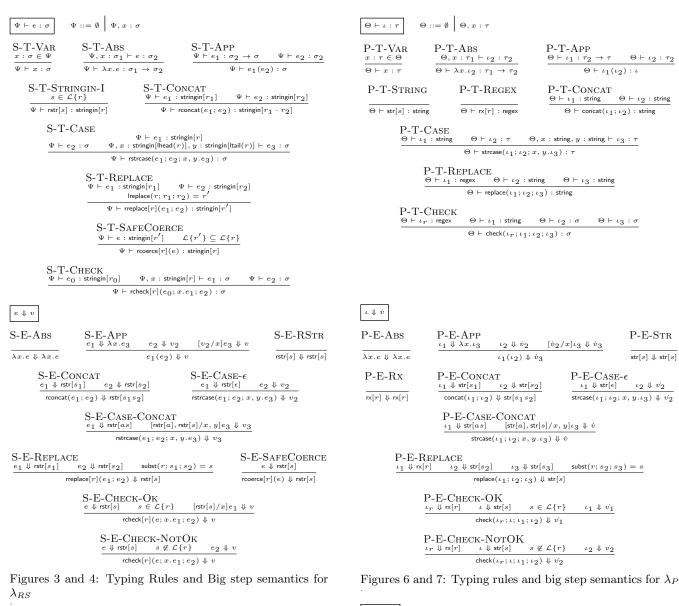
P-E-STR

 $str[s] \Downarrow str[s]$



source types

source terms

source values

target types

target terms

target values

 $s \in \Sigma^*$

 $\langle \sigma \rangle ::= \sigma \rightarrow \sigma$

 $\langle e \rangle ::= x$ $\lambda x.e$

| stringin[r]

 $\langle v \rangle ::= \lambda x.e \mid rstr[s]$

string

 $\langle \dot{v} \rangle \; ::= \; \lambda x . \iota \; | \; \mathsf{str}[\mathbf{s}] \; | \; \; \mathsf{rx}[\mathbf{r}]$

string

 $\langle \, \tau \, \rangle \; ::= \; \tau \, \rightarrow \, \tau$

 $\langle \iota \rangle ::= x$ $| \lambda x . \iota$

 $\begin{array}{l} \text{A.t.} \\ e(e) \\ \text{rstr}[s] \\ \text{rconcat}(e;e) \mid \text{rstrcase}(e;e;x,y.e) \end{array}$

 $\begin{array}{l} \operatorname{rreplace}[r](e;e) \\ \operatorname{rcoerce}[r](e) \mid \operatorname{rcheck}[r](e;x.e;e) \end{array}$

 $\begin{aligned} & \widetilde{\text{rs}}[s] \\ & \kappa[r] \mid \mathsf{concat}(\iota;\iota) \mid \mathsf{strcase}(\iota;\iota;x,y.\iota) \mid \mathsf{replace}(\iota;\iota;\iota) \mid \mathsf{check}(\iota;\iota;\iota;\iota) \end{aligned}$

Figures 2 and 5: Syntax of λ_{RS} and λ_{P} .

$$\begin{array}{ll} \boxed{ \begin{bmatrix} \sigma \end{bmatrix} = \tau \\ } \\ & \frac{TR\text{-}T\text{-}STRING}{ \llbracket \mathsf{stringin}[r] \rrbracket = \mathsf{string} } \\ & \frac{TR\text{-}T\text{-}ARROW}{ \llbracket \sigma_1 \rrbracket = \tau_1 \quad \llbracket \sigma_2 \rrbracket = \tau_2 \\ \hline \llbracket \sigma_1 \to \sigma_2 \rrbracket = \tau_1 \to \tau_2 \\ \hline \end{bmatrix} \\ \boxed{ \begin{bmatrix} \Psi \end{bmatrix} = \Theta } \\ \\ & \frac{TR\text{-}T\text{-}CONTEXT\text{-}EMP}{ \llbracket \emptyset \rrbracket = \emptyset } \\ & \frac{TR\text{-}T\text{-}CONTEXT\text{-}EXT}{ \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau \\ \hline \llbracket \sigma \rrbracket = \iota 1 \quad \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_1 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \iota_2 \quad \llbracket \sigma \rrbracket = \iota_2 \\ \hline \llbracket \sigma \rrbracket = \sigma \rrbracket =$$

Figure 8: Translation from source terms (e) to target terms $(\iota).$