# Digital Image Processing (C06041) HOMEWORK#2

TA: Yi-Hao Lin (林邑豪)

Adviser: Chih-Wei Tang (唐之瑋)

Visual Communications Lab
Department of Communication Engineering
National Central University

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### **Block Diagram** Uniform Noise Generator HW2-3 HW2-4 $512 \times 512$ Add Noise to 2-D FFT Low-Pass Filter the Image MSE & PSNR 512 HW2-5 2-D IFFT MSE & PSNR $512 \times 512$ HW2-2 HW2-1 8-bit bmp 2-D FFT Downsample 2-D IFFT MSE & PSNR

 $256 \times 256$ 

# Radix-2 Fast Fourier Transform(1/4)

- The time complexity of the discrete Fourier transform is  $O(N^2)$ , which will cause computational burden when the sampling rate is large.
- Fast Fourier transform (FFT) algorithm can be used to decompose the calculation amount, then merge to reduce the time complexity to  $O(N \log N)$ .
- We split the N-point data sequence into two N/2-point data sequences  $f_1(n)$  and  $f_2(n)$ , corresponding to the **even-numbered** and **odd-numbered** samples of x(n), respectively, that is:

$$f_1(n) = x(2n)$$
  
 $f_2(n) = x(2n+1), n = 0,1,..., \frac{N}{2} - 1$ 

# Radix-2 Fast Fourier Transform(2/4)

• To compute a discrete Fourier transform:

$$X(k) = \sum_{x=0}^{N-1} x(n)W_N^{kn}, W_N = e^{-j2\pi/N} \text{ for } k = 0,1,2,...,N-1$$

$$= \sum_{x=0} x(n)W_N^{kn} + \sum_{odd} x(n)W_N^{kn}$$

$$= \sum_{m=0}^{N-1} x(2m)W_N^{2mk} + \sum_{m=0}^{N-1} x(2m+1)W_N^{(2m+1)k}$$

$$= \sum_{m=0}^{N-1} f_1(m)W_N^{mk} + \sum_{m=0}^{N-1} f_2(m)W_N^{2mk}W_N^{k}$$

$$= F_1(k) + F_2(k)W_N^{kn}$$

• where  $F_1(k)$  and  $F_2(k)$  are the N/2-point DFTs of the sequences  $f_1(m)$  and  $f_2(m)$ , respectively.

# Radix-2 Fast Fourier Transform(3/4)

• Since  $F_1(k)$  and  $F_2(k)$  are periodic, with period N/2, so

$$X\left(k + \frac{N}{2}\right) = F_1\left(k + \frac{N}{2}\right) + F_2\left(k + \frac{N}{2}\right)W_N^{k + \frac{N}{2}}$$

$$= F_1(k) - W_N^k F_2(k)$$

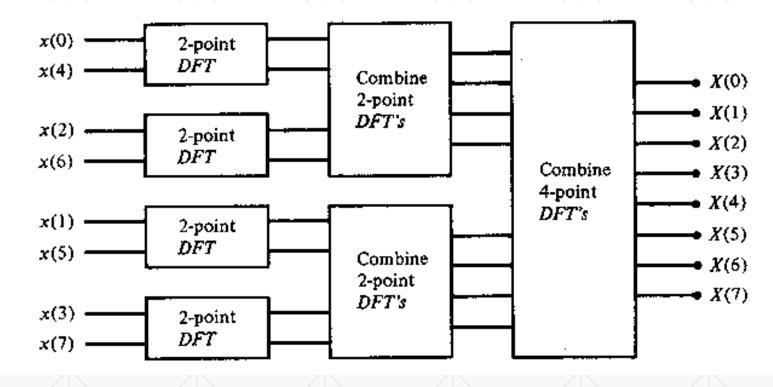
$$: W_N^{k + \frac{N}{2}} = e^{-j\frac{2\pi}{N}k}e^{-j\frac{2\pi N}{N}} = W_N^k * (-1)$$

Hence the equation may be expressed as

$$X(k) = F_1(k) + W_N^k F_2(k), k = 0,1,..., \frac{N}{2} - 1$$

$$X\left(k+\frac{N}{2}\right) = F_1(k) - W_N^k F_2(k), k = 0,1,...,\frac{N}{2} - 1$$

# Fast Fourier Transform(4/4)



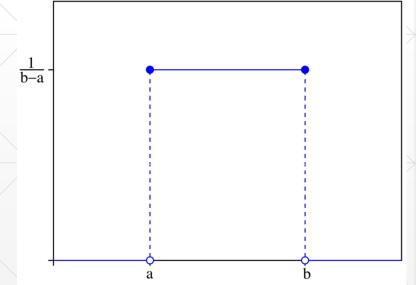
Three stages in the computation of an N = 8-point DFT.

# **Generating Uniform Noise**

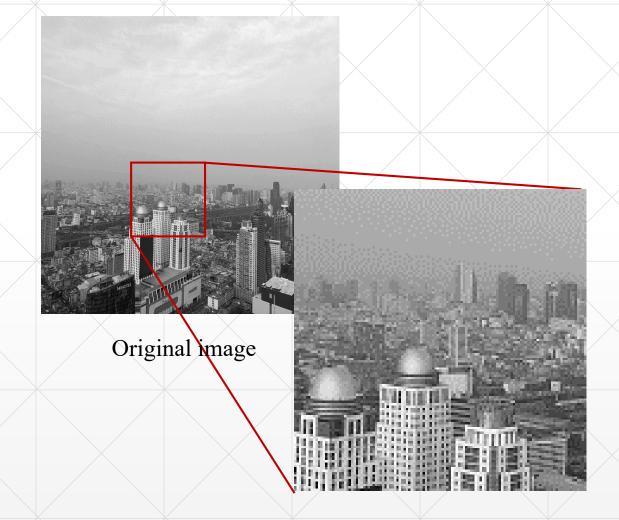
• The general formula for the probability density function of the uniform distribution is:

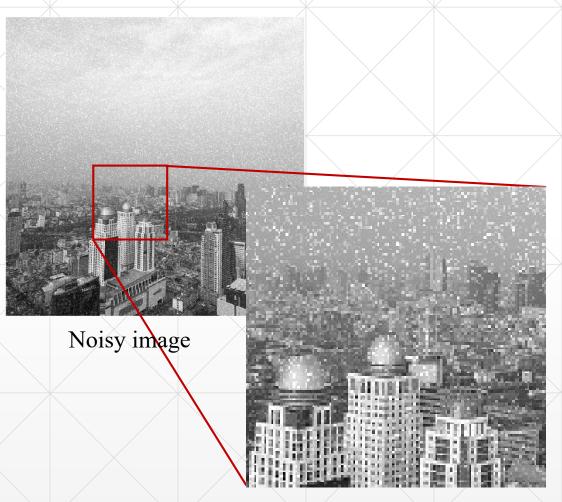
$$f_X(x) = \begin{cases} \frac{1}{b-a}, & \text{for } a \leq x \leq b \\ 0, & \text{otherwise} \end{cases}$$

- We set a = -20 & b = 20
- After adding noise, set grayscale values over 255 to 255, and to 0 for those are less than 0.



# Adding Noise to Image





### Low-Pass Filter

- A low-pass filter is a filter that passes signals with a frequency lower than a selected cutoff frequency and attenuates signals with frequencies higher than the cutoff frequency.
- Objective: Achieve higher PSNR of the denoised image than the noisy image.

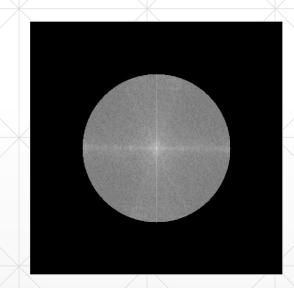
$$H(u,v) = \begin{cases} 1 & \text{if } D(u,v) \le D_0 \\ 0 & \text{if } D(u,v) > D_0 \end{cases}$$

$$D(u,v) = \left[ \left( u - \frac{M}{2} \right)^2 + \left( v - \frac{N}{2} \right)^2 \right]^{\frac{1}{2}}$$

D(u, v): image in the frequency domain.

H(u, v): filter mask in the frequency domain.

(u, v): index of frequency domain.



Low-Pass Filter with  $D_0 = 150$  in the frequency domain

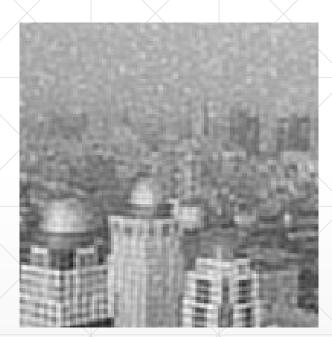
# Low-Pass Filter



Original image



Noisy image



Denoised image with  $D_0 = 150$  (after IFFT)

# **Image Quality Metrics**

MSE (Mean Squared Error):

$$MSE = \frac{1}{Image Size} \sum_{i=1}^{Image Size} (Y_i - \hat{Y}_i)^2$$

PSNR (Peak Signal-to-Noise Ratio):

$$PSNR = 10 \times \log\left(\frac{255^2}{MSE}\right)$$

where

 $Y_i$ : The *i-th* pixel value of the original image

 $\hat{Y}_i$ : The *i-th* pixel value of the image processed by IDCT

*Image Size*: Image length × Image width

# Grading

- Code & Demo (70%): Use the C/C++ only. Matlab or OpenCV is not allowed
  - 2-D FFT (20%) (HW2-1)
  - 2-D IFFT & MSE, PSNR measuring (10% + 10%) (HW2-2)
  - Generating Uniform-noisy image & MSE, PSNR measuring (5% + 5%) (HW2-3)
  - Mask filtering (10%) (HW2-4)
  - 2-D IFFT & MSE, PSNR measuring (5% + 5%) (HW2-5)
- Report (30%):
  - <u>Flowchart</u> (10%)
  - Experiment results (10%)
  - Discussion and Analysis (10%)

### Due Date & Demo Schedule

- **Demo Date**: Dec. 13 (Monday) or Dec. 14 (Tuesday)
- **Demo Time & Location**: 13:30 ~ 17:30 @TBD
- The demo schedule will be announced at the TA webpage.
- You should compress your entire project (including .c/.cpp, .exe file, etc.) and report (.pdf) as a .zip file and submit to New ee-class before Dec. 13, 13:00.
- No delay. (If you have any special case, please inform us by sending an email early.)

### Note

- Do it yourself!
- You will get a zero when you delay or fail to operation in demo (code and demo part), but you can still get points in report part.
- Everyone will be asked a few questions and operations when you are in demo. (Do not call for help.)
- The TA will use another image to test your code.
- If you have a notebook, please bring your own notebook. Otherwise, some people may not be able to execute the code during the demo.
- Remote connection/control is not allowed.

The details will be announced on our course website:

https://sites.google.com/view/ncuvclab/home/course/fall-2021-ta-dip

## REFERENCES

- Gonzalez, Rafael C., and Richard E. Woods, "Digital image processing," Prentice Hall, 2007.
- Test image "DIPpic1.bmp" download:

https://drive.google.com/file/d/1zI86 Dat0xKyGKOTiknqeTlD5tVgdMGu/view?usp=sharing