

Contents

0 Basic	1
0A .vimrc	1
0B PBDS	1
0C pragma	1
0D Default Code	1
0E LambdaCompare	1
1 Graph	1
1A 2SAT/SCC	1
1B Vertex BCC	2
1C Edge BCC	2
1D Virtual Tree	2
1E Maximum Clique	2
1F MinimumSteinerTree	3
1G Dominator Tree	3
1H Directed MST (slow)	4
1I Directed MST (fast)	4
1J Minimum Clique Cover	5
1K Count Maximal Clique	5
1L Theorems	5
2 Flow-Matching	5
2A Hopcroft-Karp	5
2B KM (Hungarian Alg.)	5
2C Max Flow (Dinic)	6
2D MCMF	6
2E General Graph Matching	7
2F Max Weight Maching	7
2G Global Min Cut	9
2H Gomory-Hu Tree	9
2I Min Cost Circulation	9
2J Flow Models Building	9
3 Data Struture	10
3A LichaoTree	10
3B Treap	10
3C LinkCutTree	10
3D CentroidDecomposition	11
3E HeavylightDecomposition	11
4 String	12
4A KMP	12
4B Z	12
4C Manacher	12
4D SuffixArray	12
4E SA-IS(Induced Sorting)	12
4F ACAutomaton	13
4G MinRotation	13
4H ExtSAM	13
5 Number Theory	14
5A Primes	14
5B ExtGCD	14
5C FloorCeil	14
5D MillerRabin	14
5F PollardRho	14
5G Fraction	15
5H ChineseRemainder	15
5I FactorialMod ^p	15
5J QuadraticResidue	15
5K MeisselLehmer	15
5L DiscreteLog	15
5M Theorems	16
5N Estimation	16
5O Numbers	16
5P GeneratingFunctions	16
6 Linear Algebra	16
6A GaussianElimination	16
6B BerlekampMassey	17
6C Simplex	17
7 Polynomials	17
7A NTT (FFT)	17
7B FHWT	18
7C PolynomialOperations	18
7D NewtonMethod+MiscGF	19
8 Geometry	19
8A Basic	19
8B ConvexHull	19
8C SortByAngle	19
8D Formulas	19
8E TriangleHearts	20
8F PointSegmentDist	20
8G PointInCircle	20
8H PointInConvex	20
8I PointTangentConvex	20
8J CircTangentCirc	20
8K LineCircleIntersect	20
8L LineConvexIntersect	20
8M CircIntersectCirc	21
8N PolyIntersectCirc	21
8O PolyUnion	21
8P MinkowskiSum	21
8Q MinMaxEnclosingRect	21
8R CircleCover	22
8S LineCmp	22
8T Trapezoidalization	22
8U HalfPlaneIntersect	23
8V RotatingSweepLine	23
8W DelaunayTriangulation	23
8X VoronoiDiagram	24
9 Misc	24
9A ManhattanMST	24
9B SternBrocotTree	24
9C CDQ	24
9D SimulatedAnnealing	25
9E Python	25

0 Basic

0A .vimrc

```
sy on
set si nu rnu cin cul et so=10 ts=4 sw=4 mouse=a
ino {<cr>} {<cr>} <esc>ko
ino jk <esc>
map <F7> :w<CR>:!g++ "%"
=std
=c++17 -DLOCAL -Wall -Wextra -Wshadow -Wconversion
-fsanitize=address,undefined -g && ./a.out<CR>
ca Hash w !cpp -dD -P -fpreprocessed
 \| tr -d "[[:space:]]" \| md5sum \| cut -c-6
```

0B PBDS

```
// Tree and fast PQ
#include <bits/extc++.h>
using namespace __gnu_pbds;

#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/tree_policy.hpp>
tree<int, null_type, less<int>, rb_tree_tag
, tree_order_statistics_node_update> bst;
// order_of_key(n): # of elements <= n
// find_by_order(n): 0-indexed

#include <ext/pb_ds/assoc_container.hpp>
#include <ext/pb_ds/priority_queue.hpp>
__gnu_pbds::priority_queue<int, greater<int>, thin_heap_tag> pq;
```

0C pragma

```
#pragma GCC optimize("Ofast,unroll-loops")
#pragma GCC target("avx,avx2,sse,sse2
, sse3,ssse3,sse4,popcnt,abm,mmx,fma,tune=native")
// chrono
::steady_clock::now().time_since_epoch().count()
```

0D Default Code

```
using namespace std;

#define F first
#define S second
#define all(x) x.begin(), x.end()
#define pii pair<int, int>
#define pll pair<ll, ll>
#define pdd pair<double, double>
#define ll long long
#define ld long double
#define i128 __int128

#ifndef LOCAL
#define px(
    args...) LKJ("\033[1;32m(" #args ")\033[0m", args)
template<class I> void LKJ(I&x){ cerr << x << '\n'; }
template<class I, class...T> void
    LKJ(I&x, T&...t){ cerr << x << ' ', LKJ(t...); }
template<class I> void OI(I a, I b){ while
    (a < b) cerr << *a << "\n"[next(a) == b], ++a; }
#define pv(v) cerr
    << "\033[1;31m[" << #v << "]": \033[0m"; OI(all(v))
#else
#define px(...)
#define OI(...)
#define pv(v)
#endif

template<class A, class
B> ostream& operator<<(ostream &os, pair<A, B> p)
{ return os << '(' << p.F << ", " << p.S << ')'; }

void solve() {}

int main() {
    cin.tie(0)->sync_with_stdio(0);
    int T = 1;

    // cin >> T;
    while (T--) solve();
}
```

0E LambdaCompare

```
auto cmp = [] (int x, int y) { return x < y; };
std::set<int, decltype(cmp)> st(cmp);
```

1 Graph

1A 2SAT/SCC

```
struct SAT { // 0-base
    int low[N], dfn[N], bln[N], n, Time, nScc;
    bool instack[N], istrue[N];
    stack<int> st;
    vector<int> G[N], SCC[N];
    void init(int _n) {
        n = _n; // assert(n * 2 <= N);
        for (int i = 0; i < n + n; ++i) G[i].clear();
    }
    void add_edge(int a, int b) { G[a].emplace_back(b); }
    int rv(int a) {
        if (a >= n) return a - n;
        return a + n;
    }
    void add_clause(int a, int b) {
        add_edge(rv(a), b), add_edge(rv(b), a);
    }
    void dfs(int u) {
        dfn[u] = low[u] = ++Time;
```

```

instack[u] = 1, st.push(u);
for (int i : G[u])
    if (!dfn[i])
        dfs(i), low[u] = min(low[i], low[u]);
    else if (instack[i] && dfn[i] < dfn[u])
        low[u] = min(low[u], dfn[i]);
if (low[u] == dfn[u]) {
    int tmp;
    do {
        tmp = st.top(), st.pop();
        instack[tmp] = 0, bln[tmp] = nScc;
    } while (tmp != u);
    ++nScc;
}
bool solve() {
    Time = nScc = 0;
    for (int i = 0; i < n + n; ++i)
        SCC[i].clear(), low[i] = dfn[i] = bln[i] = 0;
    for (int i = 0; i < n + n; ++i)
        if (!dfn[i]) dfs(i);
    for (int i =
        0; i < n + n; ++i) SCC[bln[i]].emplace_back(i);
    bool flag = true;
    for (int i = 0; i < n; ++i) {
        if (bln[i] == bln[i + n]) flag = false;
        istrue[i] = bln[i] < bln[i + n];
        istrue[i + n] = !istrue[i];
    }
    return flag;
    // return whether there is a set of solutions
    // istrue[] are one set of solutions if any
}
};

```

1B Vertex BCC

```

int n, m, dfn[N], low[N], is_cut[N], nbcc = 0, t = 0;
vector<int> g[N], bcc[N], G[2 * N];
stack<int> st;
void tarjan(int p, int lp) {
    dfn[p] = low[p] = ++t;
    st.push(p);
    for (auto i : g[p]) {
        if (!dfn[i]) {
            tarjan(i, p);
            low[p] = min(low[p], low[i]);
            if (dfn[p] <= low[i])
                nbcc++;
            is_cut[p] = 1;
            for (int x = 0; x != i; st.pop()) {
                x = st.top();
                bcc[nbcc].push_back(x);
            }
            bcc[nbcc].push_back(p);
        }
    } else low[p] = min(low[p], dfn[i]);
}
void build() { // [n+1,n+nbcc] cycle, [1,n] vertex
    for (int i = 1; i <= nbcc; i++) {
        for (auto j : bcc[i]) {
            G[i + n].push_back(j);
            G[j].push_back(i + n);
        }
    }
}

```

1C Edge BCC

```

namespace bridge_cc {
    vector<int> tim, low;
    stack<int, vector<int>> st;
    int t, bcc_id;
    void dfs(int u, int p, const vector<
        vector<pair<int, int>>> &edge, vector<int> &pa) {
        tim[u] = low[u] = t++;

```

```

        st.push(u);
        for (const auto &[v, id] : edge[u]) {
            if (id == p)
                continue;
            if (tim[v])
                low[u] = min(low[u], tim[v]);
            else {
                dfs(v, id, edge, pa);
                if (low[v] > tim[u]) {
                    int x;
                    do {
                        pa[x = st.top()] = bcc_id;
                        st.pop();
                    } while (x != v);
                    bcc_id++;
                }
            }
        }
        low[u] = min(low[u], low[v]);
    }
}
vector<int> solve(const vector<
    vector<pair<int, int>>> &edge) { // (to, id)
    int n = edge.size();
    tim.resize(n);
    low.resize(n);
    t = bcc_id = 1;
    vector<int> pa(n);

    for (int i = 0; i < n; i++) {
        if (!tim[i]) {
            dfs(i, -1, edge, pa);
            while (!st.empty()) {
                pa[st.top()] = bcc_id;
                st.pop();
            }
            bcc_id++;
        }
    }
    return pa;
} // return bcc id(start from 1)
};


```

1D Virtual Tree

```

// requires DFS io, lca, is_child
vector<int> tre[N];
bool cmp(int a, int b){ return in[a] < in[b]; }
void add_edge(int a, int b){
    tre[a].emplace_back(b);
    tre[b].emplace_back(a);
}
void virtual_tree(vector<int> arr, int k){
    vector<int> sta;
    sort(arr.begin(), arr.end(), cmp);
    for (int i = 1; i < k; i++)
        arr.emplace_back(lca(arr[i], arr[i - 1]));
    sort(arr.begin(), arr.end(), cmp);
    arr.resize(
        unique(arr.begin(), arr.end()) - arr.begin());
    for (auto i : arr){
        while (!sta.empty()
            () && !is_child(sta.back(), i)) sta.pop_back();
        if (!sta.empty()) add_edge(sta.back(), i);
        sta.push_back(i);
    }
}

```

1E Maximum Clique

```

struct MaxClique { // 最大完全子圖, fast when N <= 100
    bitset<N> G[N], cs[N];
    int ans, sol[N], q, cur[N], d[N], n;
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n; ++i) G[i].reset();
    }
}

```

```

void add_edge(int u, int v) {
    G[u][v] = G[v][u] = 1;
}
void pre_dfs(vector<int> &r, int l, bitset<N> mask) {
    if (l < 4) {
        for (int i : r) d[i] = (G[i] & mask).count();
        sort(all(r));
        [&](int x, int y) { return d[x] > d[y]; });
    }
    vector<int> c(r.size());
    int lft = max(ans - q + 1, 1), rgt = 1, tp = 0;
    cs[1].reset(), cs[2].reset();
    for (int p : r) {
        int k = 1;
        while ((cs[k] & G[p]).any()) ++k;
        if (k > rgt) cs[++rgt + 1].reset();
        cs[k][p] = 1;
        if (k < lft) r[tp++] = p;
    }
    for (int k = lft; k <= rgt; ++k)
        for (int p = cs[k]._Find_first()
              (); p < N; p = cs[k]._Find_next(p))
            r[tp] = p, c[tp] = k, ++tp;
    dfs(r, c, l + 1, mask);
}
void dfs(vector<
    int> &r, vector<int> &c, int l, bitset<N> mask) {
    while (!r.empty()) {
        int p = r.back();
        r.pop_back(), mask[p] = 0;
        if (q + c.back() <= ans) return;
        cur[q++] = p;
        vector<int> nr;
        for (int i : r) if (G[p][i]) nr.emplace_back(i);
        if (!nr.empty()) pre_dfs(nr, l, mask & G[p]);
        else if (q > ans) ans = q, copy_n(cur, q, sol);
        c.pop_back(), --q;
    }
}
int solve() {
    vector<int> r(n);
    ans = q = 0, iota(all(r), 0);
    pre_dfs(r, 0, bitset<N>(string(n, '1')));
    return ans;
}
};

```

1F MinimumSteinerTree

```

struct SteinerTree { // 0-base
    int n, dst[N][N], dp[1 << T][N], tdst[N];
    int vcst[N]; // the cost of vertexs
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n; ++i) {
            fill_n(dst[i], n, INF);
            dst[i][i] = vcst[i] = 0;
        }
    }
    void chmin(int &x, int val) {
        x = min(x, val);
    }
    void add_edge(int ui, int vi, int wi) {
        chmin(dst[ui][vi], wi);
    }
    void shortest_path() {
        for (int k = 0; k < n; ++k)
            for (int i = 0; i < n; ++i)
                for (int j = 0; j < n; ++j)
                    chmin(dst[i][j], dst[i][k] + dst[k][j]);
    }
    int solve(const vector<int>& ter) {
        shortest_path();
        int t = ter.size(), full = (1 << t) - 1;
        for (int i = 0; i <= full; ++i)
            fill_n(dp[i], n, INF);

```

```

copy_n(vcst, n, dp[0]);
for (int msk = 1; msk <= full; ++msk) {
    if (!(msk & (msk - 1))) {
        int who = __lg(msk);
        for (int i = 0; i < n; ++i)
            dp[msk][i] = vcst[ter[who]] + dst[ter[who]][i];
    }
    for (int i = 0; i < n; ++i)
        for (int sub = (msk - 1) & msk; sub; sub = (sub - 1) & msk)
            chmin(dp[msk][i], dp[sub][i] + dp[msk ^ sub][i] - vcst[i]);
    for (int i = 0; i < n; ++i) {
        tdst[i] = INF;
        for (int j = 0; j < n; ++j)
            chmin(tdst[i], dp[msk][j] + dst[j][i]);
    }
    copy_n(tdst, n, dp[msk]);
}
return *min_element(dp[full], dp[full] + n);
}; // O(V 3^T + V^2 2^T)

```

1G Dominator Tree

```

struct DominatorTree { // 1-base
    vector<int> G[N], rG[N];
    int n, pa[N], dfn[N], id[N], Time;
    int semi[N], idom[N], best[N];
    vector<int> tree[N]; // dominator_tree
    void init(int _n) {
        n = _n;
        for (int i = 1; i <= n; ++i)
            G[i].clear(), rG[i].clear();
    }
    void add_edge(int u, int v) {
        G[u].emplace_back(v), rG[v].emplace_back(u);
    }
    void dfs(int u) {
        id[dfn[u]] = ++Time = u;
        for (auto v : G[u])
            if (!dfn[v]) dfs(v), pa[dfn[v]] = dfn[u];
    }
    int find(int y, int x) {
        if (y <= x) return y;
        int tmp = find(pa[y], x);
        if (semi[best[y]] > semi[best[pa[y]]])
            best[y] = best[pa[y]];
        return pa[y] = tmp;
    }
    void tarjan(int root) {
        Time = 0;
        for (int i = 1; i <= n; ++i) {
            dfn[i] = idom[i] = 0;
            tree[i].clear();
            best[i] = semi[i] = i;
        }
        dfs(root);
        for (int i = Time; i > 1; --i) {
            int u = id[i];
            for (auto v : rG[u])
                if (v = dfn[v]) {
                    find(v, i);
                    semi[i] = min(semi[i], semi[best[v]]);
                }
            tree[semi[i]].emplace_back(i);
            for (auto v : tree[pa[i]]) {
                find(v, pa[i]);
                idom[v] =
                    semi[best[v]] == pa[i] ? pa[i] : best[v];
            }
            tree[pa[i]].clear();
        }
        for (int i = 2; i <= Time; ++i) {
            if (idom[i] != semi[i]) idom[i] = idom[idom[i]];
        }
    }
}

```

```

        tree[id[dom[i]]].emplace_back(id[i]);
    }
}
};


```

1H Directed MST (slow)

```

struct DMST { // O(VE)
    struct edge {
        int u, v;
        ll w;
    };
    vector<edge> E; // O-base
    int pe[N], id[N], vis[N];
    ll in[N];
    void init() { E.clear(); }
    void add_edge(int u, int v, ll w) {
        if (u != v) E.emplace_back(edge{u, v, w});
    }
    ll build(int root, int n) {
        ll ans = 0;
        for (;;) {
            fill_n(in, n, INF);
            for (int i = 0; i < (int)E.size(); ++i)
                if (E[i].u != E[i].v && E[i].w < in[E[i].v])
                    pe[E[i].v] = i, in[E[i].v] = E[i].w;
            for (int u = 0; u < n; ++u) // no solution
                if (u != root && in[u] == INF) return -INF;
            int cntnode = 0;
            fill_n(id, n, -1), fill_n(vis, n, -1);
            for (int u = 0; u < n; ++u) {
                if (u != root) ans += in[u];
                int v = u;
                while (vis[v] != u && !~id[v] && v != root)
                    vis[v] = u, v = E[pe[v]].u;
                if (v != root && !~id[v]) {
                    for (int x = E[pe[v]].u; x != v;
                        x = E[pe[x]].u)
                        id[x] = cntnode;
                    id[v] = cntnode++;
                }
            }
            if (!cntnode) break; // no cycle
            for (int u = 0; u < n; ++u)
                if (!~id[u]) id[u] = cntnode++;
            for (int i = 0; i < (int)E.size(); ++i) {
                int v = E[i].v;
                E[i].u = id[E[i].u], E[i].v = id[E[i].v];
                if (E[i].u != E[i].v) E[i].w -= in[v];
            }
            n = cntnode, root = id[root];
        }
        return ans;
    }
};

```

II Directed MST (fast)

```

// O(E + V log V)
#define rep(i, a, b) for (int i = a; i < (b); ++i)
#define sz(x) (int(x).size())
typedef vector<int> vi;
struct RollbackUF {
    vi e;
    vector<pii> st;
    RollbackUF(int n) : e(n, -1) {}
    int size(int x) { return -e[find(x)]; }
    int find(int x) { return e[x] < 0 ? x : find(e[x]); }
    int time() { return sz(st); }
    void rollback(int t) {
        for (int i = time(); i-- > t;)
            e[st[i].first] = st[i].second;
        st.resize(t);
    }
    bool join(int a, int b) {
        a = find(a), b = find(b);
        if (a == b) return false;
    }
};


```

```

if (e[a] > e[b]) swap(a, b);
st.push_back({a, e[a]});
st.push_back({b, e[b]});
e[a] += e[b];
e[b] = a;
return true;
}
};

struct Edge {
    int a, b;
    ll w;
};
struct Node { // lazy skew heap node
    Edge key;
    Node *l, *r;
    ll delta;
    void prop() {
        key.w += delta;
        if (l) l->delta += delta;
        if (r) r->delta += delta;
        delta = 0;
    }
    Edge top() {
        prop();
        return key;
    }
};
Node *merge(Node *a, Node *b) {
    if (!a || !b) return a ?: b;
    a->prop(), b->prop();
    if (a->key.w > b->key.w) swap(a, b);
    swap(a->l, (a->r = merge(b, a->r)));
    return a;
}
void pop(Node *&a) {
    a->prop();
    a = merge(a->l, a->r);
}

pair<ll, vi> dmst(int n, int r, vector<Edge> &g) {
    RollbackUF uf(n);
    vector<Node *> heap(n);
    for (Edge e : g)
        heap[e.b] = merge(heap[e.b], new Node{e});
    ll res = 0;
    vi seen(n, -1), path(n), par(n);
    seen[r] = r;
    vector<Edge> Q(n), in(n, {-1, -1}), comp;
    deque<tuple<int, int, vector<Edge>>> cycs;
    rep(s, 0, n) {
        int u = s, qi = 0, w;
        while (seen[u] < 0) {
            if (!heap[u]) return {-1, {}};
            Edge e = heap[u]->top();
            heap[u]->delta -= e.w, pop(heap[u]);
            Q[qi] = e, path[qi++] = u, seen[u] = s;
            res += e.w, u = uf.find(e.a);
            if (seen[u] == s) { // found cycle, contract
                Node *cyc = new Node();
                int end = qi, time = uf.time();
                do cyc = merge(cyc, heap[w = path[--qi]]);
                while (uf.join(u, w));
                u = uf.find(u), heap[u] = cyc, seen[u] = -1;
                cycs.push_front({u, time, {&Q[qi], &Q[qi]}});
            }
        }
        rep(i, 0, qi) in[uf.find(Q[i].b)] = Q[i];
    }
    for (auto &[u, t, cmp] : cycs) {
        // restore sol (optional)
        uf.rollback(t);
        Edge inEdge = in[u];
        for (auto &e : cmp) in[uf.find(e.b)] = e;
        in[uf.find(inEdge.b)] = inEdge;
    }
    rep(i, 0, n) par[i] = in[i].a;
}


```

```

    return {res, par};
}

```

1J Minimum Clique Cover

```

struct CliqueCover {
    // 0-base, O(n2^n), 用最少數量的團覆蓋無向圖
    int co[1 << N], n, E[N];
    int dp[1 << N];
    void init(int _n) {
        n = _n, fill_n(dp, 1 << n, 0);
        fill_n(E, n, 0), fill_n(co, 1 << n, 0);
    }
    void add_edge(int u, int v) {
        E[u] |= 1 << v, E[v] |= 1 << u;
    }
    int solve() {
        for (int i = 0; i < n; ++i)
            co[1 << i] = E[i] | (1 << i);
        co[0] = (1 << n) - 1;
        dp[0] = (n & 1) * 2 - 1;
        for (int i = 1; i < (1 << n); ++i) {
            int t = i & -i;
            dp[i] = -dp[i ^ t];
            co[i] = co[i ^ t] & co[t];
        }
        for (int i = 0; i < (1 << n); ++i)
            co[i] = (co[i] & i) == i;
        fwt(co, 1 << n, 1); // needs FWHT
        for (int ans = 1; ans < n; ++ans) {
            int sum = 0; // probabilistic
            for (int i = 0; i < (1 << n); ++i)
                sum += (dp[i] *= co[i]);
            if (sum) return ans;
        }
        return n;
    }
}

```

1K Count Maximal Clique

```

struct BronKerbosch { // 1-base
    int n, a[N], g[N][N];
    int S, all[N][N], some[N][N], none[N][N];
    void init(int _n) {
        n = _n;
        for (int i = 1; i <= n; ++i)
            for (int j = 1; j <= n; ++j) g[i][j] = 0;
    }
    void add_edge(int u, int v) {
        g[u][v] = g[v][u] = 1;
    }
    void dfs(int d, int an, int sn, int nn) {
        if (S > 1000) return; // pruning
        if (sn == 0 && nn == 0) ++S;
        int u = some[d][0];
        for (int i = 0; i < sn; ++i) {
            int v = some[d][i];
            if (g[u][v]) continue;
            int tsn = 0, tnn = 0;
            copy_n(all[d], an, all[d + 1]);
            all[d + 1][an] = v;
            for (int j = 0; j < sn; ++j)
                if (g[v][some[d][j]])
                    some[d + 1][tsn++] = some[d][j];
            for (int j = 0; j < nn; ++j)
                if (g[v][none[d][j]])
                    none[d + 1][tnn++] = none[d][j];
            dfs(d + 1, an + 1, tsn, tnn);
            some[d][i] = 0, none[d][nn++] = v;
        }
    }
    int solve() {
        iota(some[0], some[0] + n, 1);
        S = 0, dfs(0, 0, n, 0);
        return S;
    }
}

```

```

    };

```

1L Theorems

$|\max \text{ independent edge set}| = |V| - |\min \text{ edge cover}|$
 $|\max \text{ independent set}| = |V| - |\min \text{ vertex cover}|$

2 Flow-Matching

2A Hopcroft-Karp

```

struct HopcroftKarp { // 0-based, return btoa to
    get matching, O(E sqrt(V)) bipartite graph matching
    bool dfs(int a, int L, vector<vector<int>> &g,
              vector<int> &btoa, vector<int> &A,
              vector<int> &B) {
        if (A[a] != L) return 0;
        A[a] = -1;
        for (int b : g[a])
            if (B[b] == L + 1) {
                B[b] = 0;
                if (btoa[b] == -1 || dfs(btoa[b], L + 1, g, btoa, A, B))
                    return btoa[b] = a, 1;
            }
        return 0;
    }
    int solve(vector<vector<int>> &g, int m) {
        int res = 0;
        vector<int> btoa(m, -1), A(g.size()), B(btoa.size()), cur, next;
        for (;;) {
            fill(all(A), 0), fill(all(B), 0);
            cur.clear();
            for (int a : btoa)
                if (a != -1) A[a] = -1;
            for (int a = 0; a < (int)g.size(); a++)
                if (A[a] == 0) cur.push_back(a);
            for (int lay = 1;; lay++) {
                bool islast = 0;
                next.clear();
                for (int a : cur)
                    for (int b : g[a]) {
                        if (btoa[b] == -1) {
                            B[b] = lay;
                            islast = 1;
                        } else if (btoa[b] != a && !B[b]) {
                            B[b] = lay;
                            next.push_back(btoa[b]);
                        }
                    }
                if (islast) break;
                if (next.empty()) return res;
                for (int a : next) A[a] = lay;
                cur.swap(next);
            }
            for (int a = 0; a < (int)g.size(); a++)
                res += dfs(a, 0, g, btoa, A, B);
        }
        return res;
    // or btoa
}

```

```

};

```

2B KM (Hungarian Alg.)

```

struct KM { // 0-base, maximum matching
    ll w[N][N], hl[N], hr[N], slk[N];
    int fl[N], fr[N], pre[N], qu[N], ql, qr, n;
    bool vl[N], vr[N];
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n; ++i)
            fill_n(w[i], n, -INF);
    }
    void add_edge(int a, int b, ll wei) {
        w[a][b] = wei;
    }
    bool Check(int x) {

```

```

    if (vl[x] = 1, ~fl[x])
        return vr[qu[qr++]] = fl[x] = 1;
    while (~x) swap(x, fr[fl[x] = pre[x]]);
    return 0;
}
void bfs(int s) {
    fill_n(slk
        , n, INF), fill_n(vl, n, 0), fill_n(vr, n, 0);
    ql = qr = 0, qu[qr++] = s, vr[s] = 1;
    for (ll d;;) {
        while (ql < qr)
            for (int x = 0, y = qu[ql++]; x < n; ++x)
                if (!vl[x] && slk
                    [x] >= (d = hl[x] + hr[y] - w[x][y])) {
                        if (pre[x] = y, d) slk[x] = d;
                        else if (!Check(x)) return;
                }
        d = INF;
        for (int x = 0; x < n; ++x)
            if (!vl[x] && d > slk[x]) d = slk[x];
        for (int x = 0; x < n; ++x) {
            if (vl[x]) hl[x] += d;
            else slk[x] -= d;
            if (vr[x]) hr[x] -= d;
        }
        for (int x = 0; x < n; ++x)
            if (!vl[x] && !slk[x] && !Check(x)) return;
    }
}
ll solve() {
    fill_n(fl
        , n, -1), fill_n(fr, n, -1), fill_n(hr, n, 0);
    for (int i = 0; i < n; ++i)
        hl[i] = *max_element(w[i], w[i] + n);
    for (int i = 0; i < n; ++i) bfs(i);
    ll res = 0;
    for (int i = 0; i < n; ++i) res += w[i][fl[i]];
    return res;
}
};

```

2C Max Flow (Dinic)

```

struct BoundedFlow { // 0-base
    struct edge { // note int!
        int to, cap, flow, rev;
    };
    vector<edge> G[N];
    int n, s, t, dis[N], cur[N], cnt[N];
    void init(int _n) {
        n = _n;
        for (int i = 0; i < n + 2; ++i)
            G[i].clear(), cnt[i] = 0;
    }
    void add_edge(int u, int v, int lcap, int rcap) {
        cnt[u] -= lcap, cnt[v] += lcap;
        G[u].emplace_back(
            edge{v, rcap, lcap, (int)G[v].size()});
        G[v].emplace_back(
            edge{u, 0, 0, (int)G[u].size() - 1});
    }
    void add_edge(int u, int v, int cap) {
        G[u].emplace_back(
            edge{v, cap, 0, (int)G[v].size()});
        G[v].emplace_back(
            edge{u, 0, 0, (int)G[u].size() - 1});
    }
    int dfs(int u, int cap) {
        if (u == t || !cap) return cap;
        for (int &i = cur[u]; i < (int)G[u].size(); ++i) {
            edge &e = G[u][i];
            if (dis[e.to] == dis[u] + 1 && e.cap != e.flow) {
                int df = dfs(e.to, min(e.cap - e.flow, cap));
                if (df) {
                    e.flow += df, G[e.to][e.rev].flow -= df;
                    return df;
                }
            }
        }
    }
};

```

```

        }
    }
    dis[u] = -1;
    return 0;
}
bool bfs() {
    fill_n(dis, n + 3, -1);
    queue<int> q;
    q.push(s), dis[s] = 0;
    while (!q.empty()) {
        int u = q.front();
        q.pop();
        for (edge &e : G[u])
            if (!~dis[e.to] && e.flow != e.cap)
                q.push(e.to), dis[e.to] = dis[u] + 1;
    }
    return dis[t] != -1;
}
int maxflow(int _s, int _t) {
    s = _s, t = _t;
    int flow = 0, df;
    while (bfs()) {
        fill_n(cur, n + 3, 0);
        while ((df = dfs(s, INF))) flow += df;
    }
    return flow;
}
bool solve() {
    int sum = 0;
    for (int i = 0; i < n; ++i)
        if (cnt[i] > 0)
            add_edge(n + 1, i, cnt[i]), sum += cnt[i];
        else if (cnt[i] < 0) add_edge(i, n + 2, -cnt[i]);
    if (sum != maxflow(n + 1, n + 2)) sum = -1;
    for (int i = 0; i < n; ++i)
        if (cnt[i] > 0)
            G[n + 1].pop_back(), G[i].pop_back();
        else if (cnt[i] < 0)
            G[i].pop_back(), G[n + 2].pop_back();
    return sum != -1;
}
int solve(int _s, int _t) {
    add_edge(_t, _s, INF);
    if (!solve()) return -1; // invalid flow
    int x = G[_t].back().flow;
    return G[_t].pop_back(), G[_s].pop_back(), x;
}
};


```

2D MCMF

```

struct MinCostMaxFlow { // 0-base
    struct Edge {
        ll from, to, cap, flow, cost, rev;
    };
    *past[N];
    vector<Edge> G[N];
    int inq[N], n, s, t;
    ll dis[N], up[N], pot[N];
    bool BellmanFord() {
        fill_n(dis, n, INF), fill_n(inq, n, 0);
        queue<int> q;
        auto relax = [&](int u, ll d, ll cap, Edge *e) {
            if (cap > 0 && dis[u] > d) {
                dis[u] = d, up[u] = cap, past[u] = e;
                if (!inq[u]) inq[u] = 1, q.push(u);
            }
        };
        relax(s, 0, INF, 0);
        while (!q.empty()) {
            int u = q.front();
            q.pop(), inq[u] = 0;
            for (auto &e : G[u]) {
                ll d2 = dis[u] + e.cost + pot[u] - pot[e.to];
                relax(
                    e.to, d2, min(up[u], e.cap - e.flow), &e);
            }
        }
    }
};


```

```

    }
    return dis[t] != INF;
}
bool Dijkstra() {
    fill_n(dis, n, INF);
    priority_queue<pll, vector<pll>, greater<pll>> pq;
    auto relax = [&](int u, ll d, ll cap, Edge *e) {
        if (cap > 0 && dis[u] > d) {
            dis[u] = d, up[u] = cap, past[u] = e;
            pq.push(pll(d, u));
        }
    };
    relax(s, 0, INF, 0);
    while (!pq.empty()) {
        auto [d, u] = pq.top();
        pq.pop();
        if (dis[u] != d) continue;
        for (auto &e : G[u]) {
            ll d2 = dis[u] + e.cost + pot[u] - pot[e.to];
            relax(
                e.to, d2, min(up[u], e.cap - e.flow), &e);
        }
    }
    return dis[t] != INF;
}
void solve(int _s, int _t, ll &flow, ll &cost,
    bool neg = true) {
    s = _s, t = _t, flow = 0, cost = 0;
    if (neg) BellmanFord(), copy_n(dis, n, pot);
    // do BellmanFord() if time isn't tight
    for (; Dijkstra(); copy_n(dis, n, pot)) {
        for (int i = 0; i < n; ++i)
            dis[i] += pot[i] - pot[s];
        flow += up[t], cost += up[t] * dis[t];
        for (int i = t; past[i]; i = past[i]->from) {
            auto &e = *past[i];
            e.flow += up[t], G[e.to][e.rev].flow -= up[t];
        }
    }
    void init(int _n) {
        n = _n, fill_n(pot, n, 0);
        for (int i = 0; i < n; ++i) G[i].clear();
    }
    void add_edge(ll a, ll b, ll cap, ll cost) {
        G[a].emplace_back(
            Edge{a, b, cap, 0, cost, (int)G[b].size()});
        G[b].emplace_back(
            Edge{b, a, 0, 0, -cost, (int)G[a].size() - 1});
    }
}

```

2E General Graph Matching

```

struct Matching { // 0-base, O(VE^2)
    queue<int> q; int n;
    vector<int> fa, s, vis, pre, match;
    vector<vector<int>> G;
    int Find(int u)
    { return u == fa[u] ? u : fa[u] = Find(fa[u]); }
    int LCA(int x, int y) {
        static int tk = 0; tk++; x = Find(x); y = Find(y);
        for (;;) swap(x, y) if (x != n) {
            if (vis[x] == tk) return x;
            vis[x] = tk;
            x = Find(pre[match[x]]);
        }
    }
    void Blossom(int x, int y, int l) {
        for (; Find(x) != l; x = pre[y]) {
            pre[x] = y, y = match[x];
            if (s[y] == 1) q.push(y), s[y] = 0;
            for (int z: {x, y}) if (fa[z] == z) fa[z] = l;
        }
    }
    bool Bfs(int r) {

```

```

        iota(all(fa), 0); fill(all(s), -1);
        q = queue<int>(); q.push(r); s[r] = 0;
        for (; !q.empty(); q.pop()) {
            for (int x = q.front(); int u : G[x])
                if (s[u] == -1) {
                    if (pre[u] = x, s[u] = 1, match[u] == n) {
                        for (int a = u, b = x, last;
                            b != n; a = last, b = pre[a])
                            last =
                                match[b], match[b] = a, match[a] = b;
                        return true;
                    }
                    q.push(match[u]); s[match[u]] = 0;
                } else if (!s[u] && Find(u) != Find(x)) {
                    int l = LCA(u, x);
                    Blossom(x, u, l); Blossom(u, x, l);
                }
        }
        return false;
    }
    Matching(int _n) : n(_n), fa(n + 1), s(n + 1), vis
        (n + 1), pre(n + 1, n), match(n + 1, n), G(n) {}
    void add_edge(int u, int v)
    { G[u].emplace_back(v), G[v].emplace_back(u); }
    int solve() {
        int ans = 0;
        for (int x = 0; x < n; ++x)
            if (match[x] == n) ans += Bfs(x);
        return ans;
    } // match[x] == n means not matched
};

```

2F Max Weight Matching

```

#define rep(i, l, r) for (int i = (l); i <= (r); ++i)
struct WeightGraph { // 1-based, note int!
    struct edge {
        int u, v, w;
    };
    int n, nx;
    vector<int> lab;
    vector<vector<edge>> g;
    vector<int> slack, match, st, pa, S, vis;
    vector<vector<int>> flo, flo_from;
    queue<int> q;
    WeightGraph(int n_)
        : n(n_), nx(n * 2), lab(nx + 1),
          g(nx + 1, vector<edge>(nx + 1)), slack(nx + 1),
          flo(nx + 1), flo_from(nx + 1, vector<int>(n + 1, 0)),
          match = st = pa = S = vis = slack;
        rep(u, 1, n) rep(v, 1, n) g[u][v] = {u, v, 0};
    }
    int ED(edge e) {
        return lab[e.u] + lab[e.v] - g[e.u][e.v].w * 2;
    }
    void update_slack(int u, int x, int &s) {
        if (!s || ED(g[u][x]) < ED(g[s][x])) s = u;
    }
    void set_slack(int x) {
        slack[x] = 0;
        for (int u = 1; u <= n; ++u)
            if (g[u][x].w > 0 && st[u] != x && S[st[u]] == 0)
                update_slack(u, x, slack[x]);
    }
    void q_push(int x) {
        if (x <= n) q.push(x);
        else
            for (int y : flo[x]) q.push(y);
    }
    void set_st(int x, int b) {
        st[x] = b;
        if (x > n)
            for (int y : flo[x]) set_st(y, b);
    }
    vector<int> split_flo(auto &f, int xr) {
        auto it = find(all(f), xr);
        if (auto pr = it - f.begin(); pr % 2 == 1)

```

```

    reverse(1 + all(f)), it = f.end() - pr;
auto res = vector(f.begin(), it);
return f.erase(f.begin(), it), res;
}
void set_match(int u, int v) {
match[u] = g[u][v].v;
if (u <= n) return;
int xr = flo_from[u][g[v][u].u];
auto &f = flo[u], z = split_flo(f, xr);
rep(i, 0, (int)z.size() - 1)
set_match(z[i], z[i ^ 1]);
set_match(xr, v);
f.insert(f.end(), all(z));
}
void augment(int u, int v) {
for (;;) {
int xnv = st[match[u]];
set_match(u, v);
if (!xnv) return;
set_match(xnv, st[pa[xnv]]);
u = st[pa[xnv]], v = xnv;
}
}
int lca(int u, int v) {
static int t = 0;
++t;
for (++t; u || v; swap(u, v))
if (u) {
if (vis[u] == t) return u;
vis[u] = t;
u = st[match[u]];
if (u) u = st[pa[u]];
}
return 0;
}
void add_blossom(int u, int o, int v) {
int b = find(n + 1 + all(st), 0) - begin(st);
lab[b] = 0, S[b] = 0;
match[b] = match[o];
vector<int> f = {o};
for (int x = u, y; x != o; x = st[pa[y]])
f.emplace_back(x),
f.emplace_back(y = st[match[x]]), q.push(y);
reverse(1 + all(f));
for (int x = v, y; x != o; x = st[pa[y]])
f.emplace_back(x),
f.emplace_back(y = st[match[x]]), q.push(y);
flo[b] = f;
set_st(b, b);
for (int x = 1; x <= nx; ++x)
g[b][x].w = g[x][b].w = 0;
fill(all(flo_from[b]), 0);
for (int xs : flo[b]) {
for (int x = 1; x <= nx; ++x)
if (g[b][x].w == 0 ||
ED(g[xs][x]) < ED(g[b][x]))
g[b][x] = g[xs][x], g[x][b] = g[x][xs];
for (int x = 1; x <= n; ++x)
if (flo_from[xs][x]) flo_from[b][x] = xs;
}
set_slack(b);
}
void expand_blossom(int b) {
for (int x : flo[b]) set_st(x, x);
int xr = flo_from[b][g[b][pa[b]].u], xs = -1;
for (int x : split_flo(flo[b], xr)) {
if (xs == -1) {
xs = x;
continue;
}
pa[xs] = g[x][xs].u;
S[xs] = 1, S[x] = 0;
slack[xs] = 0;
set_slack(x);
q.push(x);
}
}

```

```

xs = -1;
}
for (int x : flo[b])
if (x == xr) S[x] = 1, pa[x] = pa[b];
else S[x] = -1, set_slack(x);
st[b] = 0;
}
bool on_found_edge(const edge &e) {
if (int u = st[e.u], v = st[e.v]; S[v] == -1) {
int nu = st[match[v]];
pa[v] = e.u;
S[v] = 1;
slack[v] = slack[nu] = 0;
S[nu] = 0;
q.push(nu);
} else if (S[v] == 0) {
if (int o = lca(u, v)) add_blossom(u, o, v);
else return augment(u, v), augment(v, u), true;
}
return false;
}
bool matching() {
fill(all(S), -1), fill(all(slack), 0);
q = queue<int>();
for (int x = 1; x <= nx; ++x)
if (st[x] == x && !match[x])
pa[x] = 0, S[x] = 0, q.push(x);
if (q.empty()) return false;
for (;;) {
while (q.size()) {
int u = q.front();
q.pop();
if (S[st[u]] == 1) continue;
for (int v = 1; v <= n; ++v)
if (g[u][v].w > 0 && st[u] != st[v]) {
if (ED(g[u][v]) != 0)
update_slack(u, st[v], slack[st[v]]);
else if (on_found_edge(g[u][v]))
return true;
}
}
int d = INF;
for (int b = n + 1; b <= nx; ++b)
if (st[b] == b && S[b] == 1)
d = min(d, lab[b] / 2);
for (int x = 1; x <= nx; ++x)
if (int s = slack[x];
st[x] == x && s && S[x] <= 0)
d = min(d, ED(g[s][x]) / (S[x] + 2));
for (int u = 1; u <= n; ++u)
if (S[st[u]] == 1) lab[u] += d;
else if (S[st[u]] == 0) {
if (lab[u] <= d) return false;
lab[u] -= d;
}
}
rep(b, n + 1, nx) if (st[b] == b && S[b] >= 0)
lab[b] += d * (2 - 4 * S[b]);
for (int x = 1; x <= nx; ++x)
if (int s = slack[x]; st[x] == x && s &&
st[s] != x && ED(g[s][x]) == 0)
if (on_found_edge(g[s][x])) return true;
for (int b = n + 1; b <= nx; ++b)
if (st[b] == b && S[b] == 1 && lab[b] == 0)
expand_blossom(b);
}
return false;
}
pair<ll, int> solve() {
fill(all(match), 0);
rep(u, 0, n) st[u] = u, flo[u].clear();
int w_max = 0;
rep(u, 1, n) rep(v, 1, n) {
flo_from[u][v] = (u == v ? u : 0);
w_max = max(w_max, g[u][v].w);
}
}
```

```

fill(all(lab), w_max);
int n_matches = 0;
ll tot_weight = 0;
while (matching()) ++n_matches;
rep(u, 1, n) if (match[u] && match[u] < u)
    tot_weight += g[u][match[u]].w;
return make_pair(tot_weight, n_matches);
}
void add_edge(int u, int v, int w) {
    g[u][v].w = g[v][u].w = w;
}
};

```

2G Global Min Cut

```

struct StoerWagner { // O(V^3), is it O(VE + V log V)?
int vst[N], edge[N][N], wei[N];
void init(int n) {
    for (int i = 0; i < n; ++i) fill_n(edge[i], n, 0);
}
void addEdge(int u, int v, int w) {
    edge[u][v] += w;
    edge[v][u] += w;
}
int search(int &s, int &t, int n) {
    fill_n(vst, n, 0), fill_n(wei, n, 0);
    s = t = -1;
    int mx, cur;
    for (int j = 0; j < n; ++j) {
        mx = -1, cur = 0;
        for (int i = 0; i < n; ++i)
            if (wei[i] > mx) cur = i, mx = wei[i];
        vst[cur] = 1, wei[cur] = -1;
        s = t;
        t = cur;
        for (int i = 0; i < n; ++i)
            if (!vst[i]) wei[i] += edge[cur][i];
    }
    return mx;
}
int solve(int n) {
    int res = INF;
    for (int x, y; n > 1; n--) {
        res = min(res, search(x, y, n));
        for (int i = 0; i < n; ++i)
            edge[i][x] = (edge[x][i] += edge[y][i]);
        for (int i = 0; i < n; ++i) {
            edge[y][i] = edge[n - 1][i];
            edge[i][y] = edge[i][n - 1];
        } // edge[y][y] = 0;
    }
    return res;
}
} sw;

```

2H Gomory-Hu Tree

```

// 最小割樹，樹上兩點最小割 = 樹上兩點最小割
BoundedFlow Dinic;
int g[N];
void add_edge(int u, int v, int w); // TODO
void GomoryHu(int n) { // 0-base
    fill_n(g, n, 0);
    for (int i = 1; i < n; ++i) {
        Dinic.init(n);
        // build the graph
        add_edge(i, g[i], Dinic.maxflow(i, g[i]));
        for (int j = i + 1; j <= n; ++j)
            if (g[j] == g[i] && ~Dinic.dis[j])
                g[j] = i;
    }
}

```

2I Min Cost Circulation

```

struct MinCostCirculation { // 0-base
    struct Edge {
        ll from, to, cap, fcap, flow, cost, rev;
    };
}

```

```

} *past[N];
vector<Edge> G[N];
ll dis[N], inq[N], n;
void BellmanFord(int s) {
    fill_n(dis, n, INF), fill_n(inq, n, 0);
    queue<int> q;
    auto relax = [&](int u, ll d, Edge *e) {
        if (dis[u] > d) {
            dis[u] = d, past[u] = e;
            if (!inq[u]) inq[u] = 1, q.push(u);
        }
    };
    relax(s, 0, 0);
    while (!q.empty()) {
        int u = q.front();
        q.pop(), inq[u] = 0;
        for (auto &e : G[u])
            if (e.cap > e.flow)
                relax(e.to, dis[u] + e.cost, &e);
    }
}
void try_edge(Edge &cur) {
    if (cur.cap > cur.flow) return ++cur.cap, void();
    BellmanFord(cur.to);
    if (dis[cur.from] + cur.cost < 0) {
        ++cur.flow, --G[cur.to][cur.rev].flow;
        for (int i = cur.from; past[i]; i = past[i]->from) {
            auto &e = *past[i];
            ++e.flow, --G[e.to][e.rev].flow;
        }
        ++cur.cap;
    }
}
void solve(int mxlg) {
    for (int b = mxlg; b >= 0; --b) {
        for (int i = 0; i < n; ++i)
            for (auto &e : G[i])
                e.cap *= 2, e.flow *= 2;
        for (int i = 0; i < n; ++i)
            for (auto &e : G[i])
                if (e.fcap > b & 1)
                    try_edge(e);
    }
}
void init(int _n) { n = _n;
    for (int i = 0; i < n; ++i) G[i].clear();
}
void add_edge(ll a, ll b, ll cap, ll cost) {
    G[a].emplace_back(Edge{a, b, 0, cap, 0, cost, (ll)G[b].size() + (a == b)});
    G[b].emplace_back(Edge{b, a, 0, 0, -cost, (ll)G[a].size() - 1});
}
} mcmf; // O(VE * ElogC)

```

2J Flow Models Building

- Maximum/Minimum flow with lower bound / Circulation problem
 1. Construct super source S and sink T .
 2. For each edge (x,y,l,u) , connect $x \rightarrow y$ with capacity $u-l$.
 3. For each vertex v , denote by $in(v)$ the difference between the sum of incoming lower bounds and the sum of outgoing lower bounds.
 4. If $in(v) > 0$, connect $S \rightarrow v$ with capacity $in(v)$, otherwise, connect $v \rightarrow T$ with capacity $-in(v)$.
 - To maximize, connect $t \rightarrow s$ with capacity ∞ (skip this in circulation problem), and let f be the maximum flow from S to T . If $f \neq \sum_{v \in V, in(v) > 0} in(v)$, there's no solution. Otherwise, the maximum flow from s to t is the answer.
 - To minimize, let f be the maximum flow from S to T . Connect $t \rightarrow s$ with capacity ∞ and let the flow from S to T be f' . If $f + f' \neq \sum_{v \in V, in(v) > 0} in(v)$, there's no solution. Otherwise, f' is the answer.
 5. The solution of each edge e is $l_e + f_e$, where f_e corresponds to the flow of edge e on the graph.

- Construct minimum vertex cover from maximum matching M on bipartite graph (X,Y)
 - Redirect every edge: $y \rightarrow x$ if $(x,y) \in M$, $x \rightarrow y$ otherwise.
 - DFS from unmatched vertices in X .
 - $x \in X$ is chosen iff x is unvisited.
 - $y \in Y$ is chosen iff y is visited.
- Minimum cost cyclic flow
 - Construct super source S and sink T
 - For each edge (x,y,c) , connect $x \rightarrow y$ with $(cost, cap) = (c, 1)$ if $c > 0$, otherwise connect $y \rightarrow x$ with $(cost, cap) = (-c, 1)$
 - For each edge with $c < 0$, sum these cost as K , then increase $d(y)$ by 1, decrease $d(x)$ by 1
 - For each vertex v with $d(v) > 0$, connect $S \rightarrow v$ with $(cost, cap) = (0, d(v))$
 - For each vertex v with $d(v) < 0$, connect $v \rightarrow T$ with $(cost, cap) = (0, -d(v))$
 - Flow from S to T , the answer is the cost of the flow $C+K$
- Maximum density induced subgraph
 - Binary search on answer, suppose we're checking answer T
 - Construct a max flow model, let K be the sum of all weights
 - Connect source $s \rightarrow v$, $v \in G$ with capacity K
 - For each edge (u,v,w) in G , connect $u \rightarrow v$ and $v \rightarrow u$ with capacity w
 - For $v \in G$, connect it with sink $v \rightarrow t$ with capacity $K+2T-(\sum_{e \in E(v)} w(e))-2w(v)$
 - T is a valid answer if the maximum flow $f < K|V|$
- Minimum weight edge cover
 - For each $v \in V$ create a copy v' , and connect $u' \rightarrow v'$ with weight $w(u,v)$.
 - Connect $v \rightarrow v'$ with weight $2\mu(v)$, where $\mu(v)$ is the cost of the cheapest edge incident to v .
 - Find the minimum weight perfect matching on G' .
- Project selection problem
 - If $p_v > 0$, create edge (s,v) with capacity p_v ; otherwise, create edge (v,t) with capacity $-p_v$.
 - Create edge (u,v) with capacity w with w being the cost of choosing u without choosing v .
 - The mincut is equivalent to the maximum profit of a subset of projects.
- Dual of minimum cost maximum flow
 - Capacity c_{uv} , Flow f_{uv} , Cost w_{uv} , Required Flow difference for vertex b_u .
 - If all w_{uv} are integers, then optimal solution can happen when all p_u are integers.
$$\min \sum_{uv} w_{uv} f_{uv}$$

$$-f_{uv} \geq -c_{uv} \Leftrightarrow \min \sum_u b_u p_u + \sum_{uv} c_{uv} \max(0, p_v - p_u - w_{uv})$$

$$\sum_v f_{vu} - \sum_v f_{uv} = -b_u \quad p_u \geq 0$$

3 Data Struture

3A LichaoTree

```
struct lichao { // maxn: range
    struct line {
        ll a, b;
        line() : a(0), b(0) {} // or b(LINF) if min
        line(ll a, ll b) : a(a), b(b) {}
        ll operator()(ll x) { return a * x + b; }
        // v[x] if after discretization
    } arr[maxn << 2];
    void insert(int l, int r, int id, line x) {
        int m = (l + r) >> 1;
        if (arr[id](m) < x(m)) swap(arr[id], x);
        if (l == r - 1) return;
        if (arr[id].a < x.a) insert(m, r, id << 1 | 1, x);
        else insert(l, m, id << 1, x);
    } // change to > if query min
    // maxn -> v.size() after li san hua
    void insert(ll a, ll b) {
        insert(0, maxn, 1, line(a, b));
    }
    ll que(int l, int r, int id, int p) {
        if (l == r - 1) return arr[id](p);
        int m = (l + r) >> 1;
        if (p < m)
            return max(arr[id](p), que(l, m, id << 1, p));
        else
            return min(arr[id](p), que(m, r, id << 1, p));
    }
}
```

```
return max(arr[id](p), que(m, r, id << 1 | 1, p));
} // chnage to min if query min
// maxn -> v.size() after li san hua
ll que(int p) { return que(0, maxn, 1, p); }
} tree;
```

3B Treap

```
mt19937 rd(1);
#define sz(t) ((t) == 0 ? 0 : (t)->size)
struct Treap {
    int pri, size;
    Treap *l, *r;
    Treap(ll val = 0) : pri(rd()), size(1), l(0), r(0) {};
    void push(); void pull() { size = 1 + sz(l) + sz(r); }
};
void spilt(int k, Treap *rt, Treap *&a, Treap *&b) {
    if (!rt) return a = b = 0, void();
    rt->push();
    int lsz = 1 + sz(rt->l);
    if (k >= lsz)
        a = rt, spilt(k - lsz, a->r, a->r, b), a->pull();
    else b = rt, spilt(k, b->l, a, b->l), b->pull();
}
Treap *merge(Treap *l, Treap *r) {
    if (!l) return r;
    if (!r) return l;
    if (l->pri < r->pri) {
        l->push(), l->r = merge(l->r, r), l->pull();
        return l;
    } else {
        r->push(), r->l = merge(l, r->l), r->pull();
        return r;
    }
}
```

3C LinkCutTree

```
#define ls(x) Tree[x].son[0]
#define rs(x) Tree[x].son[1]
#define fa(x) Tree[x].fa
struct node {
    int son[2], Min, id, fa, lazy;
} Tree[N];
int n, m, q, w[N], Min;
struct Node {
    int u, v, w;
} a[N];
inline bool IsRoot(int x) {
    return (ls(fa(x)) == x || rs(fa(x)) == x) ? false
        : true;
}
inline void PushUp(int x) {
    Tree[x].Min = w[x], Tree[x].id = x;
    if (ls(x) && Tree[ls(x)].Min < Tree[x].Min) {
        Tree[x].Min = Tree[ls(x)].Min;
        Tree[x].id = Tree[ls(x)].id;
    }
    if (rs(x) && Tree[rs(x)].Min < Tree[x].Min) {
        Tree[x].Min = Tree[rs(x)].Min;
        Tree[x].id = Tree[rs(x)].id;
    }
}
inline void Update(int x) {
    Tree[x].lazy ^= 1;
    swap(ls(x), rs(x));
}
inline void PushDown(int x) {
    if (!Tree[x].lazy) return;
    if (ls(x)) Update(ls(x));
    if (rs(x)) Update(rs(x));
    Tree[x].lazy = 0;
}
inline void Rotate(int x) {
    int y = fa(x), z = fa(y), k = rs(y) == x,
```

```

        w = Tree[x].son[!k];
    if (!IsRoot(y)) Tree[z].son[rs(z) == y] = x;
    fa(x) = z, fa(y) = x;
    if (w) fa(w) = y;
    Tree[x].son[!k] = y, Tree[y].son[k] = w;
    PushUp(y);
}

inline void Splay(int x) {
    stack<int> Stack;
    int y = x, z;
    Stack.push(y);
    while (!IsRoot(y)) Stack.push(y = fa(y));
    while (!Stack.empty())
        PushDown(Stack.top()), Stack.pop();
    while (!IsRoot(x)) {
        y = fa(x), z = fa(y);
        if (!IsRoot(y))
            Rotate((ls(y) == x) ^ (ls(z) == y) ? x : y);
        Rotate(x);
    }
    PushUp(x);
}

inline void Access(int root) {
    for (int x = 0; root; x = root, root = fa(root))
        Splay(root), rs(root) = x, PushUp(root);
}

inline void MakeRoot(int x) {
    Access(x), Splay(x), Update(x);
}

inline int FindRoot(int x) {
    Access(x), Splay(x);
    while (ls(x)) x = ls(x);
    return Splay(x), x;
}

inline void Link(int u, int v) {
    MakeRoot(u);
    if (FindRoot(v) != u) fa(u) = v;
}

inline void Cut(int u, int v) {
    MakeRoot(u);
    if (FindRoot(v) != u || fa(v) != u || ls(v)) return;
    fa(v) = rs(u) = 0;
}

inline void Split(int u, int v) {
    MakeRoot(u), Access(v), Splay(v);
}

inline bool Check(int u, int v) {
    return MakeRoot(u), FindRoot(v) == u;
}

inline int LCA(int root, int u, int v) {
    MakeRoot(root), Access(u), Access(v), Splay(u);
    if (!fa(u)) {
        Access(u), Splay(v);
        return fa(v);
    }
    return fa(u);
}

/* ETT
每次進入節點和走邊都放入一次共  $3n - 2$ 
node(u) 表示進入節點  $u$  放入 treap 的位置
edge(u, v) 表示  $u \rightarrow v$  的邊放入 treap 的位置 (push v)
Makeroott u :
L1 = [begin, node(u) - 1], L2 = [node(u), end]
-> L2 + L1
Insert u, v :
Tu -> L1 = [begin, node(u) - 1], L2 = [node(u), end]
Tv -> L3 = [begin, node(v) - 1], L4 = [node(v), end]
-> L2 + L1 + edge(u, v) + L4 + L3 + edge(v, u)

Delete u, v :
maybe need swap u, v
T -> L1 + edge(u, v) + L2 + edge(v, u) + L3
-> L1 + L3, L2
*/

```

3D CentroidDecomposition

```

struct Cent_Dec { // 1-base
    vector<pll> G[N];
    pll info[N]; // store info. of itself
    pll upinfo[N]; // store info. of climbing up
    int n, pa[N], layer[N], sz[N], done[N];
    ll dis[lg(N) + 1][N];
    void init(int _n) {
        n = _n, layer[0] = -1;
        fill_n(pa + 1, n, 0), fill_n(done + 1, n, 0);
        for (int i = 1; i <= n; ++i) G[i].clear();
    }
    void add_edge(int a, int b, int w) {
        G[a].pb(pll(b, w)), G[b].pb(pll(a, w));
    }
    void get_cent(
        int u, int f, int &mx, int &c, int num) {
        int mxsz = 0;
        sz[u] = 1;
        for (pll e : G[u])
            if (!done[e.X] && e.X != f) {
                get_cent(e.X, u, mx, c, num);
                sz[u] += sz[e.X], mxsz = max(mxsz, sz[e.X]);
            }
        if (mx > max(mxsz, num - sz[u]))
            mx = max(mxsz, num - sz[u]), c = u;
    }
    void dfs(int u, int f, ll d, int org) {
        // if required, add self info or climbing info
        dis[layer[org]][u] = d;
        for (pll e : G[u])
            if (!done[e.X] && e.X != f)
                dfs(e.X, u, d + e.Y, org);
    }
    int cut(int u, int f, int num) {
        int mx = 1e9, c = 0, lc;
        get_cent(u, f, mx, c, num);
        done[c] = 1, pa[c] = f, layer[c] = layer[f] + 1;
        for (pll e : G[c])
            if (!done[e.X]) {
                if (sz[e.X] > sz[c])
                    lc = cut(e.X, c, num - sz[c]);
                else lc = cut(e.X, c, sz[e.X]);
                upinfo[lc] = pll(), dfs(e.X, c, e.Y, c);
            }
        return done[c] = 0, c;
    }
    void build() { cut(1, 0, n); }
    void modify(int u) {
        for (int a = u, ly = layer[a]; a;
             a = pa[a], --ly) {
            info[a].X += dis[ly][u], ++info[a].Y;
            if (pa[a])
                upinfo[a].X += dis[ly - 1][u], ++upinfo[a].Y;
        }
    }
    ll query(int u) {
        ll rt = 0;
        for (int a = u, ly = layer[a]; a;
             a = pa[a], --ly) {
            rt += info[a].X + info[a].Y * dis[ly][u];
            if (pa[a])
                rt -=
                    upinfo[a].X + upinfo[a].Y * dis[ly - 1][u];
        }
        return rt;
    }
};

```

3E HeavylightDecomposition

```

struct Heavy_light_Decomposition { // 1-base
    int n, ulink[N], deep[N], mxson[N], w[N], pa[N];
    int t, pl[N], data[N], dt[N], bln[N], edge[N], et;
    vector<pii> G[N];

```

```

void init(int _n) {
    n = _n, t = 0, et = 1;
    for (int i = 1; i <= n; ++i)
        G[i].clear(), mxson[i] = 0;
}
void add_edge(int a, int b, int w) {
    G[a].pb(pii(b, et));
    G[b].pb(pii(a, et));
    edge[et++] = w;
}
void dfs(int u, int f, int d) {
    w[u] = 1, pa[u] = f, deep[u] = d++;
    for (auto &i : G[u])
        if (i.X != f) {
            dfs(i.X, u, d), w[u] += w[i.X];
            if (w[mxson[u]] < w[i.X]) mxson[u] = i.X;
        } else bIn[i.Y] = u, dt[u] = edge[i.Y];
}
void cut(int u, int link) {
    data[pl[u]] = t++ = dt[u], ulink[u] = link;
    if (!mxson[u]) return;
    cut(mxson[u], link);
    for (auto i : G[u])
        if (i.X != pa[u] && i.X != mxson[u])
            cut(i.X, i.X);
}
void build() { dfs(1, 1, 1), cut(1, 1), /*build*/; }
int query(int a, int b) {
    int ta = ulink[a], tb = ulink[b], re = 0;
    while (ta != tb)
        if (deep[ta] < deep[tb])
            /*query*/, tb = ulink[b = pa[tb]];
        else /*query*/, ta = ulink[a = pa[ta]];
    if (a == b) return re;
    if (pl[a] > pl[b]) swap(a, b);
    /*query*/
    return re;
}

```

4 String

4A KMP

```

vector<int> pi(const string& s) {
    vector<int> p((int)s.size());
    for (int i=1; i<(int)s.size(); i++) {
        int g = p[i-1];
        while (g && s[i] != s[g]) g = p[g-1];
        p[i] = g + (s[i] == s[g]);
    }
    return p;
}

```

4B Z

```

vector<int> Z(const string& S) {
    vector<int> z((int)S.size());
    int l = -1, r = -1;
    for (int i=1; i<(int)S.size(); i++) {
        z[i] = i >= r ? 0 : min(r - i, z[i - l]);
        while (i +
            z[i] < (int)S.size() && S[i + z[i]] == S[z[i]])
            z[i]++;
        if (i + z[i] > r)
            l = i, r = i + z[i];
    }
    return z;
}

```

4C Manacher

```

vector<int> manacher(const string& s) {
    int n = s.size();
    array<vector<int>, 2> p = {vector<int>(n+1), vector<int>(n)};
    for (int z
        = 0; z < 2; z++)
        for (int i=0, l=0, r=0; i < n; i++) {

```

```

            int t = r-i+z;
            if (i < r) p[z][i] = min(t, p[z][l+t]);
            int L = i-p[z][i], R = i+p[z][i]-!z;
            while (L>=1 && R+1<n && s[L-1] == s[R+1])
                p[z][i]++, L--, R++;
            if (R>r) l=L, r=R;
        }
        vector<int> res(n*2+1);
        for (int i=0; i<n; i++){
            res[2*i]=p[0][i];
            res[2*i+1]=p[1][i];
        }
        res[2*n]=p[0][n];
        return res;
    }

```

4D SuffixArray

```

struct SuffixArray {
#define add(x, k) (x + k + n) % n
    vector<int> sa, cnt, rk, tmp, lcp;
    // sa: order, rk[i]: pos of s[i..],
    // lcp[i]: LCP of sa[i], sa[i-1]
    void SA(string s) { // remember to append '\1'
        int n = (int)s.size();
        sa.resize(n), cnt.resize(n);
        rk.resize(n), tmp.resize(n);
        iota(all(sa), 0);
        sort(all(sa),
            [&](int i, int j) { return s[i] < s[j]; });
        rk[0] = 0;
        for (int i = 1; i < n; i++)
            rk[sa[i]] =
                rk[sa[i - 1]] + (s[sa[i - 1]] != s[sa[i]]);
        for (int k = 1; k <= n; k <= 1) {
            fill(all(cnt), 0);
            for (int i = 0; i < n; i++)
                cnt[rk[add(sa[i], -k)]]++;
            for (int i = 1; i < n; i++) cnt[i] += cnt[i - 1];
            for (int i = n - 1; i >= 0; i--)
                tmp[--cnt[rk[add(sa[i], -k)]]] =
                    add(sa[i], -k);
            sa.swap(tmp);
            tmp[sa[0]] = 0;
            for (int i = 1; i < n; i++)
                tmp[sa[i]] = tmp[sa[i - 1]] +
                    (rk[sa[i - 1]] != rk[sa[i]] ||
                     rk[add(sa[i - 1], k)] !=
                     rk[add(sa[i], k)]);
            rk.swap(tmp);
        }
    }
    void LCP(string s) {
        int n = (int)s.size(), k = 0;
        lcp.resize(n);
        for (int i = 0; i < n; i++)
            if (rk[i] == 0) lcp[rk[i]] = 0;
            else {
                if (k) k--;
                int j = sa[rk[i] - 1];
                while (
                    max(i, j) + k < n && s[i + k] == s[j + k])
                    k++;
                lcp[rk[i]] = k;
            }
    }
};

```

4E SA-IS(Induced Sorting)

```

auto sais(const auto &s) {
    const int n = (int)s.size(), z = ranges::max(s) + 1;
    if (n == 1) return vector{0};
    vector<int> c(z);
    for (int x : s) ++c[x];
    partial_sum(all(c), begin(c));
}

```

```

vector<int> sa(n);
auto I = views::iota(0, n);
vector<bool> t(n, true);
for (int i = n - 2; i >= 0; --i)
    t[i] =
        (s[i] == s[i + 1] ? t[i + 1] : s[i] < s[i + 1]);
auto is_lms = views::filter(
    [&t](int x) { return x && t[x] && !t[x - 1]; });
auto induce = [&] {
    for (auto x = c; int y : sa)
        if (y--)
            if (!t[y]) sa[x[s[y] - 1]++] = y;
    for (auto x = c; int y : sa | views::reverse)
        if (y--)
            if (t[y]) sa[--x[s[y]]] = y;
};
vector<int> lms, q(n);
lms.reserve(n);
for (auto x = c; int i : I | is_lms)
    q[i] = (int)lms.size(),
    lms.emplace_back(sa[--x[s[i]]] = i);
induce();
vector<int> ns((int)lms.size());
for (int j = -1, nz = 0; int i : sa | is_lms) {
    if (j >= 0) {
        int len = min({n - i, n - j, lms[q[i] + 1] - i});
        ns[q[i]] = nz += lexicographical_compare(
            begin(s) + j, begin(s) + j + len, begin(s) + i,
            begin(s) + i + len);
    }
    j = i;
}
fill(all(sa), 0);
auto nsa = sais(ns);
for (auto x = c; int y : nsa | views::reverse)
    y = lms[y], sa[--x[s[y]]] = y;
return induce(), sa;
}

// sa[i]: sa[i]-th suffix is the i-th lexicographically
// smallest suffix. hi[i]: LCP of suffix sa[i] and
// suffix sa[i - 1].
struct Suffix {
    int n;
    vector<int> sa, hi, ra;
    Suffix(const auto &s, int _n)
        : n(_n), hi(n), ra(n) {
        vector<int> s(n + 1); // s[n] = 0;
        copy_n(_s, n, begin(s)); // _s shouldn't contain 0
        sa = sais(s);
        sa.erase(sa.begin());
        for (int i = 0; i < n; ++i) ra[sa[i]] = i;
        for (int i = 0, h = 0; i < n; ++i) {
            if (!ra[i]) {
                h = 0;
                continue;
            }
            for (int j = sa[ra[i]] - 1;
                max(i, j) + h < n && s[i + h] == s[j + h];)
                ++h;
            hi[ra[i]] = h ? h-- : 0;
        }
    }
};

};


```

4F ACAutomaton

```

#define sigma 26
#define base 'a'
struct AhoCorasick { // N: sum of length
    int ch[N][sigma] = {{}}, f[N] = {-1}, tag[N],
    mv[N][sigma], jump[N], cnt[N];
    int idx = 0, t = -1;
    vector<int> E[N], q;
    pii o[N];
    int insert(string &s) {
        int j = 0;
        for (int i = 0; i < (int)s.size(); i++) {

```

```

            if (!ch[j][s[i] - base])
                ch[j][s[i] - base] = ++idx;
            j = ch[j][s[i] - base];
        }
        tag[j] = 1;
        return j;
    }
    int next(int u, int c) {
        return u < 0 ? 0 : mv[u][c];
    }
    void dfs(int u) {
        o[u].F = ++t;
        for (auto v : E[u]) dfs(v);
        o[u].S = t;
    }
    void build() {
        int k = -1;
        q.emplace_back(0);
        while (++k < (int)q.size()) {
            int u = q[k];
            for (int v = 0; v < sigma; v++) {
                if (ch[u][v]) {
                    f[ch[u][v]] = next(f[u], v);
                    q.emplace_back(ch[u][v]);
                }
                mv[u][v] =
                    (ch[u][v] ? ch[u][v] : next(f[u], v));
            }
            if (u) jump[u] = (tag[f[u]] ? f[u] : jump[f[u]]);
        }
        reverse(q.begin(), q.end());
        for (int i = 1; i <= idx; i++)
            E[f[i]].emplace_back(i);
        dfs(0);
    }
    void match(string &s) {
        fill(cnt, cnt + idx + 1, 0);
        for (int i = 0, j = 0; i < (int)s.size(); i++)
            cnt[j = next(j, s[i] - base)]++;
        for (int i : q)
            if (f[i] > 0) cnt[f[i]] += cnt[i];
    }
} ac;

```

4G MinRotation

```

int mincyc(string s) {
    int n = (int)s.size();
    s = s + s;
    int i = 0, ans = 0;
    while (i < n) {
        ans = i;
        int j = i + 1, k = i;
        while (j < 2 * n && s[j] >= s[k]) {
            k = (s[j] > s[k] ? i : k + 1);
            ++j;
        }
        while (i <= k) i += j - k;
    }
    return ans;
}

```

4H ExtSAM

```

#define CNUM 26
struct exSAM {
    int len[N * 2], link[N * 2]; // maxlen, suflink
    int next[N * 2][CNUM], tot; // [0, tot), root = 0
    int lenSorted[N * 2]; // topo. order
    int cnt[N * 2]; // occurrence
    int newnode() {
        fill_n(next[tot], CNUM, 0);
        len[tot] = cnt[tot] = link[tot] = 0;
        return tot++;
    }
    void init() { tot = 0, newnode(), link[0] = -1; }
    int insertSAM(int last, int c) {

```

```

int cur = next[last][c];
len[cur] = len[last] + 1;
int p = link[last];
while (p != -1 && !next[p][c])
    next[p][c] = cur, p = link[p];
if (p == -1) return link[cur] = 0, cur;
int q = next[p][c];
if (len
    [p] + 1 == len[q]) return link[cur] = q, cur;
int clone = newnode();
for (int i = 0; i < CNUM; ++i)
    next[
        clone][i] = len[next[q][i]] ? next[q][i] : 0;
len[clone] = len[p] + 1;
while (p != -1 && next[p][c] == q)
    next[p][c] = clone, p = link[p];
link[link[cur] = clone] = link[q];
link[q] = clone;
return cur;
}
void insert(const string &s) {
    int cur = 0;
    for (auto ch : s) {
        int &nxt = next[cur][int(ch - 'a')];
        if (!nxt) nxt = newnode();
        cnt[cur = nxt] += 1;
    }
}
void build() {
    queue<int> q;
    q.push(0);
    while (!q.empty()) {
        int cur = q.front();
        q.pop();
        for (int i = 0; i < CNUM; ++i)
            if (next[cur][i])
                q.push(insertSAM(cur, i));
    }
    vector<int> lc(tot);
    for (int i = 1; i < tot; ++i) ++lc[len[i]];
    partial_sum(all(lc), lc.begin());
    for (int i
        = 1; i < tot; ++i) lenSorted[--lc[len[i]]] = i;
}
void solve() {
    for (int i = tot - 2; i >= 0; --i)
        cnt[link[lenSorted[i]]] += cnt[lenSorted[i]];
}
};

```

5 Number Theory

5A Primes

12721 13331 14341 75577 123457 222557 556679 999983
 1097774749 1076767633 100102021 999997771 1001010013
 1000512343 987654361 999991231 999888733 98789101
 98777733 999991921 1010101333 1010102101 1000000000039
 100000000000037 2305843009213693951 4611686018427387847
 9223372036854775783 18446744073709551557

5B ExtGCD

```

// beware of negative numbers!
void extgcd(ll a, ll b, ll c, ll &x, ll &y) {
    if (b == 0) x = c / a, y = 0;
    else {
        extgcd(b, a % b, c, y, x);
        y -= x * (a / b);
    }
}

```

// $|x| \leq b/2$, $|y| \leq a/2$

5C FloorCeil

```

int floor(int a, int b)
{
    return a / b - (a % b && (a < 0) ^ (b < 0));
}
int ceil(int a, int b)
{
    return a / b + (a % b && (a < 0) ^ (b > 0));
}

```

5D FloorSum

Computes

$$f(a,b,c,n) = \sum_{i=0}^n \left\lfloor \frac{a \cdot i + b}{m} \right\rfloor$$

Furthermore, Let $m = \left\lfloor \frac{an+b}{c} \right\rfloor$:

$$g(a,b,c,n) = \sum_{i=0}^n i \left\lfloor \frac{ai+b}{c} \right\rfloor$$

$$= \begin{cases} \left\lfloor \frac{a}{c} \right\rfloor \cdot \frac{n(n+1)(2n+1)}{6} + \left\lfloor \frac{b}{c} \right\rfloor \cdot \frac{n(n+1)}{2} \\ + g(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ \frac{1}{2} \cdot (n(n+1)m - f(c, c-b-1, a, m-1)) \\ - h(c, c-b-1, a, m-1), & \text{otherwise} \end{cases}$$

$$h(a,b,c,n) = \sum_{i=0}^n \left\lfloor \frac{ai+b}{c} \right\rfloor^2$$

$$= \begin{cases} \left\lfloor \frac{a}{c} \right\rfloor^2 \cdot \frac{n(n+1)(2n+1)}{6} + \left\lfloor \frac{b}{c} \right\rfloor^2 \cdot (n+1) \\ + \left\lfloor \frac{a}{c} \right\rfloor \cdot \left\lfloor \frac{b}{c} \right\rfloor \cdot n(n+1) \\ + h(a \bmod c, b \bmod c, c, n) \\ + 2 \left\lfloor \frac{a}{c} \right\rfloor \cdot g(a \bmod c, b \bmod c, c, n) \\ + 2 \left\lfloor \frac{b}{c} \right\rfloor \cdot f(a \bmod c, b \bmod c, c, n), & a \geq c \vee b \geq c \\ 0, & n < 0 \vee a = 0 \\ nm(m+1) - 2g(c, c-b-1, a, m-1) \\ - 2f(c, c-b-1, a, m-1) - f(a, b, c, n), & \text{otherwise} \end{cases}$$

```

ll floorsum(ll A, ll B, ll C, ll N) {
    if (A == 0) return (N + 1) * (B / C);
    if (A > C || B > C)
        return (N + 1) * (B / C) +
            N * (N + 1) / 2 * (A / C) +
            floorsum(A % C, B % C, C, N);
    ll M = (A * N + B) / C;
    return N * M - floorsum(C, C - B - 1, A, M - 1);
}

```

5E MillerRabin

```

// n < 4,759,123,141      3 : 2, 7, 61
// n < 1,122,004,669,633  4 : 2, 13, 23, 1662803
// n < 3,474,749,660,383  6 : primes <= 13
// n < 2^64                 7 :
// 2, 325, 9375, 28178, 450775, 9780504, 1795265022
ll mul(ll a, ll b, ll mod) {
    return (ll)(__int128(a) * b % mod);
}
bool Miller_Rabin(ll a, ll n) { // O(log(n)^3)
    if ((a = a % n) == 0) return 1;
    if (n % 2 == 0) return n == 2;
    ll tmp = (n - 1) / ((n - 1) & (1 - n));
    ll t = __lg(((n - 1) & (1 - n))), x = 1;
    for (; tmp; tmp >>= 1, a = mul(a, a, n))
        if (tmp & 1) x = mul(x, a, n);
    if (x == 1 || x == n - 1) return 1;
    while (--t)
        if ((x = mul(x, x, n)) == n - 1) return 1;
    return 0;
}

```

5F PollardRho

```

map<ll, int> cnt;
void PollardRho(ll n) { // O(n^(1/4))
    if (n == 1) return;
    if (prime(n)) return ++cnt[n], void();
    if (n % 2 == 0)
        return PollardRho(n / 2), ++cnt[2], void();
    ll x = 2, y = 2, d = 1, p = 1;
    #define f(x, n, p) ((mul(x, x, n) + p) % n)
    while (true) {
        if (d != n && d != 1) {
            PollardRho(n / d);
            PollardRho(d);
            return;
        }
    }
}

```

```

    }
    if (d == n) ++p;
    x = f(x, n, p), y = f(f(y, n, p), n, p);
    d = gcd(abs(x - y), n);
}
}

```

5G Fraction

```

struct fraction {
    ll n, d;
    fraction(const ll &_n = 0, const ll &_d = 1)
        : n(_n), d(_d) {
        ll t = __gcd(n, d);
        n /= t, d /= t;
        if (d < 0) n = -n, d = -d;
    }
    fraction operator-() const {
        return fraction(-n, d);
    }
    fraction operator+(const fraction &b) const {
        return fraction(n * b.d + b.n * d, d * b.d);
    }
    fraction operator-(const fraction &b) const {
        return fraction(n * b.d - b.n * d, d * b.d);
    }
    fraction operator*(const fraction &b) const {
        return fraction(n * b.n, d * b.d);
    }
    fraction operator/(const fraction &b) const {
        return fraction(n * b.d, d * b.n);
    }
    void print() {
        cout << n;
        if (d != 1) cout << "/" << d;
    }
};

```

5H ChineseRemainder

```

ll solve(ll x1, ll m1, ll x2, ll m2) {
    ll g = gcd(m1, m2);
    if ((x2 - x1) % g) return -1; // no sol
    m1 /= g; m2 /= g;
    ll x, y;
    extgcd(m1, m2, __gcd(m1, m2), x, y);
    ll lcm = m1 * m2 * g;
    ll res = x * (x2 - x1) * m1 + x1;
    // be careful with overflow
    return (res % lcm + lcm) % lcm;
}

```

5I FactorialMod p^k

```

// O(p^k + log^2 n), pk = p^k
ll prod[MAXP];
ll fac_no_p(ll n, ll p, ll pk) {
    prod[0] = 1;
    for (int i = 1; i <= pk; ++i)
        if (i % p) prod[i] = prod[i - 1] * i % pk;
        else prod[i] = prod[i - 1];
    ll rt = 1;
    for (; n; n /= p) {
        rt = rt * mpow(prod[pk], n / pk, pk) % pk;
        rt = rt * prod[n % pk] % pk;
    }
    return rt;
} // (n! without factor p) % p^k

```

5J QuadraticResidue

```

// Berlekamp-Rabin, log^2(p)
ll trial(ll y, ll z, ll m) {
    ll a0 = 1, a1 = 0, b0 = z, b1 = 1, p = (m - 1) / 2;
    while (p) {
        if (p & 1)
            tie(a0, a1) =
                make_pair((a1 * b1 % m * y + a0 * b0) % m,

```

```

                (a0 * b1 + a1 * b0) % m);
        tie(b0, b1) =
            make_pair((b1 * b1 % m * y + b0 * b0) % m,
                (2 * b0 * b1) % m);
        p >>= 1;
    }
    if (a1) return inv(a1, m);
    return -1;
}
mt19937 rd(49);
ll psqrt(ll y, ll p) { // sqrt(y) mod p
    if (y == 0) return 0;
    if (fpow(y, (p - 1) / 2, p) != 1) return -1;
    for (int i = 0; i < 30; i++) {
        ll z = rd() % p;
        if (z * z % p == y) return z;
        ll x = trial(y, z, p);
        if (x == -1) continue;
        return x;
    }
    return -1;
}

```

5K MeisselLehmer

```

ll PrimeCount(ll n) { // n ~ 10^13 => < 2s
    if (n <= 1) return 0;
    int v = sqrt(n), s = (v + 1) / 2, pc = 0;
    vector<int> smalls(v + 1), skip(v + 1), roughs(s);
    vector<ll> larges(s);
    for (int i = 2; i <= v; ++i) smalls[i] = (i + 1) / 2;
    for (int i = 0; i < s; ++i) {
        roughs[i] = 2 * i + 1;
        larges[i] = (n / (2 * i + 1) + 1) / 2;
    }
    for (int p = 3; p <= v; ++p) {
        if (smalls[p] > smalls[p - 1]) {
            int q = p * p;
            ++pc;
            if (1LL * q * q > n) break;
            skip[p] = 1;
            for (int i = q; i <= v; i += 2 * p) skip[i] = 1;
            int ns = 0;
            for (int k = 0; k < s; ++k) {
                int i = roughs[k];
                if (skip[i]) continue;
                ll d = 1LL * i * p;
                larges[ns] = larges[k] - (d <= v ? larges
                    [smalls[d] - pc] : smalls[n / d]) + pc;
                roughs[ns++] = i;
            }
            s = ns;
            for (int j = v / p; j >= p; --j) {
                int c =
                    smalls[j] - pc, e = min(j * p + p, v + 1);
                for (int i = j * p; i < e; ++i) smalls[i] -= c;
            }
        }
        for (int k = 1; k < s; ++k) {
            const ll m = n / roughs[k];
            ll t = larges[k] - (pc + k - 1);
            for (int l = 1; l < k; ++l) {
                int p = roughs[l];
                if (1LL * p * p > m) break;
                t -= smalls[m / p] - (pc + l - 1);
            }
            larges[0] -= t;
        }
    }
    return larges[0];
}

```

5L DiscreteLog

```

int DiscreteLog(int s, int x, int y, int m) {
    constexpr int kStep = 32000;
    unordered_map<int, int> p;
    int b = 1;

```

```

for (int i = 0; i < kStep; ++i) {
    p[y] = i;
    y = 1LL * y * x % m;
    b = 1LL * b * x % m;
}
for (int i = 0; i < m + 10; i += kStep) {
    s = 1LL * s * b % m;
    if (p.find(s) != p.end()) return i + kStep - p[s];
}
return -1;
}

int DiscreteLog(int x, int y, int m) {
    if (m == 1) return 0;
    int s = 1;
    for (int i = 0; i < 100; ++i) {
        if (s == y) return i;
        s = 1LL * s * x % m;
    }
    if (s == y) return 100;
    int p = 100 + DiscreteLog(s, x, y, m);
    if (fpow(x, p, m) != y) return -1;
    return p;
}

```

5M Theorems

- Cramer's Rule

$$\begin{aligned} ax+by=e \\ cx+dy=f \end{aligned} \Rightarrow \begin{aligned} x &= \frac{ed-bf}{ad-bc} \\ y &= \frac{af-ec}{ad-bc} \end{aligned}$$

- Vandermonde's Identity

$$C(n+m,k) = \sum_{i=0}^k C(n,i)C(m,k-i)$$

- Kirchhoff's Theorem

Denote L be a $n \times n$ matrix as the Laplacian matrix of graph G , where $L_{ii}=d(i)$, $L_{ij}=-c$ where c is the number of edge (i,j) in G .

- The number of undirected spanning in G is $|\det(\tilde{L}_{11})|$.
- The number of directed spanning tree rooted at r in G is $|\det(\tilde{L}_{rr})|$.

- Tutte's Matrix

Let D be a $n \times n$ matrix, where $d_{ij} = x_{ij}$ (x_{ij} is chosen uniformly at random) if $i < j$ and $(i,j) \in E$, otherwise $d_{ij} = -d_{ji}$. $\frac{\text{rank}(D)}{2}$ is the maximum matching on G .

- Cayley's Formula

- Given a degree sequence d_1, d_2, \dots, d_n for each labeled vertices, there are $\frac{(n-2)!}{(d_1-1)!(d_2-1)!\cdots(d_n-1)!}$ spanning trees.
- Let $T_{n,k}$ be the number of labeled forests on n vertices with k components, such that vertex $1, 2, \dots, k$ belong to different components. Then $T_{n,k} = kn^{n-k-1}$.

- Erdős-Gallai Theorem

A sequence of nonnegative integers $d_1 \geq \dots \geq d_n$ can be represented as the degree sequence of a finite simple graph on n vertices if and only if $d_1 + \dots + d_n$ is even and $\sum_{i=1}^k d_i \leq k(k-1) + \sum_{i=k+1}^n \min(d_i, k)$ holds for every $1 \leq k \leq n$.

- Gale-Ryser Theorem

A pair of sequences of nonnegative integers $a_1 \geq \dots \geq a_n$ and b_1, \dots, b_n is bigraphic (degree sequence of bipartite graph) if and only if $\sum_{i=1}^n a_i = \sum_{i=1}^n b_i$ and $\sum_{i=1}^k a_i \leq \sum_{i=1}^n \min(b_i, k)$ holds for every $1 \leq k \leq n$.

- Fulkerson-Chen-Anstee Theorem

A sequence $(a_1, b_1), \dots, (a_n, b_n)$ of nonnegative integer pairs with $a_1 \geq \dots \geq a_n$ is digraphic (in, out degree of a directed graph) if and only if $\sum_{i=1}^n a_i = \sum_{i=1}^n b_i$ and $\sum_{i=1}^k a_i \leq \sum_{i=1}^k \min(b_i, k-1) + \sum_{i=k+1}^n \min(b_i, k)$ holds for every $1 \leq k \leq n$.

- Möbius Inversion Formula

- $f(n) = \sum_{d|n} g(d) \Leftrightarrow g(n) = \sum_{d|n} \mu(d) f\left(\frac{n}{d}\right)$
- $f(n) = \sum_{n|d} g(d) \Leftrightarrow g(n) = \sum_{n|d} \mu\left(\frac{d}{n}\right) f(d)$

- Lagrange Multiplier

- Optimize $f(x_1, \dots, x_n)$ when k constraints $g_i(x_1, \dots, x_n) = 0$.

- Lagrangian function $\mathcal{L}(x_1, \dots, x_n, \lambda_1, \dots, \lambda_k) = f(x_1, \dots, x_n) - \sum_{i=1}^k \lambda_i g_i(x_1, \dots, x_n)$.
- The solution corresponding to the original constrained optimization is always a saddle point of the Lagrangian function.

5N Estimation

• Number of divisors	$n \leq$	100	10^3	10^6	10^9	10^{12}	10^{15}	10^{18}
	$\max d(n)$	12	32	240	1344	6720	26880	103680
• Unordered integer partition	n	2	3	4	5	6	7	8
	$p(n)$	2	3	5	7	11	15	22
	n	9	20	30	40	50	60	100
	B_n	2	5	15	52	203	877	4140
								$2 \cdot 10^{-5}$
								$2 \cdot 10^{-8}$

5O Numbers

- Bernoulli numbers

$$B_0 = 1, B_1^{\pm} = \pm \frac{1}{2}, B_2 = \frac{1}{6}, B_3 = 0$$

$$\sum_{j=0}^m \binom{m+1}{j} B_j = 0, \text{ EGF is } B(x) = \frac{x}{e^x - 1} = \sum_{n=0}^{\infty} B_n \frac{x^n}{n!}.$$

$$S_m(n) = \sum_{k=1}^n k^m = \frac{1}{m+1} \sum_{k=0}^m \binom{m+1}{k} B_k^+ n^{m+1-k}$$
- Stirling numbers of the second kind Partitions of n distinct elements into exactly k groups.

$$S(n,k) = S(n-1, k-1) + kS(n-1, k), S(n,1) = S(n,n) = 1$$

$$S(n,k) = \frac{1}{k!} \sum_{i=0}^k (-1)^{k-i} \binom{k}{i} i^n$$

$$x^n = \sum_{i=0}^n S(n,i) (x)_i$$
- Pentagonal number theorem

$$\prod_{n=1}^{\infty} (1-x^n) = 1 + \sum_{k=1}^{\infty} (-1)^k \left(x^{k(3k+1)/2} + x^{k(3k-1)/2} \right)$$
- Catalan numbers

$$C_n^{(k)} = \frac{1}{(k-1)n+1} \binom{kn}{n}$$

$$C^{(k)}(x) = 1 + x[C^{(k)}(x)]^k$$
- Eulerian numbers

Number of permutations $\pi \in S_n$ in which exactly k elements are greater than the previous element. k : s.t. $\pi(j) > \pi(j+1)$, $k+1$: s.s.t. $\pi(j) \geq j$, k : s.s.t. $\pi(j) > j$.

$$E(n,k) = (n-k)E(n-1, k-1) + (k+1)E(n-1, k)$$

$$E(n,0) = E(n, n-1) = 1$$

$$E(n,k) = \sum_{j=0}^k (-1)^j \binom{n+1}{j} (k+1-j)^n$$

5P GeneratingFunctions

- Ordinary Generating Function $A(x) = \sum_{i \geq 0} a_i x^i$
 - $A(rx) \Rightarrow r^n a_n$
 - $A(x) + B(x) \Rightarrow a_n + b_n$
 - $A(x)B(x) \Rightarrow \sum_{i=0}^n a_i b_{n-i}$
 - $A(x)^k \Rightarrow \sum_{i_1+i_2+\dots+i_k=n} a_{i_1} a_{i_2} \dots a_{i_k}$
 - $xA(x)' \Rightarrow nan$
 - $\frac{A(x)}{1-x} \Rightarrow \sum_{i=0}^n a_i$
- Exponential Generating Function $A(x) = \sum_{i \geq 0} \frac{a_i}{i!} x^i$
 - $A(x) + B(x) \Rightarrow a_n + b_n$
 - $A^{(k)}(x) \Rightarrow a_{n+k}$
 - $A(x)B(x) \Rightarrow \sum_{i=0}^n \binom{n}{i} a_i b_{n-i}$
 - $A(x)^k \Rightarrow \sum_{i_1+i_2+\dots+i_k=n} \binom{n}{i_1, i_2, \dots, i_k} a_{i_1} a_{i_2} \dots a_{i_k}$
 - $xA(x) \Rightarrow na_n$
- Special Generating Function
 - $(1+x)^n = \sum_{i \geq 0} \binom{n}{i} x^i$
 - $\frac{1}{(1-x)^n} = \sum_{i \geq 0} \binom{i}{n-1} x^i$
 - $S_k = \sum_{x=1}^n x^k : S = \sum_{p=0}^{\infty} x^p = \frac{e^x - e^{x(n+1)}}{1-e^x}$

6 Linear Algebra

6A Gaussian Elimination

```

struct matrix { // m variables, n equations
    int n, m;
    fraction A[N][N + 1], sol[N];
    int solve() { // -1: inconsistent, >= 0: rank
        for (int i = 0; i < n; ++i) {
            int piv = 0;
            while (piv < m && !A[i][piv].n) ++piv;
            if (piv == m) continue;
            for (int j = 0; j < n; ++j) {
                if (i == j) continue;
                fraction tmp = -A[j][piv] / A[i][piv];
                for (int k = 0; k <= m; ++k)
                    A[j][k] += tmp * A[i][k];
            }
        }
    }
}

```

```

        A[j][k] = tmp * A[i][k] + A[j][k];
    }
}

int rank = 0;
for (int i = 0; i < n; ++i) {
    int piv = 0;
    while (piv < m && !A[i][piv].n) ++piv;
    if (piv == m && A[i][m].n) return -1;
    else if (piv < m)
        ++rank, sol[piv] = A[i][m] / A[i][piv];
}
return rank;
}

```

6B BerlekampMassey

```

template <typename T>
vector<T> BerlekampMassey(const vector<T> &output) {
    vector<T> d(output.size() + 1), me, he;
    for (int f = 0, i = 1; i <= output.size(); ++i) {
        for (int j = 0; j < me.size(); ++j)
            d[i] += output[i - j - 2] * me[j];
        if ((d[i] -= output[i - 1]) == 0) continue;
        if (me.empty()) {
            me.resize(f = i);
            continue;
        }
        vector<T> o(i - f - 1);
        T k = -d[i] / d[f];
        o.emplace_back(-k);
        for (T x : he) o.emplace_back(x * k);
        o.resize(max(o.size(), me.size()));
        for (int j = 0; j < me.size(); ++j) o[j] += me[j];
        if (i - f + (int)he.size() >= (int)me.size()) he = me, f = i;
        me = o;
    }
    return me;
}

```

6C Simplex

Standard form: maximize $\mathbf{c}^T \mathbf{x}$ subject to $A\mathbf{x} \leq \mathbf{b}$ and $\mathbf{x} \geq 0$.
Dual LP: minimize $\mathbf{b}^T \mathbf{y}$ subject to $A^T \mathbf{y} \geq \mathbf{c}$ and $\mathbf{y} \geq 0$.
 $\bar{\mathbf{x}}$ and $\bar{\mathbf{y}}$ are optimal if and only if for all $i \in [1, n]$, either $\bar{x}_i = 0$ or $\sum_{j=1}^m A_{ji} \bar{y}_j = c_i$ holds and for all $i \in [1, m]$ either $\bar{y}_i = 0$ or $\sum_{j=1}^n A_{ij} \bar{x}_j = b_j$ holds.

1. In case of minimization, let $c'_i = -c_i$
2. $\sum_{1 \leq i \leq n} A_{ji} x_i \geq b_j \rightarrow \sum_{1 \leq i \leq n} -A_{ji} x_i \leq -b_j$
3. $\sum_{1 \leq i \leq n} A_{ji} x_i = b_j$
 - $\sum_{1 \leq i \leq n} A_{ji} x_i \leq b_j$
 - $\sum_{1 \leq i \leq n} A_{ji} x_i \geq b_j$
4. If x_i has no lower bound, replace x_i with $x_i - x'_i$

```

struct Simplex {
    using T = long double;
    static const int N = 50, M = 100;
    const T eps = 1e-7;
    int n, m;
    int Left[M], Down[N];
    T a[M][N], b[M], c[N], v, sol[N];
    bool eq(T a, T b) { return fabs(a - b) < eps; }
    bool ls (T a, T b) { return a < b && !eq(a, b); }
    void init(int _n, int _m) {
        n = _n, m = _m, v = 0;
        for(int i = 0; i < m; ++i) for (int j = 0; j < n; ++j) {
            a[i][j] = 0;
        }
        for(int i = 0; i < m; ++i) b[i] = 0;
        for(int i = 0; i < n; ++i) c[i] = sol[i] = 0;
    }
    void pivot(int x, int y) {
        swap(Left[x], Down[y]);
        T k = a[x][y]; a[x][y] = 1;
        vector<int> nz;
        for(int i = 0; i < n; ++i) {
            a[x][i] /= k;
        }
    }
}

```

```

if(!eq(a[x][i], 0)) nz.push_back(i);
}
b[x] /= k;
for(int i = 0 ; i < m; ++i) {
    if(i == x || eq(a[i][y], 0)) continue;
    k = a[i][y], a[i][y] = 0;
    b[i] -= k * b[x];
    for(int j : nz) a[i][j] -= k * a[x][j];
}
if(eq(c[y], 0)) return;
k = c[y], c[y] = 0, v += k * b[x];
for(int i : nz) c[i] -= k * a[x][i];
}
int solve() {
    for(int i = 0; i < n; ++i) Down[i] = i;
    for(int i = 0; i < m; ++i) Left[i] = n + i;
    while(1) {
        int x = -1, y = -1;
        for(int i = 0; i < m; ++i) if(
            ls(b[i], 0) && (x == -1 || b[i] < b[x])) x = i;
        if(x == -1) break;
        for(int i = 0; i < n; ++i) if(ls(a[x][i], 0) && (y == -1 || a[x][i] < a[x][y])) y = i;
        if(y == -1) return 1;
        pivot(x, y);
    }
    while(1) {
        int x = -1, y = -1;
        for(int i = 0; i < n; ++i) if(
            ls(0, c[i]) && (y == -1 || c[i] > c[y])) y = i;
        if(y == -1) break;
        for(int i = 0; i < m; ++i) if(ls(0, a[i][y]) && (x == -1 || b[i] / a[i][y] < b[x] / a[x][y])) x = i;
        if (x == -1) return 2;
        pivot(x, y);
    }
    for(int i = 0; i < m; ++i) if(Left[i] < n) sol[Left[i]] = b[i];
    return 0;
}
}

```

7 Polynomials

7A NTT (FFT)

	Mod	g	Form
65 537	3	$2^{16} + 1$	
998 244 353	3	$119 \cdot 2^{23} + 1$	
1 315 962 881	3	$1255 \cdot 2^{20} + 1$	
1 711 276 033	29	$51 \cdot 2^{25} + 1$	
9 223 372 036 737 335 297	3	$549755813881 \cdot 2^{24} + 1$	

```

#define base ll // complex<double>
// const double PI = acos(-1);
const ll mod = 998244353, g = 3;
base omega[4 * N], omega_[4 * N];
int rev[4 * N];

ll fpow(ll b, ll p);

ll inverse(ll a) { return fpow(a, mod - 2); }

void calcW(int n) {
    ll r = fpow(g, (mod - 1) / n), invr = inverse(r);
    omega[0] = omega_[0] = 1;
    for (int i = 1; i < n; i++) {
        omega[i] = omega[i - 1] * r % mod;
        omega_[i] = omega_[i - 1] * invr % mod;
    }
    // double arg = 2.0 * PI / n;
    // for (int i = 0; i < n; i++) {
    //     omega[i] = base(cos(i * arg), sin(i * arg));
    //     omega_[i] = base(cos(-i * arg), sin(-i * arg));
    // }
}

```

```

void calcrev(int n) {
    int k = __lg(n);
    for (int i = 0; i < n; i++) rev[i] = 0;
    for (int i = 0; i < n; i++)
        for (int j = 0; j < k; j++)
            if (i & (1 << j)) rev[i] ^= 1 << (k - j - 1);
}

vector<base> NTT(vector<base> poly, bool inv) {
    base *w = (inv ? omega_ : omega);
    int n = (int)poly.size();
    for (int i = 0; i < n; i++)
        if (rev[i] > i) swap(poly[i], poly[rev[i]]);

    for (int len = 1; len < n; len <= 1) {
        int arg = n / len / 2;
        for (int i = 0; i < n; i += 2 * len)
            for (int j = 0; j < len; j++) {
                base odd =
                    w[j * arg] * poly[i + j + len] % mod;
                poly[i + j + len] =
                    (poly[i + j] - odd + mod) % mod;
                poly[i + j] = (poly[i + j] + odd) % mod;
            }
    }
    if (inv)
        for (auto &a : poly) a = a * inverse(n) % mod;
    return poly;
}

vector<base> mul(vector<base> f, vector<base> g) {
    int sz = 1 << (__lg(f.size()) + g.size() - 1) + 1;
    f.resize(sz), g.resize(sz);
    calcrev(sz);
    calcW(sz);
    f = NTT(f, 0), g = NTT(g, 0);
    for (int i = 0; i < sz; i++)
        f[i] = f[i] * g[i] % mod;
    return NTT(f, 1);
}

```

7B FHTW

```

/* x: a[j], y: a[j + (L >> 1)]
or: (y += x * op), and: (x += y * op)
xor: (x, y = (x + y) * op, (x - y) * op)
op: 1, invop: or, and, xor = -1, -1, 1/2 */
void fwt(int *a, int n, int op) { // or
    for (int L = 2; L <= n; L <= 1)
        for (int i = 0; i < n; i += L)
            for (int j = i; j < i + (L >> 1); ++j)
                a[j + (L >> 1)] += a[j] * op;
}

const int P = 21; // power of max N
int f[P][1 << P], g[P][1 << P], h[P][1 << P],
ct[1 << P];
void subset_convolution(
    int *a, int *b, int *c, int L) {
    // c_k = \sum_{i | j = k, i & j = 0} a_i * b_j
    int n = 1 << L;
    for (int i = 1; i < n; ++i)
        ct[i] = ct[i & (i - 1)] + 1;
    for (int i = 0; i < n; ++i)
        f[ct[i]][i] = a[i], g[ct[i]][i] = b[i];
    for (int i = 0; i <= L; ++i)
        fwt(f[i], n, 1), fwt(g[i], n, 1);
    for (int i = 0; i <= L; ++i)
        for (int j = 0; j <= i; ++j)
            for (int x = 0; x < n; ++x)
                h[i][x] += f[j][x] * g[i - j][x];
    for (int i = 0; i <= L; ++i) fwt(h[i], n, -1);
    for (int i = 0; i < n; ++i) c[i] = h[ct[i]][i];
}

```

7C PolynomialOperations

```

#define poly vector<ll>
poly inv(poly A) {
    A.resize(1 << (__lg(A.size() - 1) + 1));
    poly B = {inverse(A[0])};
    for (int n = 1; n < (int)A.size(); n <= 1) {
        poly pA(A.begin(), A.begin() + 2 * n);
        calcrev(4 * n), calcW(4 * n);
        pA.resize(4 * n), B.resize(4 * n);
        pA = NTT(pA, 0);
        B = NTT(B, 0);
        for (int i = 0; i < 4 * n; i++)
            B[i] =
                ((B[i] * 2 - pA[i] * B[i] % mod * B[i]) % mod +
                 mod) %
                mod;
        B = NTT(B, 1);
        B.resize(2 * n);
    }
    return B;
}

pair<poly, poly> div(poly A, poly B) {
    if (A.size() < B.size()) return make_pair(poly(), A);
    int n = A.size(), m = B.size();
    poly revA = A, invrevB = B;
    reverse(all(revA)), reverse(all(invrevB));
    revA.resize(n - m + 1);
    invrevB.resize(n - m + 1);
    invrevB = inv(invrevB);
    poly Q = mul(revA, invrevB);
    Q.resize(n - m + 1);
    reverse(all(Q));
    poly R = mul(Q, B);
    R.resize(m - 1);
    for (int i = 0; i < m - 1; i++)
        R[i] = (A[i] - R[i] + mod) % mod;
    return make_pair(Q, R);
}

poly modulo(poly A, poly B) { return div(A, B).S; }

ll fast_kitamasa(ll k, poly A, poly C) {
    int n = A.size();
    C.emplace_back(mod - 1);
    poly Q, R = {0, 1}, F = {1};
    R = modulo(R, C);
    for (; k; k >= 1) {
        if (k & 1) F = modulo(mul(F, R), C);
        R = modulo(mul(R, R), C);
        k >= 1;
    }
    ll ans = 0;
    for (int i = 0; i < F.size(); i++)
        ans = (ans + A[i] * F[i]) % mod;
    return ans;
}

vector<ll> fpow(vector<ll> f, ll p, ll m) {
    int b = 0;
    while (b < f.size() && f[b] == 0) b++;
    f = vector<ll>(f.begin() + b, f.end());
    int n = f.size();
    f.emplace_back(0);
    vector<ll> q(min(m, b * p), 0);
    q.emplace_back(fpow(f[0], p));
    for (int k = 0; q.size() < m; k++) {
        ll res = 0;
        for (int i = 0; i < min(n, k + 1); i++)
            res = (res +
                   p * (i + 1) % mod * f[i + 1] % mod *
                   q[k - i + b * p]) %
                   mod;
        for (int i = 1; i < min(n, k + 1); i++)
            res = (res -
                   f[i] * (k - i + 1) % mod *
                   q[k - i + 1 + b * p]) %
                   mod;
        res = (res < 0 ? res + mod : res) *

```

```

    inv(f[0] * (k + 1) % mod) % mod;
    q.emplace_back(res);
}
return q;
}

```

7D NewtonMethod+MiscGF

Given $F(x)$ where

$$F(x) = \sum_{i=0}^{\infty} \alpha_i (x - \beta)^i$$

for β being some constant. Polynomial P such that $F(P) = 0$ can be found iteratively. Denote by Q_k the polynomial such that $F(Q_k) = 0 \pmod{x^{2^k}}$, then

$$Q_{k+1} = Q_k - \frac{F(Q_k)}{F'(Q_k)} \pmod{x^{2^{k+1}}}$$

- A^{-1} : $B_{k+1} = B_k(2 - AB_k) \pmod{x^{2^{k+1}}}$
- $\ln A$: $(\ln A)' = \frac{A'}{A}$
- $\exp A$: $B_{k+1} = B_k(1 + A - \ln B_k) \pmod{x^{2^{k+1}}}$
- \sqrt{A} : $B_{k+1} = \frac{1}{2}(B_k + AB_k^{-1}) \pmod{x^{2^{k+1}}}$

8 Geometry

8A Basic

```

typedef pair<pdd, pdd> Line;
struct Cir{ pdd O; double R; };
const double pi = acos(-1);
const double eps = 1e-8;
pll operator+(pll a, pll b)
{ return pll(a.F + b.F, a.S + b.S); }
pll operator-(pll a, pll b)
{ return pll(a.F - b.F, a.S - b.S); }
pll operator*(pll a)
{ return pll(-a.F, -a.S); }
pll operator*(pll a, ll b)
{ return pll(a.F * b, a.S * b); }
pdd operator/(pll a, double b)
{ return pdd(a.F / b, a.S / b); }
ll dot(pll a, pll b)
{ return a.F * b.F + a.S * b.S; }
ll cross(pll a, pll b)
{ return a.F * b.S - a.S * b.F; }
ll abs2(pll a)
{ return dot(a, a); }
double abs(pll a)
{ return sqrt(dot(a, a)); }
int sign(ll a)
{ return fabs(a) < eps ? 0 : a > 0 ? 1 : -1; }
int ori(pll a, pll b, pll c)
{ return sign(cross(b - a, c - a)); }
bool collinearity(pll p1, pll p2, pll p3)
{ return sign(cross(p1 - p3, p2 - p3)) == 0; }
bool btw(pll a, pll b, pll c) {
    return collinearity
        ((a, b, c) && sign(dot(a - c, b - c)) <= 0;
}
bool seg_strict_intersect
    (pdd p1, pdd p2, pdd p3, pdd p4) {
    int a123 = ori(p1, p2, p3);
    int a124 = ori(p1, p2, p4);
    int a341 = ori(p3, p4, p1);
    int a342 = ori(p3, p4, p2);
    return a123 * a124 < 0 && a341 * a342 < 0;
}
bool seg_intersect(pdd p1, pdd p2, pdd p3, pdd p4) {
    int a123 = ori(p1, p2, p3);
    int a124 = ori(p1, p2, p4);
    int a341 = ori(p3, p4, p1);
    int a342 = ori(p3, p4, p2);
    if (a123 == 0 && a124 == 0)
        return btw(p1, p2, p3) || btw(p1, p2, p4) ||
            btw(p3, p4, p1) || btw(p3, p4, p2);
    return a123 * a124 <= 0 && a341 * a342 <= 0;
}

```

```

pdd intersect(pdd p1, pdd p2, pdd p3, pdd p4) {
    double a123 = cross(p2 - p1, p3 - p1);
    double a124 = cross(p2 - p1, p4 - p1);
    return (p4
        * a123 - p3 * a124) / (a123 - a124); // C^3 / C^2
}
pdd orth(pdd p1)
{ return pdd(-p1.S, p1.F); }
pdd projection(pdd p1, pdd p2, pdd p3)
{ return p1 + (
    p2 - p1) * dot(p3 - p1, p2 - p1) / abs2(p2 - p1); }
pdd reflection(pdd p1, pdd p2, pdd p3)
{ return p3 + orth(p2 - p1
    ) * cross(p3 - p1, p2 - p1) / abs2(p2 - p1) * 2; }
pdd linearTransformation
    (pdd p0, pdd p1, pdd q0, pdd q1, pdd r) {
    pdd dp = p1 - p0
        , dq = q1 - q0, num(cross(dp, dq), dot(dp, dq));
    return q0 + pdd(
        cross(r - p0, num), dot(r - p0, num)) / abs2(dp);
} // from line p0--p1 to q0--q1, apply to r

```

8B ConvexHull

```

vector<pll> hull(vector<pll> dots) { // n=1 => ans = {}
    sort(dots.begin(), dots.end());
    vector<pll> ans(1, dots[0]);
    for (int ct = 0; ct < 2; ++ct, reverse(all(dots)))
        for (int i = 1, t = (int)ans.size();
            i < (int)dots.size();
            ans.emplace_back(dots[i++]))
            while ((int)ans.size() > t &&
                ori(ans.end()[-2], ans.back(), dots[i]) <= 0)
                ans.pop_back(); // "<" for keeping collinear
    ans.pop_back();
    return ans;
}

```

8C SortByAngle

```

bool down(pll k) {
    return sign(k.S) < 0 ||
        (sign(k.S) == 0 && sign(k.F) < 0);
}
int cmp(pll a, pll b, bool same = true) {
    int A = down(a), B = down(b);
    if (A != B) return A < B;
    if (sign(cross(a, b)) == 0)
        return same ? abs2(a) < abs2(b) : -1;
    return sign(cross(a, b)) > 0;
}

```

8D Formulas

- Rotation

$$M(\theta) = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix}$$

90 degree: $(x, y) = (Y - y, x)$

- Pick's theorem

For simple integer-coordinate polygon,

$$A = B + \frac{I}{2} - 1$$

Where A is the area; B, I is #lattice points in the interior, on the boundary.

- Spherical Cap

- A portion of a sphere cut off by a plane.
- r : sphere radius, a : radius of the base of the cap, h : height of the cap, θ : $\arcsin(a/r)$.
- Volume = $\pi h^2(3r - h)/3 = \pi h(3a^2 + h^2)/6 = \pi r^3(2 + \cos\theta)(1 - \cos\theta)^2/3$.
- Area = $2\pi rh = \pi(a^2 + h^2) = 2\pi r^2(1 - \cos\theta)$.

- Nearest points of two skew lines

- Line 1: $v_1 = p_1 + t_1 d_1$
- Line 2: $v_2 = p_2 + t_2 d_2$
- $n = d_1 \times d_2$
- $n_1 = d_1 \times n$
- $n_2 = d_2 \times n$
- $c_1 = p_1 + \frac{(p_2 - p_1) \cdot n_2}{d_1 \cdot n_2} d_1$
- $c_2 = p_2 + \frac{(p_1 - p_2) \cdot n_1}{d_2 \cdot n_1} d_2$

8E TriangleHearts

```

pdd excenter(
    pdd p0, pdd p1, pdd p2) { // radius = abs(center)
    p1 = p1 - p0, p2 = p2 - p0;
    auto [x1, y1] = p1;
    auto [x2, y2] = p2;
    double m = 2. * cross(p1, p2);
    pdd center = pdd((x1 * x1 * y2 - x2 * x2 * y1 +
        y1 * y2 * (y1 - y2)),
        (x1 * x2 * (x2 - x1) - y1 * y1 * x2 +
        x1 * y2 * y2)) / m;
    return center + p0;
}
pdd incenter(
    pdd p1, pdd p2, pdd p3) { // radius = area / s * 2
    double a = abs(p2 - p3), b = abs(p1 - p3),
        c = abs(p1 - p2);
    double s = a + b + c;
    return (p1 * a + p2 * b + p3 * c) / s;
}
pdd masscenter(pdd p1, pdd p2, pdd p3) {
    return (p1 + p2 + p3) / 3;
}
pdd orthcenter(pdd p1, pdd p2, pdd p3) {
    return masscenter(p1, p2, p3) * 3 -
        excenter(p1, p2, p3) * 2;
}

```

8F PointSegmentDist

```

double PointSegDist(pdd q0, pdd q1, pdd p) {
    if (abs(q0 - q1) <= eps) return abs(q0 - p);
    if (dot(q1 - q0,
        p - q0) >= -eps && dot(q0 - q1, p - q1) >= -eps)
        return fabs(cross(q1 - q0, p - q0) / abs(q0 - q1));
    return min(abs(p - q0), abs(p - q1));
}

```

8G PointInCircle

```

// return q'
// s relation with circumcircle of tri(p[0],p[1],p[2])
bool in_cc(const array<pll, 3> p, pll q) {
    __int128 det = 0;
    for (int i = 0; i < 3; ++i)
        det += __int128(abs2(p[i]) - abs2(q)) *
            cross(p[(i + 1) % 3] - q, p[(i + 2) % 3] - q);
    return det > 0; // in: >0, on: =0, out: <0
}

```

8H PointInConvex

```

bool PointInConvex
    (const vector<pll> &C, pll p, bool strict = true) {
    int a = 1, b = (int)C.size() - 1, r = !strict;
    if ((int)C.size() == 0) return false;
    if ((int)
        C.size() < 3) return r && btw(C[0], C.back(), p);
    if (ori(C[0], C[a], C[b]) > 0) swap(a, b);
    if (ori
        (C[0], C[a], p) >= r || ori(C[0], C[b], p) <= -r)
        return false;
    while (abs(a - b) > 1) {
        int c = (a + b) / 2;
        (ori(C[0], C[c], p) > 0 ? b : a) = c;
    }
    return ori(C[a], C[b], p) < r;
}

```

8I PointTangentConvex

```

/* The point should be strictly out of hull
   return arbitrary point on the tangent line */
/* bool pred(int a, int b);
f(0) ~ f(n - 1) is a cyclic-shift U-function
return idx s.t. pred(x, idx) is false for all x*/
int cyc_tsearch(int n, auto pred) {

```

```

if (n == 1) return 0;
int l = 0, r = n; bool rv = pred(1, 0);
while (r - l > 1) {
    int m = (l + r) / 2;
    if (pred(0, m) ? rv: pred(m, (m + 1) % n)) r = m;
    else l = m;
}
return pred(l, r % n) ? l : r % n;
}
pii get_tangent(vector<pll> &C, pll p) {
    auto gao = [&](int s) {
        return cyc_tsearch((int)C.size(), [&](int x, int y) {
            { return ori(p, C[x], C[y]) == s; });
    };
    return pii(gao(1), gao(-1));
} // return (a, b), ori(p, C[a], C[b]) >= 0

```

8J CircTangentCirc

```

vector<Line> go(Cir c1, Cir c2, int sign1) {
    // sign1 = 1 for outer tang, -1 for inter tang
    vector<Line> ret;
    double d_sq = abs2(c1.0 - c2.0);
    if (sign(d_sq) == 0) return ret;
    double d = sqrt(d_sq);
    pdd v = (c2.0 - c1.0) / d;
    double c = (c1.R - sign1 * c2.R) / d;
    if (c * c > 1) return ret;
    double h = sqrt(max(0.0, 1.0 - c * c));
    for (int sign2 = 1; sign2 >= -1; sign2 -= 2) {
        pdd n = pdd(v.F * c - sign2 * h * v.S,
            v.S * c + sign2 * h * v.F);
        pdd p1 = c1.0 + n * c1.R;
        pdd p2 = c2.0 + n * (c2.R * sign1);
        if (sign(p1.F - p2.F) == 0 and
            sign(p1.S - p2.S) == 0)
            p2 = p1 + perp(c2.0 - c1.0);
        ret.emplace_back(Line(p1, p2));
    }
    return ret;
}

```

8K LineCircleIntersect

```

vector<pdd> circleLine(pdd c, double r, pdd a, pdd b) {
    pdd p
        = a + (b - a) * dot(c - a, b - a) / abs2(b - a);
    double s = cross
        (b - a, c - a), h2 = r * r - s * s / abs2(b - a);
    if (h2 < 0) return {};
    if (h2 == 0) return {p};
    pdd h = (b - a) / abs(b - a) * sqrt(h2);
    return {p - h, p + h};
}

```

8L LineConvexIntersect

```

int cyc_tsearch(int n, auto pred); // ref: TanPointHull
int TangentDir(vector<pll> &C, pll dir) {
    return cyc_tsearch((int)C.size(), [&](int a, int b) {
        return cross(dir, C[a]) > cross(dir, C[b]);
    });
}
#define cmpL(i) sign(cross(C[i] - a, b - a))
pii lineHull(pll a, pll b, vector<pll> &C) {
    int A = TangentDir(C, a - b);
    int B = TangentDir(C, b - a);
    int n = (int)C.size();
    if (cmpL(A) < 0 || cmpL(B) > 0)
        return pii(-1, -1); // no collision
    auto gao = [&](int l, int r) {
        for (int t = l; (l + 1) % n != r;) {
            int m = ((l + r + (l < r ? 0 : n)) / 2) % n;
            (cmpL(m) == cmpL(t) ? l : r) = m;
        }
        return (l + !cmpL(r)) % n;
    };
}

```

```

pii res = pii(gao(B, A), gao(A, B)); // (i, j)
if (res.F == res.S) // touching the corner i
    return pii(res.F, -1);
if (!cmpL(res.F) &&
    !cmpL(res.S)) // along side i, i+1
    switch ((res.F - res.S + n + 1) % n) {
        case 0: return pii(res.F, res.F);
        case 2: return pii(res.S, res.S);
    }
/* crossing sides (i, i+1) and (j, j+1)
crossing corner i is treated as side (i, i+1)
returned in the same order as the line hits the
convex */
return res;
} // convex cut: (r, l)

```

8M CircIntersectCirc

```

bool CCinter(Cir &a, Cir &b, pdd &p1, pdd &p2) {
    pdd o1 = a.0, o2 = b.0;
    double r1 =
        a.R, r2 = b.R, d2 = abs2(o1 - o2), d = sqrt(d2);
    if(d < max
        (r1, r2) - min(r1, r2) || d > r1 + r2) return 0;
    pdd u = (o1 + o2) * 0.5
        + (o1 - o2) * ((r2 * r2 - r1 * r1) / (2 * d2));
    double A = sqrt((r1 + r2 + d) *
        (r1 - r2 + d) * (r1 + r2 - d) * (-r1 + r2 + d));
    pdd v
        = pdd(o1.S - o2.S, -o1.F + o2.F) * A / (2 * d2);
    p1 = u + v, p2 = u - v;
    return 1;
}

```

8N PolyIntersectCirc

```

// Divides into multiple triangle, and sum up
const double PI = acos(-1);
double _area(pdd pa, pdd pb, double r) {
    if (abs(pa) < abs(pb)) swap(pa, pb);
    if (abs(pb) < eps) return 0;
    double S, h, theta;
    double a = abs(pb), b = abs(pa), c = abs(pb - pa);
    double cosB = dot(pb, pb - pa) / a / c,
        B = acos(cosB);
    double cosC = dot(pa, pb) / a / b, C = acos(cosC);
    if (a > r) {
        S = (C / 2) * r * r;
        h = a * b * sin(C) / c;
        if (h < r && B < PI / 2)
            S -= (acos(h / r) * r * r -
                h * sqrt(r * r - h * h));
    } else if (b > r) {
        theta = PI - B - asin(sin(B) / r * a);
        S = .5 * a * r * sin(theta) +
            (C - theta) / 2 * r * r;
    } else S = .5 * sin(C) * a * b;
    return S;
}
double area_poly_circle(const vector<pdd> poly,
    const pdd &O, const double r) {
    double S = 0;
    for (int i = 0; i < (int)poly.size(); ++i)
        S += _area(poly[i] - O,
            poly[(i + 1) % (int)poly.size() - 0, r] *
            ori(
                0, poly[i], poly[(i + 1) % (int)poly.size()]);
    return fabs(S);
}

```

8O PolyUnion

```

double rat(pll a, pll b) {
    return sign
        (b.F) ? (double)a.F / b.F : (double)a.S / b.S;
} // all poly. should be ccw
double polyUnion(vector<vector<pll>> &poly) {
    double res = 0;

```

```

for (auto &p : poly)
    for (int a = 0; a < (int)p.size(); ++a) {
        pll A = p[a], B = p[(a + 1) % (int)p.size()];
        vector<pair<double, int>> segs = {{0, 0}, {1, 0}};
        for (auto &q : poly) {
            if (&p == &q) continue;
            for (int b = 0; b < (int)q.size(); ++b) {
                pll C = q[b], D = q[(b + 1) % (int)q.size()];
                int sc = ori(A, B, C), sd = ori(A, B, D);
                if (sc != sd && min(sc, sd) < 0) {
                    double sa = cross(D - C, B - C)
                        - C, A - C, sb = cross(D - C, B - C);
                    segs.emplace_back
                        (sa / (sa - sb), sign(sc - sd));
                }
            }
            if (!sc && !sd &&
                &q < &p && sign(dot(B - A, D - C)) > 0) {
                segs.emplace_back(rat(C - A, B - A), 1);
                segs.emplace_back(rat(D - A, B - A), -1);
            }
        }
        sort(all(segs));
        for (auto &s : segs) s.F = clamp(s.F, 0.0, 1.0);
        double sum = 0;
        int cnt = segs[0].second;
        for (int j = 1; j < (int)segs.size(); ++j) {
            if (!cnt) sum += segs[j].F - segs[j - 1].F;
            cnt += segs[j].S;
        }
        res += cross(A, B) * sum;
    }
    return res / 2;
}

```

8P MinkowskiSum

```

vector<pll> Minkowski
    (vector<pll> A, vector<pll> B) { // |A|, |B|>=3
    A = hull(A), B = hull(B);
    vector<pll> C(1, A[0] + B[0]), s1, s2;
    for (int i = 0; i < A.size(); ++i)
        s1.emplace_back(A[(i + 1) % A.size() - A[i]]);
    for (int i = 0; i < B.size(); ++i)
        s2.emplace_back(B[(i + 1) % B.size() - B[i]]);
    for (int i = 0, j = 0; i < A.size() || j < B.size();)
        if (j >= B.size()
            || (i < A.size() && cross(s1[i], s2[j]) >= 0))
            C.emplace_back(B[j % B.size()] + A[i++]);
        else
            C.emplace_back(A[i % A.size()] + B[j++]);
    return
        hull(C); // dis(A, B) = dis(Minkowski(A, -B), 0)
}

```

8Q MinMaxEnclosingRect

```

const double qi = acos(-1) / 2 * 3;
pdd solve(vector<pll> &dots) {
#define diff(u, v) (dots[u] - dots[v])
#define vec(v) (dots[v] - dots[i])
    hull(dots);
    double Max = 0, Min = INF, deg;
    int n = (int)dots.size();
    dots.emplace_back(dots[0]);
    for (int i = 0, u = 1, r = 1, l = 1; i < n; ++i) {
        pll nw = vec(i + 1);
        while (cross(nw, vec(u + 1)) > cross(nw, vec(u)))
            u = (u + 1) % n;
        while (dot(nw, vec(r + 1)) > dot(nw, vec(r)))
            r = (r + 1) % n;
        if (!i) l = (r + 1) % n;
        while (dot(nw, vec(l + 1)) < dot(nw, vec(l)))
            l = (l + 1) % n;
        Min = min(Min, (double)(dot(nw, vec(r)) - dot
            (nw, vec(l))) * cross(nw, vec(u)) / abs2(nw));
    }
}

```

```

    deg = acos(dot(diff(r
        , l), vec(u)) / abs(diff(r, l)) / abs(vec(u)));
    deg = (qi - deg) / 2;
    Max = max(Max, abs(diff
        (r, l)) * abs(vec(u)) * sin(deg) * sin(deg));
}
return pdd(Min, Max);
}

```

8R CircleCover

```

// N ~= 1000
struct CircleCover {
    int C;
    Cir c[N];
    bool g[N][N], overlap[N][N];
    // Area[i] : area covered by at least i circles
    double Area[ N ];
    void init(int _c){ C = _c;}
    struct Teve {
        pdd p; double ang; int add;
        Teve() {}
        Teve(pdd _a
            , double _b, int _c):p(_a), ang(_b), add(_c){}
        bool operator<(const Teve &a) const
        {return ang < a.ang;}
    }eve[N * 2];
    // strict: x = 0, otherwise x = -1
    bool disjuct(Cir &a, Cir &b, int x)
    {return sign(abs(a.0 - b.0) - a.R - b.R) > x;}
    bool contain(Cir &a, Cir &b, int x)
    {return sign(a.R - b.R - abs(a.0 - b.0)) > x;}
    bool contain(int i, int j) {
        /* c[j] is non-strictly in c[i]. */
        return (sign
            (c[i].R - c[j].R) > 0 || (sign(c[i].R - c[j].
            R) == 0 && i < j)) && contain(c[i], c[j], -1);
    }
    void solve(){
        fill_n(Area, C + 2, 0);
        for(int i = 0; i < C; ++i)
            for(int j = 0; j < C; ++j)
                overlap[i][j] = contain(i, j);
        for(int i = 0; i < C; ++i)
            for(int j = 0; j < C; ++j)
                g[i][j] = !(overlap[i][j] || overlap[j][i] ||
                    disjuct(c[i], c[j], -1));
        for(int i = 0; i < C; ++i){
            int E = 0, cnt = 1;
            for(int j = 0; j < C; ++j)
                if(j != i && overlap[j][i])
                    ++cnt;
            for(int j = 0; j < C; ++j)
                if(i != j && g[i][j]) {
                    pdd aa, bb;
                    CCinter(c[i], c[j], aa, bb);
                    double A =
                        atan2(aa.S - c[i].0.S, aa.F - c[i].0.F);
                    double B =
                        atan2(bb.S - c[i].0.S, bb.F - c[i].0.F);
                    eve[E++] = Teve
                        (bb, B, 1), eve[E++] = Teve(aa, A, -1);
                    if(B > A) ++cnt;
                }
            if(E == 0) Area[cnt] += pi * c[i].R * c[i].R;
            else{
                sort(eve, eve + E);
                eve[E] = eve[0];
                for(int j = 0; j < E; ++j){
                    cnt += eve[j].add;
                    Area[cnt]
                        += cross(eve[j].p, eve[j + 1].p) * .5;
                    double theta = eve[j + 1].ang - eve[j].ang;
                    if (theta < 0) theta += 2. * pi;
                    Area[cnt] += (theta
                        - sin(theta)) * c[i].R * c[i].R * .5;
                }
            }
        }
    }
}

```

```

    }
}
};


```

8S LineCmp

```

struct lineCmp { // coordinates should be even!
    bool operator()(Line l1, Line l2) const {
        int X =
            (max(l1.F.F, l2.F.F) + min(l1.S.F, l2.S.F)) / 2;
        ll p1 =
            (X - l1.F.F) * l1.S.S + (l1.S.F - X) * l1.F.S,
        p2 =
            (X - l2.F.F) * l2.S.S + (l2.S.F - X) * l2.F.S,
        q1 = (l1.S.F - l1.F.F), q2 = (l2.S.F - l2.F.F);
        if (q1 == 0) p1 = l1.F.S + l1.S.S, q1 = 2;
        if (q2 == 0) p2 = l2.F.S + l2.S.S, q2 = 2;
        // for query a point: ask make_pair(P, P)
        if (l1.F == l2.F || l2.F == l2.S) l1 = l2;
        return make_tuple((__int128)(p1 * q2), l1) <
            make_tuple((__int128)(p2 * q1), l2);
    }
};

```

8T Trapezoidalization

```

template<class T>
struct SweepLine {
    struct cmp {
        cmp(const SweepLine &swp): swp(_swp) {}
        bool operator()(int a, int b) const {
            if (abs(swp.get_y(a) - swp.get_y(b)) <= swp.eps)
                return swp.slope_cmp(a, b);
            return swp.get_y(a) + swp.eps < swp.get_y(b);
        }
        const SweepLine &swp;
    } _cmp;
    T curTime, eps, curQ;
    vector<Line> base;
    multiset<int, cmp> sweep;
    multiset<pair<T, int>> event;
    vector<typename multiset<int, cmp>::iterator> its;
    vector<typename multiset<pair<T, int>>::iterator> eits;
    bool slope_cmp(int a, int b) const {
        assert(a != -1);
        if (b == -1) return 0;
        return sign(cross(base
            [a].S - base[a].F, base[b].S - base[b].F)) < 0;
    }
    T get_y(int idx) const {
        if (idx == -1) return curQ;
        Line l = base[idx];
        if (l.F.F == l.S.F) return l.S.S;
        return ((curTime - l.F.F) * l.S.S
            + (l.S.F - curTime) * l.F.S) / (l.S.F - l.F.F);
    }
    void insert(int idx) {
        its[idx] = sweep.insert(idx);
        if (its[idx] != sweep.begin())
            update_event(*prev(its[idx]));
        update_event(idx);
        event.emplace
            (base[idx].S.F, idx + 2 * (int)base.size());
    }
    void erase(int idx) {
        assert(eits[idx] == event.end());
        auto p = sweep.erase(its[idx]);
        its[idx] = sweep.end();
        if (p != sweep.begin())
            update_event(*prev(p));
    }
    void update_event(int idx) {
        if (eits[idx] != event.end())
            event.erase(eits[idx]);
        eits[idx] = event.end();
    }
}

```

```

    auto nxt = next(its[idx]);
    if (nxt == sweep.end() || !slope_cmp(idx, *nxt)) return;
    auto t = intersect(base[idx].F, base[*nxt].S, base[*nxt].F);
    if (t + eps < curTime || t >= min(base[idx].S.F, base[*nxt].S.F)) return;
    eits[idx] = event.emplace(t, idx + (int)base.size());
}
void swp(int idx) {
    assert(eits[idx] != event.end());
    eits[idx] = event.end();
    int nxt = *next(its[idx]);
    swap((int&)*its[idx], (int&)*its[nxt]);
    swap(its[idx], its[nxt]);
    if (its[nxt] != sweep.begin())
        update_event(*prev(its[nxt]));
    update_event(idx);
}
// only expected to call the functions below
SweepLine(T t, T e, vector<Line> vec): _cmp
    (*this), curTime(t), eps(e), curQ(), base(vec),
    sweep(_cmp), event(), its((int)vec.size(), sweep.end()), eits((int)vec.size(), event.end()) {
for (int i = 0; i < (int)base.size(); ++i) {
    auto &[p, q] = base[i];
    if (p > q) swap(p, q);
    if (p.F <= curTime && curTime <= q.F)
        insert(i);
    else if (curTime < p.F)
        event.emplace(p.F, i);
}
void setTime(T t, bool ers = false) {
    assert(t >= curTime);
    while (!event.empty() && event.begin()->F <= t) {
        auto [et, idx] = *event.begin();
        int s = idx / (int)base.size();
        idx %= (int)base.size();
        if (abs(et - t) <= eps && s == 2 && !ers) break;
        curTime = et;
        event.erase(event.begin());
        if (s == 2) erase(idx);
        else if (s == 1) swp(idx);
        else insert(idx);
    }
    curTime = t;
}
T nextEvent() {
    if (event.empty()) return INF;
    return event.begin()->F;
}
int lower_bound(T y) {
    curQ = y;
    auto p = sweep.lower_bound(-1);
    if (p == sweep.end()) return -1;
    return *p;
}

```

8U HalfPlaneIntersect

```

pll area_pair(Line a, Line b)
{ return pll(cross(a.S - a.F, b.S - a.F), cross(a.S - a.F, b.F - a.F));
bool isin(Line l0, Line l1, Line l2) {
    // Check inter(l1, l2) strictly in l0
    auto [a02X, a02Y] = area_pair(l0, l2);
    auto [a12X, a12Y] = area_pair(l1, l2);
    if (a12X - a12Y < 0) a12X *= -1, a12Y *= -1;
    return (_int128)
        a02Y * a12X - (_int128) a02X * a12Y > 0; // C^4
}
/* Having solution, check size > 2 */
/* --^- Line.X --^- Line.Y --^- */

```

```

vector<Line> halfPlaneInter(vector<Line> arr) {
    sort(all(arr), [&](Line a, Line b) -> int {
        if (cmp(a.S - a.F, b.S - b.F, 0) != -1)
            return cmp(a.S - a.F, b.S - b.F, 0);
        return ori(a.F, a.S, b.S) < 0;
    });
    deque<Line> dq(1, arr[0]);
    for (auto p : arr) {
        if (cmp(
            dq.back().S - dq.back().F, p.S - p.F, 0) == -1)
            continue;
        while ((int)dq.size() >= 2
            && !isin(p, dq[(int)dq.size() - 2], dq.back()))
            dq.pop_back();
        while ((int)dq.size() >= 2 && !isin(p, dq[0], dq[1]))
            dq.pop_front();
        dq.emplace_back(p);
    }
    while ((int)dq.size() >= 3 &&
        !isin(dq[0], dq[(int)dq.size() - 2], dq.back()))
        dq.pop_back();
    while ((int)
        dq.size() >= 3 && !isin(dq.back(), dq[0], dq[1]))
        dq.pop_front();
    return vector<Line>(all(dq));
}

```

8V RotatingSweepLine

```

void rotatingSweepLine(vector<pii> &ps) {
    int n = (int)ps.size(), m = 0;
    vector<int> id(n), pos(n);
    vector<pii> line(n * (n - 1));
    for (int i = 0; i < n; ++i)
        for (int j = 0; j < n; ++j)
            if (i != j) line[m++] = pii(i, j);
    sort(all(line), [&](pii a, pii b) {
        return cmp(ps[a.S] - ps[a.F], ps[b.S] - ps[b.F]);
    }); // cmp(): polar angle compare
    iota(all(id), 0);
    sort(all(id), [&](int a, int b) {
        if (ps[a].S != ps[b].S) return ps[a].S < ps[b].S;
        return ps[a] < ps[b];
    }); // initial order, since (1, 0) is the smallest
    for (int i = 0; i < n; ++i) pos[id[i]] = i;
    for (int i = 0; i < m; ++i) {
        auto l = line[i];
        // do something
        tie(pos[l.F], pos[l.S], id[pos[l.F]], id[pos[l.S]])
            = make_tuple(pos[l.S], pos[l.F], l.S, l.F);
    }
}

```

8W DelaunayTriangulation

```

/* Delaunay Triangulation:
Given a sets of points on 2D plane, find a triangulation such that no points will strictly
inside circumcircle of any triangle. */
struct Edge {
    int id; // oidx[id]
    list<Edge>::iterator twin;
    Edge(int _id = 0) : id(_id) {}
};
struct Delaunay { // O-base
    int n, oidx[N];
    list<Edge> head[N]; // result udir. graph
    pll p[N];
    void init(int _n, pll _p[]) {
        n = _n, iota(oidx, oidx + n, 0);
        for (int i = 0; i < n; ++i) head[i].clear();
        sort(oidx, oidx + n,
            [&](int a, int b) { return _p[a] < _p[b]; });
        for (int i = 0; i < n; ++i) p[i] = _p[oidx[i]];
        divide(0, n - 1);
    }
}

```

```

void addEdge(int u, int v) {
    head[u].push_front(Edge(v));
    head[v].push_front(Edge(u));
    head[u].begin()->twin = head[v].begin();
    head[v].begin()->twin = head[u].begin();
}
void divide(int l, int r) {
    if (l == r) return;
    if (l + 1 == r) return addEdge(l, l + 1);
    int mid = (l + r) >> 1, nw[2] = {l, r};
    divide(l, mid), divide(mid + 1, r);
    auto gao = [&](int t) {
        pll pt[2] = {p[nw[0]], p[nw[1]]};
        for (auto it : head[nw[t]]) {
            int v = ori(pt[1], pt[0], p[it.id]);
            if (v > 0 ||
                (v == 0 &&
                 abs2(pt[t ^ 1] - p[it.id]) <
                 abs2(pt[1] - pt[0])))
                return nw[t] = it.id, true;
        }
        return false;
    };
    while (gao(0) || gao(1));
    addEdge(nw[0], nw[1]); // add tangent
    while (true) {
        pll pt[2] = {p[nw[0]], p[nw[1]]};
        int ch = -1, sd = 0;
        for (int t = 0; t < 2; ++t)
            for (auto it : head[nw[t]])
                if (ori(pt[0], pt[1], p[ch]) > 0 &&
                    (ch == -1 ||
                     in_cc({pt[0], pt[1], p[ch]}, p[it.id])))
                    ch = it.id, sd = t;
        if (ch == -1) break; // upper common tangent
        for (auto it = head[nw[sd]].begin();
             it != head[nw[sd]].end();)
            if (seg_strict_intersect(
                pt[sd], p[it->id], pt[sd ^ 1], p[ch]))
                head[it->id].erase(it->twin),
                head[nw[sd]].erase(it++);
            else ++it;
        nw[sd] = ch, addEdge(nw[0], nw[1]);
    }
}
} tool;

```

8X VoronoiDiagram

```

// all coord. is even
// you may want to call halfPlaneInter after then
vector<vector<Line>> vec;
void build_voronoi_line(int n, pll *arr) {
    tool.init(n, arr); // Delaunay
    vec.clear(), vec.resize(n);
    for (int i = 0; i < n; ++i)
        for (auto e : tool.head[i])
            int u = tool.oidx[i], v = tool.oidx[e.id];
            pll m = (arr[v]
                ] + arr[u]) / 2LL, d = perp(arr[v] - arr[u]);
            vec[u].emplace_back(Line(m, m + d));
}

```

9 Misc

9A ManhattanMST

```

#define p3i tuple<int, int, int>
struct DSU {
    vector<int> v;
    DSU(int n);
    int query(int u);
    void merge(int x, int y);
};
vector<p3i> manhattanMST(vector<pll> ps) {
    vector<int> id(ps.size());

```

```

iota(id.begin(), id.end(), 0);
vector<p3i> edges;
for (int k = 0; k < 4; ++k) {
    sort(id.begin(), id.end(), [&](int i, int j) {
        return (ps[i] - ps[j]).F < (ps[j] - ps[i]).S;
    });
    map<int, int> sweep;
    for (int i : id) {
        for (auto it = sweep.lower_bound(-ps[i].S);
             it != sweep.end(); sweep.erase(it++)) {
            int j = it->second;
            pll d = ps[i] - ps[j];
            if (d.S > d.F) break;
            edges.emplace_back(d.S + d.F, i, j);
        }
        sweep[-ps[i].S] = i;
    }
    for (auto &p : ps)
        if (k & 1) p.F = -p.F;
        else swap(p.F, p.S);
}
return edges;
}

vector<int> MST(int n, const vector<p3i> &e) {
    vector<int> idx(e.size());
    iota(idx.begin(), idx.end(), 0);
    sort(idx.begin(), idx.end(), [&](int i, int j) {
        return get<0>(e[i]) < get<0>(e[j]);
    });
    vector<int> r;
    DSU dsu(n);
    for (int o : idx) {
        const auto &[w, i, j] = e[o];
        if (dsu.query(i) == dsu.query(j)) continue;
        r.push_back(o);
        dsu.merge(i, j);
    }
    return r;
}

```

9B SternBrocotTree

- Construction: Root $\frac{1}{1}$, left/right neighbor $\frac{0}{1}, \frac{1}{0}$, each node is sum of last left/right neighbor: $\frac{a}{b}, \frac{c}{d} \rightarrow \frac{a+c}{b+d}$
- Property: Adjacent (mid-order DFS) $\frac{a}{b}, \frac{c}{d} \Rightarrow bc-ad=1$.
- Search known $\frac{p}{q}$: keep L-R alternative. Each step can calculated in $O(1) \Rightarrow$ total $O(\log C)$.
- Search unknown $\frac{p}{q}$: keep L-R alternative. Each step can calculated in $O(\log C)$ checks \Rightarrow total $O(\log^2 C)$ checks.

9C CDQ

```

void solve(int l, int r, vector<Point> &a) { // 三維偏序
    if (l == r) return;
    int mid = (l+r)>>1;
    solve(l, mid, a), solve(mid+1, r, a);
    int lp = l, rp = mid+1;
    vector<Point> tmp;
    while(lp <= mid && rp <= r) {
        if (a[lp].y > a[rp].y) {
            bit.upd(a[lp].z, 1);
            tmp.pb(a[lp++]);
        } else {
            ans[a[rp].id
                ] += (bit.sum(maxn)-bit.sum(a[rp].z));
            tmp.pb(a[rp++]);
        }
    }
    while(lp <= mid) {
        bit.upd(a[lp].z, 1);
        tmp.pb(a[lp++]);
    }
    while(rp <= r) {
        ans[a[rp
            ].id] += (bit.sum(maxn)-bit.sum(a[rp].z));
        tmp.pb(a[rp++]);
    }
}

```

```
| for (int i = l; i <= mid; ++i) bit.upd(a[i].z,-1);  
| for (int i = l; i <= r; ++i) a[i] = tmp[i-l];  
| }
```

9D SimulatedAnnealing

```
double factor = 100000;  
const int base = 1e9; // remember to run ~ 10 times  
for (int it = 1; it <= 1000000; ++it) {  
    // ans: answer, nw: current value  
    if (exp(-(nw -  
        ans) / factor) >= (double)(rd() % base) / base)  
        ans = nw;  
    factor *= 0.99995;  
}
```

9E Python

```
import math  
math.isqrt(2) # integer sqrt  
from decimal import *  
Decimal(str(0.1)) # prevent precision issue  
getcontext().prec = 100
```