1. Sublevel sets and epigraph of K-convex functions. Let  $K \subseteq \mathbb{R}^m$  be a proper convex cone with associated generalized inequality  $\preceq_K$ , and let  $f : \mathbb{R}^n \to \mathbb{R}^m$ . For  $\alpha \in \mathbb{R}^m$ , the  $\alpha$ -sublevel set of f (with respect to  $\preceq_K$ ) is defined as

$$C_{\alpha} = \{ \mathbf{x} \in \mathbb{R}^n \mid f(\mathbf{x}) \leq_K \alpha \}.$$

The epigraph of f, with respect to  $\leq_K$ , is defined as the set

$$\mathbf{epi}_K f = \{ (\mathbf{x}, \mathbf{t}) \in \mathbb{R}^{n+m} \mid f(\mathbf{x}) \leq K \mathbf{t} \}.$$

Show the following:

- (a) If f is K-convex, then its sublevel sets  $C_{\alpha}$  are convex for all  $\alpha$ .
- (b) f is K-convex iff  $\mathbf{epi}_K f$  is a convex set.
- 2. Show that the function  $f(\mathbf{X}) = \mathbf{X}^{-1}$  is matrix convex on  $\mathbb{S}_{++}^n$ .

3. Schur complement. Suppose  $\mathbf{X} \in \mathbb{S}^n$  partitioned as

$$\mathbf{X} = \begin{bmatrix} \mathbf{A} & \mathbf{B} \\ \mathbf{B}^T & \mathbf{C} \end{bmatrix},$$

where  $\mathbf{A} \in \mathbb{S}^k$ . The Schur complement of  $\mathbf{X}$  (with respect to  $\mathbf{A}$ ) is  $\mathbf{S} = \mathbf{C} - \mathbf{B}^T \mathbf{A}^{-1} \mathbf{B}$ . Show that the Schur complement, viewed as function from  $\mathbb{S}^n$  into  $\mathbb{S}^{n-k}$ , is matrix concave on  $\mathbb{S}^n_{++}$ .

4. Let  $\pi_{\mathcal{C}}$  be the projection operator onto a convex set  $\mathcal{C}$ . Prove:

$$\langle \pi_{\mathcal{C}}(\mathbf{y}) - \mathbf{x}, \pi_{\mathcal{C}}(\mathbf{y}) - \mathbf{y} \rangle \leq 0.$$

Further show that

$$\|\pi_{\mathcal{C}}(\mathbf{y}) - \mathbf{x}\|^2 + \|\pi_{\mathcal{C}}(\mathbf{y}) - \mathbf{y}\|^2 \le \|\mathbf{x} - \mathbf{y}\|^2.$$

5. If f is an L-smooth function (a short for " $\nabla f$  is Lipschitz continuous with a Lipschitz constant L"), prove

$$f\left(\mathbf{x} - \frac{1}{\beta}\nabla f(\mathbf{x})\right) - f(\mathbf{x}) \le -\frac{1}{2\beta}\|\nabla f(\mathbf{x})\|^2.$$

6. Let f satisfy

$$0 \le f(\mathbf{x}) - f(\mathbf{y}) - \langle \nabla f(\mathbf{y}), \mathbf{x} - \mathbf{y} \rangle \le \frac{\beta}{2} ||\mathbf{x} - \mathbf{y}||^2, \quad \forall \mathbf{x}, \mathbf{y}.$$

Prove that

$$f(\mathbf{x}) - f(\mathbf{y}) \le \langle \nabla f(\mathbf{x}), \mathbf{x} - \mathbf{y} \rangle \le \frac{1}{2\beta} \| \nabla f(\mathbf{x}) - \nabla f(\mathbf{y}) \|^2, \quad \forall \mathbf{x}, \mathbf{y}$$

7. Let f be L-smooth and  $\mu$ -strongly convex on  $\mathbb{R}^n$ . Then

$$\langle \nabla f(\mathbf{x}) - \nabla f(\mathbf{y}), \mathbf{x} - \mathbf{y} \rangle \ge \frac{L\mu}{L+\mu} \|\mathbf{x} - \mathbf{y}\|^2 + \frac{1}{L+\mu} \|\nabla f(\mathbf{x}) - \nabla f(\mathbf{y})\|^2, \quad \forall \mathbf{x}, \mathbf{y} \in \mathbb{R}$$

8. Suppose f is strongly convex with  $m\mathbf{I} \leq \nabla^2 f(\mathbf{x}) \leq M\mathbf{I}$ . Let  $\Delta \mathbf{x}$  be a descent direction at  $\mathbf{x}$ . Show that the backtracking stopping condition holds for

$$0 < t \le -\frac{\nabla f(\mathbf{x})^T \Delta \mathbf{x}}{M \|\Delta \mathbf{x}\|_2^2}.$$

Use this to give an upper bound on the number of backtracking iterations.

9. Consider the problem for computing the analytic center of the set of linear inequalities:

$$\min_{\mathbf{x}} f(\mathbf{x}) = -\sum_{i=1}^{m} \log(1 - \mathbf{a}_{i}^{T} \mathbf{x}) - \sum_{i=1}^{n} \log(1 - x_{i}^{2}),$$

with variable  $\mathbf{x} \in \mathbb{R}^n$ , and dom  $f = \{\mathbf{x} | \mathbf{a}_i^T \mathbf{x} < 1, i = 1, \dots, m, |x_i| < 1, i = 1, \dots, n\}$ .

We can choose  $\mathbf{x}^{(0)} = \mathbf{0}$  as our initial point. You can generate instances of this problem by choosing  $\mathbf{a}^i$  from some distribution on  $\mathbb{R}^n$ . Use the gradient method to solve the problem, using reasonable choices for the backtracking parameters, and a stopping criterion of the form  $\|\nabla f(\mathbf{x})\|_2 \leq \eta$ . Plot the objective function and step length versus iteration number. (Once you have determined  $p^*$  to high accuracy, you can also plot  $f - p^*$  versus iteration.) Experiment with the backtracking parameters  $\alpha$  and  $\beta$  to see their effect on the total number of iterations required. Hand in your code and a report showing how the parameters are chosen and the figures.