

Lec. 15 (11/10/2022)

Example - Dual of LP

Primal problem : $p^* = \min_{\underline{x} \in \mathbb{R}^n} \langle \underline{c}, \underline{x} \rangle$

s.t. $G \underline{x} \preceq \underline{h} \in \mathbb{R}^m$

$$A \underline{x} = \underline{b} \in \mathbb{R}^p$$

Step 1 : Write the Lagrangian:

$$\begin{aligned} \underbrace{L(\underline{x}, \underline{\lambda}, \underline{v})}_{\text{is affine in primal variable } \underline{x}} &= \langle \underline{c}, \underline{x} \rangle + \langle \underline{\lambda}, G \underline{x} - \underline{h} \rangle \\ &\quad + \langle \underline{v}, A \underline{x} - \underline{b} \rangle \\ &= (\underline{c}^T + \underline{\lambda}^T G + \underline{v}^T A) \underline{x} - \underline{\lambda}^T \underline{h} - \underline{v}^T \underline{b} \end{aligned}$$

Step 2 : derive Lagrange dual function:

$$g(\underline{\lambda}, \underline{v}) := \inf_{\underline{x} \in \mathbb{R}^n} L(\underline{x}, \underline{\lambda}, \underline{v})$$

$$= \begin{cases} -\underline{\lambda}^T \underline{h} - \underline{v}^T \underline{b} & \text{if } \underline{c} + \underline{A}^T \underline{\lambda} + \underline{A}^T \underline{v} = \underline{0} \\ -\infty & \text{else} \end{cases}$$

Step 3 : derive the Lagrange dual problem

$$\left. \begin{array}{l} \sup \\ \underline{\lambda} \in \mathbb{R}_{\geq 0}^m \\ \underline{v} \in \mathbb{R}^p \end{array} g(\underline{\lambda}, \underline{v}) \right\} \Leftrightarrow \begin{array}{l} \min \\ \left(\begin{array}{c} \underline{h} \\ \underline{\lambda} \\ \underline{v} \end{array} \right)^T \left(\begin{array}{c} \underline{1} \\ \underline{b} \\ \underline{v} \end{array} \right) \\ \text{s.t.} \quad \underline{\lambda} \geq \underline{0}, \quad \underline{c} + \underline{A}^T \underline{\lambda} + \underline{A}^T \underline{v} = \underline{0} \end{array}$$

A different
LP

Example: Nonconvex but strong duality holds

This problem has a name: "Trust region problem"

$$\left. \begin{array}{ll} \min_{\underline{x} \in \mathbb{R}^n} & \underline{x}^T A \underline{x} + 2 \underline{b}^T \underline{x} \\ \text{s.t.} & \underline{x}^T \underline{x} \leq 1 \end{array} \right\} \begin{array}{l} A \in \mathbb{S}^n \\ \text{possibly} \\ \text{sign indefinite} \end{array}$$

Step 1: Lagrangian

$$L(\underline{x}, \lambda) = \underline{x}^T A \underline{x} + 2 \underline{b}^T \underline{x} + \lambda (\underline{x}^T \underline{x} - 1)$$

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Step 3: Dual problem:

$$\begin{cases} \max & -\underline{b}^T (A + \lambda I)^+ \underline{b} - \lambda \\ \text{s.t.} & A + \lambda I \succcurlyeq 0 \\ & \text{and } \underline{b} \in \text{range}(A + \lambda I) \end{cases}$$

→ convex problem ← the text p. 229 checks this
(has to be from duality theory)

The text also shows: $\boxed{d^* = p^*}$ ← Strong duality holds!!

Application of duality:

(Algorithm to solve convex problems)

$\underline{x}^{(k)}$

feasible
primal
sequence

$(\underline{d}^{(k)}, \underline{v}^{(k)})$

feasible
dual
sequence

numerical
tolerance

Stopping condition:

$$f_0(\underline{x}^{(k)}) - g(\underline{d}^{(k)}, \underline{v}^{(k)}) \leq \text{numerical tolerance}$$

Complimentary slackness:

Suppose strong duality holds

\Leftrightarrow

$$p^* = d^*$$

\Leftrightarrow

$$f_0(\underline{x}^*) = \underbrace{g(\underline{\lambda}^*, \underline{v}^*)}_{ii}$$

$$= \inf_{\underline{x} \in \mathbb{R}^n} L(\underline{x}, \underline{\lambda}^*, \underline{v}^*)$$

$$\leq L(\underline{x}, \underline{\lambda}^*, \underline{v}^*) \Big|_{\underline{x} = \underline{x}^*}$$

\underline{x}^* is primal optimizer

$(\underline{\lambda}^*, \underline{v}^*)$ are dual optimizers

$$\Leftrightarrow \cancel{f_0(x^*)} \leq \cancel{f_0(x^*)} + \sum_{i=1}^m \lambda_i^* \cancel{f_i(x^*)} + \sum_{i=1}^p \nu_i^* \cancel{h_i(x^*)}$$

0 (because $\underline{x^*}$ is feasible)

$$\Leftrightarrow 0 \leq \sum_{i=1}^m \lambda_i^* f_i(x^*)$$

On the other hand, $\lambda_i^* \geq 0$ and $f_i(x^*) \leq 0$

$$\therefore \sum_{i=1}^m \lambda_i^* f_i(x^*) \leq 0$$

\therefore we must have:

$$\sum_{i=1}^m \underbrace{\lambda_i^*}_{\geq 0} \underbrace{f_i(\underline{x}^*)}_{\leq 0} = 0$$

$$\Leftrightarrow \boxed{\lambda_i^* f_i(\underline{x}^*) = 0 \quad \forall i=1, \dots, m}$$

$$\left. \begin{aligned} \lambda_i^* > 0 &\Leftrightarrow f_i(\underline{x}^*) = 0 \\ \lambda_i^* = 0 &\Leftrightarrow f_i(\underline{x}^*) < 0 \end{aligned} \right\} \begin{array}{l} \text{complementary} \\ \text{slackness} \end{array}$$

Relation between Lagrange duality and Legendre-Fenchel conjugate duality

We know that the Legendre-Fenchel conjugate of $f(\cdot)$ is

$$f^*(\underline{y}) = \sup_{\underline{x} \in \text{dom}(f)} \{ \langle \underline{y}, \underline{x} \rangle - f(\underline{x}) \}$$

\uparrow
convex in \underline{y}

\uparrow
possible nonconvex in \underline{x}

Consider the primal problem: *maybe complicated*

$$\min_{\underline{x} \in \mathbb{R}^n} f_0(\underline{x})$$

$$\text{s.t. } \left. \begin{array}{l} A\underline{x} \leq \underline{b} \\ C\underline{x} = \underline{d} \end{array} \right\} \text{linear constraint}$$

Can directly derive

Lagrange dual function $g(\underline{\lambda}, \underline{v})$:

$$g(\underline{\lambda}, \underline{v}) = \inf_{\underline{x} \in \mathbb{R}^n} L(\underline{x}, \underline{\lambda}, \underline{v})$$

$$= \inf_{\underline{x} \in \mathbb{R}^n} \left\{ f_0(\underline{x}) + \underline{\lambda}^T (A\underline{x} - \underline{b}) + \underline{v}^T (C\underline{x} - \underline{d}) \right\}$$

$$= -\underline{b}^T \underline{\lambda} - \underline{d}^T \underline{v} + \inf_{\underline{x} \in \mathbb{R}^n} \left\{ f_0(\underline{x}) + (A^T \underline{\lambda} + C^T \underline{v})^T \underline{x} \right\}$$

$$= -\underline{b}^T \underline{\lambda} - \underline{d}^T \underline{v} - \underbrace{f_0^*(-A^T \underline{\lambda} - C^T \underline{v})}$$

we are using

$$\inf_{\underline{x}} (\dots) = - \sup_{\underline{x}} \{ -(\dots) \}$$

ditto

Moral: If we encounter nonlinear optimization problem with linear constraints, then we can directly write down Lagrange dual function & hence the Lagrange dual problem using Fenchel conjugates.

Example:

$$\max_{\underline{x} \in \Delta^{n-1}} f_0(\underline{x}) = - \sum_{i=1}^n x_i \log x_i$$

s.t. $A \underline{x} \preceq \underline{b} \in \mathbb{R}^m$ (m linear inequality constraints)

$$\therefore d^* = \min_{\substack{\lambda \in \mathbb{R}_+^m}} \left\{ b^T \lambda + \log \left(\sum_{i=1}^n \exp(-a_i^T \lambda) \right) \right\}$$

(sub-
v* back)

This is a GP

End of example

see
Lec. 13, p. 6-13.