

OPTIMAL DESIGN OF DECENTRALIZED CONSTRUCTED WETLAND TREATMENT SYSTEM UNDER UNCERTAINTIES

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Optimal design of decentralized constructed wetland treatment system under uncertainties

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1. Introduction

1.1. Globalization and rapid urbanization

Today, more than half of the world's population, 3.5 billion people, are living in urban areas. By 2050, it is predicted that the proportion of people living in urban areas will rise to 6.5 billion, or 60 percent of the population ([United Nations, 2014](#)). This rapid progress in urbanization has been made possible due to advancements in technology and communications worldwide. However, such progress has been achieved at the cost of environmental deterioration, various types of pollution, widening economic disparity, climate change and more ([Barry Dalal-Clayton, 2002](#)). The uncertainty surrounding the climate of the future has led to calls for sustainable development. Sustainable development intends for nations to be able to have positive social and economic development while reducing the environmental impact of the actions taken for such progress. Through various conferences and processes such as those arising following the Brundtland Report (1987), nations have since come to an agreement that development should be sustainable.

As the world becomes more and more urbanized, we are looking at more cities evolving into megacities, which are cities which have populations of more than 10 million. As of 2014, there are 28 megacities across the globe, and by 2050, there is expected to be 41 megacities in the world ([United Nations, 2014](#)). Taking this into consideration together with the uncertain future of our environment, there is a need to plan the growth and development of these cities so that they are sustainable.

1.2. City infrastructure

Traditionally, regular sized cities have the bulk of its infrastructure centralized in convenient areas within the city. For example, in Singapore, solid waste is collected across the country and transported to one of the four waste-to-energy plants for disposal via incineration ([National Environment Agency, 2016](#)). These plants are all located in the southwest of the country. In Trondheim, the third most populous city in Norway ([Statistics Norway, 2013](#)), has two large police stations serving the entire city ([Politiet, 2016](#)). Having centralized infrastructure provides benefits

that often come with economies of scale. In the case of solid waste management in Singapore, the capital cost of building a waste-to-energy plant does not increase significantly with the increased capacity of the plant, and the capital cost to build a plant that serves a smaller capacity is already very large, hence building a larger plant allows each dollar spent to be stretched further.

Decentralized wastewater management systems such as constructed wetlands are increasingly gaining traction as the costs of construction become comparable to centralized wastewater management systems. This is because of the many advantages decentralized systems give over centralized ones. For one, a decentralized system has more treatment sites, which reduces the impact of the failure of a treatment site. If a centralized treatment plant were to fail, the wastewater collected will accumulate and there is no backup plant available to treat the water. On the other hand, if one treatment site of a decentralized system fails, the wastewater may be rerouted to other sites temporarily, ensuring that the system does not come to a standstill.

While constructed wetlands can essentially be implemented wherever there is space, the maximum effectiveness of using this decentralized wastewater treatment system is only achieved when it is located at an optimal distance to the areas which it serves. The performance of constructed wetlands also depends on whether the size is sufficient to handle the projected wastewater flow rate from the area. In addition, the components of wastewater is easily affected by the source and weather. Due to this natural variation, the pollutant composition in wastewater is not deterministic. The ideal configuration (location and size) of treatment sites from a deterministic optimization model may not be feasible under such uncertainty. Hence, this project aims to show how a probabilistic model may be used in this situation to account for the uncertainty with the application of the formulated model in an area in Mobile, Alabama.

1.3. Decentralised wastewater management

Traditional wastewater treatment systems collect wastewater from households and are designed to handle large amounts of wastewater at a central location of the area it serves. With the implementation of centralized treatment systems in many countries, water pollution in those locations have been successfully controlled ([Li et al., 2014](#)). However, such treatment systems often

require technology that are expensive, such as membrane bioreactors. As urbanised areas grow in size and population, the amount of wastewater produced per day in an urban area increases. In addition to the negative consequences of relying on a single location for wastewater treatment (Wilderer and Schreff, 2000; Bakir, 2001), a centralised wastewater management system becomes unwieldy and costly to build on a large scale (Wilderer and Schreff, 2000). In order to tackle this, decentralised wastewater management systems have been proposed to reduce the distance from the wastewater source to the release point, cutting down on the cost of transporting wastewater to a dedicated facility (Otterpohl et al., 1997; Wilderer and Schreff, 2000; Bakir, 2001). Various case studies have conducted a cost-benefit analysis on the implementation of a centralised wastewater management system against a decentralised one and have concluded that the decentralised wastewater management is generally cheaper to maintain (Prihandrijanti et al., 2008; Mobile Area Water & Sewer System et al., 2015).

1.4. Constructed Wetlands

One approach to decentralised wastewater management is the constructed wetlands concept. Essentially, constructed wetlands aim to simulate real wetlands where water flows through and has its nutrients removed via biological processes. In the constructed version, wastewater flows through the wetland to provide the pollutants within as a nutrient source for plant absorption. The end product of wastewater going through these processes is water that meets the standards for release. The use of plants to treat the water allows the procedure of treating wastewater to be more hands off, thus requiring less maintenance. Thus, the costs involved in implementing constructed wetlands is relatively low as it uses the natural ability of plants to treat wastewater (Kadlec and Wallace, 2009; Mobile Area Water & Sewer System et al., 2015). However, the cost effectiveness of constructed wetlands is contingent on the following:

- Treatment sites are in optimal locations.
- Treatment sites are of a suitable size to handle the expected wastewater volume from the sources.

The size of the constructed treatment wetlands has to be big enough to serve the amount of wastewater produced, but not too big as the system may collapse due to a lack of nutrients for the plants towards the end of the wetlands. Additionally, the location of the constructed wetlands has to be taken into consideration to determine the shortest distance of pipes required to link the wastewater sources to the treatment area to balance the cost of transporting wastewater and building the site. ([Mobile Area Water & Sewer System et al., 2015](#)) In order to determine the ideal location and size of constructed wetlands in a defined area, a mathematical model has been developed to represent the problem. Solving this model will give the ideal location and size of constructed wetlands to be designed.

1.4.1. Process Model for Constructed Wetlands

Over the years, implementation of more treatment wetlands in addition to higher water quality standards have encouraged studies to focus on establishing process design tools for the wetlands. Of all the types of wetlands that have been implemented, the horizontal sub-surface flow (HSSF) constructed wetlands is one of the most common. [Rousseau et al. \(2004\)](#) recommends the first-order $k-C^*$ model for representing the constructed wetlands reaction process as it is a good balance between scientific accuracy and complexity as compared to other models that have been developed.

2. Methodology

2.1. Case study: a decentralized CWs system for municipal wastewater treatment

A case study approach is used to showcase the practical application of an optimization model for decentralized CW network to a real-life scenario. In this report, a case study of the optimal location and design size of a constructed wetlands treatment network in Mobile, Alabama.

2.1.1. Mobile, Alabama

With 412,992 people, Mobile County is the second most populated county within Alabama, a state in the United States. The population of Mobile County has been steadily increasing ([Gauthier and United States Census Bureau, 2002](#)). As populations grow, several fringe communities

are created. In order to manage the wastewater produced by such communities, the traditional approach is to link these fringe communities up with long length large diameter pipes to transport all the wastewater produced to a single municipal wastewater treatment plant to be processed and then released into nearby water sources. In Mobile, the Mobile Area Water & Sewer System (MAWSS) serves such fringe communities and overall serves approximately 530 square kilometres in Mobile County ([Mobile Area Water & Sewer System et al., 2015](#)). MAWSS supports the region mostly through centralised wastewater treatment facilities. However, annual operations and maintenance costs for such centralised wastewater management systems have been shown to be costlier than decentralized ones. This is because decentralized treatment systems largely reduce the transport cost incurred and processes wastewater to be released very close to the community ([Mobile Area Water & Sewer System et al., 2015](#)). Thus, implementation of decentralized wastewater management systems such as constructed wetlands are being considered to reduce expenses in the long term.

2.1.2. Case Study Area

The site chosen for the case study is near Mobile Regional Airport. It is a suburban area, mostly consisting of residences. As the objective of the project is to show how the optimization model can be applied, we have chosen a smaller area to keep the computation resources required reasonable. Hence, the site has been divided into 14 blocks based on six census tract blocks. The blocks are represented with blue outlines in [Figure 1](#). Geographic information about the region listed in [Table 4](#) was also retrieved from the census. ([United States Census Bureau, 2016](#)) For each block, we have assumed a point source for the wastewater (see red circles).

Potential sites for the constructed wetlands were identified from Google Maps and represented in [Figure 1](#) as green rectangles. These areas are uninhabited and thus the construction of wetlands there will impact few residents negatively. A point location is used to represent each of these sites. The coordinates of the potential sites are stated in [Table 5](#). The distances between the wastewater sources and potential sites were calculated as well and stated in [Table 6](#).

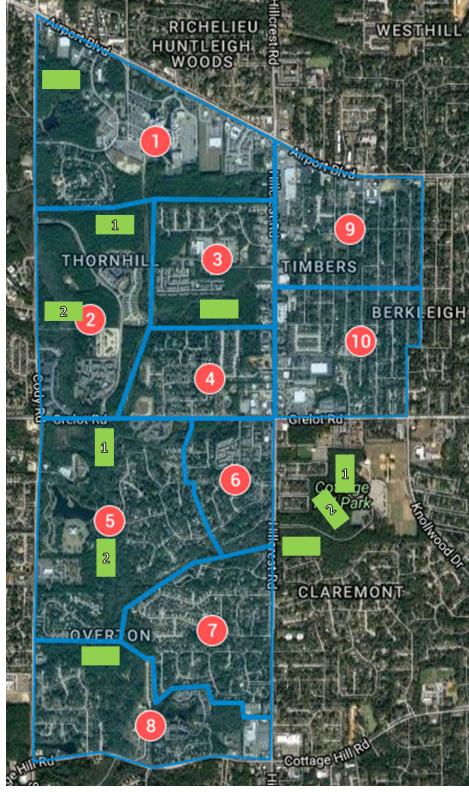


Figure 1: Case study area in Mobile, Alabama.

2.1.3. Pollutant consideration

Once again, to keep the model manageable, we have narrowed down the number of pollutants to three, the Biological Oxygen on Demand over 5 days (BOD5), Total Suspended Solids (TSS) and Total Nitrogen (TN). These pollutants have been selected due to their potential impact on the ecosystem if left untreated. BOD5, simply put, is the quantity of oxygen consumed by the aerobic biological activity of microorganisms in the water. It indicates the amount of

as seen in [Table 7](#). The pollutants have been selected based on the effects of pollution if these substances were not removed. In this case study, we will set the treatment target to be the same regardless of the intended use for the treated water.

2.2. Qualitative model formulation

In general, a decentralized constructed wetlands system in a region can be represented as in [Figure 2](#). Wastewater is generated from the sources I and routed to constructed wetlands, where

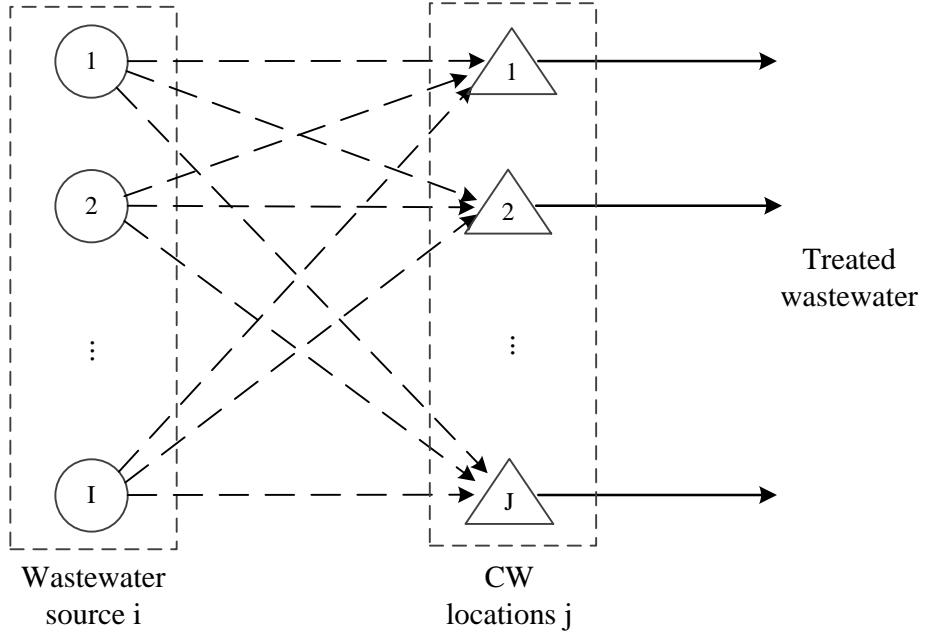


Figure 2: Superstructure of a decentralized CW treatment system network

it is treated and discharged or reused on site. Thus, given a set of wastewater sources I and a set of potential constructed wetlands locations J , the ultimate objective is to determine how to link the sources to the constructed wetlands, where the wetlands should be located and the size of the wetlands at the site.

Besides this, in line with regulatory standards for treated water effluent, treatment targets are imposed on a set of pollutants M . This means that treated water leaving the constructed wetlands must have pollutant concentrations below specified levels. Depending on the intended use for treated water, treatment targets may be adjusted accordingly for each constructed wetlands site. This constraint directly affects the size of the constructed wetlands for a site as the size of the site determines the pollutant removal rate. It also indirectly affects the routing of the wastewater sources to the treatment sites.

Thus, a solution is deemed feasible only when it satisfies all the constraints. However, due to natural variation in the environment and pollutant concentration of the influent wastewater, constructed wetlands may not always effectively remove pollutants. In reality, it is also unlikely that the treated wastewater meets the targets all the time.

Additionally, cost is a major factor for decision makers to take into account hence the best feasible solution should be one that incurs the least cost. The cost consideration affects how the wastewater sources are routed to the treatment sites as the longer the distance, the higher the cost of constructing the pipe to link the source and site up. For the model, the following assumptions are made:

- wastewater from each source $i = 1, \dots, I$ can be allocated to multiple constructed wetlands sites and each constructed wetlands can also treat wastewater from multiple wastewater sources. Sewer lines are needed to be constructed between wastewater sources and constructed wetlands.
- for any location $j = 1, \dots, J$, if it is determined to construct a constructed wetlands, K design options $k = 1, \dots, K$ could be selected. Otherwise, we use $k = 0$ to indicate that this location is not chosen to construct any constructed wetlands.
- a list of M pollutants $m = 1, \dots, M$ are evaluated. Treatment target τ_j^m is set for each pollutant m and each potential site j .

2.3. Deterministic Model

A basic list of model parameters and decision variables is provided in [Table 1](#). Other notations would be introduced and defined as per required in the rest of the paper. Before the uncertainty component is addressed, we will consider a model where there are no stochastic components.

2.3.1. Objective Function

For the deterministic case, the objective of the problem is to minimize the total cost of implementing the system in a region.

$$\min \sum_{i=1}^I \sum_{j=1}^J d_{ij} c_s x_{ij} + \sum_{j=1}^J \sum_{k=1}^K c_{cw,jk} y_{jk} \quad (1)$$

2.3.2. Constraints

The following constraints formulate the constructed wetlands design option, wastewater allocation between sources and constructed wetlands, pollutant removal performance and treatment

Table 1: Notations of model parameters and decision variables

Indices	
i	index of wastewater sources, $i \in \{1, 2, \dots, I\}$
j	index of potential CW locations, $j \in \{1, 2, \dots, J\}$
m	index of evaluated water pollutants, $m \in \{1, 2, \dots, M\}$
k	index of CW construction options, $k \in \{0, 1, 2, \dots, K\}$
Model parameters	
ε_i^m	concentration of pollutant m in the wastewater source i (mg/m^3)
τ_j^m	treatment target for pollutant m in CW site j (mg/m^3)
F_i	total wastewater flow generated by source i (m^3/d)
Q_{jk}	flow capacity of CW in option k for site j (m^3/d)
A_{jk}	area of CW in option k for site j (m^2)
$c_{cw,jk}$	construction cost of CW in design option k for site j (\$)
d_{ij}	distance between wastewater source i and site j (m)
c_s	unit construction cost of sewer lines per distance (\$/m)
Decision variables	
x_{ij}	binary variable, $x_{ij} = 1$ if sewer lines are constructed from wastewater source i to CW site j and 0 otherwise
y_{jk}	binary variable, $y_{jk} = 1$ if construction option k is chosen for site j and 0 otherwise. In particular, y_{j0} denotes the choice of not constructing any CWs in site j
z_{ij}	volume of wastewater flow assigned from wastewater source i to the CW in site j (m^3)

target fulfillment:

Constructed wetlands design options

Let y_{jk} be a binary variable that describes the design option k selected for the constructed wetlands site j . In the case where $k = 0$, there will be no constructed wetlands on the potential site j . Otherwise, any other values for k will correspond to the respective design options available. When $y_{jk} = 1$, it means that there will be a constructed wetlands of type k at site j .

The different design options result in different construction costs and pollutant removal capacities. At each potential CW site, there can only be one design option selected. Hence, the following constraints are introduced:

$$\sum_{k=0}^K y_{jk} = 1 \quad \forall j \quad (2)$$

$$y_{jk} \in \{0, 1\} \quad \forall j, k \quad (3)$$

Wastewater allocation from sources to sites

Let x_{ij} be a binary variable that describes the interconnection between the wastewater source i and potential constructed wetlands site j . When $x_{ij} = 1$, there is a pipe constructed between wastewater source i and potential constructed wetlands site j . Wastewater is allowed to flow from source i to site j . Otherwise, when $x_{ij} = 0$, there is no pipe connecting wastewater source i and potential constructed wetlands site j .

All the wastewater produced in the region studied has to be treated, so there should not be any excess wastewater volume. On top of that, the total volume of wastewater flowing into a constructed wetland cannot exceed the design capacity of the constructed wetland. If $y_{j0} = 1$ for any j , there should not be any pipes connecting any wastewater source i to the respective potential constructed wetlands site j . Finally, there should only be wastewater sent to a site j if the wastewater source i and potential constructed wetlands site j is connected (i.e. $x_{ij} = 1$).

If z_{ij} represents the volume of wastewater sent from source i to site j , F_i is the total wastewater

flow from source i and Q_{jk} is the maximum flow capacity accepted by site j with design option k :

$$\sum_{i=1}^I z_{ij} \leq \sum_{k=0}^K Q_{jk} y_{jk}, \quad \forall j \quad (4)$$

$$\sum_{j=1}^J z_{ij} = F_i, \quad \forall i \quad (5)$$

$$x_{ij} + y_{j0} \leq 1 \quad \forall i, j \quad (6)$$

$$x_{ij} \in \{0, 1\} \quad \forall i, j \quad (7)$$

$$z_{ij} \geq 0 \quad \forall i, j \quad (8)$$

Pollutant removal performance and treatment target fulfillment

First, we consider the influent of the constructed wetlands. The water that is entering the constructed wetlands should have the same amount of pollutants as all of the sources that are contributing wastewater to the site. To determine the pollutant concentration in the effluent, we use a first-order $k - C^*$ model (Rousseau et al., 2004) to calculate the pollutant removal.

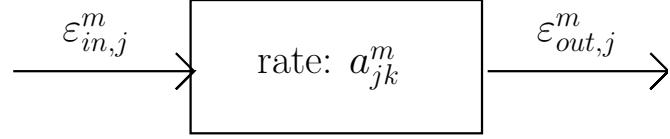
The treatment rate of a pollutant in a HSSF CW can be represented with a first-order $k - C^*$ model in the following equation:

$$\frac{C_{out} - C^*}{C_{in} - C^*} = e^{-\frac{A}{Q} k_A} \quad (9)$$

where C_{in} is the concentration of the pollutant in the influent, C_{out} is the concentration of the pollutant in the effluent, C^* is the background concentration of the pollutant in the water, A is the area of the treatment site, Q is the flow capacity of the treatment site and k_A is the areal rate constant.

The areal rate constant k_A is determined empirically for each pollutant and varies depending on the region that the data is collected from. For the purposes of the case study, we will be using k_A values based on data from North America as collated by Vymazal and Krpfelov (2008). As the area A and flow capacity Q of the CWs are determined beforehand using the various design options, the pollutant treatment rate can be reduced to a constant, which simplifies the $k - C^*$ model. In the deterministic model, we will be representing the treatment rate with an array of constants, a_{jk}^m . Therefore, the treatment rate can be treated as if the process is a linear plug-flow

reactor that follows the linear expression $ax + b$ as in [Figure 3](#).



[Figure 3](#): Pollutant treatment process

Where $\varepsilon_{in,j}^m$ is the concentration of pollutant m in the influent at potential CW site j and $\varepsilon_{out,j}^m$ is the concentration of pollutant m in the effluent at potential CW site j .

Linearization of [Equation 9](#) also results in a constant for the background concentration C^* . To address this, an array constant b_{jk}^m will be added to the effluent concentration.

$$a_{jk}^m = e^{-\frac{A_{jk}}{Q_{jk}} k_A^m} \quad \forall j, k, m$$

$$b_{jk}^m = C^* e^{-\frac{A_{jk}}{Q_{jk}} k_A^m} \quad \forall j, k, m$$

Finally, the effluent pollutant concentrations should meet treatment targets τ_j^m . The following constraint combines the treatment rate with the treatment target constraint:

$$\sum_{i=1}^I (a_{jk}^m \varepsilon_i^m + b_{jk}^m) z_{ij} - M_1 (1 - y_{jk}) \leq \tau_j^m \sum_{i=1}^I z_{ij} \quad \forall j, k, m \quad (10)$$

The following deterministic model is developed from the above constraints. It is a *Mixed-Integer*

Linear Programming (MILP) problem (Model D):

$$\text{Model D : } \min \sum_{i=1}^I \sum_{j=1}^J d_{ij} c_s x_{ij} + \sum_{j=1}^J \sum_{k=1}^K c_{cw,jk} y_{jk}$$

$$\text{s.t. } \sum_{i=1}^I (a_{jk}^m \varepsilon_i^m + b_{jk}^m) z_{ij} - M_1(1 - y_{jk}) \leq \tau_j^m \sum_{i=1}^I z_{ij} \quad \forall j, k, m \quad (1)$$

$$\sum_{i=1}^I z_{ij} \leq \sum_{k=0}^K Q_{jk} y_{jk} \quad \forall j \quad (2)$$

$$\sum_{j=1}^J z_{ij} = F_i \quad \forall i \quad (3)$$

$$z_{ij} \leq F_i x_{ij} \quad \forall i, j \quad (4)$$

$$x_{ij} + y_{j0} \leq 1 \quad \forall i, j \quad (5)$$

$$\sum_{k=0}^K y_{jk} = 1 \quad \forall j \quad (6)$$

$$x_{ij} \in \{0, 1\} \quad \forall i, j \quad (7)$$

$$y_{jk} \in \{0, 1\} \quad \forall j, k \quad (8)$$

$$z_{ij} \geq 0 \quad \forall i, j \quad (9)$$

2.3.3. Results

Table 2: Notations of new model parameters and decision variables

Indices	
n	index of scenarios to be generated, $n \in \{1, 2, \dots, N\}$
Model parameters	
ε_i^{mn}	concentration of pollutant m in the wastewater source i for scenario n (mg/m^3)
Decision variables	
z_{ij}^n	volume of wastewater flow assigned from wastewater source i to the CW in site j in scenario n (m^3)
γ^n	binary variable, $\gamma^n = 1$ if all pollutants in all effluents $\varepsilon_{out,j}^m n$ for scenario n meet the treatment target τ_j^m
λ_{ijk}^n	variable for the McCormick envelope for the bilinear term y_{jk} and z_{ij}

$$\begin{aligned}
\text{Model S1 :} \quad & \max \frac{1}{N} \sum_{n=1}^N \gamma^n \\
\text{s.t.} \quad & \sum_{k=1}^K \sum_{i=1}^I (a_{jk}^m \varepsilon_i^{mn} + b_{jk}^m) \lambda_{ijk}^n - \tau_j^m \sum_{i=1}^I z_{ij}^n \leq M_2(1 - \gamma^n) \quad \forall j, m, n \\
& \sum_{i=1}^I \sum_{j=1}^J d_{ij} c_s x_{ij} + \sum_{j=1}^J \sum_{k=1}^K c_{cw,jk} y_{jk} \leq B \\
& \sum_{i=1}^I z_{ij}^n \leq \sum_{k=0}^K Q_{jk} y_{jk} \quad \forall j, n \\
& \sum_{j=1}^J z_{ij}^n = F_i \quad \forall i, n \\
& z_{ij}^n \leq F_i x_{ij} \quad \forall i, j, n \\
& x_{ij} + y_{j0} \leq 1 \quad \forall i, j \\
& \sum_{k=0}^K y_{jk} = 1 \quad \forall j \\
& \lambda_{ijk}^n \geq z_{ij}^n + z_{ij}^{nu} y_{jk} - z_{ij}^{nu} \quad \forall i, j, k, n \\
& \lambda_{ijk}^n \geq 0 \quad \forall i, j, k, n \\
& x_{ij} \in \{0, 1\} \quad \forall i, j \\
& y_{jk} \in \{0, 1\} \quad \forall j, k \\
& z_{ij}^n \geq 0 \quad \forall i, j, n
\end{aligned}$$

Table 3: Notations of model parameters and decision variables

Indices	
i	index of wastewater sources, $i \in \{1, 2, \dots, I\}$
j	index of potential CW locations, $j \in \{1, 2, \dots, J\}$
m	index of evaluated water pollutants, $m \in \{1, 2, \dots, M\}$
k	index of CW construction options, $k \in \{0, 1, 2, \dots, K\}$
n	index of scenarios to be generated, $n \in \{1, 2, \dots, N\}$
Model parameters	
ε_i^{mn}	concentration of pollutant m in the wastewater source i for scenario n (mg/m^3)
τ_j^m	treatment target for pollutant m in CW site j (mg/m^3)
F_i	total wastewater flow generated by source i (m^3/d)
Q_{jk}	flow capacity of CW in option k for site j (m^3/d)
A_{jk}	area of CW in option k for site j (m^2)
$c_{cw,jk}$	construction cost of CW in design option k for site j (\$)
d_{ij}	distance between wastewater source i and site j (m)
c_s	unit construction cost of sewer lines per distance (\$/m)
Decision variables	
x_{ij}	binary variable, $x_{ij} = 1$ if sewer lines are constructed from wastewater source i to CW site j and 0 otherwise
y_{jk}	binary variable, $y_{jk} = 1$ if construction option k is chosen for site j and 0 otherwise. In particular, y_{j0} denotes the choice of not constructing any CWs in site j
z_{ij}^n	volume of wastewater flow assigned from wastewater source i to the CW in site j in scenario n (m^3)
η^n	largest pollutant treatment shortfall mass in scenario n (mg)

$$\begin{aligned}
\text{Model S2 :} \quad & \min \frac{1}{MN} \sum_{m=1}^M \sum_{n=1}^N \frac{\eta^{mn}}{\tau_j^m \sum_{i=1}^I F_i} \\
\text{s.t.} \quad & \sum_{i=1}^I (a_{jk}^m \varepsilon_i^{mn} + b_{jk}^m - \tau_j^m) z_{ij}^n - M_3(1 - y_{jk}) \leq \eta^{mn} \quad \forall j, k, m, n \\
& \sum_{i=1}^I \sum_{j=1}^J d_{ij} c_s x_{ij} + \sum_{j=1}^J \sum_{k=1}^K c_{cw,jk} y_{jk} \leq B \\
& \sum_{i=1}^I z_{ij}^n \leq \sum_{k=0}^K Q_{jk} y_{jk} \quad \forall j, n \\
& \sum_{j=1}^J z_{ij}^n = F_i \quad \forall i, n \\
& z_{ij}^n \leq F_i x_{ij} \quad \forall i, j, n \\
& x_{ij} + y_{j0} \leq 1 \quad \forall i, j \\
& \sum_{k=0}^K y_{jk} = 1 \quad \forall j \\
& x_{ij} \in \{0, 1\} \quad \forall i, j \\
& y_{jk} \in \{0, 1\} \quad \forall j, k \\
& z_{ij}^n \geq 0 \quad \forall i, j, n \\
& \eta^{mn} \geq 0 \quad \forall n
\end{aligned}$$

3. Further Directions

Proceeding from here, the next step would be to find a solution for the deterministic model, which will be done using MATLAB. After which, work will commence on developing the probabilistic model and running it.

Appendix

Table 4: Geographical information about the 14 blocks.

Block	Latitude	Longitude	Area(km^2)	Population	EstWastewaterPdtm(m^3/day)
1	30.67816	-88.19916	1.41	818	181.43
2	30.66729	-88.20382	1.06	818	181.43
3	30.67099	-88.19483	0.725	817	181.21
4	30.66364	-88.19536	0.593	817	181.21
5	30.65495	-88.20249	1.47	850	188.53
6	30.65746	-88.19354	0.487	849	188.31
7	30.64819	-88.19513	0.847	992	220.03
8	30.64237	-88.19952	0.986	991	219.8
9	30.672781	-88.18536	0.837	1104	244.87
10	30.665934	-88.18461	0.84	1104	244.87
11	30.653936	-88.18485	0.98	686	152.15
12	30.649967	-88.18725	0.434	685	151.93
13	30.645131	-88.18648	0.682	838	185.87
14	30.647918	-88.17757	0.667	837	185.65

Table 5: Coordinates of the potential constructed wetlands sites.

PotentialSite	Latitude	Longitude
1	30.68151	-88.20598
2-1	30.67263	-88.20227
2-2	30.66779	-88.20485
3	30.66765	-88.19583
5-1	30.65903	-88.20296
5-2	30.65249	-88.20255
8	30.64655	-88.20326
11-1	30.65777	-88.18588
11-2	30.65600	-88.18691
12	30.65356	-88.18880

Table 6: Distance in *km* between the wastewater sources and potential constructed wetlands sites.

i/j	1	2-1	2-2	3	5-1	5-2	8	11-1	11-2	12
1	0.751	0.683	1.275	1.211	2.158	2.873	3.537	2.599	2.728	2.909
2	1.595	0.612	0.113	0.765	0.922	1.65	2.307	2.016	2.047	2.096
3	1.583	0.735	1.022	0.383	1.541	2.186	2.835	1.701	1.831	2.022
4	2.232	1.198	1.018	0.448	0.889	1.418	2.045	1.117	1.173	1.285
5	2.972	1.966	1.445	1.549	0.456	0.274	0.937	1.619	1.495	1.319
6	2.927	1.882	1.578	1.154	0.918	1.024	1.528	0.734	0.655	0.627
7	3.848	2.802	2.369	2.165	1.419	0.856	0.799	1.385	1.172	0.85
8	4.396	3.375	2.872	2.833	1.882	1.162	0.587	2.153	1.937	1.612
9	2.198	1.617	1.945	1.152	2.274	2.792	3.382	1.67	1.872	2.162
10	2.679	1.846	1.947	1.09	1.916	2.276	2.798	0.916	1.126	1.433
11	3.672	2.664	2.456	1.852	1.823	1.701	1.943	0.438	0.302	0.38
12	3.938	2.901	2.6	2.131	1.809	1.49	1.578	0.877	0.672	0.426
13	4.454	3.41	3.072	2.659	2.208	1.742	1.613	1.407	1.209	0.963
14	4.619	3.624	3.419	2.804	2.725	2.443	2.462	1.354	1.267	1.244

Table 7: Selected pollutants with the respective indicators coupled with average pollutant concentration in the wastewater source and the treatment targets.

	Pollutant	Indicator	AvgInfluentConc (mg/l)	TreatmentTarget (mg/l)
1	Microorganisms	BOD ₅	242.5	30
2	Ammoniacal and organic nitrogen	TN	50.5	10
3	Suspended solids	TSS	220.5	30

Table 8: Construction cost of constructed wetlands with four different design options as well as projected area and flow capacity.

K	Q(m ³ /day)	A(m ²)	Cost(\$'000)
1	450	7000	606
2	650	10000	780
3	800	12500	912
4	950	15000	1037

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