



# CPL Theory Aircraft Systems (CSYA)

## CSYA 12 – Flight Instruments



## 1. Document Identification

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## 2. Amendment Record

Amendments made to this document since the previous version are listed below. All amendments to this document have been made in accordance with CAE OAA document management procedures.

Original Author		Date of Publication (DD/MM/YY)	
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	Typos, spelling & grammar revisions to slides 4	James Costa	01/07/2020

## 3. Disclaimer

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# TYPES OF INSTRUMENTS

## Types of Instruments

### Engine Instruments:

- Oil Temperature & Pressure Gauges
- Fuel Quantity & Pressure Gauges
- CHT & EGT Gauges
- Tachometer
- Manifold Pressure Gauge (for aircraft with MPPC)

### Navigation Instruments:

- Magnetic Compass
- Clock
- Radio Navigation Aid Instruments e.g. NDB, VOR

### Flight Instruments:

- Pressure Instruments
  - Airspeed Indicator, Altimeter, Vertical Speed Indicator
- Gyroscopic Instruments
  - Attitude Indicator, Directional Indicator, Turn Coordinator

## Types of Instruments

### Pressure Flight Instruments:

- Airspeed Indicator (ASI)
  - Altimeter
  - Vertical Speed Indicator
- Powered by the Pitot-Static System**

### Gyroscopic Flight Instruments:

- Attitude Indicator (or Artificial Horizon)
  - Directional Indicator (or Directional Gyro)
  - Turn Coordinator
- Powered by the Vacuum System**
- Powered electrically**

# MAGNETIC COMPASS

# Magnetic Compass

## How it Works:

- Also known as the direct-indicating compass, it is powered by the Earth's local magnetic field and aligns with the magnetic poles
- Your magnetic heading can be read from the compass card under the lubber line on the face of the instrument





# Magnetic Compass

## How it Works:

- You may notice that your compass is filled with a clear liquid
- This is an alcohol and helps to decrease friction and compass oscillations, making it more accurate and easier to read in flight
- This is known as a “wet compass”





# Magnetic Compass

## Deviation Error and Compass Correction Card:

- The metal structure of the aircraft, rotating parts of the engine and aircraft radios all generate their own magnetic fields
- The effect of all of these fields on the compass' ability to align with the earth's magnetic field an error known as Magnetic Deviation
- To overcome this error, a Compass Correction Card is fitted
- Note that this will not overcome the effect of you placing magnetic objects such as headsets, pens, clipboards etc. near the compass

FOR (MAGNETIC).....	N	30	60	E	120	150
STEER (COMPASS).....	0	28	57	86	117	148
FOR (MAGNETIC).....	S	210	240	W	300	330
STEER (COMPASS).....	180	212	243	274	303	332

## Magnetic Compass

### Acceleration Error:

- In the southern hemisphere, compass acceleration error can be summarised by the “SAND” mnemonic:

**“South – Accelerate”**

When accelerating east OR west, the compass will show an apparent turn to the south

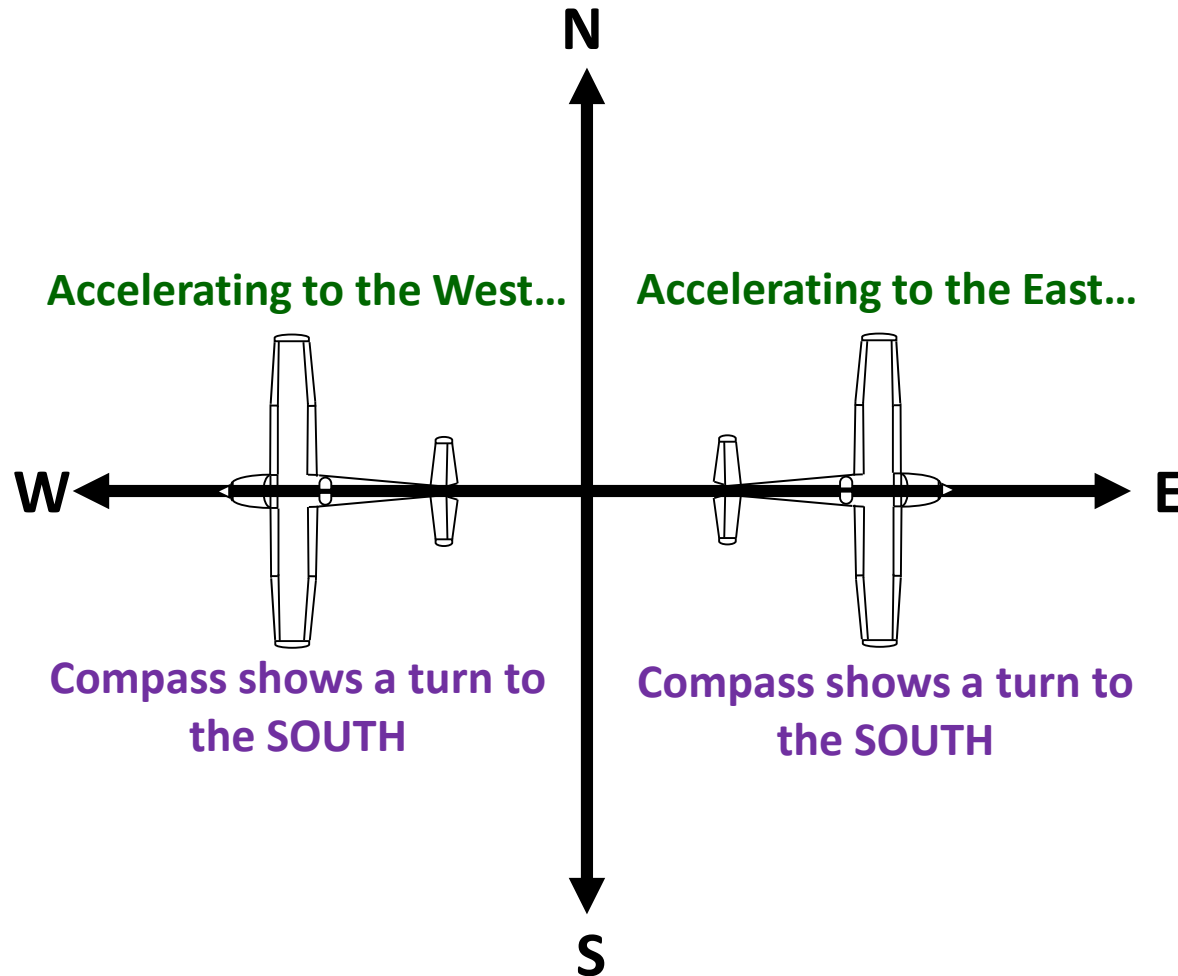
**“North – Decelerate”**

When decelerating east OR west, the compass will show an apparent turn to the north

# Magnetic Compass

Acceleration Error:

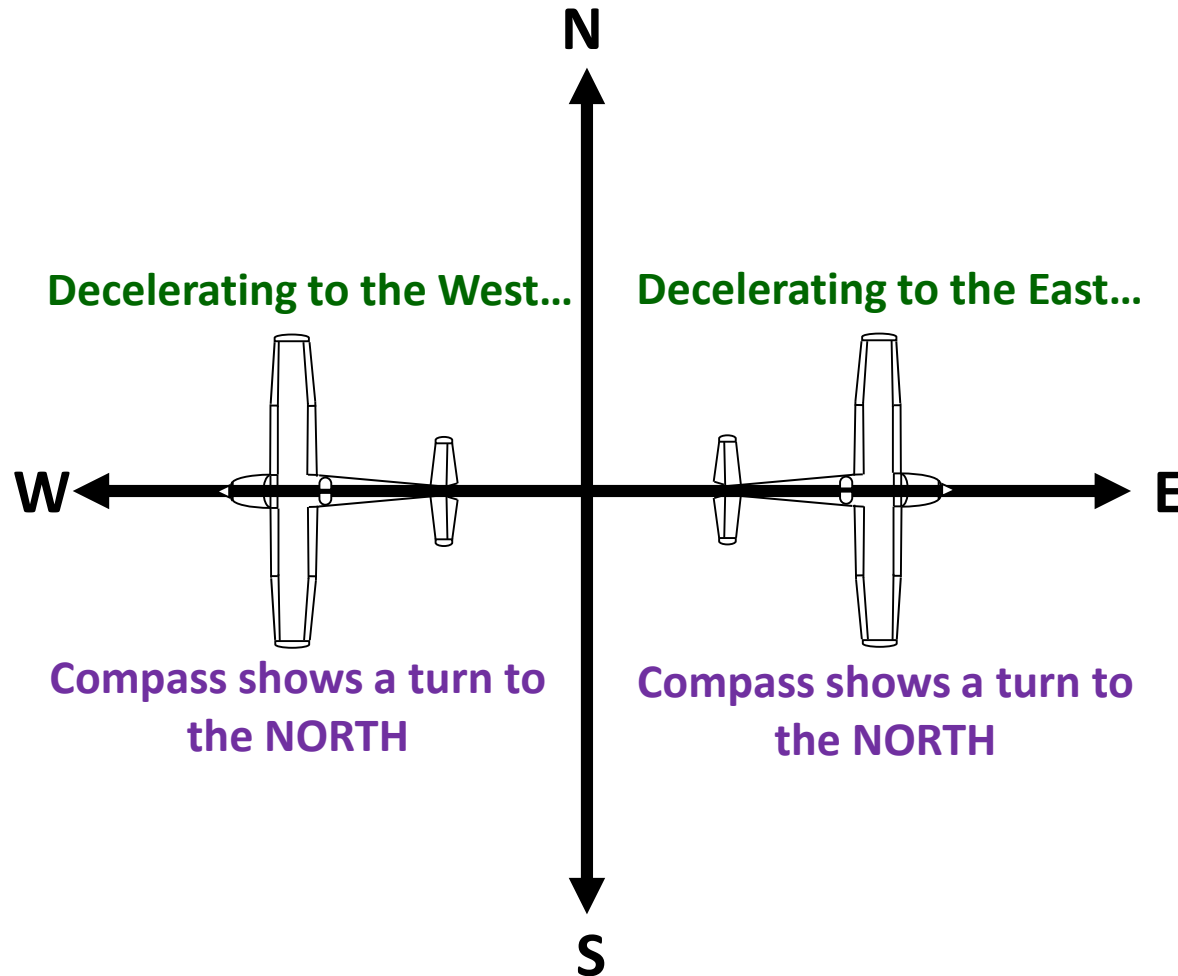
"SAND"



# Magnetic Compass

Acceleration Error:

“SAND”



# Magnetic Compass

## Turning Error:

- In the southern hemisphere, the compass rotates too fast as a turn through north is made and too slow as a turn through south is made:
- In other words, the compass is:

**“Nippy on North”**

**“Sluggish on South”**

- To overcome this, the pilot should ‘ONUS’:

**“Overshoot North”**

**“Undershoot South”**

- The over/undershoot should be about  $10^\circ$  per  $30^\circ$  of turn

## Magnetic Compass

Turning Error:

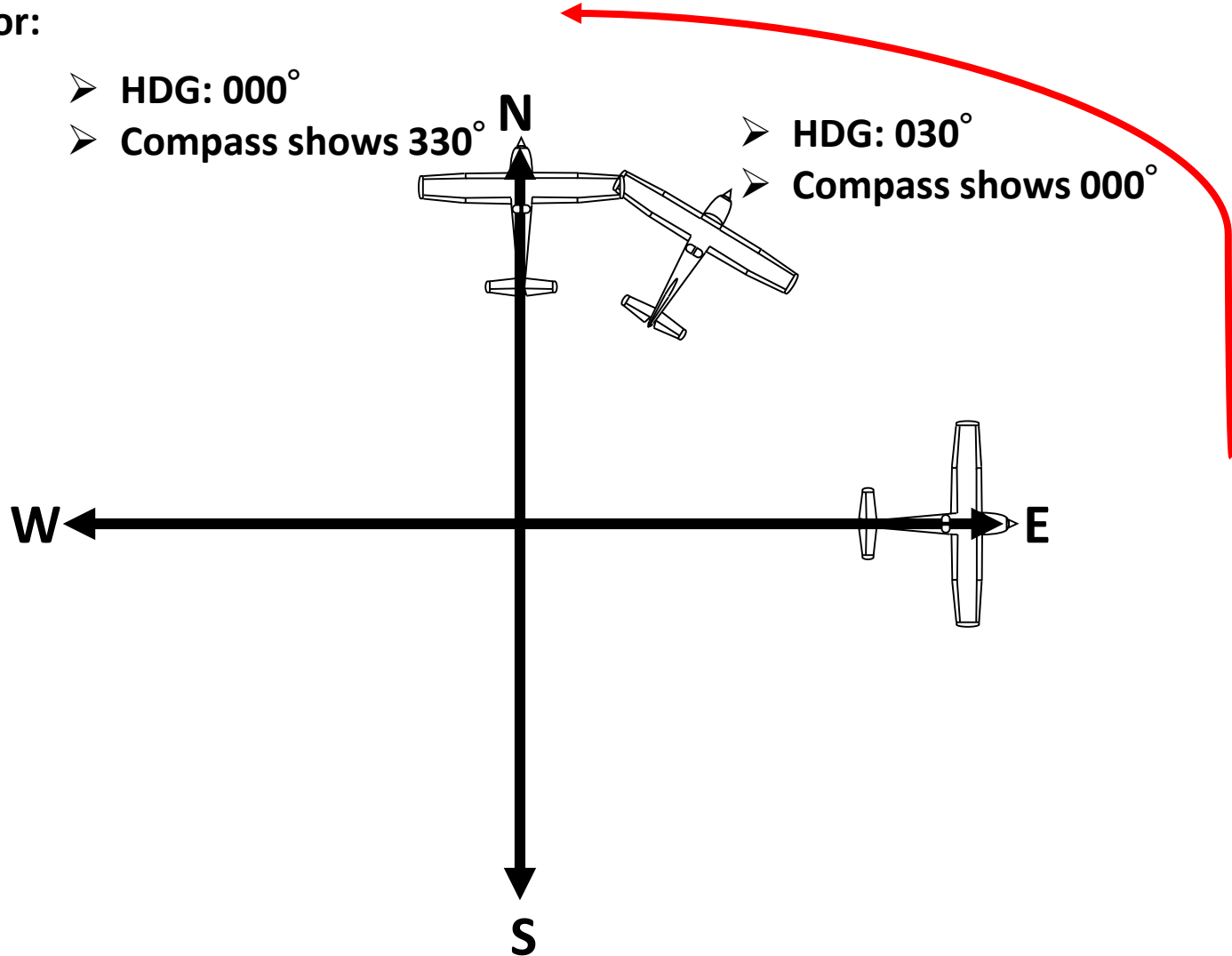
"ONUS"

➤ HDG: 000°

➤ Compass shows 330°

➤ HDG: 030°

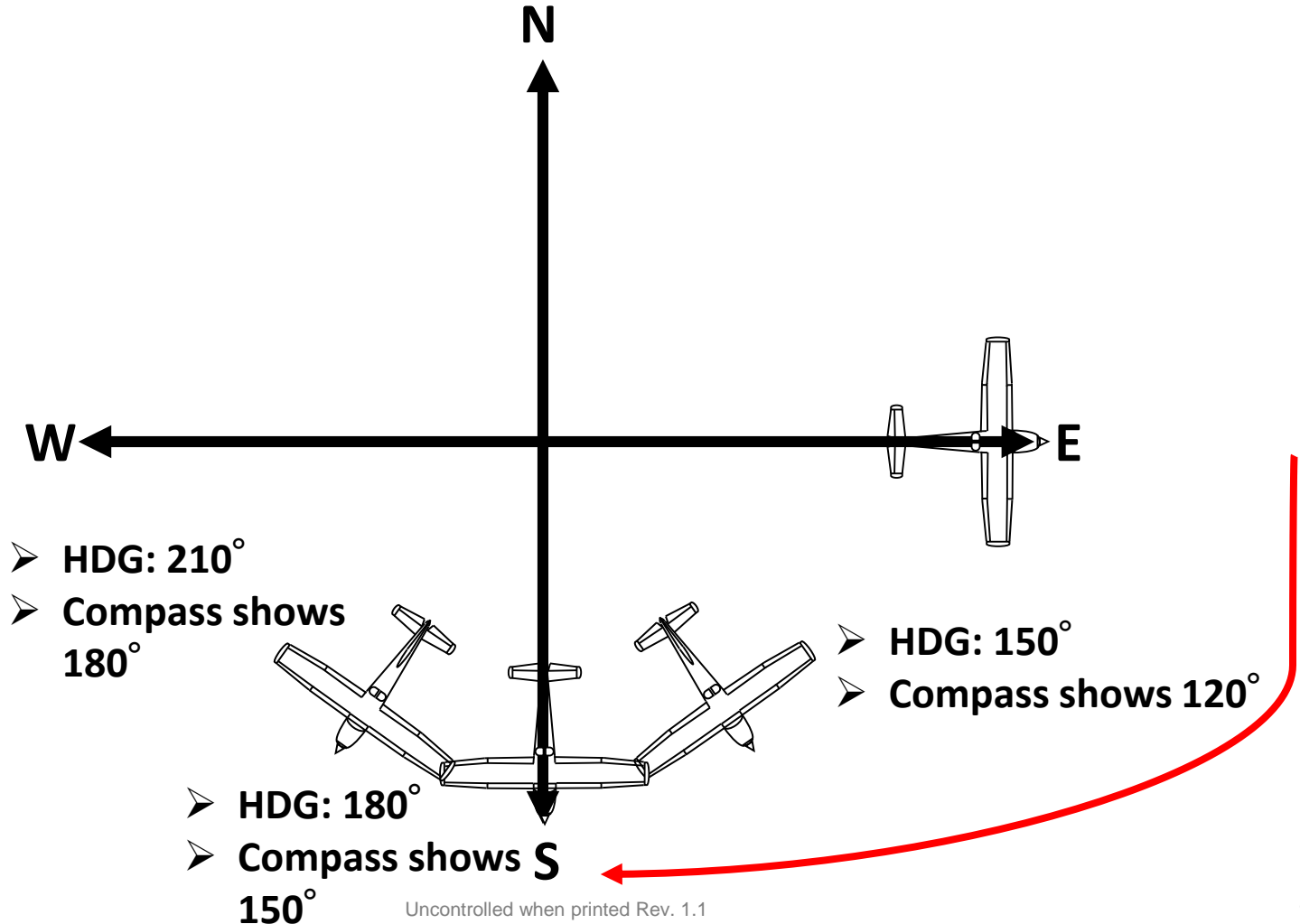
➤ Compass shows 000°



# Magnetic Compass

Turning Error:

"ONUS"

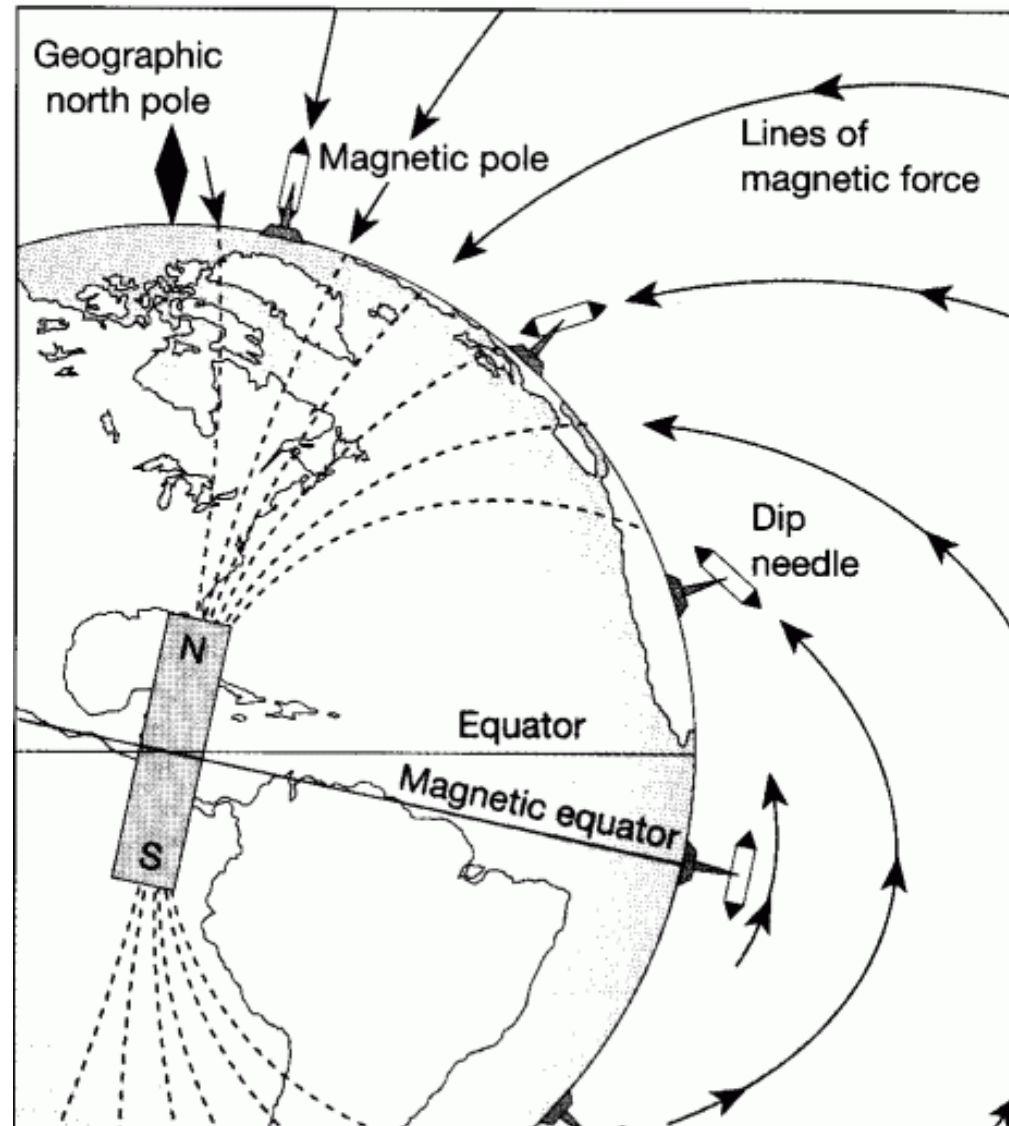




# Magnetic Compass

## Magnetic Dip:

- The magnet inside the compass will want to align itself with the magnetic field lines
- In the southern hemisphere, the north end of the compass needle will point slightly upwards
- This causes errors during banked turns and airspeed changes



# Magnetic Compass

## Determining Serviceability:

- Your compass should indicate within  $10^{\circ}$  to be serviceable
- This can be tested by aligning the aircraft with a feature of known magnetic direction e.g. a runway
- Every so often, a 'compass swing' is carried out as part of the maintenance schedule to ensure it is within limits
- Serviceability of the compass is also checked during taxi

**“Turning left, Balance Ball skidding right, AI is erect and wings level, DG is decreasing, Compass is following”**

# PRESSURE INSTRUMENTS

## Pressure Instruments



**ASI**



**ALT**



**VSI**

## Airspeed Indicator (ASI)

### System:

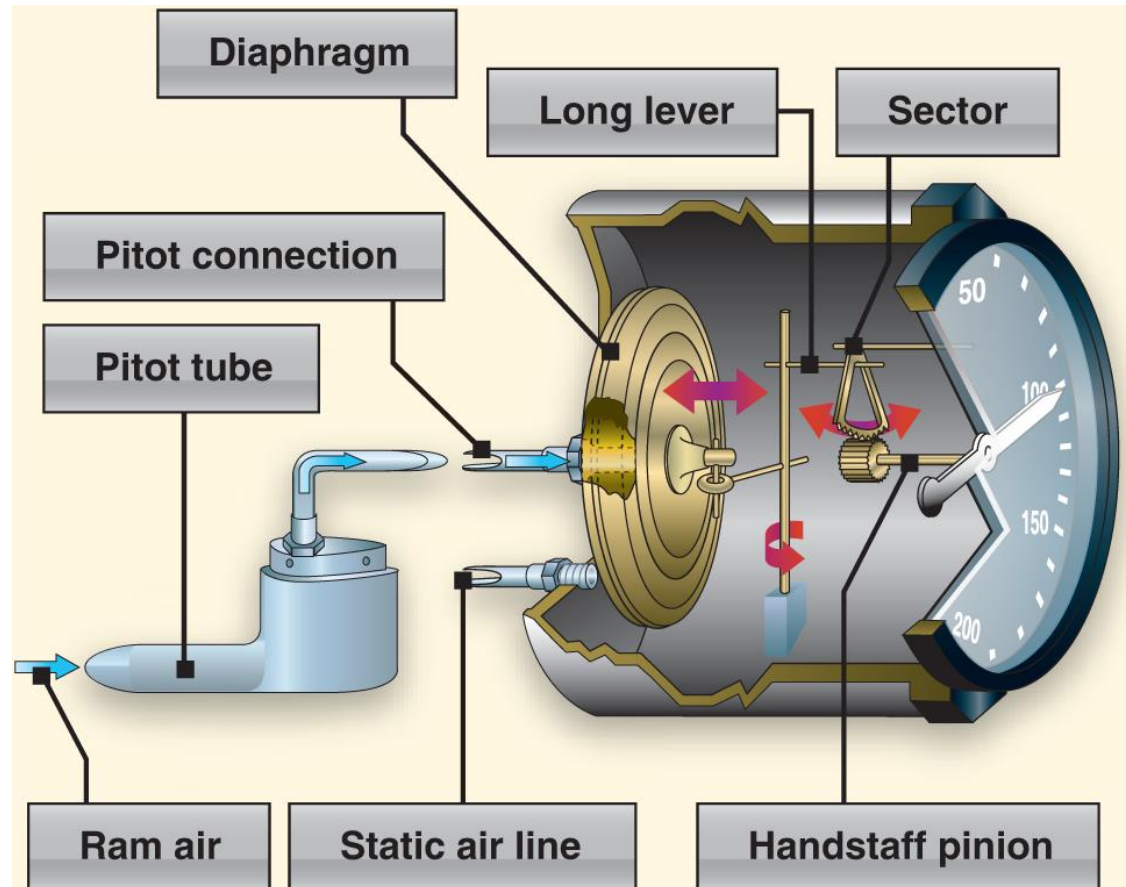
- Pitot-Static System

### Powered By:

- Pitot Tube & Static Ports

### How it Works:

- ASI measures the aircraft's dynamic pressure, calibrated in knots
- The instrument compares total pressure supplied by the pitot tube with the static pressure from the static ports



$$(P_{\text{dynamic}} = P_{\text{total}} - P_{\text{static}})$$

## Airspeed Indicator (ASI)

### Associated Errors:

1. Instrument Error and Position Error
2. At altitude, IAS will be less than TAS
3. Windshear (increase in headwind) → IAS increases then returns to normal
4. Windshear (increase in tailwind) → IAS decreases then returns to normal
5. Blockage of the pitot tube or static port e.g. due icing

- Remember **PUDSUC!**

## **Airspeed Indicator (ASI)**

**If the pitot Tube becomes blocked, the ASI will under-read during a descent**



## **Airspeed Indicator (ASI)**

**If the static Port becomes blocked, the ASI will under-read during a climb**

# Airspeed Indicator (ASI)

## Associated Errors:

1. Instrument Error and Position Error
2. At altitude, IAS will be less than TAS
3. Windshear (increase in headwind) → IAS increases then returns to normal
4. Windshear (increase in tailwind) → IAS decreases then returns to normal
5. Blockage of the pitot tube or static port e.g. due to icing
  - Remember **PUDSUC!**

## Pilot Actions to Rectify Errors:

- If the pitot tube is blocked due to ice → select pitot heat
- If the static port is blocked due to ice → select alternate static
- If alternate static is selected, air will be drawn from inside the cabin. Because this air is at a slightly lower air pressure than that outside, the ASI will **over read** slightly

## Altimeter

### System:

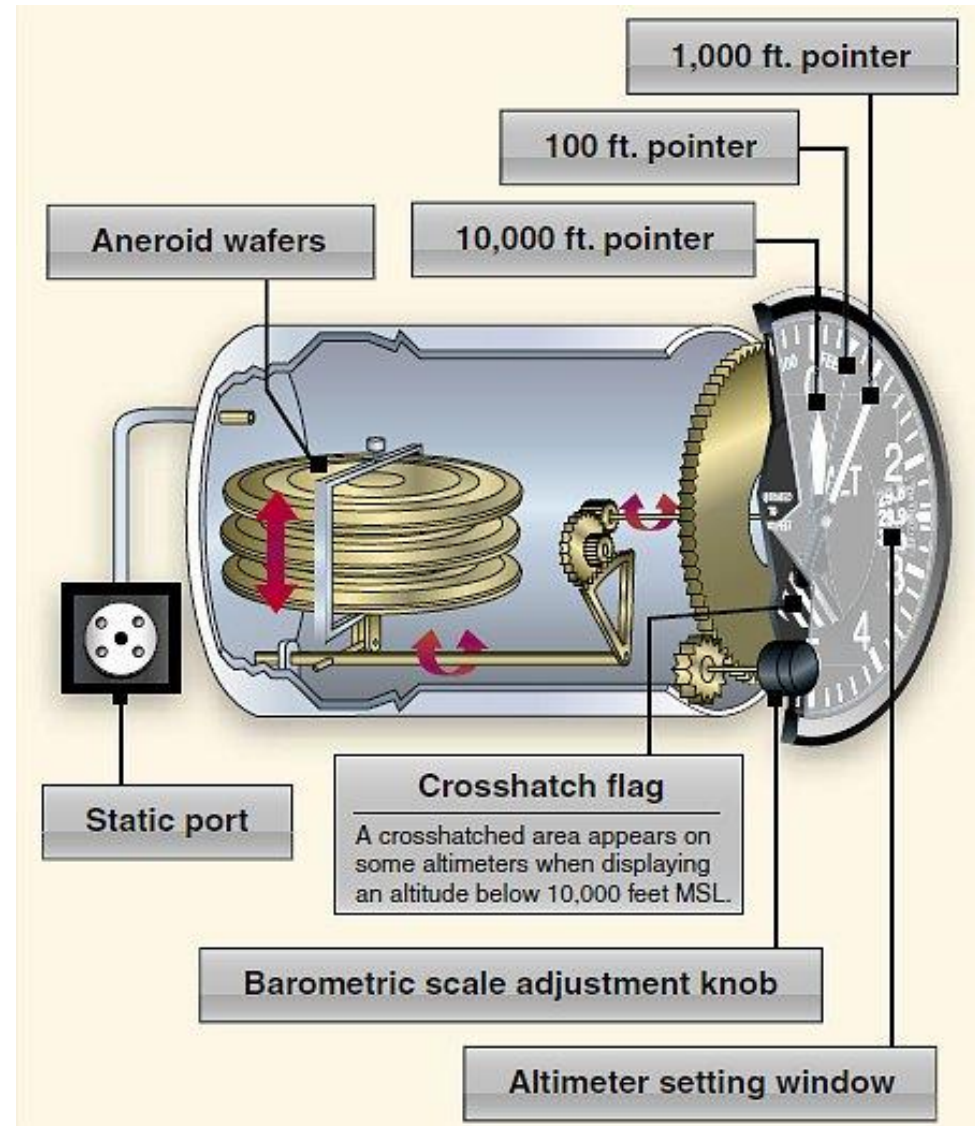
- Pitot-Static System

### Powered By:

- Static Ports only

### How it Works:

- Contains a sealed, flexible capsule called an aneroid that contains air
- As you climb, the static pressure surrounding the aneroid decreases, so the aneroid expands
- The aneroid is connected via a mechanical linkage to the needle of the altimeter, which moves as the aneroid expands and contracts



## Altimeter

### Associated Errors:

1. Instrument Lag, Instrument Error and Position Error
2. Pilot setting the wrong QNH on the subscale
  - Remember: Wind on QNH → Wind on Height
3. Blockage of the static port → Altimeter will remain fixed on the altitude at which the port became blocked

### Pilot Actions to Rectify Errors:

- Set and cross-check your QNH to ensure correct setting
- If the static port is blocked due to ice → select alternate static
- If alternate static is selected, the altimeter will over read slightly

## Vertical Speed Indicator (VSI)

### System:

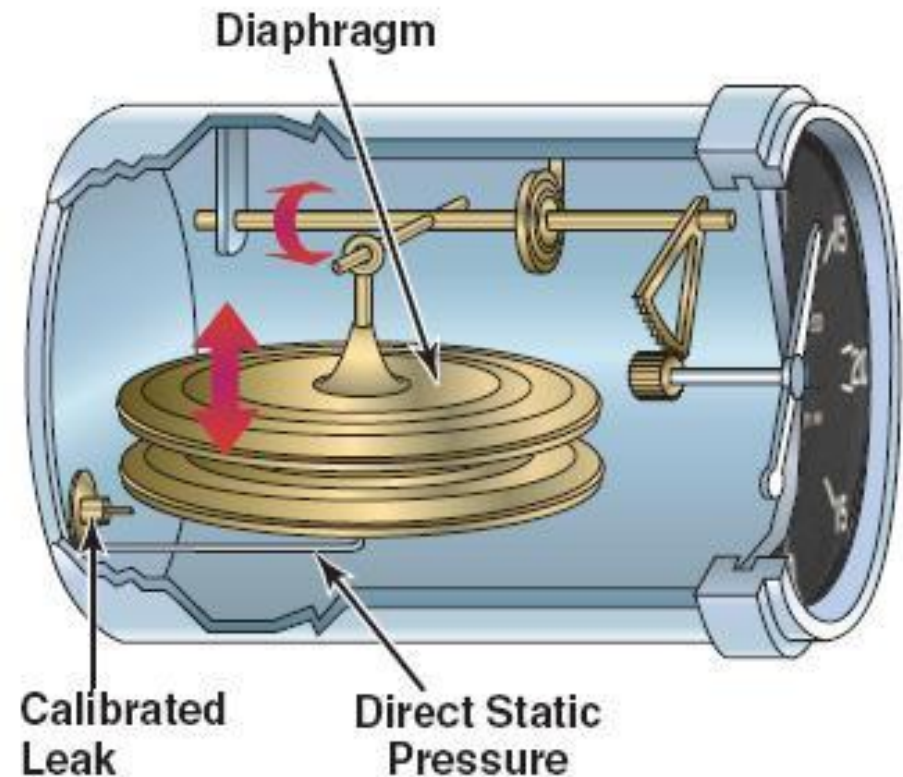
- Pitot-Static System

### Powered By:

- Static Ports only

### How it Works:

- Measures a rate of change of static pressure and converts this to a rate of change of altitude
- Static pressure is introduced into a diaphragm and also a surrounding chamber (but with slight delay)
- The time taken for the chamber pressure to “catch up” to the diaphragm is converted to a RoC/RoD



# Vertical Speed Indicator (VSI)

## Associated Errors:

1. Instrument Lag, Instrument Error and Position Error
2. Blockage of the static port → Vertical Speed Indicator will read 0

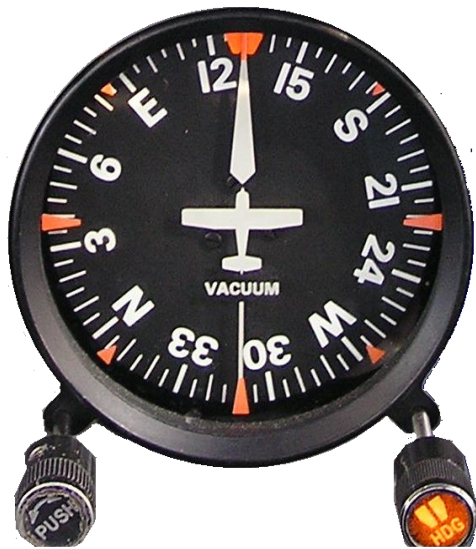
## Pilot Actions to Rectify Errors:

- If the static port is blocked due to ice → select alternate static
- Although alternate static uses the slightly lower-than-ambient cabin pressure, the VSI merely measures a **rate of change of static pressure**, and thus will not be subject to any error

# **GYROSCOPIC INSTRUMENTS**



## Gyroscopic Instruments



DG



AH



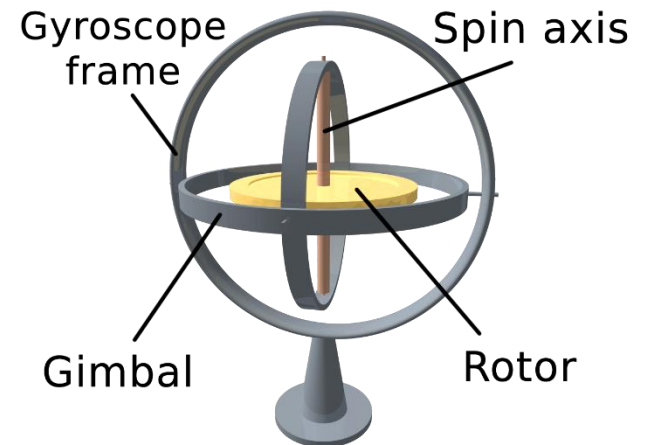
TC

## Gyroscopic Instruments

- A gyroscope is a spinning wheel mounted so that its axes can turn freely in one or more directions
- There are two important properties of gyroscopes:

### 1. Rigidity in Space

### 2. Precession



- **Rigidity:** A gyroscope is capable of maintaining the same absolute direction in space despite what goes on around it e.g. the AH remains fixed and the aircraft moves around it
- **Precession:** If a force is applied, the change of direction brought about by the force will be displayed  $90^\circ$  further in the direction of rotation. This is the cause of several errors in the gyros

## Attitude Indicator/Artificial Horizon

### System:

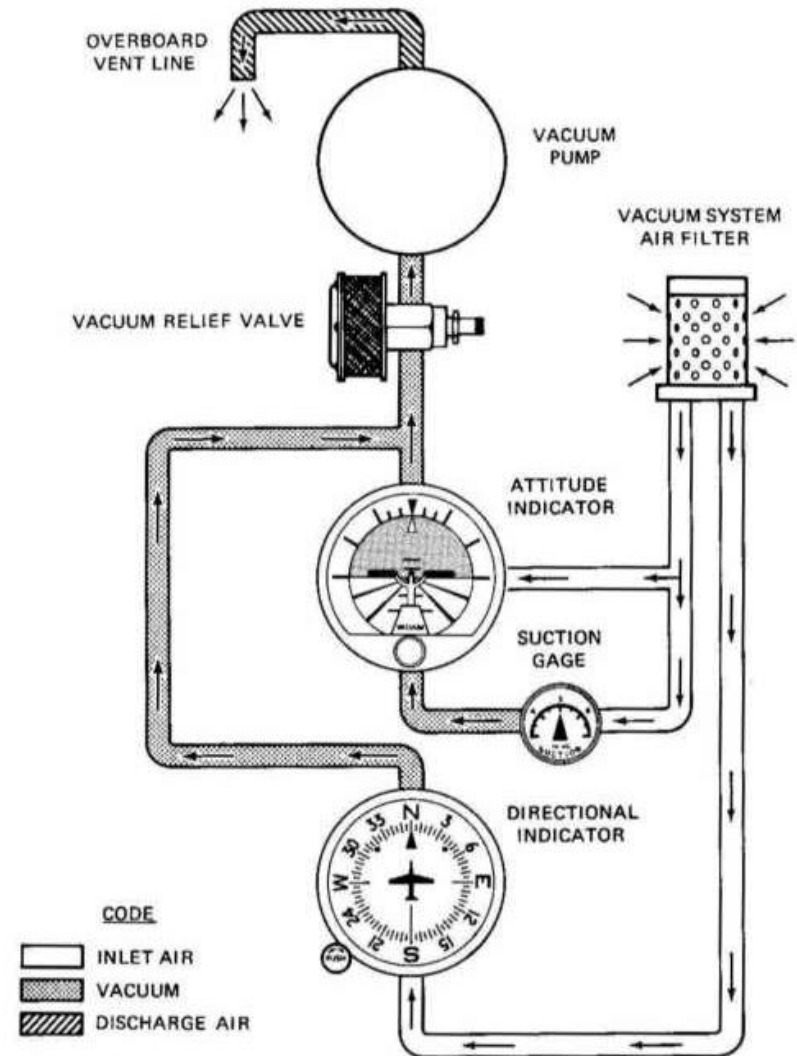
- Vacuum

### Powered By:

- Vacuum Pump (engine-driven)

### How it Works:

- Air is sucked through a filter and delivered onto the buckets of the gyro, causing it to spin in excess of 20,000 RPM
- This causes the gyro to become rigid in space
- The AH gyro is mounted to two gimbals, allowing it to indicate pitch and bank information



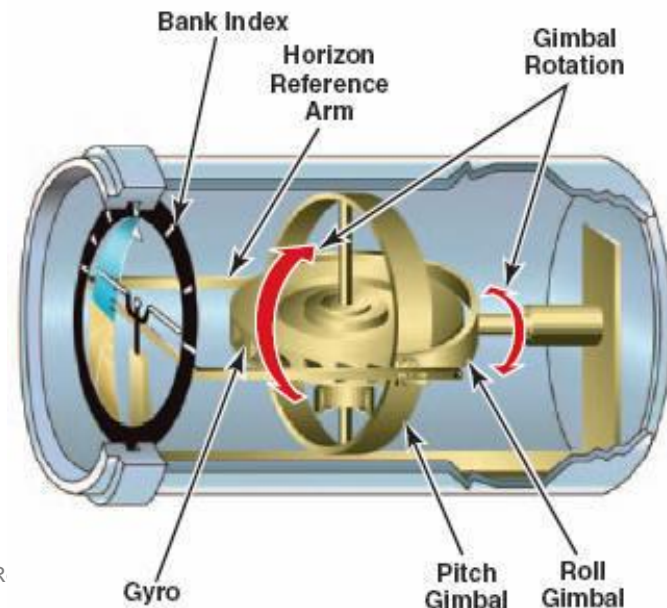
## Attitude Indicator/Artificial Horizon

### Associated Errors:

1. Toppling – unstable tumbling motion caused by extreme manoeuvres
2. Turn Error – AH will precess in a turn  
E.g. Rolling out of a  $180^\circ$  steep turn to the right, the AH will show a slight climb and left turn. This is no more than  $5^\circ$  and corrects itself
3. Acceleration/Deceleration Error – during acceleration, horizon bar moves down indicating a pitch up attitude (opposite effect for deceleration)

### Pilot Actions to Rectify Errors:

- In some aircraft, the AH has a 'cage' knob allowing the pilot to lock the gyro in place and prevent it from toppling
- Some modern gyros will actually re-erect by themselves



## Directional Indicator/Directional Gyro

### System:

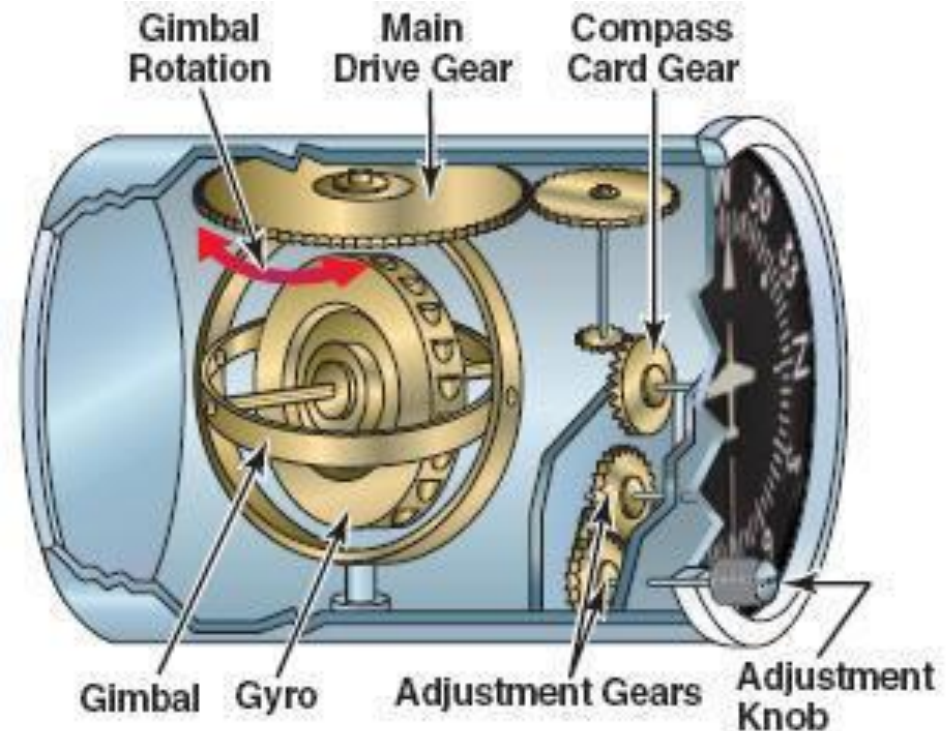
- Vacuum

### Powered By:

- Vacuum Pump (engine-driven)

### How it Works:

- Same as AH – the vacuum system allows the DG to become rigid
- The DG has no idea where north is
- We use the magnetic compass to set the DG so that the gyro has a reference
- As the aircraft moves around the rigid gyro, our heading change will be displayed



## Directional Indicator/Directional Gyro

### Associated Errors:

1. Toppling (DG will spin rapidly and eventually stop, misaligned)
  2. Earth Rate & Transport Wander → causes precession
  3. Friction/Mechanical Drift → causes precession
- Errors 2. and 3. cause the DG to drift about  $10^{\circ}$  of heading every hour (max. 30 before classified as unserviceable)

### Pilot Actions to Rectify Errors:

- Every 15-20 minutes, the DG should be realigned with the compass
- After toppling, simply realign the DG with the magnetic compass
- Make sure the aircraft is in straight & level flight at constant speed when aligning the DG to avoid any compass errors



## Turn Coordinator

### System:

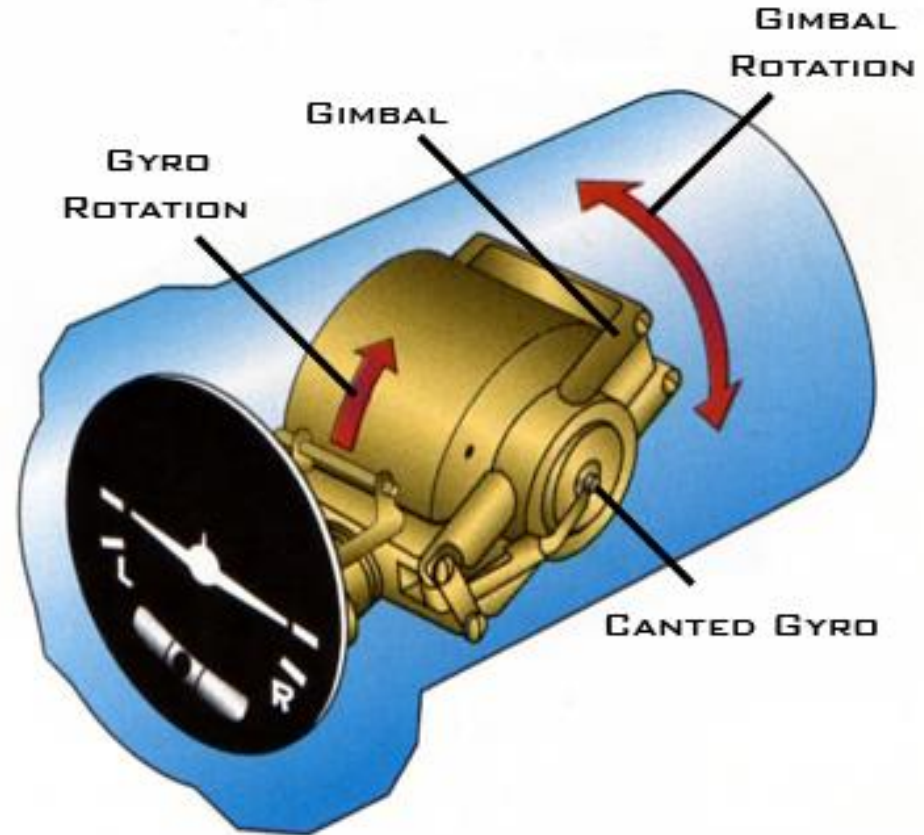
- Electrical

### Powered By:

- DC Electricity

### How it Works:

- Provides yaw and roll information and is a backup for the AH
- It is usually electric so that not all gyroscopic instruments are lost if the vacuum pump fails
- It is an electrically driven rate gyro which senses yaw and roll rates
- Note that it is different to a Turn Indicator, which only indicates yaw





## Turn Coordinator

### Associated Errors:

1. Human Error → Whilst the TC can be a backup to the AH, it will NOT show pitch information

### Pilot Actions to Rectify Errors:

- If using the TC when the AH has failed, a positive scan incorporating the Altimeter and VSI must be conducted to ensure the correct level is being maintained

## Balance Ball

- The balance ball is not part of the gyro
- It is a separate mechanical device indicating the combined effect of the earth's gravity force and any turning forces acting on the aeroplane
- It requires no power source
- Remember → step on the ball !