

YouTube lecture 30/09/16

- Have seen following methods for constructing estimators

1. MOM
2. MLE
3. Bayes

example 8

- $X_1, \dots, X_n \sim N(\mu, \sigma^2)$ σ^2 is known

- let $\mu \sim N(m, \tau^2)$

- m, τ^2 fixed unknown nos.

- following procedure from Bayes estimators:-

$$p(\mu | X_1, \dots, X_n) \propto p(X_1, \dots, X_n | \mu) p(\mu) \propto$$

$$e^{-\frac{(\mu - m)^2}{2\tau^2}}$$

$$\propto e^{-\frac{(\mu - m)^2}{2\tau^2}}$$

$$\Rightarrow \hat{\mu} = E[\mu | X] = \frac{(i) \tau^2}{(iii) \tau^2 + \frac{\sigma^2}{n}} \bar{X} + \frac{\frac{\sigma^2}{n}}{\tau^2 + \frac{\sigma^2}{n}} m$$

(i) prior variance

(ii) variance of \bar{X}

- nice combination of sample mean under MLE and prior mean

(*) Mode of posterior, as part of Bayes estimator procedure, yields MAP (rather than mean mode case)

iii: we need a way of evaluating estimators. focus on mean-squared-error as 1st step. minimax theory supplements this as a formal way of evaluating estimator quality. And then large sample theory

MSE \rightarrow minimax \rightarrow large sample theory/asymptotics.

5. MSE

- recall $\hat{\theta}$ is an r.v.
- Heuristically, MSE is mean of how far an estimator $\hat{\theta}$ deviates from its true value θ .

$$E_{\theta}(\hat{\theta} - \theta)^2 = \int \dots \int (\hat{\theta}(x_1, \dots, x_n) - \theta)^2 p(x_1; \theta) \dots p(x_n; \theta) dx_1 \dots dx_n$$

(*) Expectation is wrt joint distribution (assuming IID) (1) Clarify

(*) Computationally \rightarrow we don't evaluate this integral (or rarely)

$$\text{MSE} = \text{Bias}^2 + \text{Variance} \quad (2)$$

$$\text{Bias: } -B = E_{\theta}(\hat{\theta}) - \theta \quad (\text{"mean of an estimator minus true value"})$$

$$\text{Variance: } -V = \text{Var}_{\theta}(\hat{\theta})$$

(*) Many problems in ML involve a trade-off between B and V.

Theorem 9

$$\text{MSE} = B^2 + V$$

- add/subtract m

Proof: $\text{MSE} = E_{\theta}(\hat{\theta} - \theta)^2 = E_{\theta}(\hat{\theta} - m + m - \theta)^2$ where $m = E_{\theta}(\hat{\theta})$

$$= E_{\theta}(\hat{\theta} - m)^2 + (m - \theta)^2 + 2E_{\theta}(\hat{\theta} - m)(m - \theta)$$

$$= E_{\theta}(\hat{\theta} - m)^2 + (m - \theta)^2 + \underbrace{2(m - \theta)E_{\theta}(\hat{\theta} - m)}_{=0 \text{ as } E_{\theta}(\hat{\theta}) = m}$$

$$= E_{\theta}(\hat{\theta} - m)^2 + (m - \theta)^2$$

$$= V + B^2$$

W: Some parametric estimators have 0 bias; then $MSE = \text{variance}$.

- lots of focus on unbiasedness in 1950s/60s; now combo of bias-variance is emphasised.

Example 10:

- let $X_1, \dots, X_n \sim N(\mu, \sigma^2)$

- consider MLE estimates of μ and σ^2 :-

$$\hat{\mu}_{MLE, MOM} = \bar{X}_n \quad \hat{\sigma}_{MLE}^2 = \frac{1}{n} \sum_{i=1}^n (X_i - \bar{X}_n)^2$$

- we make adjustment $S_n^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X}_n)^2$ to ensure unbiasedness

$$\Rightarrow E[S_n^2] = \sigma^2$$

(?)

- W: not entirely significant; made more for historical reasons.

- $MSE(\hat{\mu}) = \frac{\sigma^2}{n}$ (equal to variance as $\hat{\mu}$ is unbiased.)

$$- MSE(\hat{\sigma}^2) = E[(S^2 - \sigma^2)^2] = \frac{2\sigma^4}{n-1} \quad (\text{A3} - \text{derivation})$$

- note $MSE \rightarrow 0$ as $n \rightarrow \infty$ $MSE = O(\frac{1}{n})$ - note $MSE = f(\sigma^2)$

- characteristic of many significant parametric estimators

(*) for many non-parametric estimators cannot achieve this kind of convergence for MSE

W: But, still doesn't quite give clear prescriptions on what estimators to select out of a subset of good estimators.

- As it contains an unknown parameter σ^2 (a function of it)

- computing MSE is a first step

6. Best unbiased estimators

- idea is that we restrict ourselves to unbiased estimators.

- then we can answer question of which estimator has lowest variance

W: Many theorems, textbooks on this

W: His view is that these results are not particularly 'useful' (without qualification); but important historically; hence he does not emphasize

- Rao-Blackwell: for an unbiased estimator W ; you can take $E[W|T]$ where T is a sufficient statistic; and this is still an estimator
- in the sense that an estimator can only depend on the data
- $E[W|T]$ is guaranteed to depend on the data and not on the parameter because conditioning on the sufficient statistic \Rightarrow distri no longer depends on parameter θ .
- so $E[W|T]$ defines a new estimator which automatically gives us another estimator with a unilateral decrease in variance.

Lecture Notes 8 - Minimax Theory

- A theoretical construct to evaluate quality of estimators
- see a lot of NewIPS conferences/papers with minimax
- covered in more detail in 36-702.
- this covers basic idea.

1. Minimax Theory

- more concretely
- suppose we want to estimate a parameter θ using data $x^n = (x_1, \dots, x_n)$
- what is best possible estimator $\hat{\theta} = \hat{\theta}(x_1, \dots, x_n)$ of θ ?
- minimax \rightarrow provides framework for answering.

1.1. - Introduction

- what do we mean by a parameter estimator being close to the truth?
- problem dependent \rightarrow if you tell me what you mean by 'closeness', theory will assist.

- let $\hat{\theta} = \hat{\theta}(x^n)$ be an estimator for the parameter $\theta \in \Theta$ * dropping vector notation.
- define a loss function $l(\theta, \hat{\theta})$ that measures how good an estimator is. - (AI) notes have sep. not. for vectors.

(*) Can take many functional forms; MSE \rightarrow squared error loss (squared distance is measure of loss)

examples \rightarrow e.g. $l(\theta, \hat{\theta}) = (\theta - \hat{\theta})^2$ - squared error loss

(scalar) $l(\theta, \hat{\theta}) = |\theta - \hat{\theta}|$ - abs.

$l(\theta, \hat{\theta}) = \mathbb{I}\{\theta \neq \hat{\theta}\}$ - zero-one loss

(*) minimax theory is general; gives you an optimal estimator with respect to a loss function.

(*) Classification: - (zero-one loss)

- predict $Y \in \{0, 1\}$ $l(Y, h(x)) = \mathbb{I}\{Y \neq h(x)\}$

- classifier $h(x)$

(*) Real-valued predic: -

$$l(Y, \hat{Y}) = (Y - \hat{Y})^2$$

- value of the loss function $l(\theta, \hat{\theta})$ is a random quantity, due to presence of $\hat{\theta}$.

(*) - Commit \rightarrow rem.
- (all defn.) ✓

The risk of an estimator $\hat{\theta}$: - (expected value of loss)

$$R(\theta, \hat{\theta}) = \mathbb{E}_{\theta}(l(\theta, \hat{\theta})) = \int l(\theta, \hat{\theta}(x_1, \dots, x_n)) p(x_1, \dots, x_n; \theta) dx$$

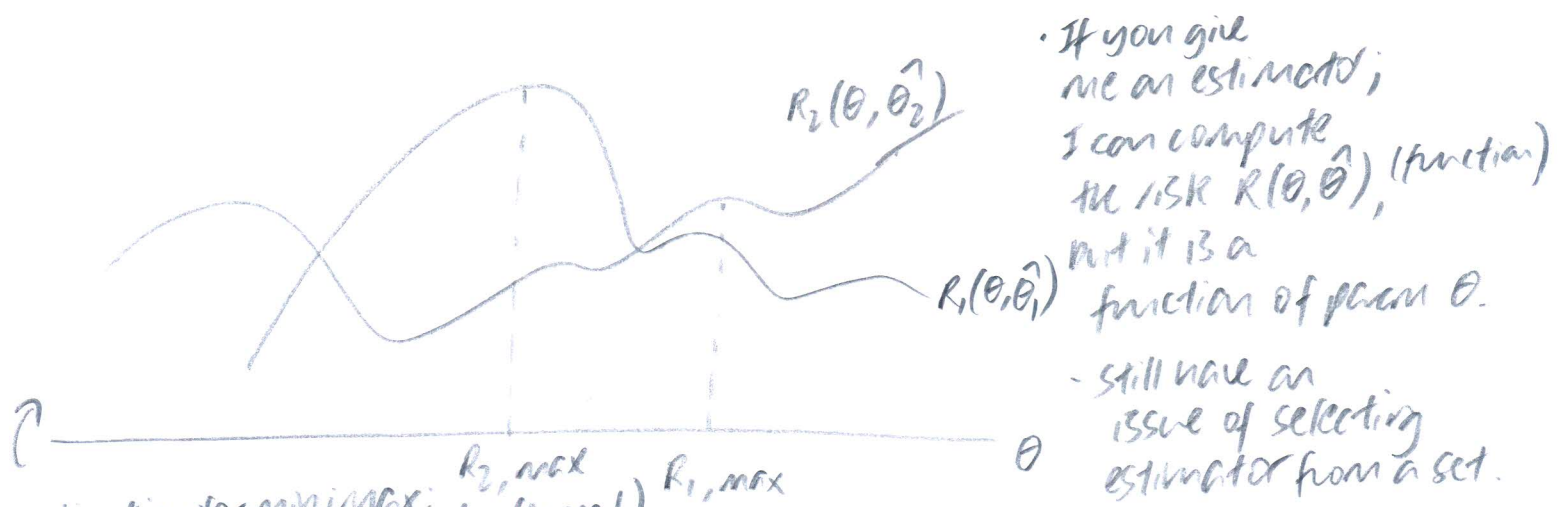
$$= \int \dots \int l(\theta, \hat{\theta}(x_1, \dots, x_n)) p(x_1; \theta) \dots p(x_n; \theta) dx_1 \dots dx_n$$

(*) loss depends on data when we evaluate it; the risk is not, as we are integrating the data out; risk still depends on the parameter θ .
and is a function of θ

(*) For l_2 loss: the risk

$$l(\theta, \hat{\theta}) = (\theta - \hat{\theta})^2 \Rightarrow R(\theta, \hat{\theta}) = \mathbb{E}_{\theta}[(\theta - \hat{\theta})^2] = \text{MSE}$$

(*) MSE is a ~~more~~ specific case of a more general concept within minimax



- motivation for minimax: (informal) $R_{2, \max}$ $R_{1, \max}$
- 'protect ourselves' from worst case, given we do not true value of θ (unknown param)
- look at $\max(R_i(\theta, \hat{\theta}_i))$ and say an estimator is 'better' if the maximum of corresponding risk is smaller than another estimator.
- i.e. for 2 estimators $\hat{\theta}_i$ and $\hat{\theta}_R$
- If $\max(R_i(\theta, \hat{\theta}_i)) < \max(R_R(\theta, \hat{\theta}_R)) \Rightarrow \hat{\theta}_i$ is a 'better estimator'
- formally:
- (13) - review concept. ✓

(*) the minimax risk :-

$$R_n = \inf_{\hat{\theta}} \sup_{\theta} R(\theta, \hat{\theta})$$

(I)

(II)

(I) Take estimator $\hat{\theta}$, compute function $R(\theta, \hat{\theta})$ and find its maximum over its argument (the unknown parameter θ). ('max a sup')

(II) Find the smallest you can make quantity (I) over all possible estimators $\hat{\theta}$. ('min a inf')

(*) In a certain sense, minimax risk is a quantification of how 'difficult' a problem is. (as the best you can do).

(*) An estimator $\hat{\theta}$ is minimax estimator if:-

$$\sup_{\theta} R(\theta, \hat{\theta}) = \inf_{\hat{\theta}} \sup_{\theta} R(\theta, \hat{\theta}) = R_n$$

Q: Prior on θ ? i.e. introduce averaging.

Q: Looking ahead. Integrating $R(\theta, \hat{\theta})$ gives you Bayes estimators

(*) Aside:-

Parametric problems:- $R_n = O(\frac{1}{n})$

nonparametric-"-:- $R_n = O(\frac{1}{n^a})$

- risk goes to 0, but at
what rate?

$a < 1$



- in CS, we have sample complexity; how big a sample size do I need to ensure
(theoretical) that risk $R_n < \epsilon$