

Final motor has its own connector on the other side of the sensor PCB

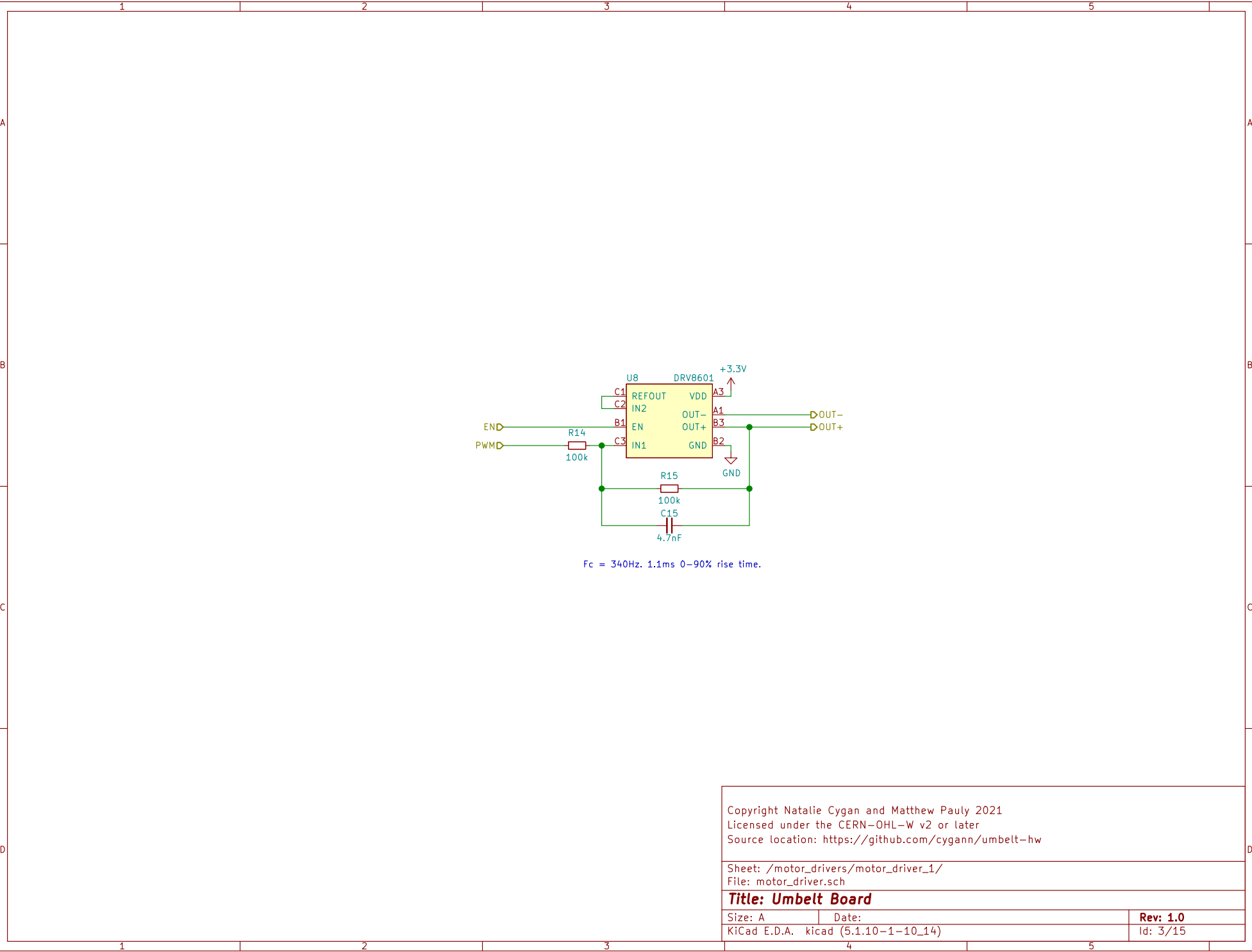
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Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/
File: motor_drivers.sch

Title: Umbelt Board

Size: A Date:
KiCad E.D.A. kicad (5.1.10-1-10_14)

Rev: 1.0
Id: 2/15



U8 DRV8601

REFOUT IN2 EN IN1 VDD OUT- OUT+ GND

+3.3V

A3

B1

B3

B2

GND

R14 100k

R15 100k

C15 4.7nF

OUT-

OUT+

END

PWM

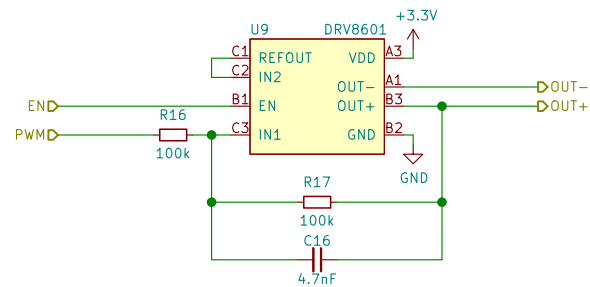
FC = 340Hz, 1.1ms 0-90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_1/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10-1-10_14)		Id: 3/15



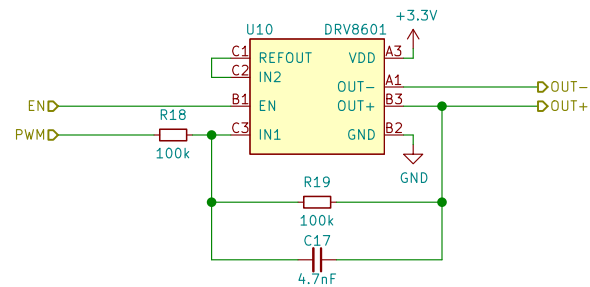
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_2/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 4/15



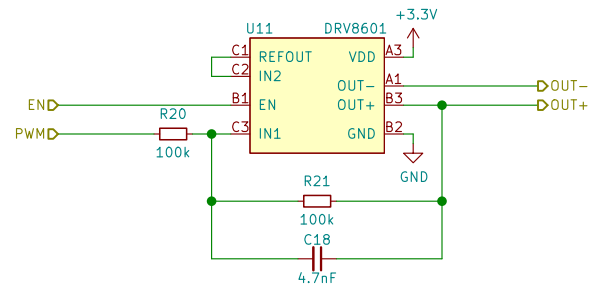
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_3/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 5/15



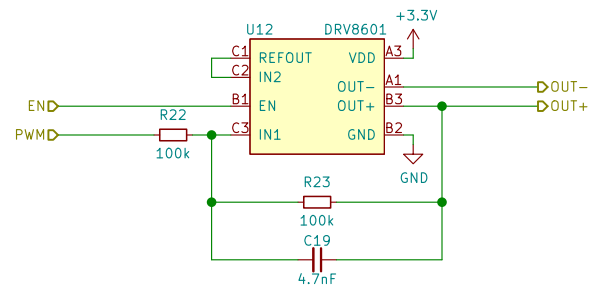
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_4/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 6/15



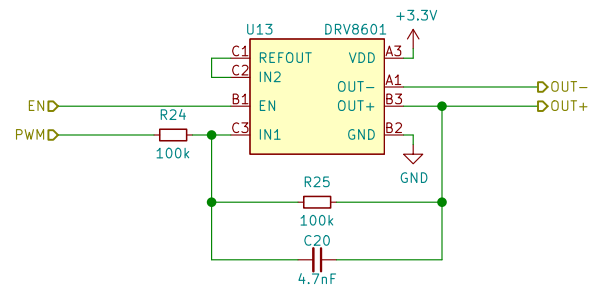
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_5/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 7/15



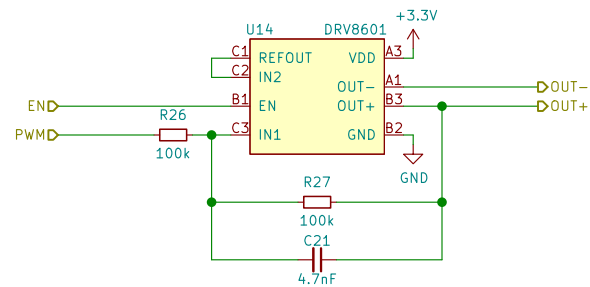
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_6/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 8/15



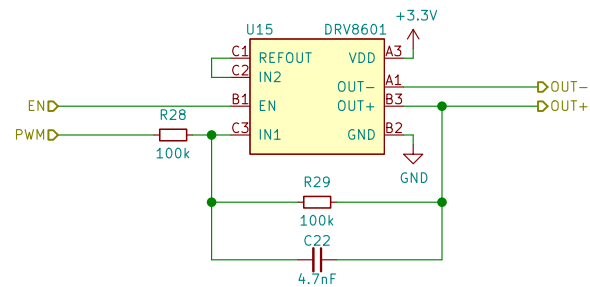
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_7/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 9/15



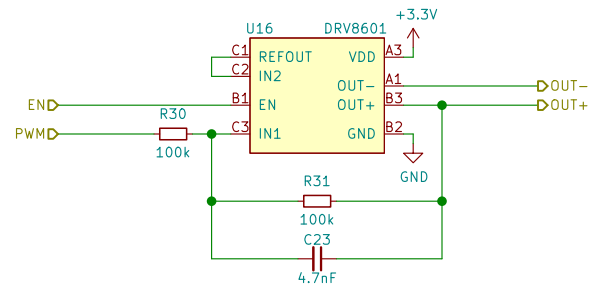
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_8/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 10/15



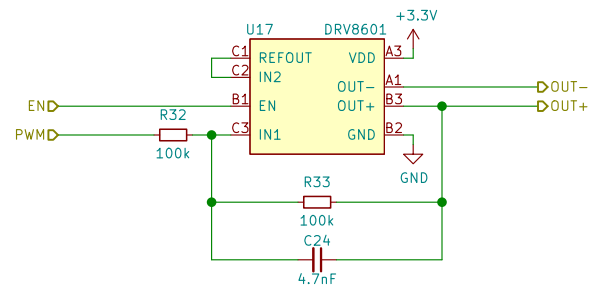
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_9/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 11/15



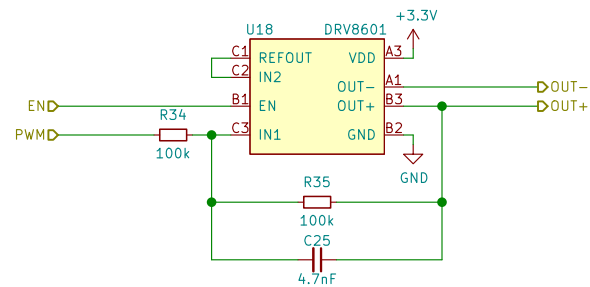
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_10/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 12/15



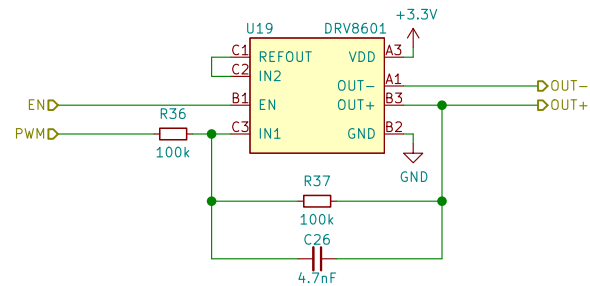
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_11/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 13/15



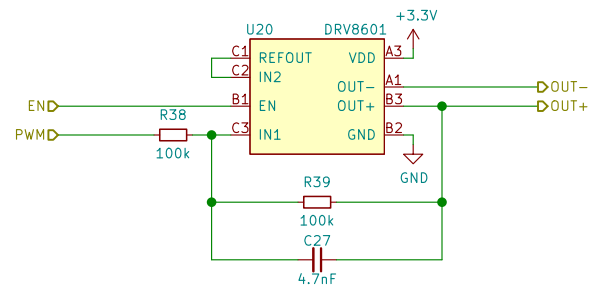
$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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 Source location: <https://github.com/cygann/umbelt-hw>

Sheet: /motor_drivers/motor_driver_12/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A.	kiCad (5.1.10–1–10_14)	Id: 14/15



$F_c = 340\text{Hz}$. 1.1ms 0–90% rise time.

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Sheet: /motor_drivers/motor_driver_0/
 File: motor_driver.sch

Title: Umbelt Board

Size: A	Date:	Rev: 1.0
KiCad E.D.A. kicad (5.1.10–1–10_14)		Id: 15/15