室内外场景定位

Installation

基础环境

ubuntu 16.04, cuda8.0(cuda9.0), MATLABR2016b

TensorFlow安装(ContextDesc环境配置)

安装**虚拟环境**py2_tf112流程如下(python==2.7, tensorflow==1.12.0)

tensorflow

```
pip install --upgrade pip
pip install https://storage.googleapis.com/tensorflow/linux/gpu/tensorflow_gpu-
1.12.0-cp27-none-linux_x86_64.whl
pip install numpy
pip install opencv_contrib (to enable SIFT)
```

其余包请在运行 ContextDesc 时自行安装! (匹配 python2 即可)

首次运行程序,模型将从预设路径自动下载,如有问题请及时联系.

OPENMVG 安装及配置

<u>openmvg</u>

1. 工具准备

CMake

Git

C/C++ compiler (GCC, Visual Studio or Clang)

2. 获取源码

git clone --recursive https://github.com/openMVG/openMVG.git

3. 安装依赖项

```
sudo apt-get install \
  libpng-dev libjpeg-dev \
  libtiff-dev libxxf86vm1 \
  libxxf86vm-dev \
  libxi-dev \
  libxrandr-dev
```

可选: 需要可视化,可安装Graphviz sudo apt-get install graphviz

4. 配置和编译

```
mkdir openMVG_Build && cd openMVG_Build
cmake -DCMAKE_BUILD_TYPE=RELEASE ../openMVG/src/
cmake --build . --target install
make test
```

5. 测试安装

make test

COLMAP 安装及配置

colmap

1. 获取源码

git clone https://github.com/colmap/colmap

2. 安装依赖项

```
sudo apt-get install \
    git \
    cmake \
    build-essential \
     libboost-program-options-dev \
     libboost-filesystem-dev \
     libboost-graph-dev \
     libboost-regex-dev \
     libboost-system-dev \
     libboost-test-dev \
     libeigen3-dev \
     libsuitesparse-dev \
     libfreeimage-dev \
     libgoogle-glog-dev \
     libgflags-dev \
     libglew-dev \
     gtbase5-dev \
     libqt5opengl5-dev \
     libcgal-dev
```

PS:在Ubuntu16.04下, CGAL的cmake配置是损坏的,必须安装CGAL的qt5包 sudo apt-get install libcgal-qt5-dev

3. 编译安装Ceres-Solver

Ceres-Solver

```
sudo apt-get install libatlas-base-dev libsuitesparse-dev git clone https://ceres-solver.googlesource.com/ceres-solver cd ceres-solver git checkout $(git describe --tags) # Checkout the latest release mkdir build cd build cmake .. -DBUILD_TESTING=OFF -DBUILD_EXAMPLES=OFF make sudo make install
```

4. 配置和编译colmap

```
git clone https://github.com/colmap/colmap.git
cd colmap
git checkout dev
mkdir build
cd build
cmake ..
make
sudo make install
```

5. 运行colmap

```
colmap -h
colmap gui
```

Structure

工程文件夹及主要程序文件说明

- 1. dataset 存放数据及数据预处理脚本, 其中officialData存放官方原始数据
- 2. scripts 存放算法主要源代码
- 3. software 存放算法所使用的软件框架
- 4. upload 存放中间运行结果及结果处理脚本
- 5. workspace 存放算法工程文件
- 6. scripts.sh 主程序脚本
- 7. upload.txt 最终运行结果

目录结构示意图如下

```
— dataset
  ├— fishEye
  ├— gt
 ├── mvpic_ofFish.py
  ├─ mvpic_ofPano.py
  ├─ officialData
  ├— pano
  ├─ panoSplit
  └─ panoSplit8
 scripts
 ├─ colmap
   ├─ contextDesc
   └─ pipeline.pdf
— scripts.sh
 software
  ├— colmap
   └─ openMVG
 - upload
 ├— cnn
  ├— dsp
  ├— final
  ├— fishEye
 ├— org
 ├─ org8
  └─ selectBest.py
- upload.txt
```

Getting Started

运行之前,需要修改两处路径为绝对路径:

```
./scripts/colmap/matchForCnn.data 第 1 行
./scripts/colmap/scriptsOfCnn/matching_pipeline.m 第 10-13 行
```

将测试数据置于以下目录(数据组织方式与预赛相同):

```
./dataset/officialData/
```

在根目录下运行:

```
sh scripts.sh
```

若运行有问题,请及时联系!

Contact Us

如果有问题请及时联系.

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星期一, 08. 七月 2019 05:14下午