Homework (19)

1. [Nonsingularity of the KKT matrix.] Consider the KKT matrix

$$egin{bmatrix} \mathbf{P} & \mathbf{A}^T \ \mathbf{A^0} & \end{bmatrix},$$

where $\mathbf{P} \in \mathbb{S}^n_+$, $\mathbf{A} \in \mathbb{R}^{p \times n}$, and rank $\mathbf{A} = p < n$. Show that each of the following statements is equivalent to nonsingularity of the KKT matrix:

- $\bullet \ \mathcal{N}(\mathbf{P}) \cap \mathcal{N}(\mathbf{A}) = \{\mathbf{0}\}.$
- $\mathbf{A}\mathbf{x} = \mathbf{0}, \ \mathbf{x} \neq \mathbf{0} \Longrightarrow \mathbf{x}^T \mathbf{P} \mathbf{x} > 0.$
- $\mathbf{F}^T \mathbf{P} \mathbf{F} \succ \mathbf{0}$, where $\mathbf{F} \in \mathbb{R}^{n \times (n-p)}$ is a matrix for which $\mathcal{R}(\mathbf{F}) = \mathcal{N}(\mathbf{A})$.
- $\mathbf{P} + \mathbf{A}^T \mathbf{Q} \mathbf{A} \succ \mathbf{0}$ for some $\mathbf{Q} \succeq \mathbf{0}$.

Homework (19)

- 2. [Projected gradient method.]
 - \bullet Let (\mathbf{v}, \mathbf{w}) be the unique solution of

$$egin{bmatrix} \mathbf{I} & \mathbf{A}^T \ \mathbf{A} & \mathbf{0} \end{bmatrix} egin{bmatrix} \mathbf{v} \ \mathbf{w} \end{bmatrix} = egin{bmatrix} -
abla f(\mathbf{x}) \ \mathbf{0} \end{bmatrix}.$$

Show that

$$\mathbf{v} = \underset{\mathbf{A}\mathbf{u}=\mathbf{0}}{\operatorname{argmin}} \| - \nabla f(\mathbf{x}) - \mathbf{u} \|_2, \quad \mathbf{w} = \underset{\mathbf{y}}{\operatorname{argmin}} \| \nabla f(\mathbf{x}) + \mathbf{A}^T \mathbf{y} \|_2.$$

• What is the relationship between the projected negative gradient \mathbf{v} and the negative gradient of the reduced unconstrained problem $f(\mathbf{Fz} + \tilde{\mathbf{x}})$, assuming $\mathbf{F}^T\mathbf{F} = \mathbf{I}$?

Homework (19)

3. [Equality constrained entropy maximumization.] We consider the equality constrained entropy maximization problem

$$\min_{\mathbf{x}} f(\mathbf{x}) = \sum_{i=1}^{n} x_i \log x_i, \quad s.t. \quad \mathbf{A}\mathbf{x} = \mathbf{b}.$$

Use the following methods to solve it at p = 100 and n = 500 (you may generate **A** and **b** randomly):

- Direct projected gradient, with inexact line search.
- Elimiate equality constraint.
- Dual approach.

Write a report to describe your settings and compare their performance (numerical accuracy vs. iteration number). Codes should also be handed in.