# Active Typechecking and Translation: A Safe Language-Internal Extension Mechanism Appendix

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#### A $@\lambda$

## A.1 Helper Functions

The following helper functions are useful for working with lists of denotations:

```
\begin{split} \mathbf{const} &:= (\lambda \mathbf{a}: \mathsf{list}[\mathsf{Den}]. \lambda \mathbf{d}: \mathsf{Den}. \mathsf{fold}(\mathbf{a}; \mathbf{d}; \_, \_, \_.\mathsf{err})) \\ \mathbf{pop} &:= (\lambda \mathbf{a}: \mathsf{list}[\mathsf{Den}]. \lambda \mathbf{f}: \mathsf{ITm} \to \star \to \mathsf{list}[\mathsf{Den}] \to \mathsf{Den}. \\ & \mathsf{fold}(\mathbf{a}; \mathsf{err}; \mathbf{d}, \mathbf{b}, \_.\mathsf{case} \ \mathbf{d} \ \mathsf{of} \ [\![\mathbf{x} \ \mathsf{as} \ \mathbf{t}]\!] \Rightarrow \mathbf{f} \ \mathbf{x} \ \mathbf{t} \ \mathsf{b} \ \mathsf{ow} \ \mathsf{err})) \\ \mathbf{pop\_final} &:= (\lambda \mathbf{a}: \mathsf{list}[\mathsf{Den}]. \lambda \mathbf{f}: \mathsf{ITm} \to \star \to \mathsf{Den}. \\ & \mathsf{fold}(\mathbf{a}; \mathsf{err}; \mathbf{d}, \mathbf{b}, \_. \\ & \mathsf{fold}(\mathbf{b}; \mathsf{case} \ \mathbf{d} \ \mathsf{of} \ [\![\mathbf{x} \ \mathsf{as} \ \mathbf{t}]\!] \Rightarrow \mathbf{f} \ \mathbf{x} \ \mathsf{t} \ \mathsf{ow} \ \mathsf{err}; \_, \_, \_.\mathsf{err}))) \end{split}
```

The following helper function is useful for checking the equivalence of two types before producing a denotation. If the two types are not equivalent, an error is returned.

```
\mathbf{check\_type} := (\lambda \mathbf{t1} : \star . \lambda \mathbf{t2} : \star . \lambda \mathbf{d} : \mathsf{Den.if} \ \mathbf{t1} \equiv_{\star} \mathbf{t2} \ \mathsf{then} \ \mathbf{d} \ \mathsf{else} \ \mathsf{err})
```

### A.2 Definition of Arrow types

The definition of the Arrow type family is built into  $@\lambda$  as follows:

```
\begin{split} \varSigma_0 &:= \mathrm{Arrow}[\star \times \star, \boldsymbol{ap}[1]] \\ \varPhi_0 &:= \mathrm{Arrow}[\theta_0, \mathbf{i}. \blacktriangledown(\mathsf{rep}(\mathsf{fst}(\mathbf{i})) \to \mathsf{rep}(\mathsf{snd}(\mathbf{i})))] \\ \theta_0 &:= \boldsymbol{ap}[1](\mathbf{i}, \mathbf{a.pop} \ \mathbf{a} \ \lambda \mathbf{x1}: \mathsf{Den}. \lambda \mathbf{t1}: \star. \lambda \mathbf{b}: \mathsf{list}[\mathsf{Den}]. \\ & \mathbf{pop\_final} \ \mathbf{b} \ \lambda \mathbf{x2}: \mathsf{Den}. \lambda \mathbf{t2}: \star. \\ & \mathsf{case} \ \mathbf{t1} \ \mathsf{of} \ \mathsf{Arrow} \langle \mathbf{j} \rangle \Rightarrow \\ & \mathsf{check\_type} \ \mathsf{fst}(\mathbf{j}) \ \mathbf{t2} \ \llbracket \triangledown(\triangle(\mathbf{x1}) \ \triangle(\mathbf{x2})) \ \mathsf{as} \ \mathsf{snd}(\mathbf{j}) \rrbracket \\ & \mathsf{ow} \ \mathsf{err}) \\ \varXi_0 &:= \mathsf{Arrow} \end{split}
```

#### A.3 Deabstraction

$$\vdash_{\Phi} \sigma \notin \sigma'$$

$$\vdash_{\Phi} \gamma \notin \gamma'$$

$$\frac{\text{DEABS-LAM}}{\text{DEABS-VAR}} = \frac{ \begin{array}{c} \text{DEABS-LAM} \\ \vdash_{\varPhi}^{\Xi_0} \sigma \leadsto \sigma' & \vdash_{\varPhi} \sigma' \not \downarrow \sigma'' \\ \\ \vdash_{\varPhi} \gamma \not \downarrow \gamma' \\ \\ \vdash_{\varPhi} \lambda x : \sigma . \gamma \not \downarrow \lambda x : \sigma'' . \gamma' \end{array} }{ \begin{array}{c} \text{DEABS-FIX} \\ \vdash_{\varPhi}^{\Xi_0} \sigma \leadsto \sigma' & \vdash_{\varPhi} \sigma' \not \downarrow \sigma'' \\ \\ \vdash_{\varPhi} \gamma \not \downarrow \gamma' \\ \\ \vdash_{\varPhi} \text{ fix } x : \sigma \text{ is } \gamma \not \downarrow \text{ fix } x : \sigma'' \text{ is } \gamma' \end{array}$$

(omitted forms have trivially recursive rules)

## B Examples

#### B.1 Gödel's T

The implementation of Gödel's T in  $@\lambda$  encodes the following static and dynamic semantics.

#### **Statics**

$$\begin{array}{c} \text{VAR} \\ \hline \Gamma, x : \tau \vdash x : \tau \end{array} \qquad \begin{array}{c} \text{ARROW-INTRO} \\ \hline \Gamma, x : \tau \vdash e : \tau' \\ \hline \Gamma \vdash \lambda x : \tau \vdash e : \tau' \end{array} \qquad \begin{array}{c} \text{ARROW-ELIM} \\ \hline \Gamma \vdash e_1 : \tau \to \tau' \qquad \Gamma \vdash e_2 : \tau \\ \hline \Gamma \vdash e_1 \; e_2 : \tau' \end{array}$$
 
$$\begin{array}{c} \text{NAT-INTRO-S} \\ \hline \Gamma \vdash z : \text{nat} \end{array} \qquad \begin{array}{c} \text{NAT-ELIM} \\ \hline \Gamma \vdash e_1 : \text{nat} \end{array} \qquad \begin{array}{c} \Gamma \vdash e_2 : \tau \\ \hline \Gamma \vdash e_3 : \text{nat} \to \tau \to \tau \end{array}$$

### **Dynamics**

$$\begin{array}{c} \text{LAM-VAL} \\ \frac{\text{LAM-VAL}}{\lambda x : \tau . e \ \text{val}} & \frac{e_1 \mapsto e_1'}{e_1 \mapsto e_1'} & \frac{\text{AP-STEP-R}}{e_2 \mapsto e_2'} & \frac{\text{AP-SUBST}}{e_2 \ \text{val}} \\ \frac{e_2 \mapsto e_2'}{\lambda x : \tau . e \ e_2} & \frac{\lambda x : \tau . e \ e_2'}{\lambda x : \tau . e \ e_2'} & \frac{\lambda x : \tau . e \ e_2 \mapsto [e_2/x] e}{\lambda x : \tau . e \ e_2 \mapsto [e_2/x] e} \\ \\ \frac{\text{Z-VAL}}{\text{z} \ \text{val}} & \frac{\text{S-STEP}}{\text{s}(e) \mapsto \text{s}(e')} & \frac{\text{S-VAL}}{\text{s}(e) \ \text{val}} & \frac{\text{REC-STEP}}{\text{rec}(e_1; e_2; e_3) \mapsto \text{rec}(e_1'; e_2; e_3)} \\ \\ \frac{\text{REC-Z}}{\text{rec}(\mathbf{z}; e_2; e_3) \mapsto e_2} & \frac{\text{REC-S}}{\text{rec}(\mathbf{s}(e); e_2; e_3) \mapsto e_3 \ e \ \text{rec}(e; e_2; e_3)} \end{array}$$

## B.2 *n*-tuples

The static and dynamic semantics of n-tuples (that is, n-ary products) shown below can be encoded in  $@\lambda$ . Notice that this judgemental description of n-tuples relies on elipses frequently. This correspond to folds over the list of types that an n-tuple is indexed by, and underscores the need for a more concrete functional language for extensions, rather than a simple declarative scheme which is only completely precise and decidable when complex side conditions, elipses and search schemes are not necessary.

## **Statics**

$$\frac{n\text{-TUPLE-INTRO}}{\Gamma \vdash e_1 : \tau_1 \quad \cdots \quad \Gamma \vdash e_n : \tau_n} \quad (n \ge 0) \qquad \frac{n\text{-TUPLE-ELIM}}{\Gamma \vdash e : (\tau_1, \dots, \tau_n)} \quad (1 \le i \le n)$$

## **Dynamics**

$$\begin{array}{ll} & n\text{-TUPLE-STEP} \\ e_1 \text{ val} & \cdots & e_{i-1} \text{ val} & e_i \mapsto e_i' \\ \hline (e_1, \dots, e_i, \dots, e_n) \mapsto (e_1, \dots, e_i', \dots, e_n) \end{array} \qquad \begin{array}{l} n\text{-TUPLE-VAL} \\ e_1 \text{ val} & \cdots & e_n \text{ val} \\ \hline (e_1, \dots, e_n) \text{ val} \\ \hline \\ \text{PROJ-} i\text{-STEP} \\ e \mapsto e' \\ \hline \text{pr}[i](e) \mapsto \text{pr}[i](e') \end{array} \qquad \begin{array}{l} \text{PROJ-} i\text{-OF-}n \\ \hline (e_1, \dots, e_n) \text{ val} \\ \hline \\ \text{pr}[i]((e_1, \dots, e_n)) \mapsto e_i \end{array} (1 \leq i \leq n) \end{array}$$

**Implementation in**  $@\lambda$  *n*-tuples are implemented differently depending on *n*. For n = 0 (that is, the unit value), the integer 0 is used. For n = 1, the tuple only contains 1 element so it is represented without any additional run-time adornment. For n > 1,

nested pairs are used.

```
family NTUPLE[list[\star]] \sim i.
                                                                                                                                                                                                                                                         (1)
              \mathsf{fold}(\mathbf{i}; \blacktriangledown(\mathbb{Z}); \mathbf{s}, \mathbf{j}, \mathbf{r}.\mathsf{fold}(\mathbf{j}; \blacktriangledown(\mathsf{rep}(\mathbf{s})); \_, \_, \_. \blacktriangledown(\mathsf{rep}(\mathbf{s}) \times \blacktriangle(\mathbf{r})))) \; \{
                                                                                                                                                                                                                                                         (2)
       new[1](\_, \mathbf{a}.\mathsf{fold}(\mathbf{a}; \llbracket \triangledown(0) \text{ as } \mathrm{NTUPLE} \langle \llbracket \rrbracket_\star \rangle \rrbracket; \mathbf{d}, \mathbf{b}, \mathbf{r}.
                                                                                                                                                                                                                                                         (3)
                      case d of \llbracket dx as dt \rrbracket \Rightarrow case r of \llbracket rx as rt \rrbracket \Rightarrow
                                                                                                                                                                                                                                                         (4)
                      \mathsf{case}\ \mathbf{rt}\ \mathsf{of}\ \mathrm{Ntuple}\langle \mathbf{i}\rangle \Rightarrow \mathsf{fold}(\mathbf{b}; \llbracket \mathbf{dx}\ \mathsf{as}\ \mathrm{Ntuple}\langle \mathbf{dt} :: \mathbf{i}\rangle \rrbracket; \_, \_, \_.
                                                                                                                                                                                                                                                        (5)
                             \llbracket \triangledown((\triangle(\mathbf{dx}), \triangle(\mathbf{rx}))) \text{ as } \mathrm{NTUPLE}\langle \mathbf{dt} :: \mathbf{i} \rangle \rrbracket) \text{ ow err ow err ow err)};
                                                                                                                                                                                                                                                         (6)
       pr[\mathbb{Z}](\mathbf{i}, \mathbf{a}.\mathbf{pop\_final} \ \mathbf{a} \ \lambda \mathbf{x}:\mathsf{Den}.\lambda \mathbf{nt}:\star.\mathsf{case} \ \mathbf{nt} \ \mathsf{of} \ \mathsf{Ntuple}\langle \mathbf{nl} \rangle \Rightarrow
                                                                                                                                                                                                                                                         (7)
              fold(\mathbf{nl}; err; \mathbf{t1}, \mathbf{j}, ...
                                                                                                                                                                                                                                                         (8)
              \mathsf{fold}(\mathbf{j};\mathsf{if}\ \mathbf{i} \equiv_{\mathbb{Z}} 0\ \mathsf{then}\ \llbracket\mathbf{x}\ \mathsf{as}\ \mathbf{t1}\rrbracket\ \mathsf{else}\ \mathsf{err};\_,\_,\_.
                                                                                                                                                                                                                                                        (9)
                      \mathsf{fst}(\mathbf{foldl}\ \mathbf{nl}\ (\llbracket \mathbf{x}\ \mathsf{as}\ \mathbf{nt} \rrbracket, 0)\ \lambda \mathbf{r}: \mathsf{Den} \times \mathbb{Z}.\lambda \mathbf{t}: \star.\lambda \mathbf{ts}: \mathsf{list}[\star].
                                                                                                                                                                                                                                                     (10)
                             if i \equiv_{\mathbb{Z}} \mathsf{snd}(\mathbf{r}) then \mathbf{r} else case \mathsf{fst}(\mathbf{r}) of [\![\mathbf{r}\mathbf{x}\ \mathsf{as}\ \_]\!] \Rightarrow
                                                                                                                                                                                                                                                     (11)
                                     if \mathbf{i} \equiv_{\mathbb{Z}} \operatorname{snd}(\mathbf{r}) + 1 then
                                                                                                                                                                                                                                                     (12)
                                            if \mathbf{ts} \equiv_{\mathsf{list}[\star]} []_{\star} then ([\![\mathbf{rx} \ \mathsf{as} \ \mathbf{t}]\!], \mathbf{i})
                                                                                                                                                                                                                                                     (13)
                                              else ([\![ \triangledown(\mathsf{fst}(\triangle(\mathbf{rx}))) \text{ as } \mathbf{t} ]\!], \mathbf{i})
                                                                                                                                                                                                                                                     (14)
                                       else ([\![ \nabla (\operatorname{snd}(\triangle(\mathbf{r}\mathbf{x}))) \text{ as } \mathbf{t} ]\!], \operatorname{snd}(\mathbf{r}) + 1) ow \operatorname{err}))) ow \operatorname{err})
                                                                                                                                                                                                                                                     (15)
}
                                                                                                                                                                                                                                                     (16)
```

This definition uses a left fold function, **foldl**, defined in terms of the right fold operator built into the type-level language in the usual way, as follows:

```
\begin{aligned} \mathbf{foldl} := \lambda \mathbf{l} : & \mathsf{list}[\star]. \lambda \mathbf{b} : \mathsf{Den} \times \mathbb{Z}. \lambda \mathbf{f} : (\mathsf{Den} \times \mathbb{Z}) \to \star \to \mathsf{list}[\star] \to (\mathsf{Den} \times \mathbb{Z}). \\ & \mathsf{fold}(\mathbf{l}; \lambda \mathbf{x} : \mathsf{Den} \times \mathbb{Z}. \mathbf{x}; \mathbf{t}, \mathbf{ts}, \mathbf{r}. \lambda \mathbf{x} : \mathsf{Den} \times \mathbb{Z}. \mathbf{r} \ (\mathbf{f} \ \mathbf{x} \ \mathbf{t} \ \mathbf{ts})) \ \mathbf{b} \end{aligned}
```