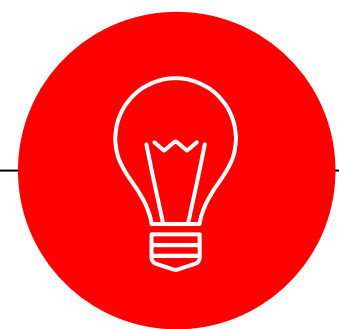


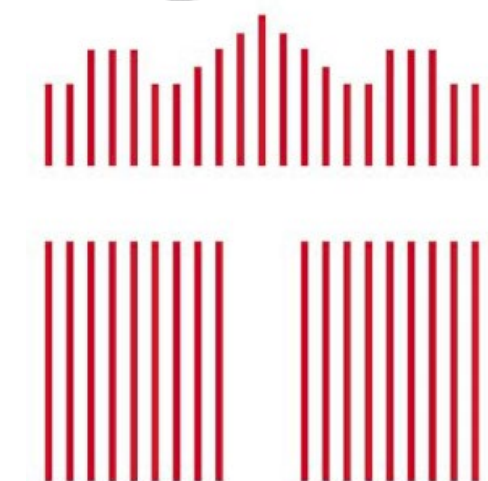
# *Applied Deep Learning*



# Transformer



September 11th, 2024 <http://adl.miulab.tw>



**National  
Taiwan  
University**  
國立臺灣大學

2

# Sequence Encoding

## Basic Attention

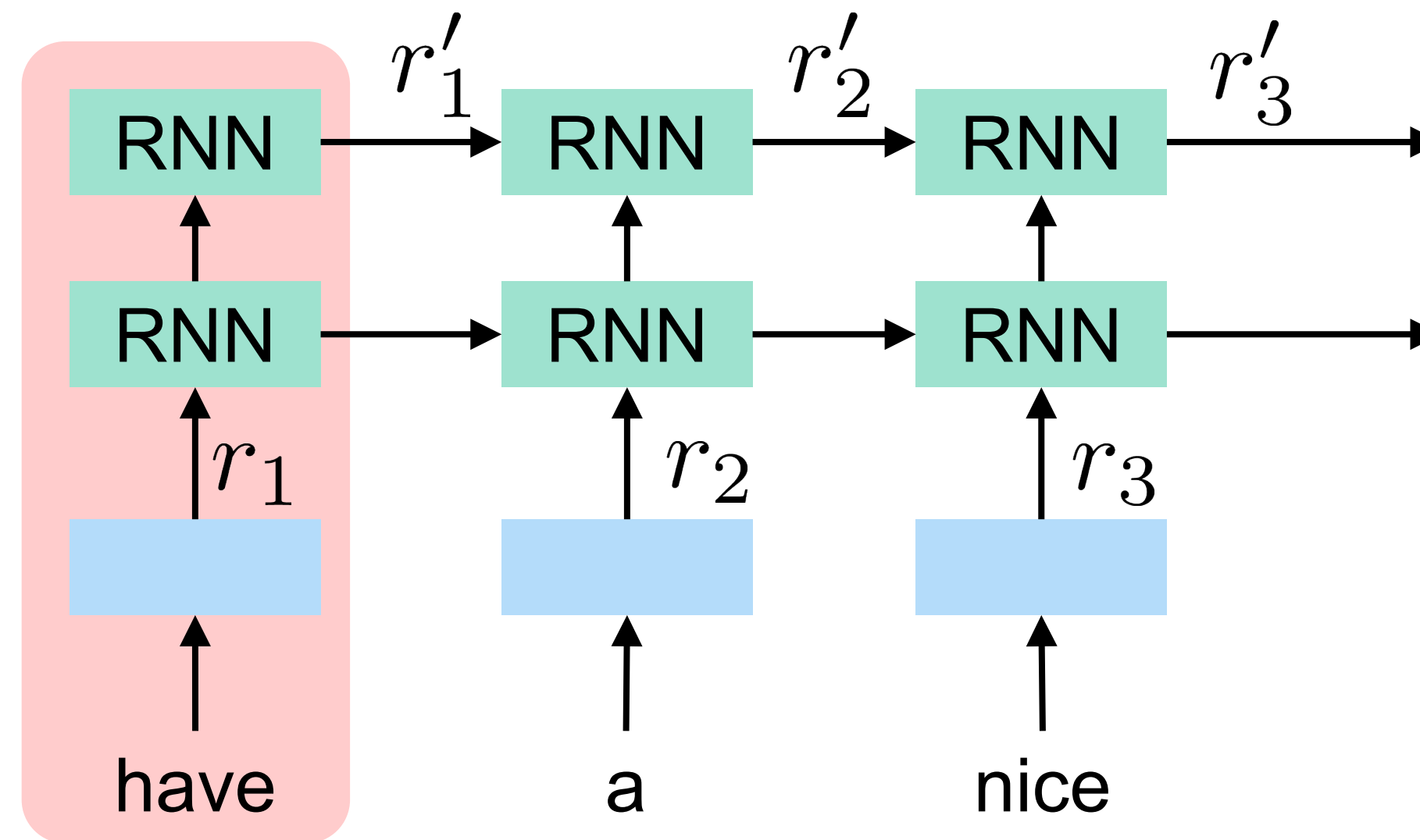
# Representations of Variable Length Data

- ◉ Input: word sequence, image pixels, audio signal, click logs
- ◉ Property: continuity, temporal, importance distribution
- ◉ Example
  - ✓ Basic combination: average, sum
  - ✓ Neural combination: network architectures should consider input domain properties
    - CNN (convolutional neural network)
    - RNN (recurrent neural network): temporal information

Network architectures should consider the input domain properties

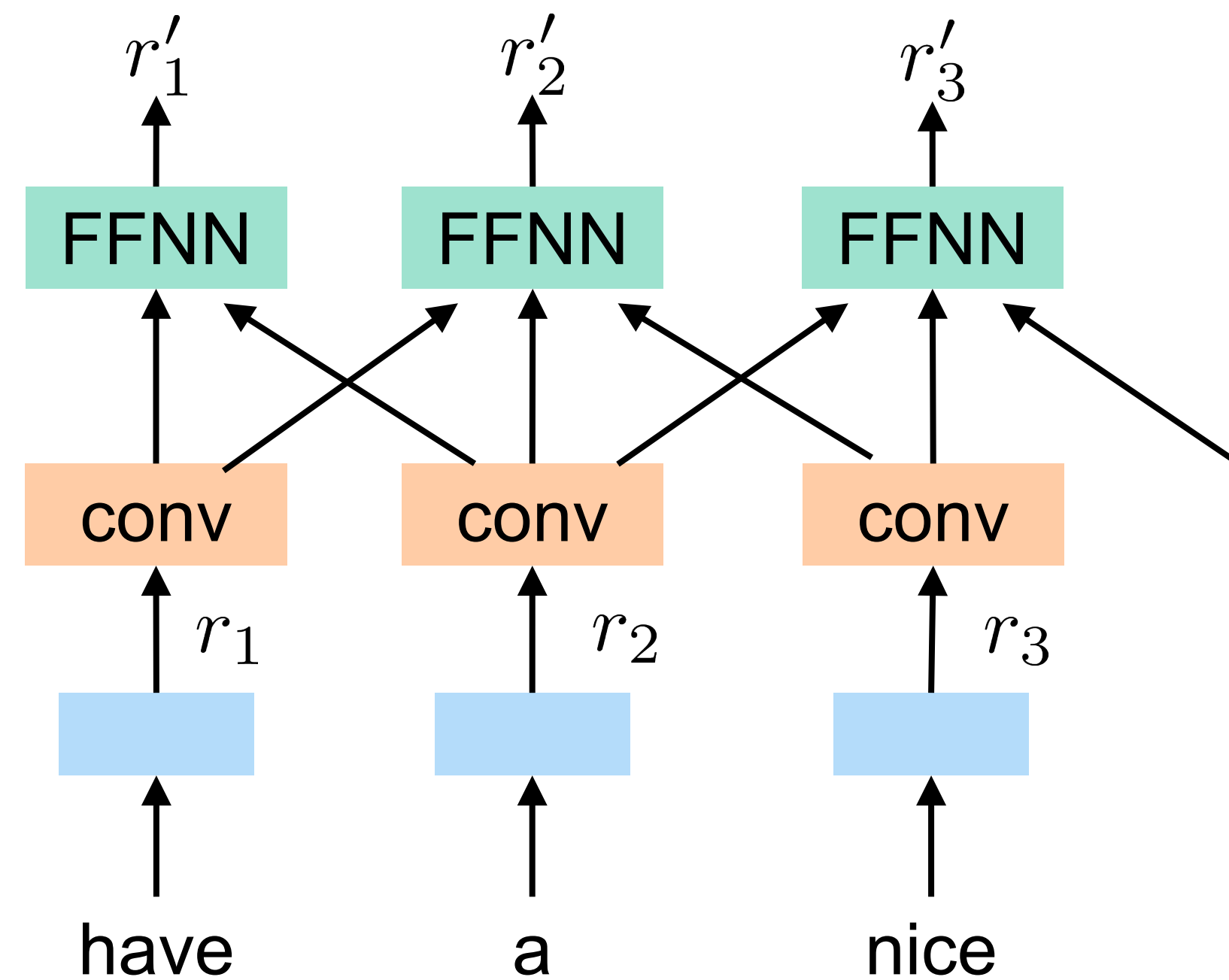
# 4 Recurrent Neural Networks

- Learning variable-length representations
  - ✓ Fit for sentences and sequences of values
- Sequential computation makes parallelization difficult
- No explicit modeling of long and short range dependencies



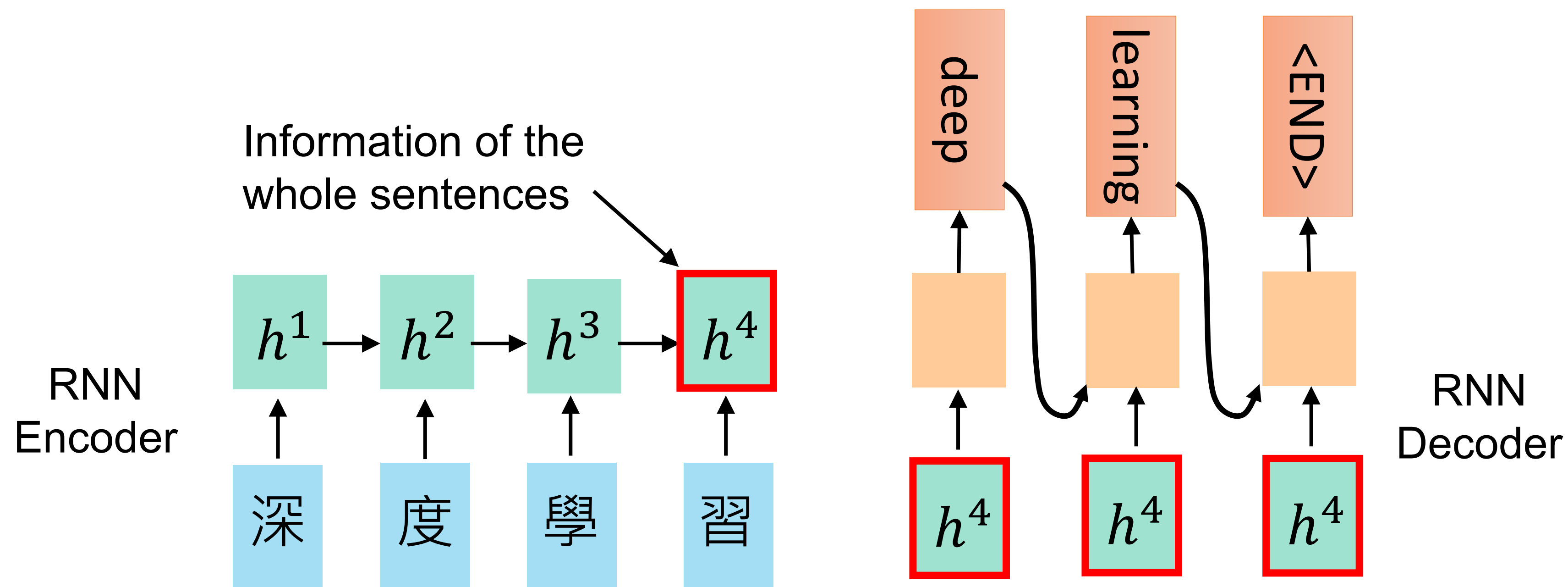
# Convolutional Neural Networks

- Easy to parallelize
- Exploit local dependencies
  - ✓ **Long-distance** dependencies require many layers



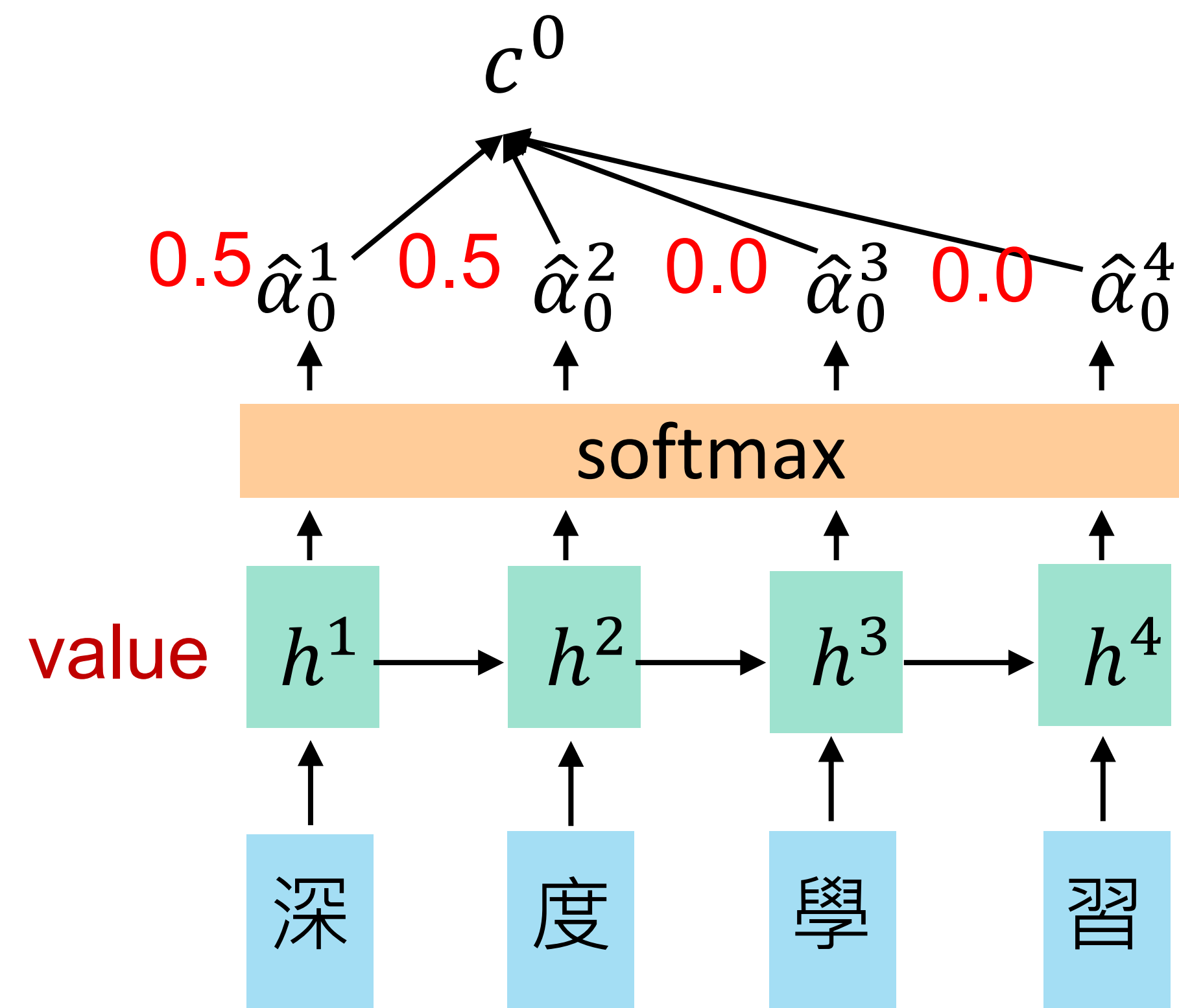
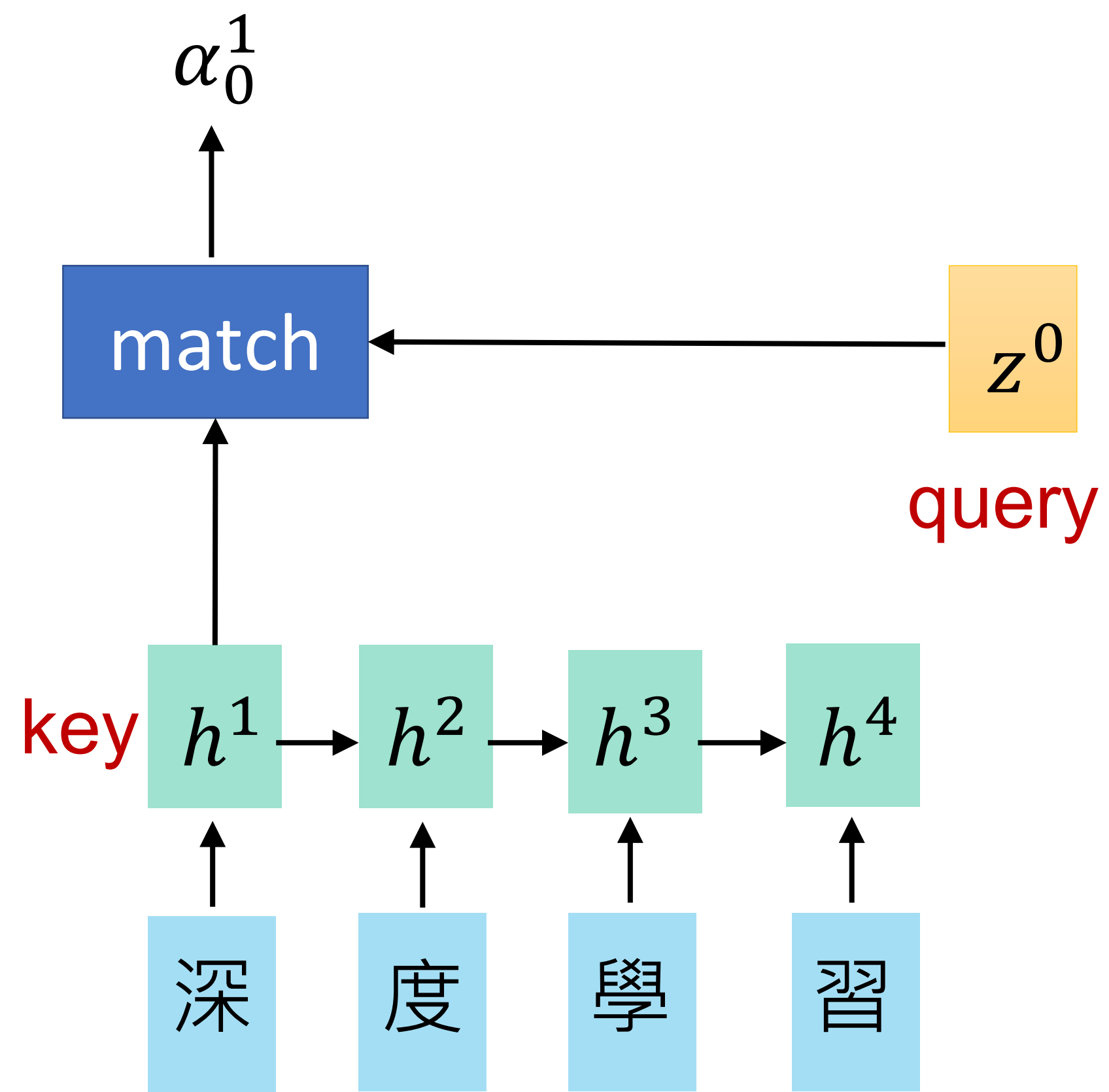
# Attention

- Encoder-decoder model is important in NMT
- RNNs need **attention mechanism** to handle long dependencies
- Attention allows us to **access any state**



7

# Basic Attention





# Dot-Product Attention

- Input: a query  $q$  and a set of key-value ( $k$ - $v$ ) pairs to an output
- Output: weighted sum of values

Inner product of  
query and corresponding key

$$A(q, K, V) = \sum_i \frac{\exp(q \cdot k_i)}{\sum_j \exp(q \cdot k_j)} v_i$$

- ✓ Query  $q$  is a  $d_k$ -dim vector
- ✓ Key  $k$  is a  $d_k$ -dim vector
- ✓ Value  $v$  is a  $d_v$ -dim vector



# Dot-Product Attention in Matrix

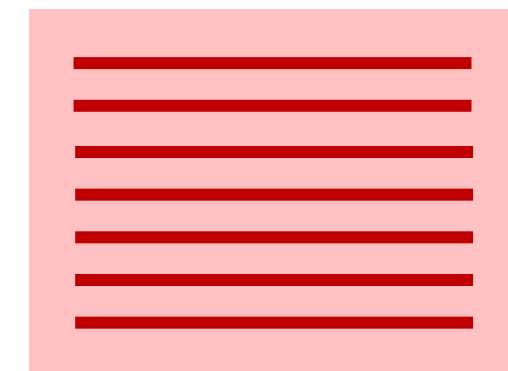
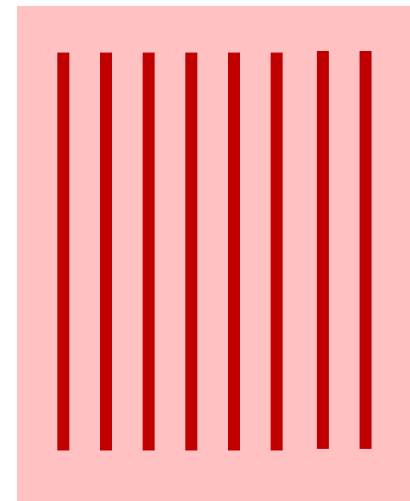
- Input: *multiple* queries  $q$  and a set of key-value ( $k$ - $v$ ) pairs to an output
- Output: a set of weighted sum of values

$$A(q, K, V) = \sum_i \frac{\exp(q \cdot k_i)}{\sum_j \exp(q \cdot k_j)} v_i$$

$$A(Q, K, V) = \text{softmax}(QK^T)V$$

$$[|Q| \times d_k] \times [d_k \times |K|] \times [|K| \times d_v]$$

softmax  
row-wise



$$= [|Q| \times d_v]$$

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# Sequence Encoding

## Self-Attention

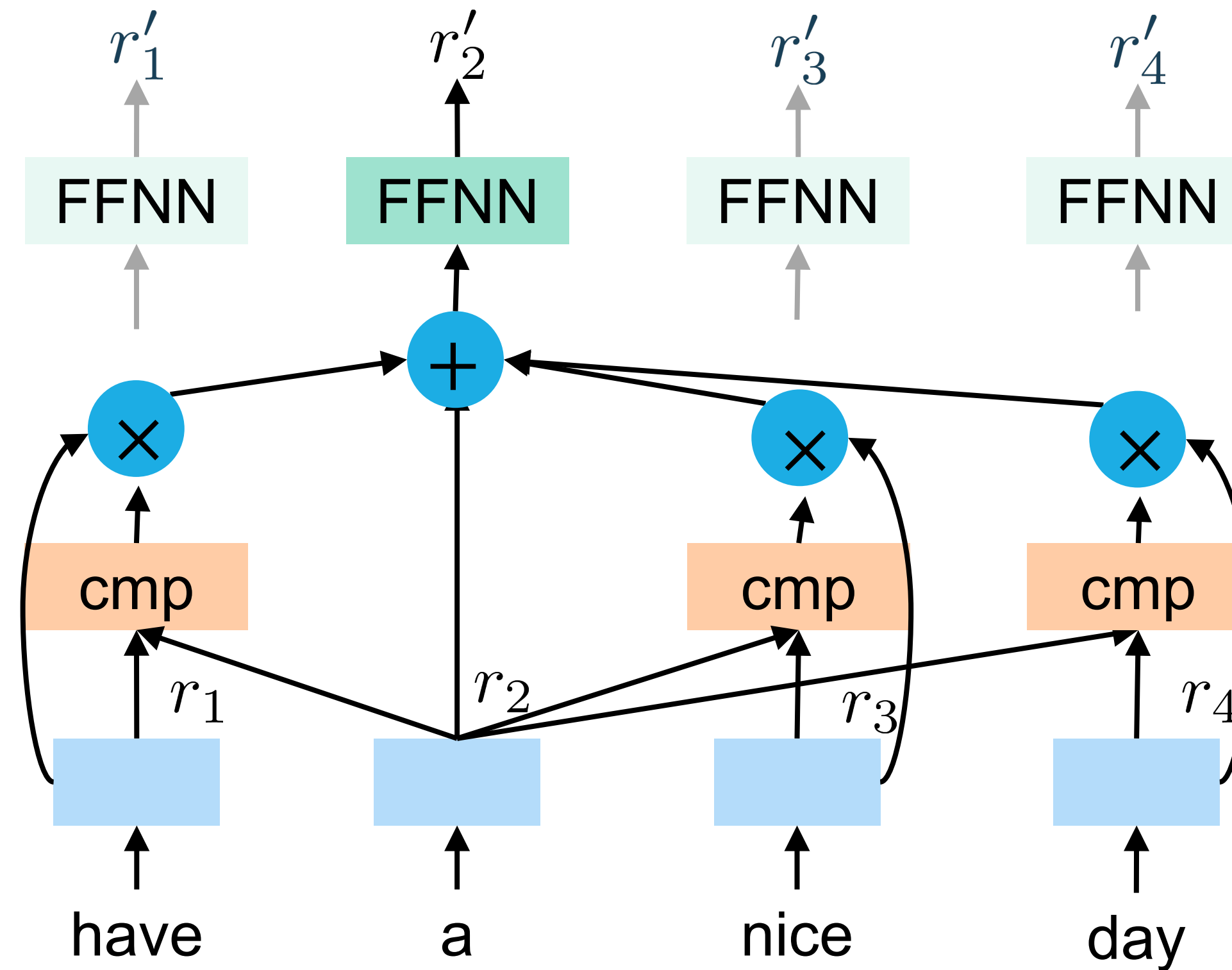
# Attention

- Encoder-decoder model is important in NMT
- RNNs need **attention mechanism** to handle long dependencies
- Attention allows us to access any state

Using attention to replace recurrence architectures

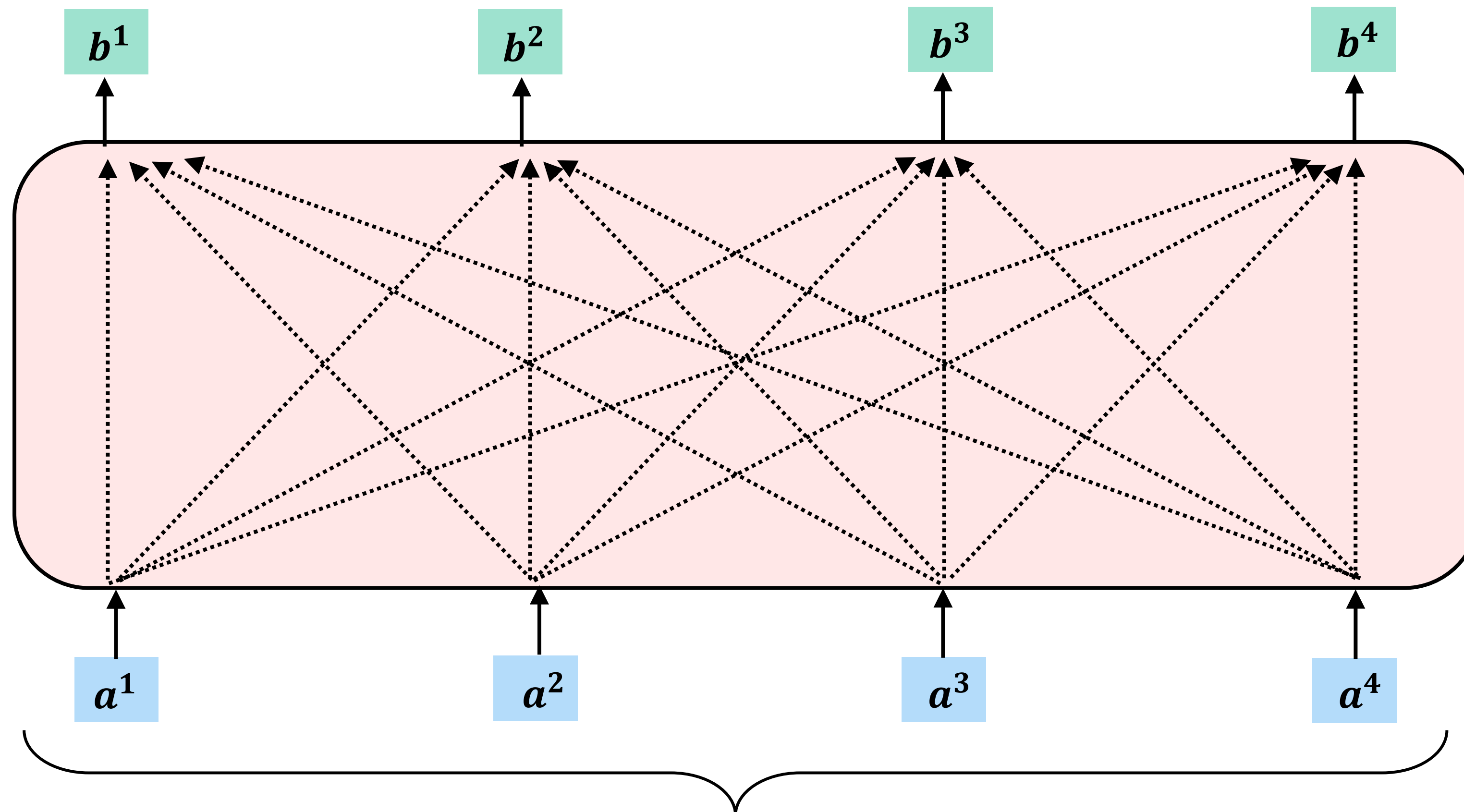
# Self-Attention

- Constant “path length” between two positions
- Easy to parallelize



# Self-Attention

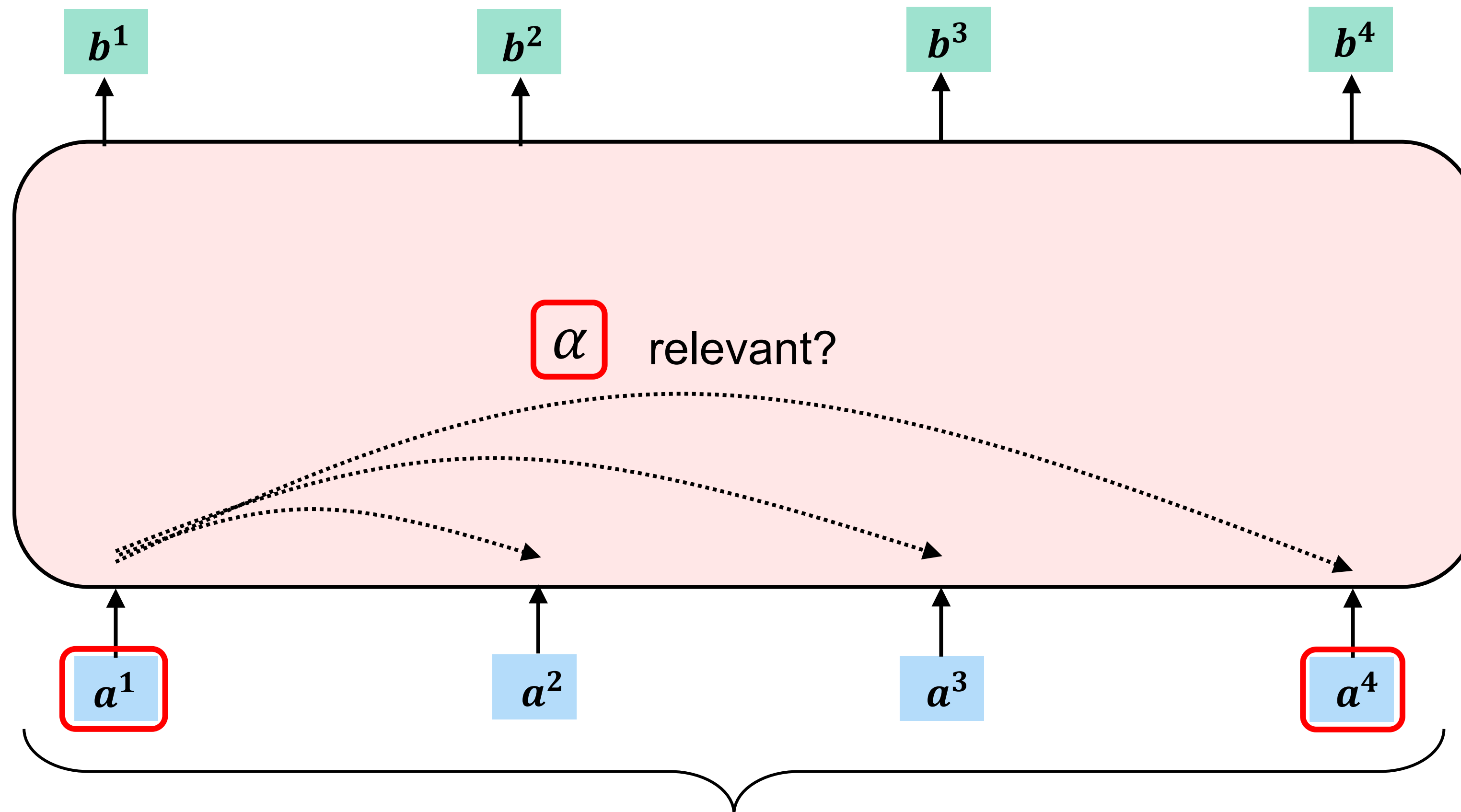
- Constant “path length” between two positions
- Easy to parallelize



Can be either **input** or a **hidden layer**

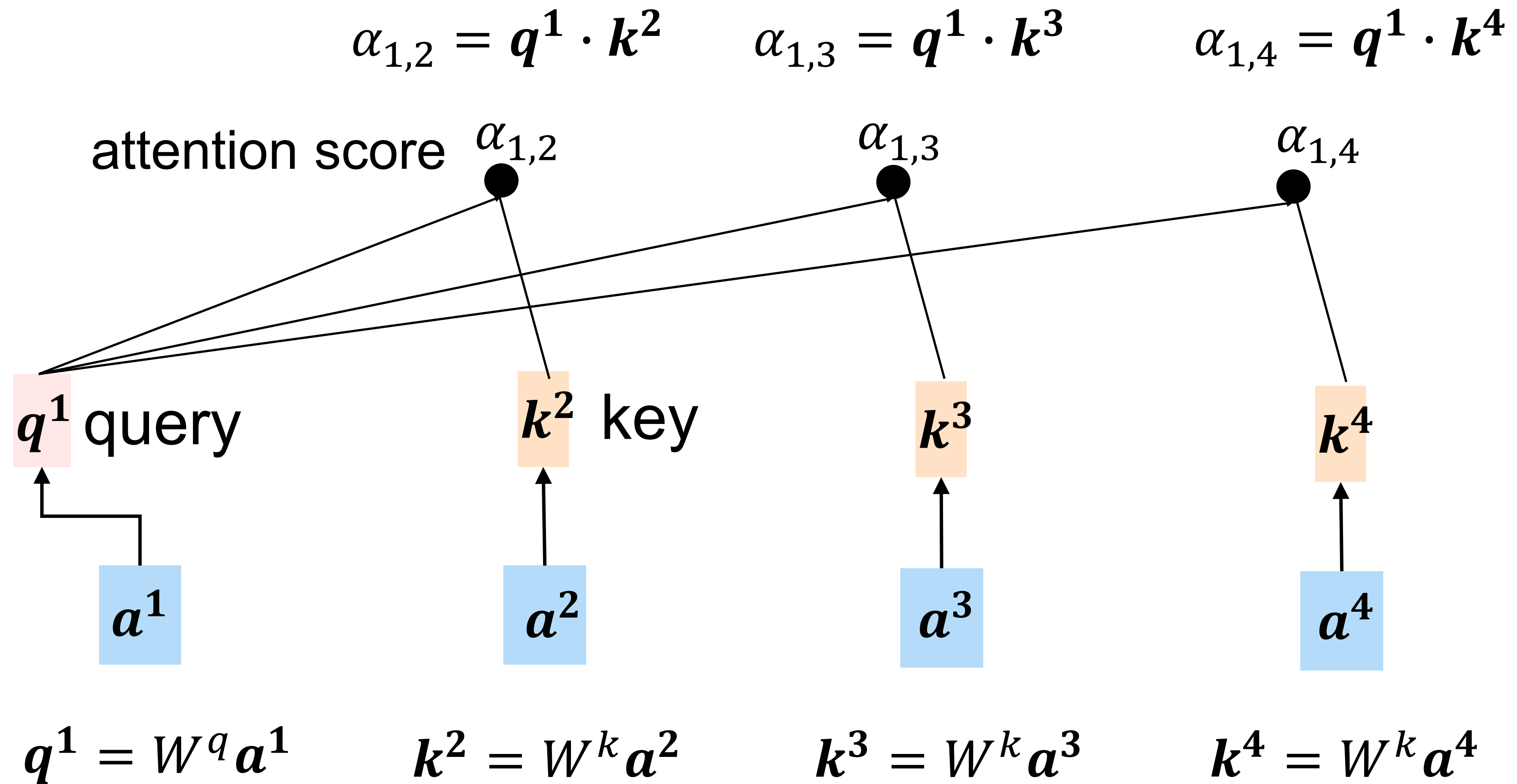
# Self-Attention

- Constant “path length” between two positions
- Easy to parallelize



Can be either **input** or a **hidden layer**

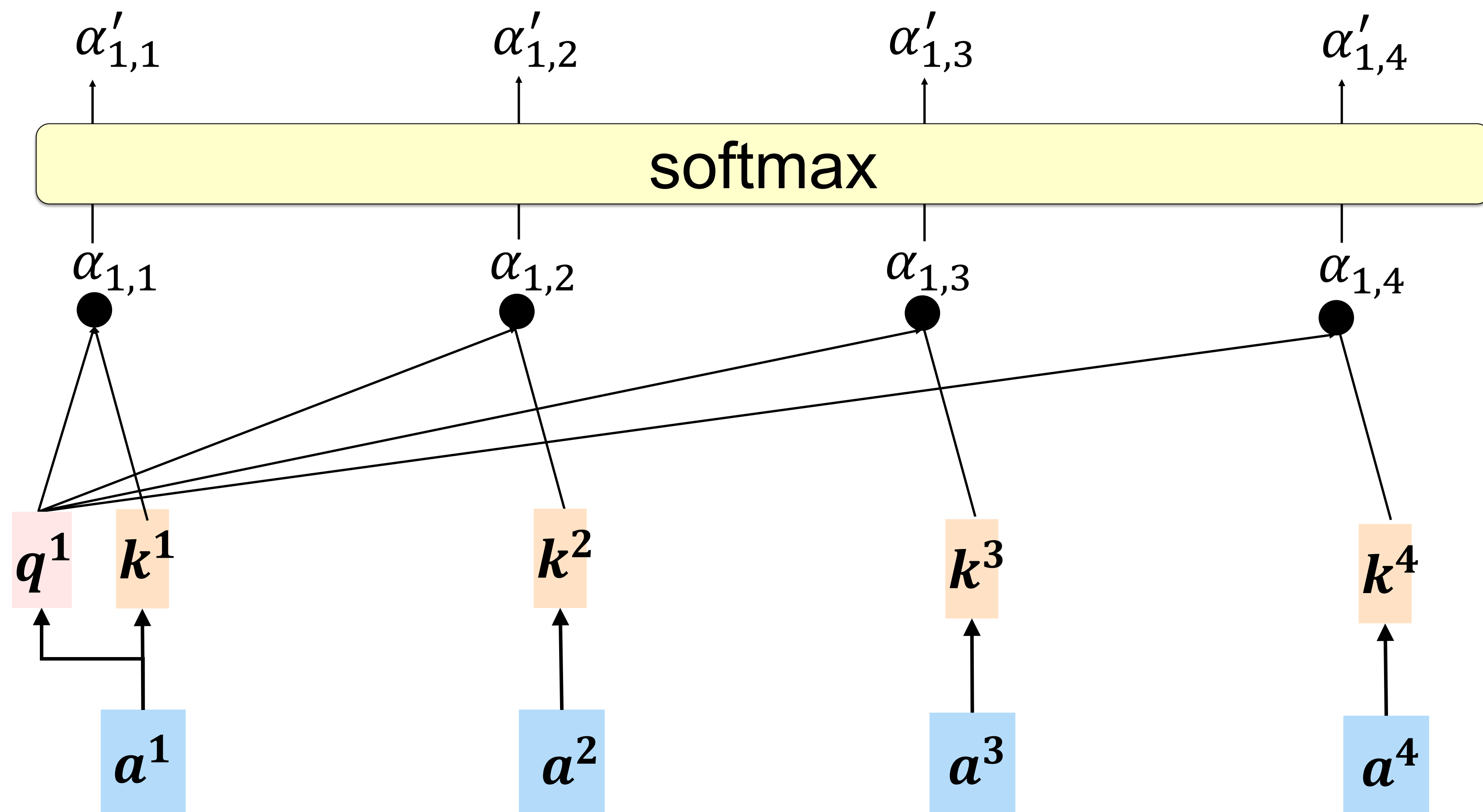
# Self-Attention





# Self-Attention

$$\alpha'_{1,i} = e^{\alpha_{1,i}} / \sum_j e^{\alpha_{1,j}}$$



$$q^1 = W^q a^1$$

$$k^1 = W^k a^1$$

$$k^2 = W^k a^2$$

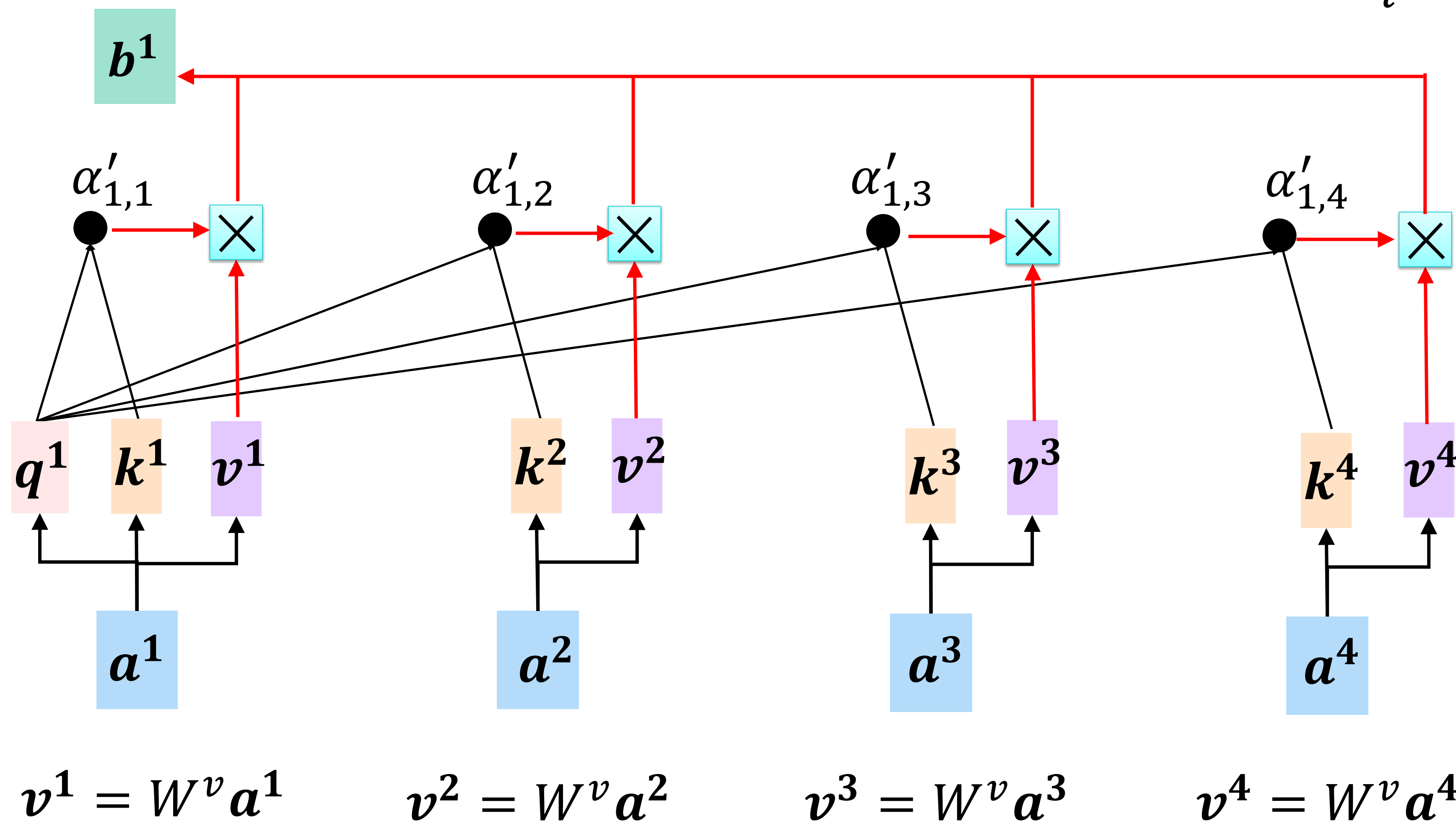
$$k^3 = W^k a^3$$

$$k^4 = W^k a^4$$

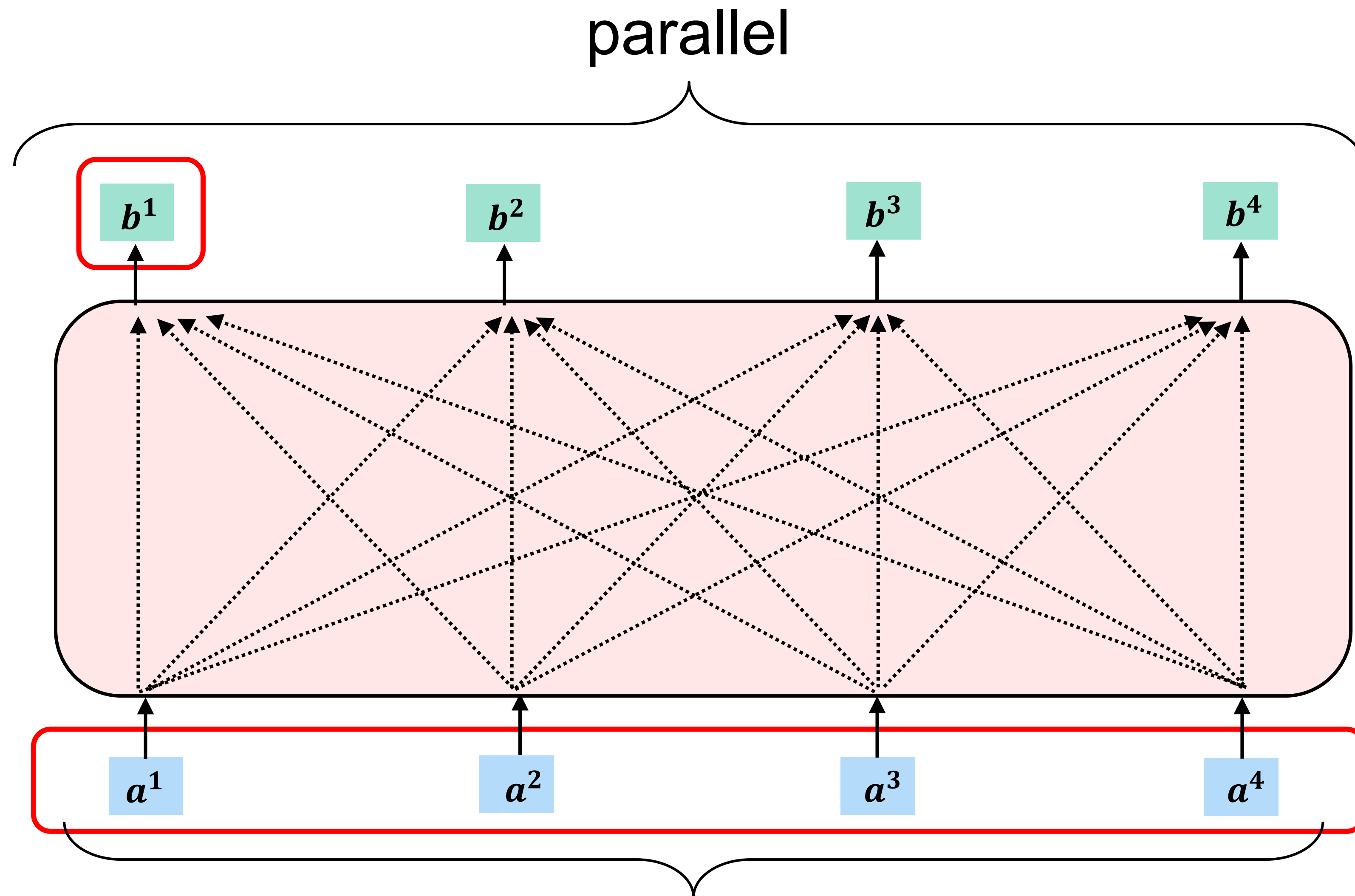
# Self-Attention

extract information based  
on attention scores

$$b^1 = \sum_i \alpha'_{1,i} v^i$$



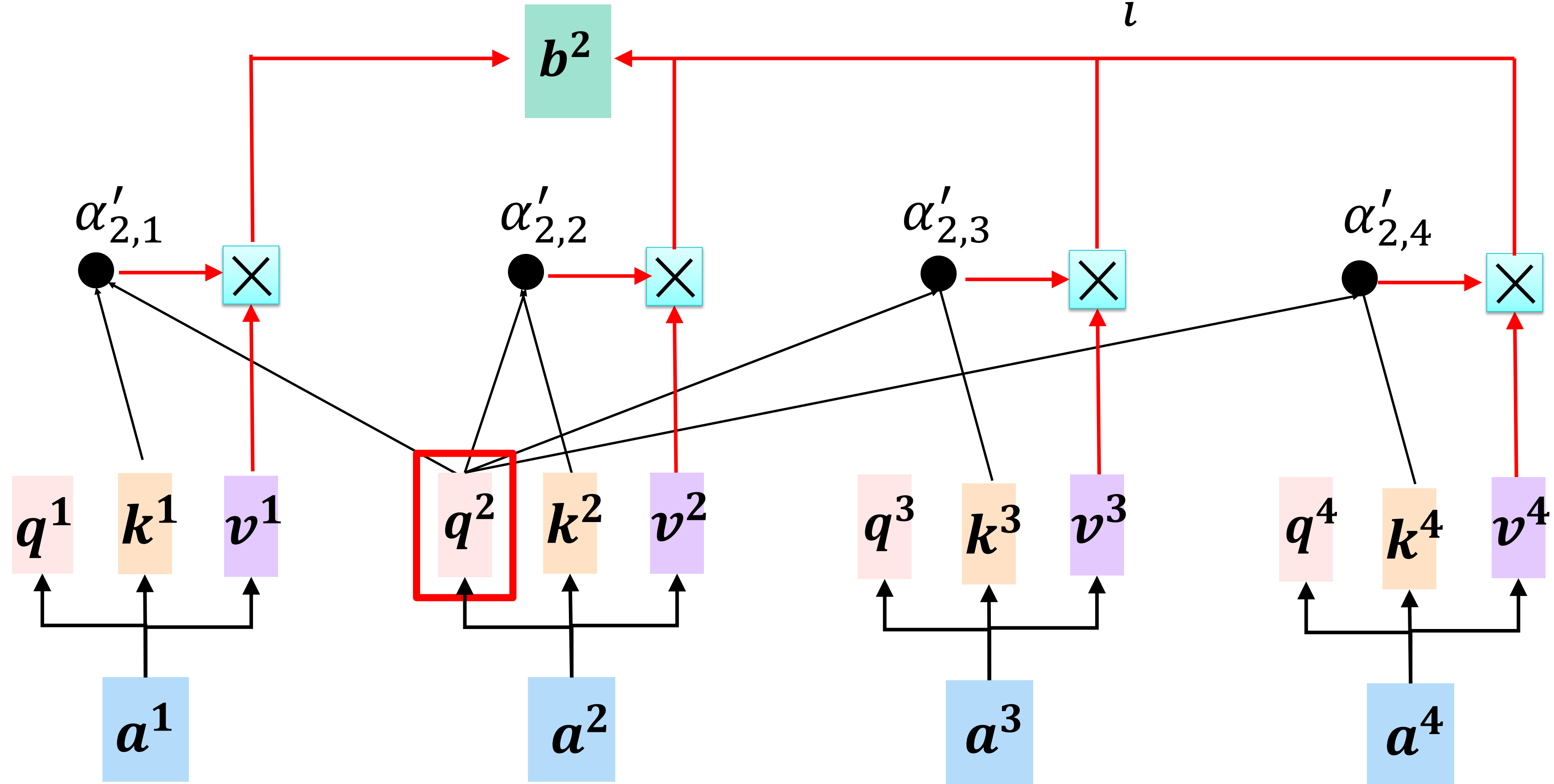
# Self-Attention



Can be either **input** or a **hidden layer**

# Self-Attention

$$b^2 = \sum_i \alpha'_{2,i} v^i$$



# Self-Attention

$q^i = W^q a^i$ 

$q^1$ 
 $q^2$ 
 $q^3$ 
 $q^4$

=

$W^q$

$a^1$ 
 $a^2$ 
 $a^3$ 
 $a^4$

$Q$

$I$

$k^i = W^k a^i$ 

$k^1$ 
 $k^2$ 
 $k^3$ 
 $k^4$

=

$W^k$

$a^1$ 
 $a^2$ 
 $a^3$ 
 $a^4$

$K$

$I$

$v^i = W^v a^i$ 

$v^1$ 
 $v^2$ 
 $v^3$ 
 $v^4$

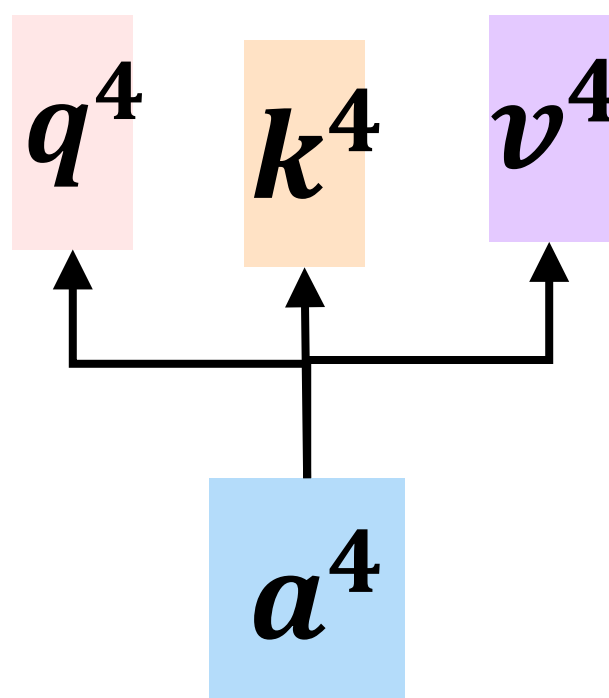
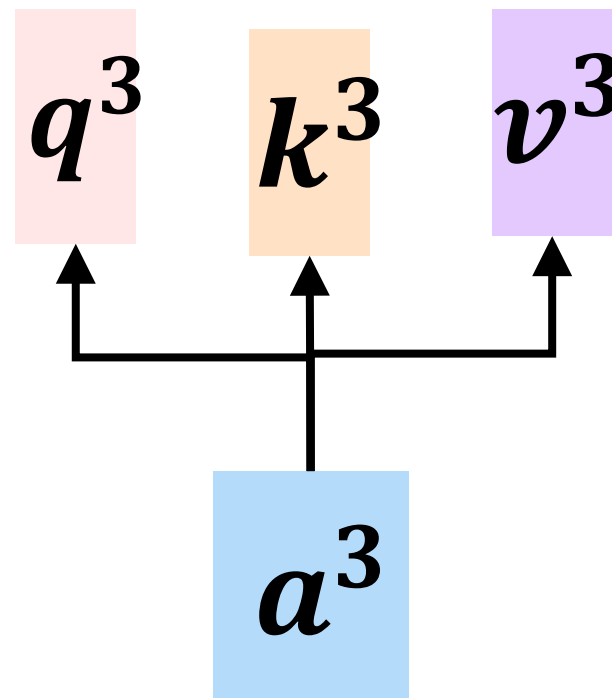
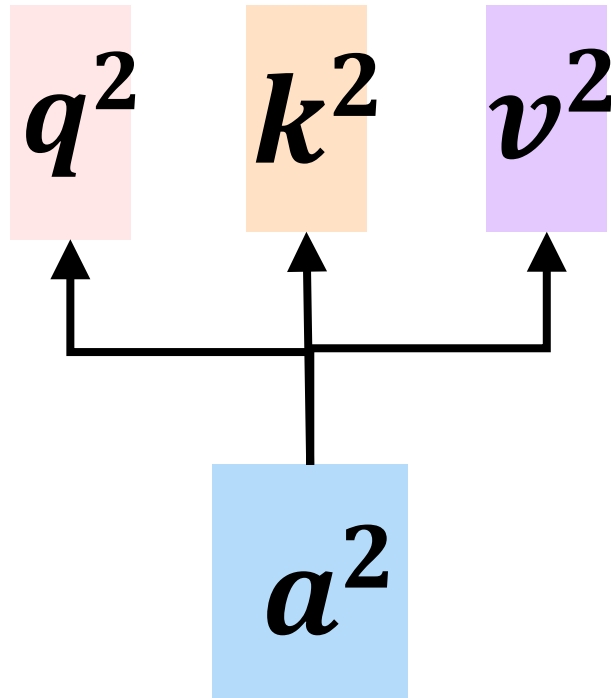
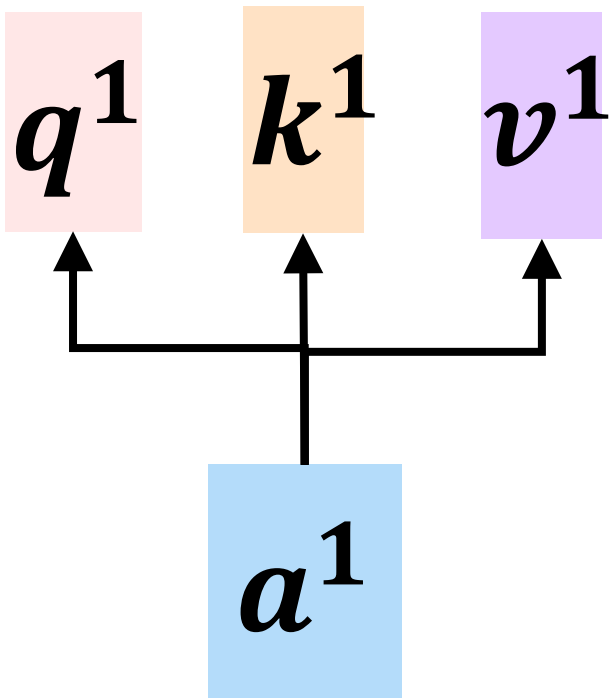
=

$W^v$

$a^1$ 
 $a^2$ 
 $a^3$ 
 $a^4$

$V$

$I$



# Self-Attention

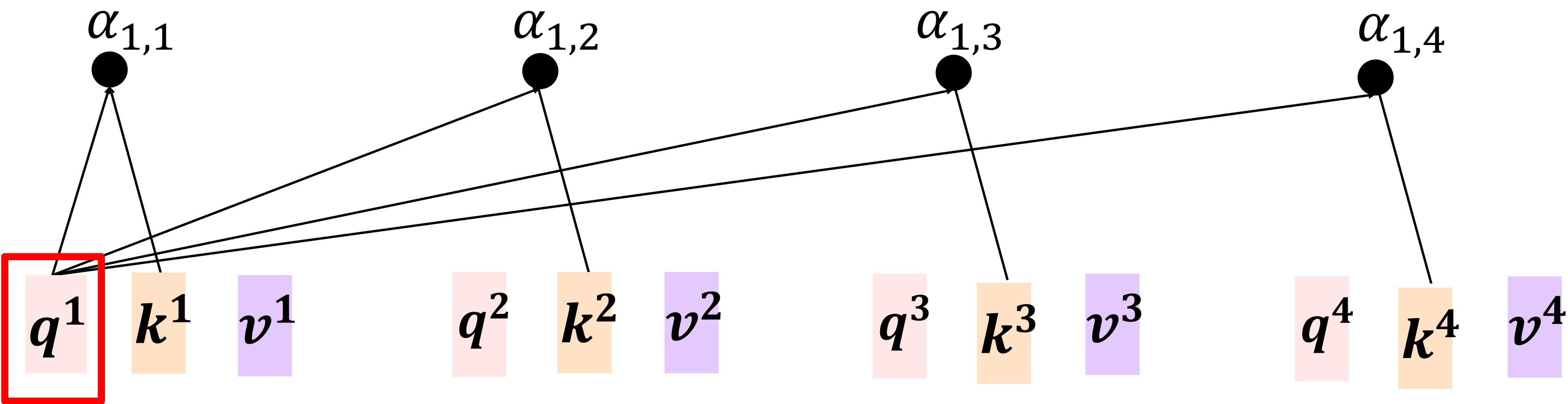
$$\begin{aligned} \alpha_{1,1} &= k^1 q^1 & \alpha_{1,2} &= k^2 q^1 \\ \alpha_{1,3} &= k^3 q^1 & \alpha_{1,4} &= k^4 q^1 \end{aligned}$$

$\alpha_{1,1}$   
 $\alpha_{1,2}$   
 $\alpha_{1,3}$   
 $\alpha_{1,4}$

=

$k^1$   
 $k^2$   
 $k^3$   
 $k^4$

$q^1$



$\alpha'_{1,1}$   
 $\alpha'_{1,2}$   
 $\alpha'_{1,3}$   
 $\alpha'_{1,4}$

$\alpha'_{2,1}$   
 $\alpha'_{2,2}$   
 $\alpha'_{2,3}$   
 $\alpha'_{2,4}$

$\alpha'_{3,1}$   
 $\alpha'_{3,2}$   
 $\alpha'_{3,3}$   
 $\alpha'_{3,4}$

$\alpha'_{4,1}$   
 $\alpha'_{4,2}$   
 $\alpha'_{4,3}$   
 $\alpha'_{4,4}$

$A'$

$\alpha_{1,1}$   
 $\alpha_{1,2}$   
 $\alpha_{1,3}$   
 $\alpha_{1,4}$

$\alpha_{2,1}$   
 $\alpha_{2,2}$   
 $\alpha_{2,3}$   
 $\alpha_{2,4}$

$\alpha_{3,1}$   
 $\alpha_{3,2}$   
 $\alpha_{3,3}$   
 $\alpha_{3,4}$

$\alpha_{4,1}$   
 $\alpha_{4,2}$   
 $\alpha_{4,3}$   
 $\alpha_{4,4}$

$A$

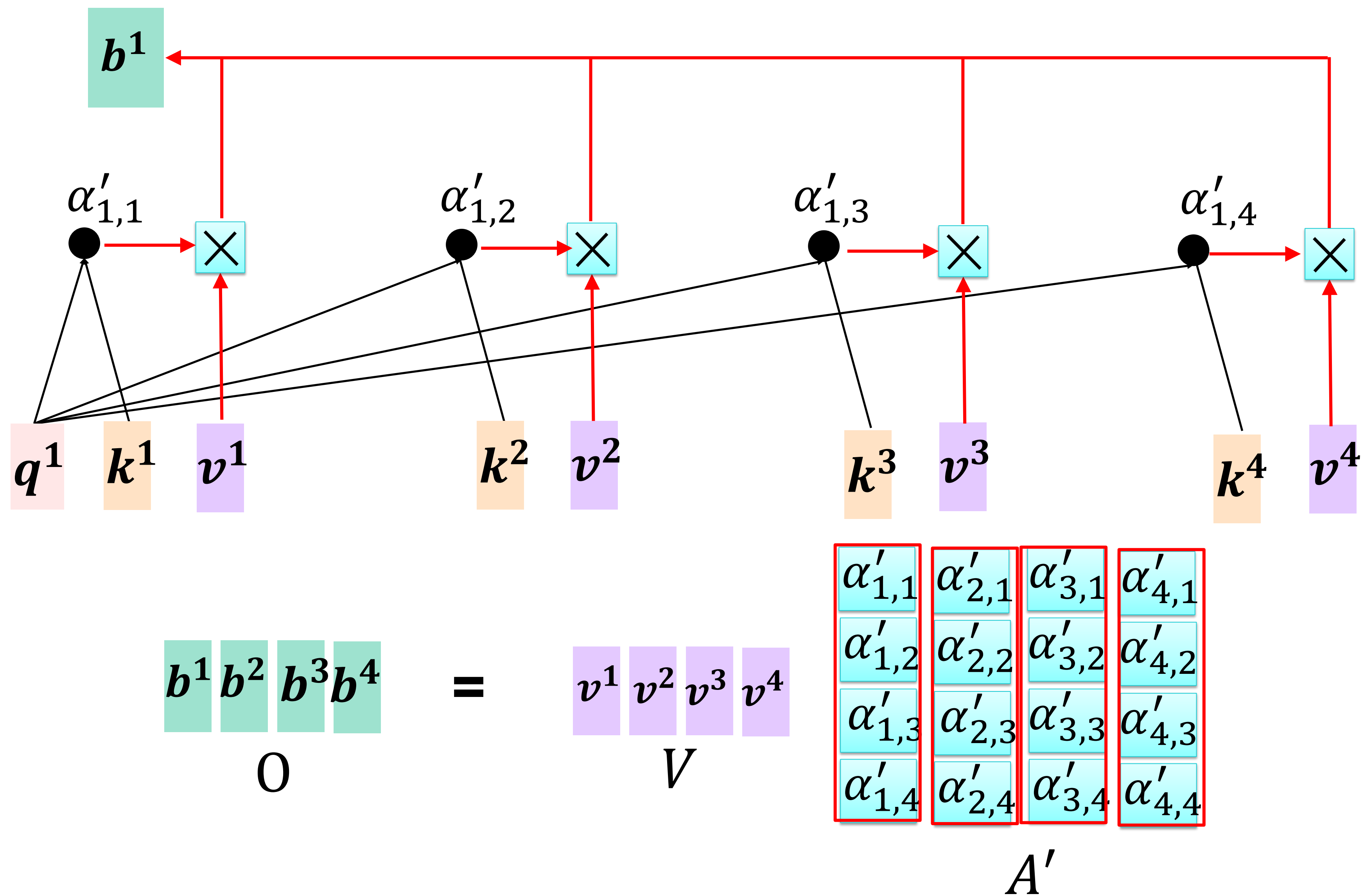
=

$k^1$   
 $k^2$   
 $k^3$   
 $k^4$

$q^1$   
 $q^2$   
 $q^3$   
 $q^4$

$K^T$   
 $Q$

# Self-Attention





# Self-Attention

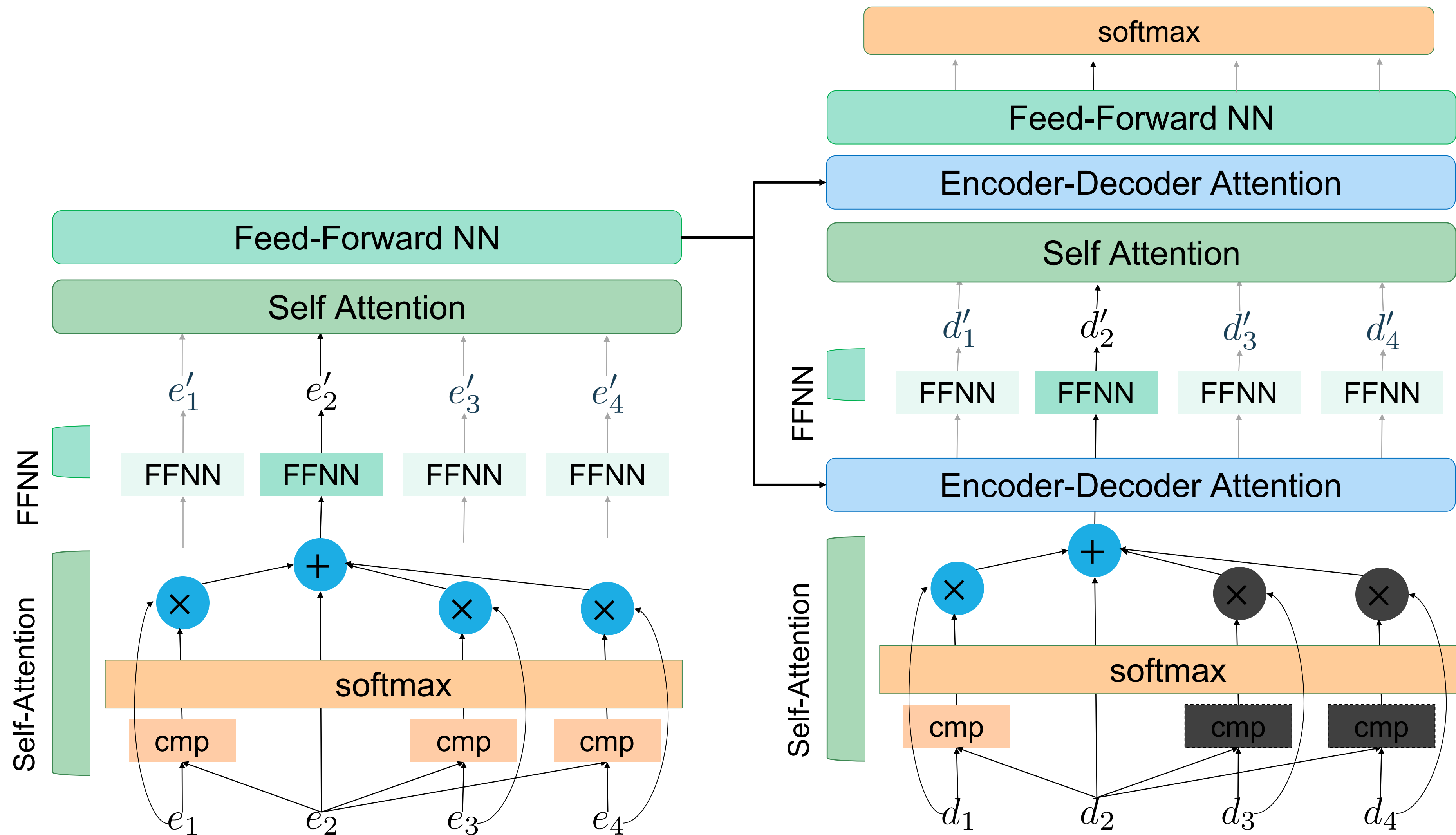
$$\begin{aligned} Q &= W^q I \\ K &= W^k I \\ V &= W^v I \end{aligned}$$

Parameters  
to be learned

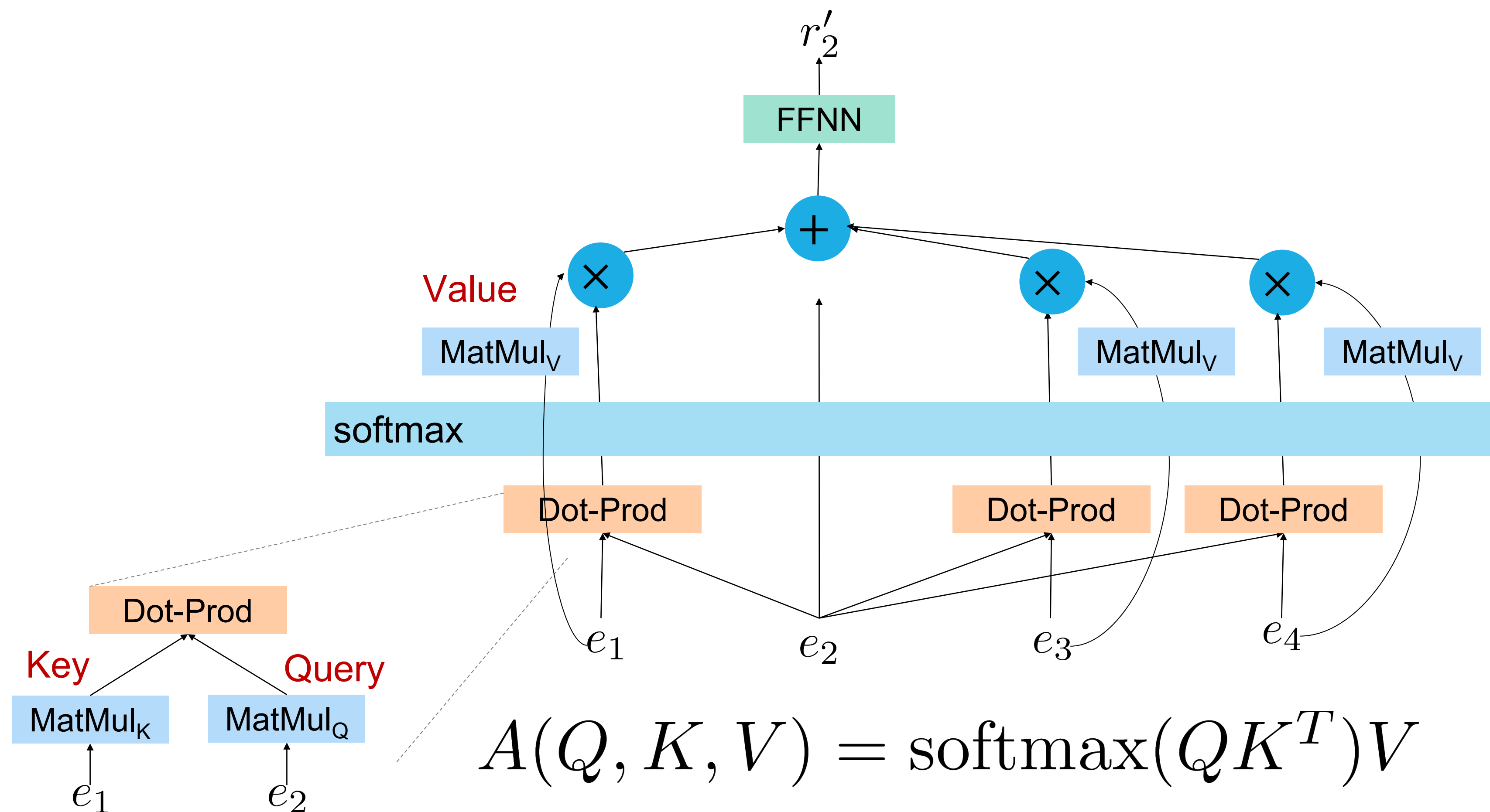
$$\begin{aligned} A' &\leftarrow A = K^T Q \\ O &= V A' \end{aligned}$$

Attention Matrix

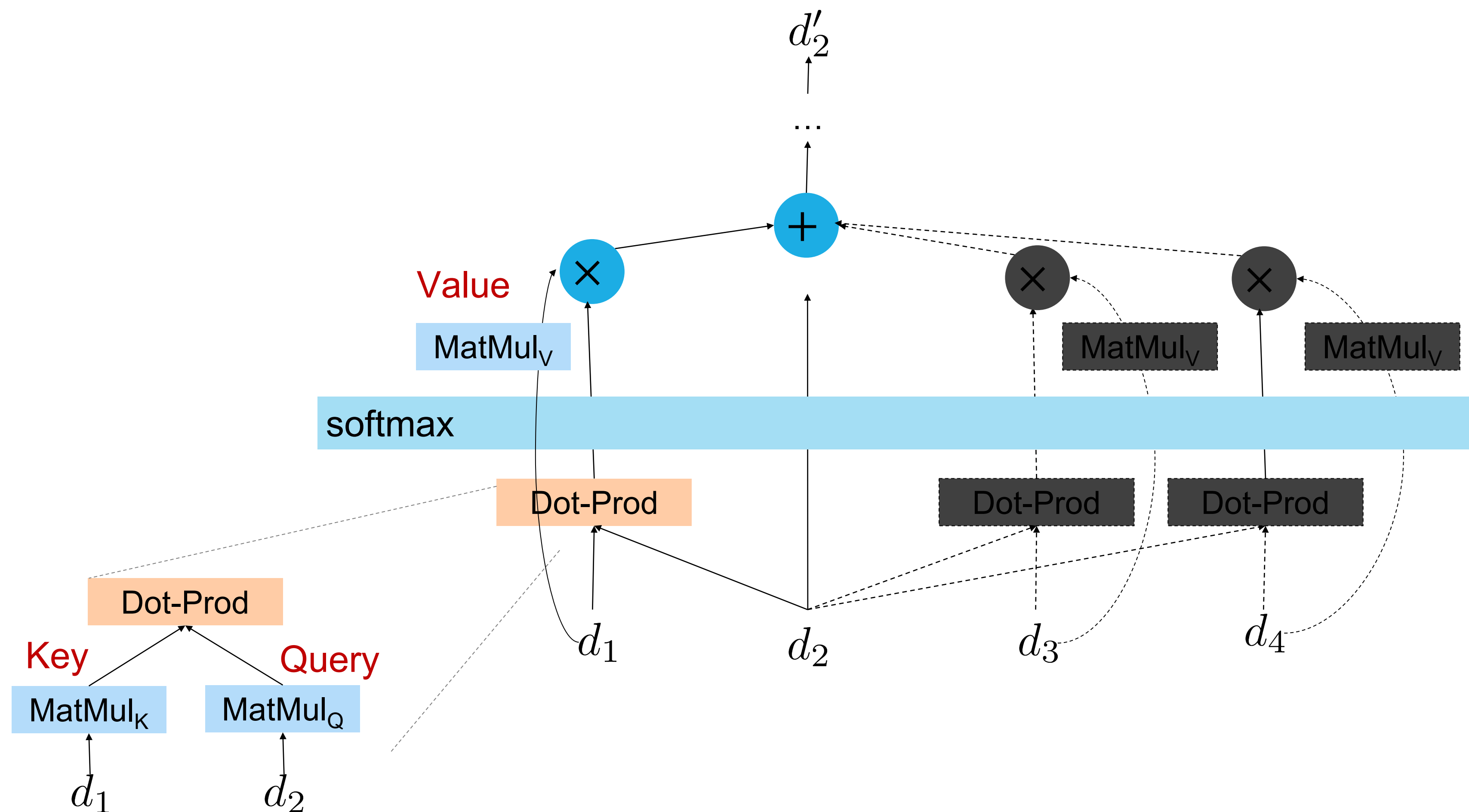
# Transformer Idea



# Encoder Self-Attention (Vaswani+, 2017)



# Decoder Self-Attention (Vaswani+, 2017)

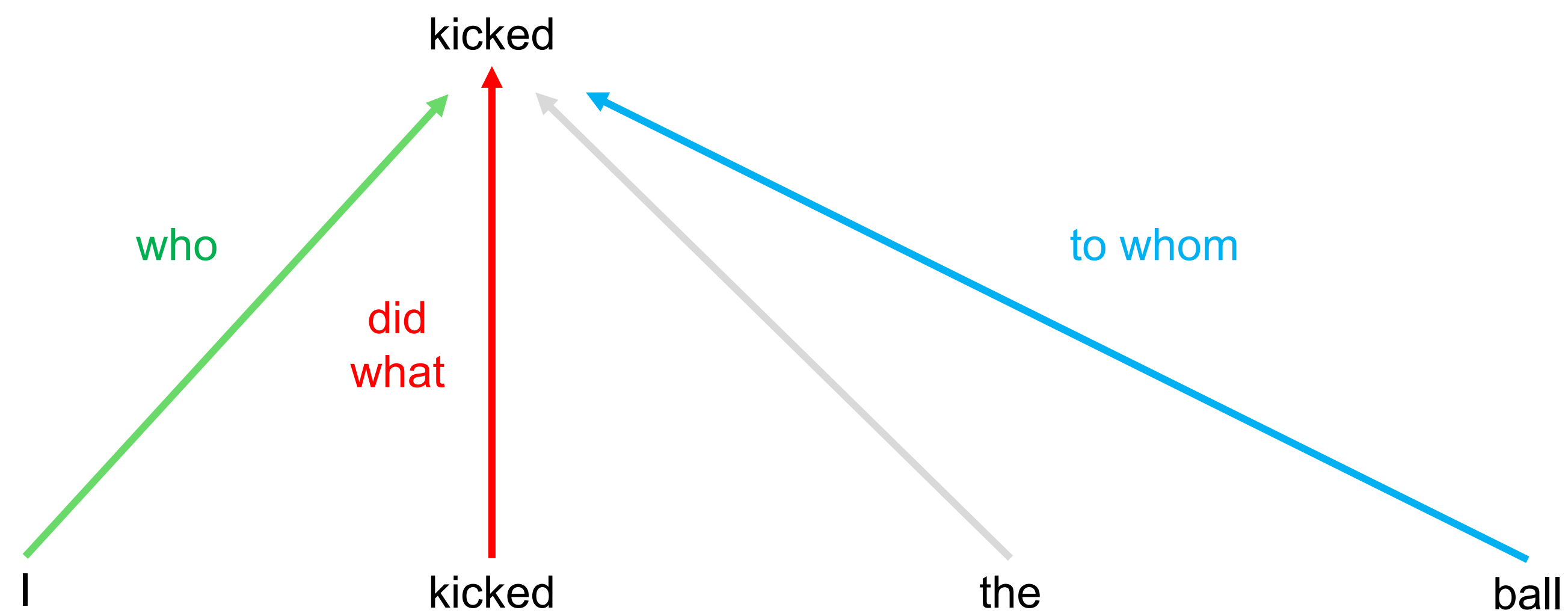


27

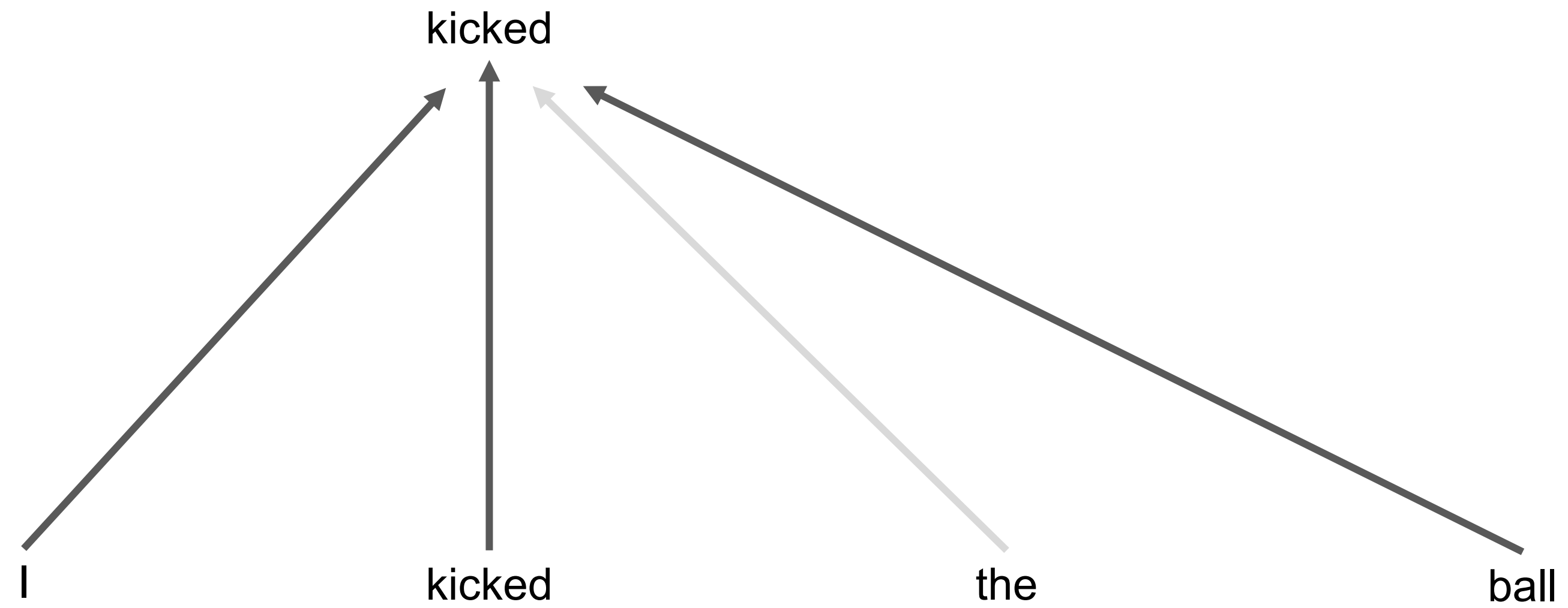
# Sequence Encoding

## Multi-Head Attention

# Convolutions

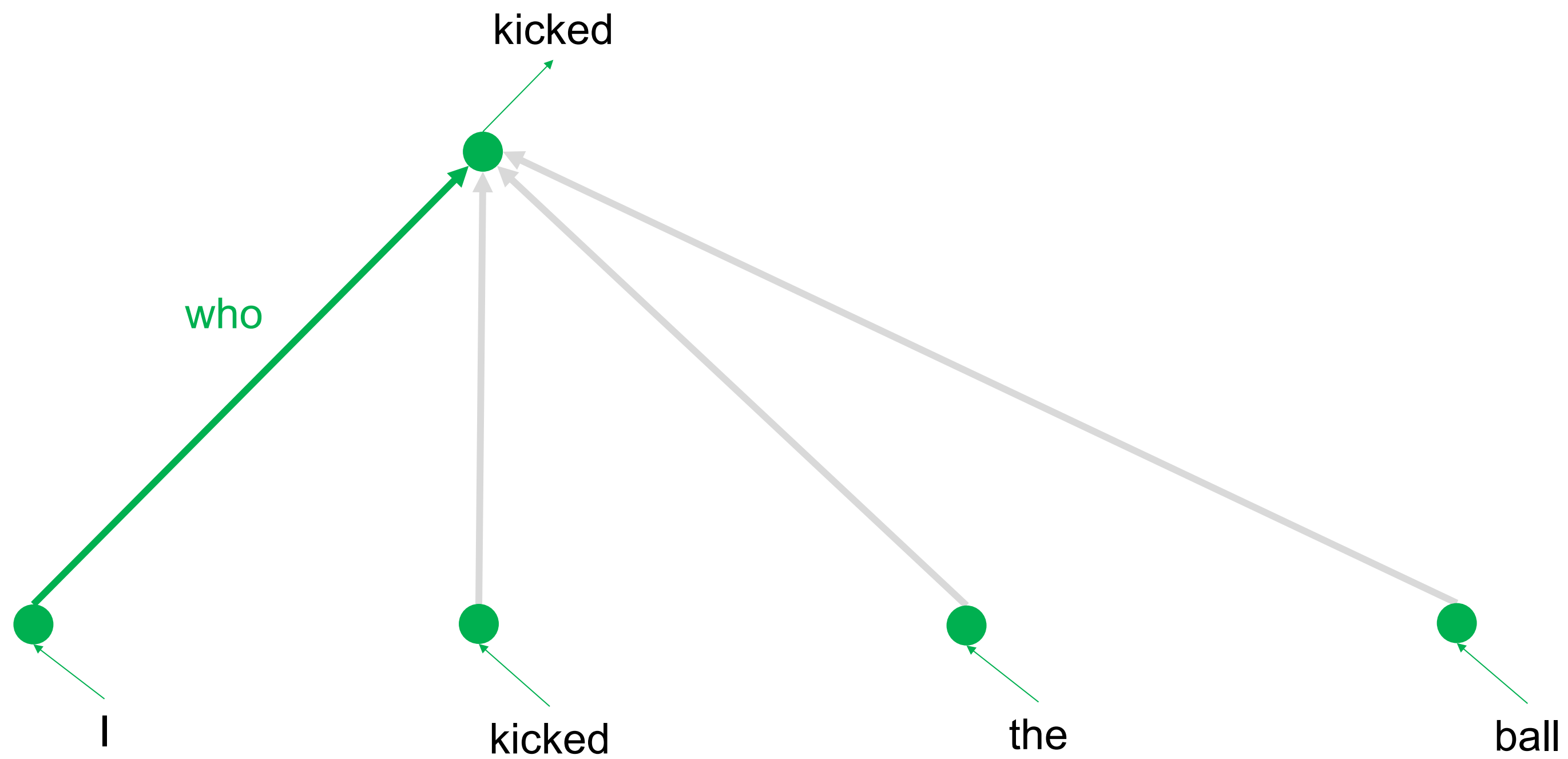


# Self-Attention

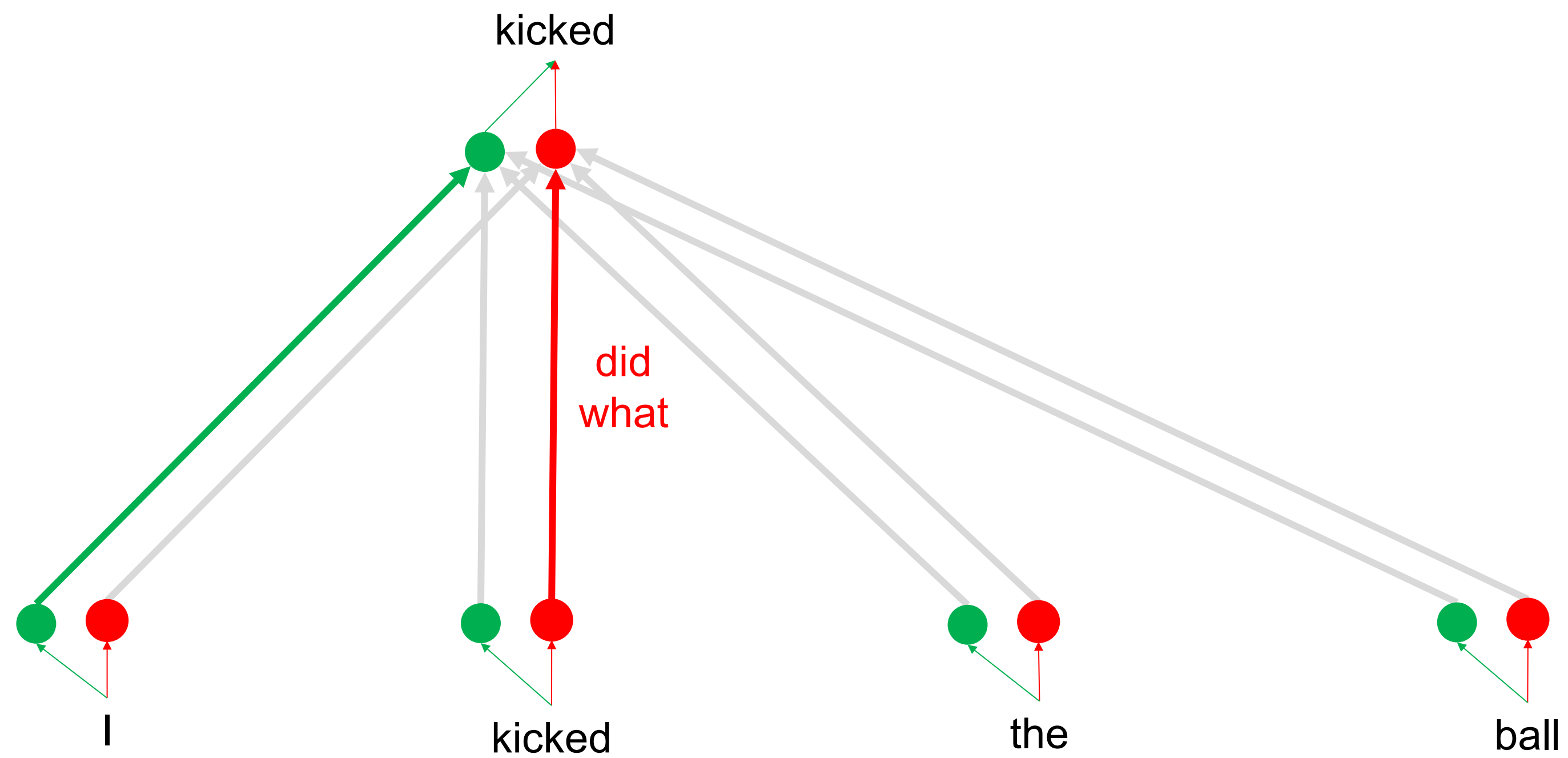




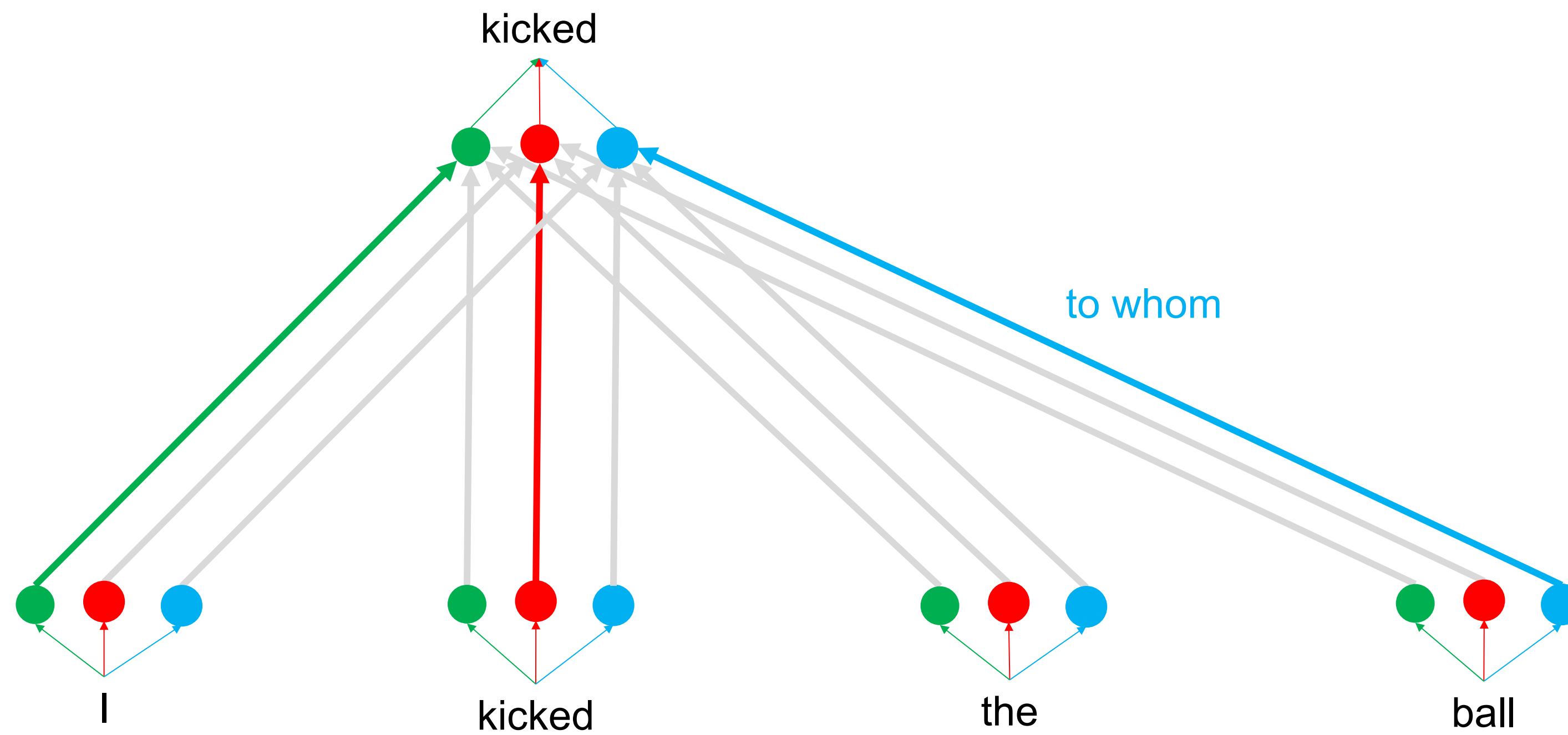
# Attention Head: who



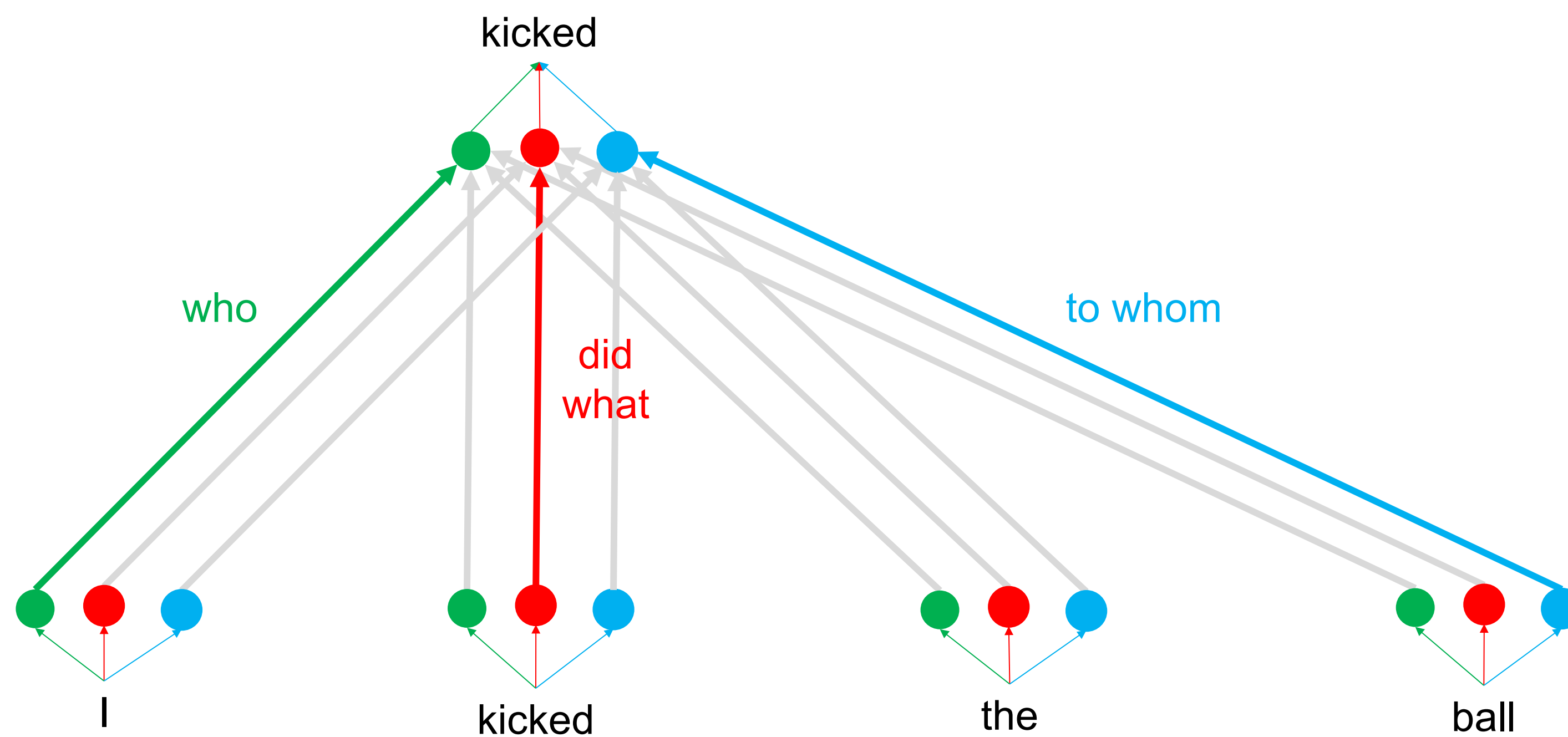
# Attention Head: did what



# Attention Head: to whom

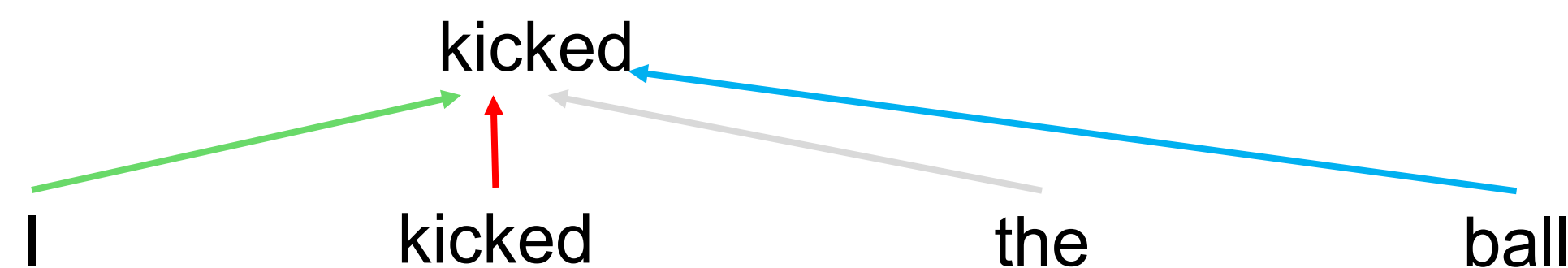


# Multi-Head Attention



# Comparison

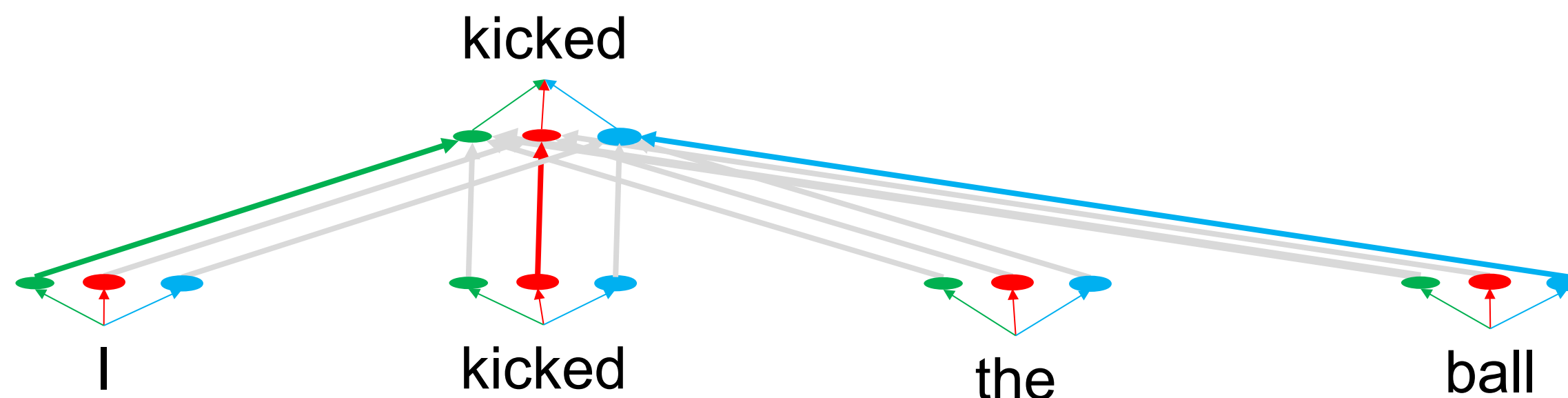
- Convolution: different linear transformations by relative positions



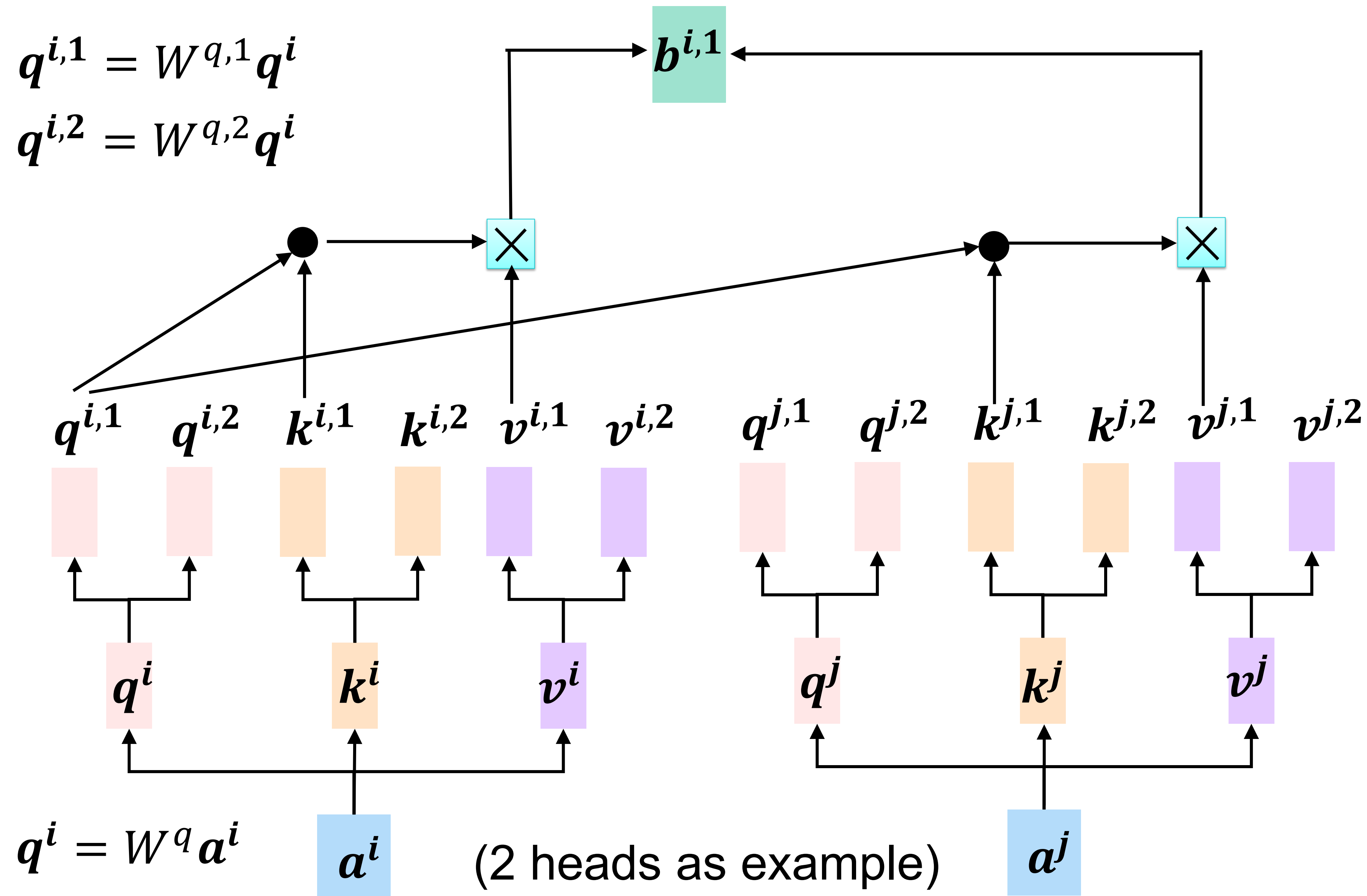
- Attention: a weighted average



- Multi-Head Attention: parallel attention layers with different linear transformations on input/output



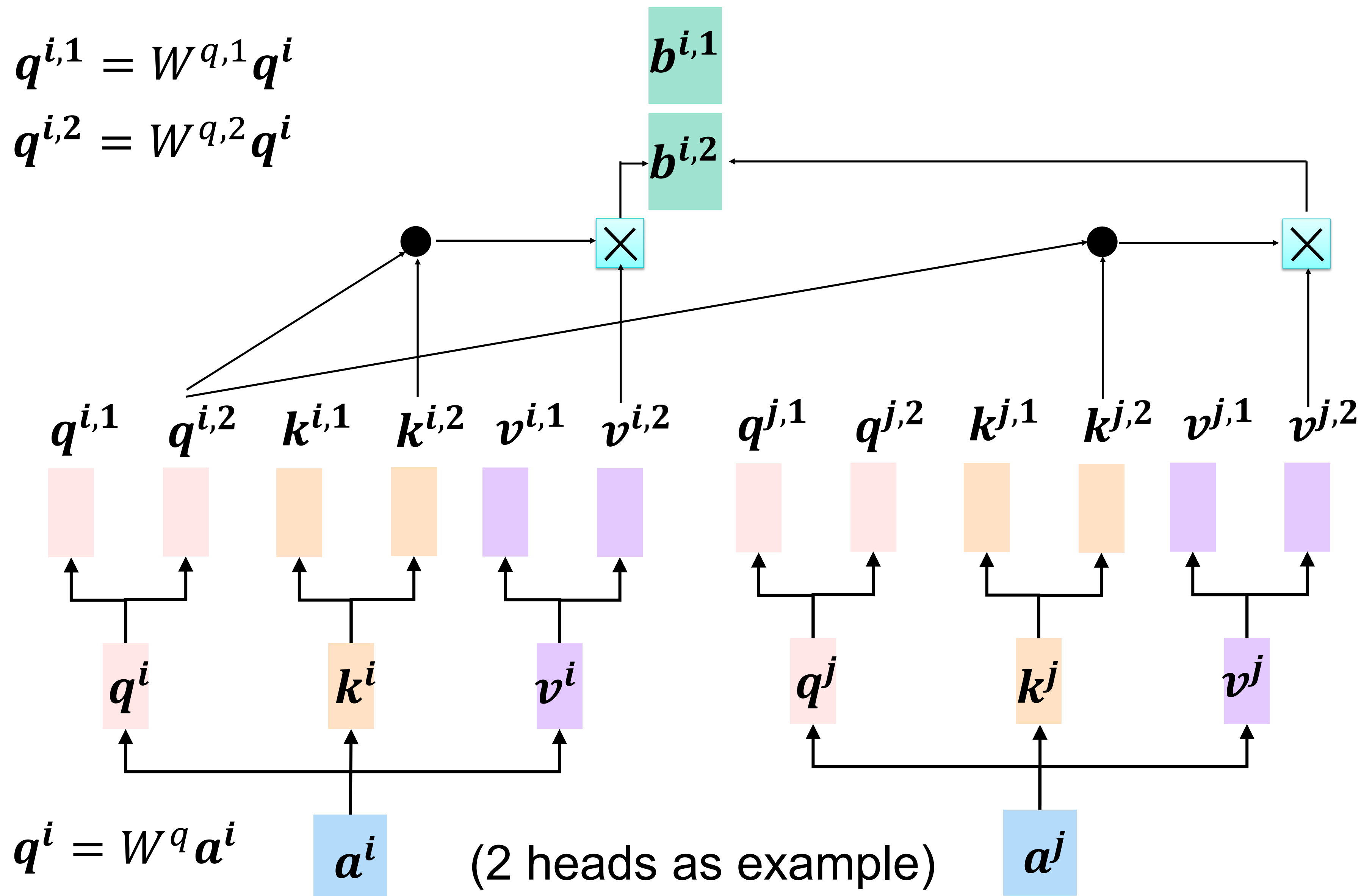
# Multi-Head Attention



# Multi-Head Attention

$$q^{i,1} = W^{q,1} q^i$$

$$q^{i,2} = W^{q,2} q^i$$





# Multi-Head Attention

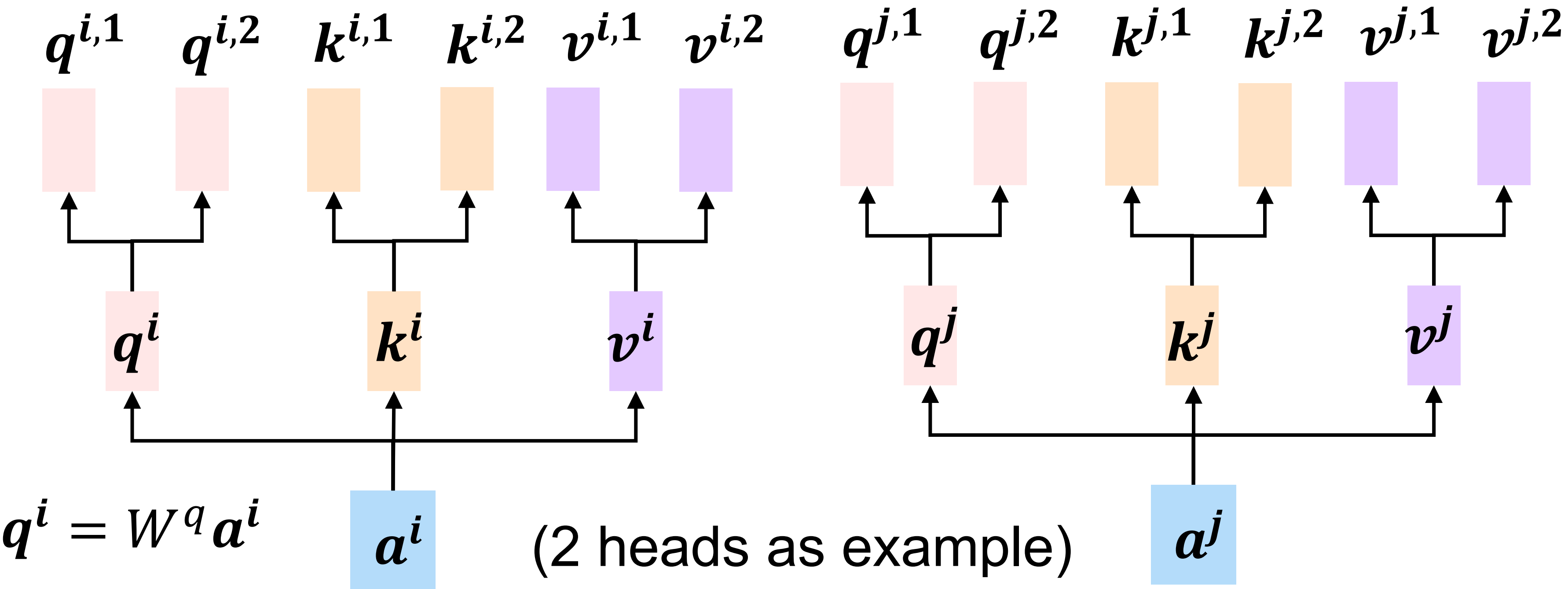
$b^i$

=

$W^O$

$b^{i,1}$

$b^{i,2}$



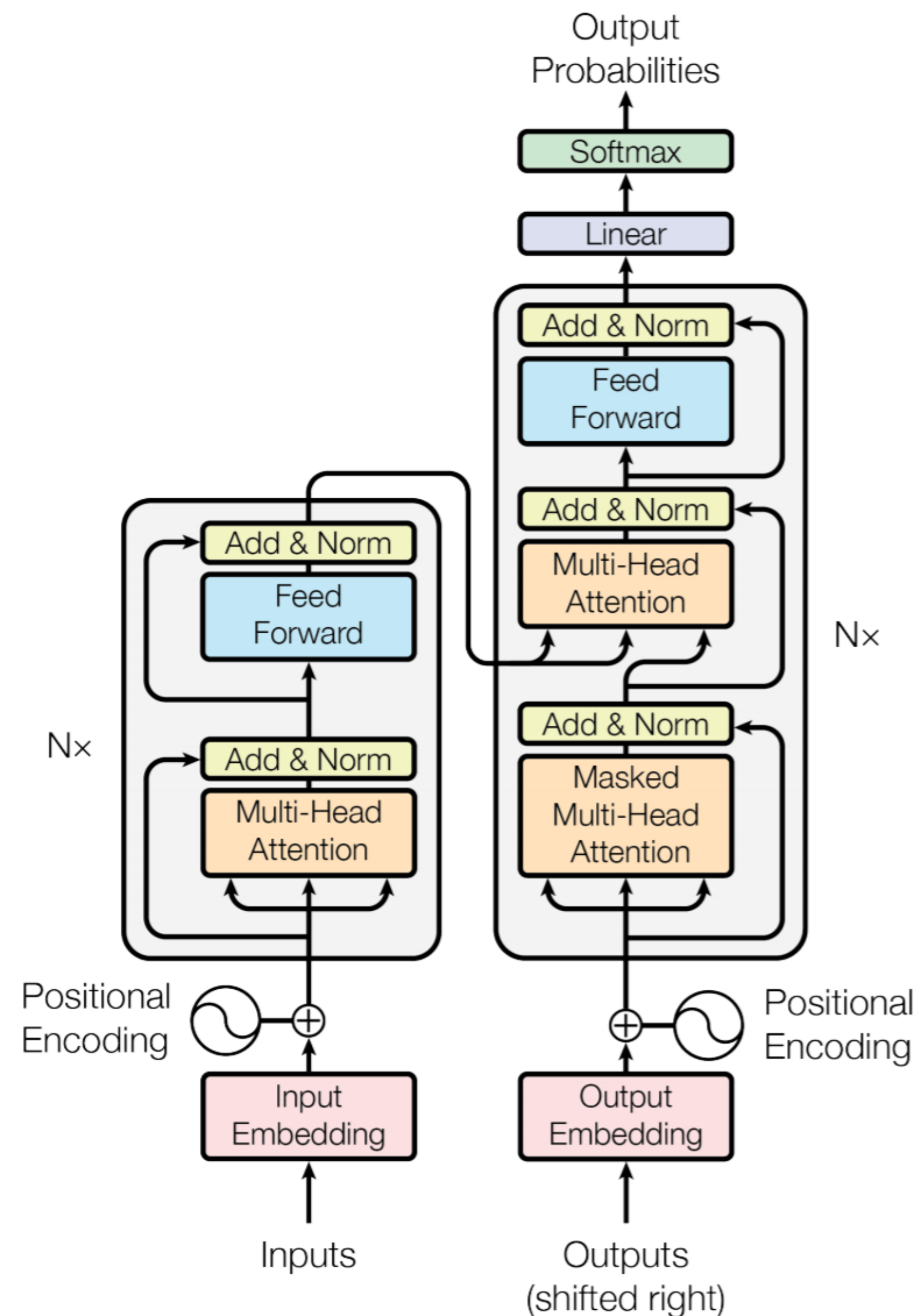
38

# Sequence Encoding Transformer



# Transformer Overview

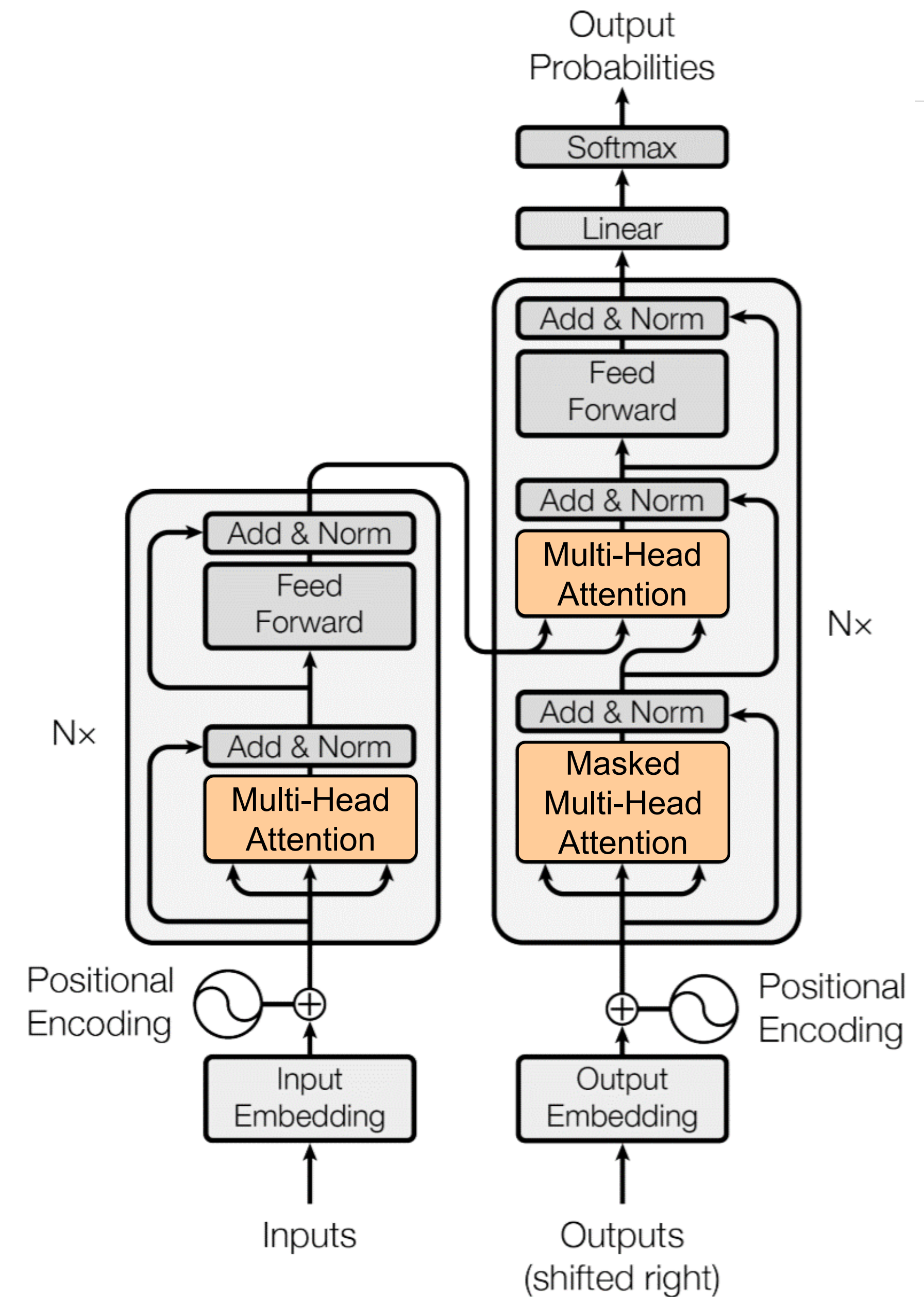
- Non-recurrent encoder-decoder for MT
- PyTorch explanation by Sasha Rush  
<http://nlp.seas.harvard.edu/2018/04/03/attention.html>





# Transformer Overview

- Non-recurrent encoder-decoder for MT
- PyTorch explanation by Sasha Rush  
<http://nlp.seas.harvard.edu/2018/04/03/attention.html>



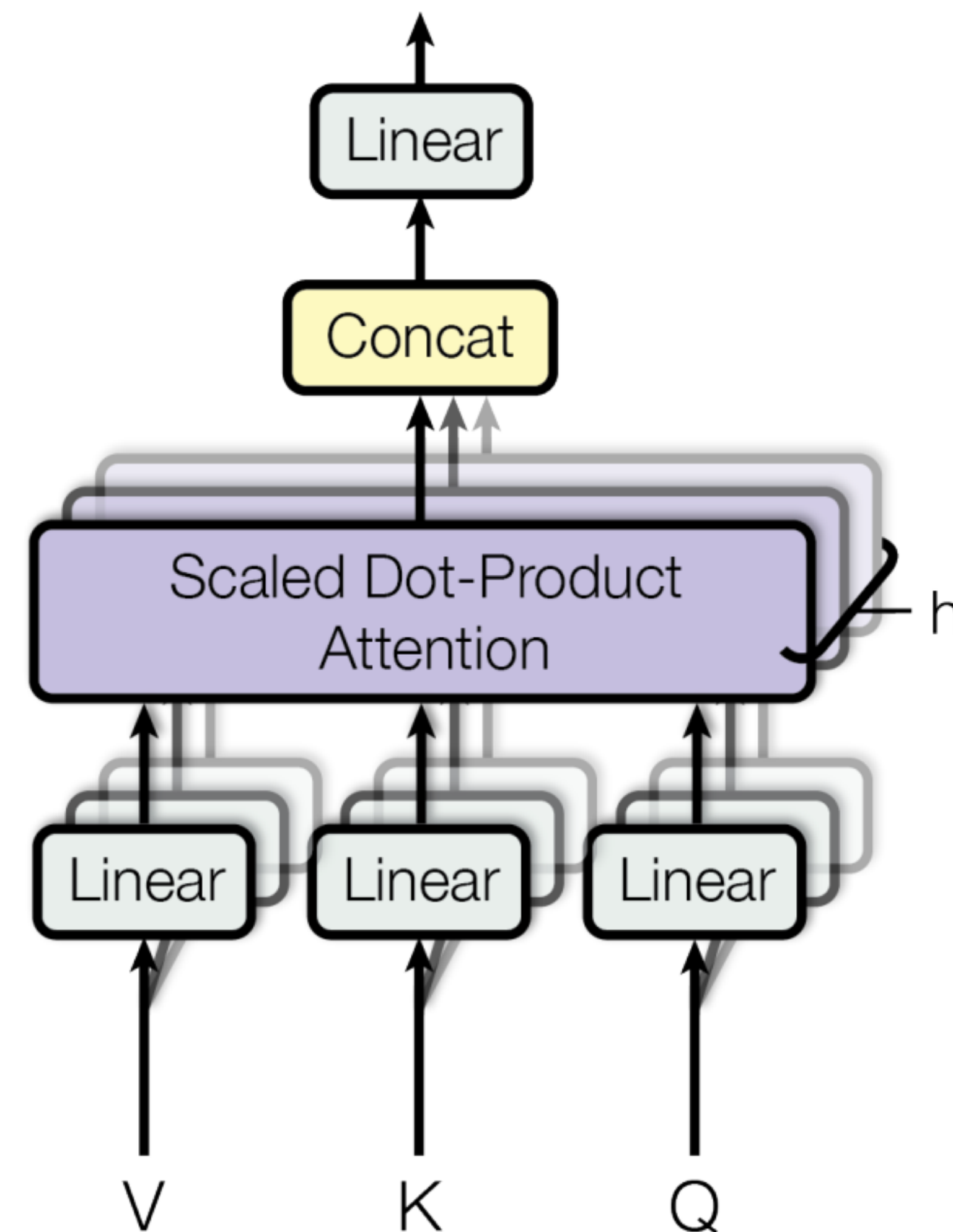
# Multi-Head Attention

- Idea: allow words to interact with one another
- Model
  - Map  $V$ ,  $K$ ,  $Q$  to lower dimensional spaces
  - Apply attention, concatenate outputs
  - Linear transformation

$$\text{MultiHead}(Q, K, V)$$

$$= \text{Concat}(\text{head}_1, \dots, \text{head}_h) W^O$$

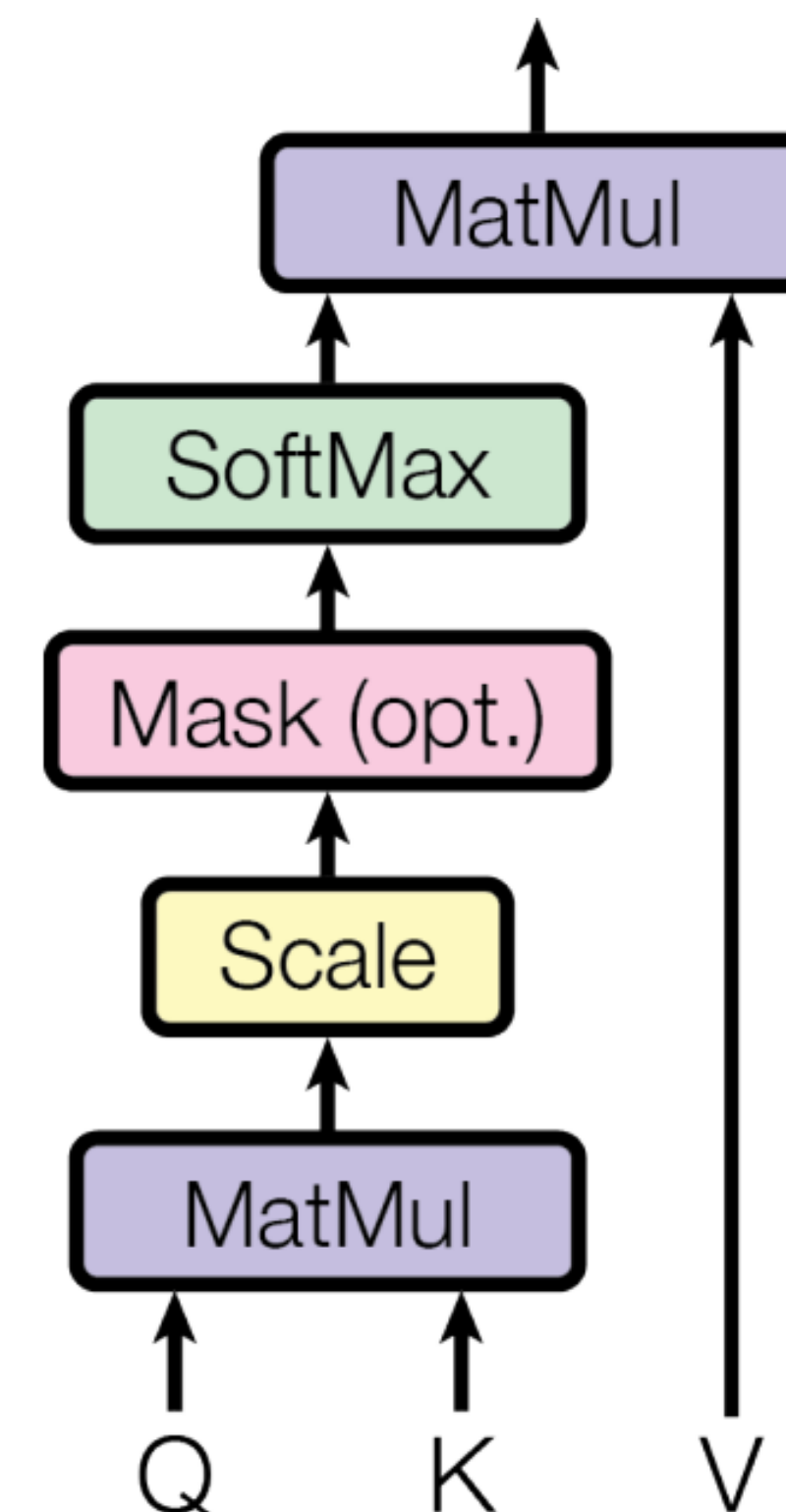
$$\text{head}_i = \text{Attention}(QW_i^Q, KW_i^K, VW_i^V)$$



# 42 Scaled Dot-Product Attention

- Problem: when  $d_k$  gets large, the variance of  $q^T k$  increases
  - $q$  and  $k$  are random variables with mean 0 and variance 1
  - $q^T k$  has mean 0 and variance  $d_k$
  - variance 1 is preferred
- Solution: scale by  $\sqrt{d_k}$

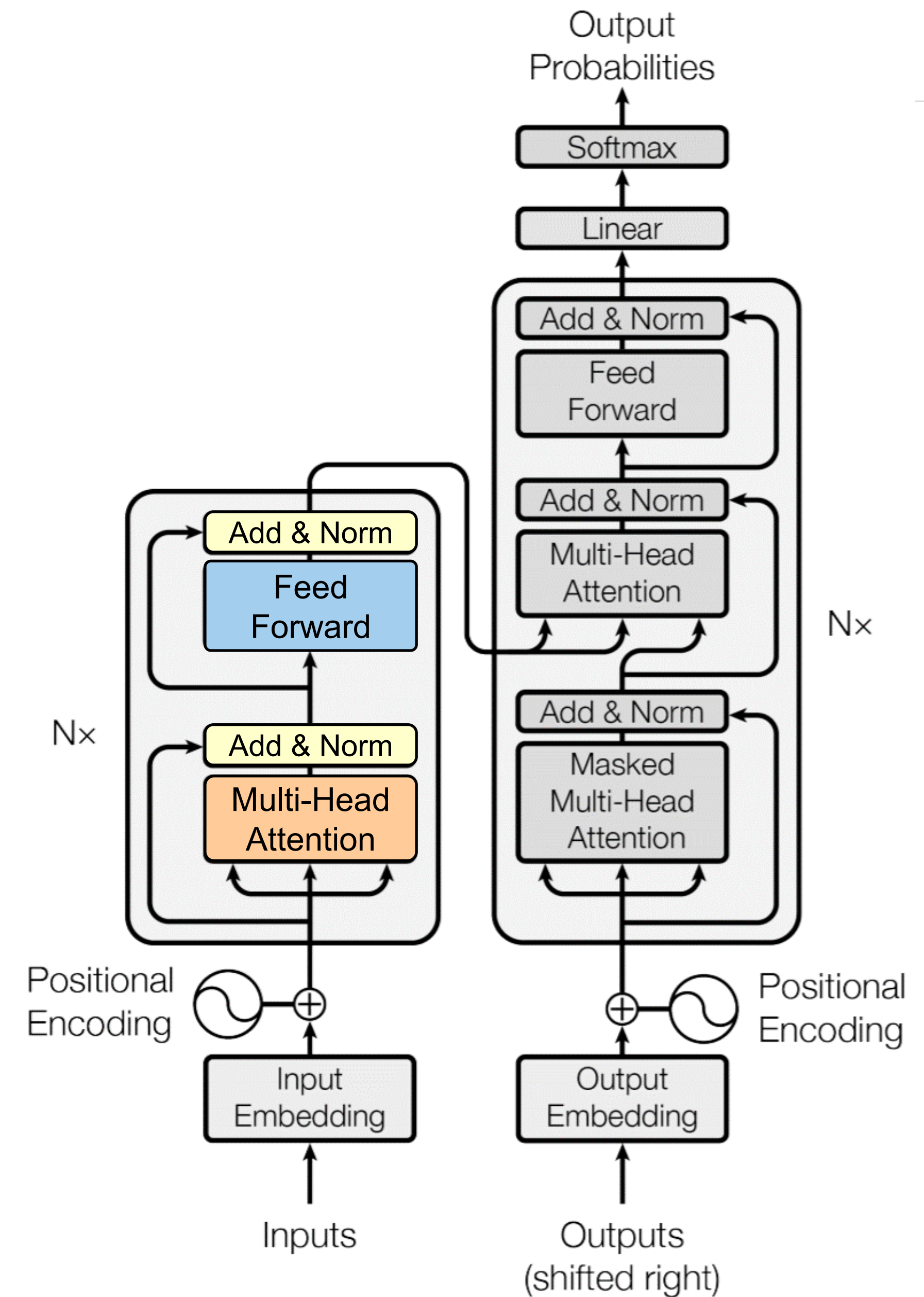
$$A(Q, K, V) = \text{softmax}\left(\frac{QK^T}{\sqrt{d_k}}\right)V$$





# Transformer Overview

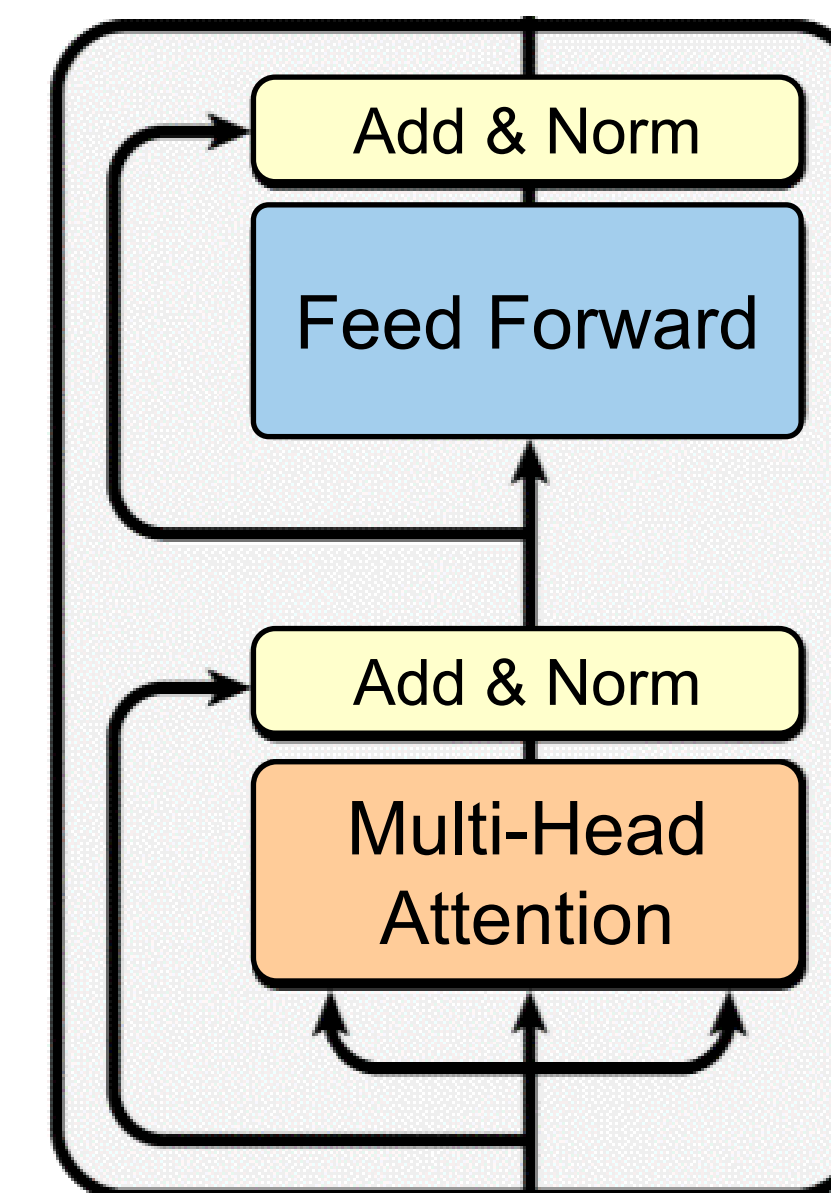
- Non-recurrent encoder-decoder for MT
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<http://nlp.seas.harvard.edu/2018/04/03/attention.html>



# Transformer Encoder Block

- Each block has
  - multi-head attention
  - 2-layer feed-forward NN (w/ ReLU)
- Both parts contain
  - Residual connection
  - Layer normalization (LayerNorm)

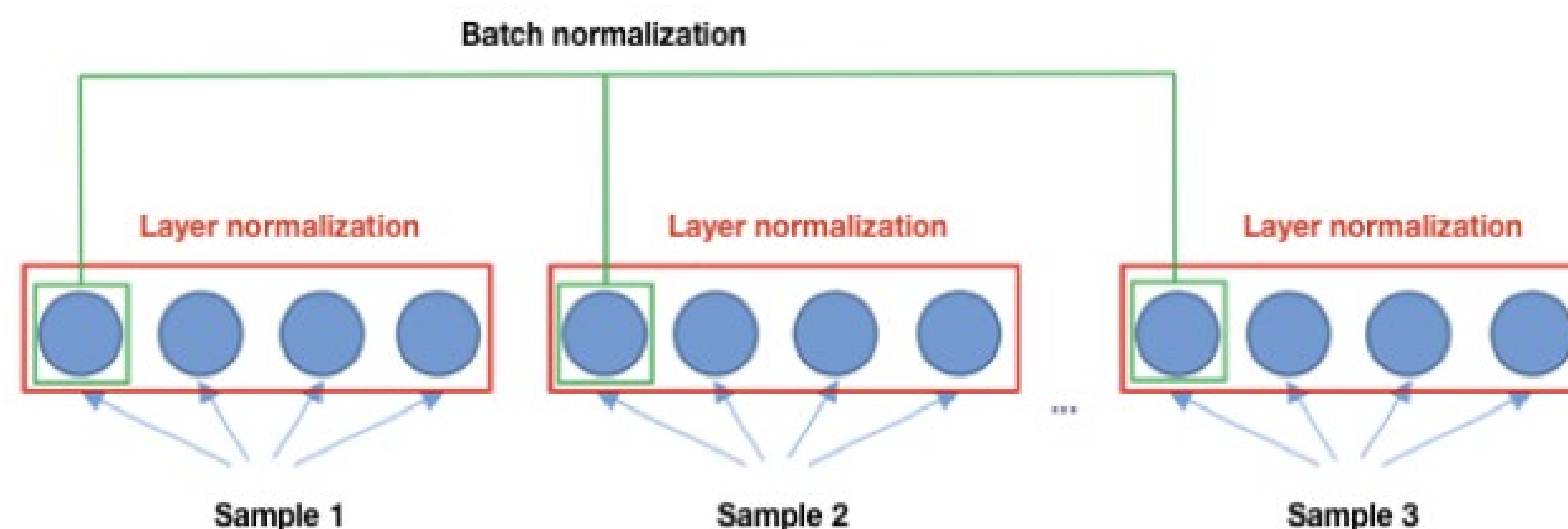
$$H(x) = g(x) = x + F(x)$$



Change input to have 0 mean and 1 variance per layer & per training point

→ LayerNorm(x + sublayer(x))

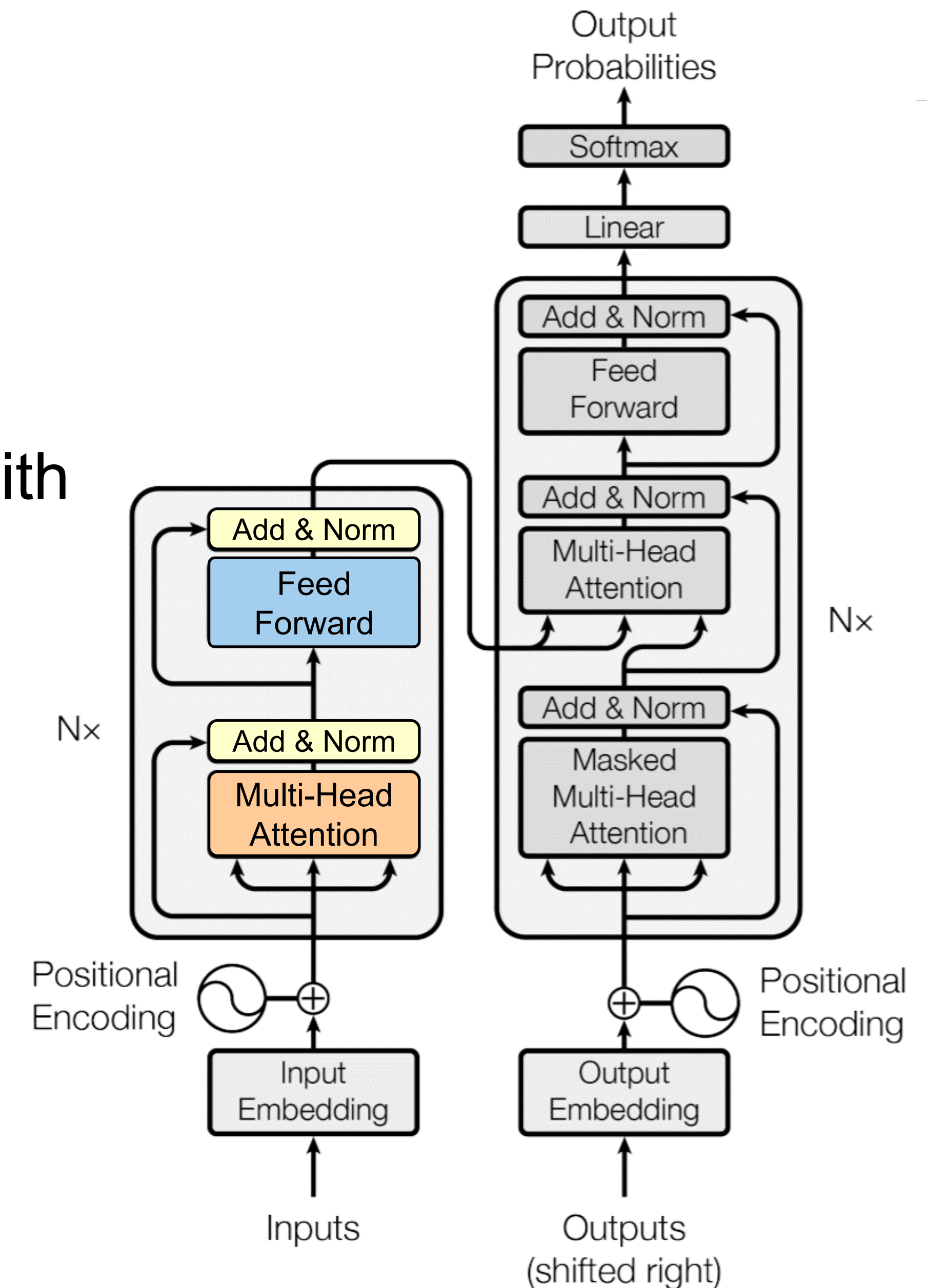
$$\mu^l = \frac{1}{H} \sum_{i=1}^H a_i^l \quad \sigma^l = \sqrt{\frac{1}{H} \sum_{i=1}^H (a_i^l - \mu^l)^2} \quad h_i = f\left(\frac{g_i}{\sigma_i} (a_i - \mu_i) + b_i\right)$$





# Encoder Input

- Problem: temporal information is missing
- Solution: **positional encoding** allows words at different locations to have different embeddings with fixed dimensions



# Positional Encoding

- Criteria for positional encoding
  - Unique encoding for each position
  - Deterministic
  - Distance between neighboring positions should be the same
  - Model can easily generalize to longer sentences

# Positional Encoding

- Criteria for positional encoding
  - ✓ Unique encoding for each position
  - ✓ Deterministic
  - ✓ Distance between neighboring positions should be the same
  - Model can easily generalize to longer sentences
- Idea 1:  $PE(pos) = pos$ 
  - A value to indicate the word's position
  - Larger value (longer sentence) may not be easily generalized 😞

# Positional Encoding

- Criteria for positional embeddings
  - ✓ Unique encoding for each position
  - ✓ Deterministic
  - ✓ Distance between neighboring positions should be the same
  - Model can easily generalize to longer sentences
- Idea 2: 1-hot encoding
  - A d-dim vector to encode d positions
  - Cannot generalize to longer sentences 😞


$[1, 0, 0, \dots, 0]$   $\Rightarrow$  only represent the sequences with the length  $\leq d$   
└──────────┘  
d-dim




# Positional Encoding

- Criteria for positional encoding
  - ✓ Unique encoding for each position
  - ✓ Deterministic
  - Distance between neighboring positions should be the same
  - ✓ Model can easily generalize to longer sentences

- Idea 3:  $PE(pos) = \frac{pos}{len}$ 
  - The normalized value of the position (0~1)
  - Distances may differ in sentences with different lengths ☹

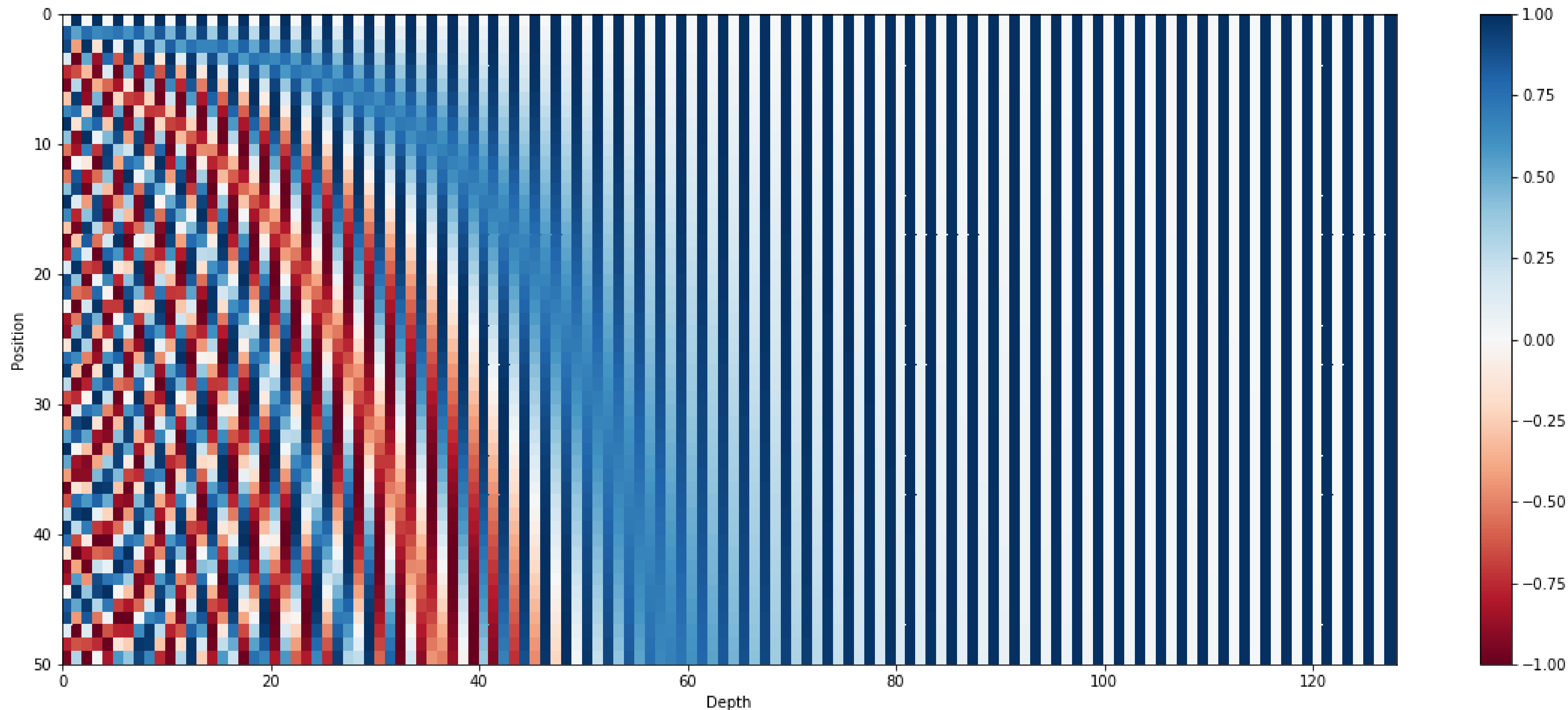
	$w_1$	$w_2$	$w_3$	$w_4$
PE	0.25	0.50	0.75	1.00
				
	0.25			

	$w_1$	$w_2$	$w_3$	$w_4$	$\cdots$	$w_{10}$
PE	0.10	0.20	0.30	0.40		1.00
						
	0.10					

# Sinusoidal Positional Encoding

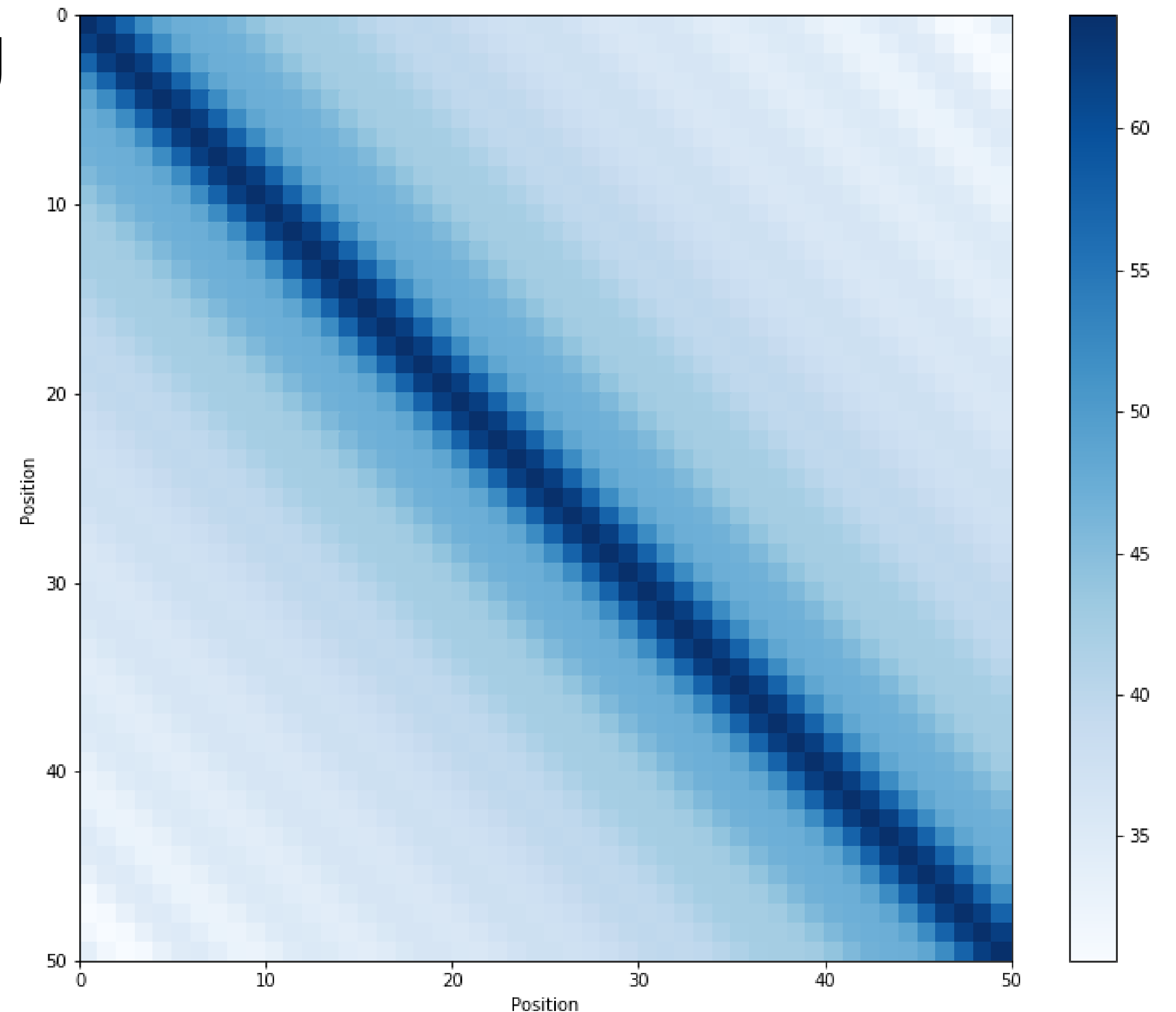
- Criteria for positional embeddings
  - ✓ Unique encoding for each position
  - ✓ Deterministic
  - ✓ Distance between neighboring positions should be the same
  - ✓ Model can easily generalize to longer sentences
- Idea:
$$\text{PE}(\text{pos}, 2i) = \sin\left(\frac{\text{pos}}{100000^{2i/d}}\right)$$
$$\text{PE}(\text{pos}, 2i + 1) = \cos\left(\frac{\text{pos}}{100000^{2i/d}}\right)$$
  - A d-dim vector to represent positions

# Sinusoidal Positional Encoding



# Sinusoidal Positional Encoding

- Distance between neighboring positions
  - symmetrical
  - decay nicely with time

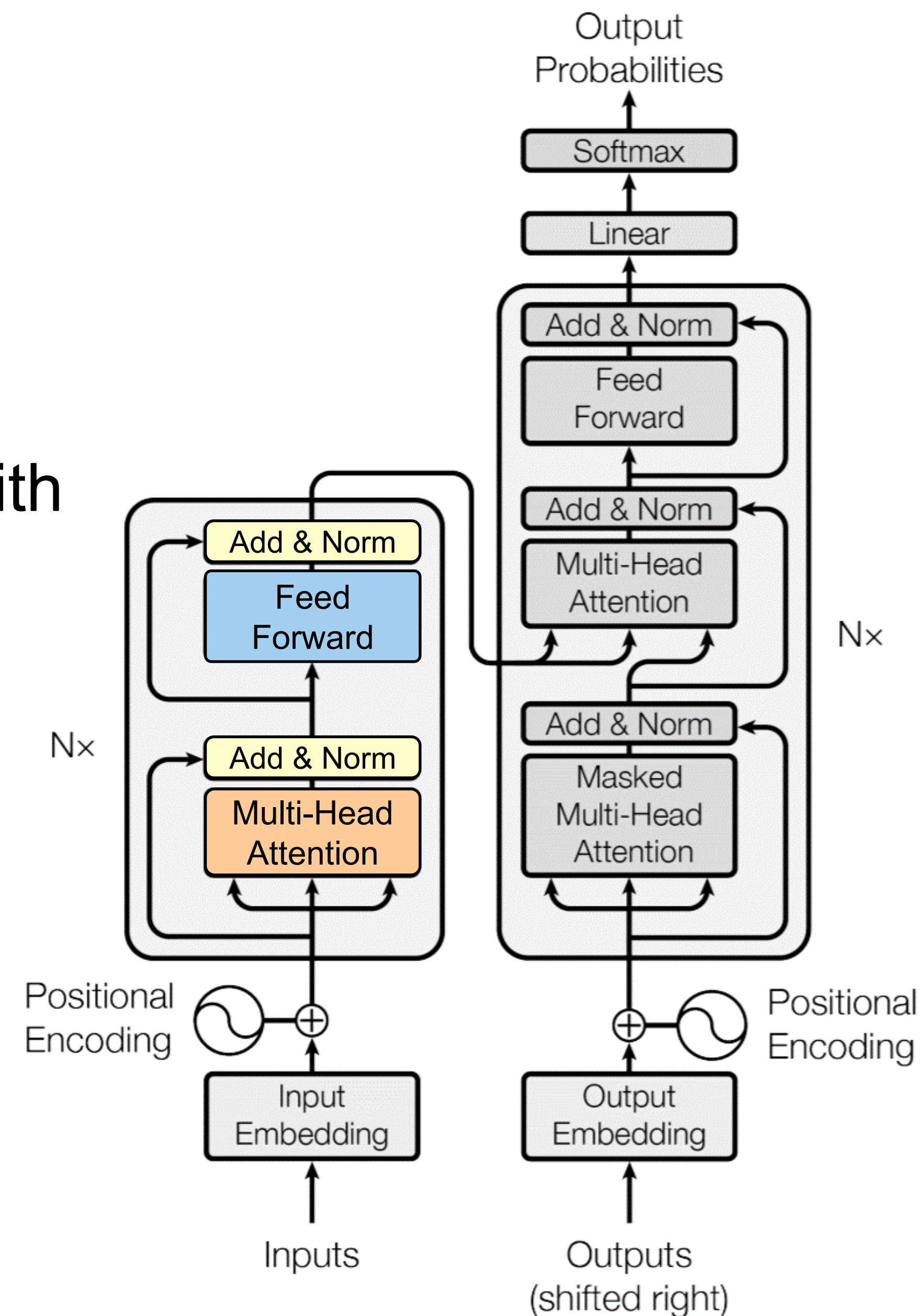


Dot product of position embeddings for all time-steps



# Encoder Input

- Problem: temporal information is missing
- Solution: **positional encoding** allows words at different locations to have different embeddings with fixed dimensions



# Multi-Head Attention Details

encoder self attention

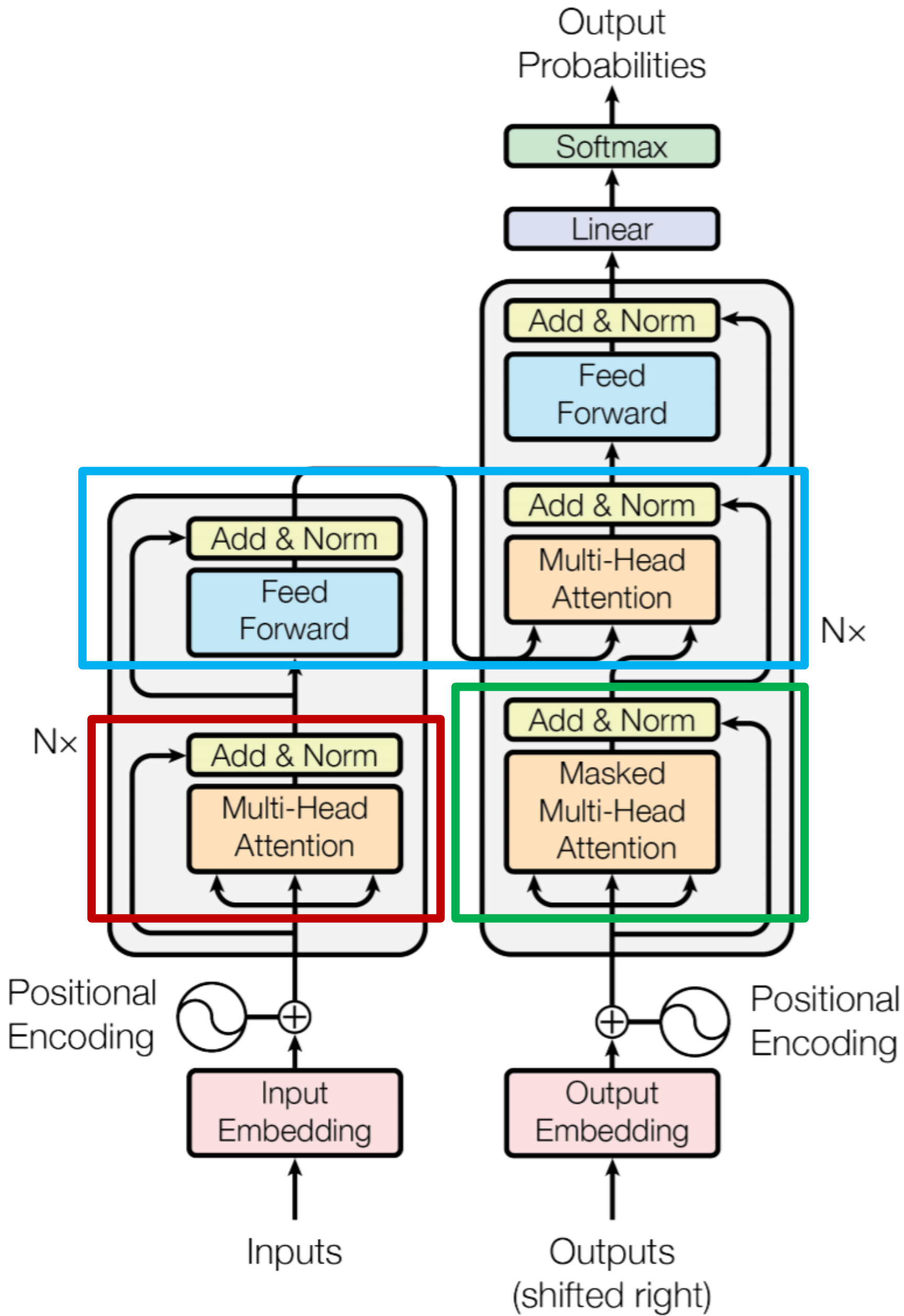
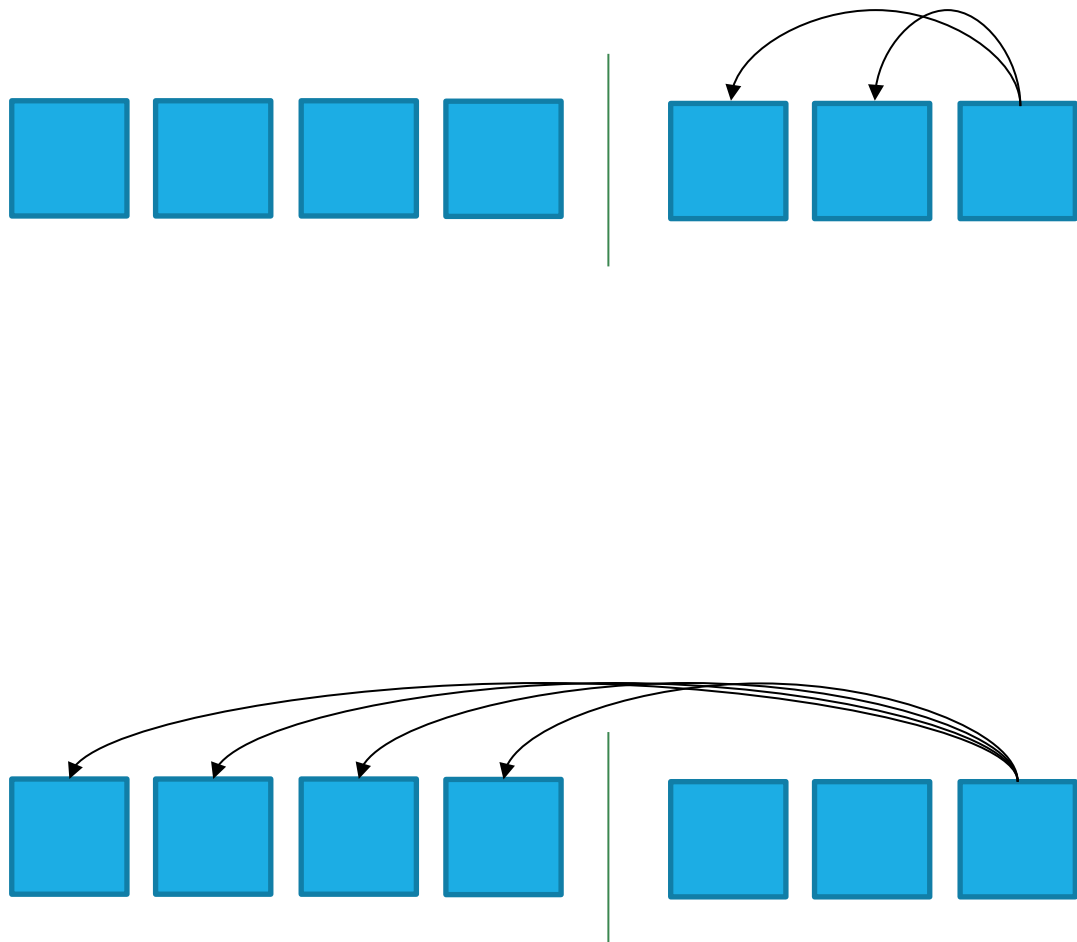
1. Multi-head Attention  
 2. **Q**uery=**K**ey=**V**alue

decoder self attention

1. **M**asked Multi-head Attention  
 2. **Q**uery=**K**ey=**V**alue

encoder-decoder attention

1. Multi-head Attention  
 2. Encoder Self attention=**K**ey=**V**alue  
 3. Decoder Self attention=**Q**uery



# Training Tips

- Byte-pair encodings (BPE)
- Checkpoint averaging
- ADAM optimizer with learning rate changes
- Dropout during training at every layer just before adding residual
- Label smoothing
- Auto-regressive decoding with beam search and length penalties

# MT Experiments

Model	BLEU		Training Cost (FLOPs)	
	EN-DE	EN-FR	EN-DE	EN-FR
ByteNet [18]	23.75			
Deep-Att + PosUnk [39]		39.2		$1.0 \cdot 10^{20}$
GNMT + RL [38]	24.6	39.92	$2.3 \cdot 10^{19}$	$1.4 \cdot 10^{20}$
ConvS2S [9]	25.16	40.46	$9.6 \cdot 10^{18}$	$1.5 \cdot 10^{20}$
MoE [32]	26.03	40.56	$2.0 \cdot 10^{19}$	$1.2 \cdot 10^{20}$
Deep-Att + PosUnk Ensemble [39]		40.4		$8.0 \cdot 10^{20}$
GNMT + RL Ensemble [38]	26.30	41.16	$1.8 \cdot 10^{20}$	$1.1 \cdot 10^{21}$
ConvS2S Ensemble [9]	26.36	<b>41.29</b>	$7.7 \cdot 10^{19}$	$1.2 \cdot 10^{21}$
Transformer (base model)	27.3	38.1	<b><math>3.3 \cdot 10^{18}</math></b>	
Transformer (big)	<b>28.4</b>	<b>41.8</b>	$2.3 \cdot 10^{19}$	



# Parsing Experiments

Parser	Training	WSJ 23 F1
Vinyals & Kaiser et al. (2014) [37]	WSJ only, discriminative	88.3
Petrov et al. (2006) [29]	WSJ only, discriminative	90.4
Zhu et al. (2013) [40]	WSJ only, discriminative	90.4
Dyer et al. (2016) [8]	WSJ only, discriminative	91.7
Transformer (4 layers)	WSJ only, discriminative	91.3
Zhu et al. (2013) [40]	semi-supervised	91.3
Huang & Harper (2009) [14]	semi-supervised	91.3
McClosky et al. (2006) [26]	semi-supervised	92.1
Vinyals & Kaiser et al. (2014) [37]	semi-supervised	92.1
Transformer (4 layers)	semi-supervised	92.7
Luong et al. (2015) [23]	multi-task	93.0
Dyer et al. (2016) [8]	generative	93.3

# Concluding Remarks

- **Non-recurrence** model is easy to parallelize
- **Multi-head attention** captures different aspects by interacting between words
- **Positional encoding** captures location information
- Each transformer block can be applied to diverse tasks

