

Sequential Monte Carlo methods

Lecture 16 – SMC samplers

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Outline – Lecture 3

Aim: Introduce the SMC sampler

Outline:

1. Problem formulation – when is an SMC sampler applicable?
2. The annealing/tempering idea
3. Constructing the SMC sampler
4. User aspects

Main reference

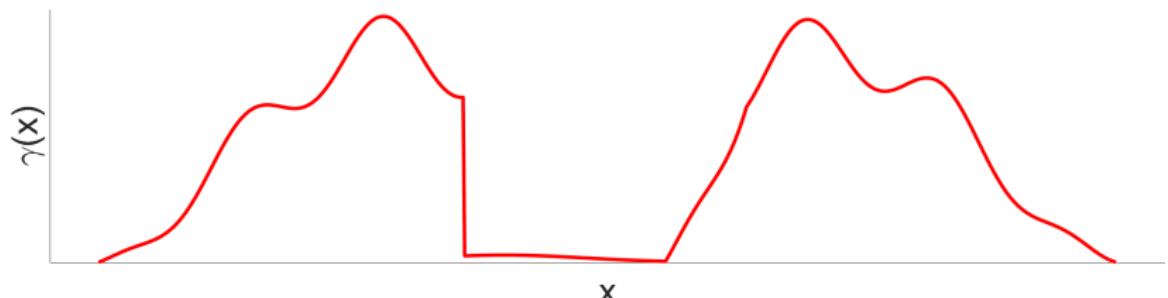
-  Pierre Del Moral, Arnaud Doucet, and Ajay Jasra 2006:. **Sequential Monte Carlo samplers.** *Journal of the Royal Statistical Society: Series B*, 68(3), pp. 411–436.

Problem formulation

Let \mathcal{X} be a space on which a probability density γ is defined. Let $\tilde{\gamma}$ be an unnormalized version of the density, as $\gamma(x) = \frac{\tilde{\gamma}(x)}{Z}$. Assume that only $\tilde{\gamma}(x)$ can be evaluated pointwise.

Goal: Generate N samples $x^i \in \mathcal{X}$ from the density $\gamma(x)$.

(A typical situation is when γ is a parameter posterior or Z is the marginal likelihood/model evidence.)



Most common solution

MCMC?

SMC sampler is an alternative!

Metropolis-Hastings

γ -invariant Metropolis-Hastings (a reminder)

for $k = 1, \dots$

Propose a new sample x' from a proposal $r(x' | x_k)$

Compute acceptance rate $\alpha = \min(1, \frac{\gamma(x') r(x_k | x')}{\gamma(x_k) r(x_k | x')})$

Set $x_{k+1} \leftarrow x'$ with probability α , otherwise set $x_{k+1} \leftarrow x_k$

Annealing/tempering

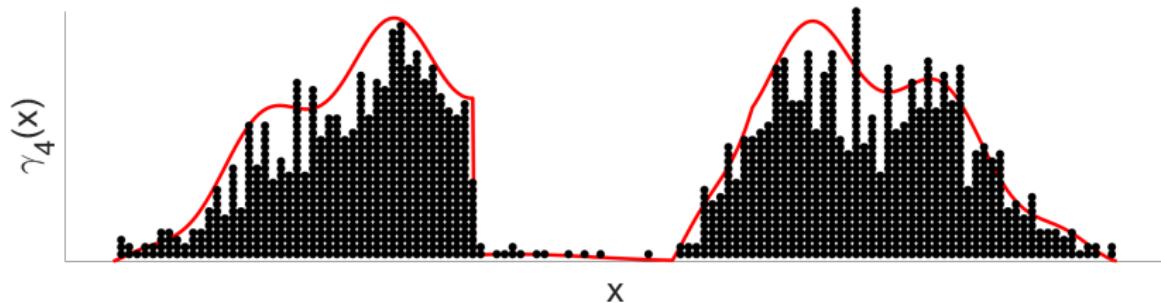
Sequential Monte Carlo needs something **sequential**. Construct a sequence which transitions ‘smoothly’ in K steps from a simple initial $\gamma_0(x)$ to the sought $\gamma_K(x) \equiv \gamma(x)$.

For example:

- If $\gamma(x)$ is a posterior $\gamma(x) \propto p(y | x)p(x)$, then $\gamma_k(x) \propto p(y | x)^{\tau_k} p(x)$, $\tau_k = k/K$ (likelihood tempering)
- If $\gamma(x)$ depends on some data $y_{1:K}$ as $\gamma(x) = p(x | y_{1:K})$, then $\gamma_k(x) = p(x | y_{1:k})$ (data tempering)

The SMC sampler: a sneak peek

Intuition: Track the evolving sequence $\gamma_0, \gamma_1, \dots, \gamma_K$ using a weighting - resampling - propagation scheme.



How do we do it? This sequence (unlike the state inference problem) is not defined as a state-space model, neither does it fall into the general SMC formulation (yet).

Attempt I

Let's try to make use of the sequence $\gamma_0, \gamma_1, \dots, \gamma_K$:

Sample x^i from γ_0 (we assume we can do that)

for $k = 1$ **to** K

$$\text{Evaluate } \tilde{w}_k^i(x^i) = \frac{\gamma_k(x^i)}{\gamma_{k-1}(x^i)}$$

Set weights $\tilde{w}^i \propto \prod_{k=1}^K \tilde{w}_k^i$ and normalize

Valid but inefficient: effectively importance sampling with proposal γ_0 and target γ .

Attempt II

Sample x_0^i from γ_0 (we assume we can do that)

for $k = 1$ **to** K

 Use some Markov kernel κ_k to sample new x_k^i from $\kappa_k(x_{k-1}^i, x_k^i)$

 Set weights $w_k^i \propto w_{k-1}^i \frac{\gamma_k(x_k^i)}{\eta_k(x_k^i)}$ and normalize

 If needed: Resample and set weights $w_k^i = 1/N$

$\eta_k(x_k^i)$ is $\eta_k(x_k) = \int_{\mathcal{X}^k} \gamma_0(x_0) \prod_{k=1}^K K_k(x_{k-1}, x_k) dx_{0:k-1}$.

In most cases intractable

Attempt III

Introduce a backward kernel $\lambda_{k-1}(x_k, x_{k-1})$, and define

$$\pi_0(x_0) = \gamma_0(x_0), x_0 \in \mathcal{X}$$

$$\pi_1(x_{0:1}) = \gamma_1(x_1)\lambda_0(x_1, x_0), x_{0:1} \in \mathcal{X} \times \mathcal{X} = \mathcal{X}^2$$

⋮

$$\pi_K(x_{0:K}) = \gamma_p(x_p) \prod_{k=1}^K \lambda_{k-1}(x_k, x_{k-1}), x_{0:K} \in \mathcal{X}^{K+1}$$

- γ_k is defined on \mathcal{X} , whereas π_k is defined on \mathcal{X}^{k+1}
- The marginal with index k of $\pi_k(x_{0:k})$ is $\int \pi_k(x_{0:k}) dx_{0:k-1} = \gamma_k(x_k)$
- The marginal with index $j < k$ of $\pi_k(x_{0:k})$ is
 $\int \pi_k(x_{0:k}) dx_{0:j-1, j+1:k} \neq \gamma_j(x_j)$

Attempt III

We now have a sequence $\pi_0, \pi_1, \dots, \pi_p$ (with marginals that we are interested in) defined on the spaces $\mathcal{X}, \mathcal{X}^2, \dots, \mathcal{X}^{K+1}$.

Use the general SMC scheme!

Sample x^i from γ_0 and set weights $w_0^i = 1/N$

for $k = 1$ **to** K

 Use γ_k -invariant Markov kernel κ_k to sample x_k^i

 Set weights $\tilde{w}_k^i = w_{k-1}^i \omega(x_{k-1:k}^i)$ and normalize to w_k^i

 If ESS too low, resample and set $w_k^i = 1/N$

Here, $\omega(x_{k-1:k}) = \frac{\gamma_k(x_k)\lambda_{k-1}(x_k, x_{k-1})}{\gamma_{k-1}(x_{k-1})\kappa_k(x_{k-1}, x_k)}$

Attempt III

How to choose the artificial backward kernels λ_{k-1} ?

- To minimize the variance of the weights, the optimal choice is

$$\lambda_{k-1} = \frac{\eta_{k-1} \kappa_k}{\eta_k}$$

\Rightarrow The intractable IS solution

- Keeping variance low *and* the weights tractable:

A generic choice, if κ_k has invariant distribution γ_k , is

$$\lambda_{k-1}(x_k, x_{k-1}) = \frac{\gamma_k(x_{k-1}) \kappa_k(x_{k-1}, x_k)}{\gamma_k(x_k)}$$

\Rightarrow

$$\omega(x_{k-1:k}) = \frac{\gamma_k(x_{k-1})}{\lambda_{k-1}(x_{k-1})}$$

Attempt III

Design choices made: κ_k and λ_{k-1}

The γ_k -invariant Markov kernel κ_k is **one option** for propagating the samples, q_k in the general SMC framework.

The backward kernel λ_{k-1} is **part of the model specification** of π_0, \dots, π_K , in the SMC context. (But since we are only interested in a marginal of π_K not depending on λ_{k-1} , it may appear to be part of the inference rather than the model.)

The final generic SMC sampler

Sample x^i from γ_0 (we assume we can do that) and set weights

$$w_0^i = 1/N$$

for $k = 1$ **to** K

Set weights $w_k^i \propto w_{k-1}^i \frac{\gamma_k(x_{k-1}^i)}{\gamma_{k-1}(x_{k-1}^i)}$ and normalize

If ESS too low, resample and set $w_k^i = 1/N$

Use γ_k -invariant Metropolis-Hastings to sample x_k^i

Estimating Z

For notational convenience, we have implicitly assumed we can evaluate $\gamma(x)$ exactly for any $x \in \mathcal{X}$. The SMC is also applicable if we only can evaluate $\tilde{\gamma}(x)$, where $\gamma(x) = \frac{\tilde{\gamma}(x)}{Z}$.

If $Z = Z_K$ is of interest, we can estimate Z_K/Z_0 as

$$\widehat{\frac{Z_K}{Z_0}} = \prod_{k=1}^K \widehat{\frac{Z_k - 1}{Z_k}}$$

where

$$\widehat{\frac{Z_{k-1}}{Z_k}} = \sum_{i=1}^N w_{k-1}^i \omega(x_{k-1:k}^i)$$

and Z_0 is the normalizing constant of the user-chosen γ_0 .
(Superior to annealed importance sampling.)

SMC sampler vs MCMC

MCMC (Metropolis-Hastings)

Set initial x_0

for $k = 1, \dots$

Propose a new sample x' from $r(x' | x_k)$

Compute $\alpha = \max(1, \frac{q(x')}{p(x_k)} \frac{q(x_k | x')}{q(x' | x_k)})$

Set $x_{k+1} \leftarrow x'$ with probability α ,
otherwise $x_{k+1} \leftarrow x_k$

end

SMC sampler

Sample x^i from γ_0 and set weights $w_0^i = 1/N$

for $k = 1$ to K

Set $\tilde{w}_k^i = w_{k-1}^i \frac{\gamma_k(x_{k-1}^i)}{\gamma_{k-1}(x_{k-1}^i)}$ and normalize

If ESS too low, resample and set $w_k^i = 1/N$

Sample x_k^i by γ_k -invariant Metropolis-Hastings

end

User's generic recipe

1. Design a simulated annealing sequence (e.g., likelihood or data tempering)
2. Design a MCMC kernel (typically Metropolis-Hastings) for γ_k
3. Run the SMC sampler

Automatic adaptation

- Adaptation of the MCMC kernels

 Paul Fearnhead and Benjamin M. Taylor 2013: **An adaptive sequential Monte Carlo sampler.** *Bayesian analysis*, 8(2), pp. 411–438.

- Adaptation of the tempering sequence

 Yan Zhou, Adam M. Johansen and John A.D. Aston 2016. **Toward Automatic Model Comparison: An Adaptive Sequential Monte Carlo Approach.** *Journal of Computational and Graphical Statistics*, 25(3), pp. 701–726.

Some further developments

- Approximate Bayesian computations (ABC)
 - ❑ Pierre Del Moral, Arnaud Doucet, Ajay Jasra 2012: **An adaptive sequential Monte Carlo method for approximate Bayesian computation.** *Statistics and computing*, 22(5), pp. 1009–1020.
- Use SMC sampler for unknown parameters in a state-space model
 - ❑ Nicolas Chopin, Pierre E. Jacob, Omiros Papaspiliopoulos 2013: **SMC²: An efficient algorithm for sequential analysis of state space models.** *Journal of the Royal Statistical Society: Series B*, 75(3), pp. 397–426.

A few concepts to summarize lecture 16

- SMC sampler is an alternative to MCMC
- The simulated annealing sequence is key
- The formal construction is made possible by the use of backward kernels L_k
- Loosely speaking, the SMC sampler manages (propagates, terminates and duplicates) N parallel MCMC chains