

General Modelling Procedure:

Apply physical laws.

→ Newton's 2nd law

→ Kirchoff's Laws (KCL, KVL)

System of differential equations.

↓ "linearize" about desired
"operating point"

System of LTZ systems.

↓ take Laplace transform + solve for relationship
between L/I/O.

Transfer functions.

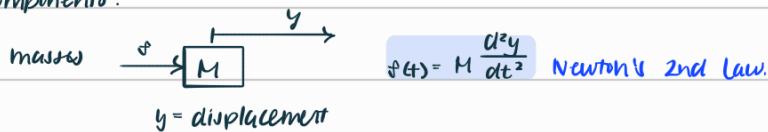
↓ identify unknown
parameters experimentally.

"model"

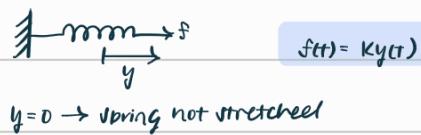
Deriving Differential Equations.

Mechanical systems. (in translation)

- Components.



linear springs.

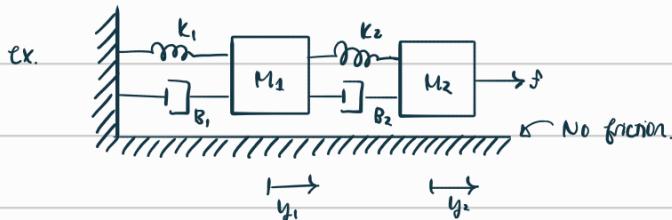


linear dashpots (damping elements)



Procedure

1. FBD for each mass
2. Apply Newton's 2nd law.
3. System of DEs.



FBDN.

$$\frac{k_1 y_1}{B_1 M_1} \cdot \frac{k_2(y_2 - y_1)}{B_2(M_1 + M_2)} \quad \frac{k_2(y_2 - y_1)}{B_2(M_2)} \cdot \frac{s}{M_2}$$

$y_1 = y_2 = 0$ both springs at natural length

Newton's 2nd Law

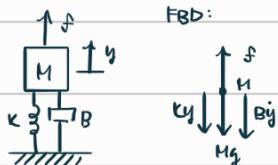
$$M_1 \ddot{y}_1 = k_2(y_2 - y_1) + B_2(\dot{y}_2 - \dot{y}_1) - k_1 y_1 - B_1 \dot{y}_1$$

$$M_2 \ddot{y}_2 = s - k_2(y_2 - y_1) - B_2(\dot{y}_2 - \dot{y}_1)$$

$$f(y_1, y_2, \dot{y}_1, \dot{y}_2, \ddot{y}_1, \ddot{y}_2, s) = 0$$

System of DEs
linear, LTI.

ex.



FBD:

Newton's 2nd Law.

$$M\ddot{y} = f - ky - B\dot{y} - Mg \Leftrightarrow M\ddot{y} + B\dot{y} + ky = f - Mg$$

$\Leftrightarrow 0 = f - ky - B\dot{y} - Mg - M\ddot{y}$

Not LTI.

Affine (nonlinear)

affine (nonlinear)

Not LTI.

Idea: change variables (coords) to cancel out constant term so their sysmtem is LTI.

→ Define $\Delta y = y - y_0$ (unknown constant)

↳ translation / disp relative to y_0 .

$$\Delta \dot{y} = \dot{y}$$

$$\Delta \ddot{y} = \ddot{y}$$

Goal:

1. Choose y_0 so that Δy satisfies an LTI DE.

2. solve for Δy using LTI methods.

3. Calc. $y = \Delta y + y_0$.

$$M\Delta \ddot{y} + B\Delta \dot{y} + K\Delta y = M\ddot{y} + B\dot{y} + Ky - Ky$$

$$= y - y_0$$

$$f - Mg$$

$$= f - Mg - Ky$$

∴ LTI

$$\text{Choose } y_0 \Rightarrow -Ky_0 = Mg \Leftrightarrow y_0 = \frac{-Mg}{K}$$