EML2322L – Design and Manufacturing Laboratory

Design Report 3R

Team 8B

Vincent Furey (1) Colton Mays (2) Cyril Moran (3)

Instructor: Sean Niemi TA: Juliana Mishur

Summer 2021

7/22/2021

Written Description

The final design was created by reviewing the designs from all group members and determining the most effective concept to solve the design challenge. This was done using a decision matrix to review the mobile platform, ball manipulator, and ball hopper subassemblies. After reviewing the decision matrix, it was decided that design 3 possessed the best attributes. The model was created using the drawings from DR1 and some changes to improve the design.

The first subsystem is the mobile platform which is framed with 80/20 aluminum extrusion. This 80/20 is the basis for the rest of the robot. The total length is 27.1 inches, height of 22.1 inches, and a width of 18.5 inches. This will allow the robot to fit in the 30x30 inch starting area. Connected to this frame is the wheel and motor assemblies. The motor is a 44 rpm Entstort Motor with 8-inch wheels attached. This combination was chosen as it provides the high level of maneuvering that is needed for the robot trajectory and positioning. It is connected using a motor mount and wheel hub. The motor mount is made of aluminum to in order to make it easier to manufacture. The motor mount is what connects to the 80/20 frame as well as the motor. The wheel hub is the connection from the motor to the actual wheel. Both the hub and mount will be manufactured using lightweight aluminum. To ensure the least amount of friction strict tolerances will be used on these parts, especially with the fasteners. The robot turns using differential steering allowing for the robot to turn with a very small radius. A caster wheel at the rear of the robot is used to balance it out as well as allow the robot to use the differential steering to turn. The motor mount is mounted on the left side of the robot and to counteract its weight one 15 lb plate from one of our home gyms will be strapped to the right side to balance out the robot.

The ball manipulator is the next subsystem. This is made up of a lever arm as well as the manipulator itself. The lever arm is 80/20 that is positioned 7 inches vertically from the mobile platform and is secured using 80/20 angle brackets. Attached to the lever arm is a 15 rpm SEI Gear Motor and its corresponding mount. The mount attaches to the 5-inch 80/20 on the lever arm as well as the motor. The motor is then connected to another piece of 80/20 which is what rotates up and down. The motor allows this arm to be rotated 90 degrees to first grab the ball at a horizontal position and then deposit it at a vertical one. The arm is one inch taller than the hopper to ensure no balls are missed or are dropped from too high. At the end of this 80/20 is the actual ball grabber that is designed out of 16-gauge sheet metal. This gauge was chosen to provide the stability and strength to grab balls. This grabber uses two arms that are 2 inches apart to secure a ball with bands of sheet metal on the bottom. The robot will use its differential steering to put the robot in a place where the grabber can

secure a ball. This ball grabber design effectively solves the design challenge of picking up tennis balls from the source tree and depositing them in the hopper for storage.

The ball hopper is what the balls are deposited into before they are released into the final bucket. It is attached to the mobile platform using 2 80/20 vertical extrusions that is then fastened to the hopper itself. The hopper is constructed using 16-gauge sheet metal to ensure it is strong enough to support all the balls. The hopper is a walled ramp that allows the balls to roll down to the release gate to wait until it is time to be deposited. The hopper is designed to hold 6 balls to fulfill the design challenge in case there is any error when depositing into the final bucket.

The release gate is connected to the back of the ball hopper by using a piece of 80/20 extruding vertically from the mobile platform. This release gate is controlled via a 15 rpm SEI Gear Motor. It is connected by welding the motor mount to the actual release gate. The clearance between the ball hopper opening and the release gate is 1 inch which secures the tennis balls until the robot is in position over the bucket. When the motor is activated the release, gate rotates downwards allowing the tennis balls to flow out into the deposit bucket. This allows for many balls to be deposited at a rapid pace into the deposit bucket.

The mobile platform, ball grabber, ball hopper, and release mechanism subsystems come together to create an effective robot to solve the design challenge. The balanced mobile platform creates a base for the other components to sit securely on. The ball grabber combined with the tight turn radius allows the robot to pickup the balls and deposit them using the lever arm. The ball hopper can hold more than enough balls to satisfy the design challenge and the release gate is able to hold the balls until it is ready to be deposited.

Project Schedule for Team 8B

Week	Task Description	Responsibility	Est. Time
	Submit DR3R Before Lab	Whole Team	-
	Submit Purchase Orders	Whole Team	-
	Welding Demonstration	Whole Team	45 min.
	Fabricate the wheel hubs for Enstort Motor (Start)	Cyril Moran	110 min.
	Fabricate motor mounts for Enstort Motor (Start)	Colton Mays	110 min.
7115/2021	Fabricate motor mount for 15 RPM SEI Motor for Lever Arm	Vincent Furey	75 min
	Fabricate wheel hub for 15 RPM SEI Motor for Release Gate	Vincent Furey	35min.
	Lab clean up	Whole Team	10 min.
	Meet outside lab to work through problems & review who's doing what next week, and prepare any necessary paperwork (POs, ECNs, etc.)	whole team	-

	Fabricate the wheel hubs for Enstort Motor (Finish)	Cyril Moran	155 min.
	Fabricate the wheel hubs for Enstort Motor (Finish)	Vincent Furey	145 min.
	Fabricate motor mounts for Enstort Motor (Finish)	Colton Mays	45 min.
7/21/2021	Fabricate motor mount for Release Gate (Start)	Vincent Furey	10 min.
1	Fabricate the Ball Hopper	Colton Mays	70 min.
	Fabricate the Release Gate	Colton Mays	40 min.
	Lab Clean up	Whole Team	10 min.
	Meet outside lab to work through problems & review who's doing what next week, and prepare any necessary paperwork (POs, ECNs, etc.)	whole team	-

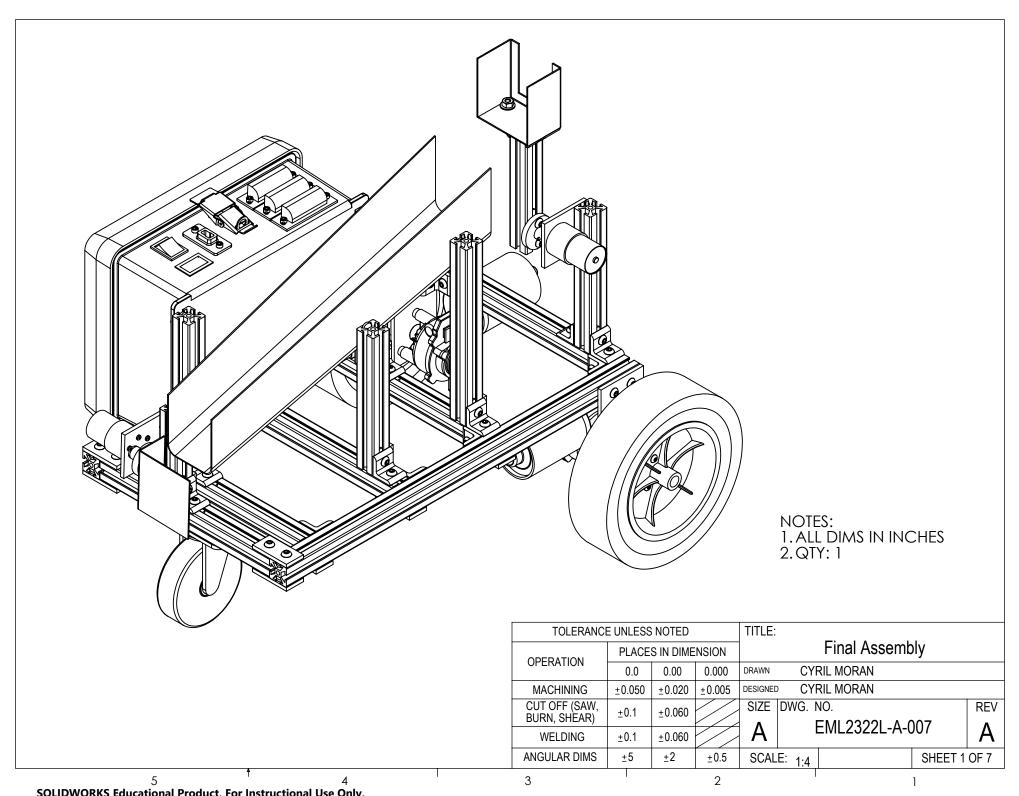
	-		
	Fabricate the Ball Manipulator sheetmetal part	Cyril Moran	60 min.
	Assemble the Ball Manipulator	Cyril Moran	30 min.
	Fabricate wheel hub for 15 RPM SEI Motor for Lever Arm	Colton Mays	55 min.
	Assemble the Mobile Platform by cutting and fastening all of the 80/20 and attatching the control box	Colton Mays	100 min.
	Assemble the Lever Arm by attaching the motor mount, wheel hub, the caster wheel, and 15 RPM SEI Motor to 80/20 and the Mobile Platform	Cyril Moran	65 min.
7/29/2021	Attach the wheel hub, motor mount, wheels, and Enstort Motors to the Mobile Platform	Vincent Furey	30 min.
	Attach the Ball Hopper to the Mobile Platform	Vincent Furey	45 min.
	Fabricate motor mount for Release Gate (Finish)	Vincent Furey	40 min.
	Assemble the Release Gate Mechanism by attatching the motor mount, wheel hub, and 15 RPM SEI Motor to the Release Gate and 80/20 support	Vincent Furey	40 min.
	Lab clean up	Whole Team	10 min.
	Meet outside lab to work through problems & review who's doing what next week, and prepare any necessary paperwork (POs, ECNs, etc.)	Whole Team	-

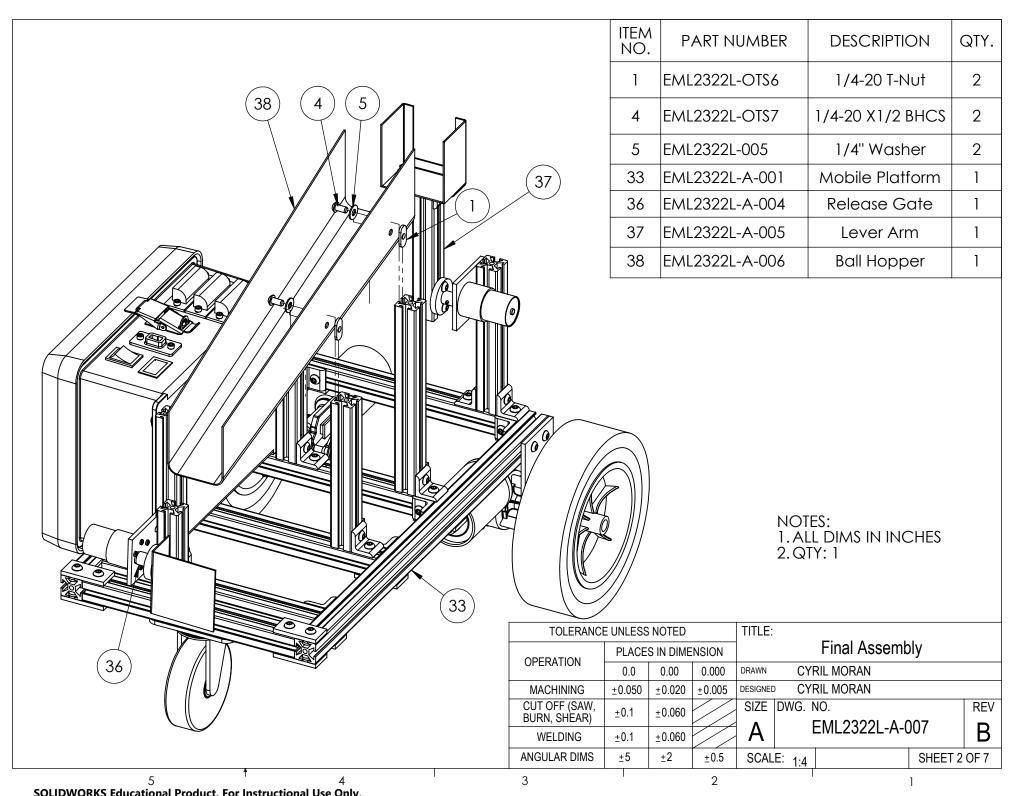
	Attach the Release gate Mechanism to the Mobile Platform	Cyril Moran	30 min.
	Attatch Ball Manipulator to Lever Arm	Colton Mays	30 min.
8/5/2021	Check all of the fasteners to ensure safety during testing	Vincent Furey	30 min.
	Testing	Whole Team	125 min.
	Lab clean up	Whole Team	10 min.
	Meet outside lab to work through problems and troubleshoot issues found during tesing.	Whole Team	-

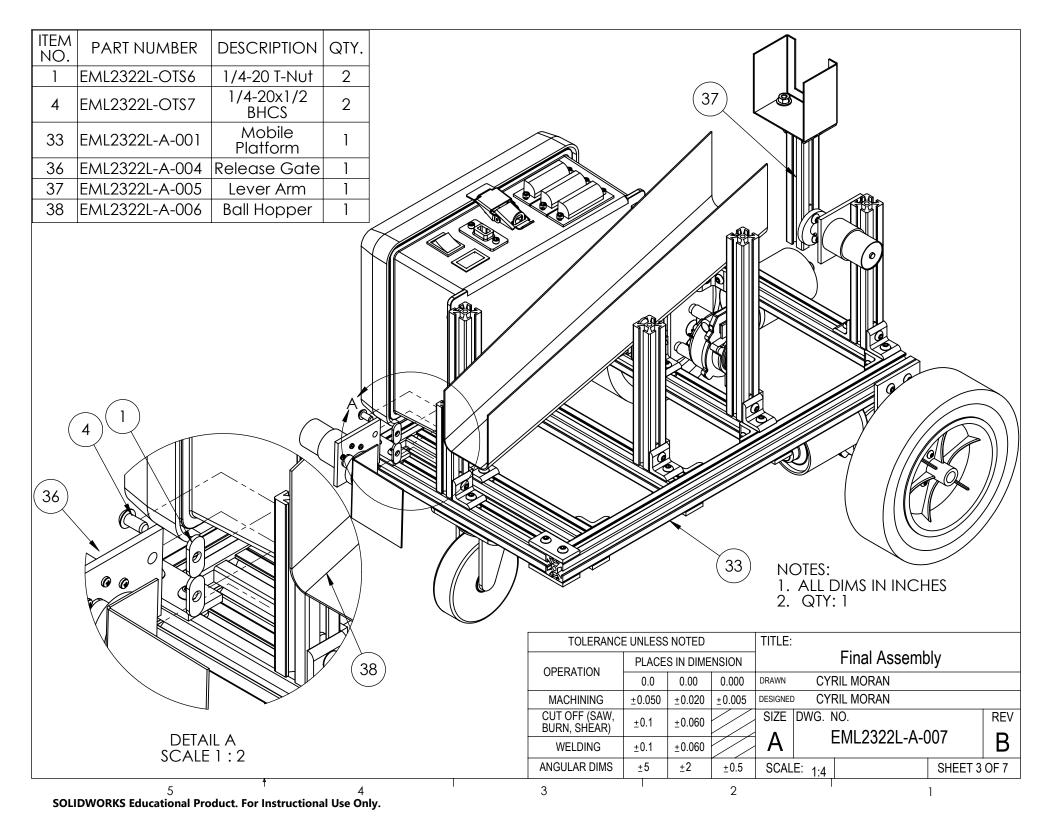
8/12/2021	Competition Day	Whole Team	155 min.
6/12/2021	Lab clean up	Whole Team	10 min.

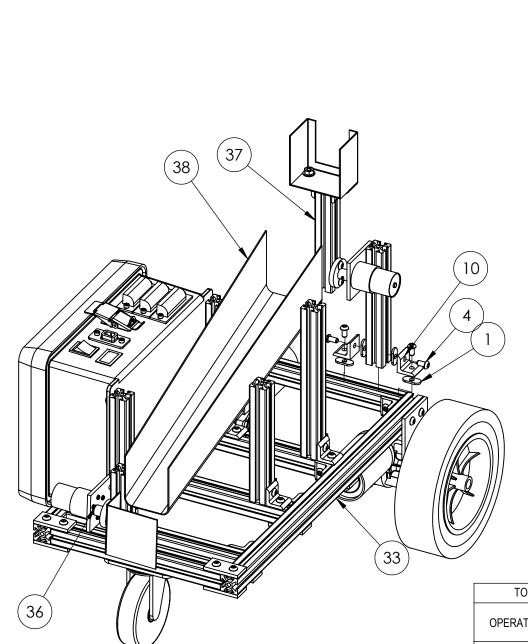
Complete BOM for Team 8B

Item No.	Part Number	Decription	Qty.
1	EML2322L-OTS-6	1/4-20 T-Nut	70
2	EML2322L-OTS1	Control Box	1
3	EML2322L-OTS20	5" Caster Wheel	1
4	EML2322L-OTS-7	1/4-20 x 1/2 inch BHCS	86
5	EML2322L-005	1/4" Washer	6
7	EML2322L-007	80-20 Extrusion, 20.9"	2
8	EML2322L-008	80-20 Extrusion, 10.0"	5
9	EML2322L-OTS-13	80/20 Straight Bracket	17
10	EML2322L-OTS-12	80/20 90 Degree Angle Bracket	17
11	EML2322-011	80-20 Extrusion 7.8"	2
12	EML2322-OTS-22	8" Wheel Type 1	2
13	EML2322L-013	Entstort Wheel Hub	2
14	EML2322L-014	10-24 1inch Button Head Screw	6
15	EML2322L-OTS-31	44 RPM Entstort Right Angle Gear Motor	2
16	EML2322L-016	Entstort Motor Mount	2
17	EML2322L-017	M6-20mm Hex Head Screw	6
18	EML2322L-018	M8 x 1.25 Hex Nut	2
19	EML2322L-019	M3 X 10mm Screw	8
20	EML2322L-OTS-29	15 RPM SEI Gear Motor	2
21	EML2322L-021	80-20 Extrusion 7.0"	2
22	EML2322L-022	80-20 Extrusion 6.5"	1
23	EML2322L-023	15 RPM SEI Gear Motor Mount	2
24	EML2322L-024	15 RPM SEI Gear Wheel Hub Lever Arm	1
25	EML2322L-025	Ball Grabber	1
26	EML2322L-026	1/4-20 Hex Nut	2
27	EML2322L-027	1/4-20 X 3/8" BHCS	4
28	EML2322L-028	80-20 Extrusion 9"	1
29	EML2322L-029	Ball Hopper Part	1
30	EML23221L-030	4-40 1/4" Set Screw	2
31	EML2322L-031	15 RPM SEI Gear Motor Hub Release Gate	1
32	EML2322L-032	Release Gate Part	1
33	EML2322L-A-001	Mobile Platform	1
34	EML2322L-A-002	Drive Assembly	2
35	EML2322-A-003	Frame Assembly	1
36	EML2322L-A-004	Release Gate	1
37	EML2322L-A-005	Lever Arm	1
38	EML2322L-A-006	Ball Hopper	1
39	EML2322L-A-007	Final Assembly	1



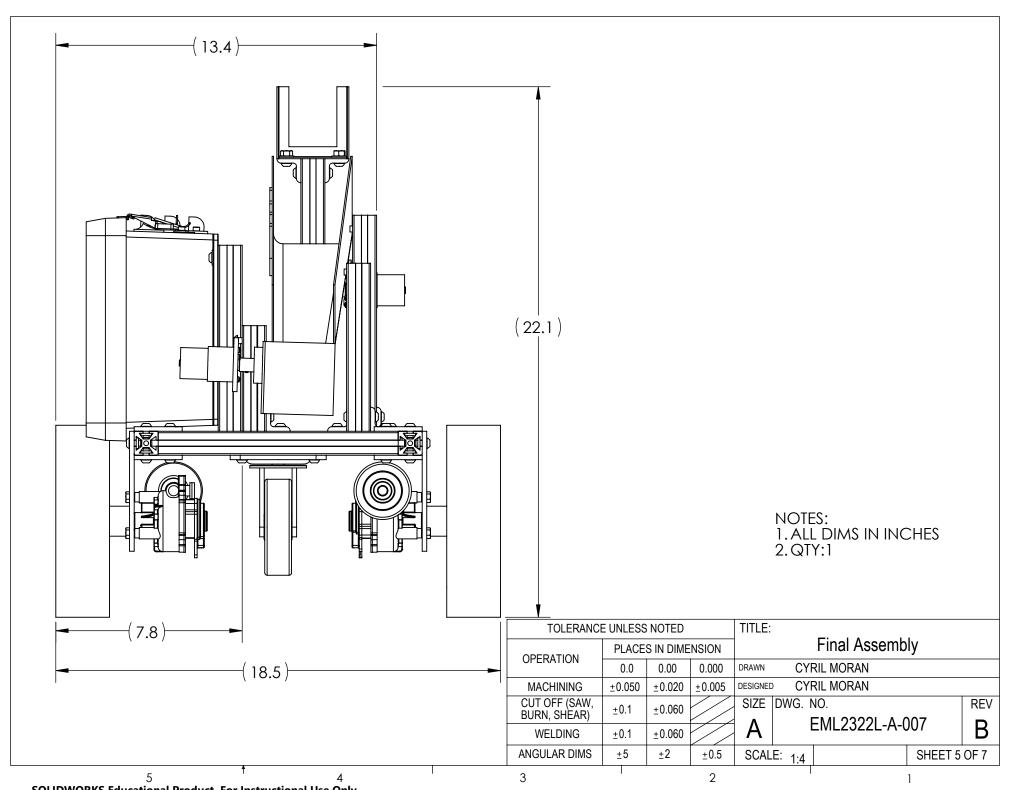


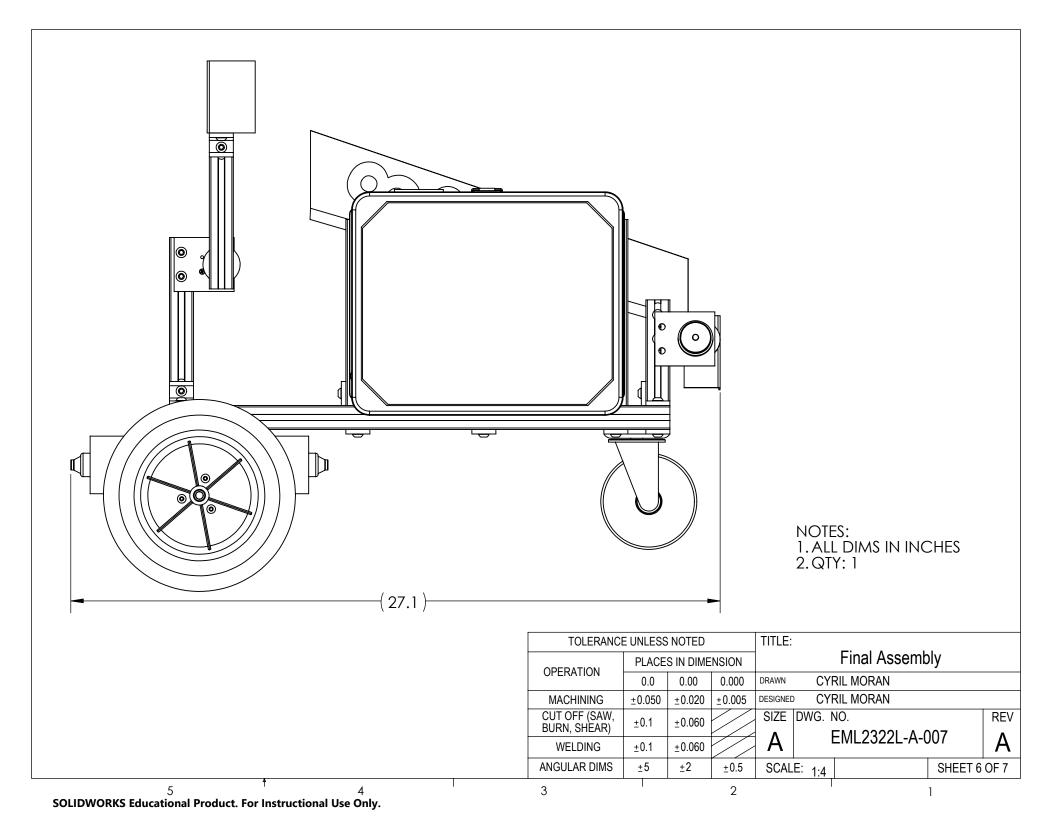


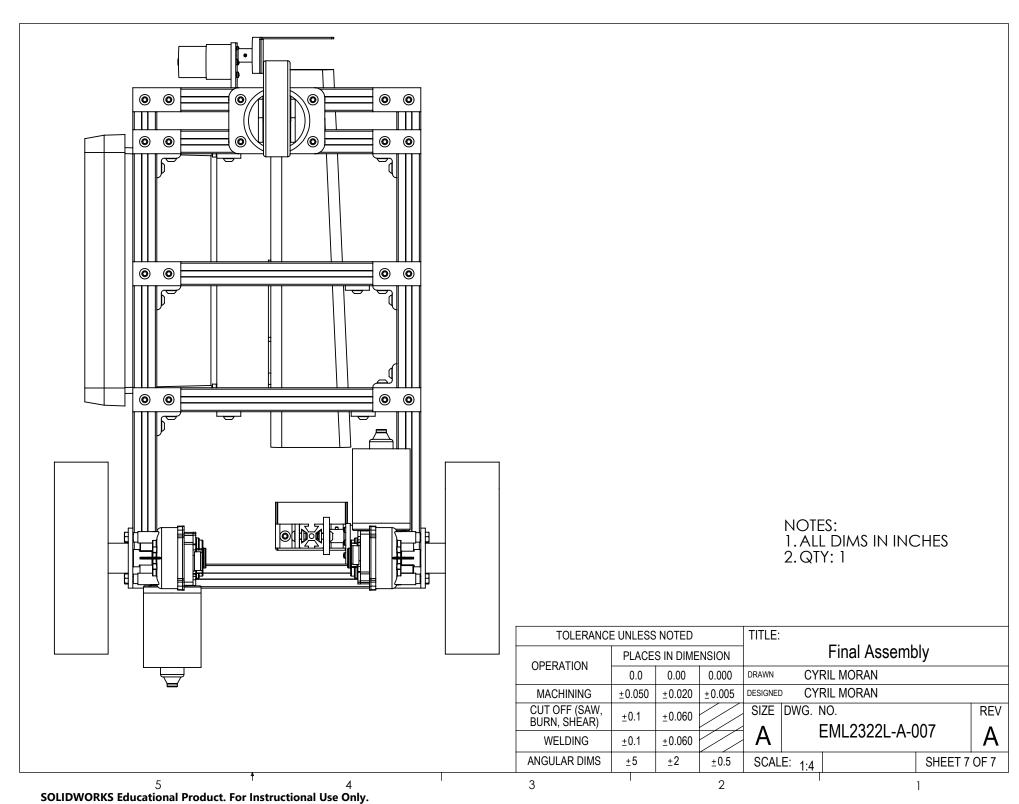


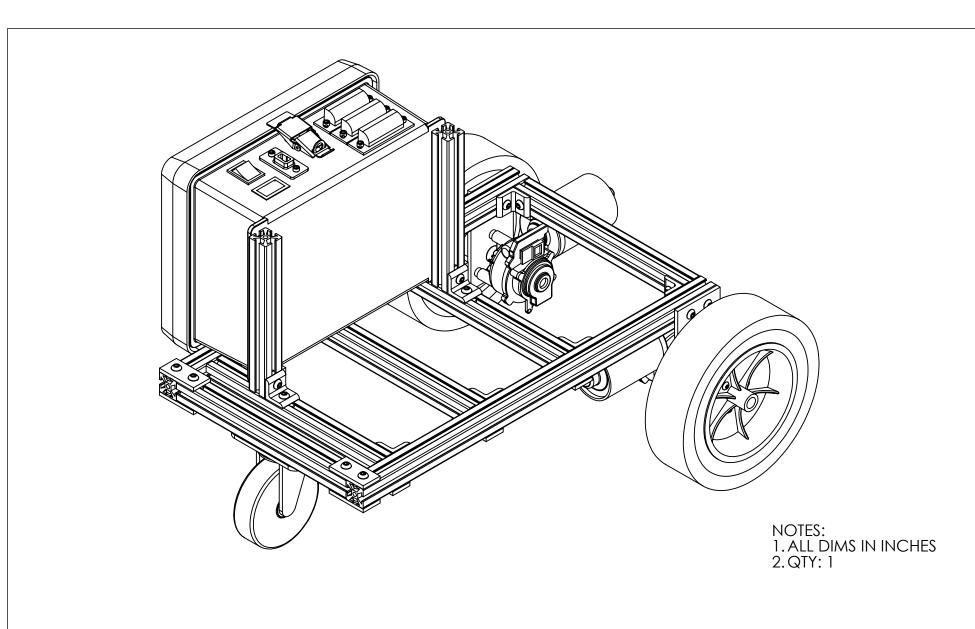
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4	EML2322L-OTS7	1/4-20 X1/2 BHCS	4
10	EML2322L-OT\$12	80/20 90 Degree Angle Bracket	2
33	EML2322L-A-001	Mobile Platform	1
36	EML2322L-A-004	Release Gate	1
37	EML2322L-A-005	Lever Arm	1
38	EML2322L-A-006	Ball Hopper	1

	TOLERANCE		TITLE:							
Ì	OPERATION PLACES IN DIMENSION					Final Asse	emb	oly		
	OPERATION 0.0		0.00	0.000	DRAWN	CYI	RIL MORAN			
	MACHINING	±0.050	±0.020	±0.005	DESIGNED	CYI	RIL MORAN			
	CUT OFF (SAW, BURN, SHEAR)	±0.1	±0.060		SIZE	DWG. 1	_	۸ (107	REV
Ī	WELDING	±0.1	±0.060		Α	I	EML2322L-	A-U	107	В
	ANGULAR DIMS	±5	<u>+</u> 2	±0.5	SCAL	E: 1:4			SHEET 4	OF 7



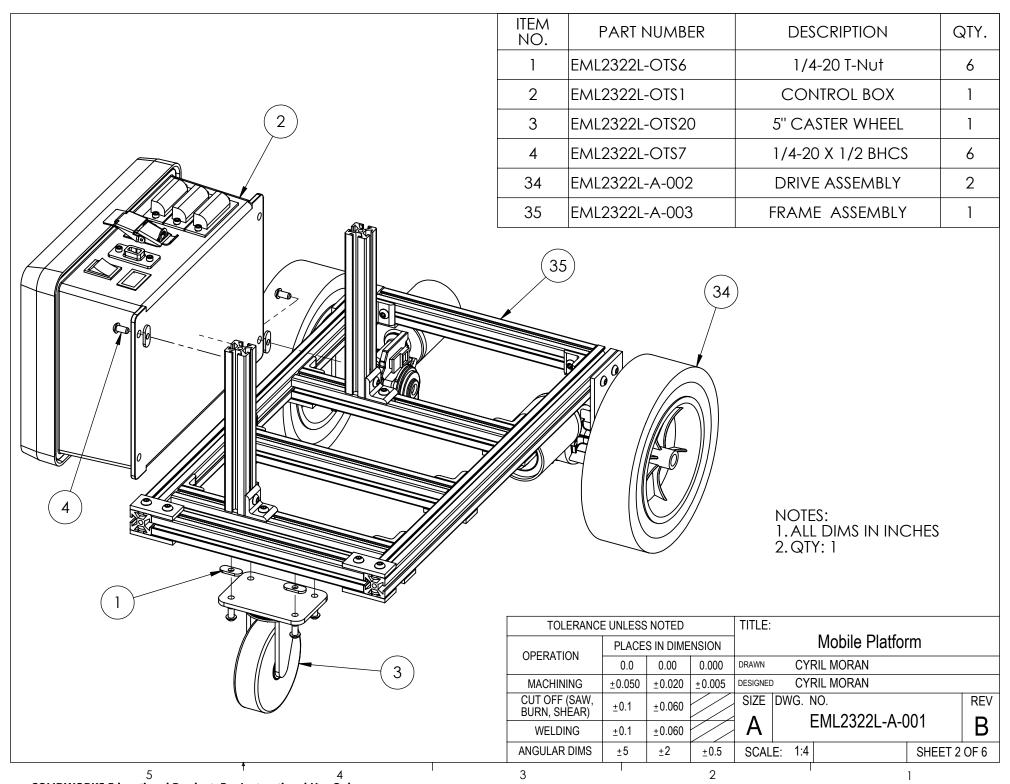


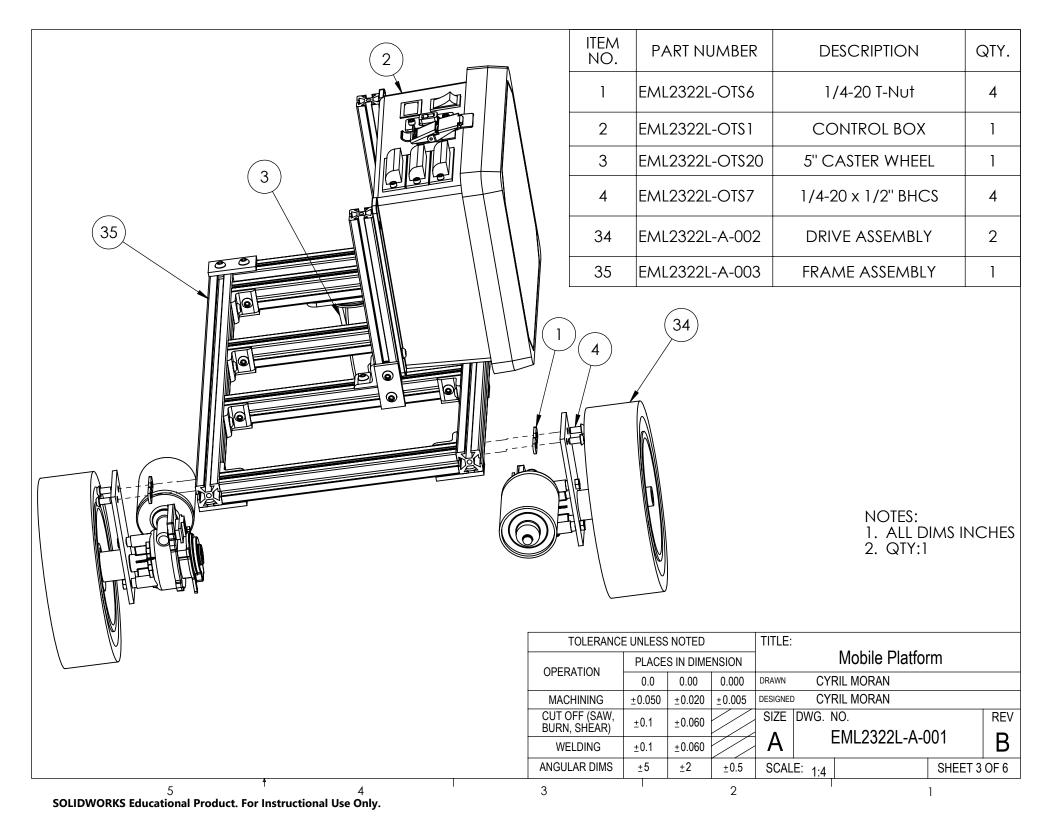


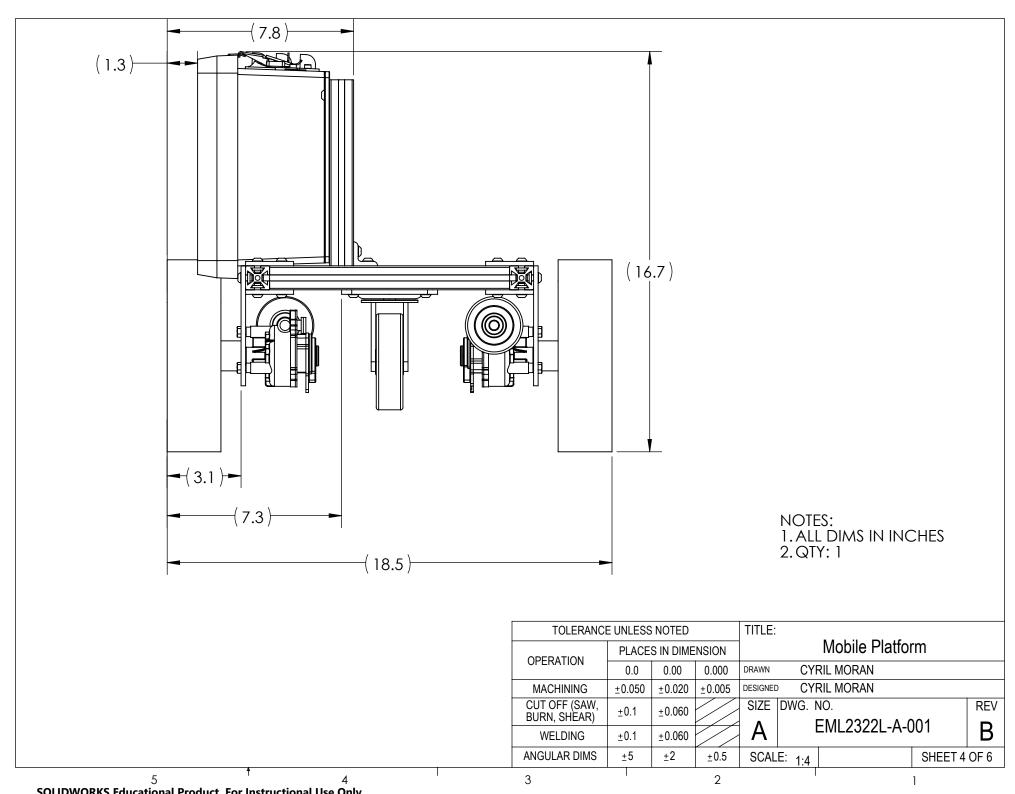


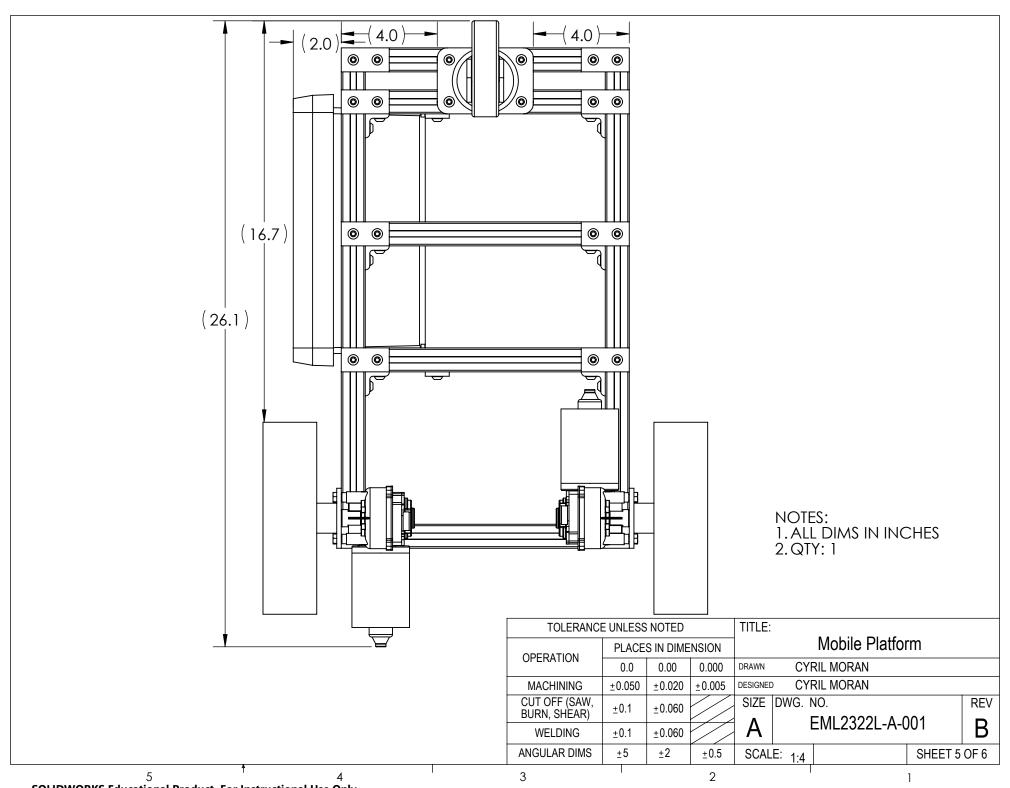
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MACHINING	±0.050	±0.020	±0.005	DESIGNED	Cyr	il Moran		
CUT OFF (SAW, BURN, SHEAR)	±0.1	±0.060		SIZE	DWG. 1	NO. EML2322L-A -	001	REV
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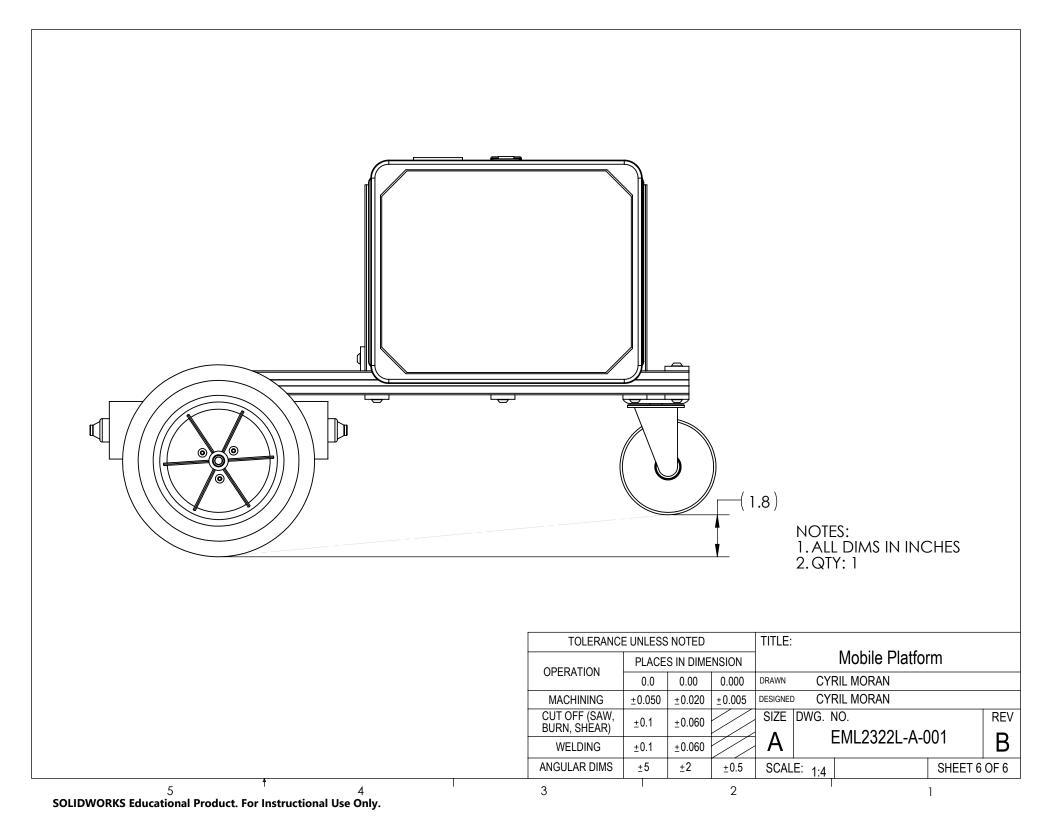
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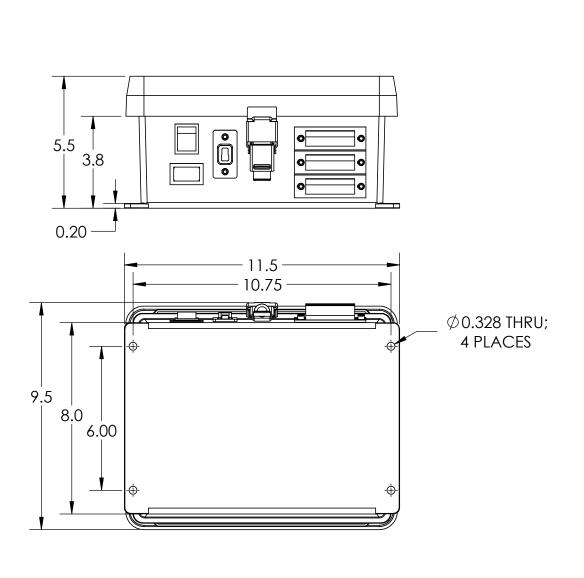


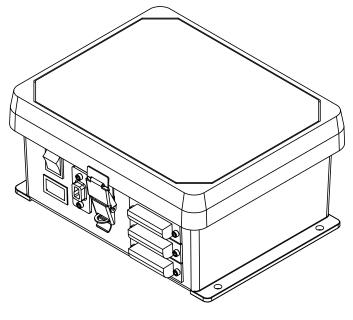












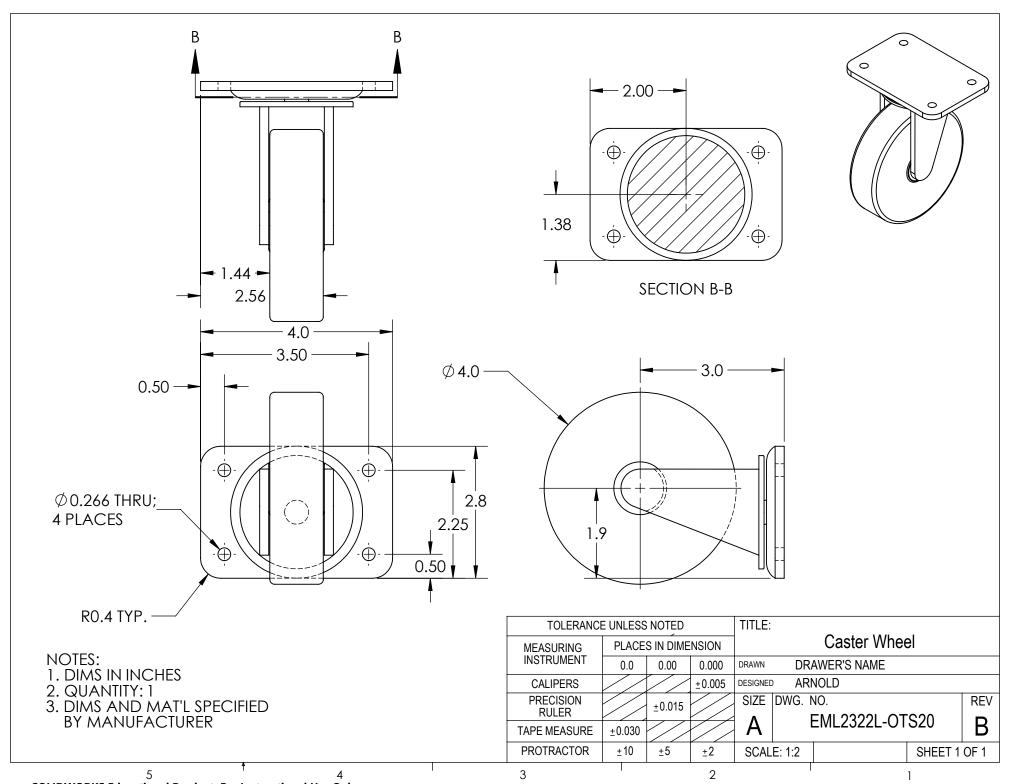
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 2. QTY SPECIFIED IN BOM
 3. DIM AND MAT'L SPECIFIED
 BY MANUFACTURER

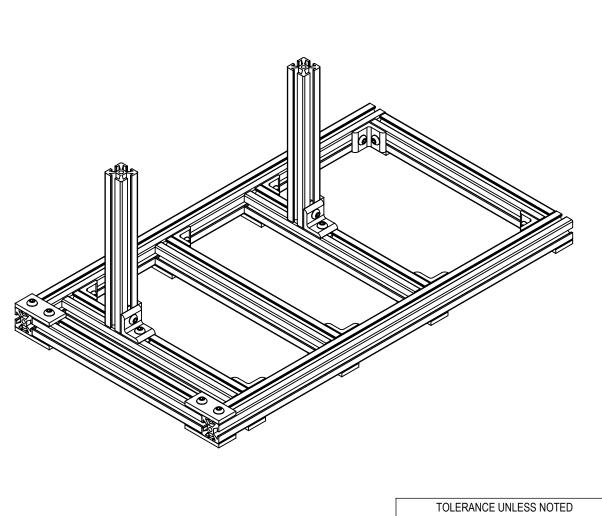
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	PRECISION RULER		±0.015		_	DWG. 1		TO 4	REV
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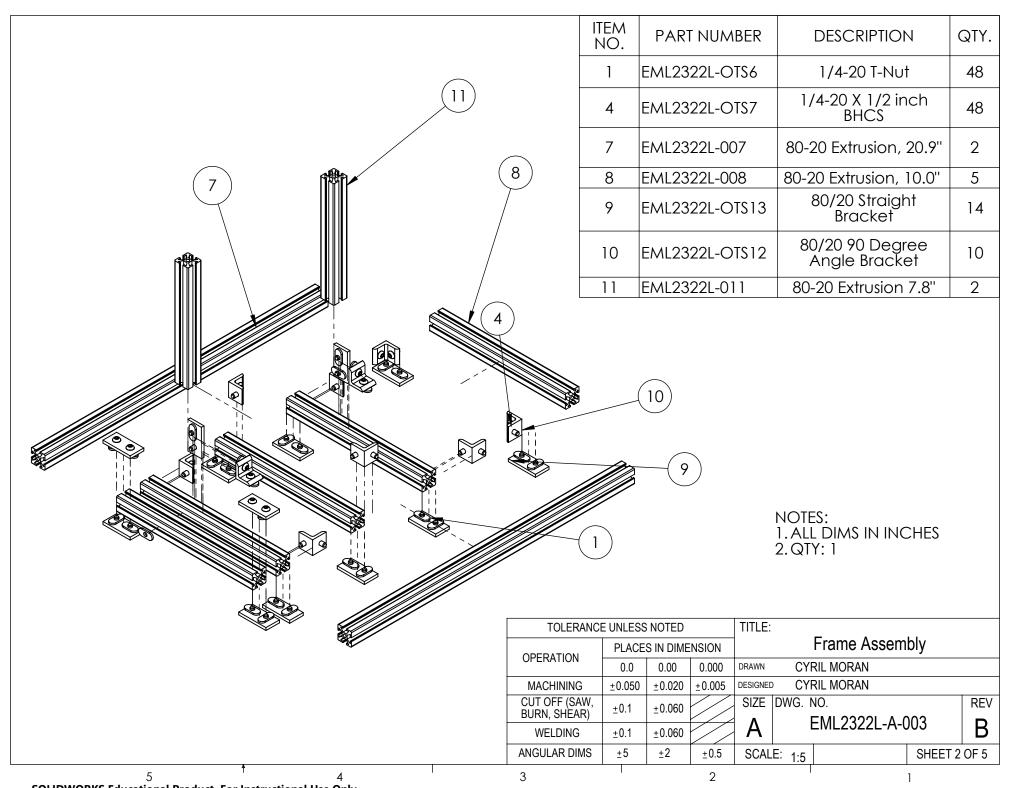
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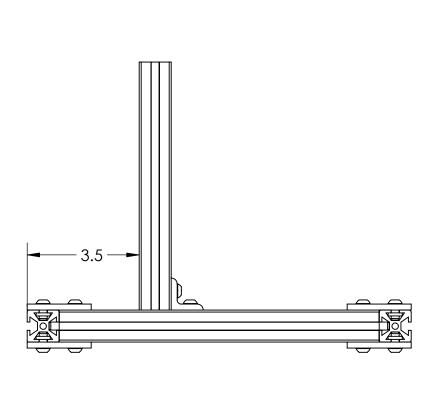




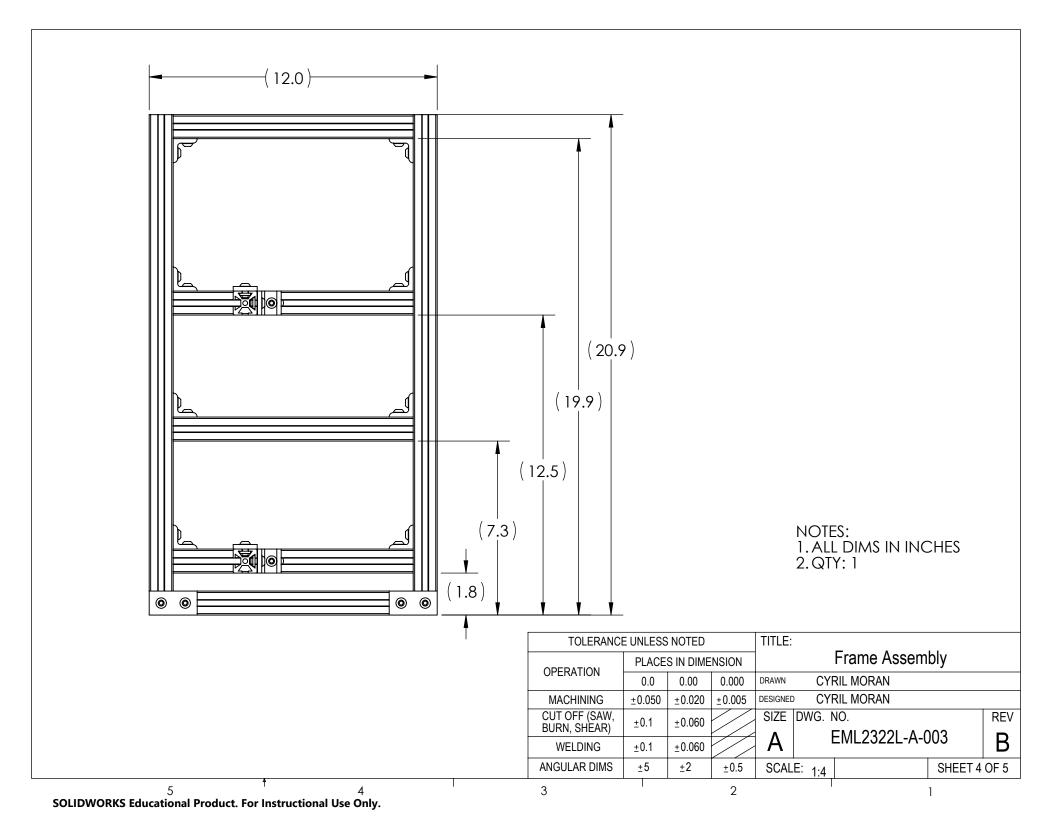
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Ī	MACHINING	±0.050	±0.020	±0.005	DESIGNED	CYI	RIL MORAN		
	CUT OFF (SAW, BURN, SHEAR)	±0.1	±0.060		SIZE	DWG. 1	_	003	REV
Ī	WELDING	±0.1	±0.060		Α	l	EML2322L-A	-003	В
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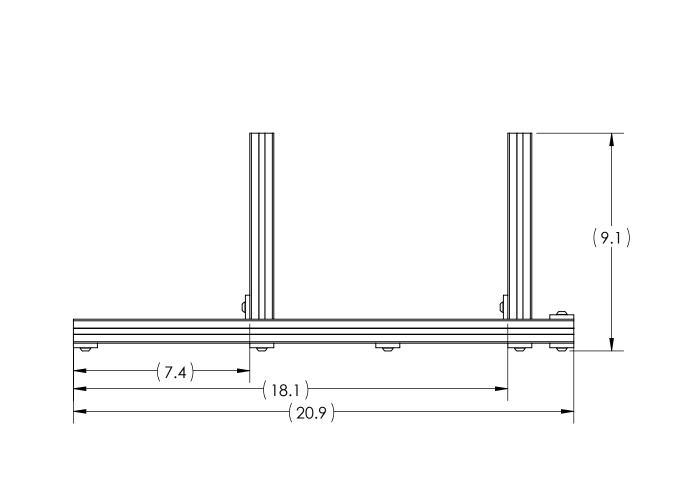
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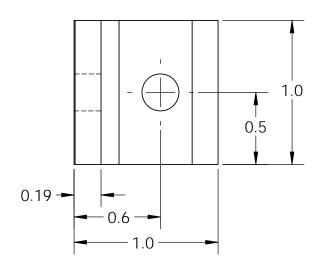
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OPERATION PLACES IN DIMENSION					Frame Ass	sem	bly			
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MAC	CHINING	±0.050	±0.020	±0.005	DESIGNED	CYI	RIL MORAN			
	OFF (SAW, I, SHEAR)	±0.1	±0.060		SIZE	DWG. I	_	۸ (າດວ	REV
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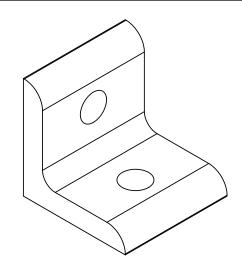


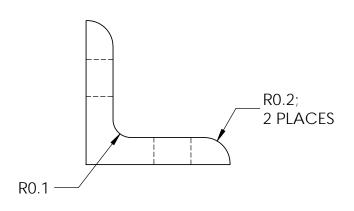


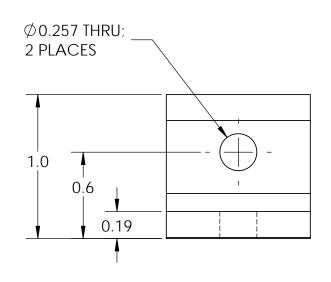
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Ī	MACHINING	±0.050	±0.020	±0.005	DESIGNED	CYI	RIL MORAN		
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	WELDING	±0.1	±0.060		Α	l	EIVILZ3ZZL-A	-003	В
	ANGULAR DIMS	±5	<u>+</u> 2	±0.5	SCAL	E: 1:4		SHEET 5	OF 5

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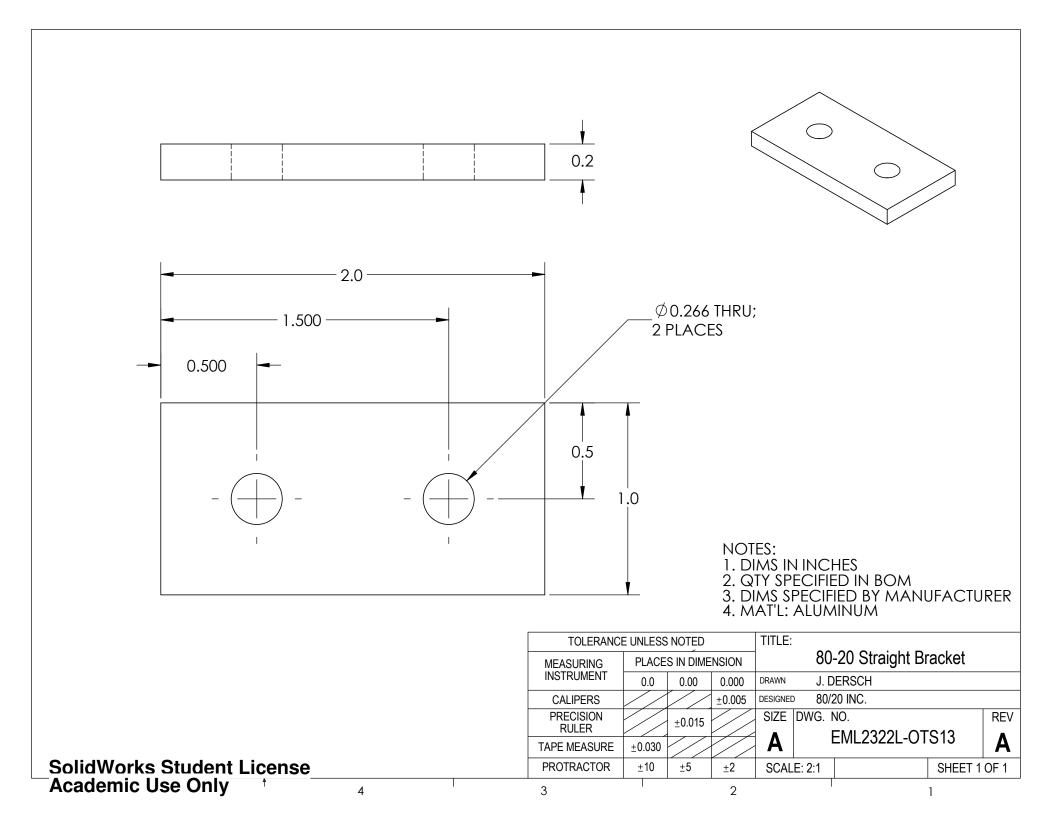


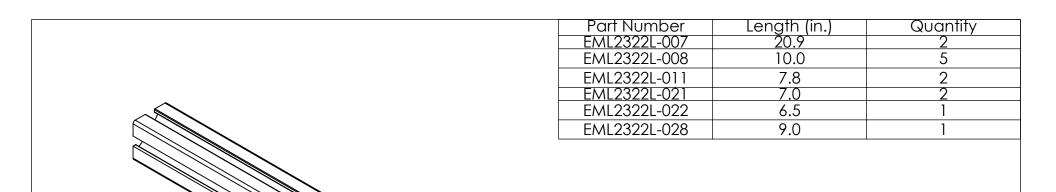


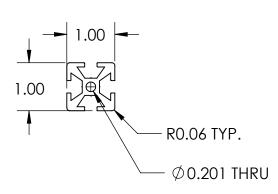


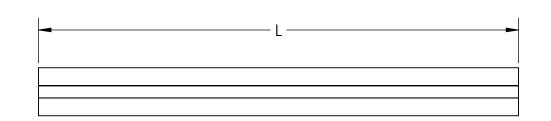
- NOTES:
 1. DIMS IN INCHES
 2. QTY SPECIFIED IN BOM
 3. DIMS SPECIFIED BY MANUFACTURER
- 4. MAT'L: ALUMINUM

TOLERANCI	E UNLESS	NOTED		TITLE:				
MEASURING	PLACE	S IN DIME	NSION	8	0/20 9	00 Degree An	gle Brack	et
INSTRUMENT 0.0 0.00 0.000 DRAW					J. D	ERSCH		
CALIPERS			±0.005	DESIGNED	80/2	20 INC.		
PRECISION		±0.015		SIZE	DWG. 1	VO.		REV
RULER TAPE MEASURE	+0.030			Δ		EML2322L-O	TS12	Δ
TAPE WEASURE	±0.030			<i>,</i> ,				/ \
PROTRACTOR	±10	±5	±2	SCAL	E: 1.5:1		SHEET 1	OF 1



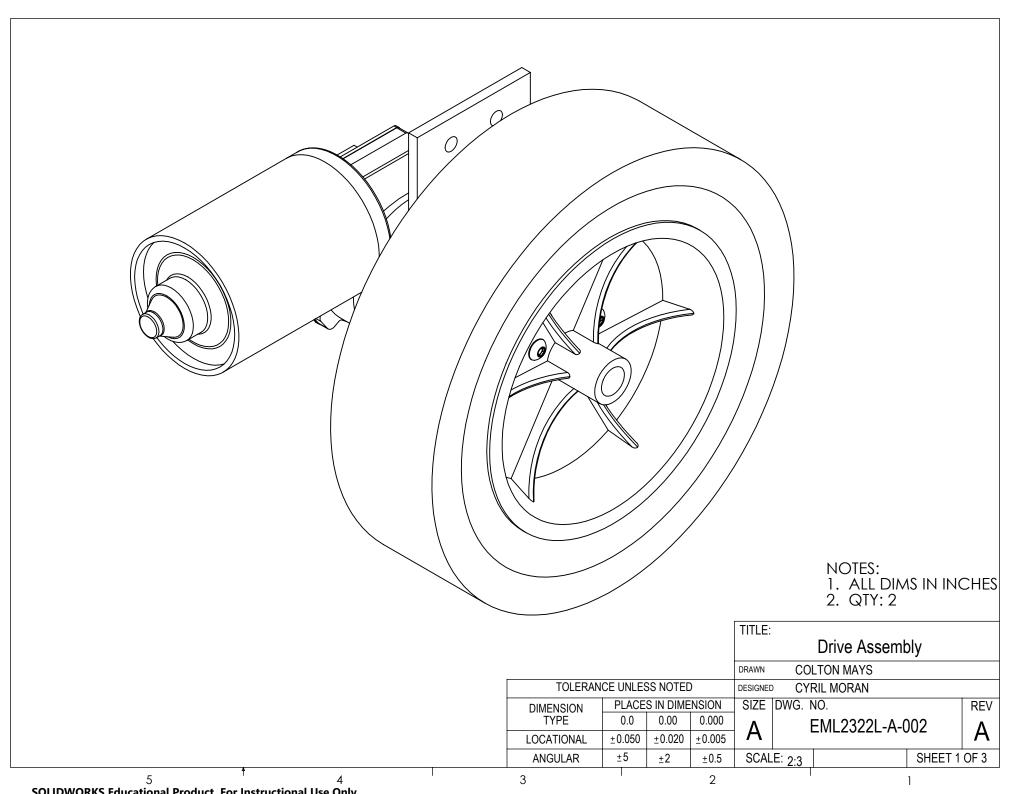


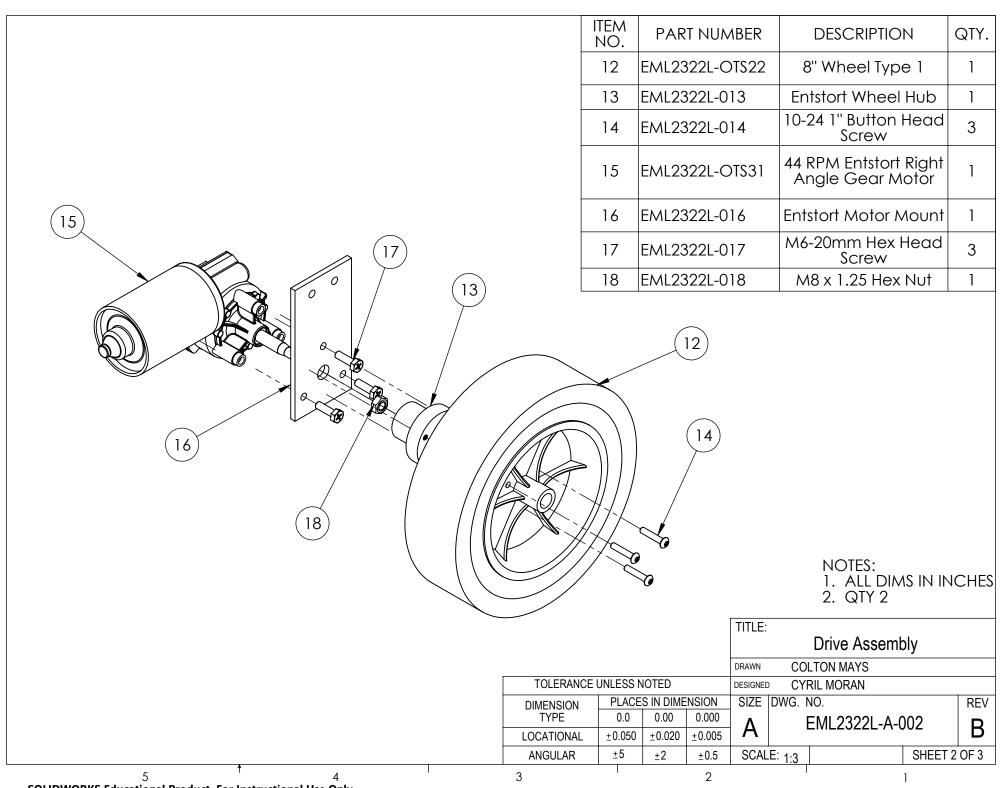


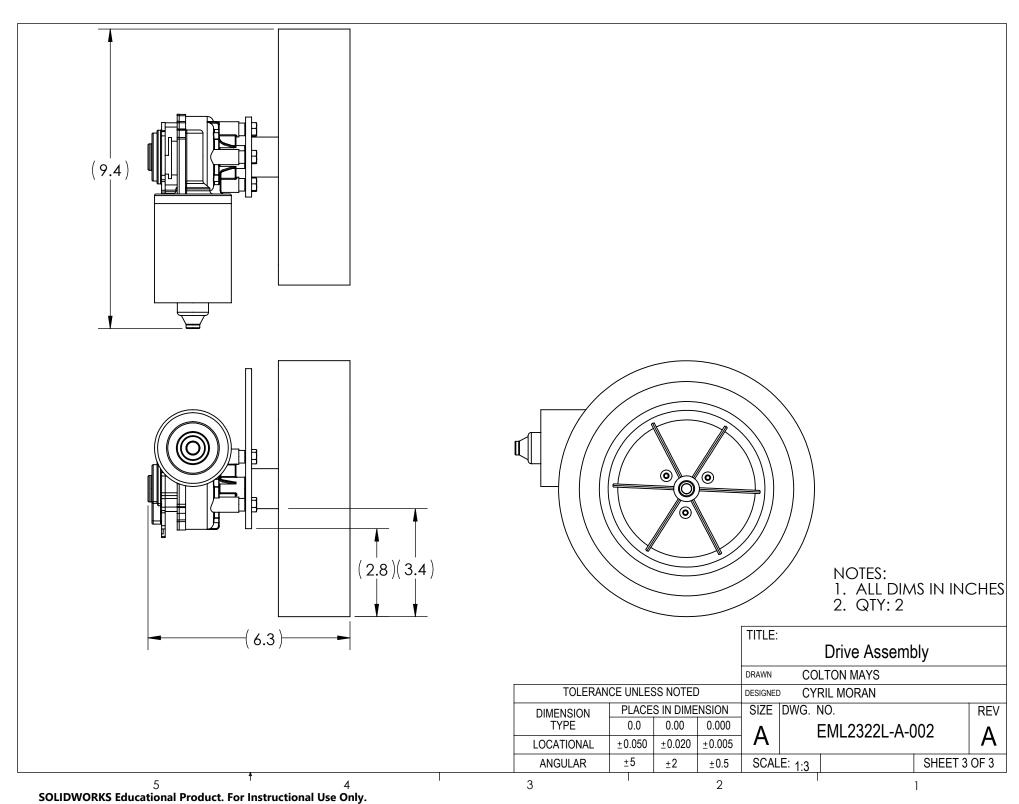


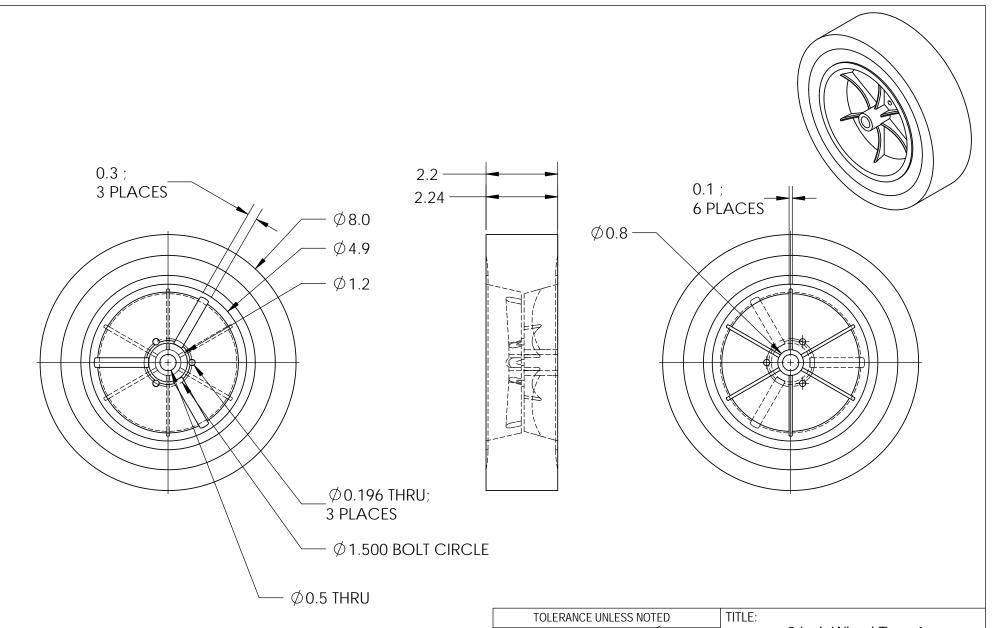
- 1. DIMS IN INCHES
- 2. MAT'L: 80/20 AL EXTRUSION
- 3. BREAK CUT ENDS
- 4. FINISH NO SURFACES
- 5. QTY SPECIFIED IN TABLE
- 6. USE CUT OFF TOLERANCES

	TOLERANCE UNLESS NOTED								
	OPERATION	PLACE	S IN DIME	NSION		80/20	DExtrusion (sii	mplified)	
	OPERATION	0.0	0.00	0.000	DRAWN	DR	AWER'S NAME		
	MACHINING	±0.050	±0.020	±0.005	DESIGNED	I. W	/IDJAJA		
	CUT OFF (SAW, BURN, SHEAR)	±0.1	±0.060		SIZE	DWG. N	_	•	REV
ŀ	WELDING	±0.1	±0.060		Α	ŀ	EML2322L-00	0	В
	ANGULAR DIMS	±5	<u>+</u> 2	±0.5	SCALE: 1:2			SHEET 1	OF 1









- 1. DIMS IN INCHES
- 2. QTY SPECIFIED IN BOM
- 3. DIMS AND MAT'L SPECIFIED BY MANUFACTURER

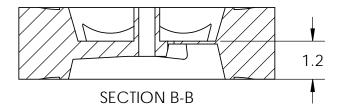
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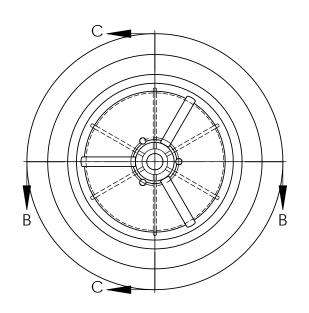
TOLERANCI	E UNLESS		TITLE:						
MEASURING	PLACE	S IN DIME	NSION	8 Inch Wheel Type 1					
INSTRUMENT	0.0	0.00	0.000	DRAWN J. DERSCH					
CALIPERS			±0.005	DESIGNED	ARI	VOLD			
PRECISION RULER		±0.015		SIZE	DWG. N				REV
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THE MERIOURE	_0.000					T			<i>,</i> ,
PROTRACTOR	±10	±5	±2	SCAL	.E: 1:3			SHEET 1	OF 2

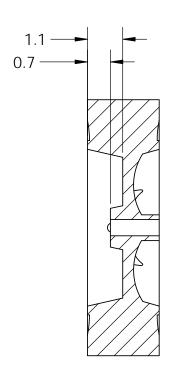
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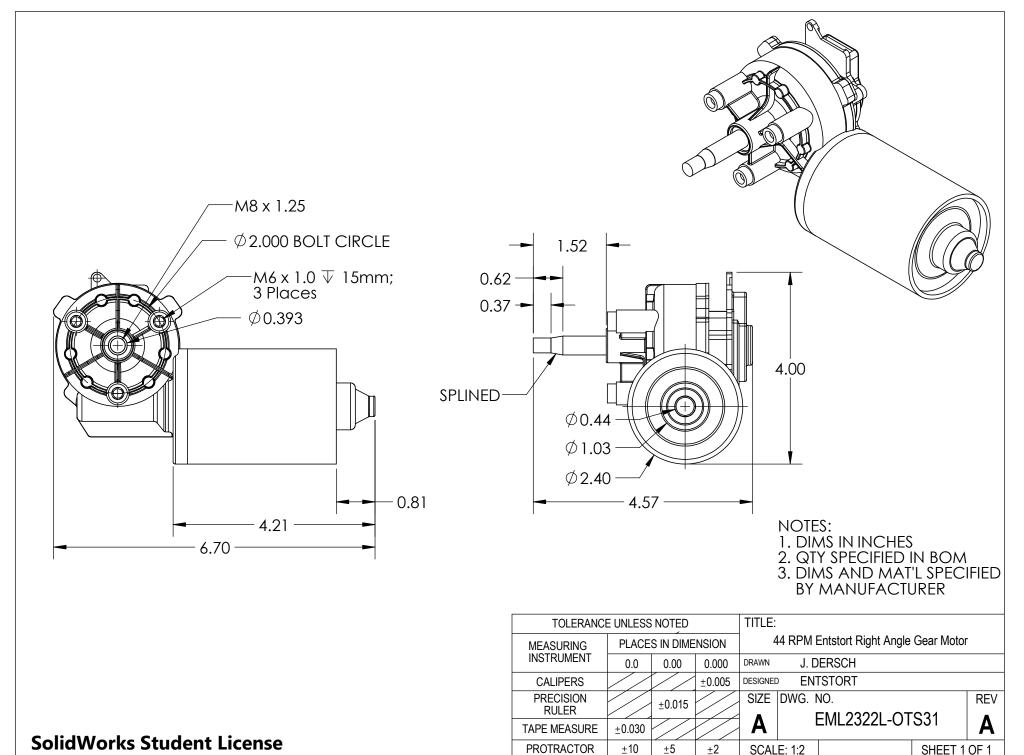


SECTION C-C

- 1. DIMS IN INCHES
- 2. QTY SPECIFIED IN BOM
 3. DIMS AND MAT'L SPECIFIED
 BY MANUFACTURER

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	TOLERANCE UNLESS NOTED											
Ī	MEASURING	PLACE	S IN DIME	NSION		8	Inch Wheel Ty	ype 1	: 1			
	INSTRUMENT	0.0	0.00	0.000	DRAWN	J. D	DERSCH					
	CALIPERS			±0.005	DESIGNED	AR	NOLD					
	PRECISION		±0.015		SIZE	DWG. I	NO.		REV			
ļ	KULEK				Λ		EN/I 33331 - 1	Γ C22	Λ			
	TAPE MEASURE	±0.030			Α		LIVILZJZZL-O I	JZZ	Α			
	PROTRACTOR	±10	±5	±2	SCAL	E: 1:3		SHEET 2	OF 2			
	PRECISION RULER TAPE MEASURE				SIZE	DWG. I			F			

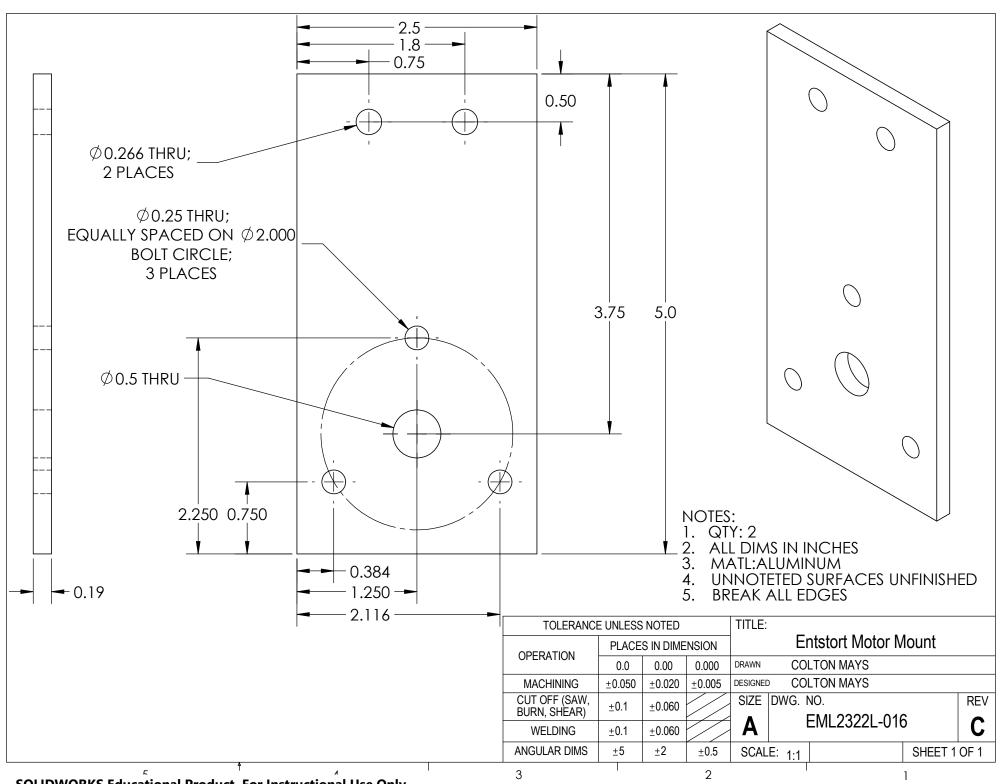


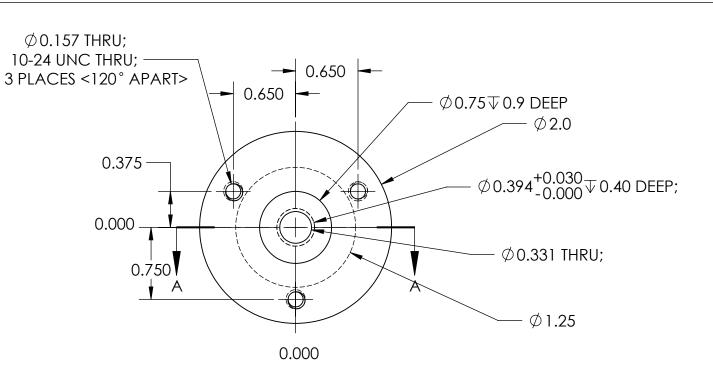
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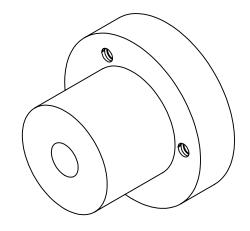
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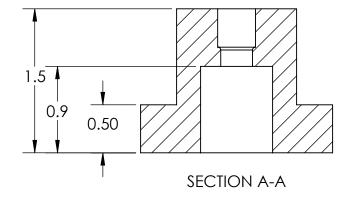
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SHEET 1 OF 1









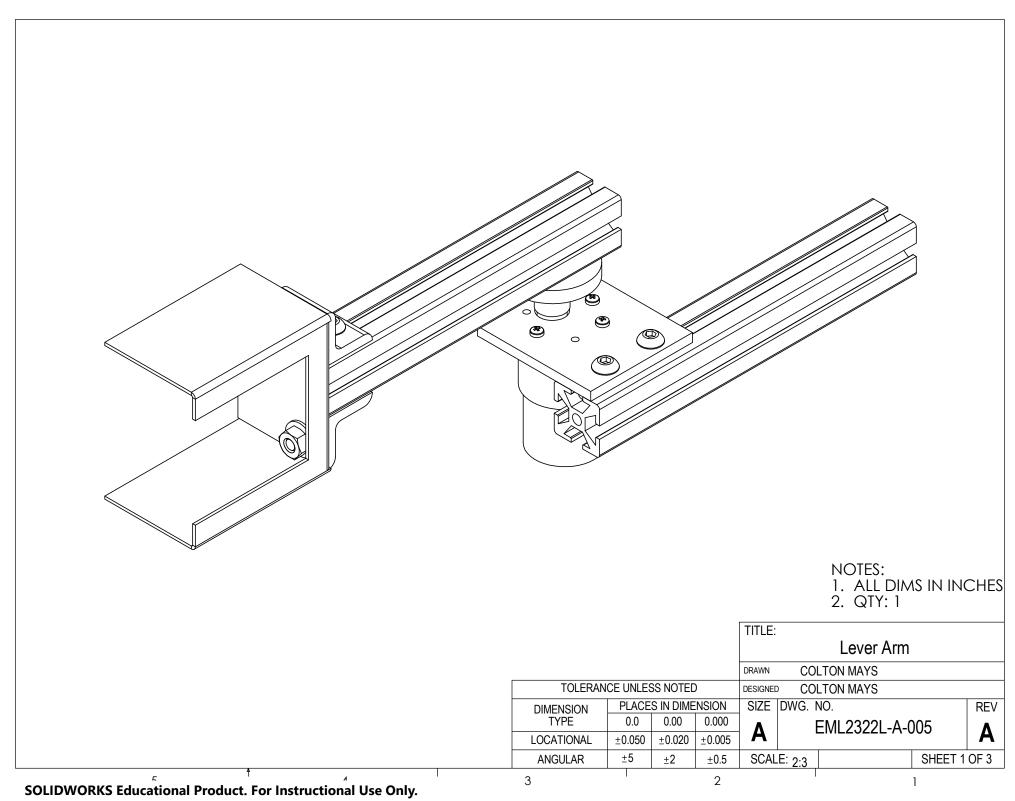
1. DIMS IN INCHES
2. QUANTITY: 1
3. MAT'L ALUMINUM

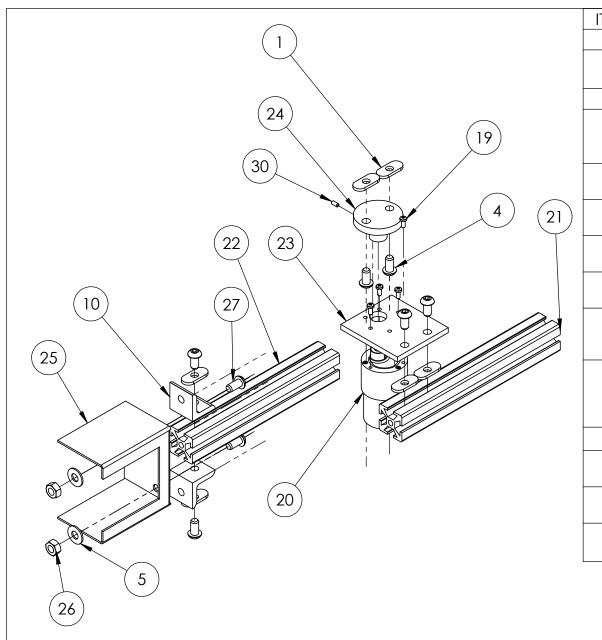
4. BREAK ALL EDGES 5. FINISH NOTES SURFACES

TOLERANCI		TITLE:						
OPERATION	PLACE	S IN DIME	NSION		E	Intstort Wheel	Hub	
OPERATION	0.0	0.00	0.000	DRAWN	CYI	RIL MORAN		
MACHINING	±0.050	±0.020	±0.005	DESIGNED	CYI	RIL MORAN		
CUT OFF (SAW, BURN, SHEAR)	±0.1	±0.060		SIZE	DWG. 1	NO. EML2322L-01	2	REV
WELDING	±0.1	±0.060		Α		EIVILZ3ZZL-U I	S	
ANGULAR DIMS	±5	<u>+</u> 2	±0.5	SCAL	E: 1:1		SHEET 1	OF 1

3

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ITEM NO.	PART NUMBER	DESCRIPTION	QTY.
1	EML2322L-OTS6	1/4-20 T-Nut	6
4	EML2322L-OTS7	1/4-20 x1/2" BHCS	6
5	EML2322L-005	1/4" Washer	2
10	EML2322L-OTS12	80/20 90 Degree Angle Bracket	2
19	EML2322L-019	M3 X 10mm Screw	4
20	EML2322L-OTS29	15 RPM SEI Gear Motor	1
21	EML2322L-021	80-20 Extrusion. 7.0"	1
22	EML2322L-022	80-20 Extrusion, 6.5"	1
23	EML2322L-023	15RPM SEI Gear Motor Mount	1
24	EML2322L-024	15 RPM SEI Gear Wheel Hub Lever Arm	1
25	EML2322L-025	Ball Grabber	1
26	EML2322L-026	1/4-20 Hex Nut	2
27	EML2322L-027	1/4-20 X 3/8" BHCS	2
30	EML2322L-030	4-40 1/4" Set Screw	1

NOTES:
1. ALL DIMS IN INCHES
2. QTY: 1

DRAWN COLTON MAYS

DESIGNED COLTON MAYS

SIZE DWG. NO. REV

A EML2322L-A-005

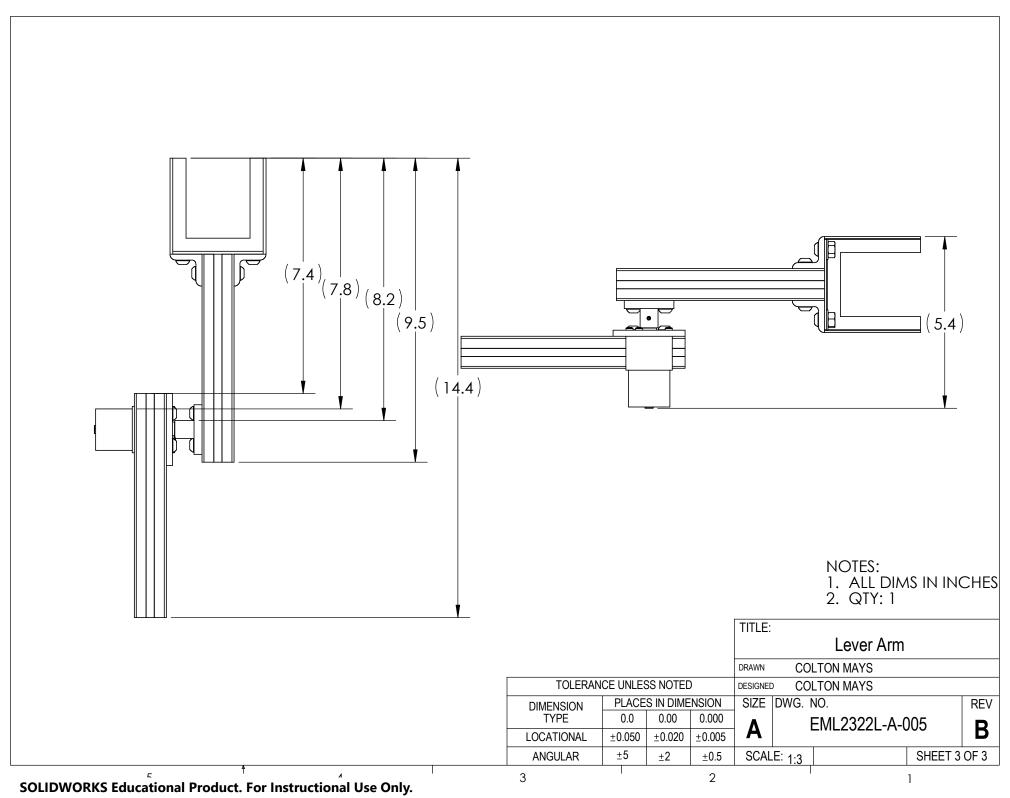
SCALE: 1:3 SHEET 2 OF 3

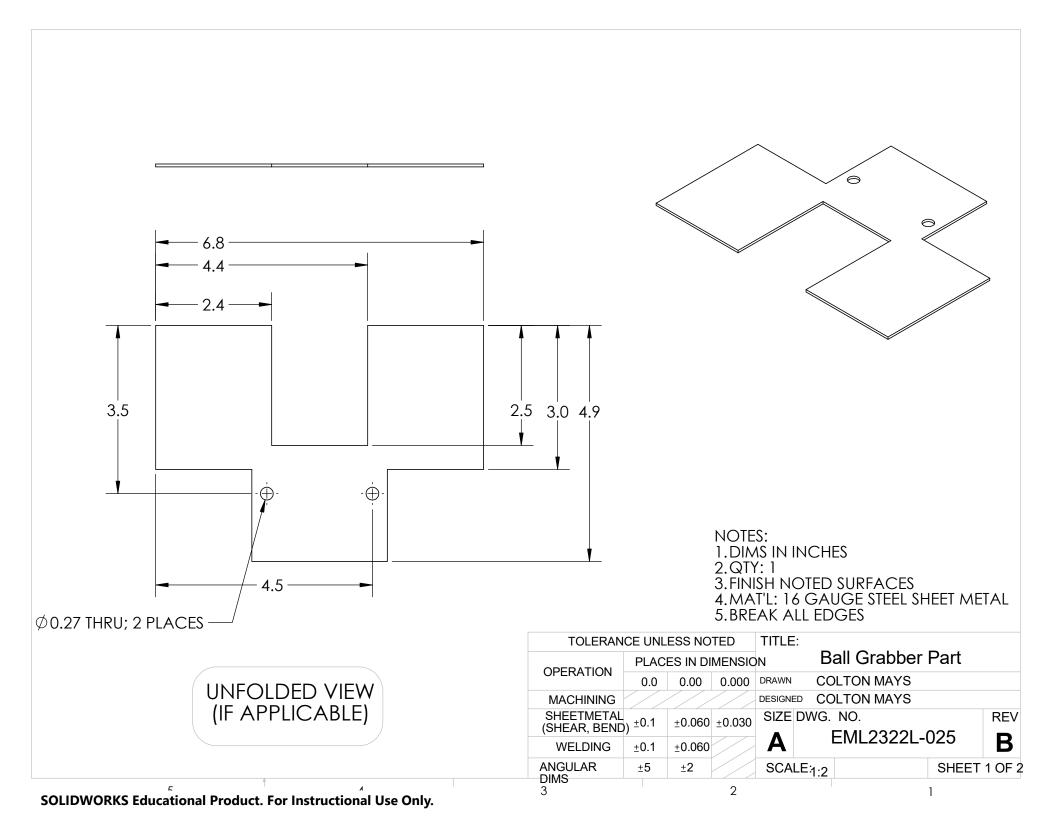
Lever Arm

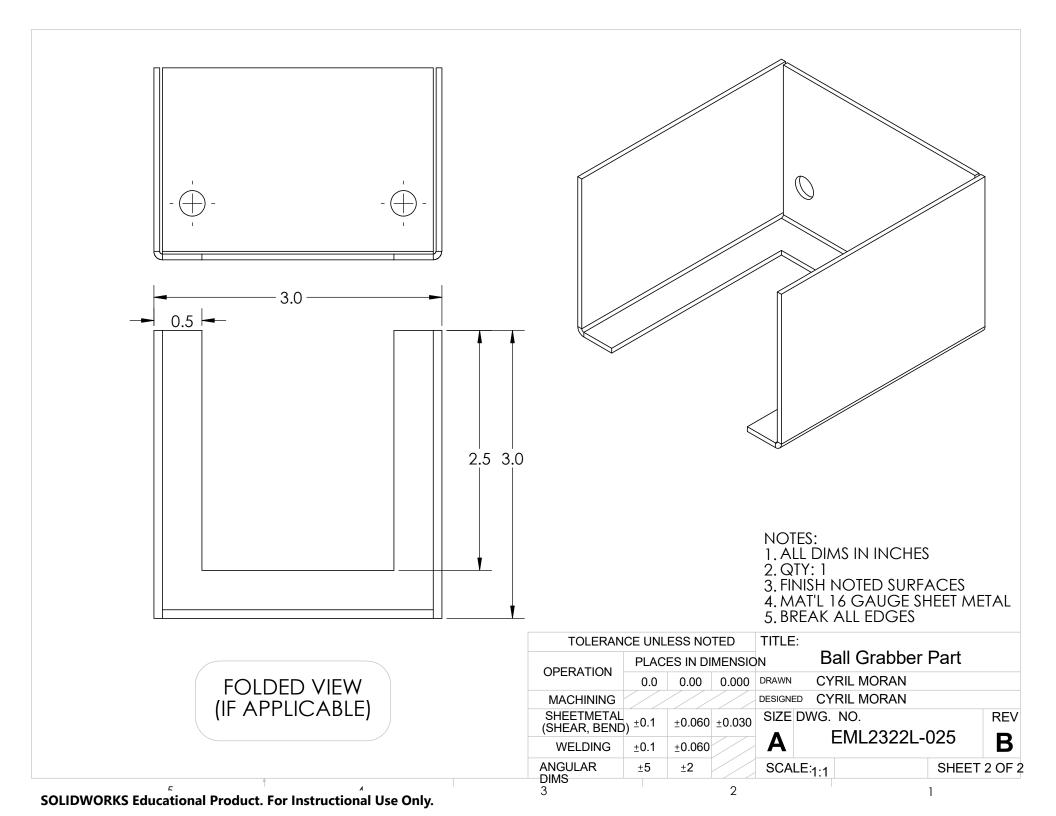
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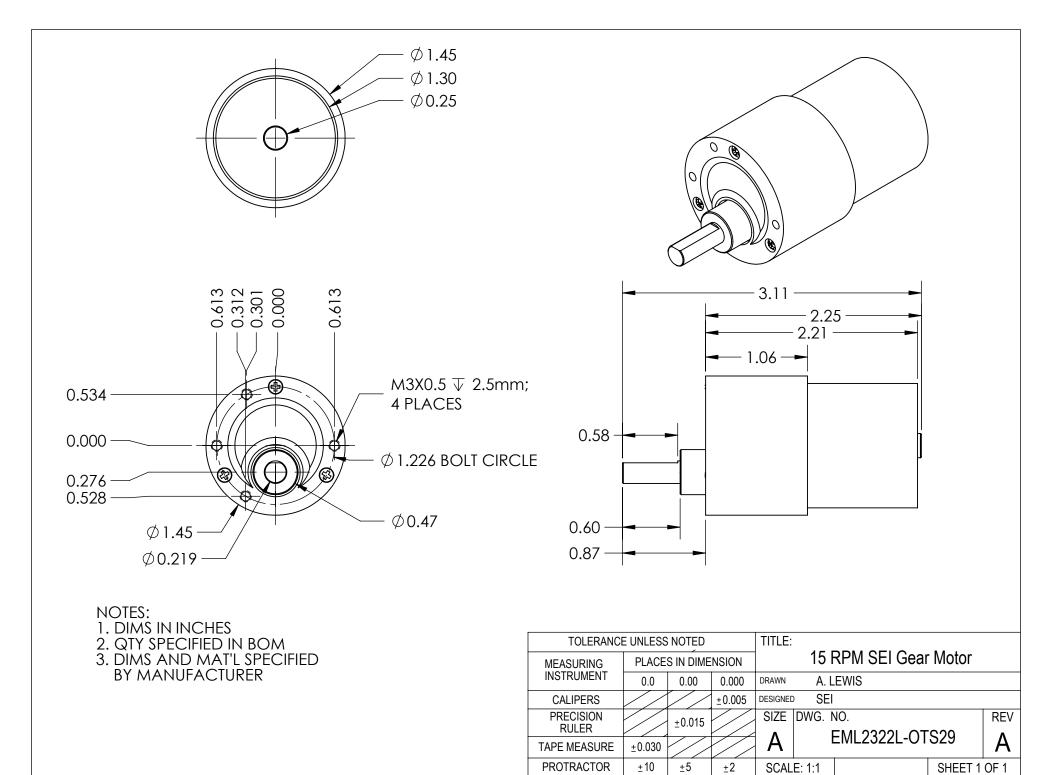
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TITLE:

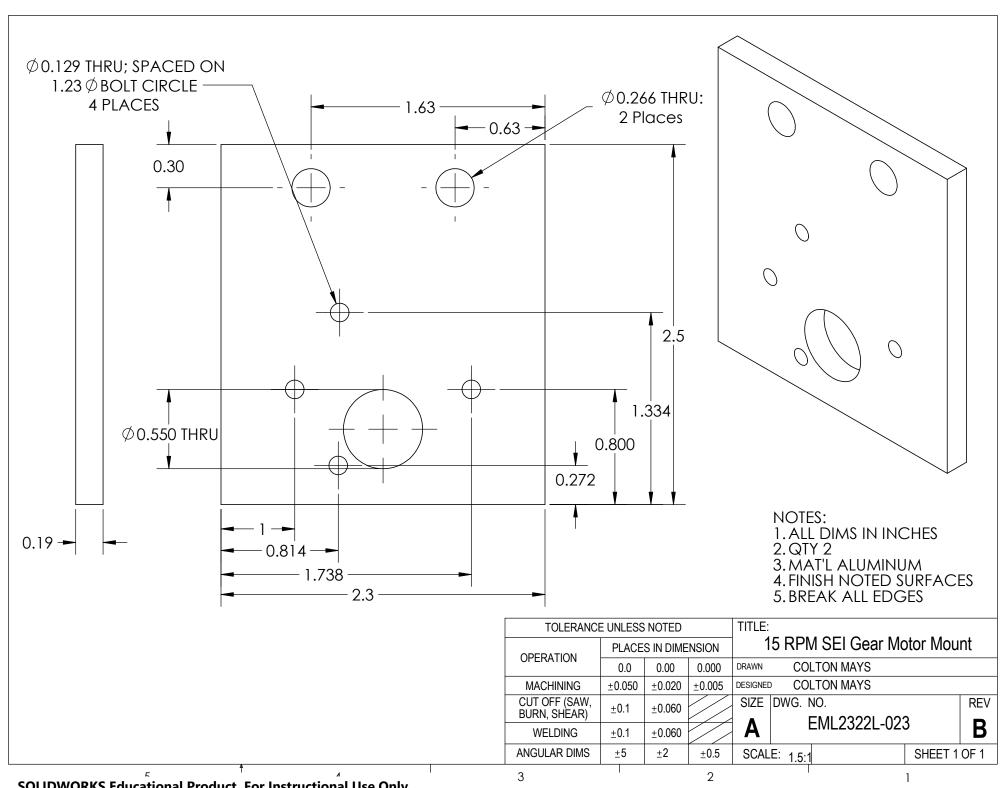


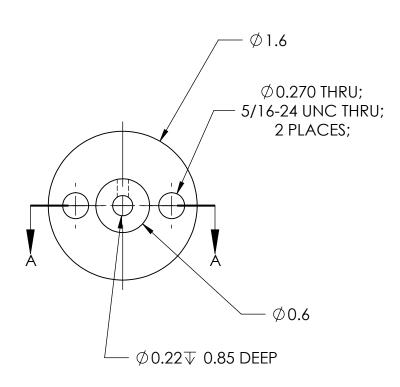


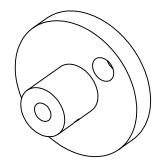


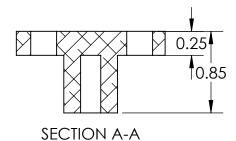


3









NOTES: 1.QTY: 1

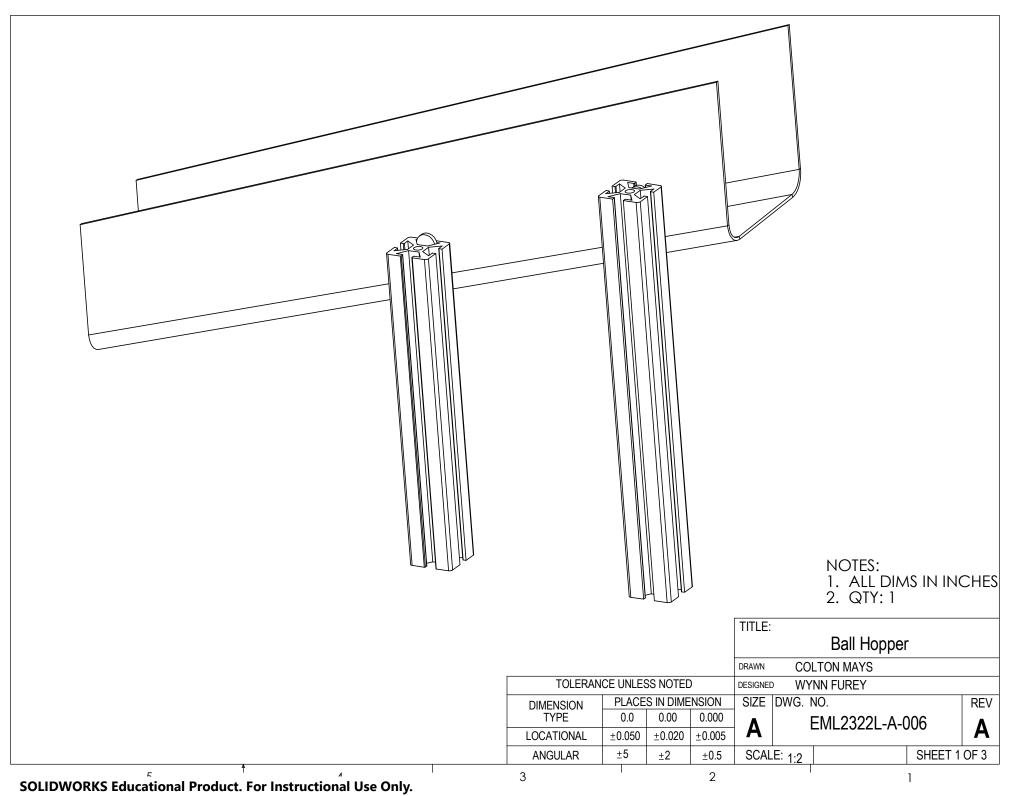
2. ALL DIMS IN INCHES 3. MAT'L ALUMINUM

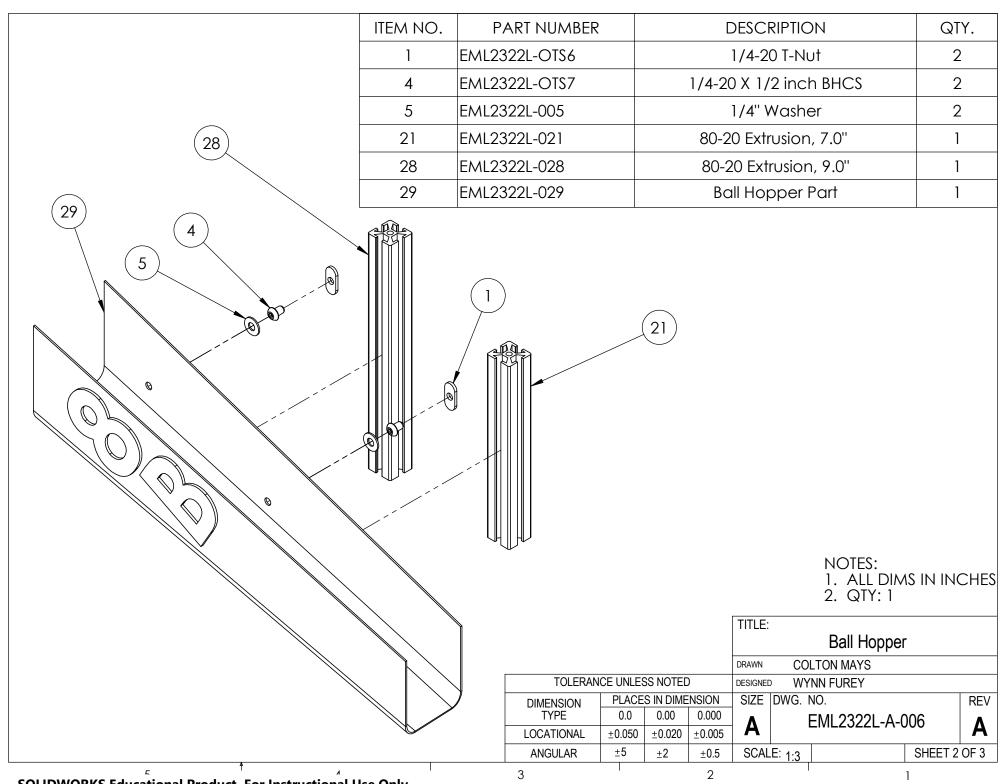
4. FINISHED NOTES SURFACES 5. BREAK ALL EDGES

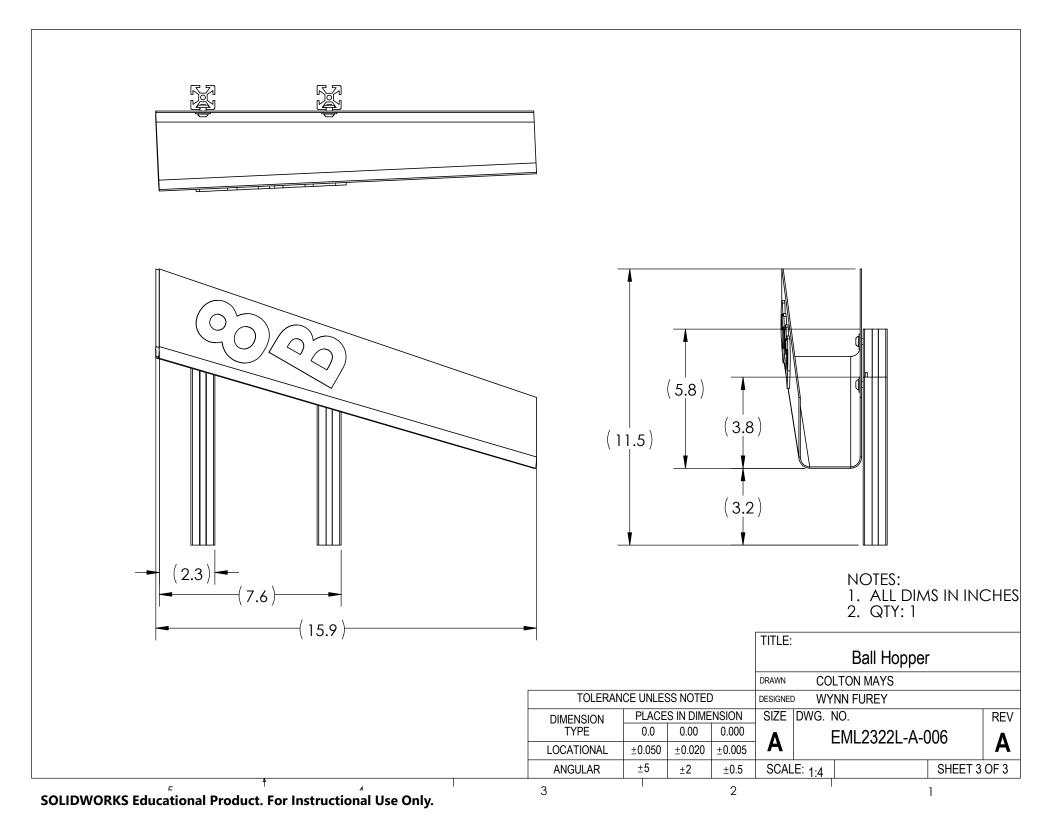
TOLERANCI	E UNLESS	NOTED		TITLE:				
OPERATION	PLACES IN DIMENSION			15 RPM SEI Gear Motor Hub Lever Arm				
OPERATION	0.0	0.00	0.000	DRAWN	CYF	RIL MORAN		
MACHINING	±0.050	±0.020	±0.005	DESIGNED	CYF	RIL MORAN		
CUT OFF (SAW, BURN, SHEAR)	±0.1	±0.060		SIZE	DWG. N	NO. E ML2322L-0 2	24	REV
WELDING	±0.1	±0.060		Α	[EIVILZ3ZZL-UZ	24	B
ANGULAR DIMS	±5	±2	±0.5	SCAL	E: 1:1		SHEET 1	OF 1

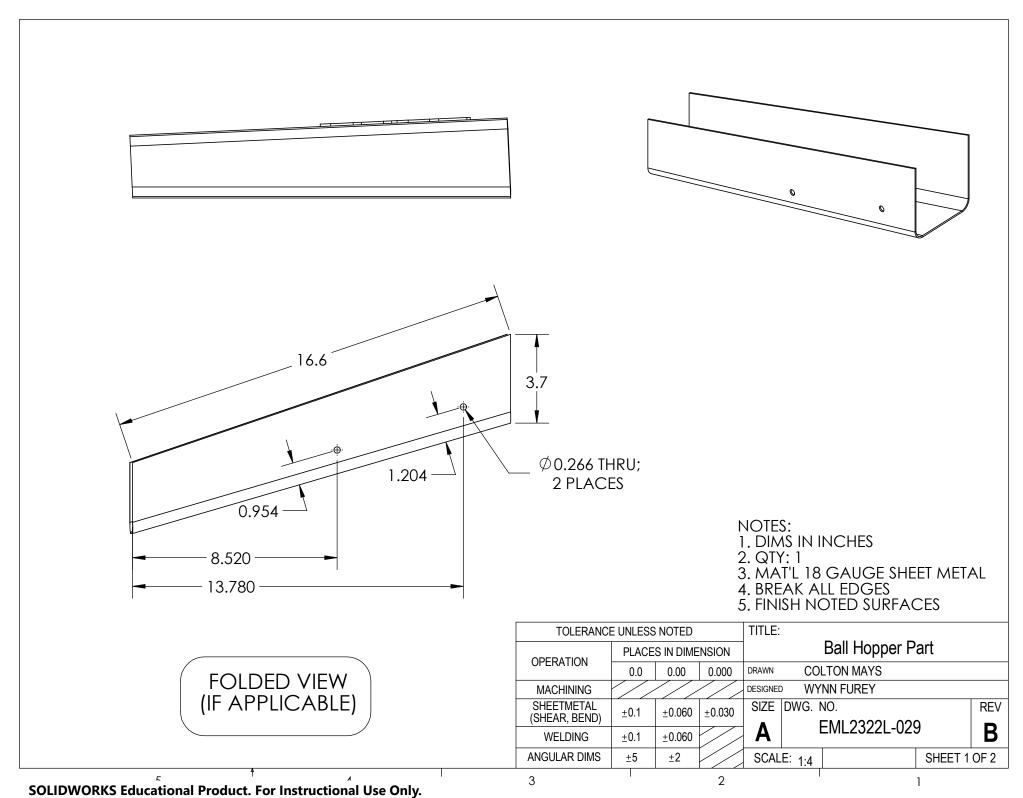
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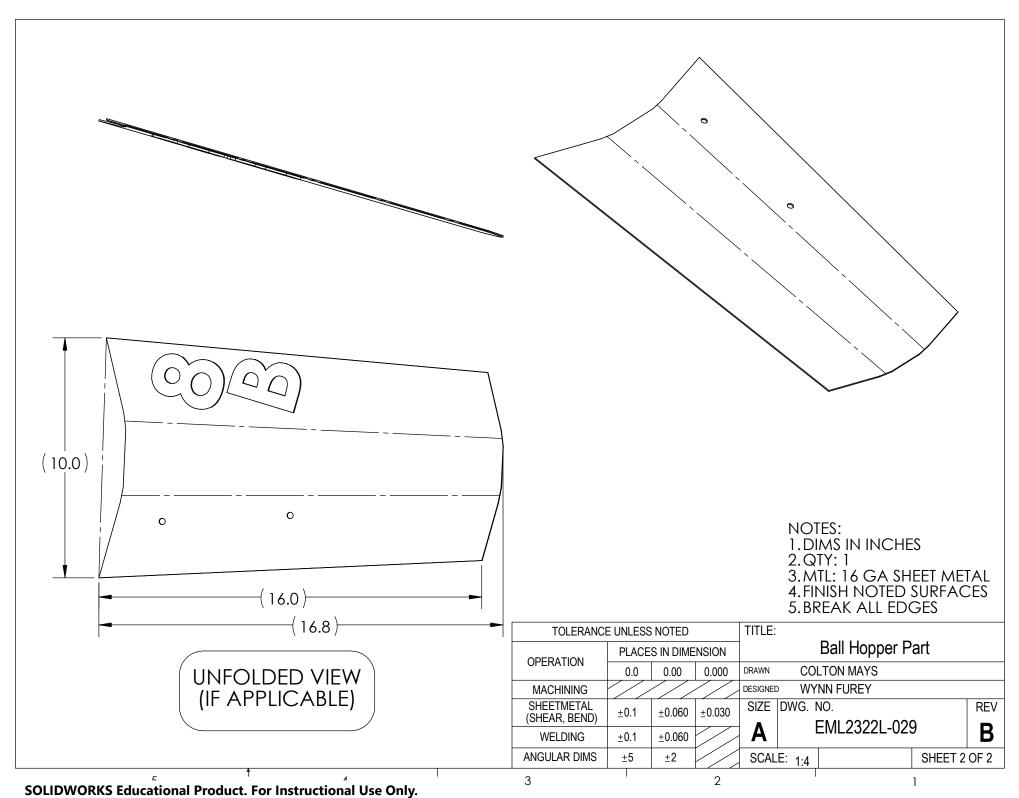
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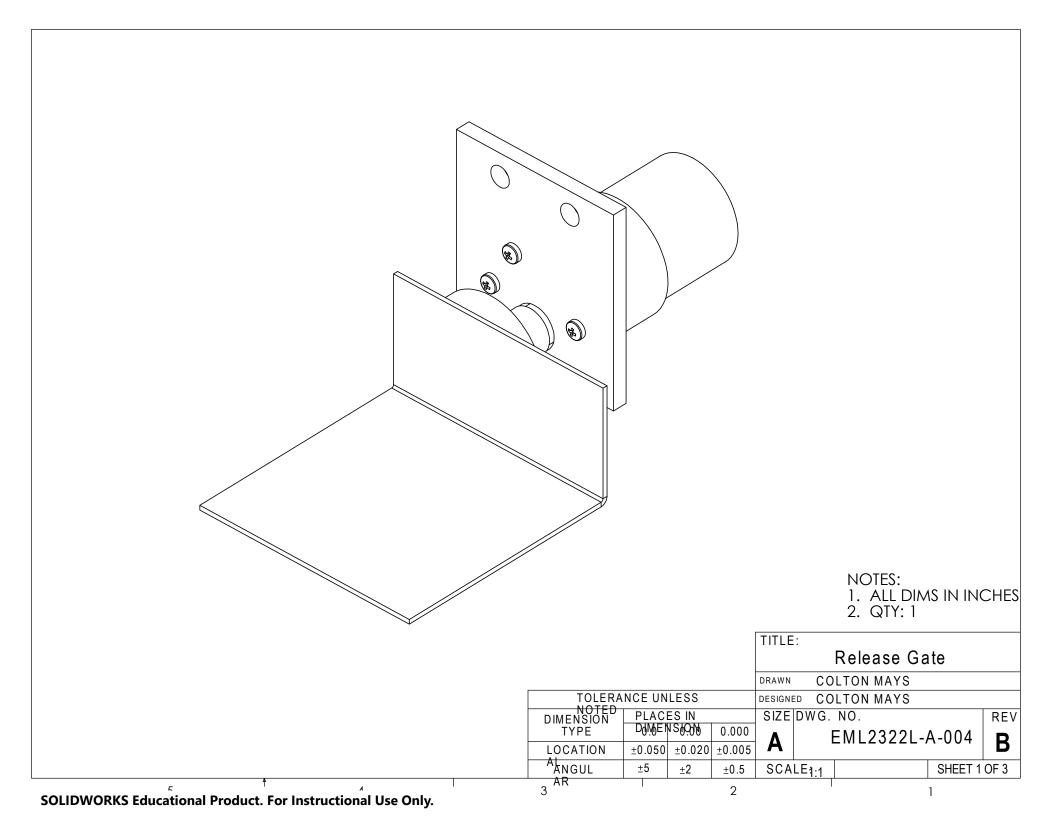




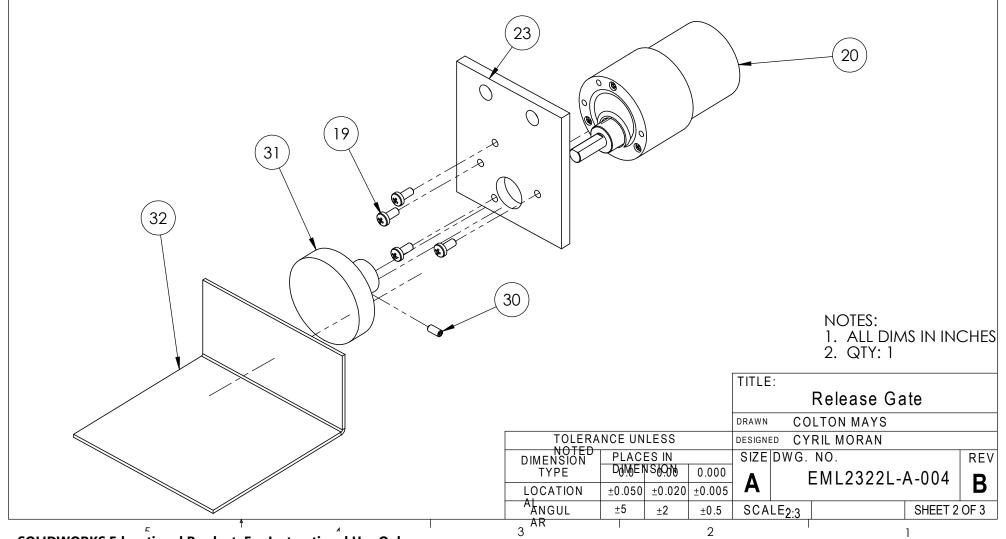


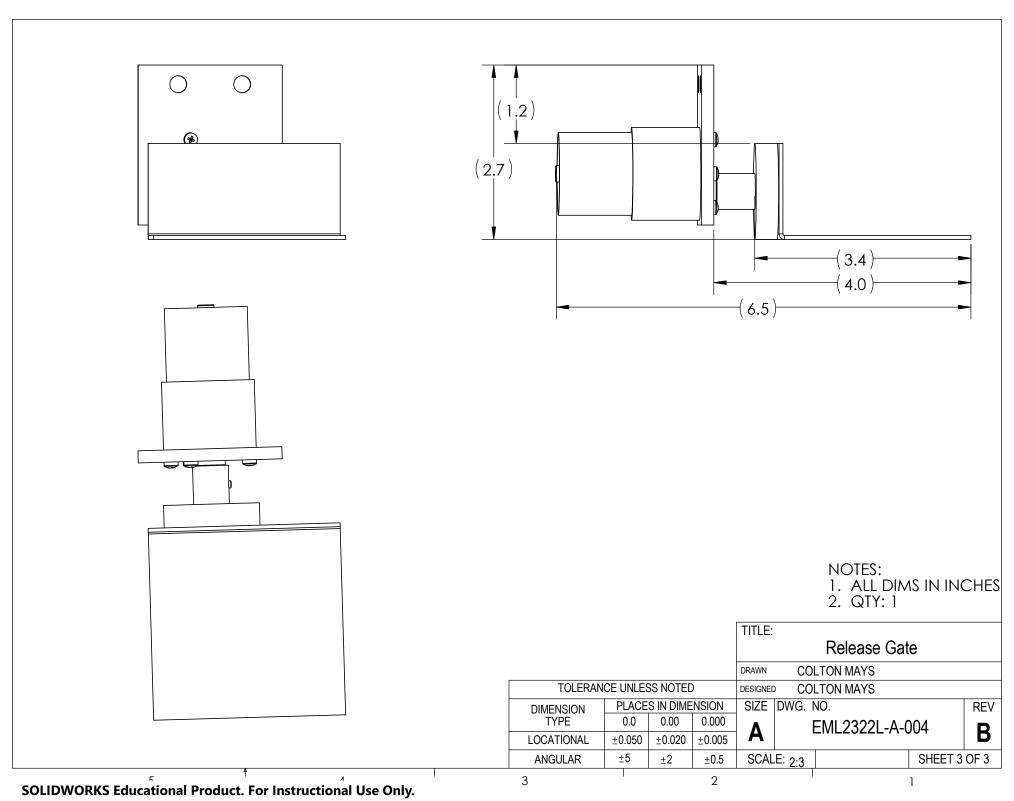


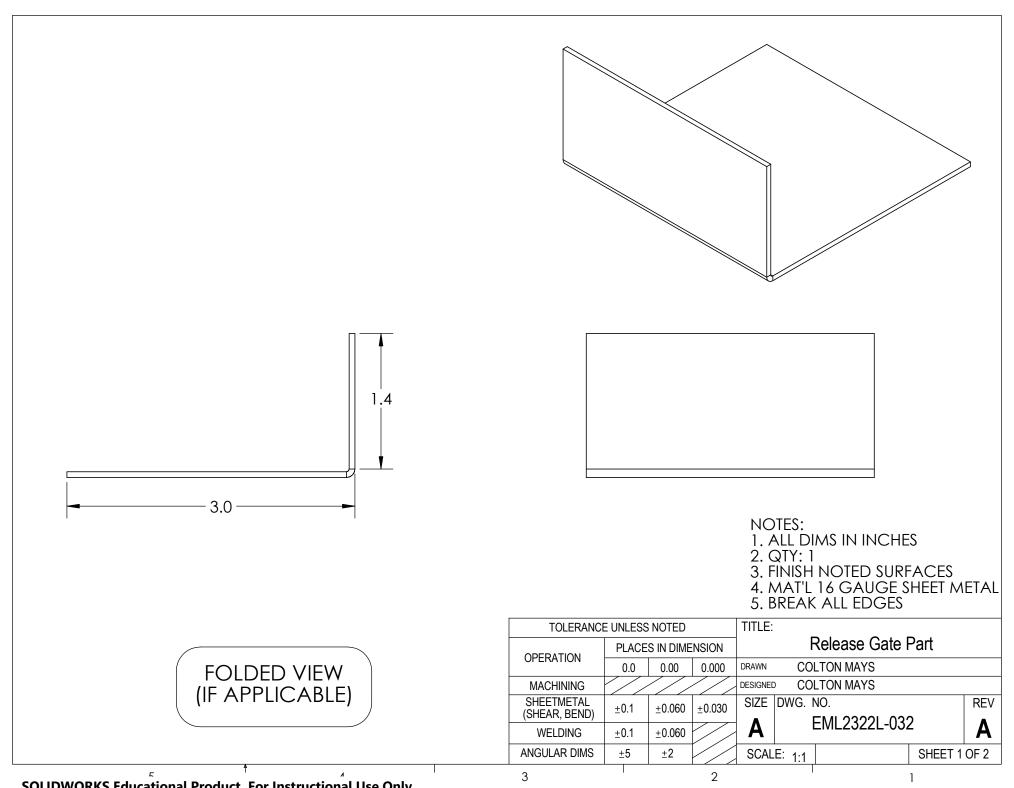


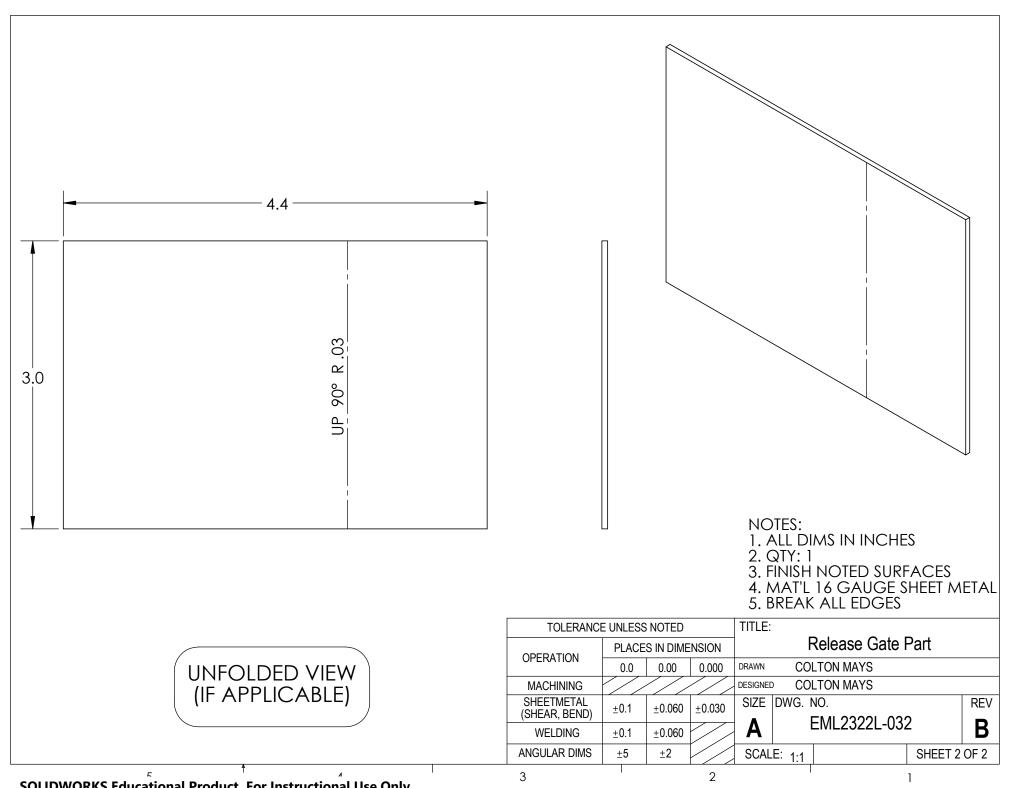


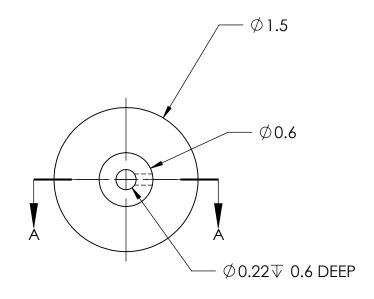
ITEM NO.	PART NUMBER	DESCRIPTION	QTY.
19	EML2322L-019	M3 X 10mm Screw	4
20	EML2322L-OTS29	15 RPM SEI Gear Motor	1
23	EML2322-023	15 RPM SEI Gear Motor Mount	1
30	EML2322-030	Alloy Steel Cup-Point Set Screw	1
31	EML2322L-031	15 RPMSEI Gear Motor Hub Release Gate	1
32	EML2322L-032	Release Gate Part	1

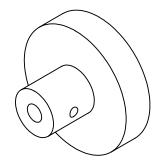


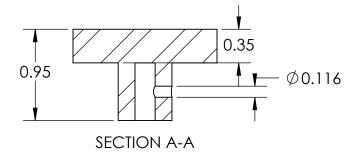












NOTES: 1. QTY: 1 2. ALL DIMS IN INCHES 3. MAT'L STEEL 4. FINISHED NOTES SURFACES 5. BREAK ALL EDGES

TOLERANCE UNLESS NOTED				TITLE:				
OPERATION	PLACES IN DIMENSION			SEI Motor Hub Release Gate				e
OPERATION	0.0	0.00	0.000	DRAWN	CYF	RIL MORAN		
MACHINING	±0.050	±0.020	±0.005	DESIGNED	CYF	RIL MORAN		
CUT OFF (SAW, BURN, SHEAR)	±0.1	±0.060		SIZE	DWG. 1	NO. E ML2322L- (no 1	REV
WELDING	±0.1	±0.060		Α	[EIVILZ3ZZL-(JST	B
ANGULAR DIMS	±5	<u>+</u> 2	±0.5	SCAL	E: 1:1		SHEET 1	OF 1

5 \$\frac{1}{5} \quad \frac{1}{5} \quad \frac{4}{5}\$ SOLIDWORKS Educational Product. For Instructional Use Only.

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Appendix D: Estimated Project Budget

Project Budget for Team 8B

Item Description	Vendor	Qty	Unit	Unit Price	Subtotal
Ø 2.0" AL round bar stock (wheel hubs)	LAB	0.33	ft	\$20.00	\$6.60
3/16" x 2.50" AL rect. bar stock (motor mounts)	LAB	1.25	ft	\$3.75	\$4.69
16 gauge steel sheetmetal (release mechanism, hopper, ball manipulator)	LAB	2	ft ²	\$4.00	\$8.00
80/20 1" x 1" aluminum extrusion (*)	LAB	5.8	ft	\$3.00	\$17.40
Ø 1.5" steel round bar stock (release gate wheel hub)	LAB	1	in.	\$10.00	\$10.00
Entstort 44 RPM right angle gear motor	LAB	2	each	N/C	N/C
Ø 8" Type 1 Wheel	LAB	2	each	N/C	N/C
Ø 5" Swivel Caster Wheel	LAB	1	each	N/C	N/C
15 RPM SEI Gear Motor	LAB	2	each	N/C	N/C
1/4 - 20 Hex Nut	LAB	2	each	N/C	N/C
80/20 1" x 1" aluminum extrusion	LAB	6	ft	N/C	N/C
80/20 aluminum right angle brackets	LAB	17	each	N/C	N/C
1/4-20 T-Nut	LAB	70	each	N/C	N/C
1/4-20 x 1/2" button head fastener (80/20)	LAB	86	each	N/C	N/C
10-24 x 1" button head screw (wheel hubs)	LAB	6	each	N/C	N/C
M8 x 1.25 nut (wheel hubs)	LAB	2	each	N/C	N/C
80/20 aluminum straight bracket	LAB	17	each	N/C	N/C
M3 x 0.5 10 mm screw	LAB	8	each	N/C	N/C
1/4 in. washer	LAB	6	each	N/C	N/C
M6 x 1.0 20 mm hex head screw	LAB	6	each	N/C	N/C
1/4-20 X 3/8" BHCS	LAB	4	each	N/C	N/C
4-40 1/4" set screw	LAB	2	each	N/C	N/C

TOTAL \$46.69

NOTES:

^(*) denotes this is in addition to the 12' provided in the project description

^(**) denotes this was provided by the team and not paid for from the project budget