Constraint Satisfaction Problems (CSPs)

CS 221 Section - 10/31/19

Chuma Kabaghe

Will Deaderick

Agenda

- CSP Problem Modeling
- N-ary Constraints
- Exam Problem Solving

Factor Graph and CSP Applications

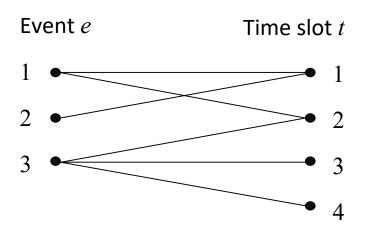
- Scheduling problems: event scheduling, resource and assembly scheduling
- Inferring relations from data
- Puzzles: sudoku, crosswords
- Satisfiability problems
- Map and graph coloring
- Object tracking
- Decoding noisy signals (images, messages etc.)

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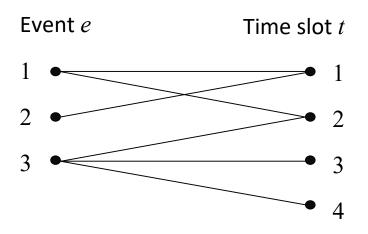
Setup:

- Have E events and T time slots
- Each event e must be put in exactly one time slot
- Each time slot t can have at most one event
- Event e only allowed at time slot t if (e, t) in A



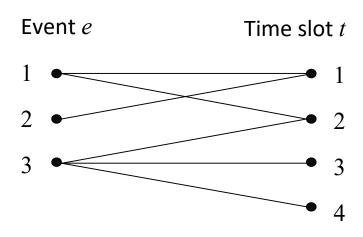
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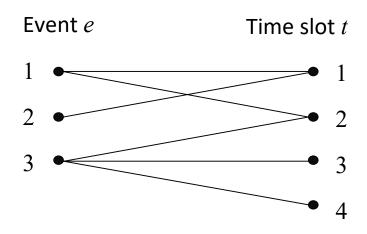


Formulation 1a:

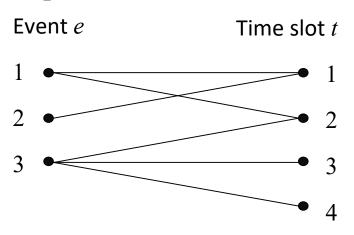
• Variables for each event $e, X_e \in \{1,...,T\}$



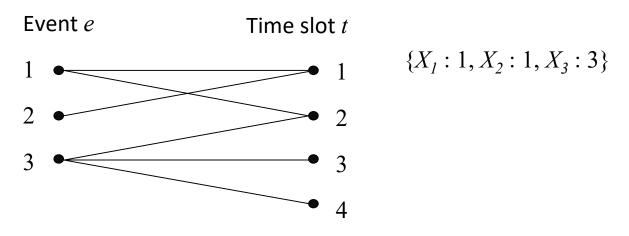
- Variables for each event $e, X_e \in \{1,...,T\}$
- Constraints (only one event per time slot): for each pair of events $e \neq e'$, enforce $[X_e \neq X_{e'}]$



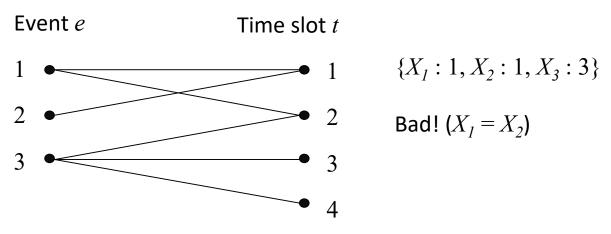
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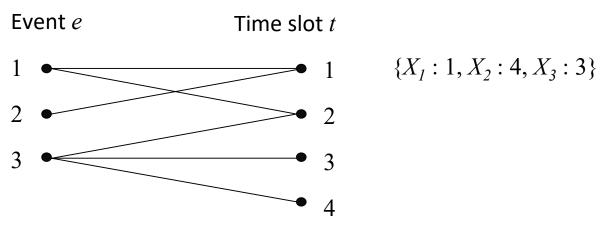
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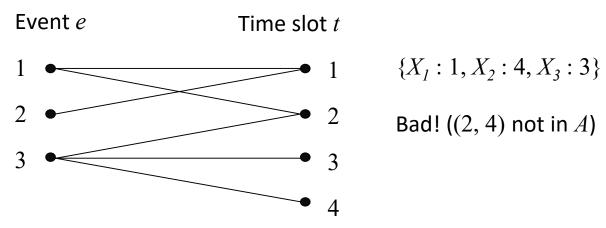
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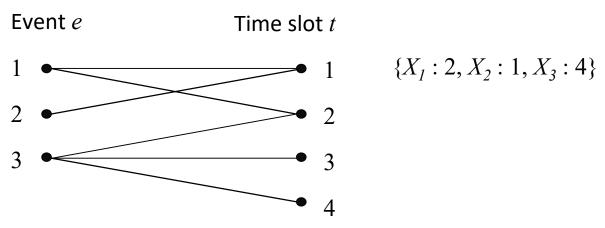
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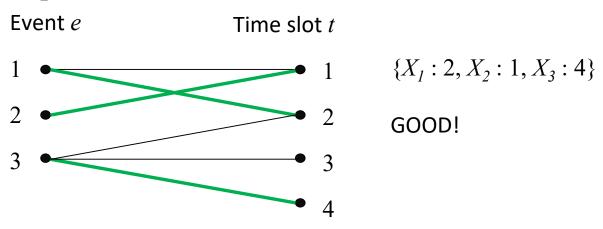
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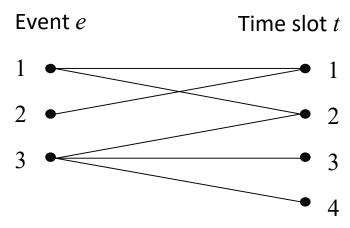
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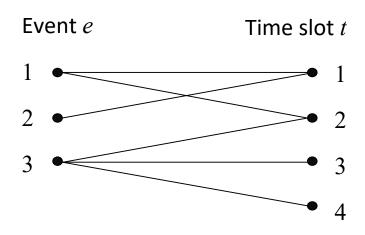


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Formulation 1b:

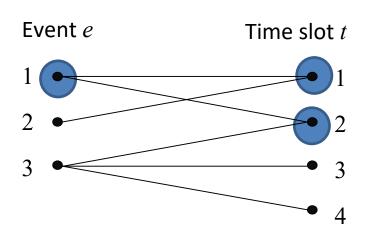
• Variables for each event $e, X_1,...,X_E$



Formulation 1b:

• Variables for each event e, $X_1,...,X_E$

$$Domain_i = \{t : (i, t) \in A\}$$

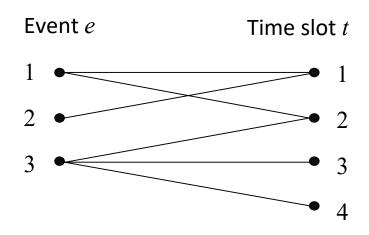


Formulation 1b:

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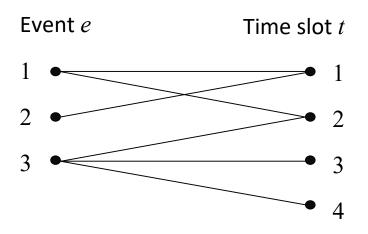
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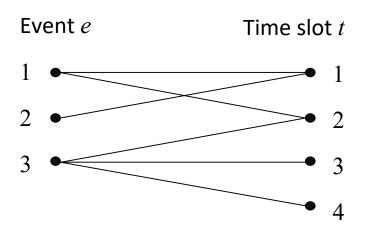


Formulation 2a:

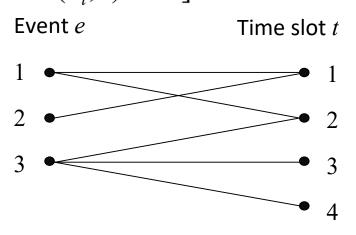
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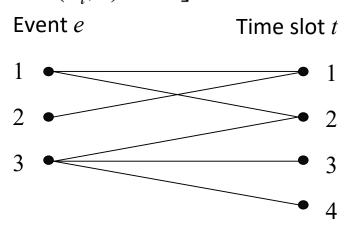
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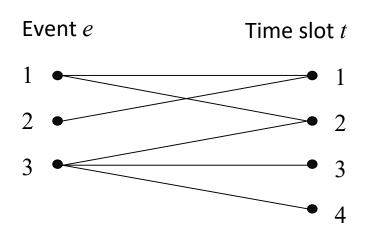


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Formulation 2b:

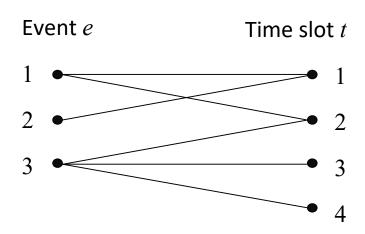
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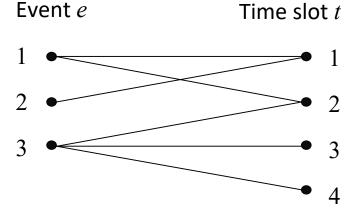


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• Constraints (each event is scheduled exactly once): for each event e, enforce $[Y_t = e$ for exactly one t]



Formulation 1a:

E variables with domain size T, and O(E^2) binary constraints.

- Variables for each event $e, X_e \in \{1,...,T\}$
- Constraints (only one event per time slot): for each pair of events $e \neq e'$, enforce $[X_e \neq X_{e'}]$
- Constraints (only schedule allowed times): for each event e, T variables with domain size E+1 enforce $[(e, X_e) \in A]$ O(T^2) variables with domain size Formulation 2a: 2 and O(T^2) binary constraints.

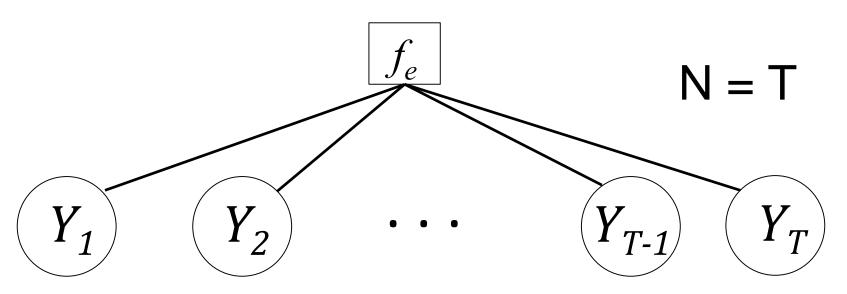
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- From event scheduling:
 - Constraints (each event is scheduled exactly once): for each event *e*, enforce

$$[Y_t = e \text{ for exactly one } t]$$



Key Idea: Auxiliary Variables

Auxiliary Variables hold intermediate computation.

Represent "for exactly one" as counting the number of values equal to e and constraining that count to be equal to one.

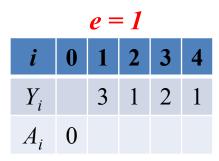
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Factors:

Initialization: $[A_0 = 0]$



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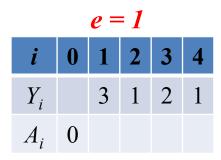
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Processing: $[A_i = A_{i-1} + 1[Y_i = e]]$



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e-1					
i	0	1	2	3	4
Y_{i}		3	1	2	1
A_{i}	0				

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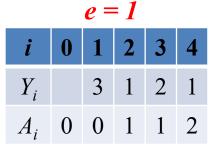
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Factors:

Initialization: $[A_{\theta} = 0]$

Processing: $[A_i = \min(A_{i-1} + 1[Y_i = e], 2)] A_i = 0 = 0 = 1 = 1 = 2$

Final Output: $1[A_T = 1]$



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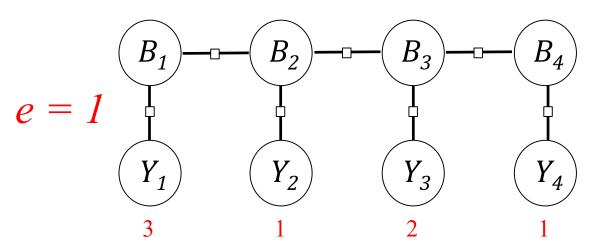
Final Output: $1[A_T = 1]$

$$e = 1$$
 i
 0
 1
 2
 3
 4
 Y_i
 3
 1
 2
 1
 A_i
 0
 0
 1
 1
 2

Still have factors with three variables...

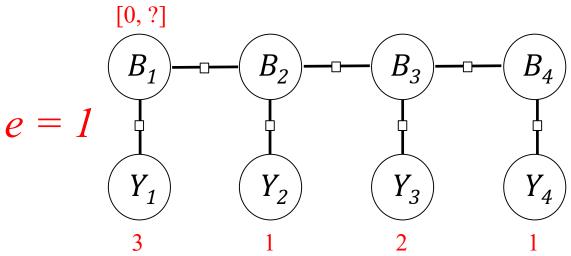
Key idea: Combine A_{i-1} and A_i into one variable B_i

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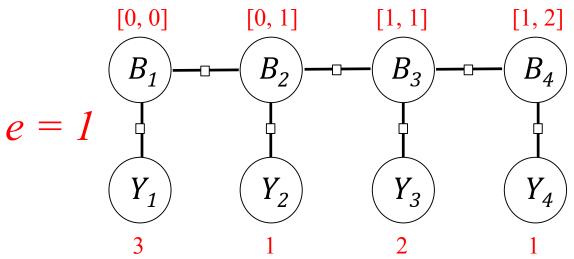
Initialization: $[B_I[0] = 0]$

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Final Output: $1[B_T[1] = 1]$

Consistency: $[B_{i-1}[1] = B_i[0]]$

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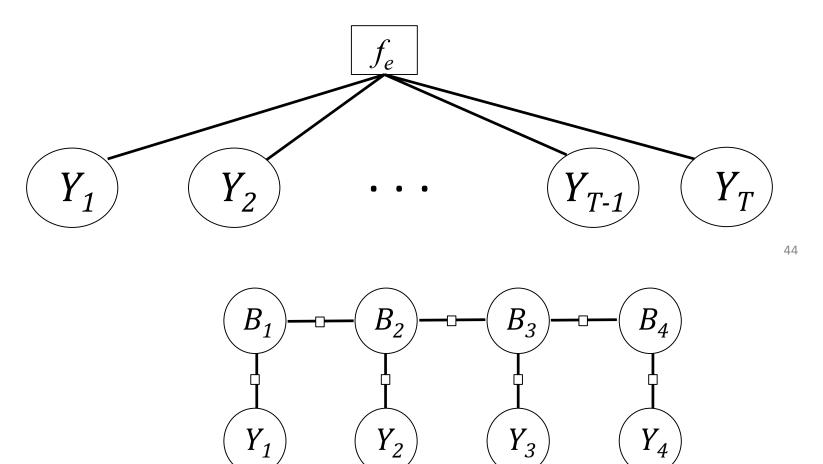
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 $[Y_t = e \text{ for exactly one } t]$



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