

YouTube 03/10/16

Lecture Notes 8 (Minimax Theory) cont.

$$R(\theta, \hat{\theta}) = E_{\theta}[L(\theta, \hat{\theta})]$$

- "risk as exp. of loss"

$$R_n = \inf_{\hat{\theta}} \sup_{\theta} R(\theta, \hat{\theta})$$

- "minimax risk"

$$\beta_n(\hat{\theta}) = \int R(\theta, \hat{\theta}) \pi(\theta) d\theta$$

- "Bayes risk"

(*) Bayes risk - integral of risk wrt prior; minimiser of Bayes risk is Bayes estimator

(#) maximum risk; minimiser of maximum risk is minimax estimator;
alternatively, minimax estimator achieves minimax risk.

QW: finding minimiser of Bayes risk is 'easy'; minimiser of maximum risk is more difficult.

(*) can use minimisation of Bayes risk as a route to getting minimax estimator

QW: derive a different expression for Bayes risk

1.3 Bayes estimator

- prior distri.

- after observing $X^n = (x_1, \dots, x_n)$

- posterior distri. $L(\theta) = p(x^n; \theta)$ (likelihood fn.)

recall θ is an r.v. under this paradigm

$$P(\theta \in A | X^n) = P(\theta | x_1, \dots, x_n) = \frac{\int_A p(x_1, \dots, x_n | \theta) \pi(\theta) d\theta}{\int_{\Theta} p(x_1, \dots, x_n | \theta) \pi(\theta) d\theta}$$

$$= \frac{\int_A L(\theta) \pi(\theta) d\theta}{\int_{\Theta} L(\theta) \pi(\theta) d\theta}$$

define the posterior risk of an estimator $\hat{\theta}(x^n)$ by:-

$$r(\hat{\theta}|x_1, \dots, x_n) = \int l(\theta, \hat{\theta}(x_1, \dots, x_n)) p(\theta|x_1, \dots, x_n) d\theta$$

- (*) Alternative way of treating loss function in the context of expectation
- (*) conventionally, risk is defined as expectation of loss with respect to the sampling distribution $E_\theta[l(\theta, \hat{\theta})]$
- (*) instead, here; we use Bayes theorem to get a posterior distribution; and also density for θ .
- (*) take loss function $l(\theta, \hat{\theta})$ which we don't know due to presence of unknown θ .
- (*) But ^{we} have a posterior density/distribution $\theta \rightarrow$ integrate out θ .
- (*) Posterior risk is integral of loss with respect to a posterior density/distr?

61) - review.

(*) marginal distri of X^n : (recall Bayesian para. now)

$$- M(x^n) = m(x_1, \dots, x_n) = \int p(x^n|\theta) \pi(\theta) d\theta$$

Theorem 6

*useful
(as an alternative to original
defn.)*

- the Bayes risk $B\pi(\hat{\theta})$ satisfies/can be written as:-

$$B\pi(\hat{\theta}) = \int r(\hat{\theta}|x^n) m(x^n) dx^n = \iint \cdots \int r(\hat{\theta}|x_1, \dots, x_n) m(x_1, \dots, x_n) dx_1 \cdots dx_n$$

(i)

- let $\hat{\theta}(x^n)$ be the value of θ that minimises $r(\hat{\theta}|x^n)$ (posterior risk)

* Then $\hat{\theta}$ is the Bayes estimator

$$\hat{\theta}(x_1, \dots, x_n)$$

W: - minimise (i) for each x^i , then entire integral is minimised.

- Note that all terms are non-negative

- minimising each element of an integral (aka summation) \rightarrow minimise the integral.

(*) In many cases, posterior risk is easy to minimise

(*) Definition of Bayes risk

(orig. val) is used for theoretical reasons; but for purposes of calculation/computation, we use the specification of Bayes risk in terms of the posterior i.e. Theorem 6.

(*) Proof of T.6 → motivation:-

- note that the term within $\int R(\theta, \hat{\theta}) \pi(\theta) d\theta$, $R(\theta, \hat{\theta})$ is an expected value w.r.t a sampling distribution (i.e. x^n "given" θ).

- Note that there is also a prior $\pi(\theta)$ within the integral. (distri of θ).
- essence is just switching integral order, manip. probabilities.

Theorem 6 (Proof)

- let $p(x, \theta) = p(x|\theta) \pi(\theta)$ be the joint density of X and θ . (i)

- The Bayes risk:-

$$B_\pi(\hat{\theta}) = \underbrace{\int R(\theta, \hat{\theta}) \pi(\theta) d\theta}_{\text{substs } R(\theta, \hat{\theta})} = \int \left(\int L(\theta, \hat{\theta}(x^n)) p(x|\theta) dx^n \right) \pi(\theta) d\theta$$

$$= \iint L(\theta, \hat{\theta}(x^n)) p(x, \theta) dx^n d\theta$$

$$= \iint L(\theta, \hat{\theta}(x^n)) p(\theta|x^n) m(x^n) dx^n d\theta$$

$$= \iint \left(\int L(\theta, \hat{\theta}(x^n)) \pi(\theta|x^n) d\theta \right) m(x^n) dx^n$$

$$= \int r(\hat{\theta}|x^n) m(x^n) dx^n$$

- Bayes risk can be viewed as expect. of usual risk $R(\theta, \hat{\theta})$ wrt prior distri
OR expect. of posterior risk wrt marginal.

(*) To find the Bayes estimator; it is sufficient to minimise posterior risk for each x^i

(*) i.e. selecting $\hat{\theta}(x^i)$ to be value that minimises $r(\theta|x^i)$ then we will minimise the integrand at every x ; and thus minimise

$$\int r(\hat{\theta}|x^i) \pi(x^i) dx^i$$

(*) use this to find Bayes est. for specific loss fns.

Theorem 7

- for $U(\theta, \hat{\theta}) = (\theta - \hat{\theta})^2$

posterior risk:

$$r(\hat{\theta}|x_1, \dots, x_n) = \int (\theta - \hat{\theta})^2 p(\theta|x_1, \dots, x_n) d\theta = \int (\theta - \hat{\theta}(x^n))^2 p(\theta|x^n) d\theta$$

- Bayes estimator $\hat{\theta}(x^n)$ minimises $r(\hat{\theta}|x^n)$

$$\text{Hence; } \frac{dr(\hat{\theta}|x^n)}{d\hat{\theta}} = 2 \int (\hat{\theta}(x^n) - \theta) \pi(\theta|x^n) d\theta = 0$$

$$\Rightarrow \int (\hat{\theta}(x^n) - \theta) \pi(\theta|x^n) d\theta = 0 \quad \text{- split integral}$$

$$\Rightarrow \int \hat{\theta}(x^n) \pi(\theta|x^n) d\theta - \int \theta \pi(\theta|x^n) d\theta = 0$$

$$\int \pi(\theta|x^n) d\theta = 1$$

$$\Rightarrow \hat{\theta} = \int \theta \pi(\theta|x^n) d\theta = \mathbb{E}(\theta|x^n=x^n)$$

(*) QW: for L_2 loss; find Bayes est. expl.

By multiplying likelihood and prior to get post. density/distr

- find mean of that distri and you have Bayes estimator wrt L_2 loss.
(i.e. minimiser of posterior risk)

(*) By 7.6 ; this also minimises the original definition of Bayes risk

\therefore Bayes est. wrt L_2 loss

(*) Mean of the posterior is the Bayes estimator for L_2 loss

(*) Lecture terminates prematurely after 19 mins

- 30 mins missing

- go through it yourself

