

IR Ch 9

- IRIS is a key example  
to understand which forms basis  
of Ch 9 and 10.

e.g. 1

$$\begin{aligned} P(C, D, I, G, S, J, L, H) = \\ P(C)P(D|C)P(I)P(G|I, D)P(S|I) \\ P(L|G)P(J|L, S)P(H|G, J) \end{aligned}$$

- Apply VE to compute  $P(J)$  using

$$f = (C, D, I, H, G, S, L)$$

dim C: compute:-  $\psi_1(C, D) = \phi_C(C) \cdot \phi_D(D, C)$

$$\pi_1(D) = \sum_C \psi_1(C, D)$$

$\phi_C(C) \phi_D(D, C) \phi_I(I)$   
 $\phi_G(G, I, D) \phi_S(S, I) \phi_L(L, G)$   
 $\phi_J(J, L, S) \phi_H(H, G, J)$

dim D: compute:-

$$\psi_2(G, I, D) = \phi_G(G, I, D) \pi_1(D)$$

$$\pi_2(G, I) = \sum_D \psi_2(G, I, D)$$

dim I:  $\psi_3(G, I, S) = \phi_I(I) \phi_S(S, I) \pi_2(G, I)$

$$\pi_3(G, S) = \sum_I \psi_3(G, I, S)$$

dim H:  $\psi_4(H, G, J) = \phi_H(H, G, J)$

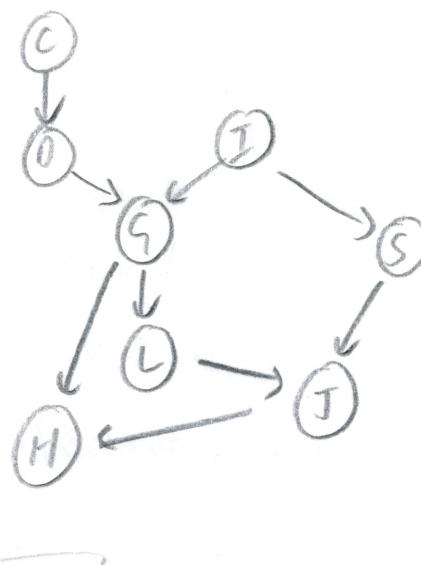
$$\pi_4(G, J) = \sum_H \psi_4(H, G, J)$$

dim L:  $\psi_5(G, J, L, S) = \phi_L(L, G) \pi_3(G, S) \pi_4(G, J)$

$$\pi_5(J, L, S) = \sum_G \psi_5(G, J, L, S)$$

dim S:  $\psi_6(J, L, S) = \phi_S(J, L, S) \pi_5(J, L, S)$

$$\pi_6(J, L) = \sum_S \psi_6(J, L, S)$$

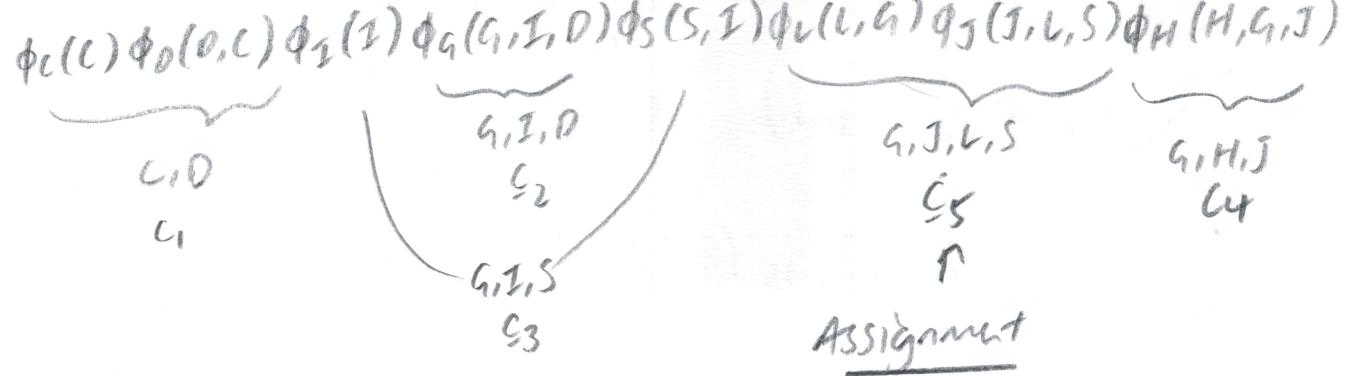


$$\text{e.l.m } L: \psi_7(J, L) = \tau_6(J, L)$$

$$\tau_7(J) = \sum_L \psi_7(J, L).$$

### Algorithmic summary

Step	Var e.l.m.	Factors used	vars involv.	New fact
1	C	$\phi_C(C), \phi_D(D, C)$	C, D	$\tau_1(D)$
2	D	$\phi_G(G, I, D) \tau_1(D)$	G, I, D	$\tau_2(G, I)$
3	I	$\phi_I(I), \phi_S(S, I) \tau_2(G, I)$	G, S, I	$\tau_3(G, S)$
4	H	$\phi_H(H, G, J)$	H, G, J	$\tau_4(G, J)$
5	G	$\tau_4(G, J) \tau_3(G, S) \phi_L(L, G)$	G, J, L, S	$\tau_5(J, L, S)$
6	S	$\tau_5(J, L, S) \phi_J(J, L, S)$	J, L, S	$\tau_6(J, L)$
7	L	$\tau_6(J, L)$	J, L	$\tau_7(J)$



$$p(C)p(D|C) = \phi_C(C)\phi_D(D, C) = c_1$$

$$p(G|I, D) = \phi_G(G, I, D) = c_2$$

$$p(I)p(S|I) = \phi_I(I)\phi_S(S, I) = c_3$$

$$p(L|G)p(J|L, S) = \phi_L(L, G)\phi_J(J, L, S) = c_5$$

$$p(H|G, J) = \phi_H(H, G, J) = c_4$$

init. pt.

$$\psi_1(c_1) = \phi_C(C)\phi_D(D, C)$$

$$\psi_5(c_5) = \phi_L(L, G)\phi_J(J, L, S)$$

- select any root clique; a clique with I

i.e.  $c_4$  or  $c_5$

$$1. c_1: \text{eliminate } C \text{ by } \sum_C \psi_1(C, D) - \delta_{1 \rightarrow 2}(D) = \sum_C \psi_1(C, D)$$

$$\delta_{1 \rightarrow 2}(D) \rightarrow c_2$$

$$2. c_2: \beta_2(G, I, D) = \delta_{1 \rightarrow 2} \cdot \psi_2(G, I, D)$$

$$\delta_{2 \rightarrow 3}(G, I) = \sum_D \beta_2(G, I, D) \rightarrow c_3$$

3.  $c_3$  elim I

$$\beta_3(G, S, I) = \delta_{2 \rightarrow 3}(G, I) \cdot \psi_3(G, S, I)$$

$$\delta_{3 \rightarrow 5}(G, S) = \sum_I \beta_3(G, S, I) \rightarrow c_5$$

$\zeta_4: \text{Elim } H:$

$$\partial_{4 \rightarrow S}(G, J) = \sum_H \psi_4(H, G, J) \quad \text{to } \zeta_S$$

$$\zeta_5: \beta_5(G, J, S, L) = \partial_{3 \rightarrow S}(G, S) \partial_{4 \rightarrow S}(G, J) \psi_5(G, J, S, L)$$

$$\beta_5(G, J, S, L)$$

$$\rho(J) = \sum_G \sum_S \sum_L \beta_5(G, J, S, L)$$

$$\alpha(\phi) = (C, D)$$

ok

ch10 - exact inference - clique trees- chapter notes

- set of factors  $\Phi$
- set of variables  $X$  which factors defined over.
- each factor  $\phi_i$  has scope  $X_i$  (takes arguments over)
- this set of factors defines an unnormalised measure

$$\hat{P}_{\Phi}(X) = \prod_{\phi_i \in \Phi} \phi_i(X_i)$$

- Bayesian nets (no evidence)

- factors - CPDs
- measure  $\hat{P}_{\Phi}$  is a normalised distribution
- Bayesian nets (evidence  $E=e$ )
- factors are CPDs restricted to  $e$
- measure  $\hat{P}_{\Phi}(X) = P_B(X, e)$
- Gibbs distn (with/without evidence)
- factors - (restricted) potentials
- unnormalised Gibbs measure  $\tilde{P}_{\Phi}$

(\*) All ops that can be performed on a normalised measure can also  
be perf. on an unnormalised measure. (a)

- marginalise  $\tilde{P}_{\Phi}$  on a subset of variables by summing out
- ALSO can consider condit. measure  $\tilde{P}_{\Phi}(X|Y) = \tilde{P}_{\Phi}(X, Y) / \tilde{P}_{\Phi}(Y)$
- same as  $P_B(X|Y)$

10.1 - variable elim, clique trees.

- V-E algo - manipulate factors.
- each step:- 1) create a factor  $\psi_i$  by multiplying existing factors
- 2) eliminate a variable in  $\psi_i$  to generate a new factor  $\tau_i$   
(used to create another).

## (\*) Alt view:

- A factor  $\phi_i$  is considered as a computational data structure
- It takes messages " $t_j$ " generated by other factors  $\phi_j$  and generates a message " $t_i$ " that is used by another factor  $\phi_i$ .

## (\*) Fig 10.1 - cluster tree

### (\*) 10.1.1. - cluster graphs

- cluster graph - data structure - graphical flowchart - factor map process
- node - cluster - graph - subset of variables
- undirected edges - connect clusters - scopes - non-empty intersection

### 10.1. - cluster graph, family pres, sepset

- A cluster graph  $G$  for a set of factors  $\Phi$  over  $X$  is an undirected graph, each of whose nodes  $i$  is associated with a subset  $S_i \subseteq X$ .
- A cluster graph must be family-preserving
  - Each factor  $\phi \in \Phi$  must be associated with a cluster  $S_i$ , denoted  $a(\phi)$ , such that  $\text{scope}[\phi] \subseteq S_i$
- Each edge between a pair of clusters  $S_i$  and  $S_j$  is associated with a sepset  $S_{i,j} \subseteq (S_i \cap S_j)$

### - VE algo $\rightarrow$ cluster graph

- (\*) Cluster for each factor  $\phi_i$  used in computation; associated with set of variables  $S_i = \text{Scope}[\phi_i]$

- (\*) draw an edge between two clusters  $S_i$  and  $S_j$  if message  $t_i$  produced by eliminating a variable in  $\phi_i$  is used in the computation of  $t_j$ .

### (\*) 10.1.2. - clique trees

- VE algo - each internal factor used at most once
  - when  $\phi_i$  is no longer used in S-PE algo to create  $\phi_j$ , it is removed from the set of factors  $\Phi$ , can no longer be used.

- (\*) cluster graph induced by VE algo  $\rightarrow$  tree.
  - (\*) VE-algo defines directionality via message flow
  - (\*) All messages flow  $\rightarrow$  root (single cluster - final result - comp)
  - (\*) CS convention:- root of tree is up
    - messages sent upward to root.
  - (\*) upstream - downstream
- P10.2 (Running intersection property)
- let  $T$  be a cluster tree over set of factors  $\Phi$
  - $V_T$  - vertices of  $T$ ;  $E_T$  - edges of  $T$
  - $T$  has running intersection property if; whenever there is a variable such that  $X \in C_i$  and  $X \in C_j$ ; then  $X$  is also in every cluster (on the unique) path in  $T$  between  $C_i$  and  $C_j$ .

(R): Running intersection property  $\Rightarrow S_{i,j} = (C_i \cap C_j)$

- running intersection property must hold for cluster tree induced by VEalgo; a variable appears in every factor from moment it is introduced (by mult. new factor (2) that mentions it) until it is summed out

#### 1.10.1

- let  $T$  be a cluster tree induced by VE algo over some set of factors  $\Phi$ . Then  $T$  satisfies the running intersection property.

#### P10.1

- let  $T$  be a cluster tree induced by a variable elimination algo over some set of factors  $\Phi$ .
- let  $C_i$  and  $C_j$  be two neighbouring clusters such that  $C_i$  passes the message  $\tau_i$  to  $C_j$
- then the scope of the messages is precisely  $C_i \cap C_j$

### 010.3 (cluster tree / running mt / clique tree)

- let  $\Phi$  be a set of factors over  $X$
- A cluster tree over  $\Phi$  that satisfies the running intersection property is called a clique tree (junction tree)
- In the case of a clique tree, the clusters are also called cliques.

R:  $T$  is a clique tree for  $\Phi$  iff  $T$  is a clique tree for a chordal graph containing  $H_\Phi$

(0.10.3)

(04.17)

properties true iff clique-tree data structure  
admits VE by passing messages over the tree

R: running intersection property  $\Rightarrow$  independence statement (04.17 clique trees)

R: let  $T$  be a cluster tree over  $\Phi$   
 $H_\Phi$  be an undirected graph over  $\Phi$ .

for any sepe set  $S_{i,j}$ , let  $W_{<(i,j)}$  be set of all variables in scope  
of clusters on  $S_i$  side of tree  $(\sim)$

$W_{<(j,i)}$  be

### 110.2

-  $T$  satisfies running intersection property iff for every sepe set  $S_{i,j}$  we have  $(\sim)$   
that  $W_{<(i,j)}$  and  $W_{<(j,i)}$  are separated in  $H_\Phi$  given  $S_{i,j}$

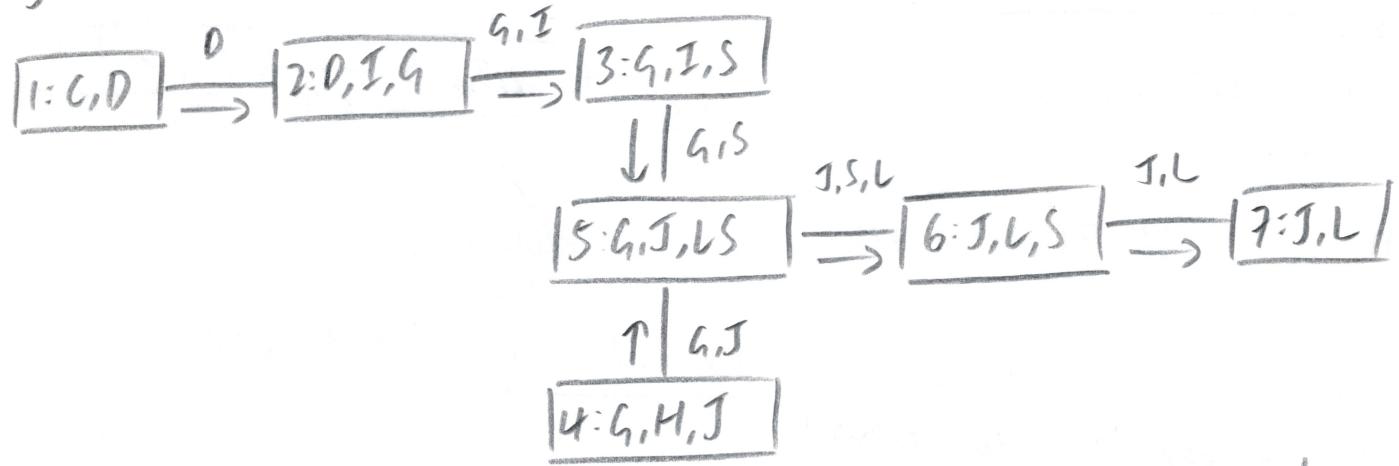
R R

- we can show equivalence of both definitions (0.10.3 and 4.17)

(\*) show that running intes. prop of tree  $T$  implies that each node in  $T$  corresponds to a clique in a chordal graph  $H'$  containing  $H$ ,  
and that each maximal clique in  $H'$  is represented in  $T$ .  $(?)$

- (\*) Accompanying diagrams (collated) for clarity
- They are crucial for an understanding of what is going on.
- Fig 9.8 (colluv)  
(BN for Student)
- 
- Fig 9.11 (a)  
(induced graph)
- 
- under V.E  $\xi = (C, D, I, H, G, S, L)$

- Fig 9.11(b) shows maximal cliques (messy to represent) (this used to gen. clique tree)
- Fig 10.1 - cluster tree for V.E  $\xi = (C, D, I, H, G, S, L)$



- (\*) note this is constructed from V.E algo under above elim order  $\xi$
- (\*) Note the clusters are not maximal.
- (\*) How we get from Fig 10.1  $\rightarrow$  Fig 10.2 will be covered later in the section

## 10.2 - message passing - sum Product

- clique tree and variable elimination.
- same clique tree - different executions - variable elim.
- data structure - caching computations - multiple efficient executions

- (\*) we have a set of factors  $\Phi$  over  $X$ ; and assume we are given a clique tree  $T$  over  $\Phi$ , as defined in D.4.17 (i.e. with maximal cliques)
- (\*)  $T$  satisfies (guaranteed) to satisfy the running intersection property and family preservation

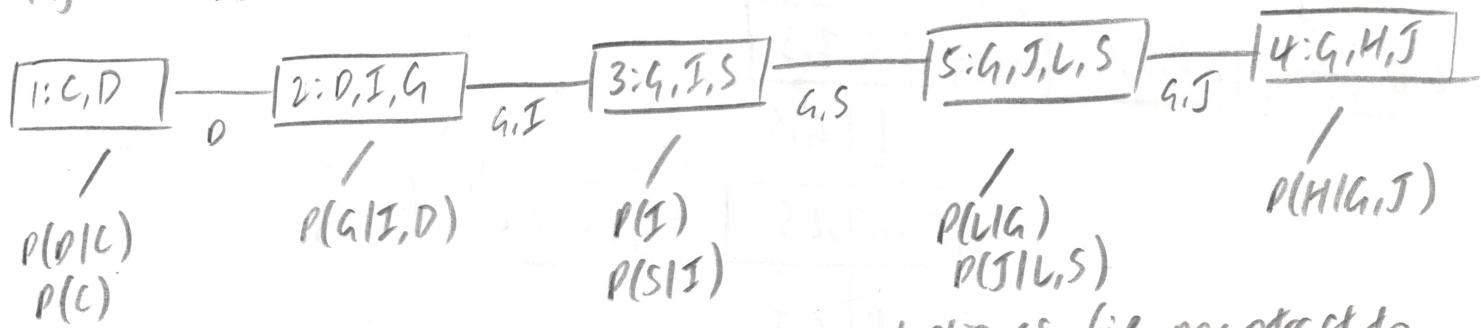
### 10.2.1 - VGM clique tree

- clique tree - VE op guidance
- (\*) factors of computed; messages sent along edges
- (\*) each clique takes incoming messages (factors), multiplies them, sums out one or more variables; sends outgoing message to another clique.
- (\*) clique tree data structure:-
  - i) organizes ops. over factors in clique tree
  - ii) partial order over operations

- (\*) if clique  $C'$  requires a message from  $C$ ;  $C'$  must wait until its comput. until  $C$  performs computation and sends message to  $C'$ .

### A key example 10.2.1.1

- fig 10.2 (simplified clique tree) (based on student network)



- (\*) note that this is constructed from maximal cliques (i.e. contrast to fig 10.1); non-maximal cliques absent  
- cover this later.

- (\*)  $T$  satisfies both family preservation; running intersection property

- (\*) also specifies assignment  $\alpha$  of initial factors (CPDs) to cliques.

- going to list steps here:-

- 1) generate initial potentials
- 2) Define query
- 3) Select root clique
- 4) execute message passing upstream to root clique

- 1) Generate initial potentials for each clique:  $\phi_{init}$
- each  $\phi_i(\xi_i)$  generated by multiplying factors assigned to clique  $\xi_i$
  - showing this all explicitly
- $$p(c, D, I, G, S, J, L, H) = p(c) p(D|c) p(I) p(G|I, D) p(S|I) p(L|G) p(J|L, S) p(H|G, J)$$
- $$= \phi_c(c) \phi_D(D, c) \phi_I(I) \phi_G(G, I, D) \phi_S(S, I) \phi_L(L, G) \phi_J(J, L, S)$$
- $$\phi_H(H, G, J)$$
- Assignment of initial factors to cliques: for initial pot.
- Clique  $\xi_1: p(c) p(D|c) \rightarrow \phi_1(c, D) = \phi_c(c) \phi_D(D, c)$
- $\xi_2: p(G|I, D) \rightarrow \phi_2(G, I, D) = \phi_G(G, I, D)$
- $\xi_3: p(I) p(S|I) \rightarrow \phi_3(G, I, S) = \phi_I(I) \phi_S(S, I)$
- $\xi_4: p(H|G, J) \rightarrow \phi_4(H, G, J) = \phi_H(H, G, J)$
- $\xi_5: p(L|G), p(J|L, S) \rightarrow \phi_5(G, J, L, S) = \phi_L(L, G) \phi_J(J, L, S)$

## 2) Repetitively - P(T)

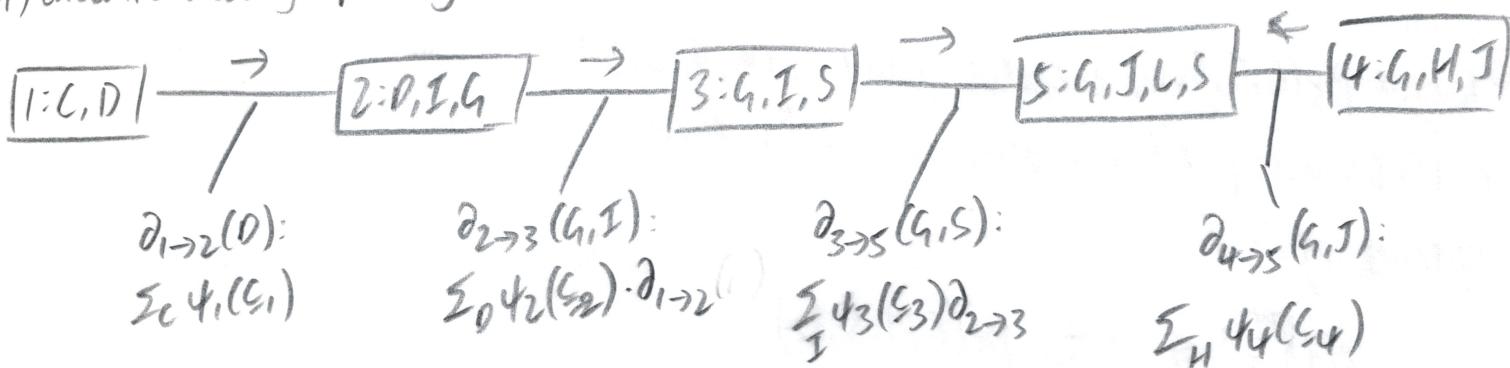
### 3) Select root clique

i.e. any of cliques  $\xi_1, \dots, \xi_5$  which contains T.

e.g.  $\xi_4$  or  $\xi_5$ : randomly choose  $\xi_5$  (makes no diff.)  
(arbitrarily)

### 4) Execute message passing:- (root clique $\xi_5$ )

root clique



PTO.



$\xi_1$ : Eliminate C:-

$\sum_C \psi_1(C, D)$  generates a factor with scope D. Define this as a message to send to  $\xi_2$ .

$$\partial_{1 \rightarrow 2}(D) = \sum_C \psi_1(C, D)$$

$\xi_2$ : Eliminate D:-

- define  $\beta_2(G, I, D) = \partial_{1 \rightarrow 2}(D) \cdot \psi_2(G, I, D)$

$\sum_D \beta_2(G, I, D)$  generates a factor over G, I. Define as message to send to  $\xi_3$ .

$$\partial_{2 \rightarrow 3}(G, I) = \sum_D \psi_2(G, I, D) \cdot \partial_{1 \rightarrow 2}(D) = \sum_D \beta_2(G, I, D)$$

$\xi_3$ : Eliminate I:-

- define  $\beta_3(G, S, I) = \partial_{2 \rightarrow 3}(G, I) \cdot \psi_3(G, S, I)$

$\sum_I \beta_3(G, S, I)$  generates factor over G, S ... to  $\xi_5$

$$\partial_{3 \rightarrow 5}(G, S) = \sum_I \psi_3(G, S, I) \partial_{2 \rightarrow 3}(G, I)$$

$\xi_4$  C.I.M. H

$$\partial_{4 \rightarrow 5}(H, J) = \sum_H \psi_4(H, G, J) \text{ to } \xi_5$$

$\xi_5$ : (root clique):-

define  $\beta_5(G, J, S, L) = \partial_{3 \rightarrow 5}(G, S) \cdot \partial_{4 \rightarrow 5}(H, J) \cdot \psi_5(G, J, S, L)$

- Factor  $\beta_5(G, J, S, L)$  encodes joint  $P(G, J, L, S)$

- All CPDs multiplied in; other variables elmn.

- Obtain Pt:-

$$P(J) = \sum_G \sum_S \sum_L \beta_5(G, J, S, L)$$

## (\*) constraint on oporder

- only constraint: clique must get all of its incoming messages from downstream neighbors before sending outgoing messages to upstream neighbors.

- ready clique - clique has received all incoming messages

## (\*) valid execution orders

- (\*) varying root clique choice; varying query (norm, charges)

### 10.2.1.2. - clique tree message passing

- A general, formal specification of above.

- component specification; then pseudocode.

### (\*) general variable elim algo - message passing on a clique tree

- (\*) let  $T$  be a clique tree with cliques  $\xi_1, \dots, \xi_R$

- multiply factors (assigned to each clique)  $\rightarrow$  initial potentials

- pass messages between neighboring cliques; sending them all to root clique

- initial potential
- each factor  $\phi \in \Phi$  is assigned to clique  $\alpha(\phi)$  ( $\alpha$  can be viewed as a function that takes factor, returns clique index)
  - initial potential of  $\xi_j$  (clique  $j$ )

$$\psi_j(\xi_j) = \prod_{\phi: \alpha(\phi)=j} \phi$$

- As each factor is assigned to one clique ( $\times$ ):

$$\prod_{\phi} \phi = \prod_j \psi_j$$

(i.e. product of all init. potentials is equivalent to product of initial factors (CPPS))

root clique;  $\xi_r$  - selected root clique

neighbours - perform sum-product w/ all cliques (start from leaves of clique tree upwards)

For a clique  $\xi_i$ :

- $N_b$  - set of indexes of cliques that are neighbors of  $\xi_i$

- $p_r(i)$  - upstream neighbour of  $i$  (one on path to root clique)
- (\*) each clique  $C_i$ , except for root, performs a message passing comp. and sends a message to upstream neighbour  $C_{p_r(i)}$

sum-prod messpass: message from  $C_i$  to  $C_j$ :-

$$S_{i \rightarrow j} = \sum_{C_k \in N(C_i) - \{C_j\}} \psi_i \cdot \prod_{k \in C_i \cap C_j} \delta_{k-i}$$

- (\*) clique  $C_i$  multiplies all incoming messages from its other neighbours with its initial clique pot., resulting in a factor of whose scope is the example earlier uses  $\beta$ ) ② clique.
- (\*) then sums out all variables except those in sepset between  $C_i$  and  $C_j$ ; sends resulting factor as a message to  $C_j$

message passing process:

- (\*) proceeds up tree - root clique culmination
  - (\*) Root clique - received-all messages  $\rightarrow$  multiply with its own initial potentials.
  - (\*) result is a factor called the beliefs  $B_r(C_r)$  (only for root clique does this special term apply (?)
- This represents:-

$$\tilde{P}_B(C_r) = \sum_{X-C_r} \prod_{k \in X} \phi_k$$

Algorithm 10.1-pseudocode (typed pass only)

- no need to write out
- check you understand (\*) select root clique
- (\*) ready cliques at beginning of algo  $\Rightarrow$  start at leaves  
(as they do not receive messages)
- (\*) CF at beginning; calls subroutines - initialise clique, SP-message.
- (\*) searches for ready cliques (implicitly defines an ordering)
  - executes sum-product message passing
  - compute belief at root clique  $C_r$  to get  $B_r$

(\*) note this algorithm can be run only for a selected root clique  $C_r$  which is informed by the grey variable.

(\*) 6.10.3  $\rightarrow$  shows importance of ordering of operations.  
- multiple orderings possible

(\*) use algo 10.1 to compute marginal prob - grey nodes ( $Y$ )  $\rightarrow p(Y)$

(\*) select grey nodes fully contained in clique to be root.  $C_r$

(\*) Do Algo 1; then:-

extract  $\tilde{P}_g(Y)$  from final pot. at  $C_r$  by summing out  $(C_r - Y)$   
(non grey variables).

### 10.2.1.3 Wcorrectness

correctness: Algo 10.1 applied to  $T$  (satisfying running intersect, fam pres.)  
computes desired expressions over messages, cliques

↳ Algo eliminates a variable  $X$  only when a message is sent  
from  $C_i$  to neighbouring  $C_j$ :  $X \in C_i$  and  $X \notin C_j$  (simple).

### Proposition 10.2

- Assume that  $X$  is eliminated when message sent from  $C_i$  to  $C_j$   
- Then  $X$  does not appear anywhere in the tree on the  $C_j$  side of the  
edge  $(i-j)$ .

### Q: semantic step of messages

• w/  $(i,j)$  be edge in clique tree

•  $F_{\leq}(i \rightarrow j)$  - set of factors on cliques on  $C_i$ -side of the edge

•  $V_{\leq}(i \rightarrow j)$  - set of variables on  $C_i$ -side but do not in sepset ( $S_{inj}$ )

(\*) see example (10.2) clique tree

$$F_{\leq}(i \rightarrow j) = \{p(C), p(O|C), p(G|I, O), p(I), p(S|I)\}$$

$$V_{\leq}(i \rightarrow j) = \{C, O, I\}$$

(\*) message passed between cliques  $C_i$  and  $C_j$  is product of all  
factors in  $F_{\leq}(i \rightarrow j)$  marginalised over the variables in the sepset  $S_{inj}$

(that is, summing out all the variables  $V_{\mathcal{L}}(i \rightarrow j)$ )

### Theorem 10.3

$$\text{- } S_{i,j} = S_{inj} = S_{C_i \cap C_j} \quad (\text{sepset variables})$$

- ut  $\partial_{i \rightarrow j}(S_{i,j})$  be a message from  $C_i$  to  $C_j$

$$\text{- then } \partial_{i \rightarrow j}(S_{i,j}) = \sum_{W_j(i \rightarrow j) \notin E_{\mathcal{L}}(i \rightarrow j)} \emptyset$$

(R): Related to T.10.2.

- sepset divides graph into conditionally independent pieces
- CI property - allows message (defined over sepset) to summarise completely the info on one side of the clique tree that is necessary for comp. on the other.

### Corollary 10.1

- $C_r$  - root clique
- $B_r$  is computed via algo 10.1

$$\cdot B_r(C_r) = \sum_{X-C_r} \tilde{P}_{\mathcal{B}}(X)$$

(R): BN,  $\mathcal{B}$ :  $\mathcal{B}$  consists of CPDs on  $\mathcal{B}$  reduced with evidence  $\mathcal{E}$

$$\Rightarrow B_r(C_r) = P_{\mathcal{B}}(C_r, \mathcal{E})$$

MNH:  $\mathcal{B}$  consists of compt/potentials

$$\Rightarrow B_r(C_r) = \hat{P}_{\mathcal{B}}(C_r)$$

- obtain probability over variables in  $C_r$ , by normalising resulting factor to sum to 1
- MN → obtain value of partition by summing up all entries in potential of root clique  $B_r(C_r)$ .

### 10.2.2 clique tree calibration

(\*) (\*\*) concerns computation of probability queries for multiple variables (rather than 1 variable as above through choice of root clique) (or variable scope of root clique)

- (\*) In particular, partially obs. settings  $\rightarrow$  follow all latent variables (and parents)
- (\*) consider computing posterior over every rv. in network:
- Naive: - run clique tree inference (upward pass Algo 10.1)  $n$  times for each  $x_1, \dots, x_n$  you want to query - comp. cost -  $nc$
  - Less Naive: - run clique tree inference for every clique - comp. cost -  $KC$
  - where c. comp. cost of one run of Algo 10.1 (upward pass of VEM C.T.)
- (\*) Can do much better
- (\*) Observation:
- 2 neighboring cliques  $C_i$  and  $C_j$  in some clique tree.
  - via 7.10.3  $\rightarrow$  value of message sent from  $C_i$  to  $C_j$  does not depend  
(?) on specific choice of root clique  $C_r$ .
- (\*) As long as root clique  $C_r$  is on the  $C_j$ -side, exactly same message / i.e. edge directionality
- is sent from  $C_i$  to  $C_j$
  - some argument for root clique on  $C_i$ -side (?)
  - essentially; it is not the specific position of root clique  $C_r$ ; but where it is relative to a particular pair of the adjacent cliques in question (i.e.  $C_i$  or  $C_j$ -side); that matters for the value of the message sent
- (\*) Any given clique tree - each edge - 2 messages - for each edge direction.
- (\*) Any given clique tree - each edge - 2 messages - for each edge direction.  
 $c$  cliques  $\Rightarrow (c-1)$  edges  $\Rightarrow 2(c-1)$  messages to compute.
- w: next move  $\rightarrow$  sum-product belief propagation / sum product message-passing;  
 or Snafir-Shenoy (1990) algorithm applied to PGMs.
- (\*) Extend previous concept of a 'ready clique' to be bidirectional (?)
- definition 10.4 (ready clique)
- T-clique tree
  - $C_i$  is ready to transmit to neighbor  $C_j$  when  $C_i$  has messages from all of its neighbors except from  $C_j$
- 
- (\*) Lays extension  $\rightarrow$  idea of upward/downward passes.
- (R): when  $C_i$  ready to transmit  $\rightarrow C_j$ ; can compute  $\delta_{i \rightarrow j}(S_{i,j})$  by multiplying initial potential with all of its incoming messages except one from  $C_j$  and then eliminate variables in  $\{S_i - S_{i,j}\}$  ✓

(\*) uses another layer of dynamic programming

- Guestrin:- VE operates on factors by caching comput  
within a single inference op e.g.  $P(X_i, e)$

CT enables caching computations across multiple  
inference ops  $P(X_i, X_j) \forall i, j$ .

(\*) Next algo; Algo 2  $\rightarrow$  sum-product belief propagation

(\*) Pseudocode - asynchronously; each clique-sends message - when ready.

(\*) Message passing process:-

upward pass:- Pick a root clique, send all messages to root.  
When complete, root has all messages.

downward pass:- Send the appropriate message to all its children.

continues until all leaves of tree reached  $\rightarrow$  no more SMPS.

(\*) Asynchronous pseudocode is equivalent; except root clique is first  
clique that happens to obtain all messages from neighbours.

(\*) Actual implement - use schedule to prevent double comp of messages.

Algo 10.2 - pseudocode - calibration using sum-product message  
passing in a clique tree.

(~): This algo requires absolute clarity (some O/S issues). (W): uses an  
arbitrary root clique;  
does not matter  
which one.

- see Jordan (2003): Ch4

Example (10.4) - shows diagrammatically (Fig 10.5)  
downward pass from a partic. root clique.

(i): At the end of the process, compute beliefs for all cliques in the tree  
by multiplying the initial potential with each of the meaning messages

(ii): Messages used in the computation of beliefs  $\beta_i(C_i)$  for clique  $C_i$

(iii): are precisely the same messages that would have been used

(iv): in a standard upwards pass of the algorithm with  $C_i$  as the root

Wolley 10.2

- Assume for each clique  $i$ ;  $\beta_i$  computed as in Algo 2; then

$$\beta_i(C_i) = \sum_{X-C_i} \hat{P}_i(X)$$

- (R)  $\xi_i$  computes message to  $\xi_j$  (neighbouring clique) based on initial potential  $\phi_i$ , not modified potential  $\beta_i$
- (\*)  $\beta_i$  already integrates information from  $j$ ; to do so  $\Rightarrow$  double counting factors assigned to  $\xi_j$ .
- (\*) Conclusion of algorithm  $\rightarrow$  each clique contains marginal (unnormalised) probability over variables in its scope
- (\*) Computing marginal prob over query variable  $\rightarrow$  eliminate other redundant variables in clique.
- (H) If  $X$  appears in two cliques; marginal must be the same.

### Definition 10.5 (calibration/clique beliefs/sepset beliefs)

- Two adjacent cliques  $\xi_i$  and  $\xi_j$  are calibrated if:-
- $$\sum_{\xi_i - \xi_{i,j}} \beta_i(\xi_i) = \sum_{\xi_j - \xi_{i,j}} \beta_j(\xi_j)$$

- A clique tree  $T$  is calibrated if all pairs of adjacent cliques are calibrated
- For a calibrated clique tree; we use the terms:-

$$\begin{aligned} i) & \text{clique beliefs: } \beta_i(\xi_i) \\ ii) & \text{sepset beliefs: } \mu_{i,j}(\xi_{i,j}) = \sum_{\xi_i - \xi_{i,j}} \beta_i(\xi_i) = \sum_{\xi_j - \xi_{i,j}} \beta_j(\xi_j) \end{aligned}$$

- (R) Key advantage of Shafer-Shenoy sum-product b.p  $\rightarrow$  computes posterior probability of all variables in a PGM in  $2x$  comp. of update pass in tree.

- (\*) Execution cost of message passing in clique tree to one root:  $c$   
Cost of Algo 10.2:  $2c$
- (\*) Compare with  $nc, Kc$  for naive runs of message passing.

