

## Readings

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- Key equations; some intuition on theorems points
- Koller (2009) / Jordan (2003) (need to shorten + hence select + concise)
- BN cannot model a distri. that satisfies  $(A \perp C | \{B, D\})$  and  $(B \perp D | \{A, C\})$  only.
- UGM  $\rightarrow$  undirected edges (prob. interaction)
- similar to BN; parametrisation of MN
  - local interactions
  - global model
- Product of local factors, normalised
- normalising constant  $\rightarrow$  partition function (MRF in statistical physics)
- MN - connection between factorisation and independence properties

0.43 (Gibbs dist'n)

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- An undirected graphical model represents a distri  $p(X_1, \dots, X_n)$  defined by an undirected graph  $H$ , and a set of (positive) potential functions  $\psi_c$  associated with cliques of  $H$  s.t.

$$p(x_1, \dots, x_n) = \frac{1}{Z} \prod_{c \in C} \psi_c(x_c) \quad Z = \sum_{x_1, \dots, x_n} \prod_{c \in C} \psi_c(x_c)$$

04.4 (min factor 3.)

- 04.4 (MN factors.)
- we say a dist $\bar{p}(x_1, \dots, x_n)$  with  $\underline{\psi} = \{\psi_1(x_1), \dots, \psi_c(x_c)\}$  <sup>(\*)</sup> factorises over a MN  $H$  if each  $x_c$  ( $c=1, \dots, C$ ) is a complete subgraph of  $H$
  - Factors that parametrise MN are clique potentials
  - (\*) Informally, subs. with idea of a maximal clique
  - (\*) Wlog, parametrisation using maximal cliques obscures structure in original

set of factors

(of a graph)

- informally: clique  $\rightarrow$  fully connected subset of nodes
- (Jordan) maximal cliques  $\rightarrow$  cliques that cannot be extended to include additional nodes without losing property of being fully connected

- formally :-

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- For  $G = \{E, V\}$ , a complete subgraph (clique) is a subgraph  $G' = \{V' \subseteq V, E' \subseteq E\}$  such that nodes  $V'$  are fully interconnected

- A maximal clique is a complete subgraph s.t. any superset  $V'' \supset V'$  is not complete
- A sub-clique is not necessarily a maximal clique

sub-cliques - can be edges, singletons

Koller (2009): see Box 4.B. - MN for CV

### 4.3. MN independencies

Similar to Kollerian pres.  $\rightarrow$  flows of prob. influence / active trails

#### 04.8

- Let  $H$  be an MN structure
- Let  $X_1 - \dots - X_k$  be a path in  $H$ .
- Let  $Z \subseteq X$  be a set of observed variables
- The path  $X_1 - \dots - X_k$  is active given  $Z$  if none of the  $X_i$ s  $k=1, \dots, k$  is in  $Z$

allows a definition of separation

### 04.9 (separation/global independencies)

- We say a set of nodes  $Z$  separates  $X$  and  $Y$  in  $H$ , denoted  $\text{sep}_H(X; Y | Z)$ , if there is no active path between any node  $X \in X$  and  $Y \in Y$  given  $Z$ .
- We define the global independencies associated with  $H$  to be:-

$$\mathcal{I}(H) = \{ (X \perp Y | Z) : \text{sep}_H(X; Y | Z) \}$$

Remark:

independencies  $\mathcal{I}(H)$  are precisely those guaranteed to hold for every distri  $P$  over  $H$ .

sep. criterion sound for detecting indep. properties over  $H$ .

(\(\backslash\)) BN  $\rightarrow$  connection with independence prop implied by MN structure

+  
factorising a distri over the graph

(\(\backslash\)) of both representation

(\*)

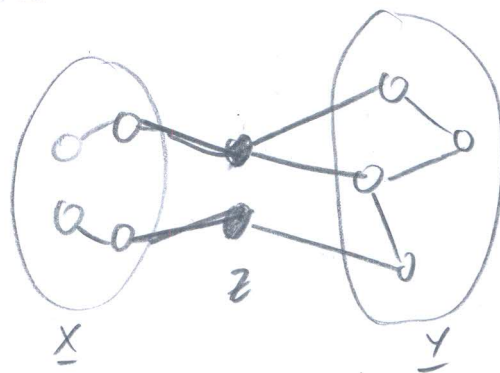
Heuristics for BN, equivalence of:-

Gibbs fact. of

distri  $P$  over a graph  $H$

$\Leftrightarrow$

$H$  is an I-map for  $P$  (that is  $P$  satisfies Markov ass.  $\mathcal{I}(H)$ )





#### 4.3.1.1. (soundness)

(11) to 4.3.2. i.e. Gibbs distri satisfies independencies associated with a graph.

i.e. soundness of separation

(factorisation  $\xLeftrightarrow[4.2/3.1]{4.1/3.2}$  C.I.)  
accord.  $G$

#### 1.4.1.

- let  $P$  be a distri over  $X$ , and  $H$  an MN structure over  $X$

- If  $P$  is a Gibbs distri that factorises over  $H$ , then  $H$  is an I-map for  $P$

other direction i.e. C.I. of distri  $\rightarrow$  factorisation: Hammersley-Clifford Theorem

- unlike for BN, HCT does not hold in general.

- require additional assumption that  $P$  is a positive distri

#### 1.4.2

- let  $P$  be a positive distri over  $X$ , and  $H$  a Markov network graph over  $X$ .

- If  $H$  is an I-map for  $P$ , then  $P$  is a Gibbs distri that factorises over  $H$ .

(\*) For positive distris, the global independencies imply that distri factorises according to the network structure.

(\*) For this class of distributions, we have that a distribution  $P$  factorises over a Markov network if and only if  $H$  is an I-map of  $P$ .

~~(\*)~~ lecture def An I-M  $H$  is an I-map for a distri  $P$  if  $I(H) \subseteq I(P)$  i.e.  $P$  entails  $I(H)$

(\*) If  $P$  is a Gibbs distri over  $H$ , then  $H$  is an I-map of  $P$ .

• soundness of separation as criterion for detecting independencies in MN.

- any distri that factorises over  $G$  satisfies the independence ass. implied by separation

- completeness - strong version of completeness does not hold

- It is NOT the case that every pair of nodes  $X$  and  $Y$  that are not separated in  $H$  are dependent in every distribution  $P$  which factorises over  $H$   
(use Markov)

#### 1.4.3

- let  $H$  be a MN structure.

- If  $X$  and  $Y$  are not separated given  $Z$  in  $H$ , then  $X$  and  $Y$  are dependent given  $Z$  in some distri  $P$  that factorises over  $H$ .

- same arguments as 1.3.5 to conclude:-

② for almost all distri  $P$  that factorise over  $H$  (all distri. except for a set of measure 0 in space of factor param.), we have  $I(P) = I(H)$ .

- our defn of  $I(H)$  is maximal one.

- for any independence assertion that is not a consequence of separation in  $H$ , we can always find a counterexample distri  $P$  that factorises over  $H$ .

#### 4.3.2. indep. revisited

BN: local indep. (each node is indep. of nondesc. given parents)

Global indep. (induced by d-sep)

- showed that these are equiv, in the sense of one implies the other.

Q: (1) to BN; can we provide local indep. induced by MN, analogously to local indep. of BN

②: 3 diff poss defn. of independencies associated with network structure  
two local, one global in def 4.9.

#### 4.3.2.1. - local Markov ass.

D.4.10 → intuitively, two variables directly connected; potential for direct correlation in an unmediated way.

- conversely, two vars not directly linked, some way of redwiring c.i.

-  $X$  and  $Y$  indep given all other nodes.

#### D.4.10 (Pairwise independencies)

Let  $H$  be a MN

We define pairwise independencies associated with  $H$  to be:-

$$I_p(H) = \{ (X \perp Y \mid X - \{X, Y\} : \{X, Y\} \notin \mathcal{M}_H) \}$$

D.4.11 → analogue to local indep. associated with B.N.

#### 4.11. (Markov blanket)

For a given graph  $H$ , we define the Markov blanket of  $X$  in  $H$ ,  $MB_H(X)$  to be the neighbors of  $X$  in  $H$ .

We define the local independencies associated with  $H$  to be:-

$$I_l(H) = \{ (X \perp X - \{X\} - MB_H(X) \mid MB_H(X) : X \in \mathcal{X}) \}$$



i.e. local independencies state that  $X$  is indep. of nodes in graph given immed. neighbours.

- we will show that these local indep. ass. hold for any distri that factorizes over  $H$ , so that  $X$ 's Markov blanket in  $H$  truly does sep. it from all other variables.

#### 4.3.2.2. - relationships between Markov properties

- 3 sets of indep. assertions assoc. with network structure  $H$ .
- For general distri  $I_p(H)$  is weaker than  $I_c(H)$  is weaker than  $I(H)$ .
- ~~All 3 are eq.~~ (\*) All 3 are equivalent for positive distri

#### Prop 4.3

- For any MN  $H$ , and any distri  $P$ , we have that if  $P \models I_c(H)$  then  $P \models I_p(H)$

#### Prop 4.4

- For any MN  $H$ , and any distri  $P$ , we have that if  $P \models I(H)$  then  $P \models I_c(H)$

#### Th 4.4

- Let  $P$  be a positive distri. If  $P$  satisfies  $I_p(H)$ , then  $P$  satisfies  $I(H)$ .

#### Corollary 4.1

- The following statements are equivalent for a positive distri  $P$ .

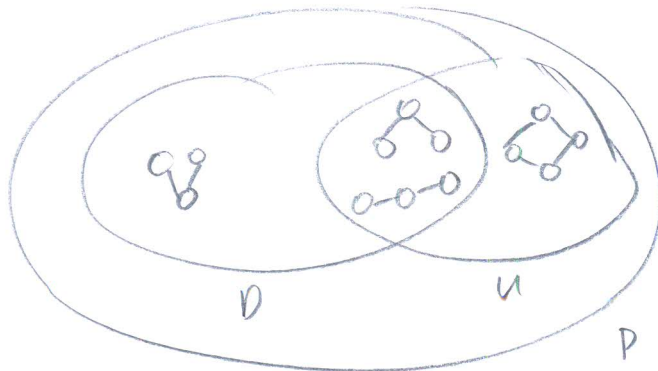
1.  $P \models I_c(H)$
2.  $P \models I_p(H)$
3.  $P \models I(H)$

#### Def 4.1

- An MN  $H$  is a perfect map for  $P$  if for any  $\underline{X}, \underline{Y}, \underline{Z}$ , we have that

$$\text{sep}_H(\underline{X} : \underline{Y} | \underline{Z}) \Leftrightarrow P \models (\underline{X} \perp \underline{Y} | \underline{Z})$$

Theorem: not every distri has a perfect map as UGM



= from here on, Jordan (2003).

- exponential form

- constraining clique potentials to be the "most convenient" possibility

Q(1): what effect does this have on equivalence of local and global Markov properties?

- represent a clique potential as:  $\phi_c(x_c) = \exp\{-\phi_c(x_c)\}$  (\*)

-  $\phi_c(x_c)$  - a 'potential'

- additive structure:  $p(x) = \frac{1}{Z} \prod_{c \in C} \exp\{-\phi_c(x_c)\}$

$$= \frac{1}{Z} \exp\left\{-\sum_{c \in C} \phi_c(x_c)\right\} = \frac{1}{Z} \exp\{-H(x)\}$$

'Boltzmann distri'

-  $H(x) = \sum_{c \in C} \phi_c(x_c)$

-  $H(x)$  - free energy

- some notable forms / graph topologies:-

Boltzmann machines

- fully connected graph, pairwise edge pot., binary valued nodes  $\{-1, 1\}$

$$p(x_1, x_2, x_3, x_4) = \frac{1}{Z} \exp\left\{\sum_{i,j} \phi_{ij}(x_i, x_j)\right\} = \frac{1}{Z} \exp\left\{\sum_{i,j} \theta_{ij} x_i x_j + \sum_i \alpha_i x_i + C\right\}$$

- overall negy fn:-

$$H(x) = \sum_{i,j} (x_i - \mu) \theta_{ij} (x_j - \mu) = (x - \mu)^T \Theta (x - \mu)$$

- low technique to learn this model, recover graph str. from data.

Ising Models

- model energy of a physical system (atom interaction)

- regular grid topology

- multi-state  $\rightarrow$  Potts.

$$p(x) = \frac{1}{Z} \exp\left\{\sum_{i,j \in N_i} \theta_{ij} x_i x_j + \sum_i \theta_{i0} x_i\right\}$$

## Restricted Boltzmann Machines

$$p(x, y | \theta) = \exp \left\{ \sum_i \theta_i \phi_i(x_i) + \sum_j \theta_j \phi_j(y_j) + \sum_{i,j} \theta_{i,j} \phi_{i,j}(x_i, y_j) - A(\theta) \right\}$$

- see paper

## CRFs

- undirected graph rep. ; encode cond. distri  $p(y|x)$   $y_i$  - target  $x$  - obs.

$$p_\theta(y|x) = \frac{1}{Z(\theta, x)} \exp \left\{ \sum_i \theta_i \phi_i(x, y_i) \right\}$$