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# cycleke (菜鸡) 的 XCPC 模板

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icpc International Collegiate  
Programming Contest



# 哈爾濱工業大學

cycleke

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# 1 数学

## 1.1 素数

素数的数目有近似  $\pi(x) \sim \frac{x}{\ln(x)}$ , 判定如下:

```

1 inline ll mmul(const ll &a, const ll &b, const ll &mod) {
2     ll k = (ll)((1.0L * a * b) / (1.0L * mod)), t = a * b - k * mod;
3     for (t -= mod; t < 0; t += mod) {}
4     return t;
5 }
6 inline ll mpow(ll a, ll b, const ll &mod) {
7     ll res = 1;
8     for (; b >= 1; a = mmul(a, a, mod)) (b & 1) && (res = mmul(res, a, mod));
9     return res;
10 }
11
12 inline bool check(const ll &x, const ll &p) {
13     if (!(x % p) || mpow(p % x, x - 1, x) ^ 1) return false;
14     for (ll k = x - 1; t; ~k & 1;) {
15         if (((t = mpow(p % x, k >= 1, x)) ^ 1) && (t ^ (x - 1))) return false;
16         if (!(t ^ (x - 1))) return true;
17     }
18     return true;
19 }
20
21 inline bool Miller_Rabin(const ll &x) {
22     if (x < 2) return false;
23     static const int p[12] = {2, 3, 5, 7, 11, 13, 17, 19, 61, 2333, 4567, 24251};
24     for (int i = 0; i < 12; ++i) {
25         if (!(x ^ p[i])) return true;
26         if (!check(x, p[i])) return false;
27     }
28     return true;
29 }

```

## 1.2 Pollard Rho

```

1 mt19937_64 rnd(chrono::high_resolution_clock::now().time_since_epoch().count());
2 inline ll rand64(ll x) { return rnd() % x + 1; }
3
4 inline ll Pollard_rho(const ll &x, const int &y) {
5     ll v0 = rand64(x), v = v0, d, s = 1;
6     for (int t = 0, k = 1;;) {
7         v = (mmul(v, v, x) + y) % x, s = mmul(s, abs(v - v0), x);
8         if (!(v ^ v0) || !s) return x;
9         if (++t == k) {
10             if ((d = __gcd(s, x)) ^ 1) return d;
11             v0 = v, k <= 1;
12         }
13     }
14 }
15
16 vector<ll> factor;
17 void findfac(ll n) {
18     if (Miller_Rabin(n)) {
19         factor.push_back(n);
20         return;
21     }
22     ll p = n;
23     while (p >= n) p = Pollard_rho(p, rand64(n));
24     findfac(p), findfac(n / p);
25 }

```

### 1.3 欧拉函数

欧拉函数的性质:

- 欧拉函数是积性函数;
- $n = \sum_{d|n} \varphi(d)$ ;
- 若  $n = p^k$ , 其中  $p$  是质数, 那么  $\varphi(n) = p^k - p^{k-1}$ ;
- 若  $\gcd(a, m) = 1$ , 则  $a^{\varphi(m)} \equiv 1 \pmod{m}$ ;

$$\text{拓展欧拉定理: } a^b \equiv \begin{cases} a^{b \bmod \varphi(p)} & \gcd(a, p) = 1 \\ a^b & \gcd(a, p) \neq 1, b < \varphi(p) \quad (\bmod p) \\ a^{b \bmod \varphi(p) + \varphi(p)} & \gcd(a, p) \neq 1, b \geq \varphi(p) \end{cases}$$

```

1 int euler_phi(int n) {
2     int ans = n;
3     for (int i = 2; i * i <= n; i++)
4         if (n % i == 0) {
5             ans = ans / i * (i - 1);
6             while (n % i == 0) n /= i;
7         }
8     if (n > 1) ans = ans / n * (n - 1);
9     return ans;
10 }
```

### 1.4 线性筛

factor 为最小质因子; mu 为莫比乌斯函数; phi 为欧拉函数; e 为质因子最高次幂, d 为因数个数; f 为因数和, g 为最小质因子的幂和, 即  $p + p^1 + p^2 + \dots + p^k$ 。理论上积性函数都可以线性筛。

```

1 const int MAXN = 1e7 + 5;
2 bitset<MAXN> vis;
3 int prime[MAXN / 15], prime_cnt;
4 int factor[MAXN], e[MAXN], d[MAXN], mu[MAXN], phi[MAXN];
5 void sieve() {
6     factor[1] = 1, e[1] = 0, d[1] = 1, mu[1] = 1, phi[1] = 1;
7     for (int i = 2; i < MAXN; ++i) {
8         if (!vis[i]) {
9             prime[prime_cnt++] = i;
10            factor[i] = i;
11            mu[i] = -1, phi[i] = i - 1;
12            e[i] = 1, d[i] = 2;
13            g[i] = f[i] = i + 1;
14        }
15        for (int j = 0, t; j < prime_cnt && (t = i * prime[j]) < MAXN; ++j) {
16            vis[t] = 1;
17            factor[t] = prime[j];
18            if (i % prime[j] == 0) {
19                mu[t] = 0, phi[t] = phi[i] * prime[j];
20                e[t] = e[i] + 1, d[t] = d[i] / e[t] * (e[t] + 1);
21                g[t] = g[i] * prime[j] + 1, f[t] = f[i] / g[i] * g[t];
22                break;
23            } else {
24                mu[t] = -mu[i], phi[t] = phi[i] * (prime[j] - 1);
25                e[t] = 1, d[t] = d[i] * 2;
26                g[t] = 1 + prime[j], f[t] = f[i] * f[prime[j]];
27            }
28        }
29    }
30 }
```

## 1.5 拓展欧几里得算法

```

1 int exgcd(int a, int b, int &x, int &y) {
2     if (b == 0) return x = 1, y = 0, a;
3     int g = exgcd(b, a % b, y, x);
4     y -= a / b * x;
5     return g;
6 }
    
```

## 1.6 莫比乌斯反演

常见积性函数 ( $f(ab) = f(a)f(b), (a, b) = 1$ ):

- 单位函数:  $\epsilon(n) = [n = 1]$  (完全积性)
- 恒等函数:  $\text{id}_k(n) = n^k$ ,  $\text{id}_1(n)$  通常简记作  $\text{id}(n)$  (完全积性)。
- 常数函数:  $1(n) = 1$  (完全积性)
- 除数函数:  $\sigma_k(n) = \sum_{d|n} d^k$ ,  $\sigma_0(n)$  通常简记作  $d(n)$  或  $\tau(n)$ ,  $\sigma_1(n)$  通常简记作  $\sigma(n)$ 。
- 欧拉函数:  $\varphi(n) = \sum_{i=1}^n [\text{gcd}(i, n) = 1]$
- 莫比乌斯函数:  $\mu(n) = \begin{cases} 1 & n = 1 \\ 0 & \exists d > 1, d^2 | n, \text{ 其中 } \omega(n) \text{ 表示 } n \text{ 的本质不同质因子个数, 它是一个加性函数 } (\omega(ab) = \omega(a) + \omega(b))。 \\ (-1)^{\omega(n)} & \text{otherwise} \end{cases}$

Dirichlet 卷积满足交换率、结合率和分配率, 常见 Dirichlet 卷积:

- $\varepsilon = \mu * 1$
- $d = 1 * 1$
- $\sigma = \text{id} * 1$
- $\varphi = \text{id} * \mu$
- $\text{id} = \varphi * 1$
- $\text{id}^2 = (\text{id} \cdot \varphi) * \text{id}$
- $f \cdot d = f * f$  ( $f$  为完全积性)

莫比乌斯反演:  $f = g * 1 \iff g = \mu * f$ 。

拓展: 对于数论函数  $f, g$  和完全积性函数  $t$  且  $t(1) = 1$ :

$$f(n) = \sum_{i=1}^n t(i)g\left(\left\lfloor \frac{n}{i} \right\rfloor\right) \iff g(n) = \sum_{i=1}^n \mu(i)t(i)f\left(\left\lfloor \frac{n}{i} \right\rfloor\right)$$

常用结论:

- $\sum_{i=x}^n \sum_{j=y}^m [\text{gcd}(i, j) = k] = \sum_{d=1}^{\lfloor \frac{n}{k} \rfloor} \mu(d) \lfloor \frac{n}{kd} \rfloor \lfloor \frac{m}{kd} \rfloor$
- $d(ij) = \sum_{x|i} \sum_{y|j} [\text{gcd}(x, y) = 1] = \sum_{p|i, p|j} \mu(p) d\left(\frac{i}{p}\right) d\left(\frac{j}{p}\right)$

## 1.7 杜教筛

设  $S(n) = \sum_{i=1}^n f(i)$ , 则  $\sum_{i=1}^n (f * g)(i) = \sum_{i=1}^n g(i)S(\lfloor \frac{n}{i} \rfloor) \Rightarrow g(1)S(n) = \sum_{i=1}^n (f * g)(i) - \sum_{i=2}^n g(i)S(\lfloor \frac{n}{i} \rfloor)$ 。  
直接分块复杂度  $O(n^{\frac{3}{4}})$ , 预处理出前  $O(n^{\frac{2}{3}})$  项复杂度为  $O(n^{\frac{2}{3}})$ 。常用结论:

- 莫比乌斯函数前缀和:  $S(n) = \sum_{i=1}^n \epsilon(i) - \sum_{i=2}^n S(\lfloor \frac{n}{i} \rfloor)$
- 欧拉函数前缀和:  $S(n) = \sum_{i=1}^n \text{id}(i) - \sum_{i=2}^n S(\lfloor \frac{n}{i} \rfloor)$

```

1 map<int, int> mp_mu;
2
3 int S_mu(int n) {
4     if (n < MAXN) return sum_mu[n];
5     if (mp_mu[n]) return mp_mu[n];
6     int ret = 1;
7     for (int i = 2, j; i <= n; i = j + 1) {
8         j = n / (n / i);
9         ret -= S_mu(n / i) * (j - i + 1);
10    }
11    return mp_mu[n] = ret;
12 }
13
14 // 使用莫比乌斯反演
15 ll S_phi(int n) {
16     ll res = 0;
17     for (int i = 1, j; i <= n; i = j + 1) {
18         j = n / (n / i);
19         res += 1LL * (S_mu(j) - S_mu(i - 1)) * (n / i) * (n / i);
20     }
21     return (res - 1) / 2 + 1;
22 }

```

## 1.8 类欧几里德算法

$$\text{求 } f = \sum_{i=0}^n \lfloor \frac{ai+b}{c} \rfloor, g = \sum_{i=0}^n i \lfloor \frac{ai+b}{c} \rfloor, h = \sum_{i=0}^n \lfloor \frac{ai+b}{c} \rfloor^2$$

```

1 const ll P = 998244353;
2 ll i2 = 499122177, i6 = 166374059;
3 struct data {
4     data() { f = g = h = 0; }
5     ll f, g, h;
6 }; // 三个函数打包
7 data calc(ll n, ll a, ll b, ll c) {
8     ll ac = a / c, bc = b / c, m = (a * n + b) / c, n1 = n + 1, n21 = n * 2 + 1;
9     data d;
10    if (a == 0) { // 迭代到底层
11        d.f = bc * n1 % P;
12        d.g = bc * n % P * n1 % P * i2 % P;
13        d.h = bc * bc % P * n1 % P;
14        return d;
15    }
16    if (a >= c || b >= c) { // 取模
17        d.f = n * n1 % P * i2 % P * ac % P + bc * n1 % P;
18        d.g = ac * n % P * n1 % P * n21 % P * i6 % P + bc * n % P * n1 % P * i2 % P;
19        d.h = ac * ac % P * n % P * n1 % P * n21 % P * i6 % P +
20            bc * bc % P * n1 % P + ac * bc % P * n % P * n1 % P;
21        d.f %= P, d.g %= P, d.h %= P;
22    }
23    data e = calc(n, a % c, b % c, c); // 迭代
24
25    d.h += e.h + 2 * bc % P * e.f % P + 2 * ac % P * e.g % P;
26    d.g += e.g, d.f += e.f;
27    d.f %= P, d.g %= P, d.h %= P;
28    return d;
29 }
30 data e = calc(m - 1, c, c - b - 1, a);
31 d.f = n * m % P - e.f, d.f = (d.f % P + P) % P;
32 d.g = m * n % P * n1 % P - e.h - e.f, d.g = (d.g * i2 % P + P) % P;
33 d.h = n * m % P * (m + 1) % P - 2 * e.g - 2 * e.f - d.f;
34 d.h = (d.h % P + P) % P;
35 return d;
36 }

```

## 1.9 中国剩余定理

```

1 ll inv(ll a, ll p) {
2     ll x, y;
3     exgcd(a, p, x, y);
4     return (x + p) % p;
5 }
6 ll CRT(ll n, ll *a, ll *m) {
7     ll lcm = 1, res = 0;
8     for (ll i = 0; i < n; ++i) lcm *= m[i];
9     for (ll i = 0; i < n; ++i) {
10         ll t = lcm / m[i], x = inv(t, m[i]);
11         res = (res + a[i] * t % lcm * x) % lcm;
12     }
13     return res;
14 }

```

模数不互质的情况  $\begin{cases} x \equiv a_1 \pmod{m_1} \\ x \equiv a_2 \pmod{m_2} \end{cases}$ , 则转换为  $m_1p - m_2q = a_2 - a_1$ , 最终解 (若有解) 为  $x \equiv m_1p + a_1 \pmod{\text{lcm}(m_1, m_2)}$ 。

## 1.10 原根

- 阶: 若  $(a, m) = 1$ , 使  $a^l \equiv 1 \pmod{m}$  成立的最小的  $l$ , 称为  $a$  关于模  $m$  的阶, 记为  $\text{ord}_m a$ 。
- 原根: 若  $(g, m) = 1, \text{ord}_m g = \varphi(m)$ , 则称  $g$  为  $m$  的一个原根。若  $m$  有原根, 则  $m$  一定是下列形式:  $\{2, 4, p^a, 2p^a\}$  (这里  $p$  为奇素数,  $a$  为正整数)。
- 求原根: 设  $p_1, p_2, \dots, p_k$  是  $\varphi(m)$  的所有不同的素因数, 则  $g$  是  $m$  的原根  $\iff \forall 1 \leq i \leq k$ , 有  $g^{\frac{\varphi(m)}{p_i}} \not\equiv 1 \pmod{m}$ , 集合  $S = \{g^s \mid 1 \leq s \leq \varphi(m), (s, \varphi(m)) = 1\}$  给出  $m$  的全部原根。

## 1.11 BSGS

大步小步算法用来求离散对数  $x^k \equiv a \pmod{p}$ 。求解  $a^x \equiv b \pmod{p}$  则, 令  $x = A\lceil\sqrt{p}\rceil - B, 0 \leq A, B \leq \lceil\sqrt{p}\rceil$ , 有  $a^{A\lceil\sqrt{p}\rceil} \equiv ba^B \pmod{p}$ , 先枚举  $A$  之后在哈希表中查找  $B$  就行。

```

1 // Finds the primitive root modulo p
2 int generator(int p) {
3     vector<int> fact;
4     int phi = p - 1, n = phi;
5     for (int i = 2; i * i <= n; ++i) {
6         if (n % i == 0) {
7             fact.push_back(i);
8             while (n % i == 0) n /= i;
9         }
10    }
11    if (n > 1) fact.push_back(n);
12    for (int res = 2; res <= p; ++res) {
13        bool ok = true;
14        for (int factor : fact)
15            if (mpow(res, phi / factor, p) == 1) {
16                ok = false;
17                break;
18            }
19        if (ok) return res;
20    }
21    return -1;
22 }
23 vector<int> BSGS(int n, int k, int a) {
24     if (a == 0) return vector<int>({0});
25
26     int g = generator(n);
27     // Baby-step giant-step discrete logarithm algorithm

```

```

28 int sq = (int)sqrt(n + .0) + 1;
29 vector<pair<int, int>> dec(sq);
30 for (int i = 1; i <= sq; ++i)
31     dec[i - 1] = {mpow(g, i * sq * k % (n - 1), n), i};
32
33 sort(dec.begin(), dec.end());
34 int any_ans = -1;
35 for (int i = 0; i < sq; ++i) {
36     int my = mpow(g, i * k % (n - 1), n) * a % n;
37     auto it = lower_bound(dec.begin(), dec.end(), make_pair(my, 0));
38     if (it != dec.end() && it->first == my) {
39         any_ans = it->second * sq - i;
40         break;
41     }
42 }
43 if (any_ans == -1) return vector<int>();
44 // Print all possible answers
45 int delta = (n - 1) / __gcd(k, n - 1);
46 vector<int> ans;
47 for (int cur = any_ans % delta; cur < n - 1; cur += delta)
48     ans.push_back(mpow(g, cur, n));
49 sort(ans.begin(), ans.end());
50 return ans;
51 }

```

## 1.12 自适应 Simpson

计算  $\int_a^b f(x)dx$ 。

```

1 double simpson(double a, double b) {
2     double c = a + (b - a) / 2;
3     return (f(a) + 4 * f(c) + f(b)) * (b - a) / 6;
4 }
5 double integral(double a, double b, double eps, double A) {
6     double c = a + (b - a) / 2;
7     double L = simpson(a, c), R = simpson(c, b);
8     if (fabs(L + R - A) <= 15 * eps) return L + R + (L + R - A) / 15;
9     return integral(a, c, eps / 2, L) + integral(c, b, eps / 2, R);
10 }
11 double integral(double a, double b, double eps) {
12     return integral(a, b, eps, simpson(a, b));
13 }

```

## 1.13 卢卡斯定理

卢卡斯定理:  $\binom{n}{m} \bmod p = \binom{\lfloor n/p \rfloor}{\lfloor m/p \rfloor} \cdot \binom{n \bmod p}{m \bmod p} \bmod p$

```

1 ll lucas(ll n, ll m, int p) {
2     ll ret = 1;
3     while (n && m) {
4         ll nn = n % p, mm = m % p;
5         if (nn < mm) return 0;
6         ret = ret * fac[nn] % p * inv_fac[mm] % p * inv_fac[nn - mm] % p;
7         n /= p, m /= p;
8     }
9     return ret;
10 }

```

拓展卢卡斯定理: 用于处理  $p$  不是质数的情况。

对于  $C_n^m \bmod p$ , 我们将其转化为  $r$  个形如  $a_i \equiv C_n^m \pmod{q_i^{\alpha_i}}$  的同余方程并分别求解; 对于  $a_i \equiv C_n^m \pmod{q_i^{\alpha_i}}$ , 将  $C_n^m$  转化为  $\frac{n!}{m! (n-m)!} q^{x-y-z}$ , 可求逆元; 对于  $\frac{m!}{q^y}$  和  $\frac{(n-m)!}{q^z}$ , 将其变换整理, 可递归求解。

```

1 ll calc(ll n, ll x, ll p) {
2     if (!n) return 1;

```



```

3  ll s = 1;
4  for (ll i = 1; i <= p; ++i) (i % x) && (s = s * i % p);
5  s = mpow(s, n / p, p);
6  for (ll i = n / p * p; i <= n; ++i) (i % x) && (s = s * (i % p) % p);
7  return s * calc(n / x, x, p) % p;
8  }
9
10 ll multi_lucas(ll n, ll m, ll x, ll p) {
11     ll cnt = 0;
12     for (ll i = n; i; i /= x) cnt += i / x;
13     for (ll i = m; i; i /= x) cnt -= i / x;
14     for (ll i = n - m; i; i /= x) cnt -= i / x;
15     return mpow(x, cnt, p) * calc(n, x, p) % p * inv(calc(m, x, p), p) % p *
16         inv(calc(n - m, x, p), p) % p;
17 }
18
19 ll exlucas(ll n, ll m, ll P) {
20     ll cnt = 0;
21     static ll p[20], a[20];
22     for (ll i = 2; i * i <= P; ++i) {
23         if (P % i) continue;
24         p[cnt] = i;
25         while (P % i == 0) p[cnt] *= i, P /= i;
26         a[cnt] = multi_lucas(n, m, i, p[cnt]);
27         ++cnt;
28     }
29     if (P > 1) p[cnt] = P, a[cnt] = multi_lucas(n, m, P, P), ++cnt;
30     return CRT(cnt, a, p);
31 }

```