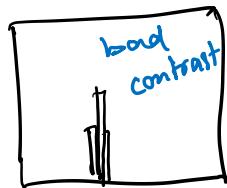


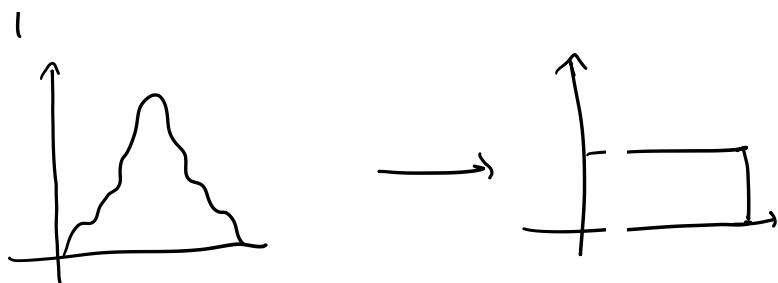
## Histogram equalization

Friday, August 6, 2021 3:34 PM

### Intensity histogram



### equalization



① convert to pmf

② Assume distribution is continuous & find  $T$  such that

$s = T(r)$  and  $s'$  has a uniform distr.

③ we look at the transform

$$s = T[r] = (l-1) \int f_{r,w}(w) dw \quad - \text{increasing function}$$

Lemma: for any one-one transform,

$$s = T(r)$$

$$f_s(s) = \left. \frac{f_r(r)}{\left| \frac{ds}{dr} \right|} \right|_{r=T^{-1}(s)}$$

proof:

If  $T$  is either increasing or decreasing:

I) Increasing  $\Rightarrow$  inv is increasing

$$F_s(s_0) = P(s < s_0) = P(T(r) < s_0)$$

$$= P(r < T^{-1}(s_0))$$

$$= F_r(T^{-1}(s_0))$$

$$\Rightarrow f_s(s_0) = \left. \frac{d}{ds} f_r(r) \right|_{s=s_0}$$

$$= \left. \frac{d}{dr} F_r(r) \cdot \frac{dr}{ds} \right|_{s=s_0}$$

II) Decreasing  $\Rightarrow$  inv is decreasing

$$F_s(s_0) = P(s < s_0) = P(T(r) < s_0) - P(r > T^{-1}(s_0))$$

$$= 1 - F(T^{-1}(s_0))$$

$$\Rightarrow f_s(s_0) = - \left. \frac{d f_r}{d r} \cdot \frac{d r}{d s} \right|_{s=s_0}$$

but  $\frac{d r}{d s}$  is +ve for I (increasing)

& -ve for II (decreasing)

$$\Rightarrow f_s(s_0) = \left. \frac{f_r(r)}{\left| \frac{d s}{d r} \right|} \right|_{r=T^{-1}(s_0)}$$

↳ since 1<sup>st</sup> degree differential

So in our case,

$$f_s(s_0) = \left. \frac{f_r(r)}{(L-1) f_r(r)} - \frac{d r}{d r} \right|_{r=T^{-1}(s)} \\ = \frac{1}{L-1}$$

④ We apply this to discrete domain

✳ Note that  $T$  is not one-one any more  
& it is an approximation

$$\boxed{s_k = (L-1) \sum_{j=0}^k F_{\text{tr}}(r_j)}$$

Q. What if we keep on applying this transform?

→ Continuous won't make a difference as the process exactly maps to Uniform.

In discrete, we will stop after some time.  
As it is a many  $\rightarrow$  one map, # non-zero bits  $\rightarrow$  one  $\rightarrow$  one.

decreases till it becomes

Histogram Specification:

Try to find a transform to a specific distribution.

①  $r \rightarrow s$  (Uniform)

②  $s \rightarrow z$  (required)

We know  $z \rightarrow s$  is  $G(z) = (L-1) \int_0^z f_z(w) dw$

$$\Rightarrow z = G^{-1}[\tau(x)]$$

τ?

CLAHF:

