

Markov Chain Monte Carlo (2/2)

MCMC

- Gibbs Sampler
 - Help to decompose big complex problem (find joint distribution) into small simple problems (use conditional distributions)
 - Limitation: still needs to know the conditional distributions, therefore, only conjugate
- Metropolis-Hastings
 - Can solve any model!

Reversibility vs. Stationarity

- Reversibility with respect to ω

$$\omega_i p_{ij} = \omega_j p_{ji}$$

- Summing both sides over i

$$\sum_i \omega_i p_{ij} = \sum_i \omega_j p_{ji} = \omega_j \sum_i p_{ji} = \omega_j$$

that is $\omega P = \omega$, which is stationary

This provides a method to find the stationary distribution of the chain

Metropolis Methods

Goal:

construct a Markov Chain whose invariant (stationary) distribution is the posterior, using only non-normalized posterior.

Metropolis idea:

given a chain which is easy to sample from, modify to have π as its invariant distribution

[similar to accept/reject sampling – sample from a proposal, accept/reject to obtain desired distribution]

Discrete Case: Metropolis-Hastings algorithm

- i. start with a chain defined by transition matrix Q .
- ii. modify to new chain with π as invariant distribution.
- iii. require only un-normalized posterior

How? Use the principle of time reversibility wrt π

Discrete Case: Metropolis-Hastings algorithm

$q_0 = q^i$ (start in state i)

draw state j with prob $(q_{i,1}, \dots, q_{i,d})$

compute $a = \min \left\{ 1, \frac{p_j q_{j,i}}{p_i q_{i,j}} \right\}$

with prob a $q_1 = q^j$ (move)

else $q_1 = q^i$ (stay)

Note: with prob $1-a$,
this chain will
repeat!!

Discrete Case: Metropolis-Hastings algorithm

why repeat?

$$\text{if } \pi_i q_{i,j} > \pi_j q_{j,i} \Rightarrow \alpha < 1$$

“too many” transitions from i to j

“not enough” transitions from j to i

if at state i, repeat i to lower number of transitions.

if at state j, always move to i!

Time reversible wrt π

$$p_{ij} = q_{ij} \alpha(i, j)$$

generating candidate j
given i

acceptance
probability

$$\pi_i p_{ij} = \pi_i q_{ij} \min \left\{ 1, \frac{\pi_j q_{ji}}{\pi_i q_{ij}} \right\} = \min \{ \pi_i q_{ij}, \pi_j q_{ji} \}$$

$$\pi_j p_{ji} = \min \{ \pi_j q_{ji}, \pi_i q_{ij} \}$$

$$\Rightarrow \pi_i p_{i,j} = \pi_j p_{j,i}$$

Metropolis-Hastings algorithm example

$$\pi = [1/3 \quad 2/3] \quad q_{ij} = 1/2 \quad Q = \begin{bmatrix} .5 & .5 \\ .5 & .5 \end{bmatrix}$$

$$p_{12} = .5 \min \left\{ 1, \frac{2/3}{1/3} \right\} = .5(1) = .5$$

$$p_{21} = .5 \min \left\{ 1, \frac{1/3}{2/3} \right\} = .5(.5) = .25 \quad P = \begin{bmatrix} 1/2 & 1/2 \\ 1/4 & 3/4 \end{bmatrix}$$

check: does $\pi P = \pi$? (yes!)

9

Continuous Metropolis-Hastings

discrete: $i \rightarrow j$

continuous: $\theta \rightarrow \vartheta$

Q is the proposal Markov chain. $q(\theta, \vartheta)$ is the kernel.
 π is the desired stationary distribution.

1. Generate $\vartheta \sim q(\theta, \vartheta)$

$$2. \alpha(\theta, \vartheta) = \min \left\{ 1, \frac{\pi(\vartheta) q(\vartheta, \theta)}{\pi(\theta) q(\theta, \vartheta)} \right\}$$

3. With prob α , move to ϑ , else stay at θ

How to Find Proposal q?

- Ideally, we want the proposal distribution $q(\theta, \vartheta)$ to have a fatter tail than the target distribution $\pi(\theta)$
 - Method 1: Random-walk proposal function
 - Method 2: Independence chain

Random Walk MH

- Random-walk proposal function

$$\vartheta = \theta + \epsilon$$

$$q(\theta, \vartheta) = q_\epsilon(\vartheta - \theta) \sim N(0, s^2 I)$$
- Random-walk Metropolis Chain
 - Start with θ_0
 - Draw $\vartheta = \theta + \epsilon, \epsilon \sim N(0, s^2 I)$
 - Compute $\alpha = \min\{1, \pi(\vartheta)/\pi(\theta)\}$
 - With probability α , take the proposal $\theta_1 = \vartheta$
 - With probability $1 - \alpha$, stay $\theta_1 = \theta_0$
 - Repeat

Independence chain

Let $q(\theta, \vartheta) = q_{\text{imp}}(\vartheta)$

“ind of current location.
“imp” for importance
function

$$\begin{aligned} \text{Then } \alpha(\theta, \vartheta) &= \min \left\{ 1, \frac{\pi(\vartheta) q_{\text{imp}}(\theta)}{\pi(\theta) q_{\text{imp}}(\vartheta)} \right\} \\ &= \min \left\{ 1, \frac{\pi(\vartheta) / q_{\text{imp}}(\vartheta)}{\pi(\theta) / q_{\text{imp}}(\theta)} \right\} \end{aligned}$$

$q_{\text{imp}}()$ should have fatter tails than π to avoid the need to reject draws to build up tail mass.

Independence chain

if q is an excellent approximation to π ,

$$\frac{\pi(\theta)}{q_{\text{imp}}(\theta)} \approx \text{constant}$$

α will be approximately 1!

how does it work?

if π has *more* mass (relative to q) at ϕ than at θ , move to ϕ with prob 1.

if π has *less* mass (relative to q) at ϕ than at θ , stay with some prob > 0 to build up mass

Independence chain

“important” that qimp have fatter tails.

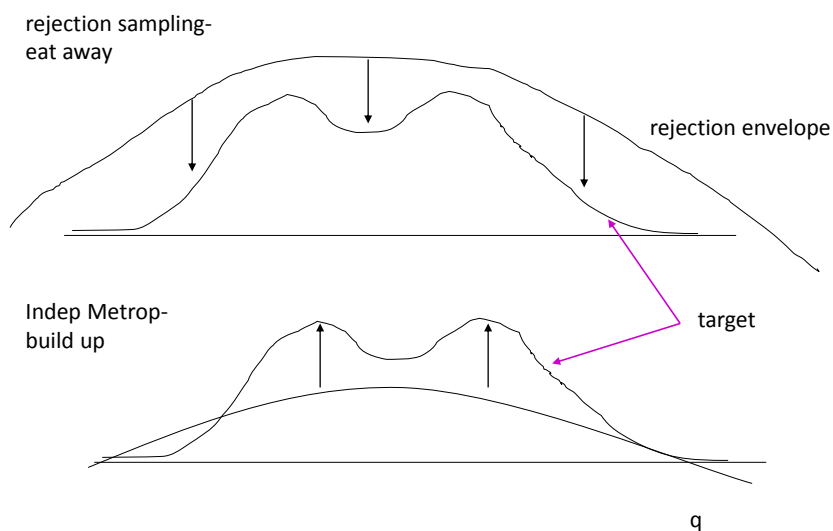
If

$$\pi(\theta) \leq M q_{\text{imp}}$$

then independence Metropolis is *uniformly* ergodic

Ind. Metropolis works well in low dimensions

Independence Metro vs. Rejection Sampling



Independence vs. RW Chains

Independence Chains:

- requires a good approximation to posterior (similar to Importance Sampling)
- implies some sort of optimizer
- more efficient than RW

RW Chains:

- will explore parameter space – no location required!
- for low dimensions will work even with “dumb” choices of increment Cov matrix
- may not work well in high dimensional spaces unless increment Cov closely approximates posterior

Choosing a step size for the RW chain

At θ , draw $\varepsilon \sim q$ independent of θ .
 candidate = $\theta + \varepsilon$

ε very small leads to small steps, higher acceptance, higher autocorrelation.

ε very large leads to large steps, lower acceptance, higher autocorrelation.

Pick $\varepsilon \sim N(0, s^2 \Sigma)$, choosing s to maximize information content.

Choosing a step size for the RW chain

Choice of Σ :

I

Asymptotic Var-Cov for Posterior or Likelihood

Run chain with I, then use cov matrix of draws

Choice of scaling constant (s):

Method 1: get the “right” acceptance rate (30-50%)

Method 2:

$$s = 2.93 / \sqrt{d = \dim(\text{state space})}$$

Applications to MNL Model

- MNL model, likelihood function

$$l(\beta) = \prod_i \prod_j \frac{\exp(X_{ij}\beta_j)^{y_{ij}}}{\sum_k \exp(X_{ik}\beta_k)^{y_{ik}}} \quad \begin{array}{l} i - \text{for data points} \\ j, k - \text{for alternatives} \end{array}$$

- Prior for the model parameters

$$\beta \sim MVN(\beta_0, \Sigma_0) \\ \exp\left(-\frac{1}{2}(\beta - \beta_0)' \Sigma_0^{-1}(\beta - \beta_0)\right)$$

- Posterior: multiply the two equations above, we get $\pi(\beta)$

- Unknown distribution, no conjugacy
- We try to establish a Markov Chain so that the stationary distribution is $\pi(\beta)$
- We cannot find the transition matrix easily, we use Metropolis-Hastings
 - Try a proposal transition matrix
 - Adjust the chain based on MH algorithm

Logit model-Hessian

Both Indep and RW Metropolis chains rely on an asymptotic approximation to the posterior

$$p(b|X, y) \propto |H|^{1/2} \exp \left\{ \frac{1}{2} (b - \hat{b})' H (b - \hat{b}) \right\}$$

Method 1: we can use the expected sample information matrix:

$$H = -E \left[\frac{\partial^2 \log \ell}{\partial b \partial b'} \right] = \sum_i X_i A_i X_i'$$

$$X = \begin{bmatrix} X_1 \\ \vdots \\ X_n \end{bmatrix}; \quad A_i = \text{Diag}(p_i) - p_i p_i'$$

Method 2: use the MLE estimate and minus Hessian

Logit model MCMC Algorithms

1. Pick an arbitrary starting value β^{old}
2. Generate candidate realization:
random walk chain: $\beta^{\text{cand}} = \beta^{\text{old}} + \varepsilon; \quad \varepsilon \sim N(0, s^2 H^{-1})$
3. Accept β^{cand} with probability α

$$\alpha = \min \left\{ 1, \frac{l(\beta^{\text{cand}}|y, X)p(\beta^{\text{cand}})}{l(\beta^{\text{old}}|y, X)p(\beta^{\text{old}})} \times \frac{q(\beta^{\text{cand}}, \beta^{\text{old}})}{q(\beta^{\text{old}}, \beta^{\text{cand}})} \right\}$$
4. Repeat