Project 2: Crane Problem

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Exhaustive Algorithm Pseudocode & Time Analysis

```
assert(setting.rows() > 0) // 3tu
 asser(setting.columns() > 0) // 3tu
 max_steps = setting.rows() + setting.columns() - 2 // 5tu
 assert(max steps < 64) // 2tu
 path best(setting) // 1tu
 for steps = 0 to max_steps do // ntu
 for path_bits = 0 to pow(2, steps) - 1 do // 2^n tu
   path candidate(setting) // 1tu
   bool valid_path = true // 1tu
   for i = 0 to steps do // mtu
     bool east = (path_bits >> i) & 1 // 3tu
     step direction dir
     // Block A:
     if east do // 1tu
      dir = STEP_DIRECTION_EAST // 1tu
       dir = STEP_DIRECTION_SOUTH // 1tu
     END IF
     // Block B:
     if candidate.is_step_valid(dir) do // 1tu
       candidate.add_step(dir) // 1tu
       valid path = false // 1tu
       break
   ENDFOR
   if valid_path and candidate.total_cranes() > best.total_cranes() do // 4tu
     best = candidate // 1tu
   ENDIF
 ENDFOR
 ENDFOR
return best
```

```
Block A = 1 + max(1,1) = 2

Block B = 1 + max(1,1) = 2

Block C = 4 + max(1,0) = 5

S. C = 3 + 3 + 5 + 2 + 1 * n * (1 * 2^n * 1 * 1 * m + 3 + Block A + Block B) + Block C

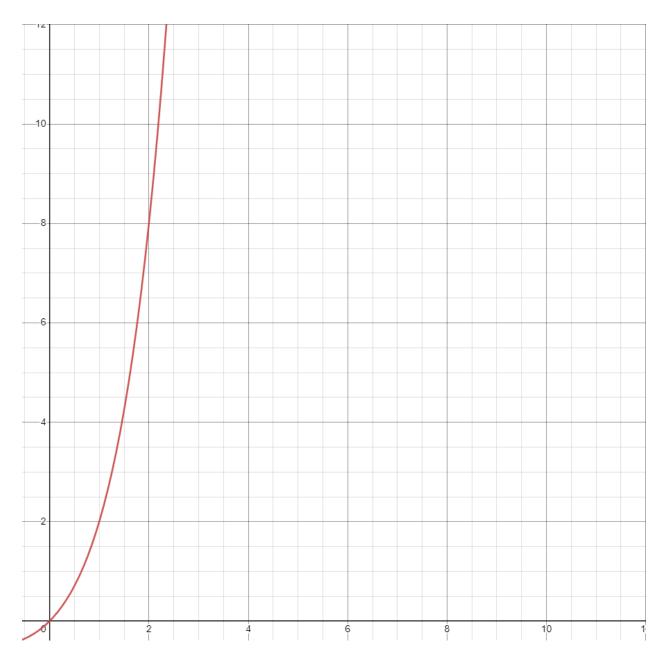
S. C = 14 * n * (1 * 2^n * 1 * 1 * m + 3 + 2 + 2) + 5

S. C = 14n * (2^n * m + 8) + 5
```

Exhaustive Algorithm Graph

Time Vs Input Size

 $T(n) = n*2^n$



Dynamic Algorithm Pseudocode & Time Analysis

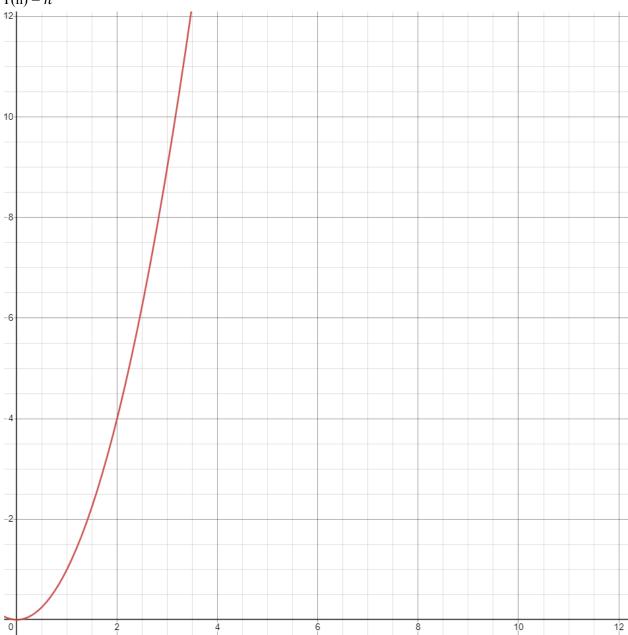
```
assert(setting.rows() > 0) // 3tu
assert(setting.columns() > 0) // 3tu
vector A = (setting.rows(), vector<cell type>(setting.columns())) // 3tu
A[0][0] = path(setting) // 2tu
assert(A[0][0].has_value()) // 2tu
for r - 0 to setting.rows() - 1 do // ((n-1)-0+1) = n
 for c = 0 to setting.columns() -1 do // (n-1-0=1) = n
   if setting.get(r,c) == CELL BUILDING do // 2tu
     A[r][c].reset(); // 2tu
     continue
    ENDIF
   from above = null // 1tu
   from_left = null // 1tu
   if r != 0 and setting.get(r-1, c) != CELL_BUILDING \&\& A[r-1][c].has_value() do // 8tu
     from above.emplace(A[r-1][c].value()) // 3 tu
     from_above->add_step(STEP_DIRECTION_SOUTH) // 1tu
    ENDIF // Block A = 8 + 3 + 1 = 12tu
    if c != 0 && setting.get(r, c-1) != CELL BUILDING && A[r][c-1].has value() do // 8tu
     from left.emplace(A[r][c-1].has value() // 3tu
      from_left->add_step(STEP_DIRECTION_EASTH) // 1tu
    ENDIF // Block B = 8 + 3 + 1 = 12tu
   if from_above.has_value() && from_left.has_value() do // 3tu
     if from_above->total_cranes() >= from_left->total_creanes() do // 3tu
       A[r][c] = from_above //3tu
      else
        A[r][c] = from left // 3tu
      ENDIF // Block C = 3 + \max(3 + \max(1, 1), ) = 7tu
    else if from above.has value() && !from left.has value() do // 4tu
     A[r][c] = from\_above // 3tu
    else if !from above.has value() && from left.has value() do // 4tu
      A[r][c] = from_left // 3tu
    ENDIF
  ENDFOR
ENDFOR
```

```
// post-processing step to find the best path
 max_rows = 0 // 1tu
 max columns = 0 // 1tu
 max_cranes = 0 // 1tu
 for rows = 0 to setting.rows() do // (n - 1 - 0 + 1) = n
   for columns = 0 to setting, columns() do // (n - 1 - 0 + 1) = n
     if A[rows][columns].has_value() && A[rows][columns]->total_cranes > mac_cranes do // 5tu
      max_rows = rows // 1tu
      max_columns = columns // 1tu
       max_cranes = A[rows][columns]->total_cranes() // 3tu
     ENDIF
   ENDFOR
 ENDFOR
 *best = &A[max_rows][max_columns] // 3tu
 assert(best->has_value()) // 2tu
 return **best
S.C = 3 + 3 + 3 + 2 + 2 + n[n * (2 + max(2 + 1 + 1 + 12 + 12 + 7 + 7 + 7, 0))] + 3 + 10n^2 + 3 + 2
S.C = 13 + n[n * (2 + max(49, 0))] + 10n^2 + 8
S.C = 13 + n[n * (2 + 49)] + 10n^2 + 8
S.C = 13 + n * 51n + 10n^2 + 8
S. C = 21 + 51n^2 + 10n^2
S.C = 61n^2 + 21
```

Dynamic Algorithm Graph

Time Vs Input Size $T(n) = n^2$





Questions

1. Is there a noticeable difference in the performance of the two algorithms? Which is faster, and by how much?

Comparing the exhaustive optimization algorithm(crane_unloading_exhaustive) with the dynamic programming algorithm(crane_unloading_dyn_prog), the results show that the dynamic programming algorithm is the faster of the two. The step count for exhaustive optimization resulted in an exponential time complexity $O(2^n)$. With increasing grid size or input, it will cause the runtime of the algorithm to grow exponentially. Whereas for the dynamic algorithm, the step count resulted in a quadratic time complexity $O(n^2)$ which is the more efficient of the two. As the input size increases the exhaustive optimization algorithm will take exponentially longer than the dynamic programming.

2. Are your empirical analyses consistent with your mathematical analyses? Justify your answer.

Our mathematical analyses are consistent with our empirical analysis. For the exhaustive algorithm, the time complexity of our solution is $O(2^n)$, which is exponential time. Therefore it makes the exhaustive optimization algorithm slow. However, the time complexity of our dynamic programming algorithm is $O(n^2)$, which is much faster, and makes it more efficient.

3. Is this evidence consistent or inconsistent with hypothesis 1? Justify your answer.

The evidence is consistent with the hypothesis. Looking at the graphs, we notice that the dynamic programming algorithm can take more instances in less time. On the other hand, the exhaustive optimization algorithm takes longer when it takes fewer instances than the dynamic programming algorithm. We can conclude that the dynamic algorithm is more efficient than the exhaustive algorithm.

4. Is this evidence consistent or inconsistent with hypothesis 2? Justify your answer. $\rm N\!/\!A$