

A Hierarchical Representation Network for Accurate and Detailed Face Reconstruction from In-The-Wild Images

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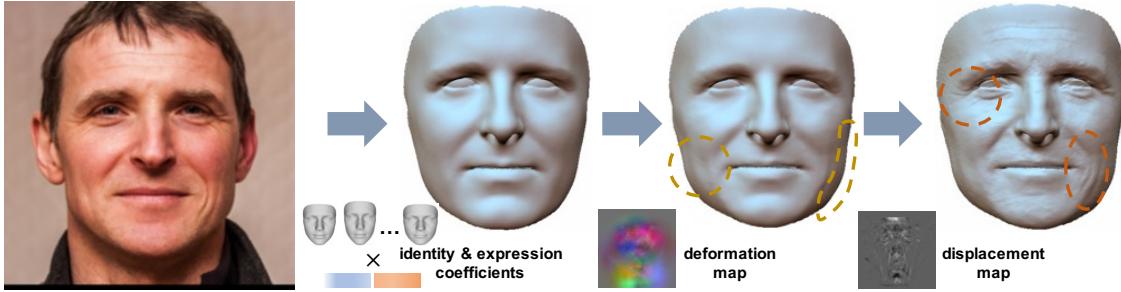


Figure 1. Example of low-frequency geometry, MF, HF facial details and the hierarchical representation.

Abstract

*Limited by the nature of the low-dimensional representational capacity of 3DMM, most of the 3DMM-based face reconstruction (FR) methods fail to recover high-frequency facial details, such as wrinkles, dimples, etc. Some attempt to solve the problem by introducing detail maps or non-linear operations, however, the results are still not vivid. To this end, we in this paper present a novel **hierarchical representation network** (HRN) to achieve accurate and detailed face reconstruction from a single image. Specifically, we implement the geometry disentanglement and introduce the hierarchical representation to fulfill detailed face modeling. Meanwhile, 3D priors of facial details are incorporated to enhance the accuracy and authenticity of the reconstruction results. We also propose a de-retouching module to achieve better decoupling of the geometry and appearance. It is noteworthy that our framework can be extended to a multi-view fashion by considering detail consistency of different views. Extensive experiments on two single-view and two multi-view FR benchmarks demonstrate that our method outperforms the existing methods in both reconstruction accuracy and visual effects. Finally, we introduce a high-quality 3D face dataset **FaceHD-100** to boost the research of high-fidelity face reconstruction.*

1. Introduction

High-fidelity 3D face reconstruction finds a wide range of applications in many scenarios, such as AR/VR, medical

treatment, film production, etc. While extensive works already achieved excellent reconstruction performance using specialized hardware like LightStage [2, 10, 34], estimating highly detailed face models from single or sparse-view images is still a challenging problem. Based on 3DMM [7], a statistical model learned from a collection of face scans, many works [15, 21, 22, 31] attempt to reconstruct the 3D face from a single image and achieve impressive results. However, limited by the nature of the low dimensional representational ability of the 3DMM, these methods can not recover the detailed facial geometry.

Recently, some methods [12, 23, 37] devote to capturing high-frequency facial details such as wrinkles by predicting a displacement map. They achieve realistic results, however, fail to model the mid-frequency details, such as the detailed contour of the jaw, cheek, etc. To this end, some works try to capture the overall details by introducing latent encoding of details [18] or non-linear operations [19, 43]. Nevertheless, it is hard to make a trade-off when handling the mid- and high-frequency details simultaneously. Another challenge is how to obtain accurate shapes and detailed 3D facial priors considering multifarious lightings and skins for different images. [9, 12] resort to the wrinkle statistics computed from 3D face scans to fulfill realistic high-frequency details, but still fail to model the mid-frequency details.

Based on the observations above, we introduce a hierarchical representation network (HRN) for accurate and de-

tailed face reconstruction from single image, as shown in Fig. 2. Firstly, we decouple the facial geometry into low-frequency geometry, mid-frequency (MF) details, and high-frequency (HF) details. Then, in a hierarchical fashion, we model these parts with face-wise blendshape coefficients, vertex-wise deformation map, and pixel-wise displacement map, respectively (shown in Fig. 1). Concretely, we employ two image translation networks [26] to estimate the corresponding detail maps (deformation and displacement map), and further employ them to generate the detailed face model in a coarse-to-fine manner. Moreover, we introduce the 3D priors of MF and HF details by fitting face scans with our hierarchical representation to facilitate accurate and faithful modeling. Inspired by [32], we propose a de-retouching module to adaptively refine the base texture to overcome the ambiguities between skin blemishes and illuminations. Extensive experiments show that our method outperforms the existing methods on two large-scale benchmarks, exhibiting excellent performance in terms of detail capturing and accurate shape modeling. Thanks to the detail disentanglement strategy and the guidance of detail priors, we extend HRN to a multi-view fashion and achieve accurate FR from only a few views. Finally, to boost the research of sparse-view and high-fidelity FR, we introduce a high-quality 3D face dataset named FaceHD-100.

Our main contributions in this work are as follows:

- (A) We present a hierarchical modeling strategy and propose a novel framework HRN for single-view FR task. Our HRN produces accurate and highly detailed FR results and outperforms the existing state-of-the-art methods on two large-scale single-view FR benchmarks.
- (B) We introduce detail priors to guide the faithful modeling of hierarchical details and design a de-retouching module to facilitate the decoupling of geometry and appearance.
- (C) We extend HRN to a multi-view fashion to form MV-HRN, which enables accurate face modeling from sparse-view images and outperforms the existing methods on two large-scale multi-view FR benchmarks.
- (D) To boost the research on sparse-view and high-fidelity FR tasks, we introduce a high-quality 3D face dataset FaceHD-100, containing 2,000 detailed 3D face models and corresponding high-definition multi-view images.

2. Related Work

Single-View Face Reconstruction. Recovering 3D face from a single image is an ill-posed problem, but the advent of the 3D morphable model (3DMM) [7, 38] has made it possible. The 3DMM provides strong prior knowledge and can represent complicated face geometry with low-dimensional coefficients. In this formulation, current methods can be categorized into either optimization-based [6, 7, 24, 30, 49] or learning-based [14, 39, 42, 50]. Optimization-based approaches usually need costly analysis-by-synthesis

processes and are sensitive to initialization, while learning-based methods directly train neural networks to regress the low-dimensional coefficients of 3DMM and recover 3D face through efficient forward inference.

However, the original 3DMM models inherently lie in low-dimensional linear space and lack fine details. Many works [13, 18, 41, 44, 47] are proposed to overcome this limitation. Tran *et al.* [44] present a nonlinear 3DMM model and achieve more powerful representational abilities. Sela *et al.* [41] employ image-to-image network to generate pixel-based geometric representation for high quality reconstructions. In addition to static face geometry details, Feng *et al.* [18] present an animatable displacement model to generate dynamic expression-depended wrinkles. Yang *et al.* [47] predict displacement maps via pix2pixHD network and combine them according to blendshape weights for dynamic details synthesis. Compared with these approaches, our method further introduces facial detail priors and can recover high fidelity facial details with hierarchical geometry representations.

Multi-View Face Reconstruction. Traditional multi-view stereo (MVS) methods [5, 8, 20] are designed for 3D reconstruction given a set of multi-view images, but they heavily rely on the precision of camera calibration, and can hardly recover intact geometry in the sparse-view situation. To address these problems, many face-specialized multi-view reconstruction methods [4, 16, 25, 35, 36, 45, 46] are proposed. Ramon *et al.* [36] introduce siamese neural networks to extract relevant features from each view, and learn the 3D shape and the individual camera poses simultaneously. Wu *et al.* [45] exploit both 3DMM and multi-view geometric constraints by estimating the alignment loss between multi-view inputs. Bai *et al.* [4] leverage non-rigid multi-view stereo optimization to explicitly enforce multi-view appearance consistency, which is able to capture medium-level details. With the emergence of implicit 3D representation, Xiao *et al.* [46] propose to learn an implicit function to recover detailed geometry from calibrated multi-view images, but the implicit function learning is time-consuming which needs dozen of seconds and is sensitive to camera count and pose estimation.

Rather than a specific design for multi-view inputs, our single-view model can be easily transferred to sparse-view face reconstruction task by adding hierarchical detail consistency between different views. Our method is robust to the calibration error of cameras thanks to the coarse-to-fine learning scheme.

3. Methods

3.1. Overview

In this paper, we propose a novel hierarchical representation network for accurate and detailed face reconstruction

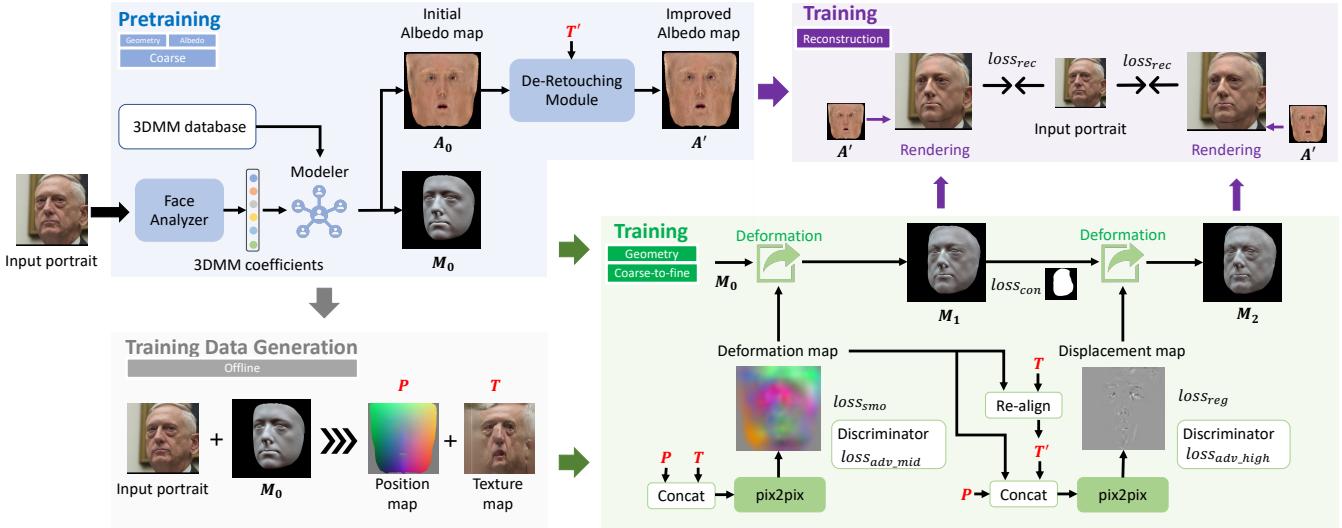


Figure 2. Overview of the proposed hierarchical representation network (HRN).

from single image. Fig. 2 illustrates the overview of our framework. We first employ 3DMM to predict a coarse mesh and albedo (blue area in Fig. 2). Then we develop a **hierarchical modeling** (Sec. 3.2) strategy to handle the complex facial details in a coarse-to-fine manner (green and purple area). To facilitate the accurate and faithful modeling of the hierarchical details, the **3D priors** are incorporated through adversarial and semi-supervised learning (Sec. 3.3). Besides, we propose a **de-retouching module** (Sec. 3.4) to fulfill better decoupling of the geometry and appearance, alleviating the ambiguities between the various skin texture and illuminations. Moreover, we extend our framework to a multi-view fashion (Sec. 3.5) and introduce a high quality 3D face dataset (Sec. 3.6) to boost the research on sparse-view face reconstruction. For simplification, we specify the related loss functions and training strategy in each section.

3.2. Hierarchical Modeling

3DMM exhibit great performance in expressing various shape of the face, while the low-dimensional representation itself severely stem its learning on the details, leading to the imperfect alignment to the face or the over-smoothed results. Some methods extend 3DMM by introducing displacement maps to reconstruct some details such as wrinkles and bumps. However, focused on the high-frequency part, **a simple displacement map still fails to handle some larger-scale details, such as the contours of the jaw and cheek**. Based on such observation, we decouple the facial geometry into three components: (1) low-frequency part, which provides the **coarse shape** roughly aligned to the input face; (2) mid-frequency details, which describe the details of the **contour and local shape** relative to the low-frequency part; (3) and high-frequency details, such as **wrinkles, micro bumps**, etc. As shown in the Fig. 1, the

scales decrease from the low-frequency part to the high-frequency detail, while the fineness increases in turn.

We design the hierarchical representation to model the above three components respectively. For the low-frequency part, we adopt the BFM as our base model and output the low-dimensional coefficients to fulfill a coarse reconstruction of the input face. Then we introduce a **three-channel deformation map**, which lies in the UV space and indicates the offset of each vertex relative to the coarse result. Worked as the representation of the mid-frequency details, the deformation map provides a flexible way to manipulate the geometries. We use the size of 64×64 to represent the deformation map to balance the fineness and smoothness of the mid-frequency details. For the high-frequency details, we employ the displacement map following [18], which is a one-channel map (256×256) denoting the geometry deformation along the direction of the normals. The displacement map is converted to detailed normals used in the rendering process in a pixel-wise manner to exhibit all the tiny details, breaking the limitation of the vertex density of the base model. Accordingly, we are enabled to describe an arbitrary complex face with these representations.

As shown in Fig. 2, given a portrait image I , we firstly utilize a regression network as the face analyzer to predict the BFM coefficients and obtain the coarse aligned mesh M_0 and albedo A_0 using the corresponding basis from the 3DMM database. Combined I and M_0 , we are able to acquire the inpainted texture T in UV space by applying the differentiable rendering with a coarse-to-fine strategy. And we concatenate the position map P and T as the input of the following modules for hierarchical details learning. We adopt two **pix2pix** [26] networks to synthesize the deformation map and displacement map in sequence. Note that, considering the deformation map will change the facial ge-

ometry and lead to the misalignment between \mathbf{T} and the deformed mesh, we generate the realigned texture \mathbf{T}' as the input of second pix2pix network by projecting the three-channel deformation map to the 2D space and transform it to a reversal flow \mathbf{F} to re-align \mathbf{T} . Taking advantage of the abundant details from \mathbf{T} and the pixel-wise learning strategy, we manage to obtain the accurate detail maps which are further employed in a coarse-to-fine manner to generate the detailed face mesh \mathbf{M}_1 and \mathbf{M}_2 . Finally, combined with the refined albedo generated from the de-retouching module (Sec. 3.4), we accomplish detailed face reconstruction from the single image.

Overall, the framework is trained in a self-supervised manner guided with 3D detail priors learned from face scans (Sec. 3.3). To reduce the training complexity, we adopt the pre-trained encoder and MLP from the [14] as the face analyzer to predict the coefficients and generate the corresponding \mathbf{P} and \mathbf{T} for the following details learning. The two image translation networks are trained jointly and the related loss functions are composed of three components:

Reconstruction Loss. The reconstruction loss is calculated between the rendered face and the input face and consists of the photometric loss L_{photo} , perception-level loss L_{per} and landmark loss L_{lan} following [14]. Thanks to the delighted albedo and the illumination system of 3DMM, the photometric loss will enforce the deformation of the facial geometry to fit the various shadows and highlight areas of the input face. It is crucial that we apply the reconstruction loss on both images rendered from the \mathbf{M}_1 and \mathbf{M}_2 , which benefit the disentanglement of the MF and HF details.

Details Loss. We apply the total variation loss L_{tv} [28] to encourage the smoothness of the deformation map, and use the L1 regularization loss L_{reg} to limit the scale of the displacement map.

Contour-aware Loss. We propose a novel contour-aware loss L_{con} to fulfill accurate modeling of the face contour. The L_{con} works on \mathbf{M}_1 and aims to pull the vertices of edge to align the face contour. As shown in Fig. 3, we firstly project vertices of \mathbf{M}_1 into the image space. Then we predict the face mask \mathbf{M}_{face} using the pre-trained face matting network [33] and implement post process to obtain the left side and right side points for each row. Given a vertex p and the corresponding projected point p' on \mathbf{M}_{face} , we obtain the vector \mathbf{l}_p and \mathbf{r}_p (from p' to the edge points in the horizontal direction). Then L_{con} can be described as:

$$L_{con} = \frac{1}{N_p} \sum_{p \in M_1} (f(p) \mathbb{1}[y(p') > \delta]), \quad (1)$$

$$f(p) = |h\left(\frac{\mathbf{l}_p \cdot \mathbf{r}_p}{\max(\|\mathbf{l}_p\|, \|\mathbf{r}_p\|)} + \lambda\right) - \lambda|, \quad (2)$$

where h is the ReLU function, and λ denotes a soft margin relative to the face contour ($\lambda = 0.01$ as default), $\mathbb{1}[y(p') >$

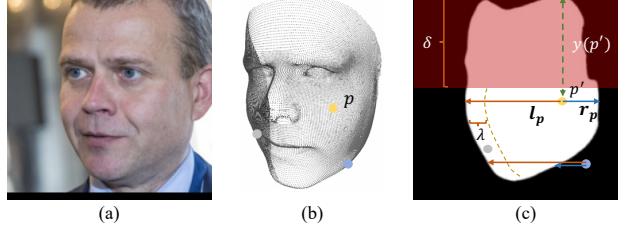


Figure 3. The details of the proposed contour loss. (a) input image, (b) the projected vertices, (c) the predicted face mask.

$\delta]$ indicates whether p' is on the lower part of the image ($\delta = 100$ as default). As we can see, L_{con} punishes the vertices outside the soft margin (such as the blue and gray points in Fig. 3) of the face and pull them to the face contour, while keeping the vertices inside the face intact. Combined with L_{tv} of the deformation map, L_{con} will avoid the unsmooth effect near the face contour. Note that we only focus on the lower part of the face contour to avoid the distraction of the hair. Compared to the common segmentation loss, L_{con} gives a more straightforward direction for optimizing the face contour and is easier for training. We conduct an ablation study to reveal the effectiveness of L_{con} in Sec. 4.4.

3.3. 3D Priors of Facial Details

Although facial details can be roughly learned from single image using the reconstruction loss (Sec. 3.2), it suffers from unreality and ambiguousness due to its ill-posed essence. Adding additional regularization may help to narrow the solution space, but also lead to severe degradation in detail accuracy and fidelity.

To address this problem, we exploit the 3D priors of facial details derived from face scans and corresponding multi-view images in our framework. Firstly, given an image and its corresponding raw scan, we transform the raw scan to align to the image in BFM space (the details can be found in the supplemental files). Then we can obtain the ground-truth deformation map and displacement map for each image by fitting the image and scan using the loss functions mentioned in Sec. 3.2 with additional supervision on vertices distance following [3]. Thanks to the powerful hierarchical representation, the details of scans can be accurately captured. See Fig. 4 for example.

We take advantage of the 3D priors of details on two aspects. On the one hand, we develop two discriminators and use the adversarial loss [27] $L_{adv,mid}$ and $L_{adv,high}$ to supervise the domain distribution of the deformation map and displacement map. On the other hand, we acquire the paired data as mentioned above from 3D scans to conduct supervised learning to guide the self-supervised learning in Sec. 3.2. Specifically, we supplement the L1 loss L_{mid} and L_{high} for the predicted deformation map and displacement map respectively. Note that a mask is used in training to remove the distraction of eyes and hair area from scans.

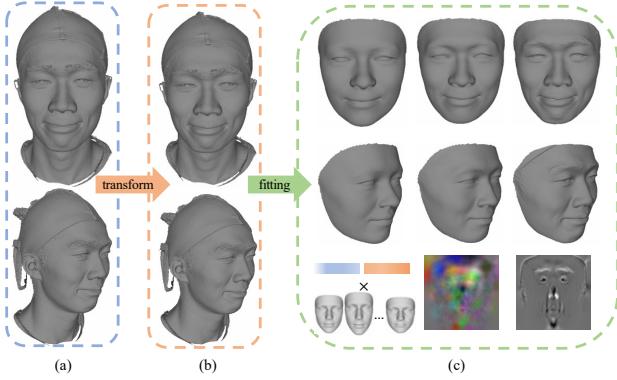


Figure 4. The capturing process of the 3D priors of facial details. (a) raw scans, (b) transformed scans that is aligned to the BFM space, (c) the captured hierarchical representation.

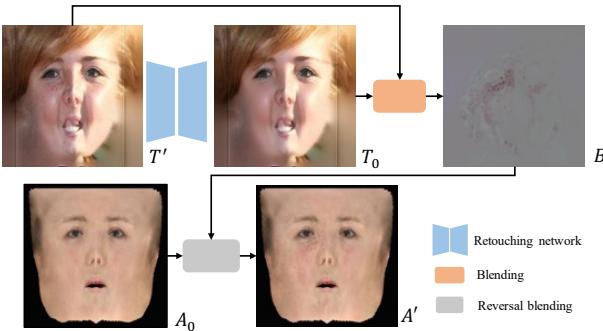


Figure 5. The details of the de-retouching module.

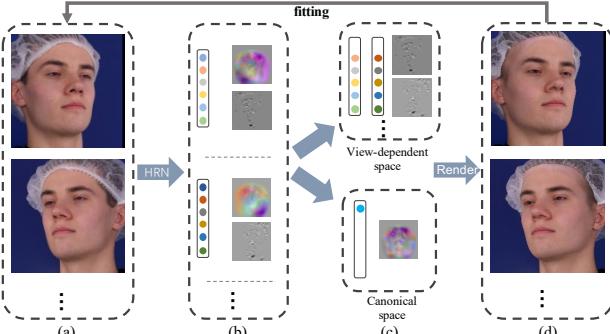


Figure 6. The pipeline of the proposed MV-HRN.

3.4. De-Retouching Module

A face image is the result of a combination of geometry, lighting, and face albedo. Prior works assume that the face albedo is smooth and model it with the low-frequency albedo from 3DMM. However, the actual skin texture is full of high-frequency details such as moles, scars, freckles, and other blemishes, which bring ambiguities to the geometry details learning especially in the single view FR task. Inspired by the [32], we propose a de-retouching module (DRM), which aims to generate the face albedo with high-frequency details and facilitate more precise decoupling of geometry and appearance.

We collect 10, 000 face images from FFHQ [29], and hire a team of professional image editors to process the im-

ages, with the goal of removing the skin blemishes and other texture details while maintaining the shape-related content such as wrinkles, bumps, etc. Then we transform the paired images into the texture maps in UV space by applying the process specified in Sec. 3.2 and train an image translation network G to fulfill skin retouching. Given the re-aligned texture T' , we firstly employ G to remove its texture details and get T_0 , as shown in Fig. 5. We aim to bake the texture details into the coarse albedo A_0 to obtain the improved albedo A' for rendering. We make an assumption that the shading from A_0 to T_0 should be consistent with the one from A' to T' , as:

$$T_0 = A_0 \odot S, \quad (3)$$

$$T' = A' \odot S, \quad (4)$$

where S denotes the shading map, \odot denotes element-wise matrix multiplication. Then we can solve the equations and obtain A' as:

$$A' = A_0 \odot B \approx A_0 \odot \frac{T' + \phi(T_0)}{T_0 + \phi(T_0)}, \quad (5)$$

$$\phi(T_0) = \frac{1}{\frac{T_0 \odot T_0 \odot T_0}{\varepsilon} + \varepsilon}, \quad (6)$$

where $\phi(T_0)$ avoids the value explosion near 0 and $\varepsilon = 1e-6$ as default. Compared to A_0 , the de-retouched albedo A' contains more high-frequency texture details, which alleviate the ambiguities between geometry and appearance, especially in single view FR task.

3.5. MV-HRN

Thanks to the hierarchical modeling and the 3D priors guidance, we can easily adapt the HRN to a multi-view fashion to fulfill precise modeling of the global facial geometry with only a few views by adding the geometry consistency between different views. Fig. 6 shows the pipeline of MV-HRN. We assume that the low-frequency identity part and the mid-frequency details are consistent between different views, while the lighting, expression, and HF details should be view-dependent to overcome the disturbance. Therefore, we develop a canonical space, which contains the shared identity coefficient and deformation map that are initialized by averaging all the single-view results, to represent the shared intrinsic face shape. Then other BFM coefficients and the displacement map of each view are utilized to dependently model the pose, lighting, expression and high-frequency details. Then we apply the loss functions mentioned in Sec. 3.2 and Sec. 3.3 to iteratively optimize all the coefficients and detail maps. Through the fitting process, the face shape is gradually restricted to a smaller and more accurate space under the supervision of different views. Extensive experiments show that MV-HRN achieves accurate

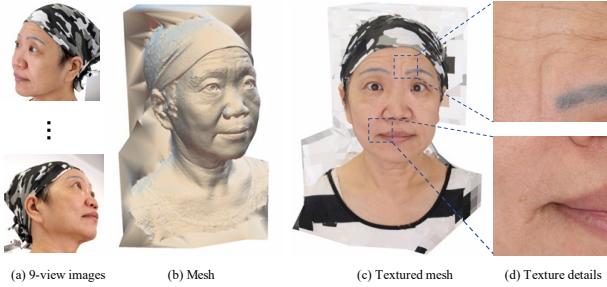


Figure 7. An example from the FaceHD-100 dataset.

reconstruction given only a few ($2 \sim 5$) views of images in a short time (less than one minute).

3.6. FaceHD-100 Dataset

To boost the research of face reconstruction from sparse-view images, we introduce a high-quality 3D face dataset FaceHD-100, which consists of 2,000 high-definition 3D mesh and corresponding multi-view images from 100 subjects. The data is captured by a multi-view 3D reconstruction system, which is composed of 9 DSLR cameras and 8 LED lights. The 9 cameras are evenly distributed in front of and to the side of the face, and each provides 8K images for geometry and texture reconstruction. The capturing subjects include 50 males and 50 females, and mostly are from Asia. The ages of these subjects are **normally distributed** from 16 to 70 years old. For each person, we follow [1] and ask them to perform 20 expressions including the neutral expression for capturing. Fig. 7 gives an example of FaceHD-100, which shows the high quality of the reconstructed geometry and texture.

4. Experiments

4.1. Implementation Details

Training Data. The training data of the proposed model is composed of two parts: **2D in-the-wild images and 3D face scans with corresponding multi-view images**. For the former, we collect in-the-wild face images from multiple sources following [14]. For the latter, the data is collected from FaceScape [48], ESRC [17] and FaceHD-100. To be specific, we split 359 samples of FaceScape into training (309 subjects) and testing sets (50 subjects), considering the balance of gender and age. The ESRC is also split in the same way as [4] and the whole FaceHD-100 dataset is used for training. In total, we **collected ~9K scans from nearly 500 subjects of different ethnicities**. The majority of subjects have 3D scans for at least 8 different expressions. Then we process all the scans and corresponding multi-view images in the way shown in Fig. 4 to generate the ground-truth deformation maps and displacement maps for each image. In the end, we collected $\sim 260K$ in-the-wild images for self-supervised training and $\sim 150K$ lab images with corre-

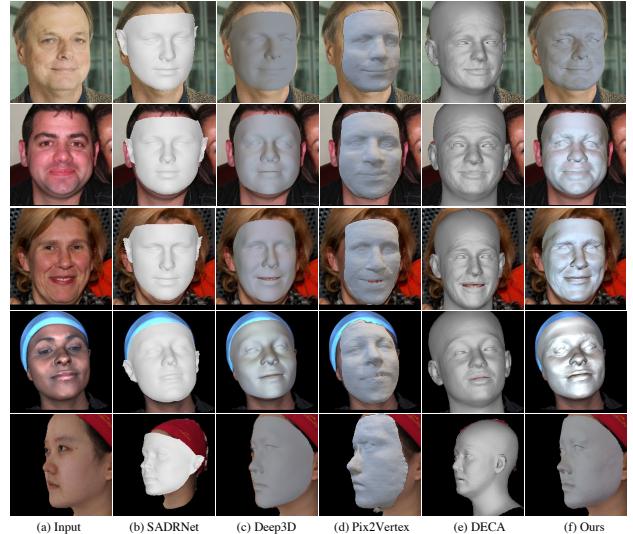


Figure 8. The single-view qualitative comparison on FFHQ (first three rows), REALY (fourth row), and FaceScape (last row).

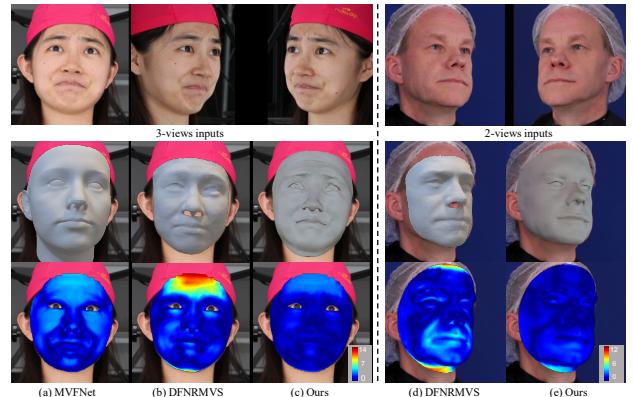


Figure 9. The multi-view qualitative comparison on FaceScape and ESRC datasets.

sponding ground-truth details map for supervised training. The input images are preprocessed following [14].

Training Strategy. Firstly, we employ the pretrained R-Net from [14] as our face analyzer to predict the 3DMM coefficients, position map and texture map as mentioned in Sec. 3.2 for the following training. We use the paired texture maps mentioned in Sec. 3.4 to train the de-retouching module. Finally, we fix the parameters of the face analyzer and de-retouching module and train the whole network with the input of face images, position maps and texture maps. We train our model using the Adam optimizer with a batch size of 4, an initial learning rate of $1e-4$, and 800K iterations. Note that the model is trained alternately with in-the-wild images and lab images in a self-supervised and supervised manner respectively. More details about the parameters and training setting are specified in supplementary materials.

4.2. Qualitative Comparison

We evaluate our model with four SOTA methods: SADRNet [39], Deep3D [14], Pix2Vertex [41], and DECA [18] for single-view 3D FR task. SADRNet tackles 3D dense face alignment and face reconstruction simultaneously with a self-aligned dual regression framework, and Deep3D leverages hybrid loss function to train CNN for 3DMM coefficients regression in a weakly-supervised manner. With the goal of adding more expressiveness and details, Pix2Vertex utilizes the Image-to-Image translation network to provide high-quality reconstructions under extreme expressions, while DECA presents an animatable displacement model to generate dynamic expression-depended face details. To make a fair comparison, we use their publicly released models and codes, and conduct experiments on FFHQ, REALY, and Facescape datasets.

The comparison results of the single-view reconstruction scenario are shown in Fig. 8. Since Deep3D only reconstructs faces using predicted 3DMM coefficients, the results are in low-dimensional space and lack high-frequency details. Although SADRNet tries to regress face shape deformation separately, the high-frequency details are still ignored in learning because of their minority. Pix2Vertex and DECA provide more fine details, such as blemishes and wrinkles. However, Pix2Vertex brings artifacts at the same time due to its unrestricted manner, and DECA cannot accurately recover face identities and expressions, resulting in similar wrinkles on the forehead among various faces. By contrast, our proposed method can produce high-fidelity 3D faces with expressive details, which are extremely consistent with the original input images.

In the multi-view scenario, we test the performance of DFNRMVS [4], MVFNet [45] and the proposed model given 3-view or 2-view images from FaceScape and ESRC datasets. As illustrated in Fig. 9, our model outperforms the other two methods in terms of fidelity, details and geometry accuracy, proving that our framework can be well generalized to both single-view and multi-view tasks.

4.3. Quantitative Comparison

Three public datasets are employed to quantitatively evaluate our method with several state-of-the-art approaches. Specifically, we choose FaceScape [48] dataset for both single-view and multi-view evaluation, and additionally use REALY [11] and ESRC [17] datasets for single-view and multi-view respectively. To evaluate the geometry accuracy of single-view face reconstruction, we use Chamfer Distance (CD) and Mean Normal Error (MNE) on the FaceScape dataset following FaceScape benchmark [48], while leveraging average Normalized Mean Square Error (NMSE) of different face regions on REALY dataset, which applies region-wise alignment and is more accurate for shape error computing.

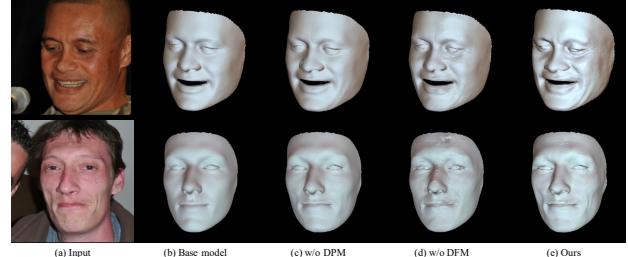


Figure 10. Ablation study toward hierarchical modeling on FFHQ.

Table 1 shows the quantitative comparison of single-view reconstruction. Our approach outperforms other methods on FaceScape-wild and REALY datasets, and achieves SOTA performance on the FaceScape-lab dataset. We find that our side-view metric is even better than the frontal-view on REALY dataset, we speculate that the slightly side-view images provide more information about mouth/node heights, which is beneficial to geometry prediction.

For multi-view reconstruction evaluation, as guided by NoW benchmark [40], we firstly choose 7 face landmarks for each predicted mesh and then apply rigid alignment to ground truth mesh, and report their scan-to-mesh distances. Due to that MVFNet public model cannot handle 2-views images, we only use it in FaceScape dataset testing. The results in Table 2 show that our approach performs better against MVFNet and DFNRMVS with the lowest reconstruction errors.

Table 1. Single-view quantitative comparison. REALY-F and REALY-S denote frontal-view and side-view reconstruction on REALY benchmark respectively.

Methods	FaceScape-wild		FaceScape-lab		REALY-F NMSE (mm)	REALY-S NMSE (mm)
	CD (mm)	MNE (rad)	CD (mm)	MNE (rad)		
Deep3D	3.8	0.092	5.28	0.118	1.657	1.691
MCGNet	3.22	0.077	4.00	0.093	1.774	1.787
PRNet	3.47	0.123	3.56	0.126	2.013	2.032
SADRNet	7.12	0.123	6.75	0.133	1.913	1.958
DECA	3.31	0.089	4.69	0.108	2.210	2.261
3DDFA	3.00	0.080	3.60	0.096	1.926	1.943
Ours	2.91	0.065	3.67	0.087	1.537	1.468

Table 2. Multi-view quantitative comparison. We only report MVFNet performance on FaceScape because its released model cannot process two-view inputs.

Methods	FaceScape (3 views)			ESRC (2 views)		
	Median (mm)	Mean (mm)	Std (mm)	Median (mm)	Mean (mm)	Std (mm)
MVFNet	1.76	2.12	1.66	N.A.	N.A.	N.A.
DFNRMVS	1.79	2.41	2.61	1.59	2.13	2.29
Ours	1.13	1.51	1.79	1.29	1.69	1.72

4.4. Ablation Study

In order to verify the rationality and effectiveness of our network design, we conduct extensive ablation exper-

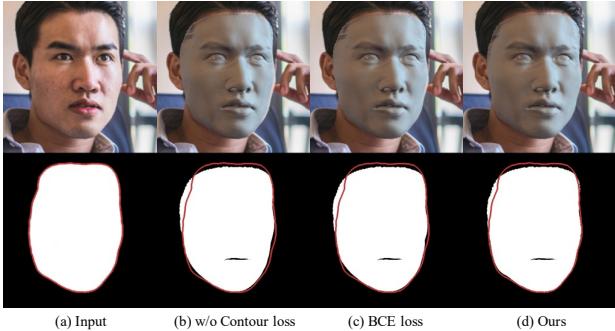


Figure 11. Ablation study toward contour loss on FFHQ.

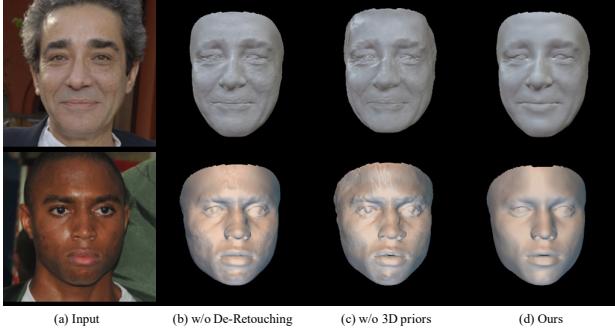


Figure 12. Ablation study toward de-retouching module and 3D detail priors on FFHQ.

Base model	HRM	L_{con}	detail priors	DRM	CD(mm)	MNE(rad)
✓					3.8	0.092
✓		✓			3.34	0.081
✓		✓	✓		3.18	0.079
✓		✓	✓	✓	2.9	0.067
✓		✓	✓	✓	2.91	0.065

Table 3. Quantitative ablation experiments on FaceScape-wild. HRM denotes the hierarchical representation modeling.

Methods	2 views	3 views	4 views	5 views	naive version (5 views)
Ours	1.17	1.13	1.11	1.10	1.23

Table 4. Quantitative ablation study toward sparse-view reconstruction on FaceScape. Only median distance(mm) is reported.

iments on FFHQ and FaceScape. Table 3 shows the quantitative results on FaceScape-wild benchmark. As revealed in the table, compared to the base 3DMM, the hierarchical modeling strategy brings a huge improvement ($\sim 0.5\text{mm}$). The contour loss produces 0.16mm improvement. 3D priors of details play a key role in our framework, achieving $\sim 0.3\text{mm}$ improvement. The quantitative contribution of the de-retouching module is minor, while the following qualitative results on FFHQ prove its effectiveness.

On hierarchical modeling. To demonstrate the necessity of the hierarchical modeling, we employ the deformation map (DFM) and displacement map (DPM) respectively (columns c, d in Fig. 10) to solely learn the overall facial details and compare the results. Without DPM, the DFM exhibit the capability of capturing high-frequency details

to a certain extent. However, the performance is limited by the mesh density and the trade-off between the MF details and HF details. In contrast, the DPM is more effective in learning some micro details, but it fails to handle some larger-scale deformation. Apparently, by introducing the hierarchical modeling strategy, the proposed method achieves more accurate and detailed reconstruction.

On contour-aware loss. The contour-aware loss L_{con} aims to enhance the reconstruction accuracy of the facial contours. As shown in Fig. 11, the network with L_{con} exhibit superior performance on learning the face contour compared with the one without L_{con} or with BCE loss.

On 3D priors of facial details. The introduced 3D priors provide the geometry distribution of the real facial details, which guide the model to achieve accurate reconstructions. As shown in Fig. 12, the network without 3D priors produces some unrealistic details. In contrast, the reconstruction results with 3D priors are smoother and more faithful.

On de-retouching module. The de-retouching module is proposed to achieve better decoupling of the facial appearance and geometry. As shown in Fig. 12, without DRM, the model is more susceptible to the distraction of various skin textures and yields some nonexistent details.

On sparse-view reconstruction. We test the performance of MV-HRN on FaceScape given different numbers of input views. As Shown in Table 4, MV-HRN achieves comparable results given only two views for input. With the increase of the number of views, the performance is gradually better, showing the ability of MV-HRN to aggregate multi-view information. Besides, we compare MV-HRN with its naive version (simply average the results of all views) and the results demonstrate the effectiveness of the network design.

4.5. Extention work and Limitation

Due to the limited paper space, more extension work (such as high-quality head reconstruction) and limitation of our method are provided in the supplementary materials.

5. Conclusion

In this paper, we propose a novel hierarchical representation network(HRN) for accurate and detailed face reconstruction from in-the-wild images. Specifically, we achieve facial geometry disentanglement and modeling by hierarchical representation learning. The 3D priors of details are further incorporated to improve the reconstruction results in accuracy and visual effects. Besides, we propose a de-retouching network, which alleviates the ambiguities between geometry and appearance. Moreover, we extend HRN to a multi-view fashion and introduce a high-quality 3D face dataset FaceHD-100 to boost the research of sparse-view FR. Extensive experiments reveal that our method achieves superior performance to the existing methods in terms of accuracy and visual effects.

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Supplementary Material for Paper: A Hierarchical Representation Network for Accurate and Detailed Face Reconstruction from In-The-Wild Images

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In this document, we present some additional statistics and more examples of the FaceHD-100 dataset in Sec. 1, ethics guidelines in Sec. 2, some implementation details in Sec. 3, head reconstruction as the extension work of our HRN (MV-HRN) in Sec. 4, more visualization results in Sec. 5, and discussions about the limitations of the proposed method and future work in Sec. 6.

1. The FaceHD-100 Dataset

This section provides more information about the FaceHD-100 dataset. Fig. 1 shows the age and gender distribution of the dataset, in which the ages of men and women are mainly concentrated between 17-35 years old, and the overall distribution is close to normal. In Fig. 2, we give an example of the 9-view face images from FaceHD-100, which shows the position distribution of the 9 cameras in our acquisition system. Fig. 3 presents some 9-view images and raw scans of different expressions from FaceHD-100. While capturing, each subject was asked to wear a hair covering to prevent hair from interfering.

We have signed an authorization agreement with each capturing subject, who grants us the exclusive rights to distribute, perform, and use the captured data within the scope of academic research (including for paper publication and representation) and legitimate business. And we will release the dataset for research purposes only.

2. Ethics Guidelines

In addition to FaceHD-100, other face datasets we use in the main paper and supplementary materials are licensed, granting us the right to use the data for research purposes, including publication of papers. Moreover, the face examples shown in the paper have also obtained the special authorization of the capturing subjects or followed the publishable list of the corresponding dataset.

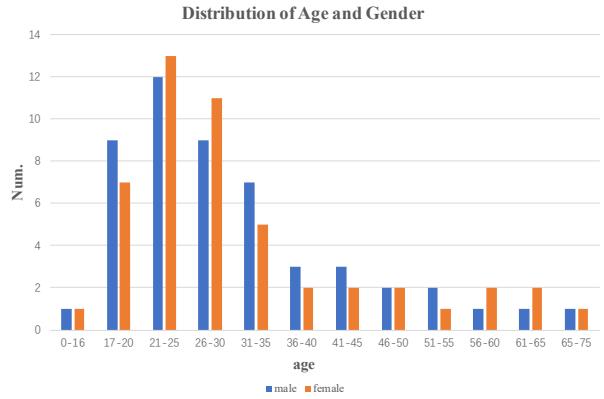


Figure 1. The age and gender distribution of the FaceHD-100 dataset.



Figure 2. An example of the 9-view face images from the FaceHD-100 dataset.



Figure 3. Some examples of different expressions from the FaceHD-100 dataset.

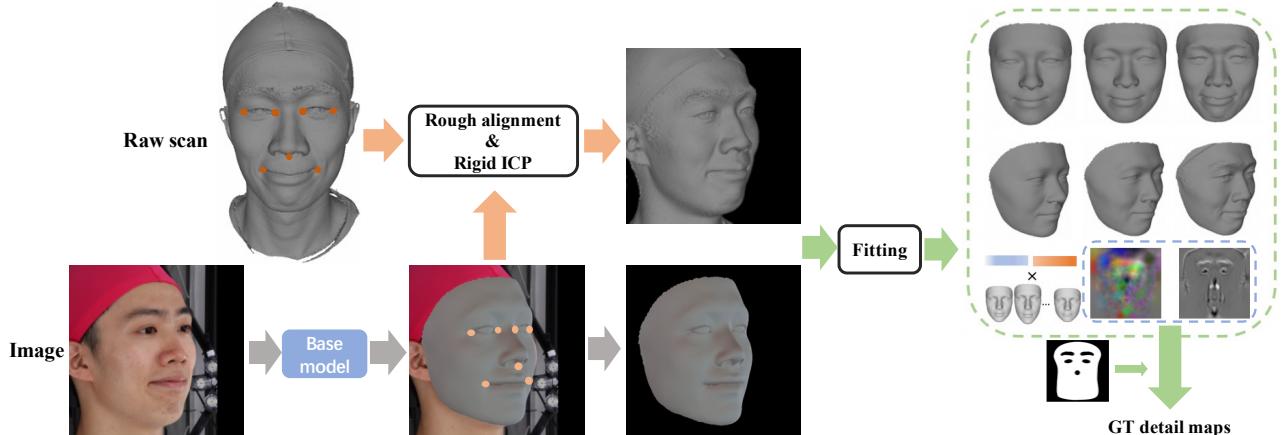


Figure 4. The pipeline of acquiring ground-truth deformation map and displacement map from a single image and the corresponding raw scan.

3. Implementation Details

3.1. Acquiring Ground-truth Detail Maps

As mentioned in Sec.3.3 in the main paper, to utilize the 3D data in our framework, we ought to transform the raw scan to align to the image in BFM space. Fig. 4 shows the pipeline of how we implement the transformation and acquire the ground-truth detail maps for training. Given a face image and its corresponding raw scan, we firstly employ the base model to predict a coarse mesh M_0 that is aligned to

the image in BFM space. Then we obtain 7 landmarks from the raw scan and M_0 respectively to achieve rough alignment [8], and the rigid ICP [9] algorithm is further used to improve the alignment between the raw scan and M_0 . Once we get the aligned scan, we are able to use the hierarchical representation to fit the scan as mentioned in Sec.3.3 in the main paper, and finally acquire the ground-truth deformation and displacement map for the input image (a mask is used in training to remove the noises of eyes, nose and hair area from raw scans). Note that since the base model is pre-trained in our network, we only optimize the detail maps

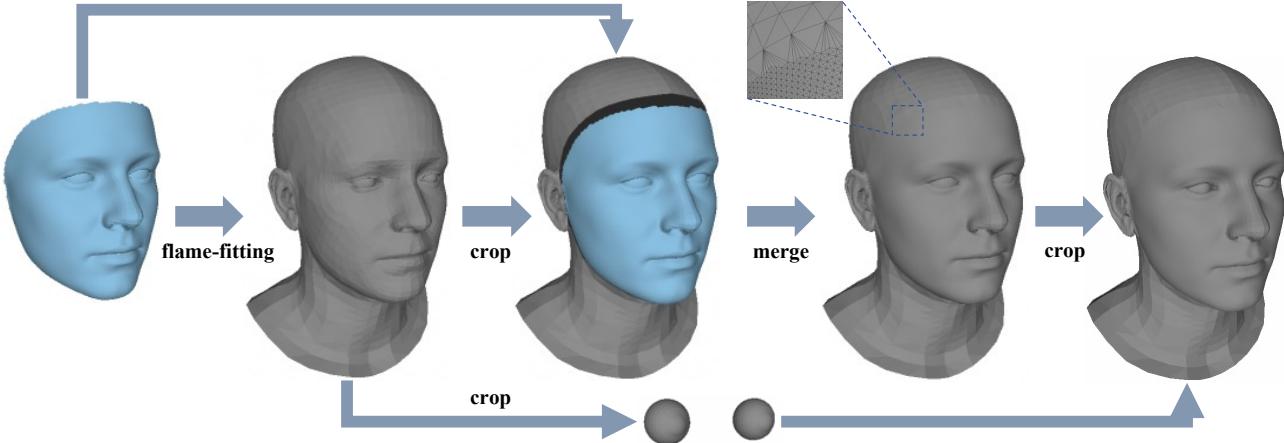


Figure 5. The pipeline of generating a new head model from the BFM model and FLAME model.

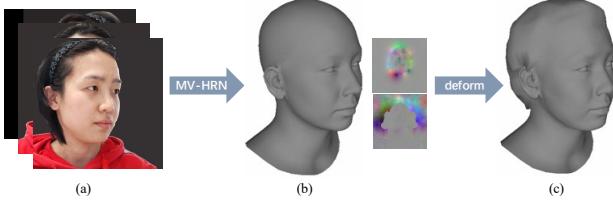


Figure 6. Simplified head reconstruction process. (a) Input multi-view images. (b) Predicted coarse head mesh, face, and hair deformation map. (c) deformed mesh.

and freeze the blendshape coefficients in the fitting process.

3.2. Loss Functions

As described in Sec.4.1 in the main paper, the training data is composed of two types of images: in-the-wild images and in-the-lab images. The former is used for training in a self-supervised manner, while the latter is combined with ground-truth detail maps generated following Sec. 3.1 and used for training in a supervised manner.

We use R_1 and R_2 to indicate the face rendered from M_1 and M_2 in Fig. 2 (main paper) respectively. Overall, the loss functions that we utilize for training consist of :

- (i) two photometric losses [1] L_{photo_1} (between I and R_1) and L_{photo_2} (between I and R_2);
- (ii) two perception-level losses [1] L_{per_1} (between I and R_1) and L_{per_2} (between I and R_2);
- (iii) a landmark loss [1] L_{lan} (between I and R_2);
- (iv) a total variation loss [4] L_{tv} for the deformation map;
- (v) an L1 regularization loss L_{reg} for the displacement map;
- (vi) a contour-aware loss L_{con} between face mask and M_1 ;
- (vii) two adversarial losses [3] L_{adv_mid} and L_{adv_high} for the deformation map and displacement map respectively;
- (viii) an L1 loss L_{mid} for the deformation map and an L1 loss L_{high} for the displacement map in supervised training.

In summary, the joint loss for self-supervised and supervised training can be written as:

$$\begin{aligned} \mathcal{L}_{self} = & \lambda_1(L_{photo_1} + L_{photo_2}) + \lambda_2(L_{per_1} + L_{per_2}) \\ & + \lambda_3 L_{lan} + \lambda_4 L_{tv} + \lambda_5 L_{reg} + \lambda_6 L_{con} \\ & + \lambda_7(L_{adv_mid} + L_{adv_high}), \end{aligned} \quad (1)$$

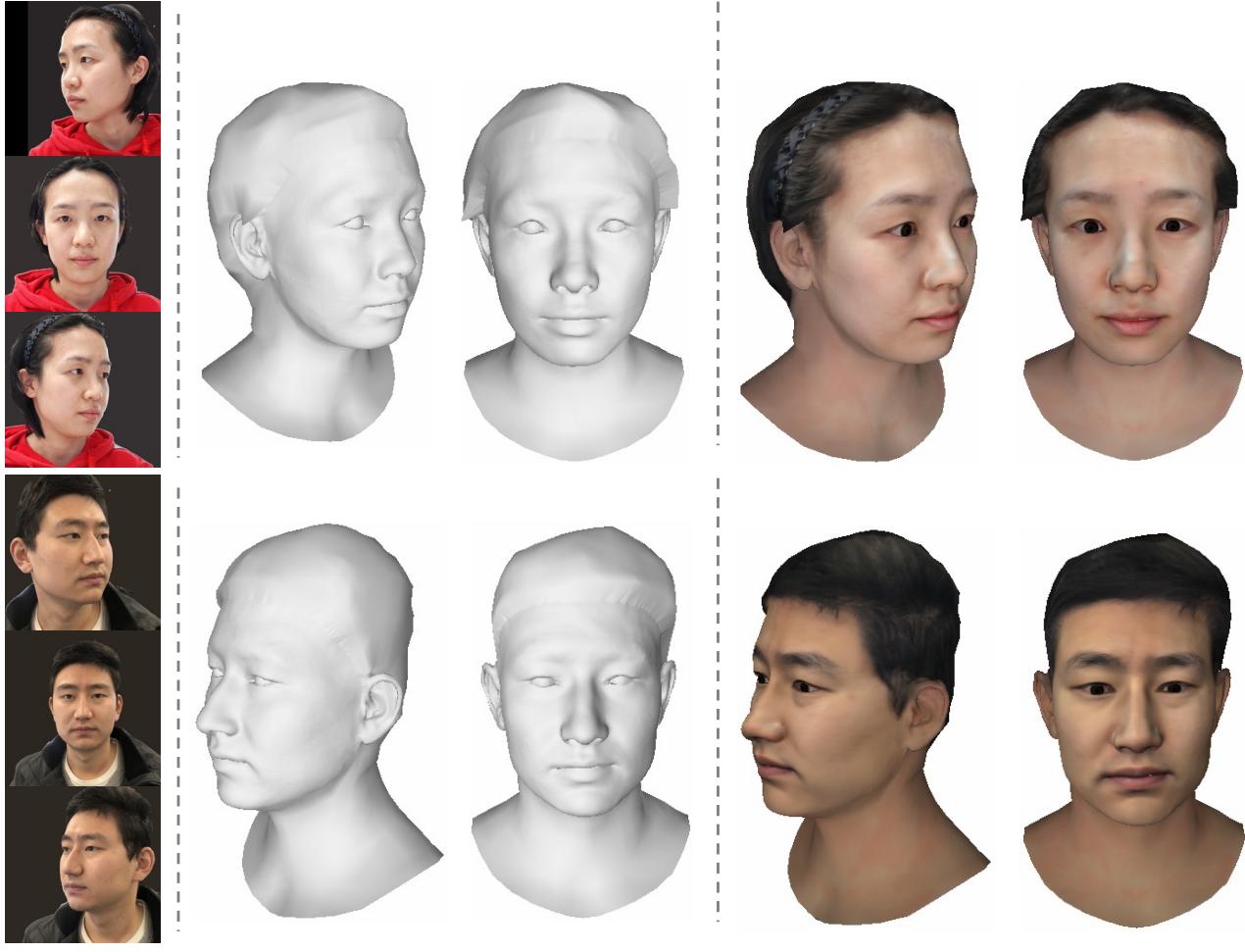
$$\mathcal{L}_{super} = \mathcal{L}_{self} + \lambda_8(L_{mid} + L_{high}), \quad (2)$$

where $\lambda_1 = 1.9$, $\lambda_2 = 0.2$, $\lambda_3 = 1.6e-4$, $\lambda_4 = 5e3$, $\lambda_5 = 10$, $\lambda_6 = 20$, $\lambda_7 = 0.2$ and $\lambda_8 = 1$ as default. We alternately train the network with \mathcal{L}_{self} for one iteration and with \mathcal{L}_{super} for one iteration.

4. Head Reconstruction

Due to the lack of completeness, the application scenarios of face reconstruction are often limited. Therefore, we extend our method and make a small modification to MV-HRN to achieve high-quality head reconstruction. Firstly, we combine BFM with FLAME and generate a new head 3DMM model. Fig. 5 shows the pipeline. Given a face model from BFM database, we firstly use a template FLAME model and apply the flame-fitting [6] algorithm to fit the face model. Then through a series of cropping and merging operations, we can get the complete head model that combines BFM and FLAME. By applying the process above to the mean model, 80 identity blendshapes and 64 expression blendshapes of BFM, we can obtain a new head 3DMM, which shares the same group of coefficients with BFM. We continue to use the albedo basis of BFM for the face area of the new head models. Since we will only calculate the photometric loss for the face area, the albedo of the rest area of the head model is set to a fixed value. In addition, we unwrap the new head model and recalculate a new set of UV coordinates.

To adapt the new head model, we modify the MV-HRN by splitting the deformation map into the face deformation



(a) 3-view images

(b) Predicted mesh

(c) Textured mesh

Figure 7. Some head reconstruction results of our method on selfie data.

map and hair deformation map, where the former is used to deform the face region and the latter is used to deform the hair region. Besides, we replaced the face mask in contour-aware loss with the head mask, which is predicted by a pre-trained head segmentation network [7]. By using the face and hair deformation map to fit the head mesh to the head masks, we can get a head model that is well aligned to the input multi-view head images. Note that since there are no 3D priors to guide the deformation of the hair region, we apply a larger weight of L_{tv} for the hair deformation map to ensure the smoothness of the hair region. Fig. 6 shows a simplified process of reconstructing the head mesh using MV-HRN. For the texture, we firstly acquire the coarse texture maps from each view by employing the differentiable rendering [5] mentioned in Sec. 3.2 (main paper). Then we blend the multi-view textures and a template head texture following [2] to obtain the complete head texture map. Combining the predicted head mesh and the head texture map, we achieve high-quality head reconstruction from sparse-view images. Fig. 7 shows some head reconstruction

results of our method on selfie data.

Due to the deficiency of prior information on hair regions and the limitation of mesh density, our head reconstruction is currently only suitable for handling portraits with simple hairstyles.

5. More Visualization Results

We provide more qualitative comparison of single-view face reconstruction results in Fig. 8, Fig. 9, and Fig. 10. Our approach consistently outperforms other methods on FFHQ, REALY and Facescape datasets with high-fidelity and fine details.

6. Limitations and Future Work

Limitations. We summarize two limitations of our method. On one hand, the generated facial details of our method are static and cannot vary with expression. One possible way is to collect multiple expressions of the same person, and then use HRN to obtain mid- and high-frequency details from



Figure 8. More visual comparisons on FFHQ dataset.

each expression and build a set of mid- and high-frequency detail blendshapes. Finally, we are enabled to use blendshape coefficients to generate dynamic facial details.

On the other hand, considering the pixel-wise learning strategy and the powerful representation ability, our proposed method cannot handle severe occlusions well. Fig. 11 presents some visual results of the proposed HRN on occluded face images from FFHQ. Our method exhibits robustness to some images with slightly occluded faces (first

two rows) but produces inaccurate results for heavily occluded faces (last three rows).

Future Work. Beyond addressing the limitations discussed above, we will further extend our method to achieve accurate, high-fidelity and animatable head avatar generation from in-the-wild images for future work, conquering some challenging problems (such as modeling complex hairstyles).

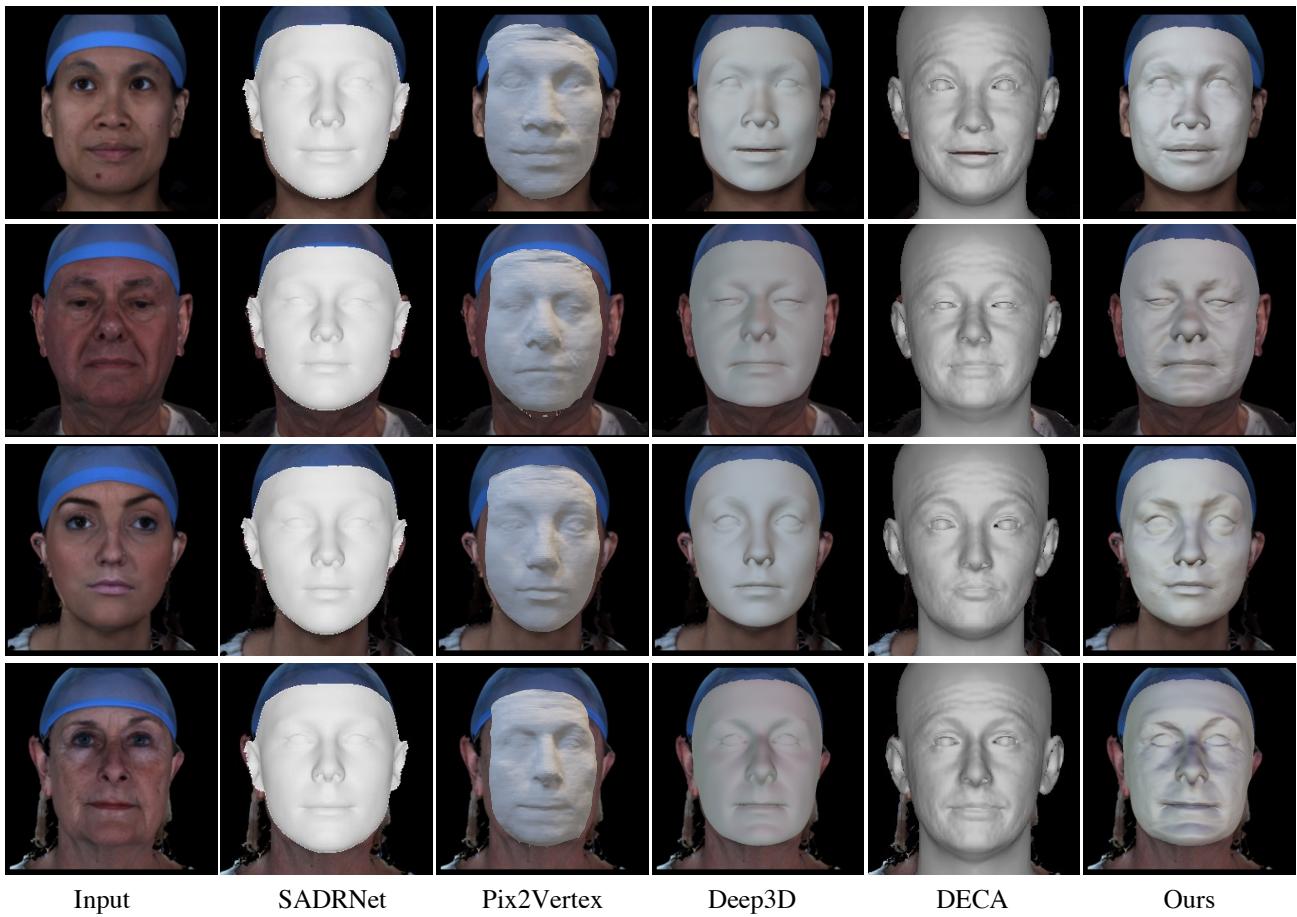


Figure 9. More visual comparisons on REALY dataset.



Figure 10. More visual comparisons on FaceScape dataset.

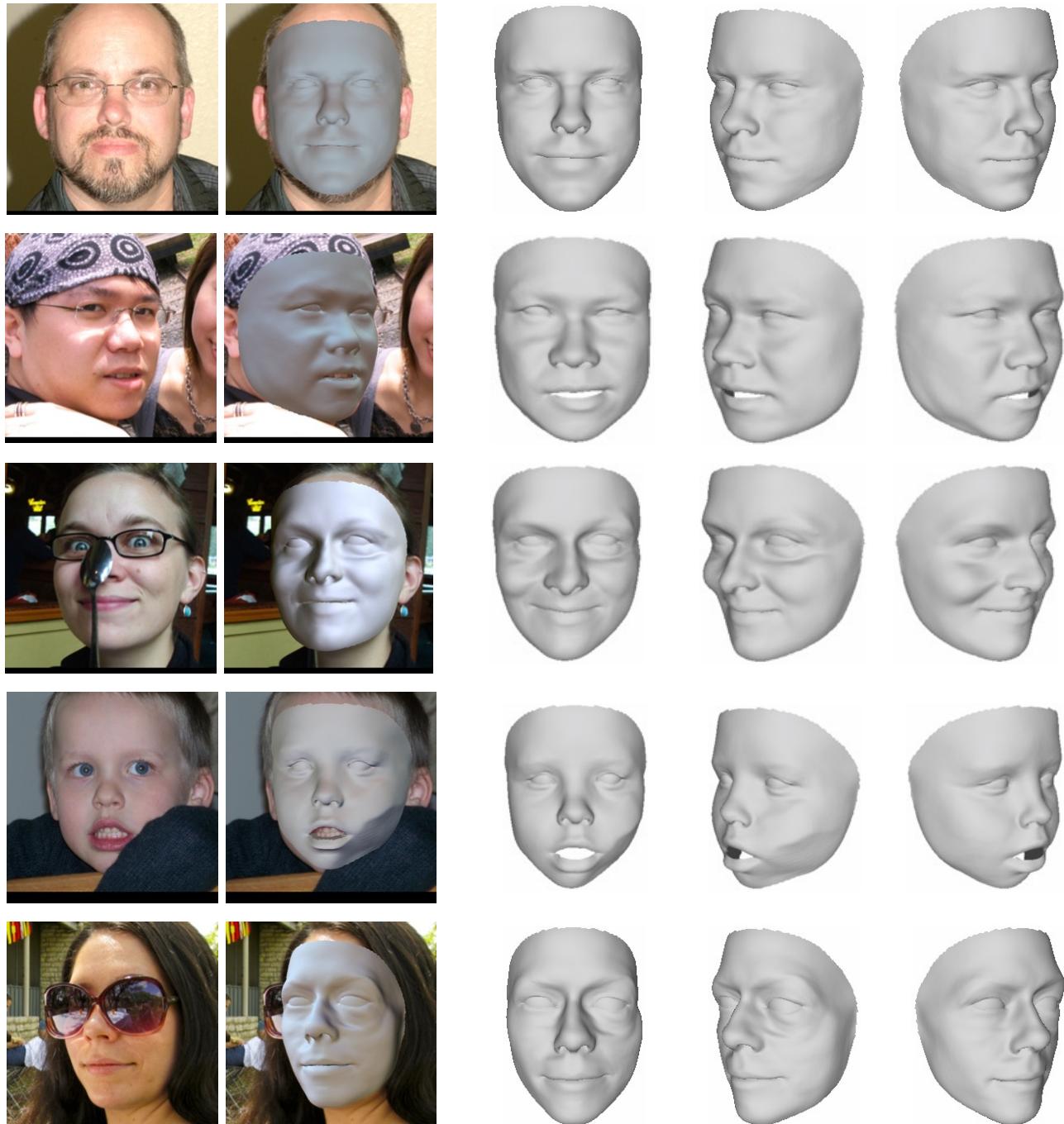


Figure 11. Visual results of our method on some occluded face images from FFHQ.

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