

CS747 Assignment-3

Windy Gridworld

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Contents

1	Introduction	1
2	Sarsa(0) plots	2
3	Comparative study	3
3.1	Comparison between updates	3
3.2	Comparison between worlds	3
3.3	Comparing hyperparameters on the baseline model	4
4	Best method	5
4.1	Baseline model	5
4.2	King's model	6

1 Introduction

For all the graphs presented below(except for Sections 3.3 and 4), the values of various parameters are shown in Table 1. In addition, each of the plot and data presented are a result of runs averaged over 50 random seeds.

Parameter	Value
Episodes	200
Learning Rate	0.7
ϵ	0.05

Table 1: Values of parameters

2 Sarsa(0) plots

Figure 1, 2, 3 show the performance of sarsa(0) update on the baseline model, windy gridworld with King's moves, and stochastic wind with King's moves respectively. Stochastic wind is added in the third model, only when there is a non-zero wind present in the cell originally.

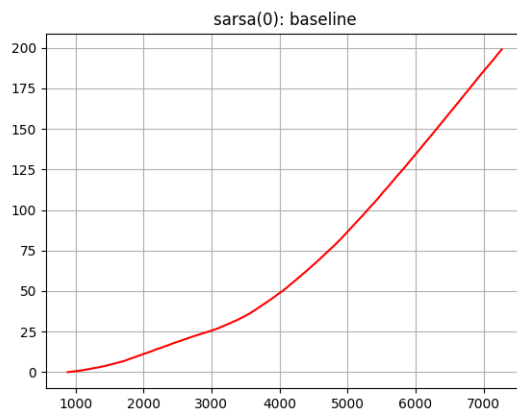


Figure 1: sarsa(0) on baseline model

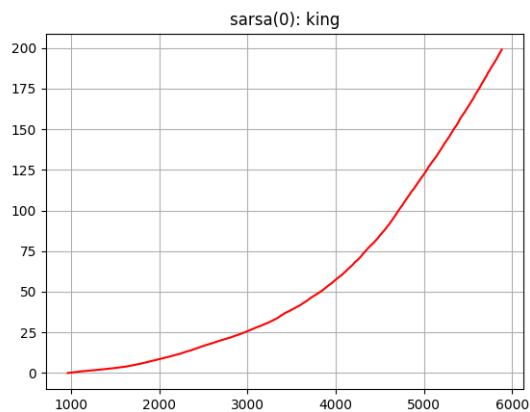


Figure 2: sarsa(0) on with king's actions

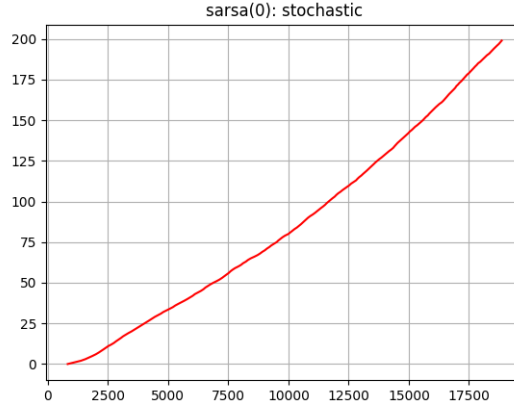
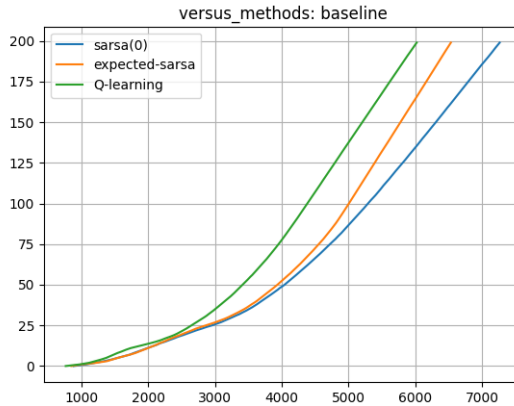


Figure 3: sarsa(0) on stochastic wind and King’s moves

3 Comparative study

3.1 Comparison between updates

This section compares the performance of different update algorithms, namely, sarsa(0), expected sarsa, and Q-learning on the baseline model. The final cumulative steps needed for finishing 200 episodes are shown in Table 2. Figure 4 shows the plots of steps vs episodes. Q-learning seems to perform the best.



Update	Steps
sarsa0	7264.4
Expected sarsa	6533.4
Q-learning	6021.7

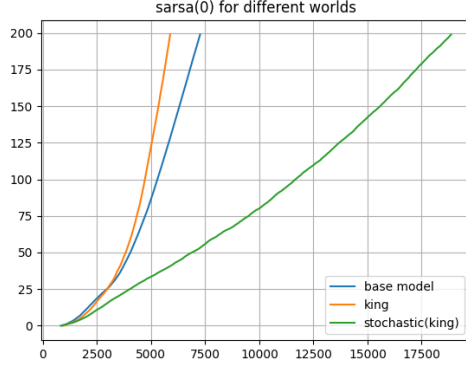
Table 2: Steps after 200 episodes

Figure 4: Different update rules on baseline model

3.2 Comparison between worlds

Figures 1, 2 and 3 have been summarised here. The final cumulative steps needed for finishing 200 episodes are shown in Table 3. Figure 5 shows the plots of steps vs episodes. The

extra actions provided in King’s world gives better performance than baseline model. When the wind becomes stochastic, it becomes more difficult to find the optimum Q-table. In fact, it does not seem to converge at all as the slope remains same throughout the 200 episodes.



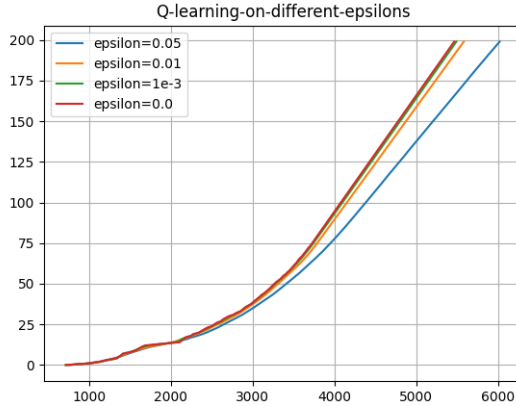
World	Steps
Baseline	7264.4
King	5880.5
Stochastic	18588

Table 3: steps after 200 episodes

Figure 5: Performance of sarsa(0) on different worlds

3.3 Comparing hyperparameters on the baseline model

This section compares the performance of Q-learning on setting different values of learning rates and ϵ . Figure 6 shows the effect of different epsilons for Q-Learning. We see that the best performance is got by setting epsilon equal to 0, which is quite interesting. The algorithm seems to converge for windy gridworld even when the policy is not GLIE.

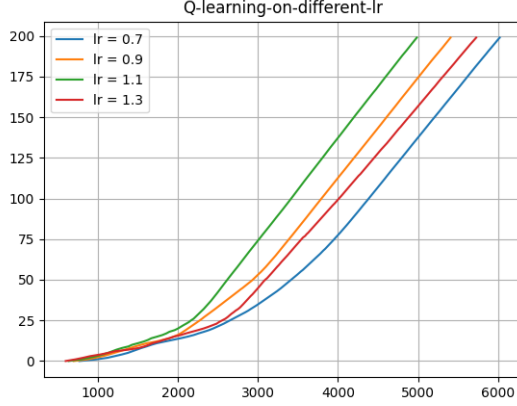


ϵ	Steps
0.05	6021.8
0.01	5583.14
$1e^{-3}$	5492.4
0.0	5466

Table 4: steps for different epsilons

Figure 6: Performance of Q-learning with different epsilons

Figure 7 shows the effect of different learning rates. We can observe a well expected 'minima' in the number of steps with regards to the learning rate(at a learning rate of 1.1 for Q-learning).



Learning rate	Steps
0.7	6021.72
0.9	5407
1.1	4985.2
1.3	5728.07

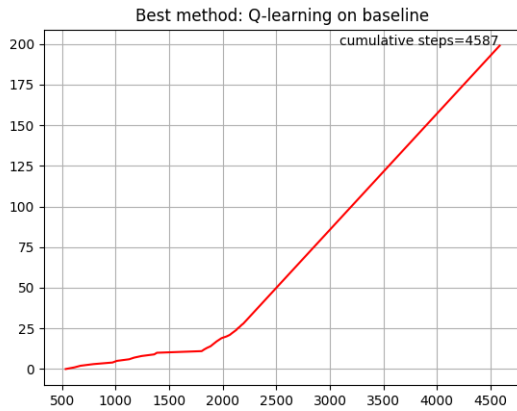
Table 5: steps for different learning rates

Figure 7: Performance of Q-learning with different learning rates

4 Best method

This section shows the best method(which converges the fastest) that could be obtained by tuning the hyperparameters and choosing between the three mentioned update methods for an agent in baseline world and in King's world.

4.1 Baseline model

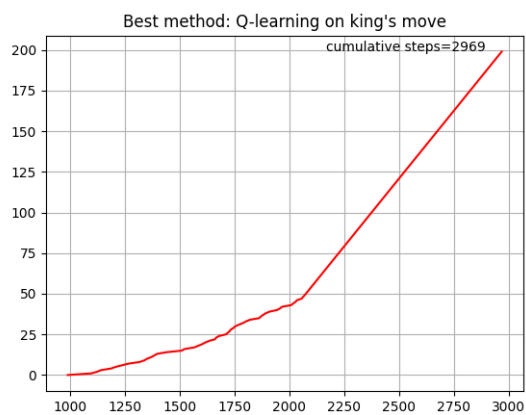


World	Steps
ϵ	0.0
learning rate	1.1

Table 6: parameters for best method(baseline)

Figure 8: Best method on baseline: Q learning

4.2 King's model



World	Steps
ϵ	0.0
learning rate	1.2

Table 7: parameters for
best method(king)

Figure 9: Best method on king: Q learning