

source types

source terms

source values

target types

target terms

target values

 $s \in \Sigma^*$ 

 $\langle \sigma \rangle ::= \sigma \rightarrow \sigma$ 

 $\langle e \rangle ::= x$  $\lambda x.e$ 

 $\mid \ \, \mathsf{stringin}[r]$ 

 $\langle v \rangle \ ::= \ \lambda x.e \mid \mathsf{rstr}[e] \mid s$ 

string

 $\langle \dot{v} \rangle \; ::= \; \lambda x . \iota \; | \; \mathsf{str}[\mathbf{s}] \; | \; \; \mathsf{rx}[\mathbf{r}]$ 

string

 $\langle \, \tau \, \rangle \; ::= \; \tau \, \rightarrow \, \tau$ 

 $\langle \iota \rangle ::= x \\ | \lambda x . \iota$ 

 $\begin{array}{l} \text{A.t.} \\ e(e) \\ \text{rstr}[s] \\ \text{rconcat}(e;e) \mid \text{rstrcase}(e;e;x,y.e) \end{array}$ 

 $\begin{array}{l} \operatorname{rreplace}[r](e;e) \\ \operatorname{rcoerce}[r](e) \mid \operatorname{rcheck}[r](e;x.e;e) \end{array}$ 

 $\begin{aligned} & \widetilde{\text{rs}}[s] \\ & \kappa[r] \mid \mathsf{concat}(\iota;\iota) \mid \mathsf{strcase}(\iota;\iota;x,y.\iota) \mid \mathsf{replace}(\iota;\iota;\iota) \mid \mathsf{check}(\iota;\iota;\iota;\iota) \end{aligned}$ 

Figures 2 and 5: Syntax of  $\lambda_{RS}$  and  $\lambda_{P}$ .

$$\begin{array}{c} \boxed{ \begin{bmatrix} \llbracket \sigma \rrbracket = \tau \end{bmatrix} } \\ \frac{TR\text{-}T\text{-}STRING}{\llbracket \mathsf{stringin}[r] \rrbracket = \mathsf{string}} & \frac{TR\text{-}T\text{-}ARROW}{\llbracket \sigma_1 \rrbracket = \tau_1 \quad \llbracket \sigma_2 \rrbracket = \tau_2} \\ \boxed{ \llbracket \Psi \rrbracket = \Theta \end{bmatrix} \\ \\ \frac{TR\text{-}T\text{-}CONTEXT\text{-}EMP}{\llbracket \emptyset \rrbracket = \emptyset} & \frac{TR\text{-}T\text{-}CONTEXT\text{-}EXT}{\llbracket \Psi \rrbracket = \Theta \quad \llbracket \sigma \rrbracket = \tau} \\ \boxed{ \llbracket \Psi \rrbracket = \omega \end{bmatrix} \\ \\ \frac{TR\text{-}VAR}{\llbracket x \rrbracket = x} & \frac{TR\text{-}ABS}{\llbracket e \rrbracket = \iota} & \frac{TR\text{-}APP}{\llbracket u_1 \rrbracket = \iota_1 \quad \llbracket e_2 \rrbracket = \iota_2} \\ \boxed{ \llbracket e_1 \rrbracket = \iota_1 \quad \llbracket e_2 \rrbracket = \iota_2 \quad \llbracket e_3 \rrbracket = \iota_3 \\ \boxed{ \llbracket \mathsf{rstrcase}(e_1; e_2; x, y. e_3) \rrbracket = \mathsf{strcase}(\iota_1; \iota_2; x, y. \iota_3)} \\ \hline \\ \frac{TR\text{-}CONCAT}{\llbracket e_1 \rrbracket = \iota_1 \quad \llbracket e_2 \rrbracket = \iota_2 \quad \llbracket e_3 \rrbracket = \iota_3 \\ \boxed{ \llbracket \mathsf{rencoat}(e_1; e_2) \rrbracket = \mathsf{concat}(\iota_1; \iota_2)} \\ \hline \\ \frac{TR\text{-}SAFECOERCE}{\llbracket e \rrbracket = \iota} & \frac{TR\text{-}CHECK}{\llbracket e \rrbracket = \iota} & \frac{e_1 \rrbracket = \iota_1 \quad \llbracket e_2 \rrbracket = \iota_2}{\llbracket \mathsf{rencek}(r](e_1; e_2) \rrbracket = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2)) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2)) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2)) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2)) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2)) = \mathsf{replace}(r_1(e_1; \iota_2)) = \mathsf{replace}(r_1(e_1; \iota_2) = \mathsf{replace}(r_1(e_1; \iota_2)) = \mathsf{rep$$

Figure 8: Translation from source terms (e) to target terms  $(\iota).$