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Deep Feature Selection

In this notebook, we will demonstrate how to implement our method on the linear simulation examples from our paper.

User Guide on linear example

In this example, a high dimensional dataset with 1000 covariates and 500 observations is generated using the linear system:

$$y = X\beta + \epsilon$$

where $\beta \in \mathbb{R}^{1000}$, but only the first 100 elements of β is non-zero. Our task is to correctly select the important variables. Please see section 5.1 of the paper for detailed generation process.

```
In [1]: import sys
    sys.path.append("../../src")
    from time import clock
    import numpy as np
    import pandas as pd
    import matplotlib.pyplot as plt
    import torch
    import torch.nn.functional as F
    from torch.autograd import Variable
    from torch.autograd import parameter
    from utils import data_load_l, measure, mse
    from models import DFS_epoch, training_l
```

Data Preparation

We will load our data in the following chunk.

The data, both covariates and response, need to be load as pytorch Tensor objects to be fed in to DFS algorithm.

The covariates matrix of training set need to be \sqrt{n} column-wise normalized, n is the sample size, i.e. summation of square of each column is n.

The covariates matrix of testing set also need to be normalized correspondingly, i.e. divided by the some normalization constant of the training set. The function data_load_l will automatically read in dataset, normalizing, and split the dataset into training and test set.

```
In [2]: # load and prepare datasets
        dirc = "../../data/linear/p_1000_N_1000_s_100/"
        k = 0 # dataset number from 0 to 9
        X, Y, X_test, Y_test, supp_true = data_load_l(k, directory=dirc)
        N, p = X.shape
        print("The covariates is of type:", type(X))
        print("The response is of type:", type(Y))
        print("The dimension of training set:", X.shape)
        print(" The sum square of the first 5 columns:")
        print("
                   ", torch.sum(X**2, dim=0)[:5])
        print()
        print("The dimension of test set:", X test.shape)
        print("
                   The sum square of the first 5 columns:")
                   ", torch.sum(X test**2, dim=0)[:5])
        print("
        The covariates is of type: <class 'torch.Tensor'>
        The response is of type: <class 'torch.Tensor'>
        The dimension of training set: torch.Size([500, 1000])
            The sum square of the first 5 columns:
             tensor([499.9998, 500.0001, 500.0001, 499.9999, 499.9999])
        The dimension of test set: torch.Size([500, 1000])
            The sum square of the first 5 columns:
             tensor([467.6035, 536.6000, 467.3558, 435.5148, 476.9774])
```

As displayed above, all columns of training set covariates matrix are normalized. The columns of test set covariates matrix is normalized by constant of training set, thus their sum square of columns are not unified. But since training set and test set follows the same distribution, they have very similar sum squares.

DFS with fixed hyper-parameters

In this section, we demonstrate how to run DFS with one given set of hyper-parameters. The hyper-parameters includes:

- s, the number of variables to be selected;
- c, the tunning parameters to control the magnitude of λ_1 and λ_2 ;
- epochs, the number of DFS iterations to be run;
- n_hidden1, the number of neurons in the fully connect neural networks;
- learning rate, the learning rate for optimizer;
- Ts & step, the parameters to control the optimization on given support

Among the above hyper-parameters, s is the most important parameters, and the selection of s will be demonstrated in next section. c can be selection through a sequence of candidates that returns the smallest loss function. Others mostly are meant to help the convergence of the optimization steps.

```
In [3]: # specify hyper-paramters
        s = 100
        c = 1
        epochs = 3 # We reduced the number of epochs in notebooks
        n hidden1 = 1
        learning rate = 0.001
        Ts = 1000
        step = 1
        # Define Model
        torch.manual_seed(1) # set seed
        # Define a model with pre-specified structure and hyper parameters
        model = Net_linear(n_feature=p, n_hidden1=n_hidden1, n_output=1)
        # Define another model to save the current best model based on loss func
        tion value
        # The purpose is to prevent divergence of the training due to large lear
        ning rate or other reason
        best model = Net linear(n feature=p, n hidden1=n hidden1, n output=1)
        # Define optimizers for the optimization with given support
        # optimizer to separately optimize the hidden layers and selection layer
        # the selection layer will be optimized on given support only.
        # the optimzation of hidden layers and selection layer will take turn in
        iterations
        optimizer = torch.optim.SGD(list(model.parameters()), lr=learning_rate,
        weight decay=0.0025*c)
        optimizer0 = torch.optim.SGD(model.hidden0.parameters(), lr=learning rat
        e, weight decay=0.0005*c)
        # Define loss function
        lf = torch.nn.MSELoss()
        # Allocated some objects to keep track of changes over iterations
        hist = []
        SUPP = []
        supp_x = list(range(p)) # initial support
        SUPP.append(supp x)
        ### DFS algorithm
        start = clock()
        for i in range(epochs):
            # One DFS epoch
            model, supp x, = DFS epoch(model, s, supp x, X, Y, lf, optimizer0,
        optimizer, Ts, step)
            supp x.sort()
            # Save current loss function value and support
            hist.append(lf(model(X), Y).data.numpy().tolist())
            SUPP.append(supp x)
            # Prevent divergence of optimization over support, save the current
         best model
            if hist[-1] == min(hist):
                best model.load state dict(model.state dict())
                best supp = supp x
            # Early stop criteria
            if len(SUPP[-1]) == len(SUPP[-2]) and len(set(SUPP[-1]).difference(S
```

```
UPP[-2])) == 0:
    break

end = clock()
print("Training finished in", len(SUPP)-1, "epochs, and took", end-start
, "seconds")
Training finished in 3 epochs, and took 2689.92 seconds
```

In the following chunk, we will demonstrate the results from the DFS algorithm, in terms of selected support, number of missed or false selected support, training mse and test mse for **one step** procedure.

```
In [4]: ### metrics calculation
         fs = set(best_supp).difference(supp_true) # false selection number
         ns = set(supp_true).difference(best_supp) # negative selection number
         _err_train = mse(best_model, X, Y) # training error
         _err_test = mse(best_model, X_test, Y_test) # testing error
         print("The support selected is:", best_supp)
         print("The index of non-zero coefficients on selection layer:",
                np.where(best model.hidden0.weight != 0)[0])
         print("False selected variables:", fs)
         print("Missed variables:", ns)
         print("The training mse of one step is:", _err_train)
         print("The test mse of one step is:", err test)
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                                      99 100 491 8531
         False selected variables: {100, 853, 491}
         Missed variables: {96, 58, 13}
         The training mse of one step is: 722.839599609375
         The test mse of one step is: 643.0396118164062
```

From the results above, we have successfully selected most of the important variables without knowing the underling model and with the presence of correlation between variables.

In the following chunk, we will perform a two-step procedure to train the best_model on the given support.

Two-step procedure is used for two reasons, to get better predictive performance and to get better estimation of bic which is important in selection of optimal s.

As we demonstrated on the above chunk, the selection layer of best_model has non-zero coefficients on given support. In the second step, we treat best_model as our initial model and update parameters only in hidden layer.

```
In [5]: # Define optimizer only update parameters in hidden layer.
        optimizer = torch.optim.Adam(list(best model.parameters())[1:], lr=0.5)
        for _ in range(5000):
            out = best_model(X)
            loss = lf(out, Y)
            _optimizer.zero_grad()
            loss.backward()
            optimizer.step()
            hist.append(loss.data.numpy().tolist())
        ### metric calculation
        mse train = mse(best model, X, Y)
        mse test = mse(best model, X test, Y test)
        print("The training mse of two step is:", mse_train)
        print("The test mse of two step is:", mse test)
        The training mse of two step is: 1.1326223611831665
        The test mse of two step is: 1.2946219444274902
```

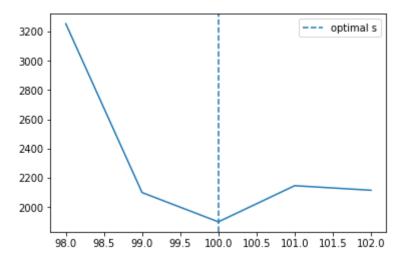
The result has shown that the predictive performance of our model is significantly increased.

All good results shown above is based on the correct given s. However, in reality, s is unknown for most of the time. So the next thing would be finding the optimal s

Selection of s

In this section, we demonstrate the procedure of selection of optimal s. We have wrapped up the training procedure above in a function training_1. For each given s, bic, defined as $n \cdot \log \hat{\sigma}^2 + c \cdot s \cdot \log n$, of the model will be automatically calculated by training_1, also the trained model with the given s will also be returned.

```
In [6]: |Ss = [98, 99, 100, 101, 102]
        BIC = []
        for i, s in enumerate(Ss):
            model, supp, bic, _, [err train, err_test] = training_l(X, Y, X_test
        , Y_test, supp_true, c, s, epochs=3, Ts=1000)
            BIC.append(bic)
            if bic == min(BIC):
                best model = model
                best_supp = supp
                best_err_train, best_err_test = err_train, err_test
        idx = np.argmin(BIC)
        best s = Ss[idx]
        plt.plot(Ss, BIC)
        plt.axvline(x=best_s, ls='--', label="optimal s")
        plt.legend()
        plt.show()
```



From the graph above, we can tell s=100 is the optimal s, and the corresponding model is stored in best model whose performance is shown below:

```
In [7]: fs = set(best_supp).difference(supp_true)
    ns = set(supp_true).difference(best_supp)
    mse_train = mse(best_model, X, Y)
    mse_test = mse(best_model, X_test, Y_test)
    print("Number of false selected variables:", fs)
    print("Number of missed variables:", ns)

print("The training mse of best model based on optimal s is:", mse_train
)
    print("The test mse of best model based on optimal s is:", mse_test)

Number of false selected variables: {100, 853, 491}
    Number of missed variables: {96, 58, 13}
    The training mse of best model based on optimal s is: 1.132622361183166
    5

The test mse of best model based on optimal s is: 1.2946219444274902
```