

Memory allocation



Systems Programming

alloc.s

```
#####GLOBAL VARIABLES#####
# This points to the beginning of the memory we are managing
heap_begin:      .quad 0
# This points to one location past the memory we are managing
current_break:   .quad 0

#####STRUCTURE INFORMATION####
.equ HEADER_SIZE,16      # Size of space for memory region header
.equ HDR_AVAIL_OFFSET,0  # Offset of the "available" flag in the header
.equ HDR_SIZE_OFFSET,8   # Offset of the size field in the header

#####CONSTANTS#####
.equ UNAVAILABLE,0      # This is the number we will use to mark
                        # space that has been given out
.equ AVAILABLE,1        # This is the number we will use to mark
                        # space that has been returned, and is
                        # available for giving out
.equ SYS_BRK,12         # System call number for the break
```

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```
##allocate_init##
#PURPOSE: Call this function to initialize the functions (specifically,
#         this sets heap_begin and current_break). This has no
#         parameters and no return value.
.globl allocate_init
.type allocate_init,@function
allocate_init:
    pushq %rbp                # Standard function stuff
    movq  %rsp,%rbp
    # If the brk system call is called with 0 in %rdi, it
    # returns the last valid usable address
    movq  $SYS_BRK,%rax       # Find out where the break is
    movq  $0,%rdi
    syscall
    movq  %rax,current_break  # Store the current break
    movq  %rax,heap_begin     # Store the current break as our
                                # first address. This will cause
                                # the allocate function to get
                                # more memory from Linux the
                                # first time it is run
    movq  %rbp,%rsp          # Exit the function
    popq  %rbp
    ret
```

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```
#PURPOSE:      This function is used to grab a section of memory. It
# checks to see if there are any free blocks, and, if not, it asks Linux
# for a new one.
#PARAMETERS: One parameter - size of memory block to allocate
#RETURN VALUE: This function returns the address of the allocated memory
# in %rax. If there is no memory available, it will return 0 in %rax
#Variables used:
#   %rdi - hold the size of the requested memory (first/only parameter)
#   %rax - current memory region being examined
#   %rdx - current break position
#   %rcx - size of current memory region
# We scan through each memory region starting with heap_begin. We look
# at the size of each one, and if it has been allocated. If it's big
# enough for the requested size, and its available, it grabs that one.
# If it does not find a region large enough, it asks Linux for more
# memory. In that case, it moves current_break up
```

```
.globl allocate
```

```
.type allocate,@function
```

```
allocate:
```

```
    pushq %rbp                # Standard function stuff
    movq  %rsp, %rbp
    movq  heap_begin, %rax     # %rax will hold the current search location
    movq  current_break, %rdx  # %rdx will hold the current break
```

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```
alloc_loop_begin:           # Here we iterate through each memory region
    cmpq   %rdx,%rax        # Need more memory if these are equal
    je     move_break
    movq   HDR_SIZE_OFFSET(%rax),%rcx # Grab the size of this memory
    cmpq   $UNAVAILABLE,HDR_AVAIL_OFFSET(%rax)
    je     next_location    # If the space is unavailable, go to next one
    cmpq   %rdi,%rcx        # If the space is available, compare
    jle    allocate_here    # the size to the needed size. If its
                             # big enough, go to allocate_here

next_location:
    addq   $HEADER_SIZE,%rax # The total size of the memory region is the
    addq   %rcx,%rax         # sum of the size requested (currently stored
                             # in %rcx), plus another 16 bytes for the
                             # header (8 for the AVAILABLE/UNAVAILABLE flag,
                             # and 8 for the size of the region). So, adding
                             # %rcx and $16 to %rax will get the address
                             # of the next memory region
    jmp    alloc_loop_begin  # Go look at the next location
```

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```
allocate_here:      # If we've made it here, that means that the
                    # region header of the region to allocate is in %rax
                    # Mark space as unavailable
movq  $UNAVAILABLE,HDR_AVAIL_OFFSET(%rax)
addq  $HEADER_SIZE,%rax  # Move %rax past the header to the usable
                        # memory (since that's what we return)
movq  %rbp,%rsp          # Return from the function
popq  %rbp
ret

move_break:        # If we've made it here, that means that we have exhausted
                    # all addressable memory, and we need to ask for more.
                    # %rdx(=%rax) holds the current endpoint of the data, and %rdi
                    # holds its size
                    # We need to increase %rdx to where we _want_ memory to end, so we
addq  $HEADER_SIZE,%rdx  # add space for the headers structure, and
addq  %rdi,%rdx          # add space for the data size requested
pushq %rax              # Save needed registers
pushq %rcx
pushq %rdx
pushq %rdi
movq  %rdx,%rdi          # Prepare parameter
movq  $SYS_BRK,%rax      # Reset break (%rdi has requested break point)
```

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```
syscall    # Under normal conditions, this should return the new break in
           # %rax, which will be either 0 if it fails, or it will be equal
           # to or larger than we asked for. We don't care in this
           # program where it actually sets the break, so as long as %rax
           # isn't 0, we don't care what it is

cmpq    $0,%rax                # Check for error conditions
je      error
popq    %rdi                   # Restore saved registers
popq    %rdx
popq    %rcx
popq    %rax                   # Note: We throw away actual new break here!
# Set this memory as unavailable, since we're about to give it away
movq    $UNAVAILABLE,HDR_AVAIL_OFFSET(%rax)
movq    %rdi,HDR_SIZE_OFFSET(%rax)    # Set the size of the memory
# Move %rax to the actual start of usable memory.
# %rax now holds the return value
addq    $HEADER_SIZE,%rax
movq    %rdx,current_break    # Save the new break
# Fall through to return from function
error:
movq    %rbp,%rsp              # On error we return zero,
popq    %rbp                  # which it already is
ret
```

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```
##deallocate##
#PURPOSE: The purpose of this function is to give back a region of
#         memory to the pool after we're done using it.
#PARAMETERS: The only parameter is the address of the memory
#            we want to return to the memory pool.
#RETURN VALUE: There is no return value
#PROCESSING: If you remember, we actually hand the program the
#            start of the memory that they can use, which is 16 storage
#            locations after the actual start of the memory region. All we
#            have to do is go back 16 locations and mark that memory as
#            available, so that the allocate function knows it can use it.
.globl deallocate
.type deallocate,@function
.equ ST_MEMORY_SEG,4          # Stack position of the memory region to free
deallocate:
# Since the function is so simple, we
# don't need any of the fancy function stuff
# Get the pointer to the real beginning of the memory
subq  $HEADER_SIZE,%rdi
# Mark it as available
movq  $AVAILABLE,HDR_AVAIL_OFFSET(%rdi)
ret   # Return
```


alloc-demo.s

```
.section .text

.globl _start
_start:
    call allocate_init # Initialize memory manager
    movq $8,%rdi        # Alloc takes size as argument
    call allocate        # Allocate space for one quad (64 bits)
    cmpq $0,%rax        # Check success
    jne use_memory
    movq $-1,%rdi        # Return -1 on error
    jmp end
use_memory:
    movq $8, (%rax)      # Write immediate 8 into the allocated space
    movq (%rax),%rdi      # Read the value from memory and load it into %rdi
    movq %rax,%rdi        # Free all used memory
    call deallocate       # Everything reserved should (must) be freed again
end:
    movq $60,%rax        # Call the kernel's exit function
                        # Return value should be 8

syscall
```

Notes on alloc.s

■ How do we get the **current break**?

- ☐ Call `brk` with 0 in RDI

■ **Allocate**

- ☐ 1. Start at beginning of heap
- ☐ 2. Check if we are at the end of the heap
- ☐ 3. If at end of heap → grab new memory and mark as unavailable
- ☐ 4. If current region is unavailable → go to next; then to step 2
- ☐ 5. If current region is too small → go to next; then to step 2
- ☐ 6. If available memory is large enough → mark as unavailable + return it

■ **Deallocate**

- ☐ Just mark region as available
 - Note: We don't check whether the address passed in is really the start of a valid (and used) block – we just assume this!

Notes on alloc.s

- Every mapped memory region has an additional **header** of 16 bytes
 - Status: 8 bytes
 - Available → 1
 - Unavailable → 0
 - Size: 8 bytes
- Example: 56 Bytes in total, 40 bytes of memory have been reserved



Notes on alloc.s

■ Problems of the simple allocator

- ☐ Too **slow** if there are many allocations
 - Linear search for fitting region
 - Regions are possibly swapped to disk
 - Bringing them back to memory takes a lot of time
- ☐ Number of system calls should be minimized
 - Expensive context switches
 - `brk` called, even if break might be much higher from the previous call
- ☐ Memory wasted
 - Use a 1KB region for 4 bytes
 - 1020 - 4 - 16 (header) bytes wasted
 - Splitting needed
- ☐ No verification whether a block freed is actually the start address of a valid block

THANK YOU FOR YOUR ATTENTION!



JOHANNES KEPLER
UNIVERSITÄT LINZ



INSTITUTE
OF NETWORKS
AND SECURITY

<http://www.ins.jku.at>

Michael Sonntag

michael.sonntag@ins.jku.at

+43 (732) 2468 - 4137

S3 235 (Science park 3, 2nd floor)

**JOHANNES KEPLER
UNIVERSITÄT LINZ**

Altenberger Straße 69
4040 Linz, Österreich
www.jku.at