

LS - parameter estimation for PLMS - review

- (*) review slides \rightarrow note key eq.
- (*) use readings to supplement areas of uncertainty

(*) general parameter est. setup

- Assume structure of graph G is fixed / given in advance
- estimate parameters from IID dataset $D = \{x_1, x_2, \dots, x_N\}$

- N training instances

- each training instance $x_n = \begin{pmatrix} x_{n,1} \\ \vdots \\ x_{n,m} \end{pmatrix} \quad x_n \in \mathbb{R}^M$ - each dim. of x_n corresponds to a realisation of an r.v. i.e. a node

(*) completely observable

- $x_{n,i}$ is known $\forall n=1, \dots, N$ and $i \in 1, \dots, M$

(*) partially observable

$\exists i : x_{n,i}$ is not observed.

- log-likelihood (function of param): - (general BN)

$$\begin{aligned} \ell(\theta; D) &= \log p(D|\theta) = \log \left(\prod_{n=1}^N \left(\prod_{i=1}^M p(x_{n,i} | x_n, \pi_i, \theta_i) \right) \right) \\ &= \sum_{n=1}^N \sum_{i=1}^M \log p(x_{n,i} | x_n, \pi_i, \theta_i) \end{aligned}$$

π_i - parents of node i

(*) exponential family distr. (Murphy 2012)

- for a ^{vector} numeric r.v. X :- (scalar?) (*)

$$p(x|\eta) = h(x) \exp \{ \eta^T I(x) - A(\eta) \} = \frac{1}{z(\eta)} h(x) \exp \{ \eta^T I(x) \}$$

- is the exponential family distn with ~~eq~~:-

(*) canonical param η

(*) sufficient statistic $I(x)$

(*) log normaliser $A(\eta) = \log z(\eta)$

(*) expfamily + GLMS \rightarrow reads many models instances of this general form

examples:-

i) MVG:

- $x \in \mathbb{R}^K$

$$p(x|\mu, \Sigma) = \frac{1}{(2\pi)^{K/2} |\Sigma|^{1/2}} \exp \left\{ -\frac{1}{2} (x-\mu)^T \Sigma^{-1} (x-\mu) \right\} \quad (6)$$

$$= \frac{1}{(2\pi)^{K/2} |\Sigma|^{1/2}} \exp \left\{ -\frac{1}{2} \text{tr}(\Sigma^{-1} x x^T) + \mu^T \Sigma^{-1} x - \frac{1}{2} \mu^T \Sigma^{-1} \mu - \log |\Sigma| \right\}$$

(i) obtained by expanding; applying the trace trick to quadratic form

$$x^T \Sigma^{-1} x$$

$$\text{As } x^T \Sigma^{-1} x = \text{tr}(x^T \Sigma^{-1} x) = \text{tr}(x x^T \Sigma^{-1}) = \text{tr}(\Sigma^{-1} x x^T)$$

Exponential family

$$\eta = \begin{bmatrix} \Sigma^{-1} \mu \\ -\frac{1}{2} \text{vec}(\Sigma^{-1}) \end{bmatrix} = \begin{bmatrix} \eta_1 \\ \text{vec}(\eta_2) \end{bmatrix}, \quad \begin{aligned} \eta_1 &= \Sigma^{-1} \mu \\ \eta_2 &= -\frac{1}{2} \Sigma^{-1} \end{aligned}$$

$$\text{vec} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a \\ c \\ b \\ d \end{bmatrix}$$

$$T(x) = \begin{bmatrix} x \\ \text{vec}(x x^T) \end{bmatrix}$$

$$A(\eta) = \frac{1}{2} \mu^T \Sigma^{-1} \mu + \log |\Sigma| = -\frac{1}{2} \text{tr}(\eta_2 \eta_1 \eta_1^T) - \frac{1}{2} \log(-2\eta_2)$$

$$h(x) = (2\pi)^{-K/2}$$

- $K+K^2$ parameters; but low due to symmetric PSD Σ

ii) Multinomial

- $x \in \text{Multinomial}(x|\pi)$

$$x = \begin{pmatrix} x_1 \\ \vdots \\ x_M \end{pmatrix} \quad \pi = \begin{pmatrix} \pi_1 \\ \vdots \\ \pi_M \end{pmatrix}$$

- Binary(?) (ex is incorrect) (not sure what lecture notes we refer to)

Jordan (2003): x is a collection of integer-valued r.v.s. representing event counts where x_k is no. of times the k^{th} event occurs in n independent trials.

(*) moment generating properties of exp family

(scalar form.)

• The moments of the relevant distri \rightarrow obtained via derivatives of log normalisation function $A(\eta) = \log(\cancel{H e^{\eta T}}) = \log z(\eta)$

$$(*) \frac{dA}{d\eta} = \frac{d}{d\eta} \log z(\eta) = \frac{1}{z(\eta)} \frac{d}{d\eta} z(\eta)$$

(?) confused by dimensionality not (*)

$$= \frac{1}{z(\eta)} \frac{d}{d\eta} \int h(x) \exp\{\eta T(x)\} dx$$

(I) \downarrow

$$= \int T(x) \frac{h(x) \exp(\eta T(x))}{z(\eta)} dx \quad (*)$$

$$= E[T(x)] \quad (\text{with respect to?})$$

$$(*) \frac{d^2 A}{d\eta^2} = \int T^2(x) \frac{h(x) \exp\{\eta T(x)\}}{z(\eta)} dx - \left(\int T(x) \frac{h(x) \exp\{\eta T(x)\}}{z(\eta)} dx \right)^2 \frac{1}{z(\eta)} \frac{d}{d\eta} z(\eta)$$

$$= E[T^2(x)] - E^2[T(x)]$$

$$= \text{Var}(T(x))$$

o/r

(*) Take derivatives of log-normaliser.

- q^{th} derivative $\rightarrow q^{\text{th}}$ centred moment

$$\frac{dA(\eta)}{d\eta} - \text{mean} \quad ; \quad \frac{d^2 A(\eta)}{d\eta^2} - \text{variance}$$

(*) sufficient statistic - vector \Rightarrow partial deriv.

(I) clarity on derivation

$$\frac{dA}{d\eta} = \frac{d}{d\eta} \left\{ \log \int \exp\{\eta T(x)\} h(x) dx \right\} = \frac{\int \frac{d}{d\eta} \exp\{\eta T(x)\} h(x) dx}{\int \exp\{\eta T(x)\} h(x) dx}$$

(*) If π_k the probability of k^{th} event occurring in any given trial:-

$$p(\underline{x}|\underline{\pi}) = \frac{n!}{x_1! x_2! \dots x_m!} \pi_1^{x_1} \pi_2^{x_2} \dots \pi_m^{x_m} \quad (\text{mult})$$

$$\Rightarrow p(\underline{x}|\underline{\pi}) = \exp \left\{ \sum_{i=1}^m x_i \ln \pi_i \right\} \quad (\text{trick})$$

(*) Issue:- factor in probability constraint $\sum_{i=1}^m \pi_i = 1$

$$\hookrightarrow A(\underline{\eta}) = 0?$$

(*) Parametrise with only $(m-1)$ components of $\underline{\pi}$:-

$$\begin{aligned} p(\underline{x}|\underline{\pi} \setminus \pi_m) &= \exp \left\{ \sum_{i=1}^m x_i \ln \pi_i \right\} \\ &= \exp \left\{ \sum_{i=1}^{m-1} x_i \ln \pi_i + \left(1 - \sum_{i=1}^{m-1} \pi_i \right) \ln \left(1 - \sum_{i=1}^{m-1} \pi_i \right) \right\} \\ &= \exp \left\{ \sum_{i=1}^{m-1} \ln \left(\frac{\pi_i}{1 - \sum_{i=1}^{m-1} \pi_i} \right) x_i + \ln \left(1 - \sum_{i=1}^{m-1} \pi_i \right) \right\} \end{aligned}$$

exp family rep

$$\underline{\eta} = \begin{bmatrix} \ln \left(\frac{\pi_i}{\pi_m} \right) \\ 0 \end{bmatrix}$$

i.e. $\underline{\eta}$ has $(m-1)$ components $\eta_i = \ln \left(\frac{\pi_i}{\pi_m} \right)$
and last component $\eta_m = 0$

$$T(\underline{x}) = \underline{x}$$

$$A(\underline{\eta}) = -\ln \left(1 - \sum_{i=1}^{m-1} \pi_i \right) = \ln \left(\sum_{i=1}^m e^{\eta_i} \right)$$

$$h(\underline{x}) = 1$$

$$(k) \text{ note } \pi_i = \frac{e^{\eta_i}}{\sum_{j=1}^m e^{\eta_j}} \quad (\text{softmax}) \quad \pi_i = \text{softmax}_i(\underline{\eta})$$

$$= \frac{\int T(x) \exp\{\eta T(x)\} h(x) dx}{\int \exp\{\eta T(x)\} h(x) dx} = \frac{\int T(x) \exp\{\eta^T T(x) - A(\eta)\} h(x) dx}{\int \exp\{\eta^T T(x) - A(\eta)\} h(x) dx}$$

$\rightarrow \textcircled{?}$ $\textcircled{\text{O/S1}}$

$$= E[T(x)]$$

(*) Moment and canonical parameters

(*) Exponential families can have { canonical parametrisation (via η)
moment parametrisation (via μ) }

$$\frac{dA(\eta)}{d\eta} = E[T(x)] = \mu \quad ; \quad \frac{d^2 A(\eta)}{d\eta^2} = \text{Var}(T(x)) > 0 \quad \left(\begin{array}{l} \text{variance} \\ \text{properties} \\ \rightarrow \text{non-neg} \end{array} \right)$$

(*) $A(\eta)$ is convex function

(*) convexity \Rightarrow one-to-one rel between argument η and first derivative.

(*) yields an invertible mapping :- \textcircled{A}

$$\eta = \psi(\mu)$$

(*) Moment matching, MLE for exponentials

- IID data:

- log likelihood:

$$\begin{aligned} \ell(\eta; D) &= \log \prod_{n=1}^N h(x_n) \exp\{\eta^T T(x_n) - A(\eta)\} \\ &= \sum_{n=1}^N \log h(x_n) + \eta^T \left(\sum_{n=1}^N T(x_n) \right) - NA(\eta) \end{aligned}$$

$$\nabla_{\eta} \ell = \sum_{n=1}^N T(x_n) - N \nabla_{\eta} A(\eta) = 0$$

$$\Rightarrow \nabla_{\eta} A(\hat{\eta}) = \frac{1}{N} \sum_{n=1}^N T(x_n)$$

O/S 2 - dimensional clarity

- define $\mu = \mathbb{E}[T(x)]$

$$\hat{\mu}_{ML} = \frac{1}{N} \sum_{n=1}^N T(x_n)$$

(*) moment matching \Rightarrow can infer canonical param via $\hat{\eta}_{ML} = \psi(\hat{\mu}_{ML})$
not vice versa

(*) Sufficiency + Neyman factor.

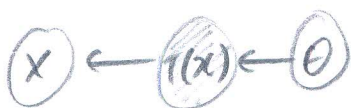
Bayesian:



$$p(\theta | T(x), x) = p(\theta | T(x)) \quad (\text{prob. spec.})$$

i.e. $\theta \perp\!\!\!\perp x | T(x)$ (C.I. rel. spec.)

Freq:



$$p(x | T(x), \theta) = p(x | T(x))$$

i.e. $(\theta \perp\!\!\!\perp x | T(x))$

Neyman fact:



(0/5 3)

- Rewrite / review
in context of
36-705

- via graphical formalism: - $T(x)$ is sufficient for θ

$$p(x, T(x), \theta) = \psi_1(T(x), \theta) \psi_2(x, T(x))$$

- proportion constant, absorbed
into one
of ψ_1, ψ_2 potentials

$$\Rightarrow p(x | \theta) = g(T(x), \theta) h(x, T(x))$$

- $T(x)$ - determ function
of x ; drop from LHS; divide
by $p(\theta)$

- for given g and h (functions).

Remarks

(*) can specify either C.I. statements or prob. versions

(*) Bayesian intuitions

- θ is an i.v. \rightarrow can make C.I. statements involving θ

(*) frequentist intuitions

- treat θ as a label rather than i.v.; $T(x)$ is sufficient for θ
if the conditional distrib of x given $T(x)$ is not a function of θ .

(*) Both imply a factorisation of $p(x|\theta)$

(*) Neyman factorisation \rightarrow frequentist definition of sufficiency

(*) Sufficiency in this context means $T(x)$ is sufficient for θ if:-

$$\theta \perp\!\!\!\perp x \mid T(x)$$

Jordan (2003)

- 8.1.8. ML and KL divergence

- A general rel. between ML and KL divergence (not spec. to exp.)

- Necessary for later lec. material 16, 17

- Statistical interp of KL divergence to illus. rel. between KL and exp. family

(*) empirical distn: $\hat{p}(x)$

- Places a point mass at each data point x_n in \mathcal{D} (dataset) (discrete)

(*) empirical distn:
$$\hat{p}(x) := \frac{1}{N} \sum_{n=1}^N \delta(x, x_n) = \frac{1}{N} \sum_{n=1}^N \mathbb{I}(x = x_n)$$

(*) Sum/integrate

$\hat{p}(x)$ against a function of x ; we evaluate

at each point x_n

(*) log likelihood: (also, cross entropy of $\hat{p}(x)$ and $p(x|\theta)$)

$$\sum_x \hat{p}(x) \log p(x|\theta) = \sum_x \left(\frac{1}{N} \sum_{n=1}^N \delta(x, x_n) \log p(x_n|\theta) \right)$$

$$= \frac{1}{N} \sum_{n=1}^N \sum_x \delta(x, x_n) \log p(x_n|\theta)$$

$$= \frac{1}{N} \sum_{n=1}^N \log p(x_n|\theta)$$

$$= \frac{1}{N} \ell(\theta|\mathcal{D})$$

δ -Kronecker
delta in cont.
case.

↙ de-trickifying

(*) Note; the scaled log likelihood (by factor $1/N$) is equivalent to the cross-entropy between the empirical distri and the model
 $(\hat{p}(x))$ $\neq p(x|\theta)$

- same result for continuous

- KL divergence between empirical; model :-

$$D(\hat{p}(x) \| p(x|\theta)) = \sum_x \hat{p}(x) \log \frac{\hat{p}(x)}{p(x|\theta)}$$

$$= \sum_x \hat{p}(x) \log \hat{p}(x) - \sum_x \hat{p}(x) \log p(x|\theta)$$

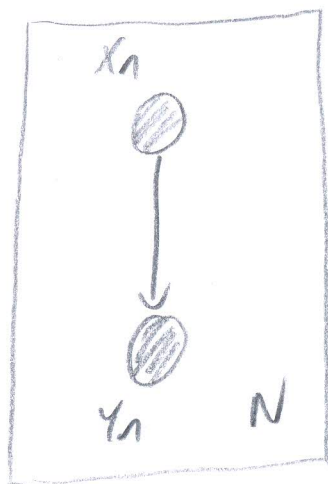
$$= \underbrace{\sum_x \hat{p}(x) \log \hat{p}(x)}_{(1)} - \underbrace{\frac{1}{N} \ell(\theta|D)}_{(2)}$$

(1) - independent of θ

- value of θ that minimises LHS is the value of θ that maximises the RHS

(*) Minimising KL divergence between the empirical distri and model distri is equivalent to maximising the likelihood

(*) Generalised linear Models (GLM) - linear regression/classification
 covers linear reg./discriminative linear classification.



(*) Both LR/UC \rightarrow both assume a rep. for conditional expectation of Y .

$$(*) \mu = f(\theta^T x) = \mathbb{E}_{Y \sim p(Y|f(x))} [Y]$$

(*) LR: $f(\cdot)$ - identity

UC: $f(\cdot)$ - sigmoid (logistic)

(*) Also: endow Y with a particular cond. prob. distribution, with μ as a parameter.

(*) Remember JP \rightarrow ColumbiaX ML (prob. intep of ML for LR!)

(*) LR - Gaussian LC - Bernoulli / Multinomial.

(*) Generalised Linear Model Framework

- 3 assumptions on $p(y|x)$:-

1. observed input x enters into model via linear comb. $\xi = \theta^T x$
2. conditional mean μ rep as a function $f(\xi)$ of the linear combination ξ where f is known as the response function
3. observed output y is assumed to be characterised by exp. family with conditional mean μ .

