

Active Typechecking and Translation: A Safe Language-Internal Extension Mechanism

Appendix

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A @λ

A.1 Helper Functions

The following helper functions are useful for working with lists of denotations:

```
const := (λa:list[Den].λd:Den.fold(a; d; -, -, -.err))
pop := (λa:list[Den].λf:ITm → * → list[Den] → Den.
        fold(a; err; d, b, -.case d of [x as t] ⇒ f x t b ow err))
pop_final := (λa:list[Den].λf:ITm → * → Den.
               fold(a; err; d, b, -.
                     fold(b; case d of [x as t] ⇒ f x t ow err; -, -, -.err)))
```

The following helper function is useful for checking the equivalence of two types before producing a denotation. If the two types are not equivalent, an error is returned.

```
check_type := (λt1:*.λt2:*.λd:Den.if t1 ≡_* t2 then d else err)
```

A.2 Definition of Arrow types

The definition of the ARROW type family is built into @λ as follows:

```
Σ0 := ARROW[* × *, ap[1]]
Φ0 := ARROW[θ0, i.▼(rep(fst(i)) → rep(snd(i)))]
θ0 := ap[1](i, a.pop a λx1:Den.λt1:*.λb:list[Den].
            pop_final b λx2:Den.λt2:*.
            case t1 of ARROW⟨j⟩ ⇒
              check_type fst(j) t2 [∀(Δ(x1) Δ(x2)) as snd(j)]
            ow err)
Ξ0 := ARROW
```

A.3 Deabstraction

$$\boxed{\vdash_{\Phi} \sigma \not\leq \sigma'}$$

$$\begin{array}{c}
\text{DEABS-INT} \quad \frac{}{\vdash_{\Phi} \mathbb{Z} \not\leq \mathbb{Z}} \quad \text{DEABS-ARROW} \quad \frac{\vdash_{\Phi} \sigma_1 \not\leq \sigma'_1 \quad \vdash_{\Phi} \sigma_2 \not\leq \sigma'_2}{\vdash_{\Phi} \sigma_1 \rightarrow \sigma_2 \not\leq \sigma'_1 \rightarrow \sigma'_2} \quad \text{DEABS-PROD} \quad \frac{\vdash_{\Phi} \sigma_1 \not\leq \sigma'_1 \quad \vdash_{\Phi} \sigma_2 \not\leq \sigma'_2}{\vdash_{\Phi} \sigma_1 \times \sigma_2 \not\leq \sigma'_1 \times \sigma'_2} \\
\\
\text{DEABS-REP} \quad \frac{\text{FAM}[\theta, \mathbf{i}, \tau_{\text{rep}}] \in \Phi \quad [\tau_{\text{idex}}/\mathbf{i}]\tau \Downarrow \nabla(\sigma) \quad \vdash_{\Phi}^{\Xi_0} \sigma \rightsquigarrow \sigma' \quad \vdash_{\Phi} \sigma' \not\leq \sigma''}{\vdash_{\Phi} \text{rep}(\text{FAM}\langle \tau_{\text{idex}} \rangle) \not\leq \sigma''}
\end{array}$$

$$\boxed{\vdash_{\Phi} \gamma \not\leq \gamma'}$$

$$\begin{array}{c}
\text{DEABS-LAM} \quad \frac{\vdash_{\Phi}^{\Xi_0} \sigma \rightsquigarrow \sigma' \quad \vdash_{\Phi} \sigma' \not\leq \sigma''}{\vdash_{\Phi} \gamma \not\leq \gamma'} \quad \text{DEABS-FIX} \quad \frac{\vdash_{\Phi}^{\Xi_0} \sigma \rightsquigarrow \sigma' \quad \vdash_{\Phi} \sigma' \not\leq \sigma''}{\vdash_{\Phi} \text{fix } x:\sigma \text{ is } \gamma \not\leq \text{fix } x:\sigma'' \text{ is } \gamma'} \\
\text{DEABS-VAR} \quad \frac{}{\vdash_{\Phi} x \not\leq x} \quad \frac{}{\vdash_{\Phi} \lambda x:\sigma.\gamma \not\leq \lambda x:\sigma''.\gamma'}
\end{array}$$

(omitted forms have trivially recursive rules)

$$\begin{array}{c}
\text{DEABS-CANCEL} \quad \frac{\vdash_{\Phi} \gamma \not\leq \gamma'}{\vdash_{\Phi} \Delta(\nabla(\gamma)) \not\leq \gamma'} \quad \text{DEABS-TRANS} \quad \frac{\vdash_{\Phi} \gamma \not\leq \gamma'}{\vdash_{\Phi} \text{trans}(\llbracket \nabla(\gamma) \text{ as FAM}\langle \tau_{\text{idex}} \rangle \rrbracket) \not\leq \gamma'}
\end{array}$$

B Examples

B.1 Gödel's T

The implementation of Gödel's T in @λ encodes the following static and dynamic semantics.

Statics

$$\begin{array}{c}
\text{VAR} \quad \frac{}{\Gamma, x:\tau \vdash x:\tau} \quad \text{ARROW-INTRO} \quad \frac{\Gamma, x:\tau \vdash e:\tau'}{\Gamma \vdash \lambda x:\tau.e:\tau \rightarrow \tau'} \quad \text{ARROW-ELIM} \quad \frac{\Gamma \vdash e_1:\tau \rightarrow \tau' \quad \Gamma \vdash e_2:\tau}{\Gamma \vdash e_1 e_2:\tau'} \\
\\
\text{NAT-INTRO-Z} \quad \frac{}{\Gamma \vdash \mathbf{z}:\mathbf{nat}} \quad \text{NAT-INTRO-S} \quad \frac{\Gamma \vdash e:\mathbf{nat}}{\Gamma \vdash \mathbf{s}(e):\mathbf{nat}} \quad \text{NAT-ELIM} \quad \frac{\Gamma \vdash e_1:\mathbf{nat} \quad \Gamma \vdash e_2:\tau \quad \Gamma \vdash e_3:\mathbf{nat} \rightarrow \tau \rightarrow \tau}{\Gamma \vdash \text{rec}(e_1; e_2; e_3):\tau}
\end{array}$$

Dynamics

$$\begin{array}{c}
\text{LAM-VAL} \quad \frac{}{\lambda x:\tau.e \text{ val}} \quad \text{AP-STEP-L} \quad \frac{e_1 \mapsto e'_1}{e_1 \ e_2 \mapsto e'_1 \ e_2} \quad \text{AP-STEP-R} \quad \frac{e_2 \mapsto e'_2}{\lambda x:\tau.e \ e_2 \mapsto \lambda x:\tau.e \ e'_2} \quad \text{AP-SUBST} \quad \frac{e_2 \text{ val}}{\lambda x:\tau.e \ e_2 \mapsto [e_2/x]e} \\
\\
\text{Z-VAL} \quad \frac{}{z \text{ val}} \quad \text{S-STEP} \quad \frac{e \mapsto e'}{s(e) \mapsto s(e')} \quad \text{S-VAL} \quad \frac{e \text{ val}}{s(e) \text{ val}} \quad \text{REC-STEP} \quad \frac{e_1 \mapsto e'_1}{\text{rec}(e_1; e_2; e_3) \mapsto \text{rec}(e'_1; e_2; e_3)} \\
\\
\text{REC-Z} \quad \frac{}{\text{rec}(z; e_2; e_3) \mapsto e_2} \quad \text{REC-S} \quad \frac{}{\text{rec}(s(e); e_2; e_3) \mapsto e_3 \ e \ \text{rec}(e; e_2; e_3)}
\end{array}$$

B.2 n -tuples

The static and dynamic semantics of n -tuples (that is, n -ary products) shown below can be encoded in $@\lambda$. Notice that this judgemental description of n -tuples relies on ellipses frequently. This correspond to folds over the list of types that an n -tuple is indexed by, and underscores the need for a more concrete functional language for extensions, rather than a simple declarative scheme which is only completely precise and decidable when complex side conditions, ellipses and search schemes are not necessary.

Statics

$$\begin{array}{c}
\text{\textit{n}-TUPLE-INTRO} \quad \frac{\Gamma \vdash e_1 : \tau_1 \quad \cdots \quad \Gamma \vdash e_n : \tau_n}{\Gamma \vdash (e_1, \dots, e_n) : (\tau_1, \dots, \tau_n)} \ (n \geq 0) \quad \text{\textit{n}-TUPLE-ELIM} \quad \frac{\Gamma \vdash e : (\tau_1, \dots, \tau_n)}{\Gamma \vdash \text{pr}[i](e) : \tau_i} \ (1 \leq i \leq n)
\end{array}$$

Dynamics

$$\begin{array}{c}
\text{\textit{n}-TUPLE-STEP} \quad \frac{e_1 \text{ val} \quad \cdots \quad e_{i-1} \text{ val} \quad e_i \mapsto e'_i}{(e_1, \dots, e_i, \dots, e_n) \mapsto (e_1, \dots, e'_i, \dots, e_n)} \quad \text{\textit{n}-TUPLE-VAL} \quad \frac{e_1 \text{ val} \quad \cdots \quad e_n \text{ val}}{(e_1, \dots, e_n) \text{ val}} \\
\\
\text{PROJ-}i\text{-STEP} \quad \frac{e \mapsto e'}{\text{pr}[i](e) \mapsto \text{pr}[i](e')} \ (1 \leq i \leq n) \quad \text{PROJ-}i\text{-OF-}n \quad \frac{(e_1, \dots, e_n) \text{ val}}{\text{pr}[i]((e_1, \dots, e_n)) \mapsto e_i} \ (1 \leq i \leq n)
\end{array}$$

Implementation in $@\lambda$ n -tuples are implemented differently depending on n . For $n = 0$ (that is, the unit value), the integer 0 is used. For $n = 1$, the tuple only contains 1 element so it is represented without any additional run-time adornment. For $n > 1$,

nested pairs are used.

$$\begin{aligned}
& \text{family NTUPLE}[\text{list}[\star]] \sim \mathbf{i}. & (1) \\
& \text{fold}(\mathbf{i}; \nabla(\mathbb{Z}); \mathbf{s}, \mathbf{j}, \mathbf{r}. \text{fold}(\mathbf{j}; \nabla(\text{rep}(\mathbf{s})); \rightarrow, \rightarrow, \rightarrow. \nabla(\text{rep}(\mathbf{s}) \times \blacktriangle(\mathbf{r})))) \{ & (2) \\
& \text{new}[1](\rightarrow, \mathbf{a}. \text{fold}(\mathbf{a}; \llbracket \nabla(0) \text{ as NTUPLE}(\llbracket \star \rrbracket) \rrbracket; \mathbf{d}, \mathbf{b}, \mathbf{r}. & (3) \\
& \text{case } \mathbf{d} \text{ of } \llbracket \mathbf{dx} \text{ as } \mathbf{dt} \rrbracket \Rightarrow \text{case } \mathbf{r} \text{ of } \llbracket \mathbf{rx} \text{ as } \mathbf{rt} \rrbracket \Rightarrow & (4) \\
& \text{case } \mathbf{rt} \text{ of NTUPLE}(\mathbf{i}) \Rightarrow \text{fold}(\mathbf{b}; \llbracket \mathbf{dx} \text{ as NTUPLE}(\mathbf{dt} :: \mathbf{i}) \rrbracket; \rightarrow, \rightarrow, \rightarrow. & (5) \\
& \llbracket \nabla((\Delta(\mathbf{dx}), \Delta(\mathbf{rx}))) \text{ as NTUPLE}(\mathbf{dt} :: \mathbf{i}) \rrbracket) \text{ ow err ow err ow err}); & (6) \\
& \text{pr}[\mathbb{Z}](\mathbf{i}, \mathbf{a}. \text{pop_final } \mathbf{a} \lambda \mathbf{x} : \text{Den}. \lambda \mathbf{nt} : \star. \text{case } \mathbf{nt} \text{ of NTUPLE}(\mathbf{nl}) \Rightarrow & (7) \\
& \text{fold}(\mathbf{nl}; \text{err}; \mathbf{t1}, \mathbf{j}, \rightarrow. & (8) \\
& \text{fold}(\mathbf{j}; \text{if } \mathbf{i} \equiv_{\mathbb{Z}} 1 \text{ then } \llbracket \mathbf{x} \text{ as } \mathbf{t1} \rrbracket \text{ else err}; \rightarrow, \rightarrow, \rightarrow. & (9) \\
& (\lambda \mathbf{p} : \text{Den} \times \mathbb{Z}. \text{if } \text{snd}(\mathbf{p}) \equiv_{\mathbb{Z}} \mathbf{i} \text{ then } \text{fst}(\mathbf{p}) \text{ else err}) & (10) \\
& (\text{foldl } \mathbf{nl} (\llbracket \mathbf{x} \text{ as } \mathbf{nt} \rrbracket, 0) \lambda \mathbf{r} : \text{Den} \times \mathbb{Z}. \lambda \mathbf{t} : \star. \lambda \mathbf{ts} : \text{list}[\star]. & (11) \\
& \text{if } \mathbf{i} \equiv_{\mathbb{Z}} \text{snd}(\mathbf{r}) \text{ then } \mathbf{r} \text{ else case } \text{fst}(\mathbf{r}) \text{ of } \llbracket \mathbf{rx} \text{ as } _ \rrbracket \Rightarrow & (12) \\
& \text{if } \mathbf{i} \equiv_{\mathbb{Z}} \text{snd}(\mathbf{r}) + 1 \text{ then} & (13) \\
& \text{if } \mathbf{ts} \equiv_{\text{list}[\star]} \llbracket _ \rrbracket \star \text{ then } (\llbracket \mathbf{rx} \text{ as } \mathbf{t} \rrbracket, \mathbf{i}) & (14) \\
& \text{else } (\llbracket \nabla(\text{fst}(\Delta(\mathbf{rx}))) \text{ as } \mathbf{t} \rrbracket, \mathbf{i}) & (15) \\
& \text{else } (\llbracket \nabla(\text{snd}(\Delta(\mathbf{rx}))) \text{ as } \mathbf{t} \rrbracket, \text{snd}(\mathbf{r}) + 1) \text{ ow err})) \text{ ow err} & (16) \\
& \} & (17)
\end{aligned}$$

This definition uses a left fold function, **foldl**, defined in terms of the right fold operator built into the type-level language in the usual way, as follows:

$$\begin{aligned}
\text{foldl} &:= \lambda \mathbf{l} : \text{list}[\star]. \lambda \mathbf{b} : \text{Den} \times \mathbb{Z}. \lambda \mathbf{f} : (\text{Den} \times \mathbb{Z}) \rightarrow \star \rightarrow \text{list}[\star] \rightarrow (\text{Den} \times \mathbb{Z}). \\
&\text{fold}(\mathbf{l}; \lambda \mathbf{x} : \text{Den} \times \mathbb{Z}. \mathbf{x}; \mathbf{t}, \mathbf{ts}, \mathbf{r}. \lambda \mathbf{x} : \text{Den} \times \mathbb{Z}. \mathbf{r} (\mathbf{f} \mathbf{x} \mathbf{t} \mathbf{ts})) \mathbf{b}
\end{aligned}$$