The Global Existance of Solutions to the Microscopic Model.

Symbols and Definitions

- 1. G(V, E) is a graph with vertex set V and edge set E.
- 2. The adjacency matrix of E is denoted by $A=(a_{ij})_{n\times n}$, where n:=|V|.
- 3. The neighbour of node/vertex $i \in V$ is defined as $N(i) := \{j : j \sim i\}$.
- 4. The conductivity and length of edge $i \to j$ are denoted by C_{ij} and L_{ij} correspondingly, where $C_{ij} \geq 0$ and $L_{ij} > 0$.
- 5. The pressure of the vertex $i \in V$ is denoted by P_i . Thus we can define the pressure drop $(\Delta P)_{ij} := P_i P_i$ by definition.
- 6. The flow rate of an oriented flux in i o j is denoted by $Q_{ij}:=rac{C_{ij}(\Delta P)_{ij}}{L_{ij}}.$
- 7. The strength of i is defined as the negative summation of Q_{ij} for all $j \in N(i)$.
- 8. $H^k(\Omega) := W^{k,2}(\Omega)$ is a kind of Соболев space, that is, the subset of functions f in $L^2(\Omega)$ such that f and its weak derivatives up to order k have a finite L^2 norm.
- 9. $H_0^1(\Omega)$ is a subset of functions g in $H^1(\Omega)$ such that g has a compact support on Ω .

Formulae

1. Kirchhoff's first law is that the algebraic sum of currents in a network of conductors meeting at a point (or node) is zero. Thus

$$S_i = \sum_{j \in N(i)} C_{ij} rac{(\Delta P)_{ji}}{L_{ij}} = -\sum_{j \in N(i)} C_{ij} rac{(\Delta P)_{ij}}{L_{ij}}$$

2. The global mass conservation reveals that

$$\sum_{i \in V} S_i = 0$$

3. The Joule's law illustrates that the kinetic energy is in proportion to both pressure drop and flow rate. Thus

$$\mathcal{E}_1[C_{ij}] := (\Delta P_{ij})Q_{ij} = rac{Q_{ij}^2}{C_{ij}}L_{ij}$$

4. The metabolic consumption (in energy form) is in proportion to its length and a power of its conductivity. Thus

$$\mathcal{E}_2[C_{ij}] := rac{
u}{\gamma} C_{ij}^{\gamma} L_{ij}$$

5. The entire energy consumption functional is given by

$$ilde{\mathcal{E}}[C] := \sum_{(i,j) \in E} \left(rac{Q_{ij}^2}{C_{ij}} + rac{
u}{\gamma} C_{ij}^{\gamma}
ight) L_{ij}$$

Analysis of Discrete Model

The gradient of energy consumption functional w.r.t. C_{ij} .

We notice that Q = Q[C], while μ and L_{ij} is independent from C_{ij} . The partial derivetive of $\tilde{\mathcal{E}}[C]$

$$egin{aligned} rac{\partial}{\partial C_{ij}} ilde{\mathcal{E}}[C] := & rac{\partial}{\partial C_{ij}} \sum_{(i,j) \in E} \left(rac{Q_{ij}^2}{C_{ij}} + rac{
u}{\gamma} C_{ij}^{\gamma}
ight) L_{ij} \ := &
u C_{ij}^{\gamma-1} L_{ij} - rac{Q_{ij}^2}{C_{ij}^2} L_{ij} + 2 \sum_{(i,j) \in E} rac{Q_{ij}}{C_{ij}} rac{\partial Q_{ij}}{\partial C_{ij}} L_{ij} \end{aligned}$$

We notice that S_i are fixed constants. Hence

$$\begin{split} 2\sum_{(i,j)\in E} \frac{Q_{ij}}{C_{ij}} \frac{\partial Q_{ij}}{\partial C_{kl}} L_{ij} &= \sum_{i=1}^{n} \sum_{j=1}^{n} a_{ij} \left(\frac{P_{j} - P_{i}}{L_{ij}} \frac{\partial Q_{ij}}{\partial C_{kl}}\right) L_{ij} \\ &= \sum_{j=1}^{n} P_{j} \sum_{i=1}^{n} a_{ij} \frac{\partial Q_{ij}}{\partial C_{kl}} - \sum_{i=1}^{n} P_{i} \sum_{j=1}^{n} a_{ij} \frac{\partial Q_{ij}}{\partial C_{kl}} \\ &= -2 \sum_{i=1}^{n} P_{i} \sum_{j=1}^{n} a_{ij} \frac{\partial Q_{ij}}{\partial C_{kl}} \\ &= -2 \sum_{i=1}^{n} P_{i} \frac{\partial}{\partial C_{kl}} \sum_{j \in N(i)} Q_{ij} \\ &= -2 \sum_{i=1}^{n} P_{i} \frac{\partial}{\partial C_{kl}} S_{i} \\ &= 0 \end{split}$$

Thus we deduce the gradient

$$egin{aligned} egin{aligned} \nabla ilde{\mathcal{E}}[C] &= \left(\cdots,
u C_{ij}^{\gamma-1} L_{ij} - rac{Q_{ij}^2}{C_{ij}^2} L_{ij}, \cdots
ight) \end{aligned}$$

The gradient descent flow

In general case, the gradient flow is introduced to find the decreasing streamline. Let $f: \mathbb{R}^n \to \mathbb{R}$ be a differentiable function with a given initial point $(x_0, f(x_0))$. There exists a streamline $\eta(x, t)$ such that $\eta(x, t) = f \circ x(t)$ descends when t is increasing.

The general formulation of a gradient flow of the functional $ilde{\mathcal{E}} \circ C(t)$ is of the form

$$\frac{\mathrm{d}C}{\mathrm{d}t} = -\mathcal{H}[C] \cdot \nabla \tilde{\mathcal{E}}[C]$$

We denote the space of tanent and cotangent vectors at $C \in \mathcal{C}$ by $\mathcal{T}_C \mathcal{C}$ and $\mathcal{T}_C^* \mathcal{C}$ respectively. Therefore $\mathcal{H}[C]$ can be regarded as a duality map

$$\mathcal{H}[C]:\mathcal{T}_{C}^{*}\mathcal{C}
ightarrow\mathcal{T}_{C}\mathcal{C}$$

For any positive difinite duality map $\mathcal{H}[C]$, we have

$$rac{\mathrm{d}\mathcal{E}[ilde{C}]}{\mathrm{d}t} =
abla ilde{\mathcal{E}}[C] \cdot rac{\mathrm{d}C}{\mathrm{d}t} = \left\langle
abla ilde{\mathcal{E}}[C],
abla ilde{\mathcal{E}}[C]
ight
angle_{\mathcal{H}[C]} < 0$$

which implies the dissipation of the energy along the solutions to gradient of energy consumption functional coupled with the Kirchhoff law.

The gradient flow of energy function coupled with the Kirchhoff law with respect to the unweighted Euclidean distance is given by the identical map \mathcal{H} . Thus

$$\frac{\mathrm{d}C}{\mathrm{d}t} = -\nabla \mathcal{E}[C]$$

Based on this general formulation, we consider the gradient flow with respect to a weighted Euclidean distance and introduce a duality map resulting in the ODE system, given by

$$\mathcal{H}[C] = \mathcal{H}_1[C] \otimes \cdots \otimes \mathcal{H}_{|E|}[C]$$

Here

$$\mathcal{H}_{ij}[C]: dC_{ij}|_C \mapsto C_{ij}^{lpha} \cdot \partial_{C_{ij}}|_C$$

Thus

$$\frac{\mathrm{d}C_{ij}}{\mathrm{d}t} = \left(\frac{Q_{ij}}{C_{ij}^2}L_{ij} - \nu C_{ij}^{\gamma}L_{ij}\right)C_{ij}^{\alpha-1}L_{ij}$$

The non-singularity of $ilde{C}$

The global existance of the solutions hinges on the the non-singularity of the Kirchhoff matrix \tilde{C}' . Consider the matrix \tilde{C} such that $\tilde{C} \cdot \mathbf{P} = \mathbf{S}$, where

$$ilde{C} \cdot \mathbf{P} = \mathbf{S} \Leftrightarrow egin{pmatrix} \sum_{j
eq 1} rac{C_{1j}}{L_{1j}} & -rac{C_{12}}{L_{12}} & \cdots & -rac{C_{1n}}{L_{1n}} \\ -rac{C_{21}}{L_{21}} & \sum_{j
eq 2} rac{C_{2j}}{L_{2j}} & \cdots & -rac{C_{2n}}{L_{2n}} \\ dots & \ddots & \ddots & dots \\ -rac{C_{n1}}{L_{n1}} & \cdots & -rac{C_{n\,n-1}}{L_{n\,n-1}} & \sum_{j
eq n} rac{C_{nj}}{L_{nj}} \end{pmatrix} egin{pmatrix} P_1 \\ P_2 \\ dots \\ P_n \end{pmatrix} = egin{pmatrix} S_1 \\ S_2 \\ dots \\ S_n \end{pmatrix}$$

Given that the all-one vector space is a trivial kernel of \tilde{C} , we shall consider the array-deleted matrix C', i.e.

$$ilde{C}' := egin{pmatrix} \sum_{j
eq 2} rac{C_{2j}}{L_{2j}} & -rac{C_{23}}{L_{23}} & \cdots & -rac{C_{2n}}{L_{2n}} \ -rac{C_{32}}{L_{32}} & \sum_{j
eq 3} rac{C_{3j}}{L_{3j}} & \cdots & -rac{C_{3n}}{L_{3n}} \ dots & \ddots & \ddots & dots \ -rac{C_{n2}}{L_{n2}} & \cdots & -rac{C_{n\,n-1}}{L_{n\,n-1}} & \sum_{j
eq n} rac{C_{nj}}{L_{nj}} \end{pmatrix}$$

which seems promising to be non-singular.

Theorem. The matrix A is non-singulat if A is weakly diagonally dominant and irreducable.

A is reducable iff the graph with respect to A is connected. An equivalent statement states that there exists a permutation matrix P such that

$$P^{-1}AP = P^TAP = \left(egin{array}{cc} A_1 & A_2 \ O & A_3 \end{array}
ight)$$

• A weakly diagonally dominant iff there for all diagonal element a_{ii} the inequality $|a_{ii}| \geq \sum_{j \neq i} |a_{ij}|$ holds, among which at least one of the equalities do not hold.

Proof. For contradiction, suppose that $\det A=0$, then $\dim \ker A\geq 1$, i.e. there exists a non zero vector $v=(v_1,\ldots,v_n)$ such that Av=0. We define Y by

$$Y:\{k:\inf_i|v_i|<|v_k|=\|v\|_\infty\}$$

1. If Y is empty, then $|v_i|-|v_j|\equiv 0$.Thus for any k

$$|a_{kk}||v_k|=|\sum_{l
eq k}a_{kl}v_l|\leq \sum_{l
eq k}|a_{kl}||v_l|$$

Thus $|a_{kk}| \leq \sum_{l \neq k} |a_{kl}|$, which contradicts the weakly diagonally dominance of A.

2. When \boldsymbol{Y} is non-empty. Notice that

$$|a_{kk}| \leq \sum_{j \neq k} |a_{kl}| \frac{|v_l|}{|v_k|}$$

and

$$|a_{kk}| \geq \sum_{j \neq k} |a_{kl}|$$

Thus for all $i \in Y$ and $j \notin Y$, we have $a_{ij} = 0$, which contradicts the reducability of A.

The proof is completed and thence we shall shift to the proof of connectivity of C and the non-vanishment of all $C_{ij} \in C$. The proof of the global existance of solutions to the formulae

$$rac{\mathrm{d}C_{ij}}{\mathrm{d}t} = \left(rac{Q_{ij}}{C_{ij}^2}L_{ij} -
u C_{ij}^{\gamma}L_{ij}
ight)C_{ij}^{lpha-1}L_{ij}$$

is presented below.

The global existance of $C_{ij}(t)$

We shall proof the global existance of the ODE system

$$rac{\mathrm{d}C_{ij}}{\mathrm{d}t} = \left(rac{Q_{ij}}{C_{ij}^2}L_{ij} -
u C_{ij}^\gamma L_{ij}
ight)C_{ij}^{lpha-1}L_{ij}$$

coupled with the Kirchhoff law. Firstly we notice that the graph generated by all non-zero initial datum of $C_{ij}(t_0)$ is connected. WLOG assume $t_0=0$, then we shall prove that $0 < C_{ij}(t) < F_{ij}(t)$ on \mathbb{R}_+ , where $F_{ij}(t)$ is a continuous dominance function defined on $(0,\infty)$. Here $\alpha \in \mathbb{R}$, $\gamma > 0$ and $\gamma + \alpha - 1 > 0$.

If $\alpha + \gamma \geq 2$, then

$$\frac{\mathrm{d}C_{ij}}{\mathrm{d}t} \ge -\nu L_{ij} C_{ij}^{\gamma+\alpha-1}$$

Since the exponent $\gamma + \alpha - 1 \ge 1$ and $C_{ij}(0) > 0$, the solution of $C_{ij}(t)$ remains positive for all t > 0. Moreover, $C_{ij}(t)$ remains bounded since the dissipation of the energy along the solutions.

If $\alpha + \gamma \in (1, 2)$, then we can divide V in to V_1 and V_2 such that the sourses and sinks induce a net flux between them. We shall prove that the connections between V_1 and V_2 maintains along the corresponding solutions.

Let $ilde{E}$ be the set of edges connecting V_1 and V_2 . By definition of V_1 and V_2 , we have

$$\Delta S := \sum_{i \in V_1} S_i = -\sum_{j \in V_2} S_j
eq 0$$

Assume that $\sum_{(i,j)\in \tilde{E}} C_{ij}(t_0) > 0$. We shall prove that

$$\sum_{(i,j)\in ilde{E}} C_{ij}(t)>0, \quad orall t>t_0$$

In light of the local existance of the solutions of C, we suppose that there exists $T>t_0$ such that

$$\lim_{t o T^-}\sum_{(i,j)\in ilde E}C_{ij}(t)=0$$

for contradiction. Since lpha-2<0 and $\gamma+lpha-1>0$, for all $t\in(t_0,T)$ we have

$$\begin{split} \frac{\mathrm{d}}{\mathrm{d}t} \sum_{(i,j)\in \tilde{E}} C_{ij}(t) &= \sum_{(i,j)\in \tilde{E}} (Q_{ij}^2 C_{ij}^{\alpha-2} - \nu C_{ij}^{\gamma+\alpha-1}) L_{ij} \\ &= \sum_{(i,j)\in \tilde{E}} Q_{ij}^2 C_{ij}^{\alpha-2} L_{ij} - \sum_{(i,j)\in \tilde{E}} \nu C_{ij}^{\gamma+\alpha-1} L_{ij} \\ &\geq \left(\sum_{(i,j)\in \tilde{E}} C_{ij}\right)^{\alpha-2} \sum_{(i,j)\in \tilde{E}} Q_{ij}^2 L_{ij} - \left(\sum_{(i,j)\in \tilde{E}} C_{ij}\right)^{\gamma+\alpha-1} \sum_{(i,j)\in \tilde{E}} \nu L_{ij} \end{split}$$

Since

$$egin{aligned} \sum_{(i,j) \in ilde{E}} Q_{ij}^2 L_{ij} &\geq \sum_{(i,j) \in ilde{E}} Q_{ij}^2 \inf_{(i,j) \in ilde{E}} L_{ij} \ &\geq rac{\left|\Delta S
ight|^2}{\left| ilde{E}
ight|} \inf_{(i,j) \in ilde{E}} L_{ij} \end{aligned}$$

Denote $\sum_{(i,j)\in \tilde{E}} C_{ij}(t)$ by u(t). We have

$$egin{aligned} rac{\mathrm{d}}{\mathrm{d}t} u(t) \geq & u^{lpha-2}(t) \cdot rac{\left|\Delta S
ight|^2}{\left| ilde{E}
ight|} \inf_{(i,j) \in ilde{E}} L_{ij} - u^{\gamma+lpha-1}(t) \sum_{(i,j) \in ilde{E}}
u L_{ij} \ rac{\mathrm{def}}{=} u^{lpha-2}(t) A + u^{lpha+\gamma-1}(t) B \end{aligned}$$

Here A and B are positive constants.

Since the derivation of u(t) remains positive when t is large enough, the minimum of u is $\min(\{u(t_0)\} \cup \{u(t): u'(t)=0\}) = \min\{u(t_0), \sqrt[\gamma+1]{A/B}\} > 0$, which contradicts the assumption that $\lim_{t\to T^-} \sum_{(i,j)\in \tilde{E}} C_{ij}(t) = 0$.

If V can be partitioned into two balanced subgraphs V_1 and V_j , then we can continue to deduct separately for each of the subgraphs (until the eventual step).

Via the graph partirioning method above, we deduce the global existence of the solutions.

Analysis of the Macroscopic Model

The energy consumption functional on \mathbb{R}^d

For all $i \in V$, denote the left and right neighbours of vertex i on the k-th spatial dimension (if exist) by $(i-1)_k$ and $(i-1)_k$ respectively. Thus the Kirchhoff law is then written as

$$-\sum_{k=1}^d C_{(i-1)_k,i} rac{(\Delta P)_{(i-1)_k,i}}{L_{(i-1)_k,i}} - C_{i,(i-1)_k} rac{(\Delta P)_{i,(i-1)_k}}{L_{i,(i-1)_k}} = S_i$$

When the points in the set V are arranged as a set of parallelotopes or rectangular tessellation, that is, with the equal length h_k to the left or right neighbour with respect to the k-th spatial dimension. The Kirchhoff law is written as

$$-\sum_{k=1}^d C_{(i-1)_k,i} rac{(\Delta P)_{(i-1)_k,i}}{h_k} - C_{i,(i-1)_k} rac{(\Delta P)_{i,(i-1)_k}}{h_k} = S_i$$

In the rescaling of the energy functional, some (abstract) weights are applied to scale linearly with the grid spacing, i.e.

$$ilde{\mathcal{E}}[C] = \sum_{(i,j) \in E} \left(rac{Q_{ij}^2}{C_{ij}} + rac{
u}{\gamma} C_{ij}^{\gamma}
ight) W_{ij}^{(d)}$$

Via the deduction of the gradient of energy consumption functional as shown above, we conclude that the formal gradient flow (with respect to the Euclidean distance) of the energy functional constrained by the rescaled Kirchhoff law is of the type, i.e.

$$rac{\mathrm{d}C_{ij}}{\mathrm{d}t} = \left(rac{Q_{ij}^2}{C_{ij}^2} +
u C_{ij}^{\gamma-1}
ight)W_{ij}^{(d)}$$

if and only if all the weights $W_{ij}^{(d)}$ are equal. Here one of the natural way to chose $W_{ij}^{(d)}$ is letting $W_{ij}^{(d)}\equiv W^{(d)}=\prod_{k=1}^d h_k^{(d)}$.

The Discrete Approximation of the Poisson Equation

One can notice that the Kirchhoff law is a finite difference discretization of the Poisson equation per se. Furthermore, the approximation is the Riemann sum of the integral-type functional.

Consider the solution p(x) of the Poisson equation

$$-
abla \cdot (c
abla p) = S$$

Here $c=\mathrm{diag}\ (c_1,c_2,\cdots,c_d)$ is a diagonal permeabwhility tensor field with scalar non-negative functions $c^k\in C(\Omega)$. The global mass balance lies that

$$\int_{\partial\Omega} S(x) \mathrm{d}x = 0$$

We as ssume that the solution p(x) is at least C^2 on Ω and c are C^1 on Ω . Since $c(x) = \mathrm{diag}\ (c_1, c_2, \ldots, c_n)$ is diagonal, the finite difference approximation of S is

$$egin{aligned} S &= -
abla \cdot (c
abla p) \ &= - \sum_{k=1}^d \partial_{x_k} (c_k \partial_{x_k} p) \ &= - \sum_{k=1}^d c_k rac{\partial_{x_k} p(x_{(i+1/2)_k}) - \partial_{x_k} p(x_{(i-1/2)_k})}{h_k^{(d)}} + O(h_k^{(d)}) \ &= - \sum_{k=1}^d rac{c_k (x_{(i+1/2)}) \cdot rac{p(x_{i+1}) - p(x_i)}{h_k^{(d)}} - c_k (x_{(i-1/2)}) \cdot rac{p(x_i) - p(x_{i-1})}{h_k^{(d)}}}{h_k^{(d)}} \ &= \cdots \ &= - \sum_{k=1}^d C_{(i-1)_k,i} rac{(\Delta P)_{(i-1)_k,i}}{L_{(i-1)_k,i}} - C_{i,(i-1)_k} rac{(\Delta P)_{i,(i-1)_k}}{L_{i,(i-1)_k}} \end{aligned}$$

When we equal $\dfrac{c_k(x_{(i\pm 1/2)_k})}{h_k^{(d)}}$ with $C_{i\,i\pm 1},\,S_i$ with $S(X_i),\,P_i$ with $p(X_i)$ and $P_{i\pm 1}$ with

 $p(X_{i\pm 1})$, the rescaled Kirchhoff's law is concluded to be the discrete approximation of the Poisson function.

Moreover, we can estimate

$$\int_{\Omega}|c_k|^{\gamma}\mathrm{d}x=W^d\sum_{i\in V}|c_k(X_{(i+1/2)_k})|^{\gamma}+O(h_k^{(d)})$$

and

$$\int_{\Omega} c_k (\partial_{x_k} p)^2 \mathrm{d}x = W \sum_{i \in V} c_k (X_{(i+1/2)_k}) \Biggl(rac{p(X_{(i+1)_k}) - p(X_i)}{h_k^{(d)}}\Biggr)^2 + O(h_k^{(d)})$$

Thus the energy functional with respect to rectangular grid parallelotopes can be written as

$$ilde{\mathcal{E}}[C] = rac{1}{2} \sum_{k=1}^d \sum_{i \in V} \sum_{j \in N(i;k)} \left(rac{Q_{ij}^2[C]}{C_{ij}} + rac{
u}{\gamma} C_{ij}^\gamma
ight) h_k^{(d)}$$

Here N(i;k) denotes $N(i) \cap \{(i \pm 1)_k\}$, that is, the neighbour in the kth spatial dimension.

Via the notation we applied in the discrete approximation, we have

$$ilde{\mathcal{E}}[C] + O(W^{(d)}) = \mathcal{E}[c] = \int_{\Omega}
abla p \cdot c
abla p + rac{
u}{\gamma} |c|^{\gamma} \mathrm{d}x$$

Here $|c|:=\sum_{k=1}^d |c_k|^{\gamma}$.

The formal L^2 -Gradient Flow of the Energy

In retrospect to how we have deducted $\frac{\mathrm{d}C}{\mathrm{d}t}$, we shall estimate the the formal L^2 – gradient flow of the continuum energy functional coupled with the Poisson equation. The relation between the discrete and continuum model is presented below.

$$ilde{\mathcal{E}}[C] + ext{Kirchhoff law} \Rightarrow ext{gradient flow in the discrete model} \ \updownarrow \qquad \qquad \updownarrow \ \mathcal{E}[c] + ext{Poisson equation} \Rightarrow ext{L^2-gradient flow in the continuum model} \$$

Let $\phi = \operatorname{diag}(\phi_1, \phi_2, \dots, \phi_n)$ be a diagonal matrix, and ε is arbitrarily small.

Via the expansion $p[c+arepsilon\phi]=p_0+arepsilon p_1+O(arepsilon^2)$

$$rac{\mathrm{d}\mathcal{E}[c+arepsilon\phi]}{\mathrm{d}arepsilon}\mid_{arepsilon=0}=\sum_{k=1}^{d}\int_{\Omega}(\partial_{x_{k}}p_{0})^{2}\phi_{k}+2c_{k}(\partial_{x_{k}}p_{0})(\partial_{x_{k}}p_{1})+
u|c_{k}|^{\gamma-2}c_{k}\phi_{k}\mathrm{d}x$$

Multiplicating the Poisson equation with permeability tensor $c+\varepsilon\phi$ by p_0 and integrating by parts, we have

$$\sum_{k=1}^d \int_\Omega (c_k + arepsilon \phi_k) (\partial_{x_k} p_0)^2 + arepsilon c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) \mathrm{d}x = \int_\Omega Sp_0 \mathrm{d}x + O(arepsilon^2)$$

Thus

$$egin{aligned} O(arepsilon^2) &= \sum_{k=1}^d \int_\Omega (c_k + arepsilon \phi_k) (\partial_{x_k} p_0)^2 + arepsilon c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) \mathrm{d}x - \int_\Omega S p_0 \mathrm{d}x \ &= \sum_{k=1}^d \int_\Omega arepsilon \phi_k (\partial_{x_k} p_0)^2 + arepsilon c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) \mathrm{d}x + \left[\int_\Omega c_k (\partial_{x_k} p_0)^2 - S p_0 \mathrm{d}x
ight] \ &= arepsilon \sum_{k=1}^d \int_\Omega \phi_k (\partial_{x_k} p_0)^2 + c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) \mathrm{d}x \end{aligned}$$

Let $\varepsilon \to 0$, We obtain the identity

$$\sum_{k=1}^d \int_\Omega \phi_k (\partial_{x_k} p_0)^2 + c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) \mathrm{d}x = 0$$

Thus

$$egin{aligned} rac{\mathrm{d}\mathcal{E}[c+arepsilon\phi]}{\mathrm{d}arepsilon} \mid_{arepsilon=0} &= \sum_{k=1}^d \int_\Omega (\partial_{x_k} p_0)^2 \phi_k + 2c_k (\partial_{x_k} p_0) (\partial_{x_k} p_1) +
u |c_k|^{\gamma-2} c_k \phi_k \mathrm{d}x \ &= \sum_{k=1}^d \int_\Omega -(\partial_{x_k} p_0)^2 \phi_k +
u |c_k|^{\gamma-2} c_k \phi_k \mathrm{d}x \ &= \sum_{k=1}^d \int_\Omega \left[-(\partial_{x_k} p_0)^2 +
u |c_k|^{\gamma-2} c_k
ight] \phi_k \mathrm{d}x \end{aligned}$$

Thus we deduce that

$$\partial_t c_k = (\partial_{x_k} p)^2 -
u |c_k|^{\gamma-2} c_k$$

In the previous part, we discuss the gradient flow with respect to rectangular parallelotopes. In fact the coordinate transform $\mathcal{T}:e_k\to f_k$ leads to the transformed continuum energy functional

$$E[c] = \int_{\Omega}
abla p^T \cdot \mathbb{T}[c] \cdot
abla p + rac{
u}{\gamma} |c|^{\gamma} \mathrm{d}x$$

coupled with the transformed Poisson equation

$$-\nabla \cdot [\mathbb{T}[c] \cdot \nabla p] = S$$

Here we define the permeability tensor $\mathbb{T}[c] := \sum_{k=1}^d c_k f_k \otimes f_k$.

Thus

$$\partial_t c_k = \left(f_k \cdot
abla p
ight)^2 -
u |c_k|^{\gamma-2} c_k$$

Global existence of Solutions of a Modified Macroscopic Model

The establishment of the full PDE system

We notice that the Poisson function suffers from two drawbacks. One is that the diagonal of the tensor c(x) might vanish, while the other one is that the random fluctuations can ill be neglected.

- 1. To tackle with the first obstakle we rewirte the permeability tensor with a prescribed function that models the isotropic background permeability of the medium, i.e. $\mathbb{T}[c] := r\mathbb{I} + c$ with $r(x) \geq r_0 > 0$, where \mathbb{I} is the unit matrix with dimension d. The PDE $-\nabla \cdot (\mathbb{T}[c]\nabla p) = S$ remains elliptic iff diagonal of c(x) are non-negative.
- 2. As for the amendment of random fluctuations term, a linear diffusive term is introduced to model the random fluctuations in the medium. Let $D^2>0$ be the constant diffusivity, we thus obtain

$$\partial_t c_k = D^2
abla^2 c_k +
abla p^T \cdot (f_k \otimes f_k) \cdot
abla p -
u |c_k|^{\gamma-2} c_k$$

Since

$$rac{D^2}{2}
abla(c+arepsilon\phi)^T\cdot
abla(c+arepsilon\phi)-rac{D^2}{2}
abla c^T\cdot
abla c=arepsilon D^2
abla c^T\cdot
abla \phi+O(arepsilon^2)$$

We deduce the amended formal L^2 -gradient flow of the energy functional

$$\mathcal{E}[c] = \int_{\Omega} rac{D^2}{2} |
abla c|^2 +
abla p^T \cdot \mathbb{T}[c]
abla p + rac{
u}{\gamma} |c|^{\gamma} \mathrm{d}x$$

Here $|\nabla c| := \nabla c^T \cdot \nabla c = \sum_{k=1}^d \partial_{x_k} c_k$.

The PDE system

$$egin{aligned} \partial_t c_k &= D^2
abla^2 c_k + |f_k \cdot
abla p|^2 -
u |c_k|^{\gamma-2} c_k \ S &= -
abla \cdot (\mathbb{T}[c]
abla p) \ \mathbb{T}[c] &= c + r \mathbb{I} \end{aligned}$$

subject to homogeneous Dirichlet boundary boundary conditions for c and no-flux boundary conditions for p. Thus for all $x\in\partial\Omega$ and t>0

$$c(t,x)\equiv 0,\quad \partial_n p(t,x)\equiv 0$$

The initial datum $c_0(x):=c(0,x)$ is a diagonal tensor field with non-negative diagonal elements.

To estimate the weak solutions, we introduce the buffer matrix $\mathbb E$ which is positive define. Let $\mathbb T'[c]$ denotes $r\mathbb I+c*\mathbb E$. Consider the convolution

$$c_k * \mathbb{E}(x) := \int_{\mathbb{R}^d} c_k(y) \mathbb{E}(x-y) \mathrm{d}y$$

The PDE system outcomes

$$egin{aligned} \partial_t c_k &= D^2
abla^2 c_k + |
abla p|^2 * \mathbb{E} -
u |c_k|^{\gamma-2} c_k \ S &= -
abla \cdot (\mathbb{T}'[c]
abla p) \ \mathbb{T}'[c] &= r \mathbb{I} + c * \mathbb{E} \end{aligned}$$

The formal L^2 -gradient flow of the energy functional is presented as

$$\mathcal{E}'[c] := \int_{\Omega} rac{D^2}{2} |
abla c|^2 +
abla p^T \cdot \mathbb{T}'[c]
abla p + rac{
u}{\gamma} |c|^{\gamma} \mathrm{d}x$$

To prove the global existence of weak solutions, we shall introduce a lemma for a semilinear PDE.

A maximum principle for a heat equation PDE

(Weak maximum principle for the heat equation) Let Ω be an open, bounded subset of \mathbb{R}^d . For a fixed T>0 denote $\Omega_T:=(0,T] imes\Omega$ and

$$C^2_1(\Omega_T):=\{u:\Omega_T o\mathbb{R}:u,
abla u,
abla^2 u,\partial_t u\in C(\partial\Omega_T)\}$$

Let $\gamma>1$ and $u\in C^2_1(\Omega_T)\cap C(\overline{\Omega_T})$ be the classical solution of the initial/boundary-value problem

$$egin{aligned} \partial_t u &= D^2
abla^2 u -
u |u|^{\gamma-2} u && ext{in } \Omega_T, \ u &= 0 && ext{on } [0,T] imes \partial \Omega, \ u &= g && ext{on } \{T=0\} imes \Omega. \end{aligned}$$

with the nonnegative initial datum $\Omega o R$. Then $\min_{\overline{\Omega^T}} u \geq 0$.

Proof. Denote
$$U_T:=\{(t,x)\in\Omega_T:u(t,x)<0\}$$
, then $\partial_t u-D^2\nabla^2 u=-\nu|u|^{\gamma-2}u>0$ in U_T . We define the parabolic boundary $\Gamma:=([0,T]\times\partial\Omega)\cup(\{T=0\}\times\Omega)$.

WLOG let D=1. Put $v(t,x)=u(t,x)-\varepsilon t$ where ε can be arbitrarily small. Then

$$\partial_t v - \nabla^2 v \le -\varepsilon < 0$$

We claim that v cannot achieve its maximum anywhere outside Γ . If not, suppose that v reaches the maximum v(t',x') in $(0,T)\times\Omega_T$, then $\partial_t v=0$ and $\nabla^2 v\leq 0$. Since $\partial_t v-\nabla^2 v$ is strictly negative, we obtain the contradiction. The statement also holds for $(t',x')\in\{T\}\times\Omega_T$ due to the existence of the solution v in $(0,T+\delta)\times\Omega_T$

As arepsilon o 0 , $\min_{\overline{\Omega^T}} u = \min_{\Gamma} u \geq -arepsilon o 0$.

Global existence of the weak solutions

The solution we obtain from the PDE system

$$egin{aligned} \partial_t c_k &= D^2
abla^2 c_k + |
abla p|^2 * \mathbb{E} -
u |c_k|^{\gamma-2} c_k \ S &= -
abla \cdot (\mathbb{T}'[c]
abla p) \ \mathbb{T}'[c] &= r \mathbb{I} + c * \mathbb{E} \end{aligned}$$

$$c(t,x)\equiv 0,\quad \partial_n p(t,x)\equiv 0,\quad ext{for all } x\in\partial\Omega ext{ and } t>0$$

is weak due to the mollifier \mathbb{E} . Let $S \in L^2(\Omega)$ and $c_0(x) \in H^1_0(\Omega)^{d \times d} \cap L^{\gamma}(\Omega)^{d \times d}$. Then for each \mathbb{E} , the PDE system admits a global weak solution (c, p) satisfying

$$egin{split} c \in L^\infty(0,\infty;H^1_0(\Omega)) \cap L^\infty(0,\infty;L^\gamma(\Omega)) \ \partial_t c \in L^2((0,\infty) imes\Omega) \
abla p \in L^\infty(0,\infty;L^2(\Omega)) \ c
abla p \in L^\infty(0,\infty;L^2(\Omega)) \end{split}$$

While the regularized energy functional satisfied

$$\mathcal{E}'[c(t)] = \mathcal{E}'[c_0] + \sum_{k=1}^d \int_0^t \int_\Omega \left(\partial_t c_k(s,x)
ight)^2 \mathrm{d}x \mathrm{d}s$$

for all $t \in (0, \infty)$.

Proof. Leave to the future.

Let $\|\mathbb{E}\|_{\infty} \to 0$ along the procedure of the "proof", we obtain the global existance of the solution.