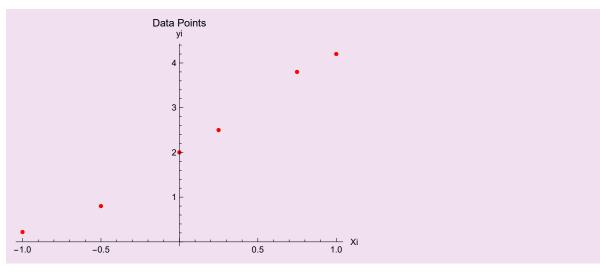
```
In[@]:=
          points = \{\{-1, 3\}, \{0, 0.5\}, \{0.5, 0\}, \{1, 1\}\};
          langrangePoly = InterpolatingPolynomial[points, x]
                              插值多项式
Out[0]=
         3 + (1 + x) (-1 + (-1 + x) (1.5 + 1.x))
          f25 = langrangePoly /. x \rightarrow 0.25
 In[0]:=
Out[0]=
          0.109375
         f75 = langrangePoly /. x \rightarrow 0/75
 In[0]:=
Out[0]=
          0.5
          points = \{\{-1, 1.5\}, \{0, 0\}, \{0.5, 0\}, \{1, 0.5\}\};
 In[0]:=
          langrangePoly = InterpolatingPolynomial[points, x];
                              插值多项式
          f25 = langrangePoly /. x \rightarrow -0.25;
          f25' = langrangePoly /. x \rightarrow 0.25;
          {langrangePoly, f25, f25'}
Out[0]=
          \{1.5 + (-0.5 + 1. (-1 + x)) (1 + x), 0.1875, -0.0625\}
 In[@]:=
          ?Fit
Out[0]=
           Symbol
                                                                                                         0
           Fit[data, {f_1, ..., f_n}, {x, y, ...}] 求变量{x, y, ...} 的函数 f_1, ..., f_n 的 data 列表拟合 a_1f_1 + ... + a_nf_n.
            Fit[\{m, v\}] 求最小化设计矩阵 m 的 \parallel m.a – v \parallel 的拟合向量 a.
            Fit[..., "prop"] 指定应返回哪些拟合属性 prop.
           Documentation Web »
                 Options {FitRegularization → None, NormFunction → Automatic, WorkingPrecision → Automatic}
                Attributes {Protected}
                Full Name System`Fit
```

```
In[ • ]:=
        data =
           \{\{-1.00, 0.22\}, \{-0.50, 0.80\}, \{0, 2.0\}, \{0.25, 2.5\}, \{0.75, 3.8\}, \{1.00, 4.2\}\};
        linearFit = Fit[data, {1, x}, x]
                    拟合
        quadraticFit = Fit[data, {1, x, x^2}, x]
                       拟合
        ListPlot[data, PlotStyle → Red, PlotLabel → "Data Points",
                       绘图样式 红色 绘图标签
         AxesLabel \rightarrow {"Xi", "yi"}, PlotRange \rightarrow All]
         坐标轴标签
                                    绘制范围
        Show[Plot[linearFit, \{x, -1.1, 1.1\}, PlotStyle \rightarrow Blue, PlotLabel \rightarrow "Linear Fit"],
                                               绘图样式
                                                         蓝色 绘图标签
         Plot[quadraticFit, \{x, -1.1, 1.1\}, PlotStyle \rightarrow Green, PlotLabel \rightarrow "Quadratic Fit"],
                                                                绘图标签
         绘图
                                                         绿色
                                                                                         拟合
                                              绘图样式
         ListPlot[data, PlotStyle → Red, PlotMarkers → Automatic],
                         绘图样式 红色 绘制点的标记 自动
         绘制点集
         PlotRange → All, AxesLabel → {"Xi", "yi"}]
                  全部 坐标轴标签
         绘制范围
Out[0]=
        2.07897 + 2.09235 x
Out[0]=
        1.94449 + 2.0851 x + 0.28191 x^{2}
Out[0]=
```



```
Out[0]=
```

```
Linear Fit
-0.5
                                                 1.0
```

```
points = {{19, 19.00}, {23, 28.50}, {30, 47.00}, {35, 68.20}, {40, 90.00}};
In[@]:=
       fit = Fit[points, \{1, x^2\}, x]
             拟合
```

```
-2.37227 + 0.0573264 x^2
```

```
In[0]:=
       points = \{\{0, 2.00\}, \{1, 2.50\}, \{2, 4.00\}, \{3, 6.00\}, \{4, 8.00\}\};
       fitParams = FindFit[points, a * Exp[b * x], {a, b}, x]
                    求拟合
       fit = a * Exp[b * x] /. fitParams
                指数形式
```

Out[0]=

```
\{\, \textbf{a} \rightarrow \textbf{1.94454,} \ \textbf{b} \rightarrow \textbf{0.358018} \,\}
```

Out[0]=

1.94454 $e^{0.358018 \times}$

```
In[\circ]:= C = \{-3, -2\};
       m = \{\{1, -2\}, \{-3, -2\}, \{-1, 1\}\};
       b = \{-4, -14, -3\};
       1 = \{0, 0\};
       solution = LinearProgramming[c, m, b]
```

Out[@]=

```
{4, 1}
```

```
| c = {2, 3, 4};
| delta = 10<sup>-5</sup>;
| m = {{-1, -2, 1}, {-1, -1, 1}, {0, -1, -2}};
| b = {10 + delta, 60, 12 + delta};
| solution = LinearProgramming[c, -m, b, {delta, delta, 1 + delta}]
```

```
\left\{\frac{2\,550\,001}{50\,000},\,\frac{999\,999}{100\,000},\,\frac{100\,001}{100\,000}\right\}
```

```
(*We make some modifications: z' = z - 1, \text{ then } z' > 0 min m = 2x+3y+4z'+4 x = x_1-x_2, y = y_1-y_2, z' = z_1-z_2*) c = \{2, -2, 3, -3, 4, -4, 0, 0\}; m = \{\{1, -1, 2, -2, -1, 1, -1, 0\}, \{1, -1, 1, -1, -1, 1, 0, 0\}, \{0, 0, 1, -1, 2, -2, 0, -1\}\}; b = \{11, 61, 10\}; solution = LinearProgramming[c, m, b]
```

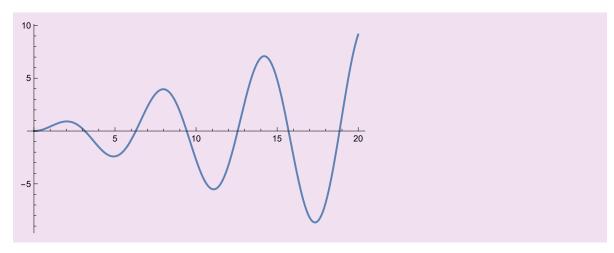
··· LinearProgramming: 该问题是无界的.

Out[0]=

```
{Indeterminate, Indeterminate, Indeterminate, Indeterminate, Indeterminate, Indeterminate}
```

$$\left\{\left\{y\left[x\right]\rightarrow\frac{1}{4}\,\left(-2\,\text{Cos}\left[x\right]\,+2\,\text{Cos}\left[x\right]^{\,3}+2\,x\,\text{Sin}\left[x\right]\,+\text{Sin}\left[x\right]\,\text{Sin}\left[2\,x\right]\right)\right\}\right\}$$

Out[0]=



2.0

1.5 1.0 0.5

Out[3]=

```
Clear ["Global`*"]

ipil solution = NDSolve \left[ \left\{ u'[t] = \theta.\theta9 * u[t] * \left( 1 - \frac{u[t]}{2\theta} \right) - \theta.45 * u[t] * v[t] \right\} \right]

v'[t] = \theta.\theta6 * v[t] * \left( 1 - \frac{v[t]}{15} \right) - \theta.\theta01 * u[t] * v[t] ,

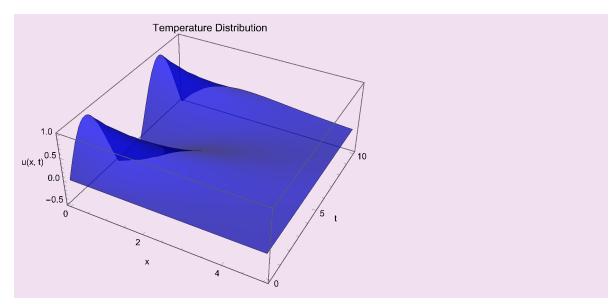
u[\theta] = 1.6, v[\theta] = 1.2 , \{u, v\}, \{t, 2\theta\} \}

Plot [Evaluate [\{u[t], v[t]\} / . solution], \{t, \theta, 2\theta\}, Plot Labels \rightarrow \{"u(t)", "v(t)"\}, \}

By By Hamping Plot Egends \rightarrow Placed \{"u(t)", "v(t)"\}, Above], Plot Style <math>\rightarrow \{Blue, Red\} \}

Example Plot [and the place of the place of the plot of the place o
```

```
In[@]:=
       heatEquation = D[u[x, t], t] = D[u[x, t], \{x, 2\}];
       initialCondition = u[x, 0] == 0;
       boundaryConditions = \{u[0, t] = Sin[t], u[5, t] = 0\};
       solution = NDSolve[
                  数值求解微分方程组
           {heatEquation, initialCondition, boundaryConditions}, u, \{x, 0, 5\}, \{t, 0, 10\}];
       Plot3D[Evaluate[u[x, t] /. solution], {x, 0, 5}, {t, 0, 10},
        PlotLabel \rightarrow "Temperature Distribution", AxesLabel \rightarrow {"x", "t", "u(x, t)"},
        Mesh \rightarrow None, \ PlotStyle \rightarrow Directive[Opacity[0.7], \ Blue]]
                    绘图样式
        网格 无
                                指令
```



```
In[63]:=
      ClearAll[u, x, t]
      清除全部
      (*定义波动方程*)len = 10; (*定义计算区域的长度*)
      pde = D[u[x, t], \{t, 2\}] = D[u[x, t], \{x, 2\}];
      (*设置初始条件*)
      ic = \{u[x, 0] = Exp[-x^2], Derivative[0, 1][u][x, 0] = 0\}; (*初始位移和速度*)
                   指数形式导数
      (*设置边界条件: 周期性边界条件*)
      bc = \{u[-len, t] = u[len, t],
         Derivative[1, 0][u][-len, t] == Derivative[1, 0][u][len, t]};
         导数
      (*使用 NDSolve 求解波动方程*)
            数值求解微分方程组
      solution = NDSolve[{pde, ic[[1]], ic[[2]], bc[[1]], bc[[2]]}, u, {x, -len, len}, {t, 0, 40}]
               数值求解微分方程组
```

Out[68]=

```
\left\{\left\{u \to \text{InterpolatingFunction} \left[\begin{array}{c} \blacksquare \\ \end{array}\right] \begin{array}{l} \text{Domain: } \{\{\text{-10., 10.}\}, \{0., 40.\}\} \\ \text{Output: scalar} \end{array}\right]\right\}\right\}
                                                                                               没有保存数据; 立即保存 ⋺
```

(*可视化解*)uSolution $[x_, t_] := u[x, t] /. solution[1];$ In[71]:= $\label{eq:plot3D} {\tt Plot3D[uSolution[x, t], \{x, -len, len\}, \{t, 0, 40\}, PlotRange} \rightarrow {\tt All},$ 绘制三维图形 绘制范围 AxesLabel \rightarrow {"x", "t", "u(x, t)"}, MeshFunctions \rightarrow {#3 &}, Mesh \rightarrow 10] 坐标轴标签 网格函数

Out[72]=

