

General Modelling Procedure:

Apply physical laws.

→ Newton's 2nd law

→ Kirchhoff's Laws (KCL, KVL)

System of differential equations.



"linearize" about desired
"operating point"

System of LTI systems.



take Laplace transform + solve for relationship
between I/O.

Transfer Functions.



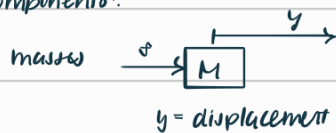
identify unknown
parameters experimentally.

"model"

Deriving differential Equations.

Mechanical systems. (in translation)

- Components.



$$F(t) = M \frac{d^2 y}{dt^2} \quad \text{Newton's 2nd Law.}$$

linear springs.

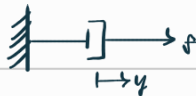


$$F(t) = Ky(t)$$

$y=0 \rightarrow$ spring not stretched



linear dashpots (damping elements)

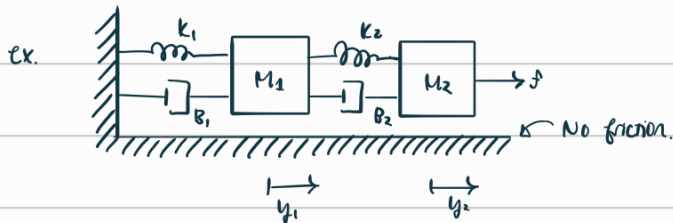


$$F(t) = -B\dot{y}(t)$$

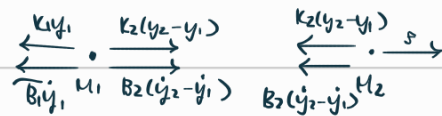


Procedure

1. FBD for each mass
2. Apply Newton's 2nd Law.
3. System of DEs.



FBD:



$y_1 = y_2 = 0$ both springs at natural lengths

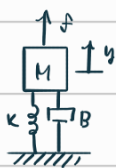
Newton's 2nd Law

$$\begin{aligned} M_1 \ddot{y}_1 &= k_2(y_2 - y_1) + B_2(\dot{y}_2 - \dot{y}_1) - k_1 y_1 - B_1 \dot{y}_1 \\ M_2 \ddot{y}_2 &= f - k_2(y_2 - y_1) - B_2(\dot{y}_2 - \dot{y}_1) \end{aligned}$$

$f(y_1, y_2, \dot{y}_1, \dot{y}_2, \ddot{y}_1, \ddot{y}_2, f) = 0$

system of DEs
linear, LTI.

ex.



FBD:



Newton's 2nd Law.

$$\begin{aligned} M \ddot{y} &= f - k y - B \dot{y} - Mg \Leftrightarrow M \ddot{y} + B \dot{y} + k y = f - Mg \\ \Leftrightarrow 0 &= f - k y - B \dot{y} - M \ddot{y} - Mg \end{aligned}$$

affine (nonlinear)
Not LTI.

Idea: change variables (coords) to cancel out constant term so that this system is LTI.

→ Define $\Delta y = y - y_0$ (unknown constant)

↳ translation / disp relative to y_0 .

$$\begin{aligned} \Delta \dot{y} &= \dot{y} \\ \Delta \ddot{y} &= \ddot{y} \end{aligned}$$

Goal:

1. Choose y_0 so that Δy satisfies an LTI DE.
2. Solve for Δy using LTI methods.
3. Calc. $y = \Delta y + y_0$.

$$\begin{aligned} M \Delta \ddot{y} + B \Delta \dot{y} + k \Delta y &= \underbrace{M \ddot{y} + B \dot{y} + k y}_{f - Mg} - k y_0 \\ &= f - Mg - k y_0 \quad \text{①} = f - \cancel{Mg} + Mg = f \end{aligned}$$

∴ LTI

Choose $y_0 \Rightarrow -k y_0 = Mg \Leftrightarrow y_0 = -\frac{Mg}{k}$