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1  # -*- coding: utf-8 -*-
2  """
3  Created on Sun Jul 17 15:17:57 2016
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5  """
6
7  import FunITK as fun
8  from FunITK import Volume
9  import datetime
10 import numpy as np
11 import matplotlib.pyplot as plt
12 import os
13
14 idxSlice = 200
15 ph2_CT = Volume(path="../data/phantom2/CT_x1", method="CT",
16                 resample=1, ref=idxSlice)
17 ph2_CT_x4 = Volume(path="../data/phantom2/CT_x4", method="CT",
18                    resample=4, ref=idxSlice)
19 ph2_CT_x9 = Volume(path="../data/phantom2/CT_x9", method="CT",
20                    resample=9, ref=idxSlice)
21 ph2_CT_x25 = Volume(path="../data/phantom2/CT_x25", method="CT",
22                     resample=25, ref=idxSlice)
23 ph2_CT_x100 = Volume(path="../data/phantom2/CT_x100", method="CT",
24                      resample=100, ref=idxSlice)
25
26 ph2_MR = Volume(path="../data/phantom2/MR_x1", method="MR",
27                 resample=1, ref=idxSlice)
28 ph2_MR_x4 = Volume(path="../data/phantom2/MR_x4", method="MR",
29                    resample=4, ref=idxSlice)
30 ph2_MR_x9 = Volume(path="../data/phantom2/MR_x9", method="MR",
31                    resample=9, ref=idxSlice)
32 ph2_MR_x25 = Volume(path="../data/phantom2/MR_x25", method="MR",
33                     resample=25, ref=idxSlice)
34 ph2_MR_x100 = Volume(path="../data/phantom2/MR_x100", method="MR",
35                      resample=100, ref=idxSlice)
36
37 vol_list = [[ph2_CT, ph2_CT_x4, ph2_CT_x9, ph2_CT_x25, ph2_CT_x100],
38             [ph2_MR, ph2_MR_x4, ph2_MR_x9, ph2_MR_x25, ph2_MR_x100]]
39 modality, sets = np.shape(vol_list)
40
41 length = ph2_CT_x100.zSize
42 spacing = ph2_CT_x100.zSpace
43 sliceNumbers = np.arange(length, dtype=int)
44
45 # for data centered around iso-centre, this is real x-axis:
46 iso = 183
47 dist = ( (sliceNumbers - iso) ).round(2)
48
49 warp_simple = np.zeros((sets, length, 2))
50 warp_iter = np.zeros((sets, length, 2))
51 warpMagnitude_simple = np.zeros((sets, length, 1))
52 warpMagnitude_iter = np.zeros((sets, length, 1))
53 lows_CT = np.zeros((sets, 2))
54 radii_CT = np.zeros((sets, 2))
55 lows_MR = np.zeros((sets, 4))
56 radii_MR = np.zeros((sets, 4))
57
58 # 2 DC for CT, 3 DC for MR (2 using MR.centroid, 1 using CT.centroid!)
59 DC_CT = np.zeros((sets, length, 2))
60 DC_CT_average = np.zeros((sets, 2))
61 DC_MR = np.zeros((sets, length, 4))
62 DC_MR_average = np.zeros((sets, 4))
63
64 for i in range(sets):
65     vol_list[0][i].getCentroid()
66     CT_DC_simple = vol_list[0][i].getDice()
67     CT_DC_simple_average = vol_list[0][i].diceAverage
68     CT_lower_simple = vol_list[0][i].lower
69     CT_radius_simple = vol_list[0][i].bestRadius
70
71     vol_list[1][i].getCentroid()
72     MR_DC_simple = vol_list[1][i].getDice()

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73 MR_DC_simple_average = vol_list[1][i].diceAverage
74 MR_lower_simple = vol_list[1][i].lower
75 MR_radius_simple = vol_list[1][i].bestRadius
76 vol_list[1][i].getMask()
77 MR_DC_simple_CT_COM = vol_list[1][i].getDice(centroid=vol_list[0][i].centroid)
78 MR_DC_simple_CT_COM_average = vol_list[1][i].diceAverage
79 MR_lower_simple_CT_COM = vol_list[1][i].lower
80 MR_radius_simple_CT_COM = vol_list[1][i].bestRadius
81 # this calculates the coordinate difference of MR.centroid relative to CT.centroid
82 warp_simple[i] = fun.sitk_coordShift(vol_list[0][i].centroid, vol_list[1][i].centroid)
83 # this calculates the norm (=absolute distance) between the centroids in each slice
84 warpMagnitude_simple[i] = fun.sitk_coordDist(warp_simple[i])
85
86
87 vol_list[0][i].getCentroid(percentLimit='auto', iterations=5, top=0.20)
88 CT_DC_iter = vol_list[0][i].dice
89 CT_DC_iter_average = vol_list[0][i].diceAverage
90 CT_lower_iter = vol_list[0][i].lower
91 CT_radius_iter = vol_list[0][i].bestRadius
92
93 vol_list[1][i].getCentroid(percentLimit='auto', iterations=6, top=0.20)
94 MR_DC_iter = vol_list[1][i].dice
95 MR_DC_iter_average = vol_list[1][i].diceAverage
96 MR_lower_iter = vol_list[1][i].lower
97 MR_radius_iter = vol_list[1][i].bestRadius
98 vol_list[1][i].getMask()
99 MR_DC_iter_CT_COM = vol_list[1][i].getDice(centroid=vol_list[0][i].centroid)
100 MR_DC_iter_CT_COM_average = vol_list[1][i].diceAverage
101 MR_lower_iter_CT_COM = vol_list[1][i].lower
102 MR_radius_iter_CT_COM = vol_list[1][i].bestRadius
103
104 # this calculates the coordinate difference of MR.centroid relative to CT.centroid
105 warp_iter[i] = fun.sitk_coordShift(vol_list[0][i].centroid, vol_list[1][i].centroid)
106 # this calculates the norm (=absolute distance) between the centroids in each slice
107 warpMagnitude_iter[i] = fun.sitk_coordDist(warp_iter[i])
108
109
110 DC_CT[i] = np.column_stack((CT_DC_simple, CT_DC_iter))
111 DC_CT_average[i] = CT_DC_simple_average, CT_DC_iter_average
112
113 DC_MR[i] = np.column_stack((MR_DC_simple, MR_DC_iter,
114                             MR_DC_simple_CT_COM, MR_DC_iter_CT_COM))
115 DC_MR_average[i] = (MR_DC_simple_average, MR_DC_iter_average,
116                     MR_DC_simple_CT_COM_average, MR_DC_iter_CT_COM_average)
117 lows_CT[i] = CT_lower_simple, CT_lower_iter
118 lows_MR[i] = MR_lower_simple, MR_lower_iter, MR_lower_simple_CT_COM, MR_lower_iter_CT_COM
119 radii_CT[i] = CT_radius_simple, CT_radius_iter
120 radii_MR[i] = MR_radius_simple, MR_radius_iter, MR_radius_simple_CT_COM,
121 MR_radius_iter_CT_COM
122
123 now = datetime.datetime.now()
124
125 COLUMNS = ('sliceNo dist warp_x warp_y warpMagnitude DC_CT DC_MR '
126            ' DC_MR_CT-COM warp_x* warp_y* warpMagnitude* DC_CT*'
127            ' DC_MR* DC_MR_CT-COM*')
128 for i in range(sets):
129     DATA = np.column_stack((sliceNumbers.astype(str),
130                             dist.astype(str),
131
132                             warp_simple[i].round(4).astype(str),
133                             warpMagnitude_simple[i].round(4).astype(str),
134                             DC_CT[i,:,0].round(4).astype(str),
135                             DC_MR[i,:,0].round(4).astype(str),
136                             DC_MR[i,:,2].round(4).astype(str),
137
138                             warp_iter[i].round(4).astype(str),
139                             warpMagnitude_iter[i].round(4).astype(str),
140                             DC_CT[i,:,1].round(4).astype(str),
141                             DC_MR[i,:,1].round(4).astype(str),
142                             DC_MR[i,:,3].round(4).astype(str)))
143     # text = np.row_stack((NAMES, DATA))

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144 head0 = ("{}_x{}\n path: {}\n thresholds:\n lower (simple): {},\n"
145 " lower (iter): {}\n upper: {}\n DC-average (simple): {} (bestRadius: {})\n"
146 " DC-average (iter): {} (bestRadius: {})\n".format(vol_list[0][i].method,
147 vol_list[0][i].resample, vol_list[0][i].path, lows_CT[i][0], lows_CT[i][1],
148 vol_list[0][i].upper, DC_CT_average[i][0], radii_CT[i][0],
149 DC_CT_average[i][1], radii_CT[i][1]))
150
151 head1 = ("{}_x{}\n path: {}\n thresholds:\n lower (simple): {},\n"
152 " lower (iter): {}\n lower (simple_CT-COM): {}\n lower (iter_CT-COM): {}\n"
153 " upper: {}\n DC-average (simple): {} (bestRadius: {})\n DC-average (iter): {}"
154 " (bestRadius: {})\n DC-average (CT-COM, simple): {} (bestRadius: {})\n"
155 " DC-average (CT-COM, iter): {} (bestRadius: {})\n".format(vol_list[1][i].method,
156 vol_list[1][i].resample, vol_list[1][i].path, lows_MR[i][0], lows_MR[i][1],
157 lows_MR[i][2], lows_MR[i][3], vol_list[1][i].upper, DC_MR_average[i][0],
158 radii_MR[i][0], DC_MR_average[i][1], radii_MR[i][1], DC_MR_average[i][2],
159 radii_MR[i][2], DC_MR_average[i][3], radii_MR[i][3]))
160
161 head = str(now) + '\n' + head0 + head1 + '\n' + COLUMNS
162 np.savetxt('./data/output_txt/phantom2_out_txt/CT-MR_x{}_{}_{}.txt'
163 .format(vol_list[0][i].resample, now.date(), now.time()), DATA,
164 delimiter=" & ", header=head, comments="# ", fmt='%3s')
165
166
167 for i in range(sets):
168
169 # creates CT.masked using CT.mask,
170 # but assigns each slice the centroid distance*1000*spacing as pixel value
171 vol_list[0][0].applyMask(replaceArray=warp_simple[i][:,0])
172 # exports 3D image as .mha file
173 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
174 "ph2_out_x{}_warpX_simple.mha".format(vol_list[0][i].resample))
175 vol_list[0][0].applyMask(replaceArray=warp_simple[i][:,1])
176 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
177 "ph2_out_x{}_warpY_simple.mha".format(vol_list[0][i].resample))
178
179 vol_list[0][0].applyMask(replaceArray=warp_iter[i][:,0])
180 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
181 "ph2_out_x{}_warpX_iter.mha".format(vol_list[0][i].resample))
182 vol_list[0][0].applyMask(replaceArray=warp_iter[i][:,1])
183 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
184 "ph2_out_x{}_warpY_iter.mha".format(vol_list[0][i].resample))
185
186 vol_list[0][0].applyMask(replaceArray=warpMagnitude_simple[i])
187 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
188 "ph2_out_x{}_warpMagnitude_simple.mha".format(vol_list[0][i].resample))
189
190 vol_list[0][0].applyMask(replaceArray=warpMagnitude_iter[i])
191 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
192 "ph2_out_x{}_warpMagnitude_iter.mha".format(vol_list[0][i].resample))
193
194 vol_list[0][0].applyMask(replaceArray=DC_MR[i,:,0])
195 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
196 "ph2_out_x{}_DC_MR_simple.mha".format(vol_list[0][i].resample))
197
198 vol_list[0][0].applyMask(replaceArray=DC_MR[i,:,2])
199 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
200 "ph2_out_x{}_DC_MR_CT-COM_simple.mha".format(vol_list[0][i].resample))
201
202
203 vol_list[0][0].applyMask(replaceArray=DC_MR[i,:,1])
204 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
205 "ph2_out_x{}_DC_MR_iter.mha".format(vol_list[0][i].resample))
206
207 vol_list[0][0].applyMask(replaceArray=DC_MR[i,:,3])
208 fun.sitk_write(vol_list[0][0].masked, "../data/output_img/ph2_out_img/mha_files",
209 "ph2_out_x{}_DC_MR_CT-COM_iter.mha".format(vol_list[0][i].resample))
210
211
212 # instead of opening the created file manually, you can use this lines in
213 # the IPython console to start 3D Slicer and open it automatically:
214 # %env SITK_SHOW_COMMAND /home/david/Downloads/Slicer-4.5.0-1-linux-amd64/Slicer
215 # sitk.Show(CT.masked)

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