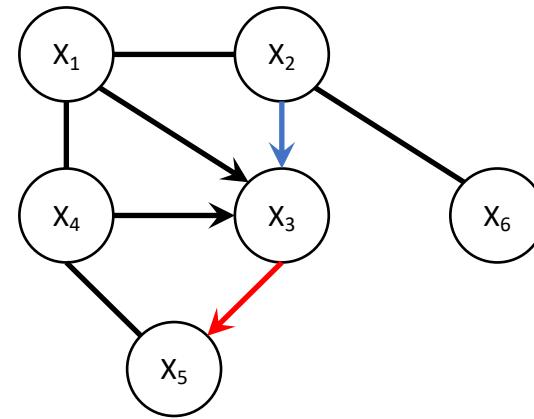
- Use CI tests: recover skeleton and v-structures
- Meek R3



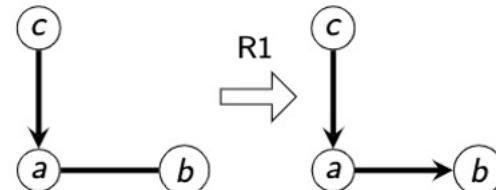
# Essential graph example



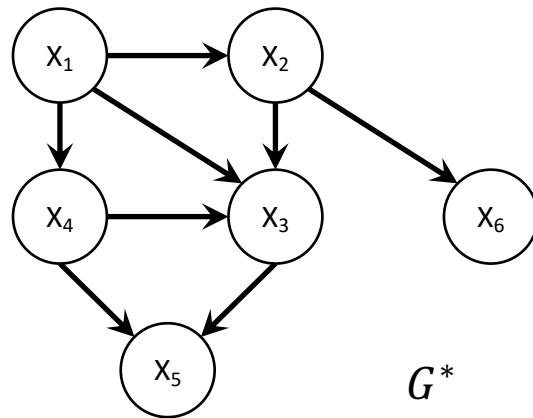
$G^*$



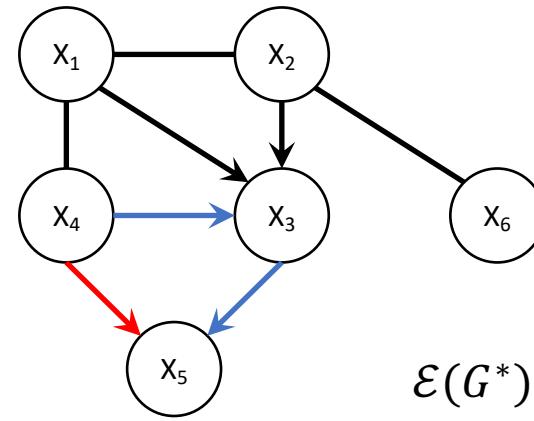
- Use CI tests: recover skeleton and v-structures
- Meek R3
- Meek R1



# Essential graph example

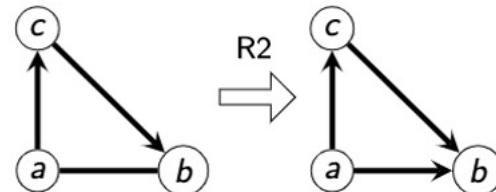


$G^*$

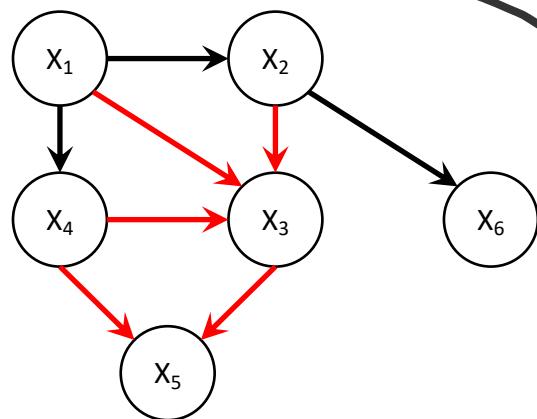


$\mathcal{E}(G^*)$

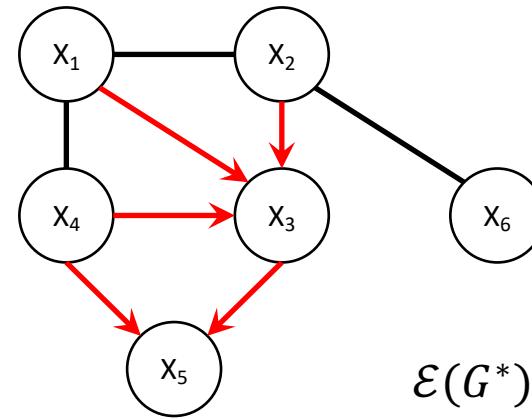
- Use CI tests: recover skeleton and v-structures
- Meek R3
- Meek R1
- Meek R2



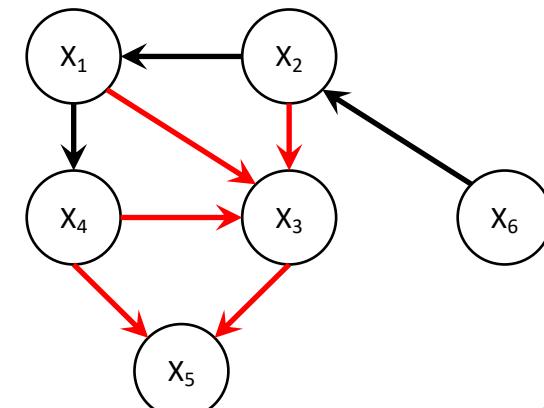
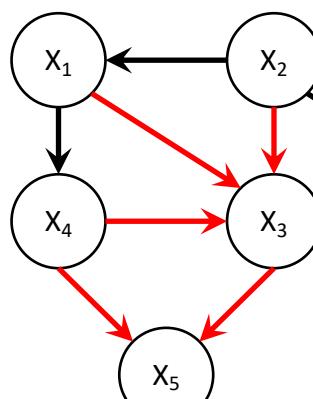
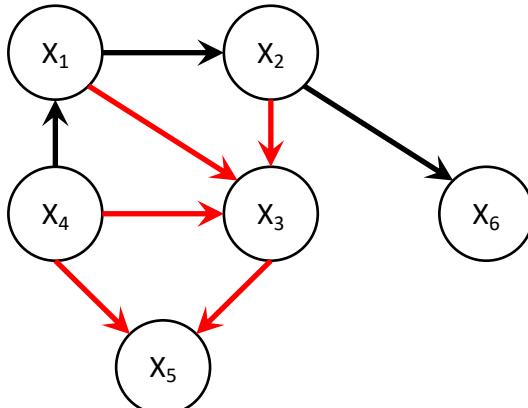
# Essential graph example



$[G^*]$



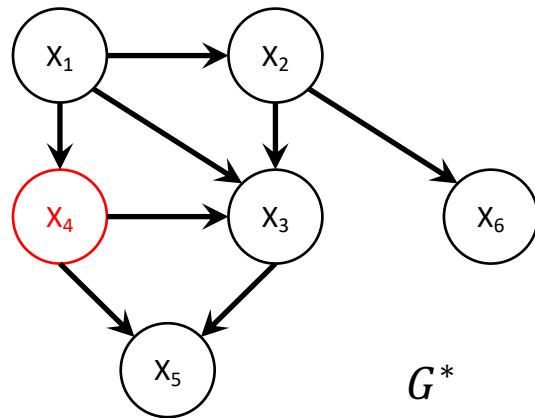
$\mathcal{E}(G^*)$



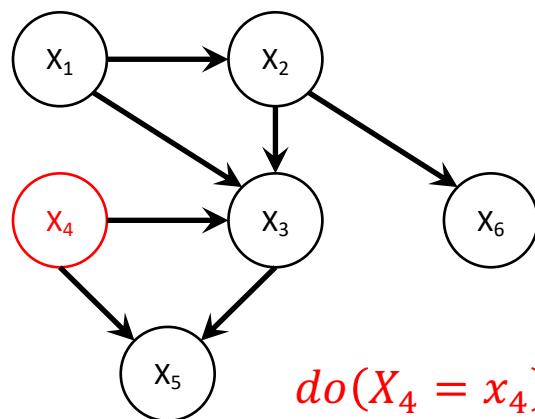
# For this talk...

- Some standard causal assumptions
  - Causal sufficiency
  - Faithfulness
  - Can identify conditional independencies from data
- Simplifying assumptions for this talk
  - Atomic intervention: One vertex per intervention
  - Each vertex has unit cost
- Objective
  - Minimize total number of vertices intervened

# Hard interventions

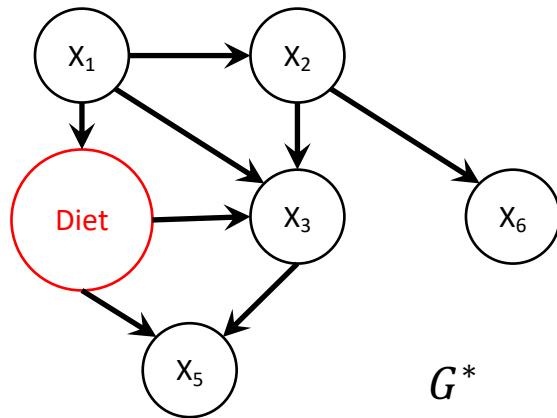


$$\begin{aligned}X_1 &= f_1(\epsilon_1) \\ X_2 &= f_2(X_1, \epsilon_2) \\ X_3 &= f_3(X_1, X_2, X_4, \epsilon_3) \\ X_4 &= f_4(X_1, \epsilon_4) \\ X_5 &= f_5(X_3, X_4, \epsilon_5) \\ X_6 &= f_6(X_2, \epsilon_6) \\ \epsilon_1, \epsilon_2, \epsilon_3, \epsilon_4, \epsilon_5, \epsilon_6 &\text{ independent noise}\end{aligned}$$

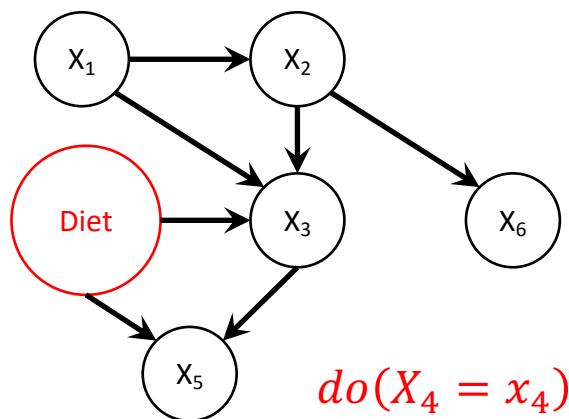


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# What can we learn from data and hard interventions?

- Essential
- Skeleton
- V-structures
- Meek rules
- Property about chordal graph

# Meek rules [Meek 1995] (Example)

- Look at path. Explain R1
- Look at clique. Explain R2

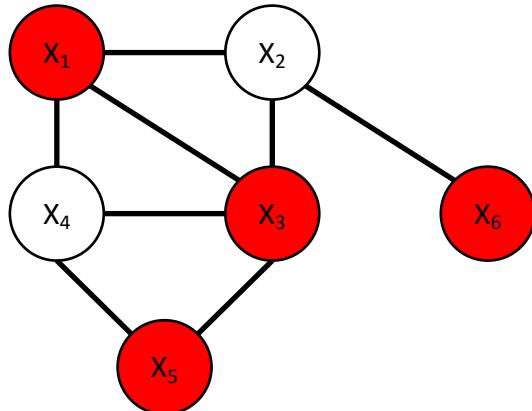
# Two classes of interventions

- Non-adaptive
  - Given MEC  $[G^*]$ , decide on a single fixed set of interventions that recovers *any possible*  $G^* \in [G^*]$
  - Need to intervene on a *G-separating system*  
[Kocaoglu, Dimakis, Vishwanath 2017]
- Adaptive
  - Given MEC  $[G^*]$ ,
    - Decide on first intervention
    - See outcome
    - Decide on second intervention
    - See outcome
    - ...

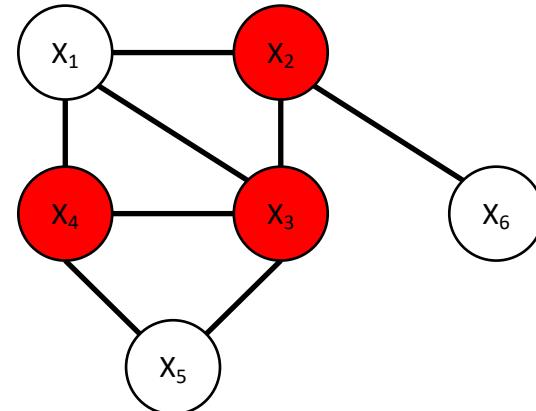
# G-separating system

[Kocaoglu, Dimakis, Vishwanath 2017]

- Fix an undirected graph  $G = (V, E)$
- A subset  $\mathcal{I} \subseteq 2^V$  is called a G-separating system if
  - For every edge  $\{u, v\} \in E$ ,  $\exists$  intervention  $I \in \mathcal{I}$  such that either  $(u \in I \wedge v \notin I)$  or  $(u \notin I \wedge v \in I)$
- For atomic interventions  $\Rightarrow$  vertex cover



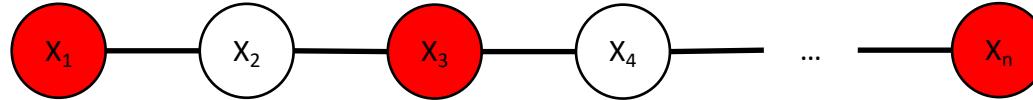
$$|\mathcal{I}| = 4$$



$$|\mathcal{I}| = 3$$

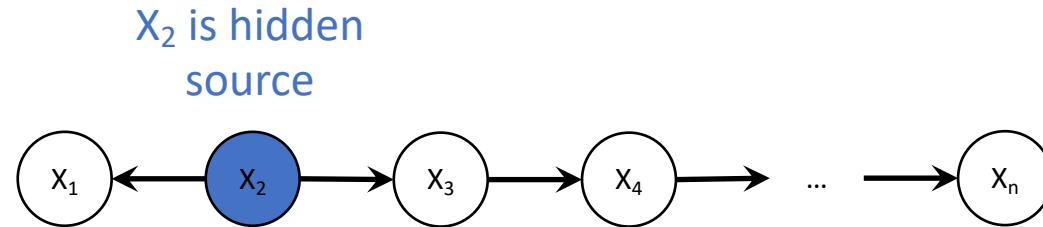
# Power of adaptivity

- Path essential graph
  - $n$  possible DAGs (pick a source node and orient away)
  - $G$ -separating system needs  $\geq \left\lfloor \frac{n}{2} \right\rfloor \in \Omega(n)$  vertices



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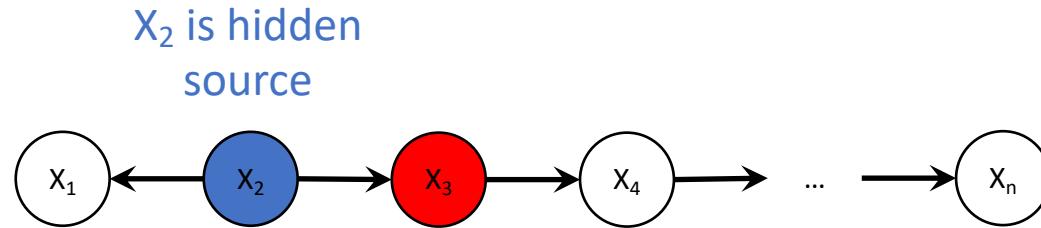
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- Meanwhile, adaptive search can act like binary search!  
i.e. only  $\mathcal{O}(\log n)$  interventions required

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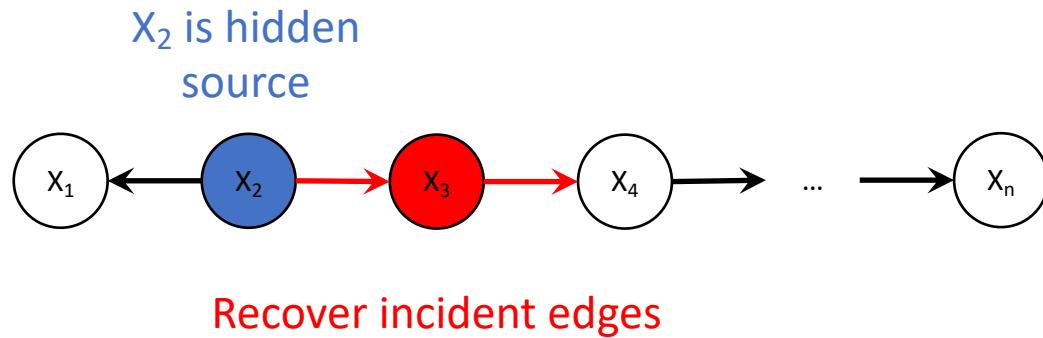
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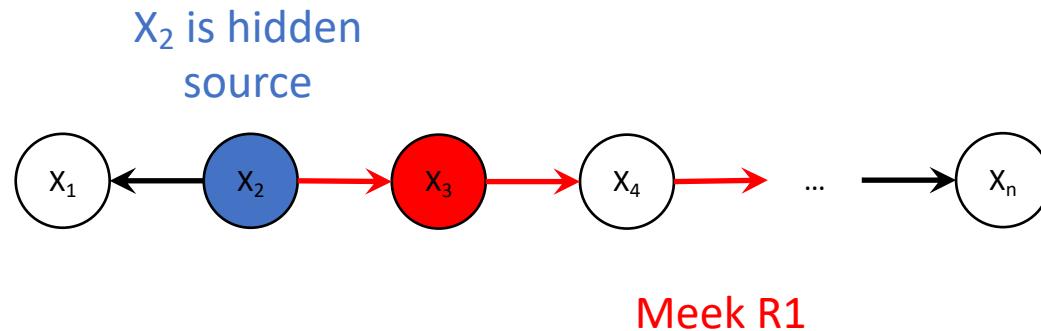
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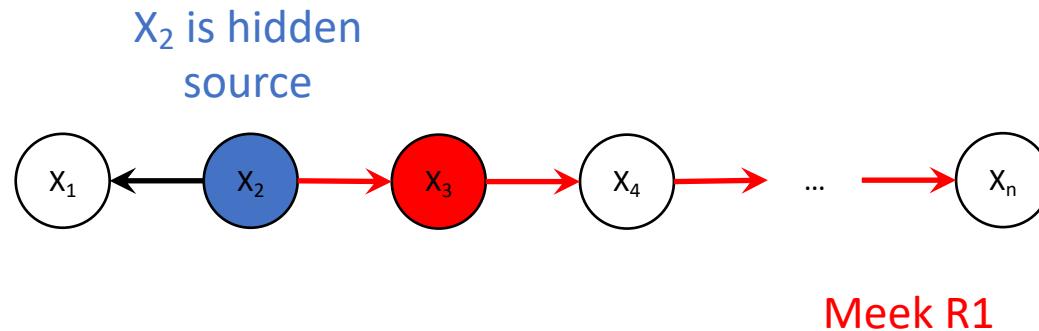
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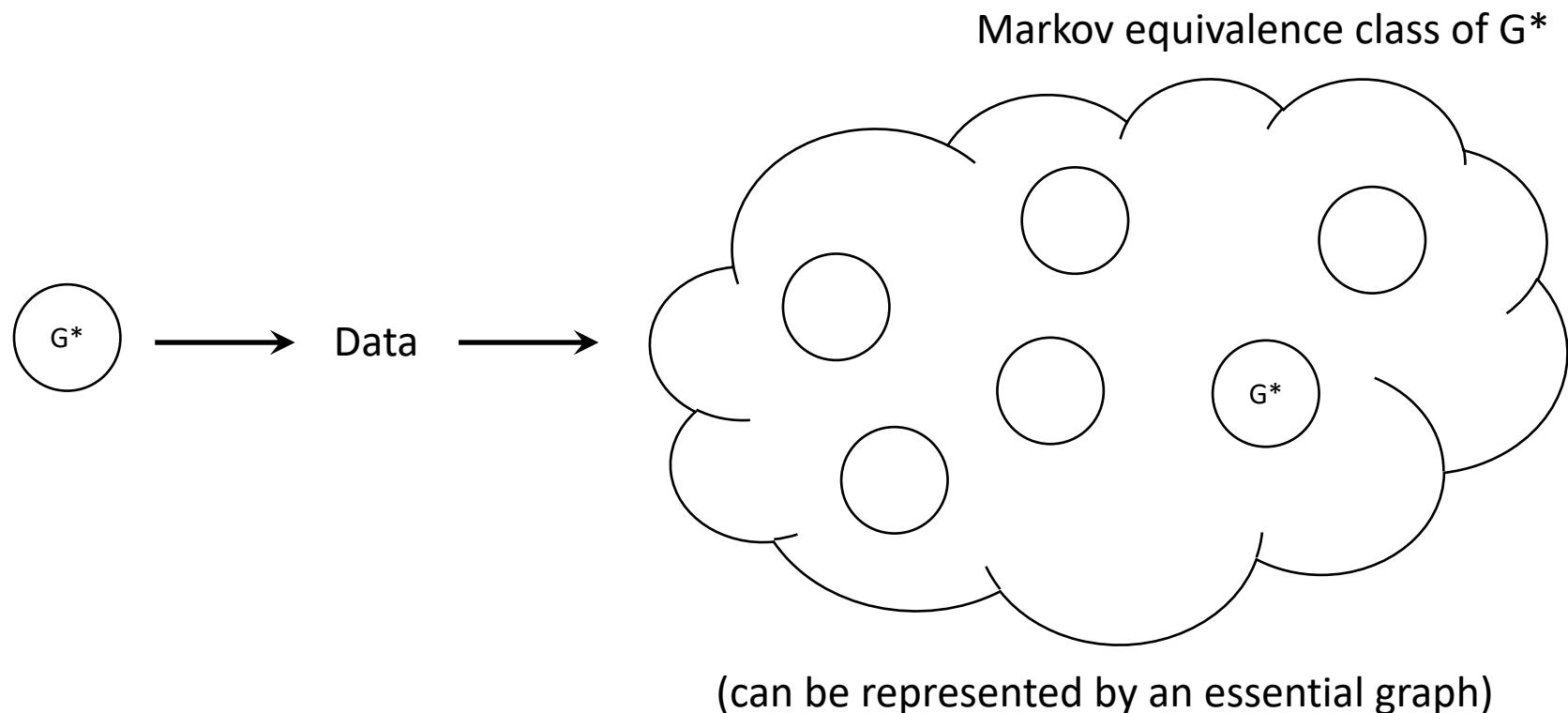
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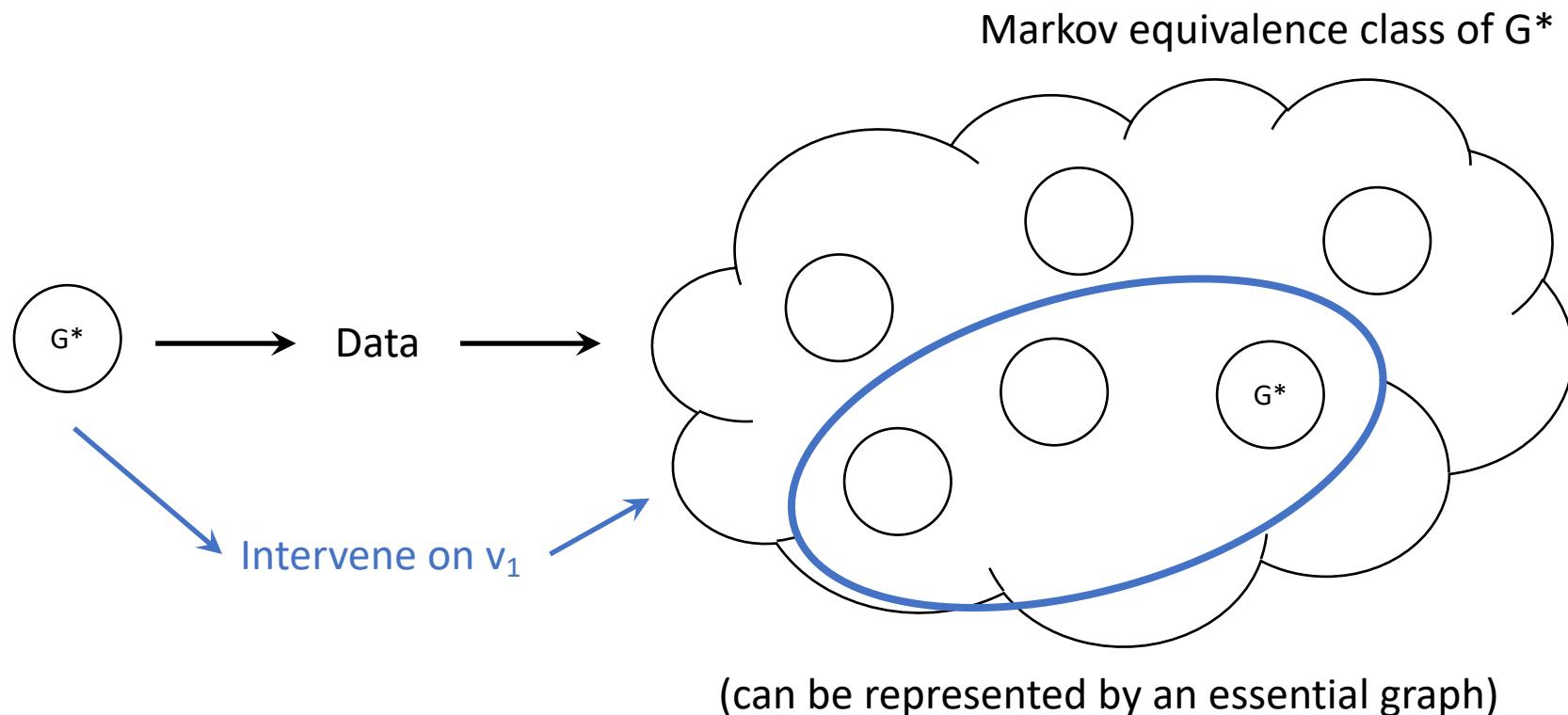
# Problem setup

Identify  $G^*$



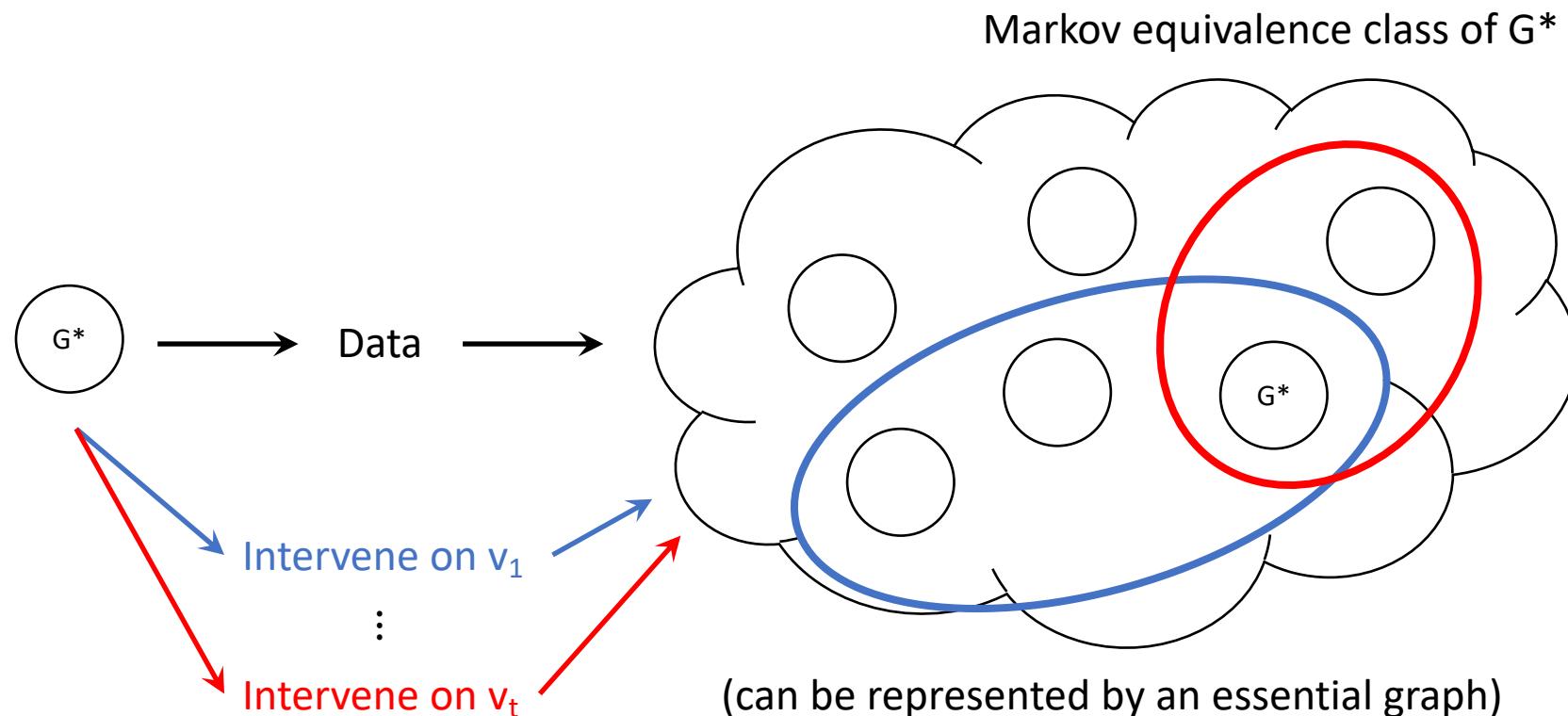
# Problem setup

Identify  $G^*$  using **interventions**



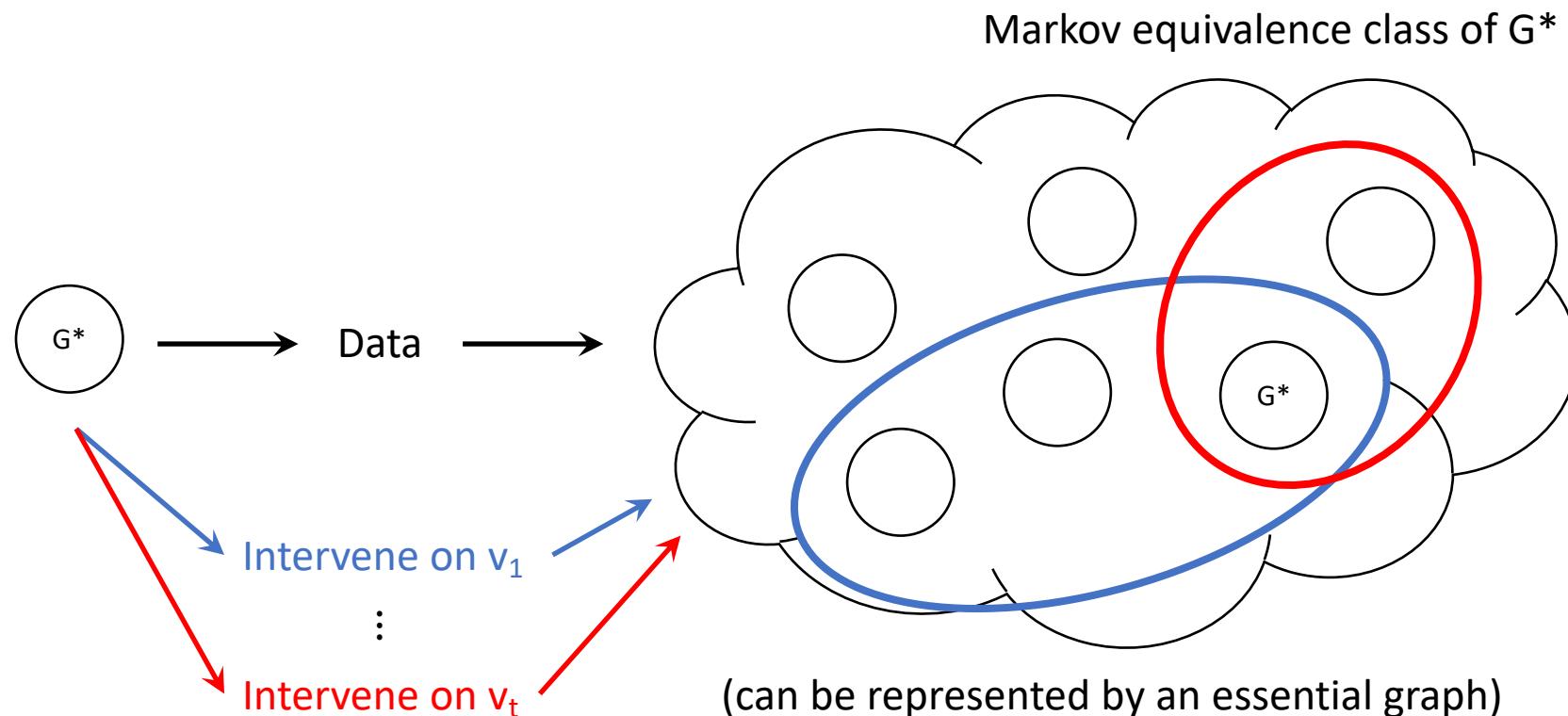
# Problem setup

Identify  $G^*$  using **interventions**



# Problem setup

Identify  $G^*$  using **as few interventions as possible** (minimize  $t$ )

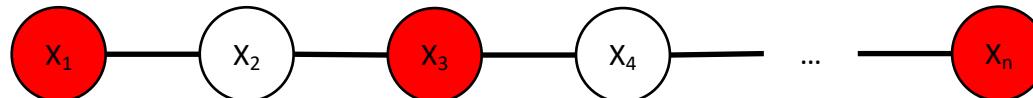


# The verification problem

- Given MEC  $[G^*]$  and some  $G \in [G^*]$ ,  
check whether  $G = G^*$  using interventions
  - Denote the minimum number required by  $\nu(G)$
  - $\nu(G^*)$  is **lower bound** for searching for  $G^*$  within  $[G^*]$

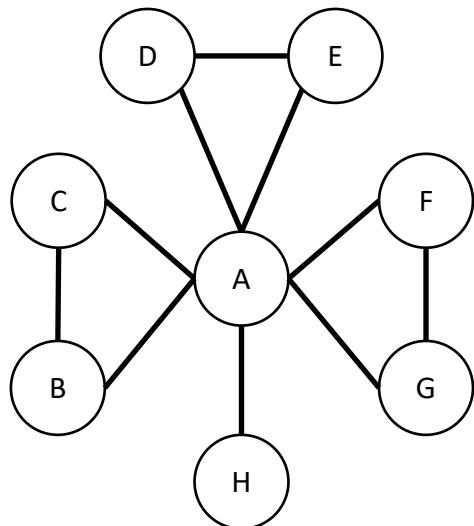
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  - $\nu(G^*)$  is **lower bound** for searching for  $G^*$  within  $[G^*]$
- Trivial solution
  - Compute minimum vertex cover on all unoriented arcs of the essential graph  $\mathcal{E}(G) = \mathcal{E}(G^*)$
  - Check if revealed orientations agree with  $G$
  - Worst case:  $\Omega(n)$  interventions, e.g. on a line



# What was known

- Maximal clique size
1.  $\nu(G) \geq \left\lfloor \frac{\omega(G)}{2} \right\rfloor$  [Squires, Magliacane, Greenewald, Katz, Kocaoglu, Shanmugam 2020]
2.  $\left\lceil \frac{n-r}{2} \right\rceil \leq \nu(G) \leq n-r$  Number of maximal cliques  
[Porwal, Srivastava, Sinha 2022]



$$n = 8, \omega(G) = 3, r = 4$$

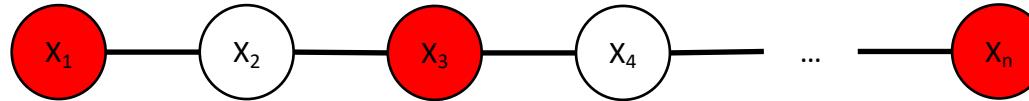
1.  $1 \leq \nu(G)$
2.  $2 \leq \nu(G) \leq 4$

MEC  $[G^*]$

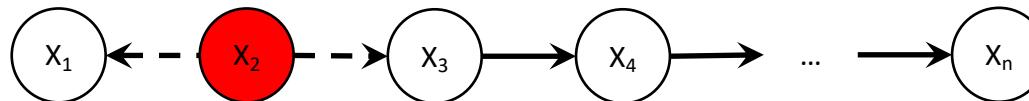
# Characterization via covered edges

- A set  $\mathcal{I} \subseteq V$  is a verifying set for DAG  $G = (V, E)$  if and only if  $\mathcal{I}$  is a **minimum vertex cover** of the **covered edges** [Chickering 1995] of  $G$ 
  - $u \sim v$  is covered edge if they share same parents

Naïve:



Our characterization:

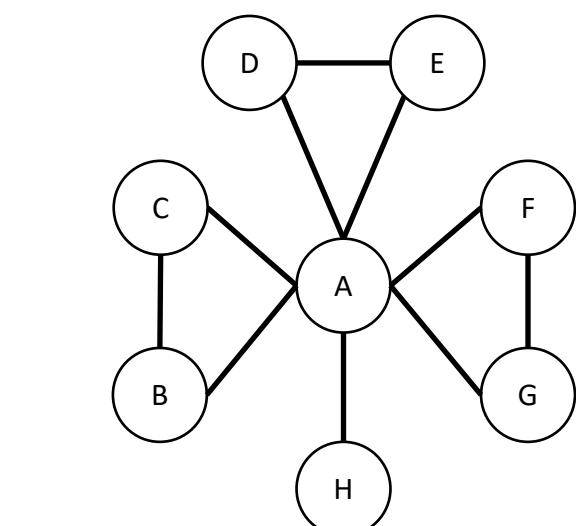


$X_2$  is source in G

# Comparison

$$1. \nu(G) \geq \left\lceil \frac{\omega(G)}{2} \right\rceil$$

$$2. \left\lceil \frac{n-r}{2} \right\rceil \leq \nu(G) \leq n-r$$



MEC  $[G^*]$

Maximal clique size

Number of maximal cliques

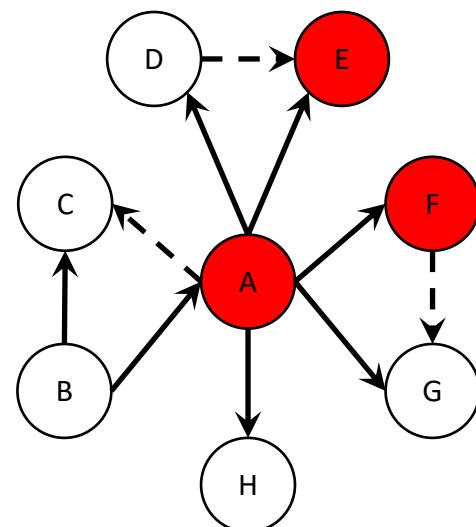
[SMG+20]

$n = 8, \omega(G) = 3, r = 4$

1.  $1 \leq \nu(G)$
2.  $2 \leq \nu(G) \leq 4$

We can compute  
**exact**  $\nu(G)$  for any  
given  $G \in [G^*]$

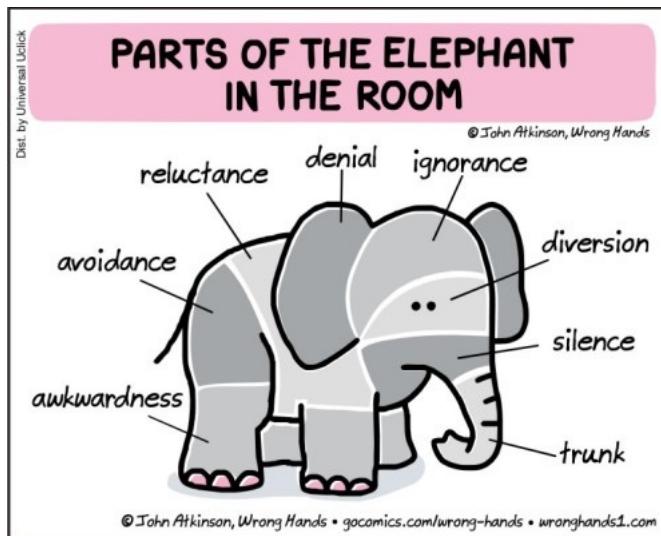
In fact,  $\nu(G) \in \{3,4\}$   
for any  $G \in [G^*]$



One possible DAG from  $[G^*]$

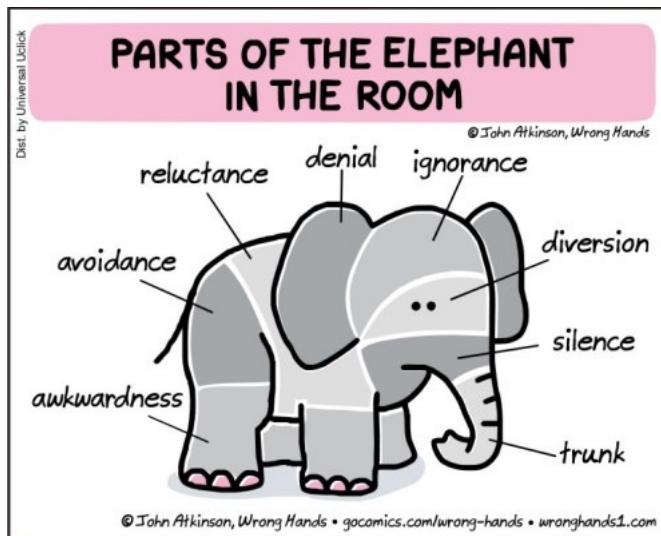
# Efficient computation

- Wait... minimum vertex cover is NP-hard in general!



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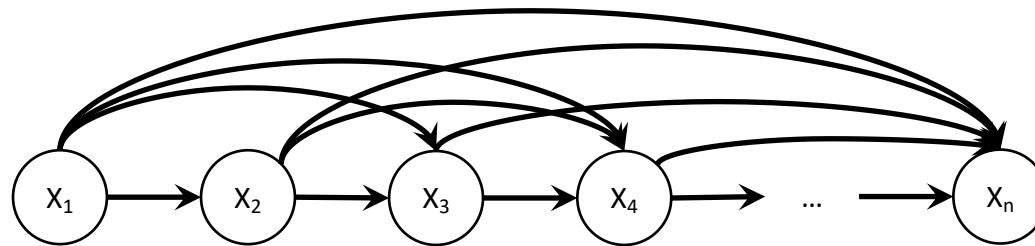
- Claim: Covered edges induce a forest
- Implication:  $\nu(G)$  can be computed **exactly** via DP

# Through the lens of covered edges

- Covered edges cannot have both endpoints as sink of any maximal clique, so  $\nu(G) \leq n - r$

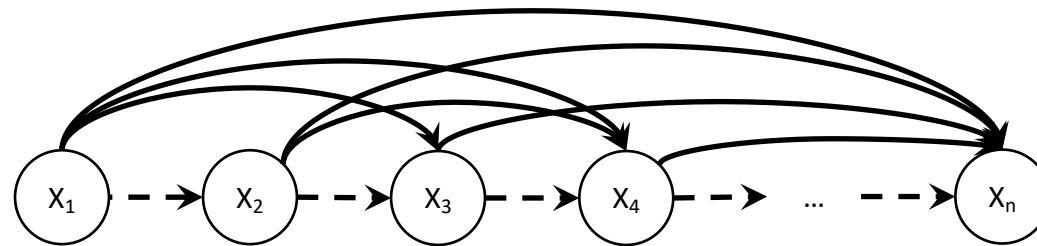
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- Covered edges cannot have both endpoints as sink of any maximal clique, so  $\nu(G) \leq n - r$
- $G$  is a clique  $\Rightarrow$  Prior work:  $\nu(G) = \left\lfloor \frac{n}{2} \right\rfloor$



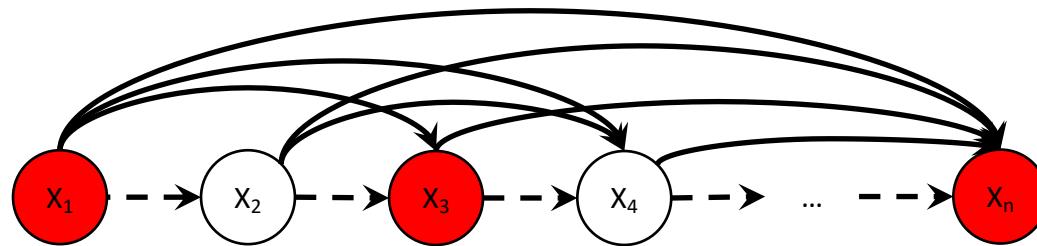
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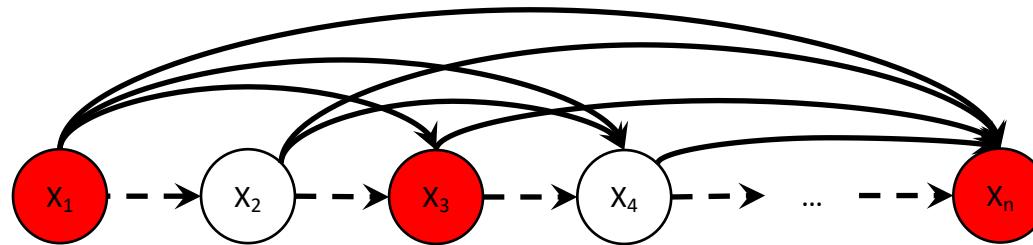
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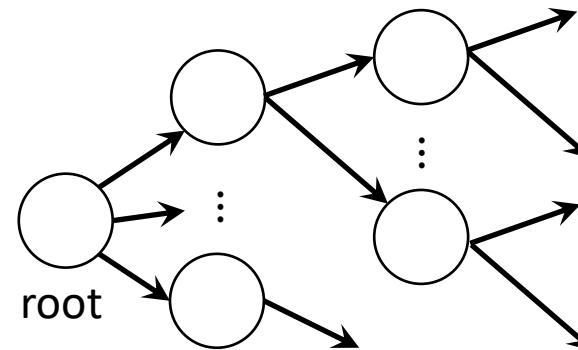


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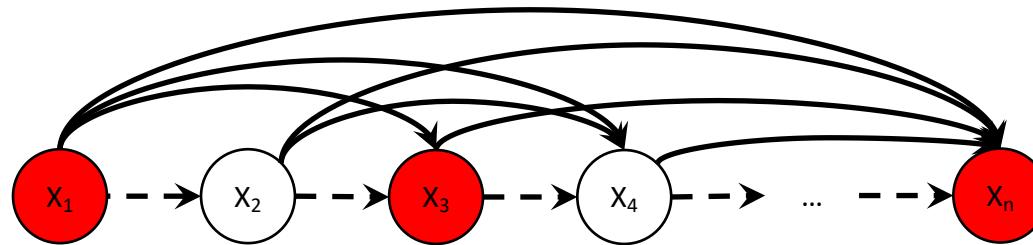


- $G$  is a tree  $\Rightarrow$   
Prior work:  $\nu(G) = 1$

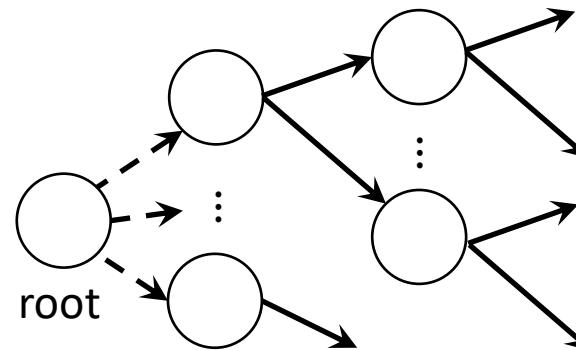


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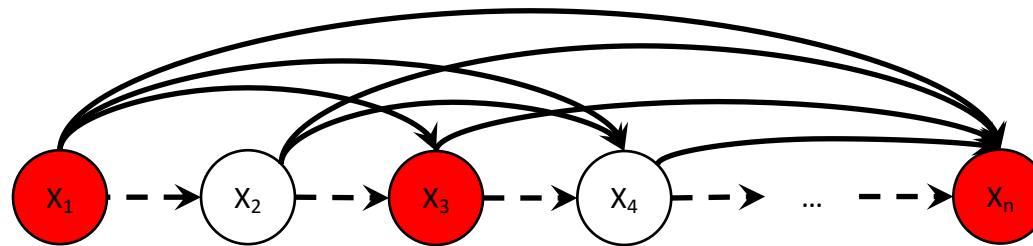


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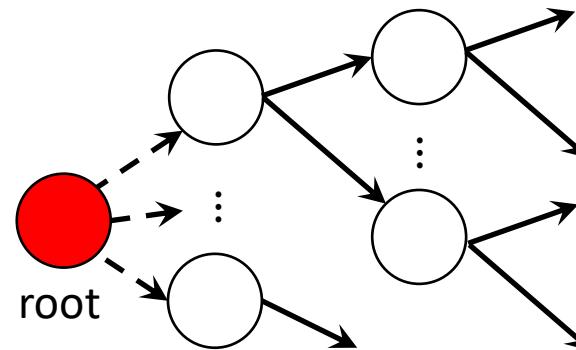


# Through the lens of covered edges

- Covered edges cannot have both endpoints as sink of any maximal clique, so  $\nu(G) \leq n - r$
- $G$  is a clique  $\Rightarrow$  Prior work:  $\nu(G) = \left\lfloor \frac{n}{2} \right\rfloor$



- $G$  is a tree  $\Rightarrow$   
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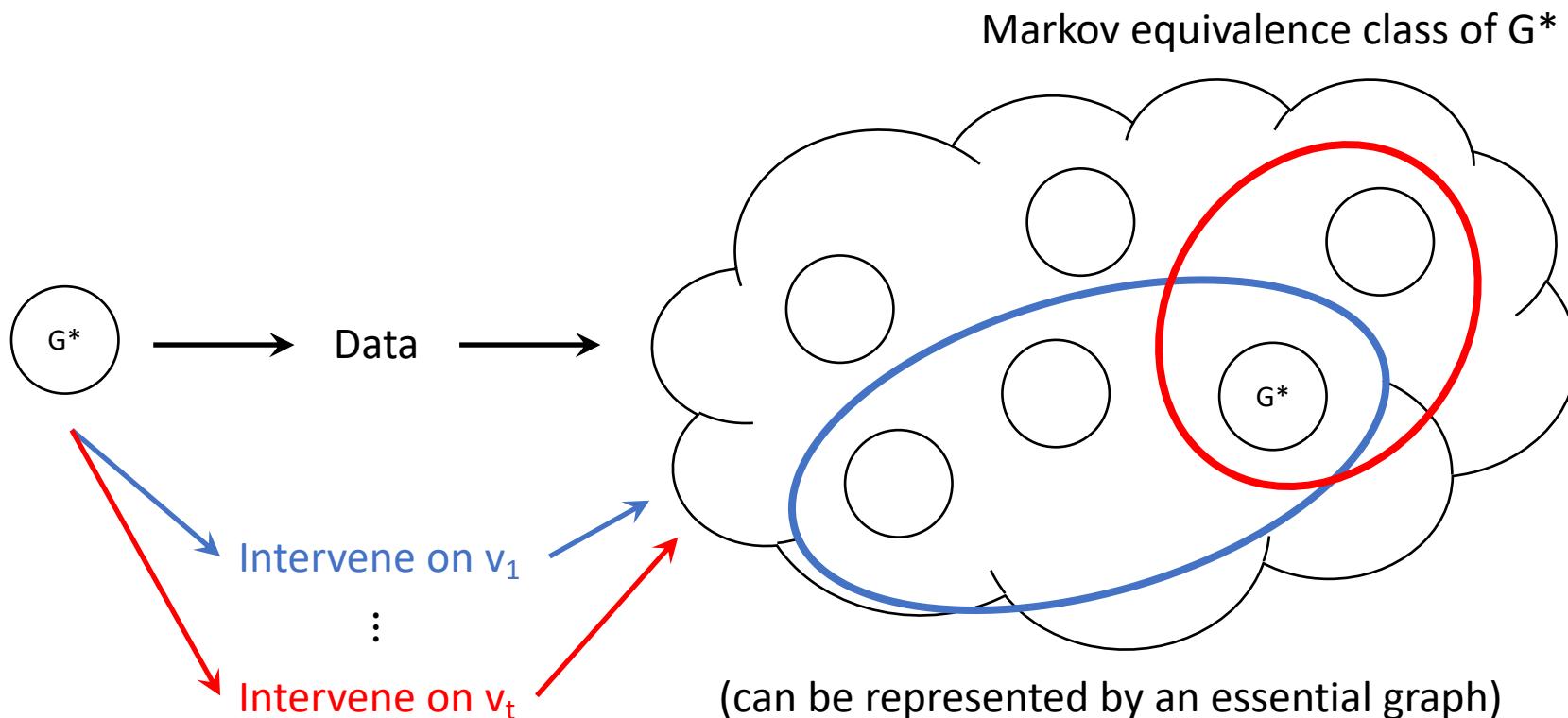
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  - Unoriented in  $\mathcal{E}(G^*) \Rightarrow$  Covered edge in *some*  $G \in [G^*]$
  - So, “non-adaptive must cut all unoriented in  $\mathcal{E}(G^*)$ ”, i.e. a G-separating system

# Problem setup

Identify  $G^*$  using **as few interventions as possible** (minimize  $t$ )



# The search problem

- Given MEC  $[G^*]$  and recover  $G^*$  using interventions
  - We know at least  $\nu(G^*)$  is necessary
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  - “Search is almost as easy as verification”
  - Algorithm does not even know what  $\nu(G^*)$  is!
  - $\Omega(\log n)$  is unavoidable when  $[G^*]$  is a path on  $n$  nodes
    - $\nu(G^*) = 1$
    - “Cannot do better than binary search”

# The adaptive search algorithm

- Intervene and remove oriented arcs  $\Rightarrow$  Chordal graph.  
Handle each connected component [Hauser, Bühlmann 2012, 2014]
- For any chordal graph  $G$ , one can compute in polynomial time a clique separator  $C$  [Gilbert, Rose, Edenbrandt 1984]

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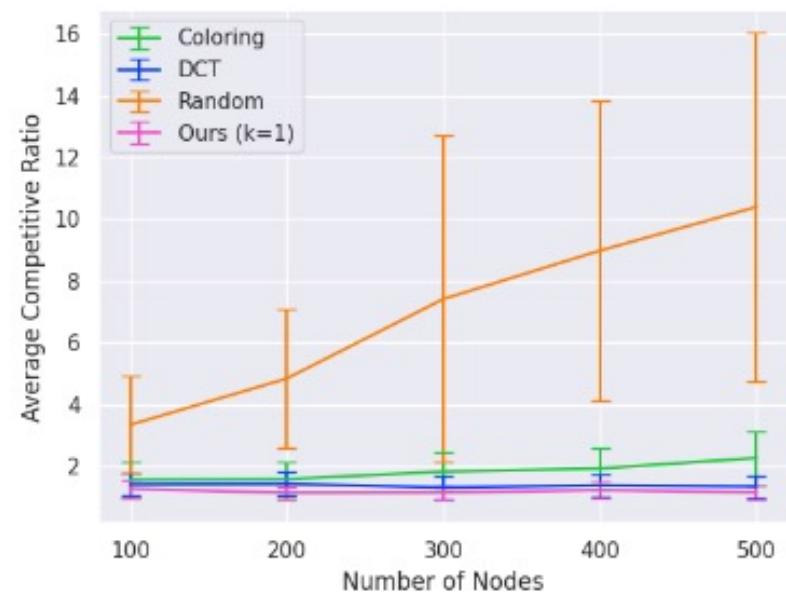
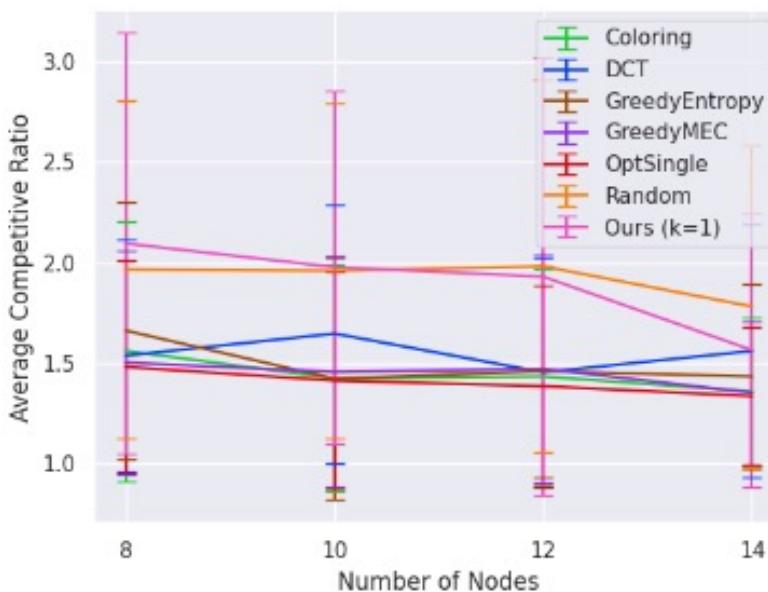
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- Algorithm: Find clique separator  $C_H$  in each component  $H$ ; Intervene on all nodes in  $C_H$ 's; Recurse
- Analysis:
  - $\mathcal{O}(\log n)$  rounds suffices  $\leftarrow$  [Gilbert, Rose, Edenbrandt 1984]
  - $\mathcal{O}(\nu(G^*))$  per round  $\leftarrow$  We prove new lower bound on  $\nu(G^*)$

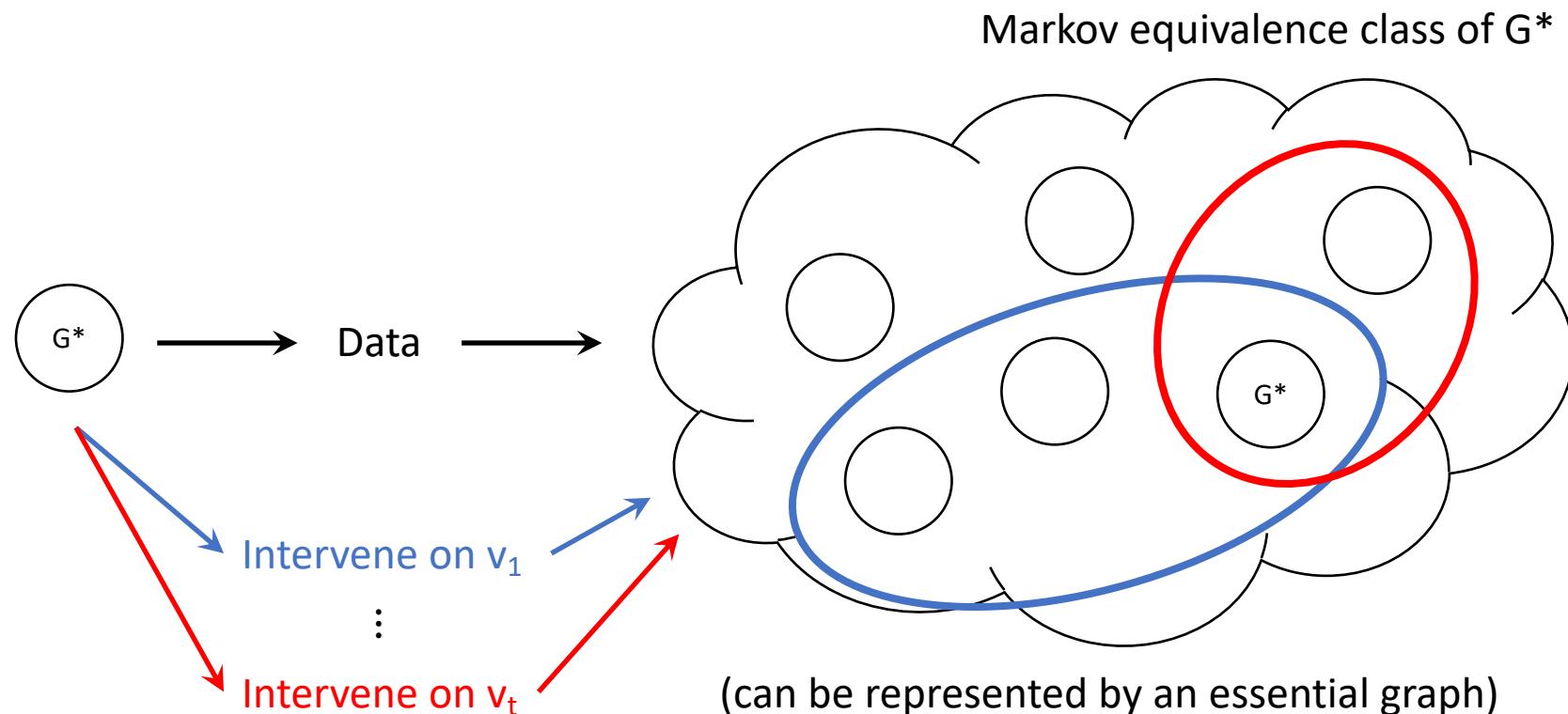
# The adaptive search algorithm

- Qualitatively, our algorithm is competitive with state-of-the-art adaptive search algorithms
  - We run  $\sim 10\times$  faster in some experiments



# Problem setup

Identify  $G^*$  using **as few interventions as possible** (minimize  $t$ )



**Verification:**  $\nu(G^*) = \text{size of minimum vertex cover of covered edges}$

[CSB22]

**Search:**  $\mathcal{O}(\log n \cdot \nu(G^*))$  interventions suffice

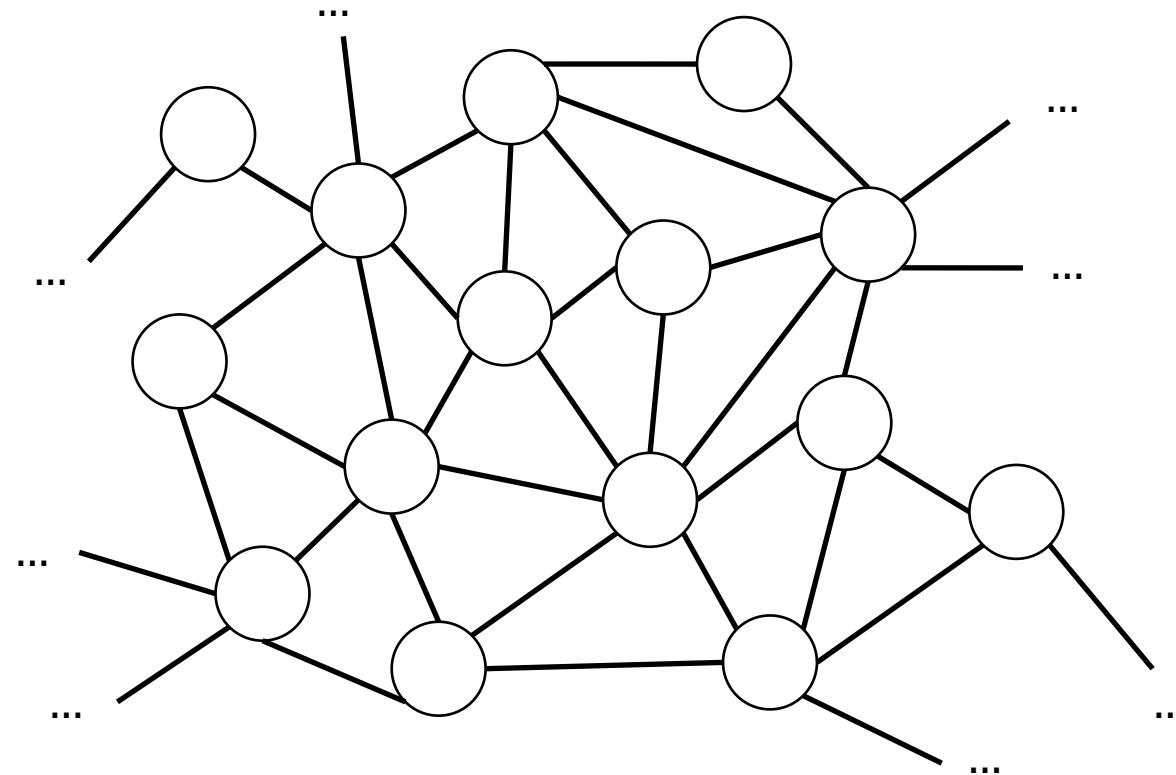
[CSB22]

But wait, there's more!

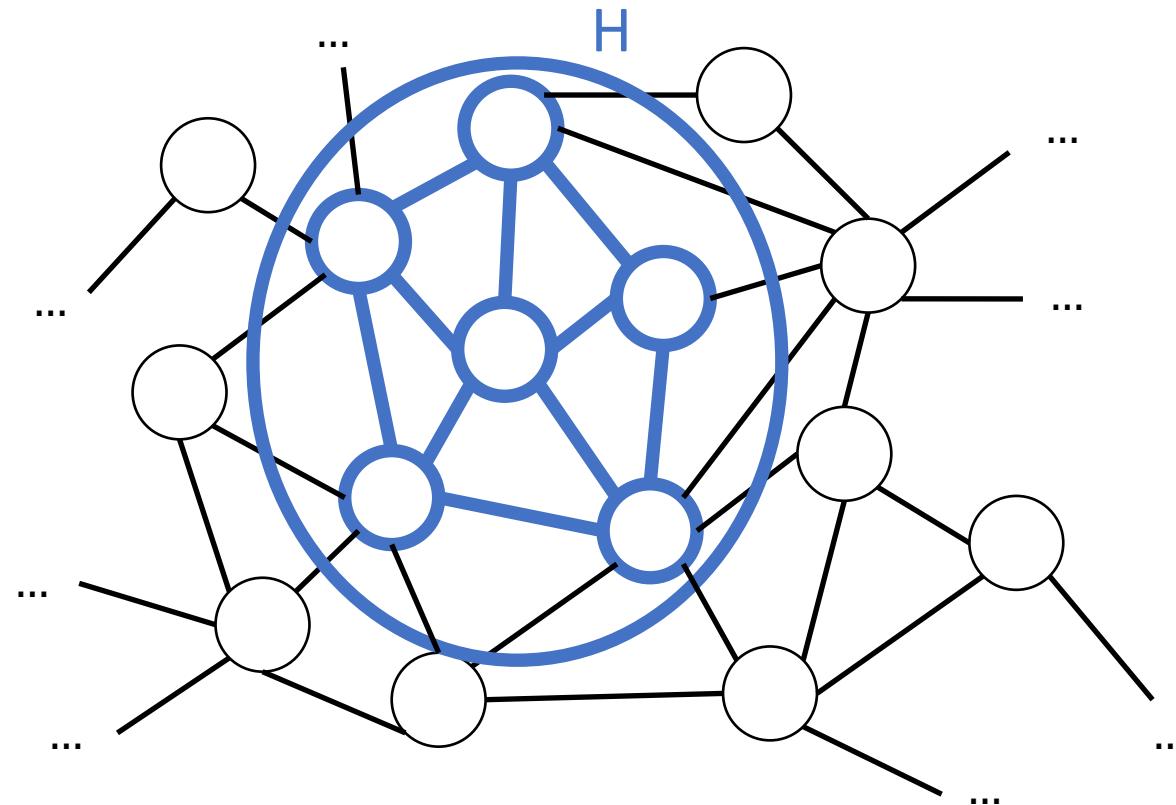
# Other extensions / questions

- What if the causal graph is HUGE?
- What if we consult domain experts for advice?
- What if we intervene >1 vertex per intervention?
  - Bounded size interventions
- What if vertices have different interventional costs?
  - Additive cost  $\Rightarrow$  cost of intervention is cost of all vertices in it
- What if we have limited rounds of adaptivity?
  - At most  $r$  rounds, for  $r < \log n$
- What if we have finite samples?
  - May incur error in conditional independence checks
- Can we weaken/remove the causal assumptions?
  - What if we don't have hard interventions? Soft/unknown interventions, etc
  - What if there are hidden confounders?
  - What if we don't have faithfulness?

# What if causal graph is HUGE?



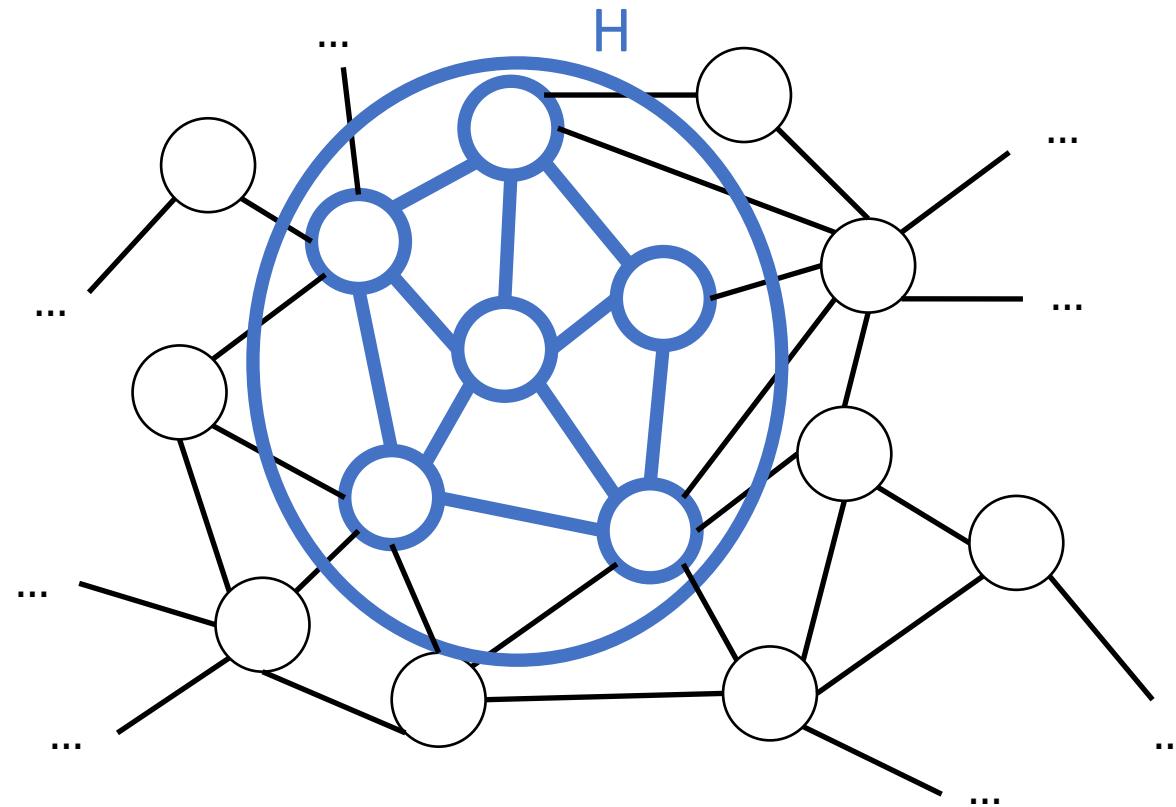
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**Local causal discovery:**

Only care about a small subgraph of the larger graph

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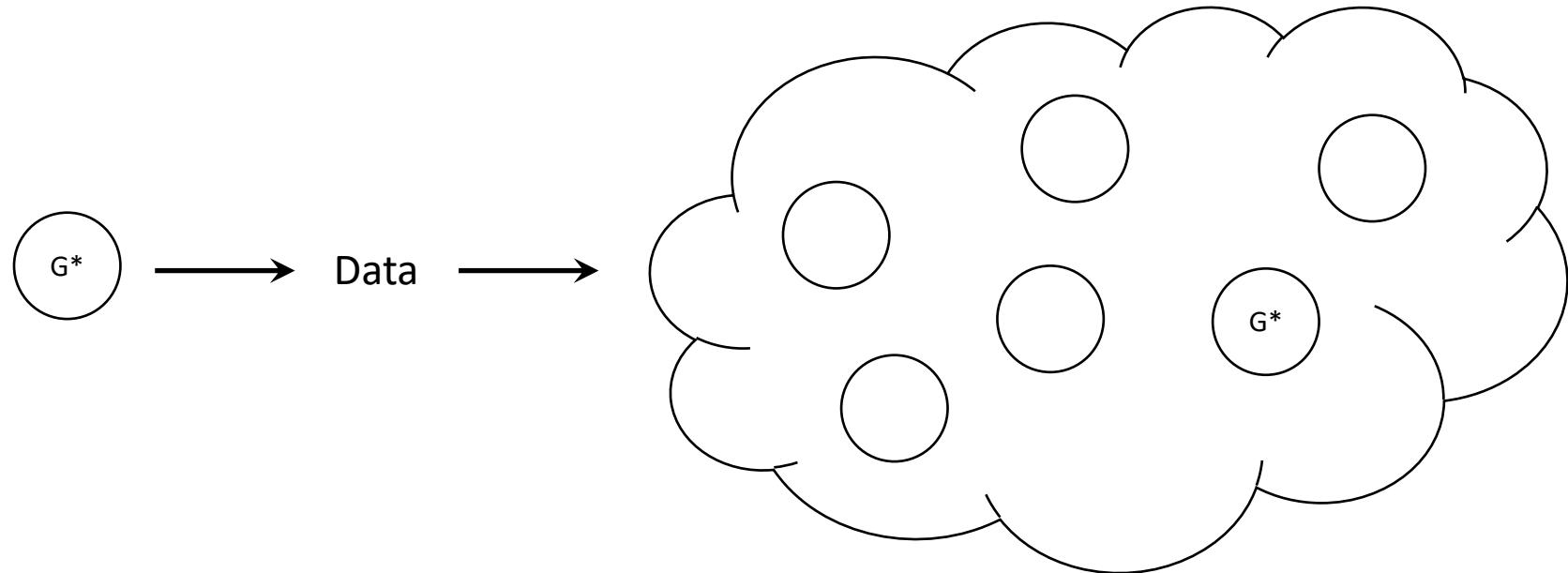
(Informal) Verification: Generalization of “DP on covered edge forest”

[CS23]

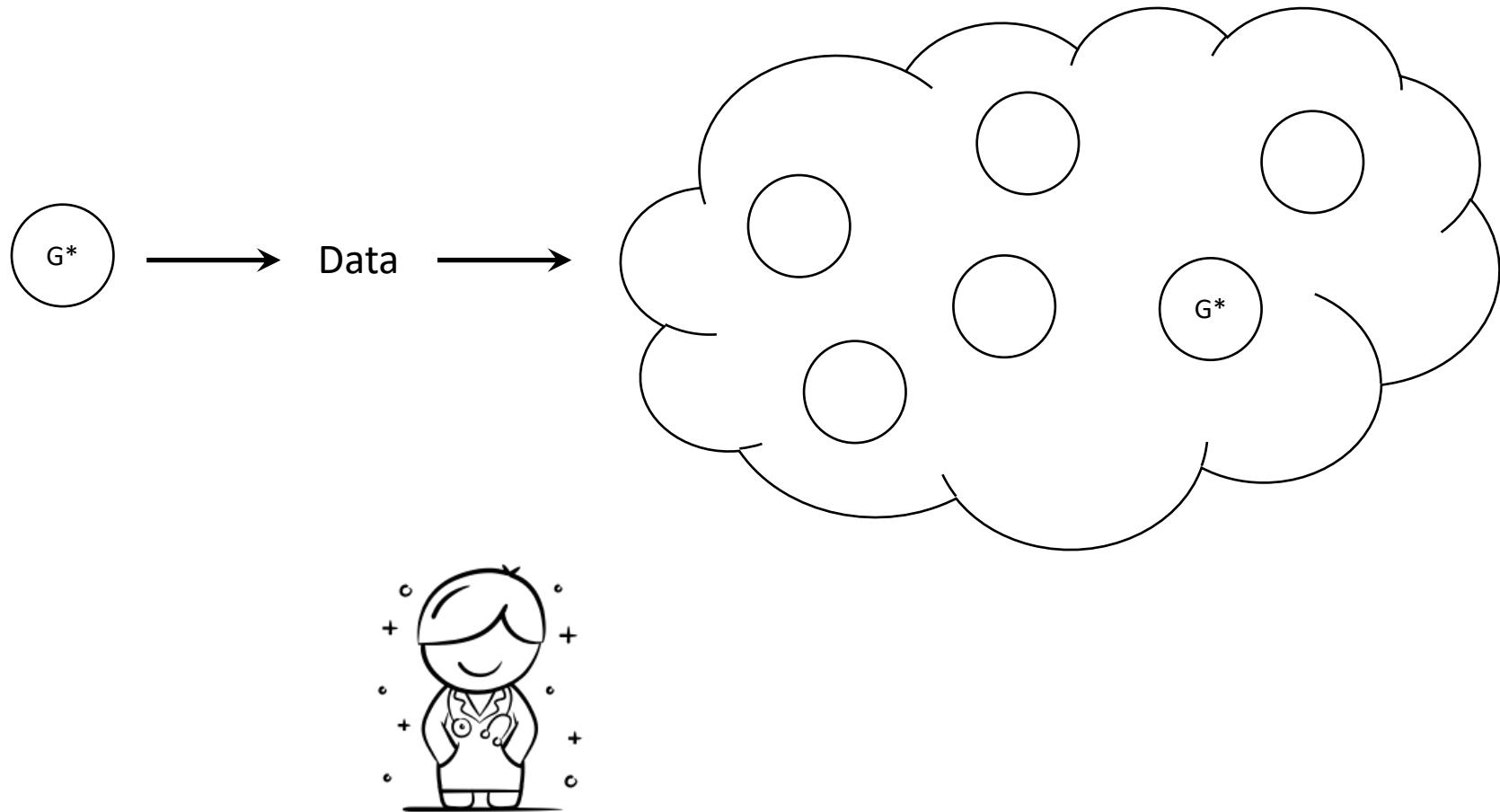
(Informal) Search:  $\mathcal{O}(\log |H| \cdot \nu(G^*))$  interventions suffices

[CS23]

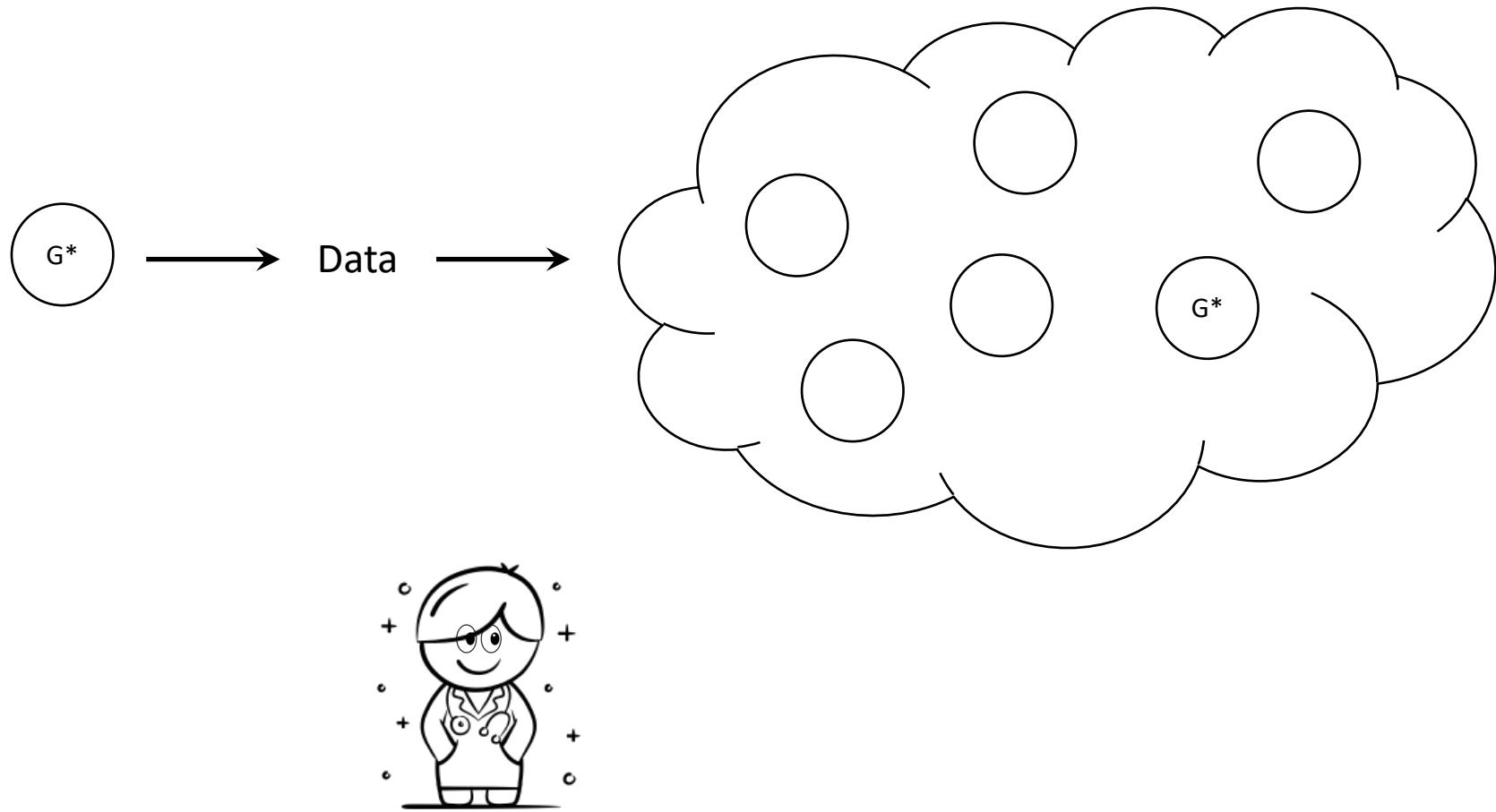
In many problem domains...



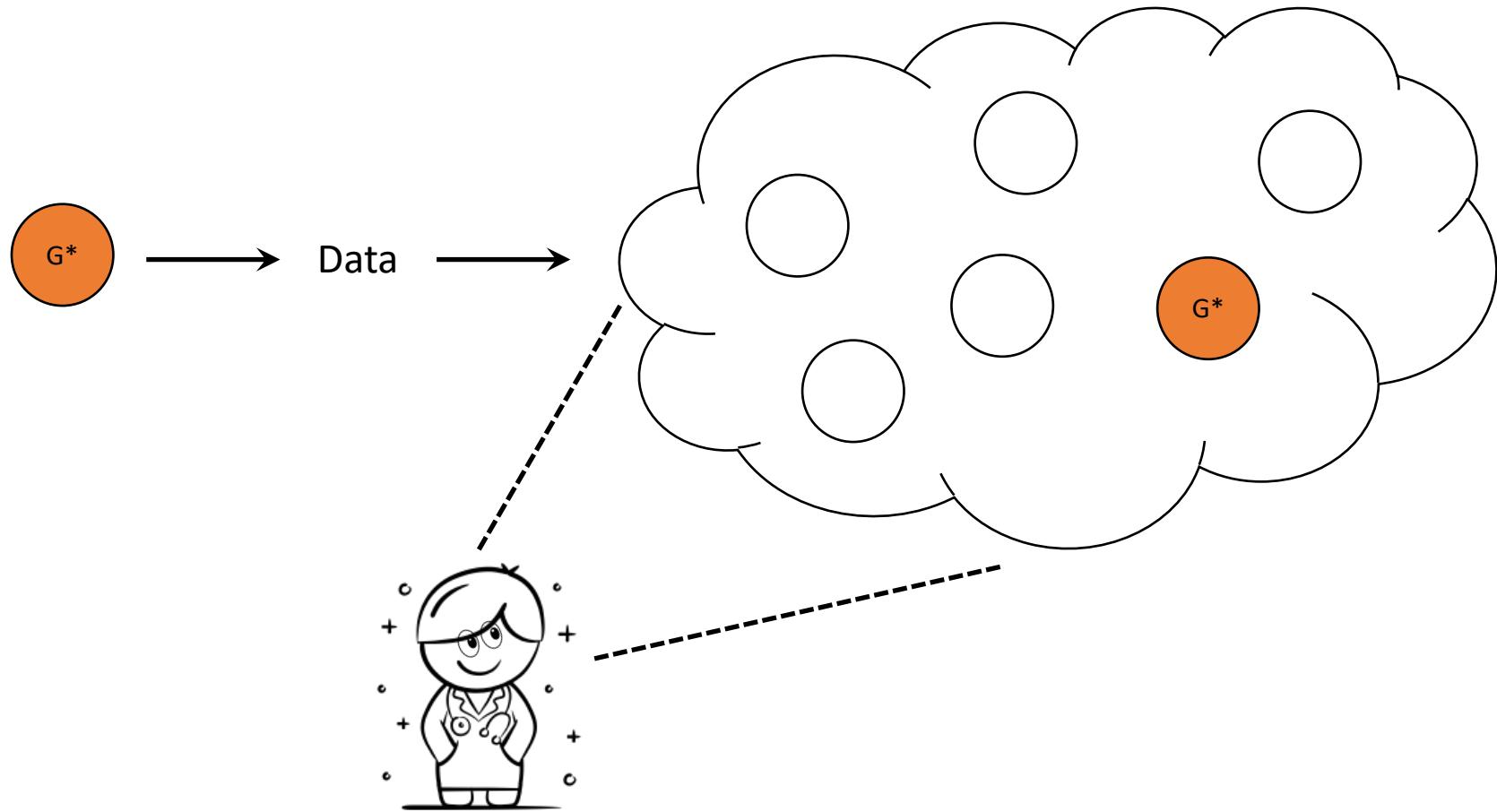
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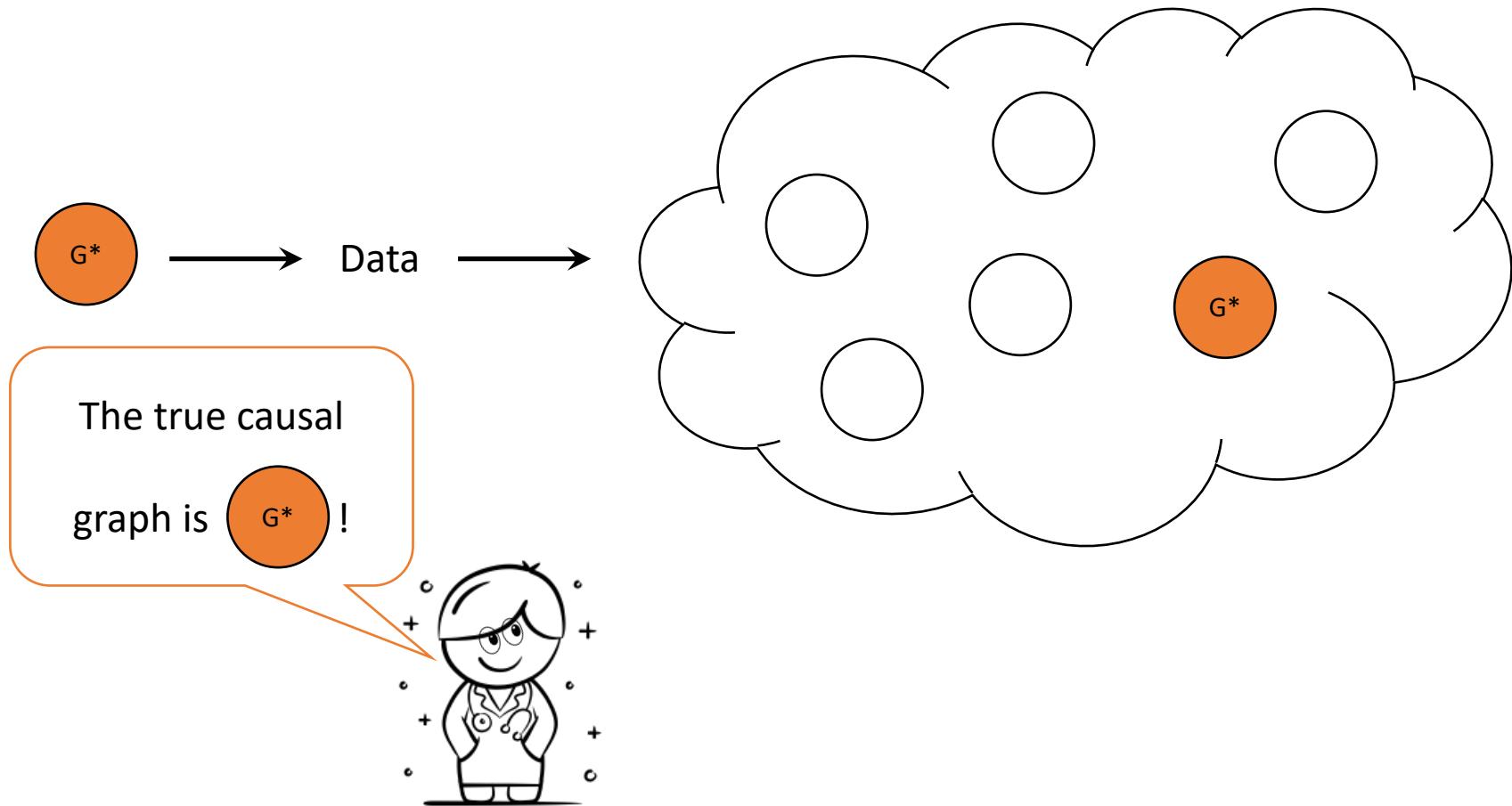
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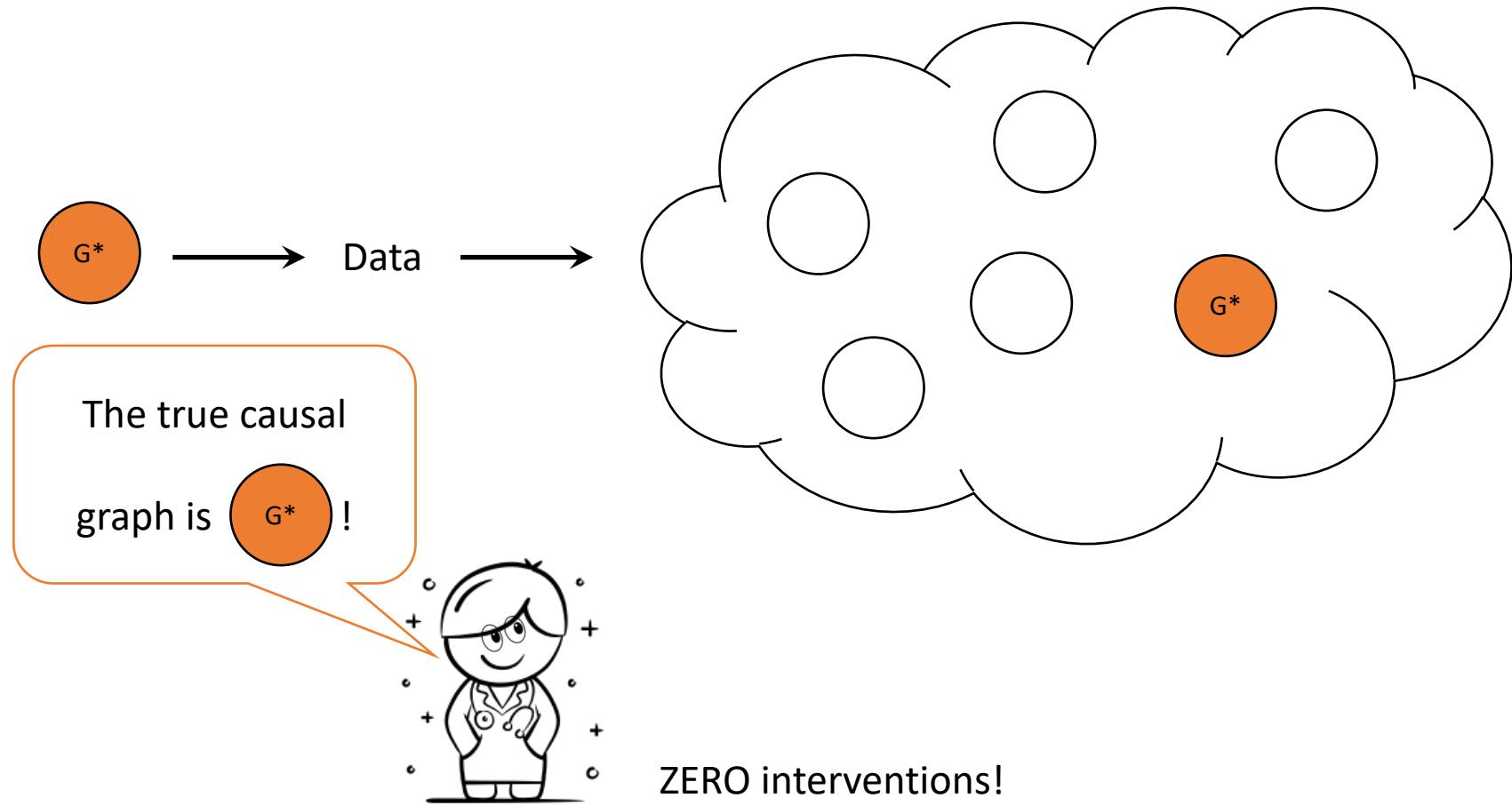
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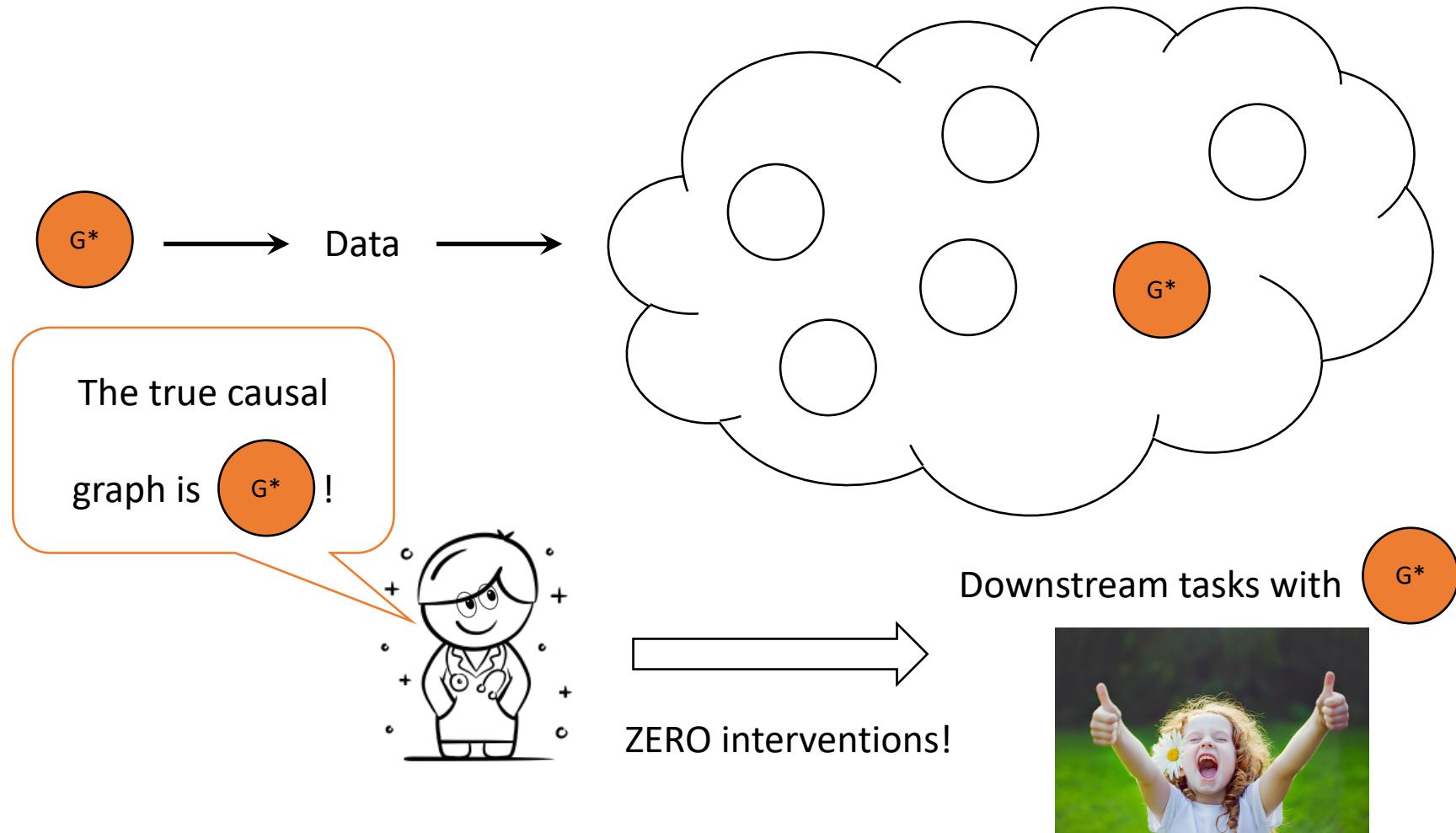
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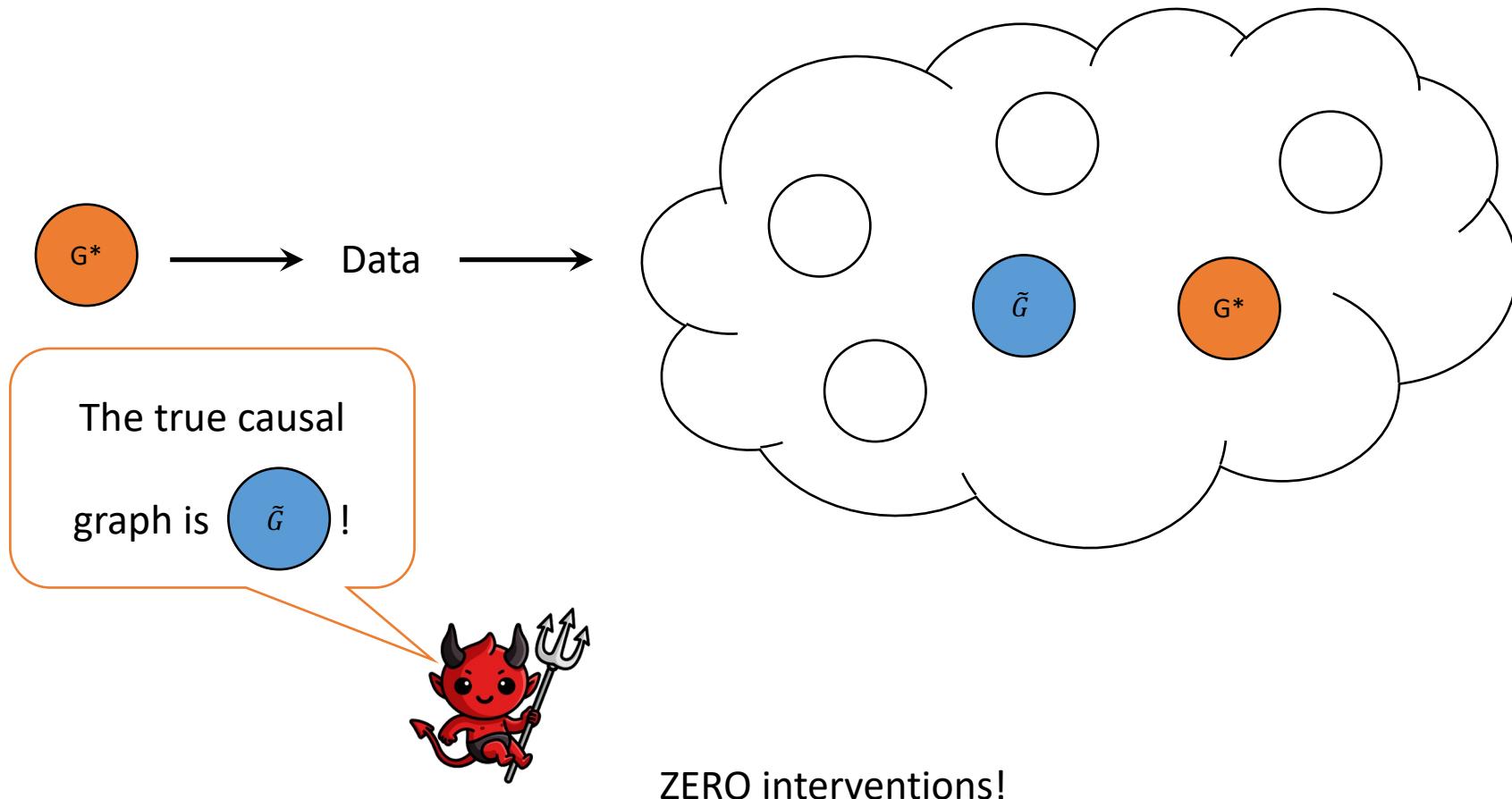
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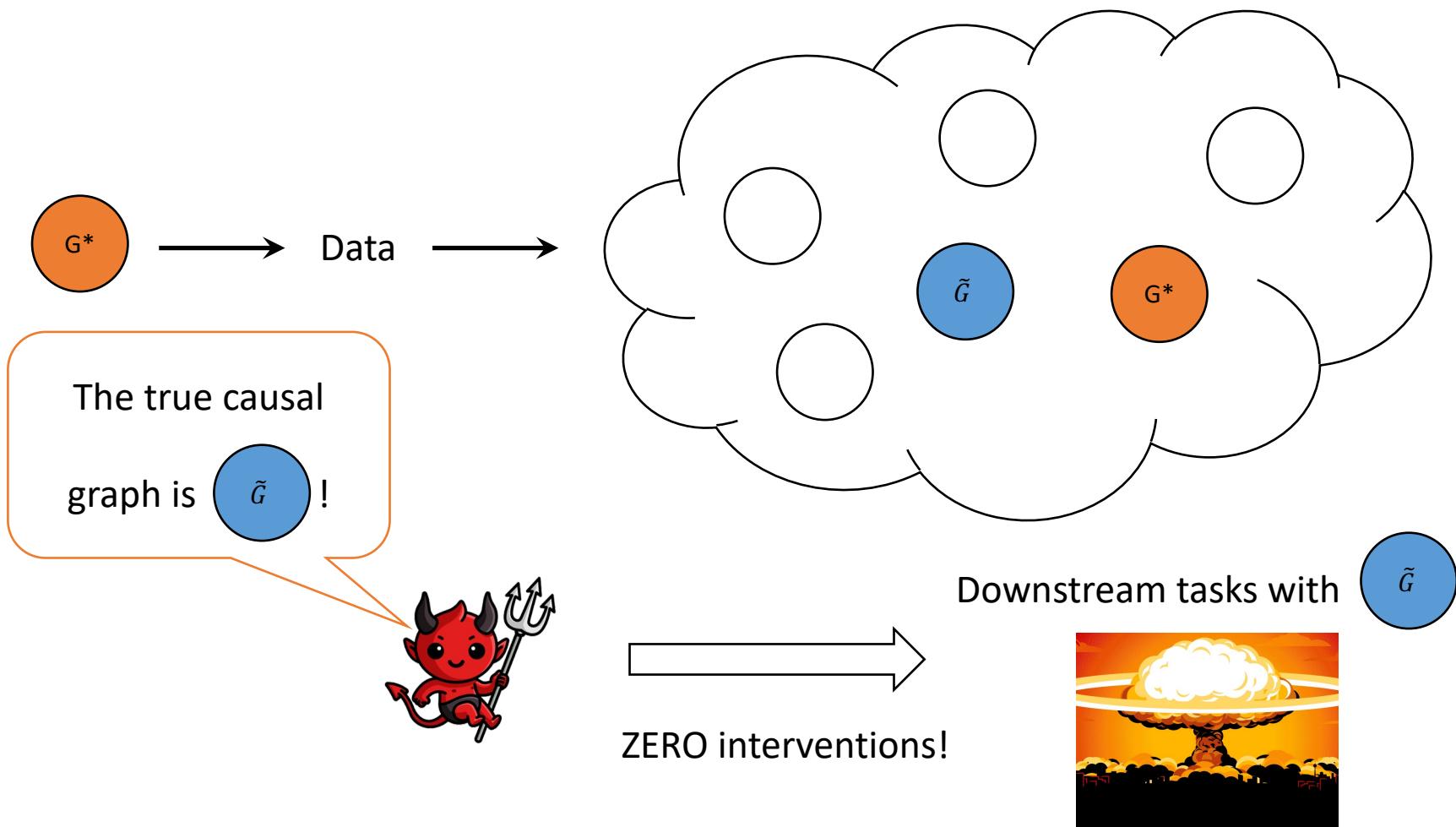
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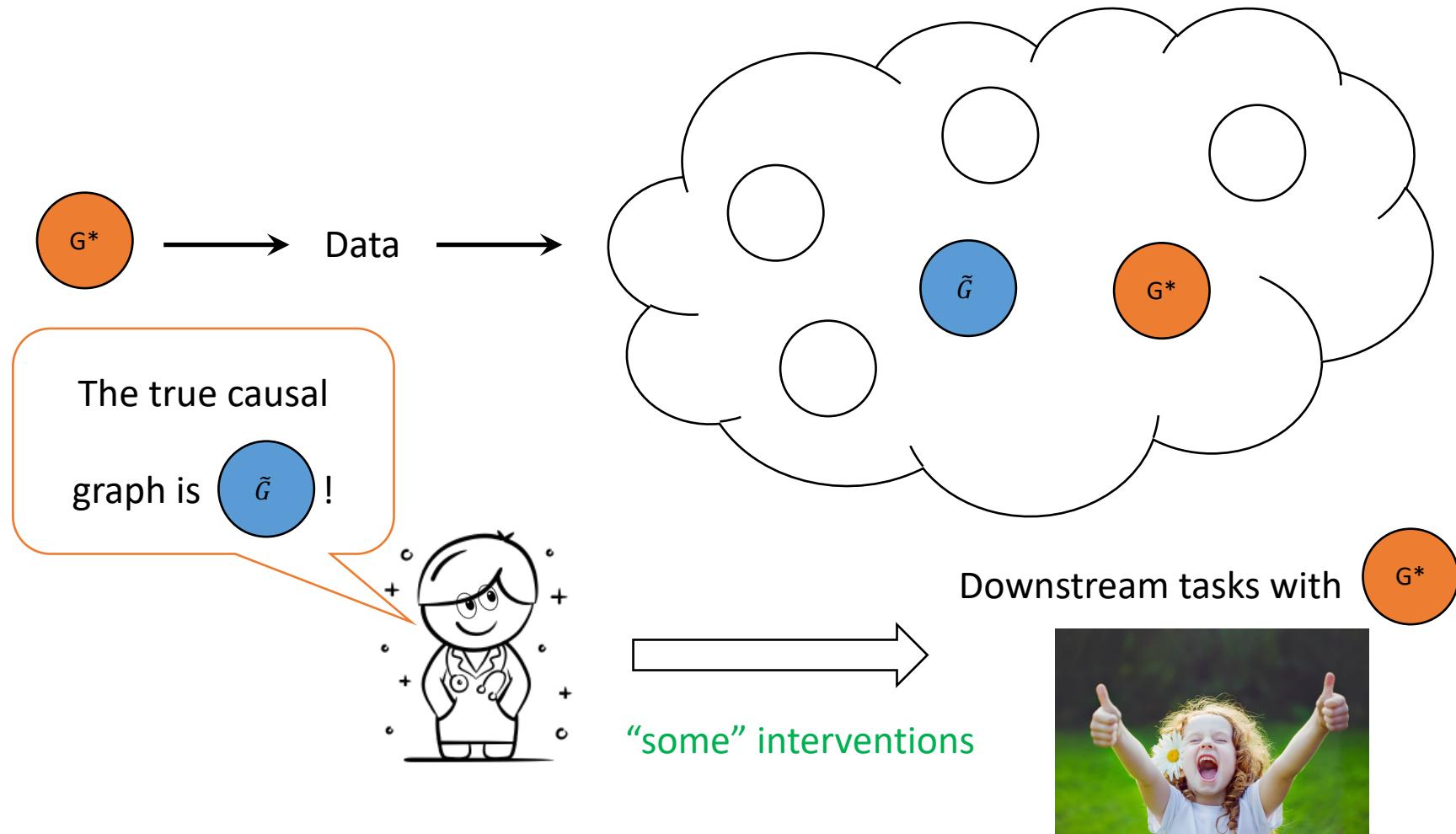
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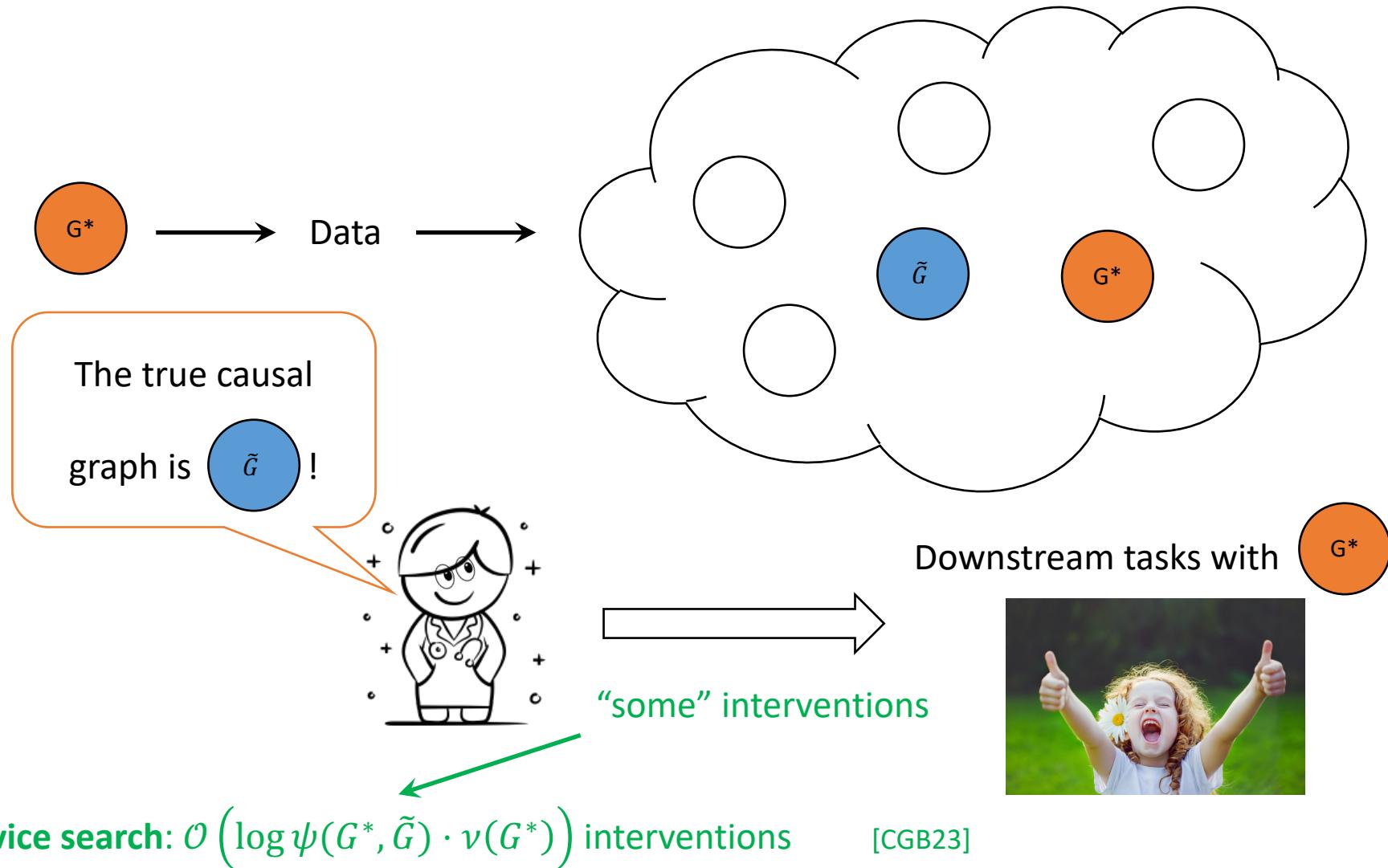
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