



CERTIFICATE OF ACHIEVEMENT



Issued to:

Hitarth Desai

PARTICIPANT NAME

Popeyes ARM

University of Toronto, Canada

TEAM NAME

For demonstrating skills in programming, control, simulation, and perception of robotic pick-and-place and grasping applications in dynamic environments. As part of their achievements in the RoboCup Autonomous Robot Manipulation Challenge 2024.

Luca Focchi

TRUSTEE, ROBOCUP FEDERATION

Lauren Tabolinsky

ACADEMIC PROGRAMS MANAGER, MATHWORKS

Rune Sjø-Knudsen

INNOVATION RESEARCHER, UNIVERSAL ROBOTS



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